# Checkpointing and Recovery in Distributed Systems

Advanced Operating Systems

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March 14, 2013



#### Outline

- Overview
- Main Issues
- Checkpointing and Recovery Protocols
  - Koo and Toueg's Protocol
  - Juang and Venkatesan's Protocol



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#### Overview

- System components often fail in real-world for many different reasons
  - Power outage
  - Operating system crash
  - Memory leakage
- Significant problem for long running applications
  - Likelihood that some component fails while the application is running is quite high



#### **Tolerating Failures**

- Assumption: Failed component eventually recovers and the application process is restarted
- Naïve Solution: Restart the application from the beginning whenever a failure occurs
  - All work done by the application before the failure is lost and has to be redone
  - No guarantee that the application will ever complete successfully!



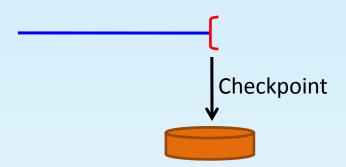
- Regularly save process' current state in reliable storage (e.g., hard disk)
  - Process' state is referred to as checkpoint
    - A checkpoint stores values of all the relevant program variables and registers
  - Reliable storage is referred to as stable storage
    - Assumed to be unaffected by failures



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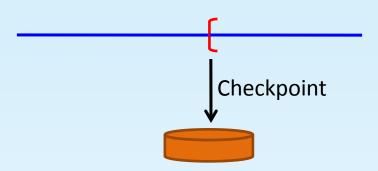


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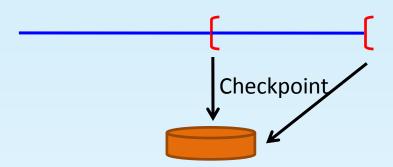


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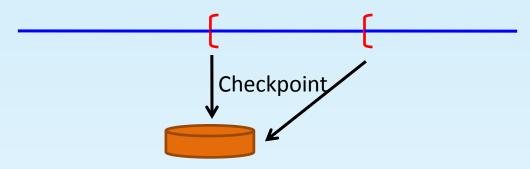


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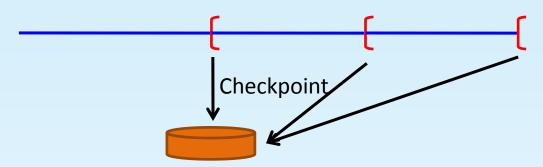


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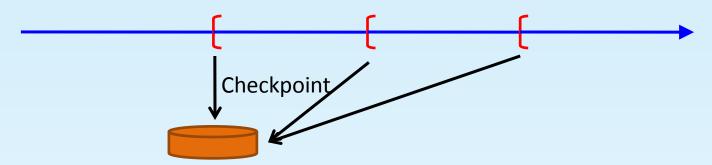


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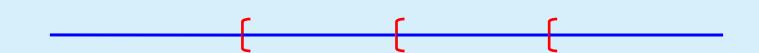


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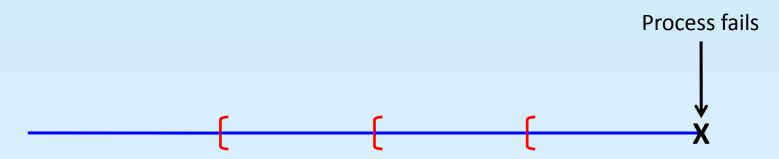


- When a process fails and recovers, resume the execution from a saved checkpoint
  - Work done since the checkpoint until the failure point is lost

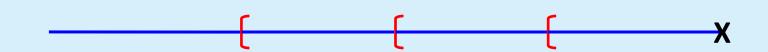




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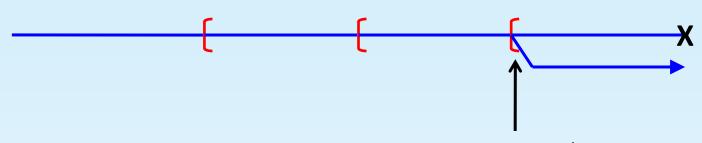


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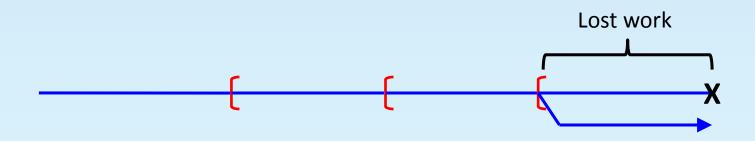
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  - Work done since the checkpoint until the failure point is lost



Process recovers and restarts



- When a process fails and recovers, resume the execution from a saved checkpoint
  - Work done since the checkpoint until the failure point is lost





#### Outline

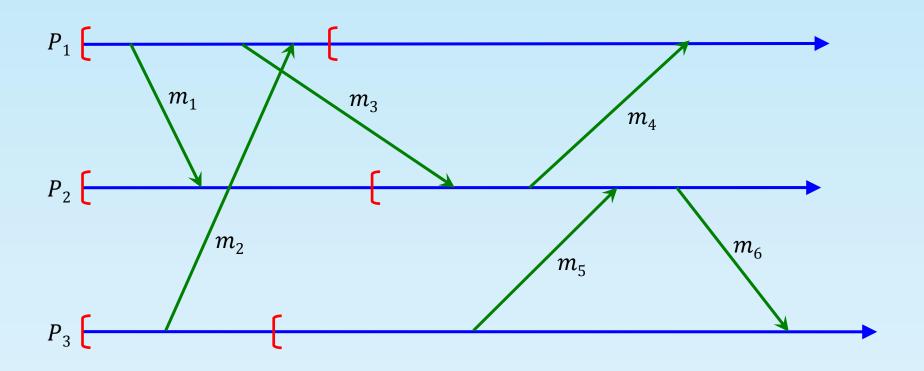
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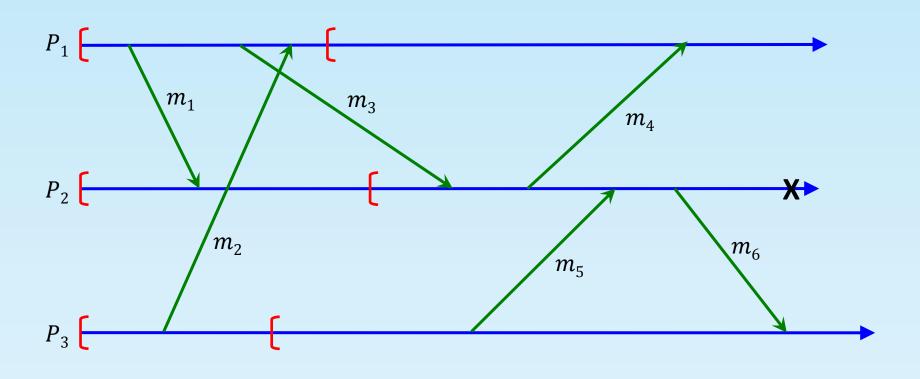


#### Issues in Distributed Systems

- Two main issues:
  - Lost messages: messages whose receive event has been lost
  - Orphan messages: messages whose send event has been lost

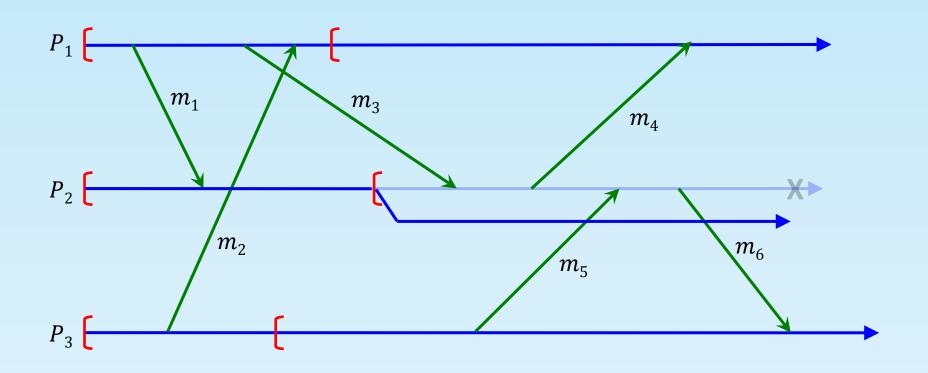






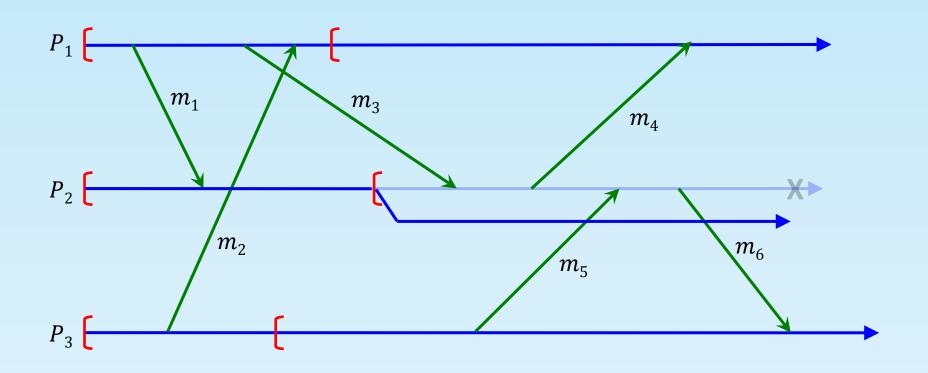
 $P_2$  fails





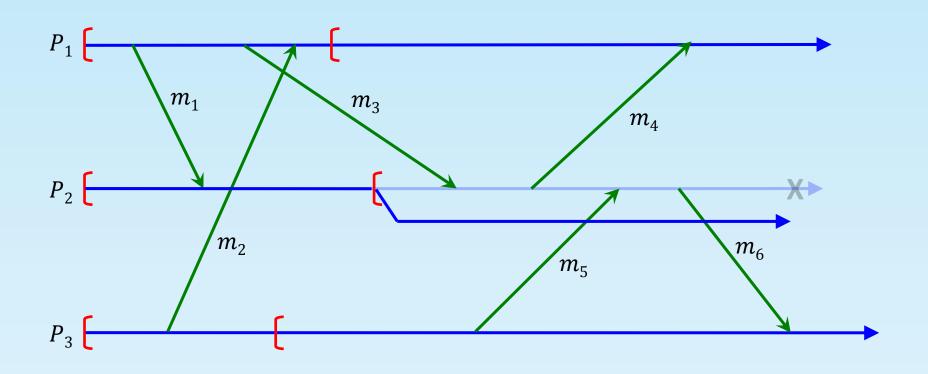
 $P_2$  recovers and restarts





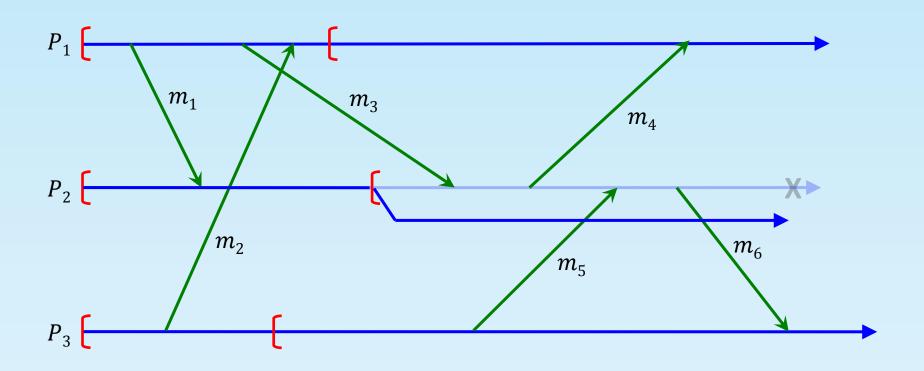
 $m_3$  and  $m_5$  become lost messages





 $m_4$  and  $m_6$  become orphan messages

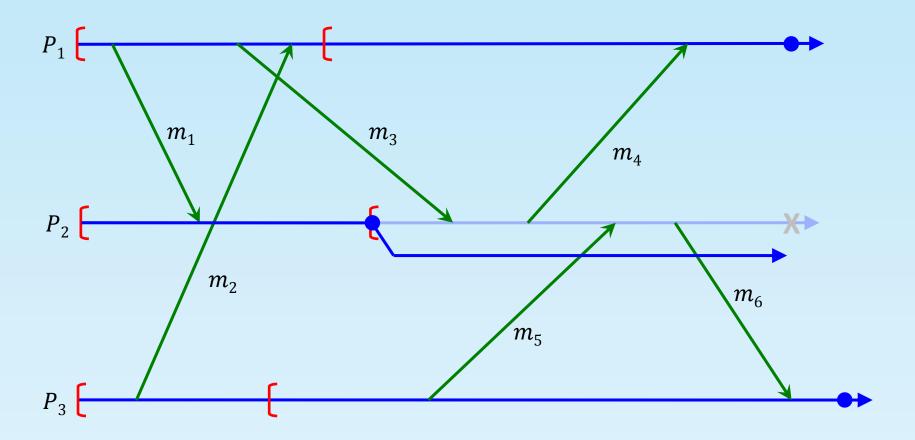




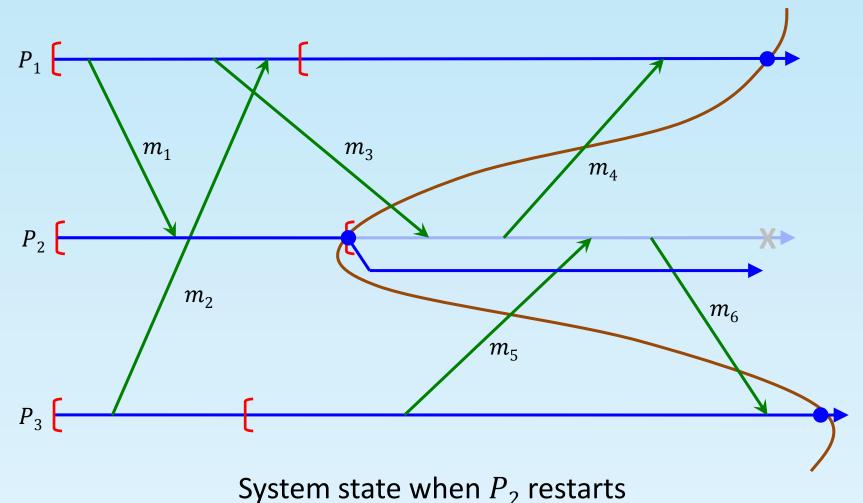
#### Lost and Orphan Messages

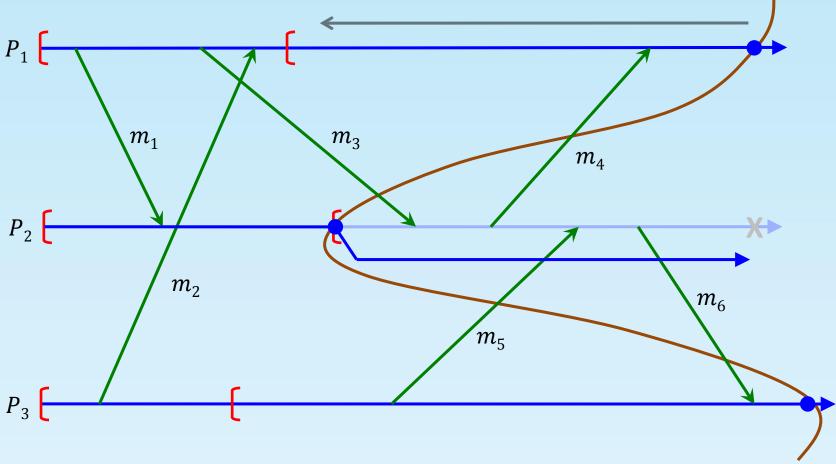
- Lost messages can be handled using retransmissions
  - At application layer
  - Requires message logging
- Orphan messages require more complex solution
  - System state depends on messages that no longer exist (and may never be generated)
  - Other processes need to be rolled back to eliminate any trace of orphan messages





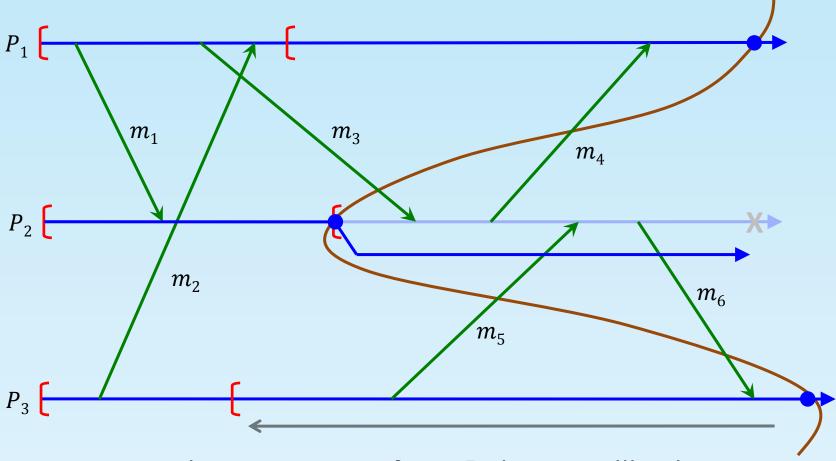






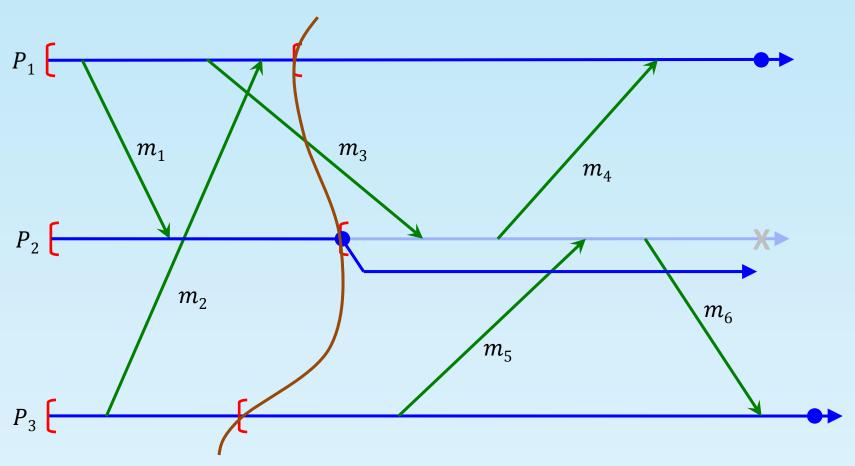






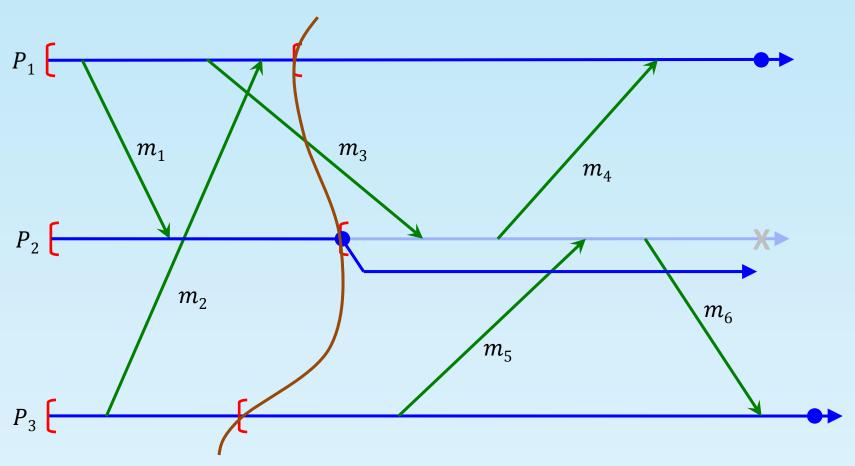
To eliminate trace of  $m_6$ ,  $P_3$  has to rollback





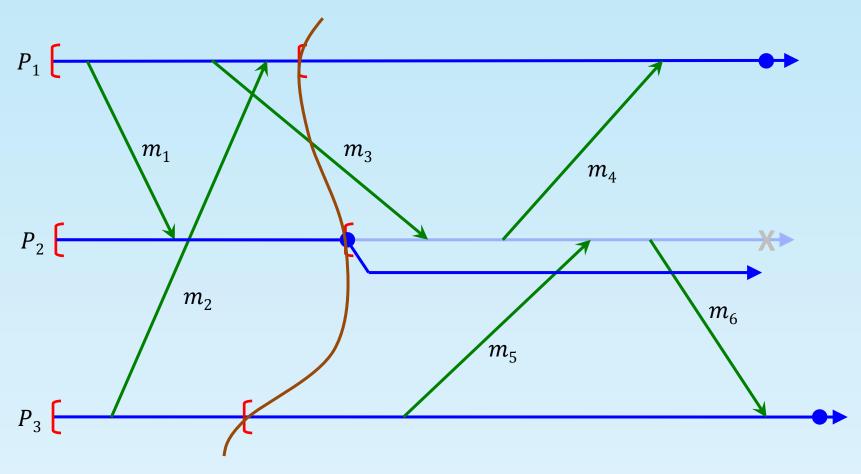
System state with all orphan messages eliminated





Message  $m_3$  is a lost message with respect to the recovery line

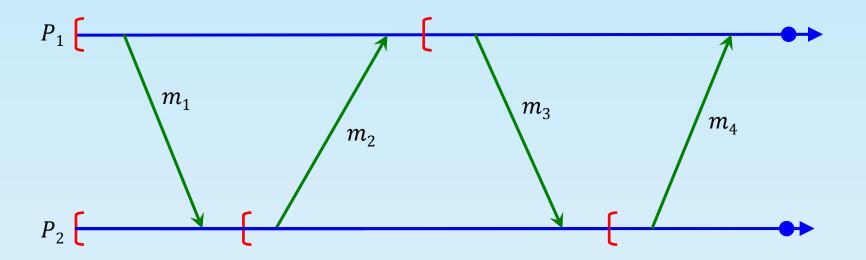


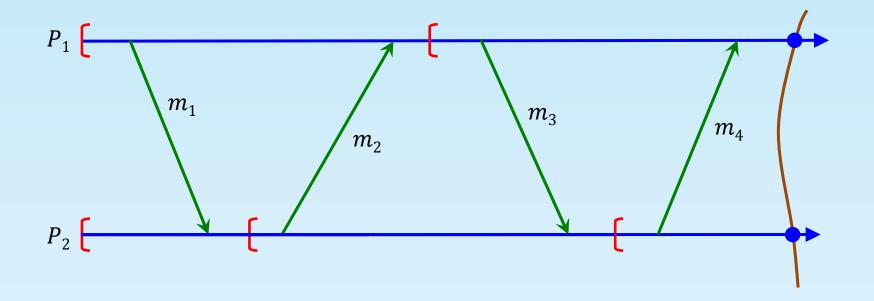


#### **Domino Effect**

- Rollback of processes that did not fail may cause other messages to become orphan
- May cause domino effect
  - Processes may repeatedly roll back each other such that the system is rolled back all the way to the initial state

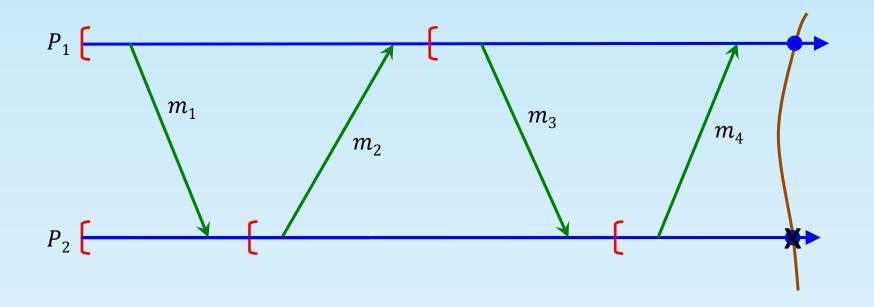
#### Domino Effect: An Illustration





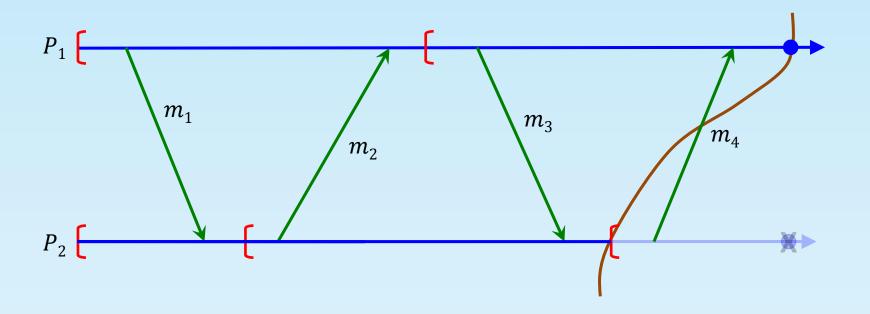
System state before failure





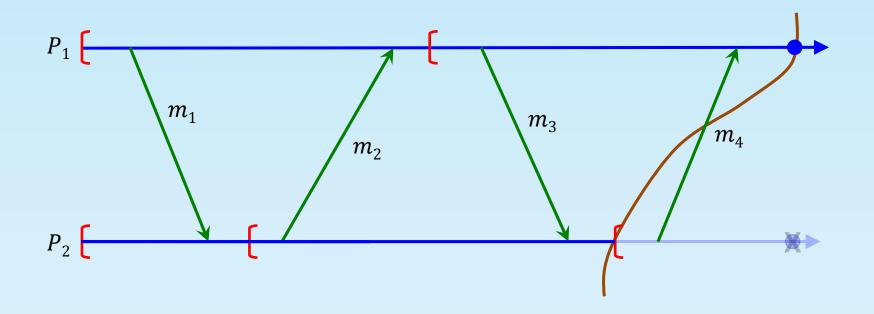
 $P_2$  fails





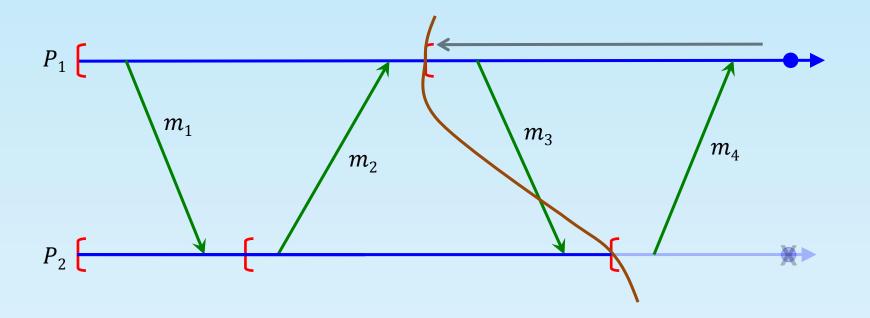
System state just after  $P_2$  restarts





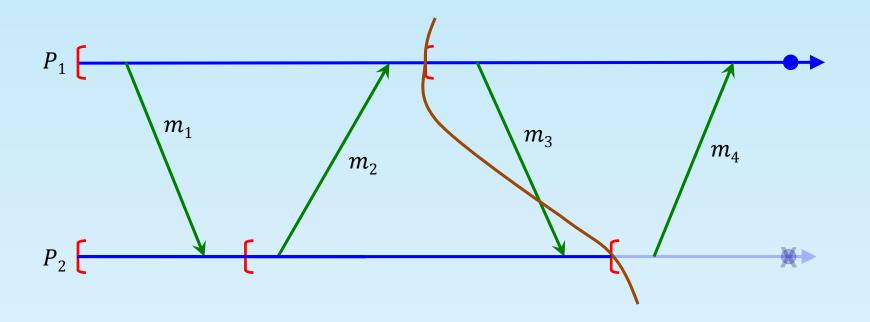
 $m_4$  becomes an orphan message





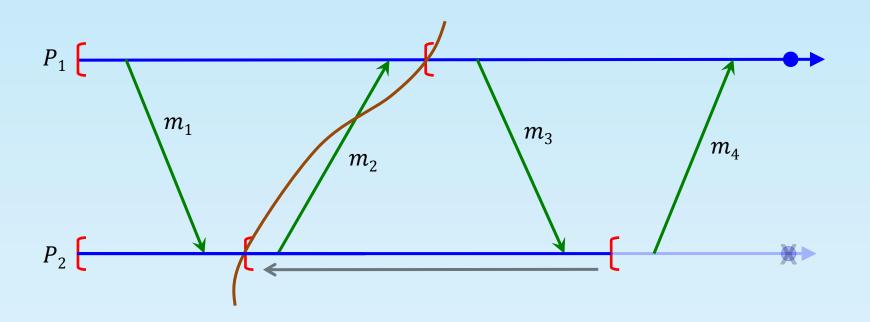
 $P_1$  has to roll back to its previous checkpoint





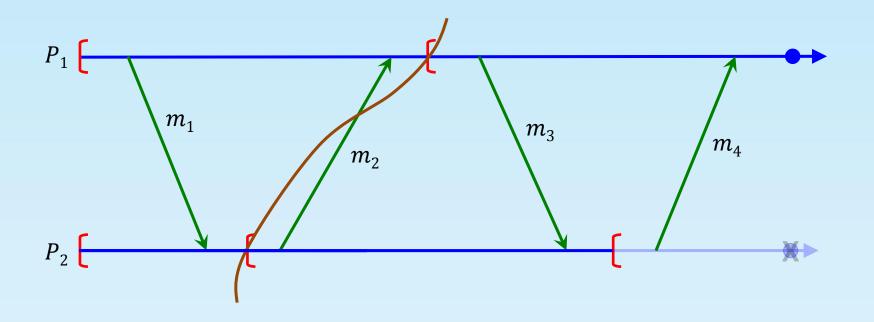
Now  $m_3$  becomes an orphan message





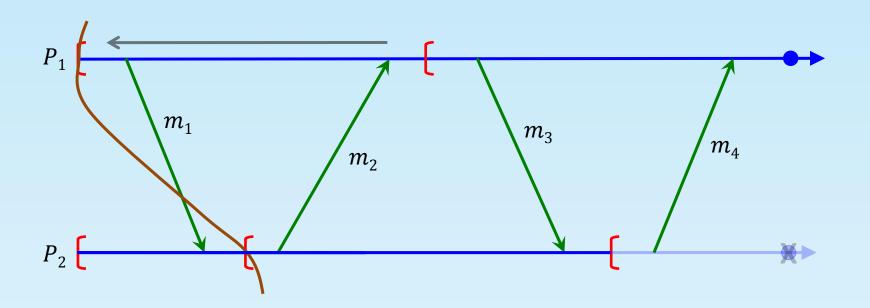
 $P_2$  has to roll back to its previous checkpoint





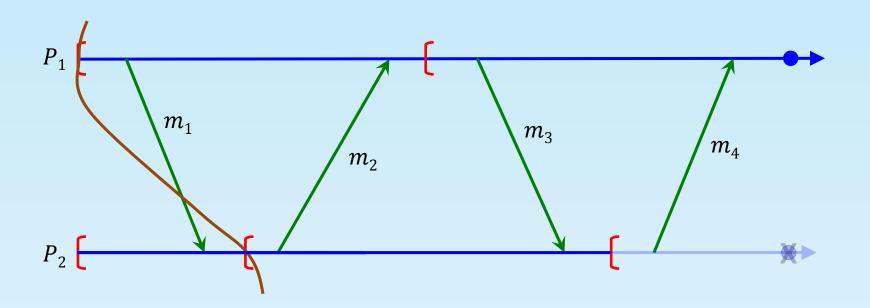
Now  $m_2$  becomes an orphan message





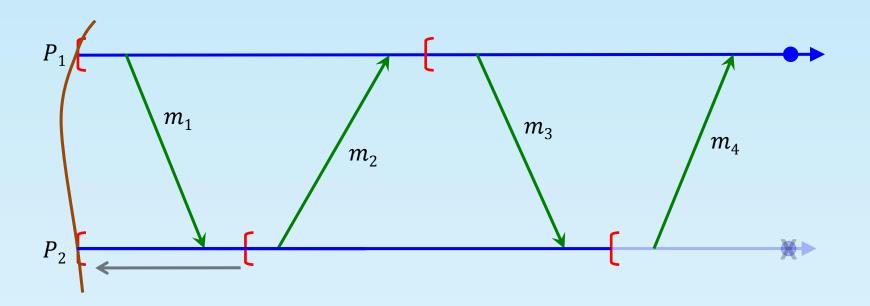
 $P_1$  has to roll back to its previous checkpoint





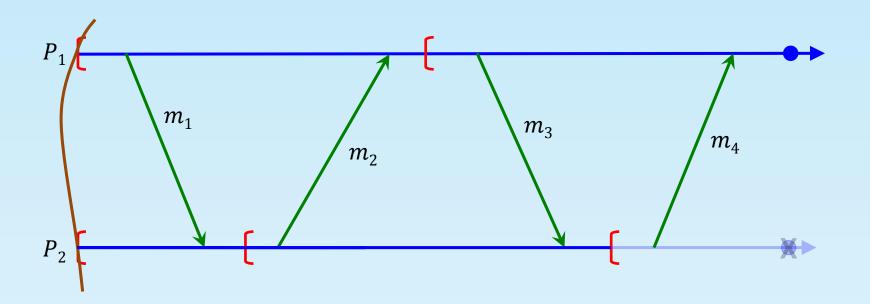
Now  $m_1$  becomes an orphan message





 $P_2$  has to roll back to its previous checkpoint





System has rolled back all the way to the beginning



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#### **Checkpointing and Recovery Protocols**

- Different protocols provide different trade off between checkpointing overhead and recovery overhead
- Koo and Toueg's Protocol
  - Checkpointing overhead: high
  - Recovery overhead: medium
- Juang and Venkatesan's Protocol
  - Checkpointing overhead: low
  - Recovery overhead: high



#### Assumptions

- All channels are FIFO
- All channels are bidirectional
- All channels are reliable
- Communication topology need not be a complete graph

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### Koo and Toueg's Protocol

Ensures that the last checkpoints of any processes are concurrent

#### As a result:

- No process has to roll back beyond its last checkpoint
- Checkpointing by one process may cause other processes to take a checkpoint as well
- Recovery involves rolling back processes to their last checkpoints



### Koo and Toueg's Protocol (Contd.)

- At any given time, multiple instances of checkpointing and recovery protocols may be in progress:
  - A process participates in at most instance (checkpointing or recovery) at any given time
    - It will refuse to participate in other instances, thereby causing them to abort
    - Aborted instances are restarted later by their initiators



### Koo and Toueg's Checkpointing Protocol

- Consists of two phases
  - First Phase:
    - Processes take tentative checkpoints if they can
      - A process after taking a tentative checkpoint cannot send any application messages until the second phase completes
  - Second Phase:
    - If all required processes are able to take checkpoints in the first phase, then tentative checkpoints are made permanent
    - Otherwise, tentative checkpoints are discarded



# Koo and Toueg's Checkpointing Protocol (Contd.)

- Minimizes the number of processes that take checkpoints
  - Each process assigns labels with monotonically increasing value to its messages
  - $-\perp$  is a special label:
    - It is smaller than any other label value
  - Each process maintains two vectors with one entry for each of its neighbors:
    - last\_label\_rcvd
    - first\_label\_sent



### Koo and Toueg's Checkpointing Protocol: Details

- Consider processes  $P_i$  and  $P_j$  that are neighbors
- Definition of last\_label\_rcvdi[j]:
  - Let m be the last message that  $P_i$  has received from  $P_j$  since its last permanent/tentative checkpoint

$$last\_label\_rcvdi[j] \triangleq \begin{cases} label \text{ of } m, & m \text{ exists} \\ \bot, & m \text{ does not exist} \end{cases}$$



# Koo and Toueg's Checkpointing Protocol: Details (Contd.)

- Definition of first\_label\_senti[j]:
  - Let m be the first message that  $P_i$  has sent to  $P_j$  since its last permanent/tentative checkpoint

$$first\_label\_sent_i[j] \triangleq \begin{cases} label \text{ of } m, & m \text{ exists} \\ \bot, & m \text{ does not exist} \end{cases}$$

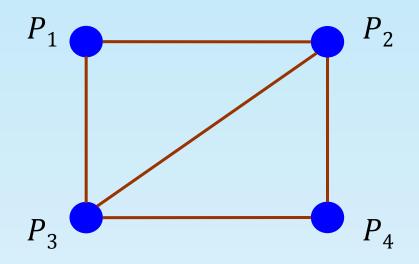


### Koo and Toueg's Checkpointing Protocol: Details (Contd.)

- Assume that  $P_i$  has taken a (tentative) checkpoint:
  - $-P_j$  does not need to take a checkpoint if  $last\_label\_rcvdi[j] = \bot$
  - Otherwise,  $P_i$  requests  $P_j$  to take a checkpoint and sends  $last\_label\_rcvdi[j]$  to  $P_j$
  - $-P_i$  takes a (tentative) checkpoint if:

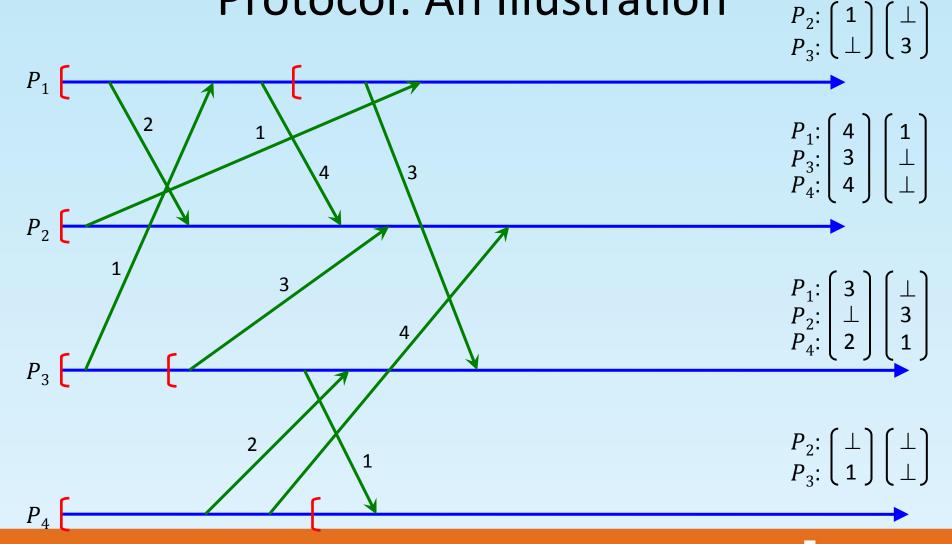
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last_label_rcvdi[j] \ge first_label_sentj[i] > \bot
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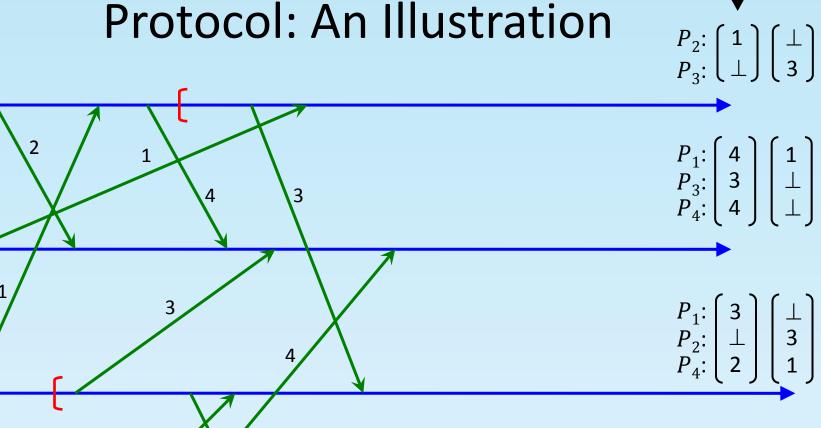


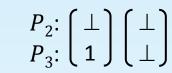


Communication topology (used in all illustrations)

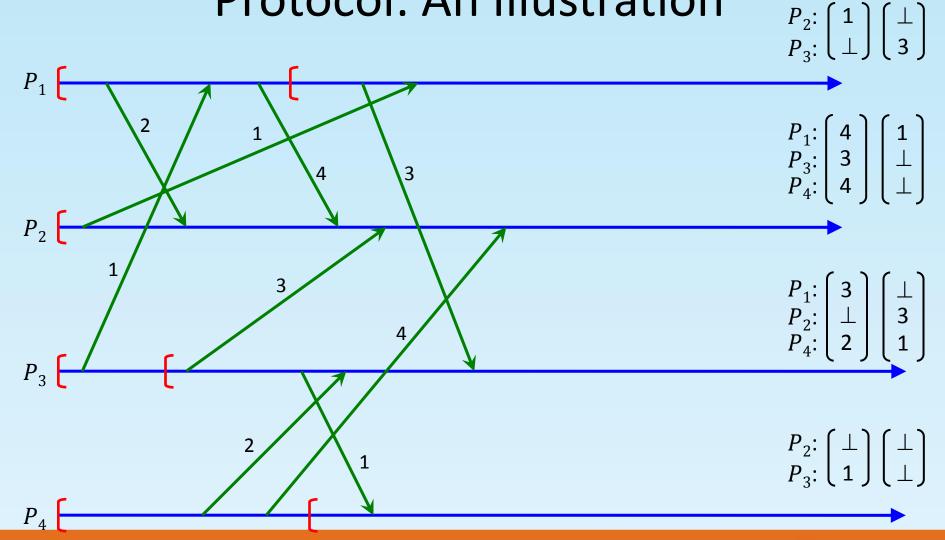




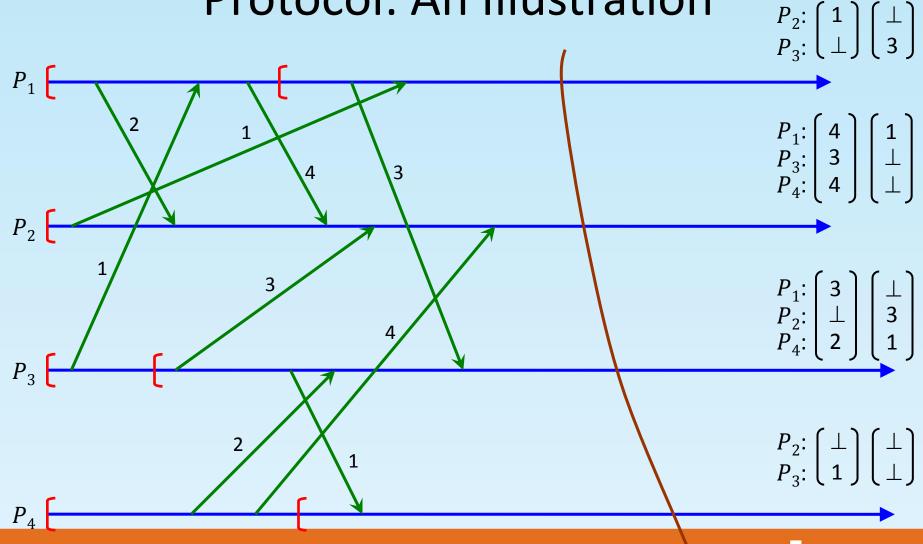


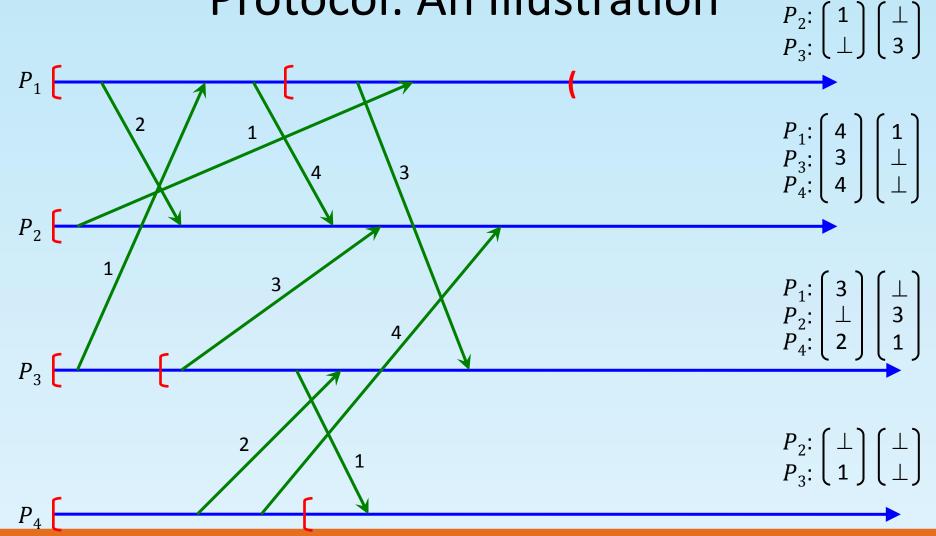


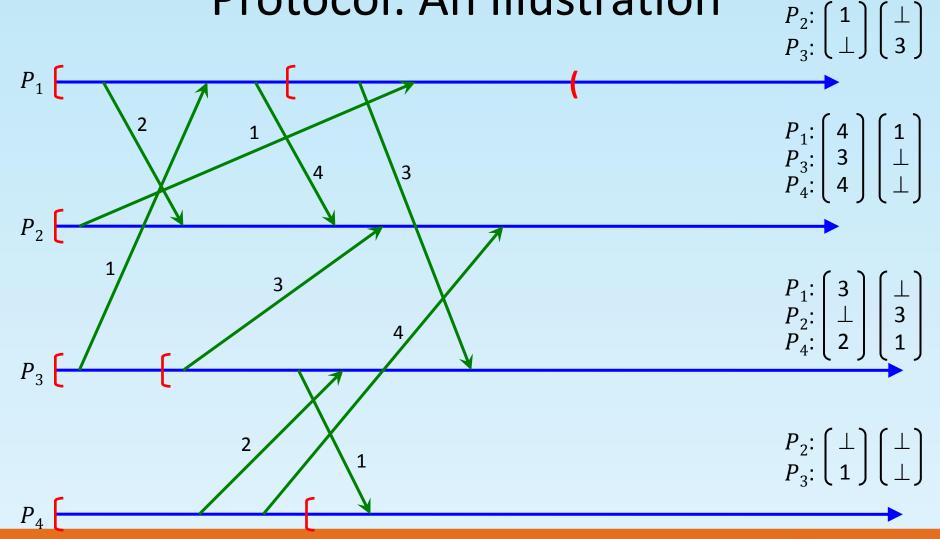


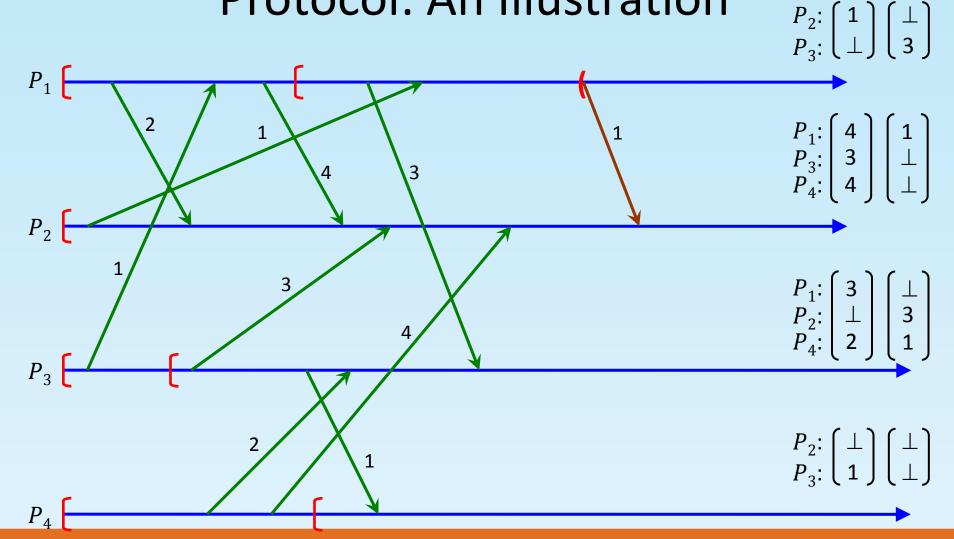


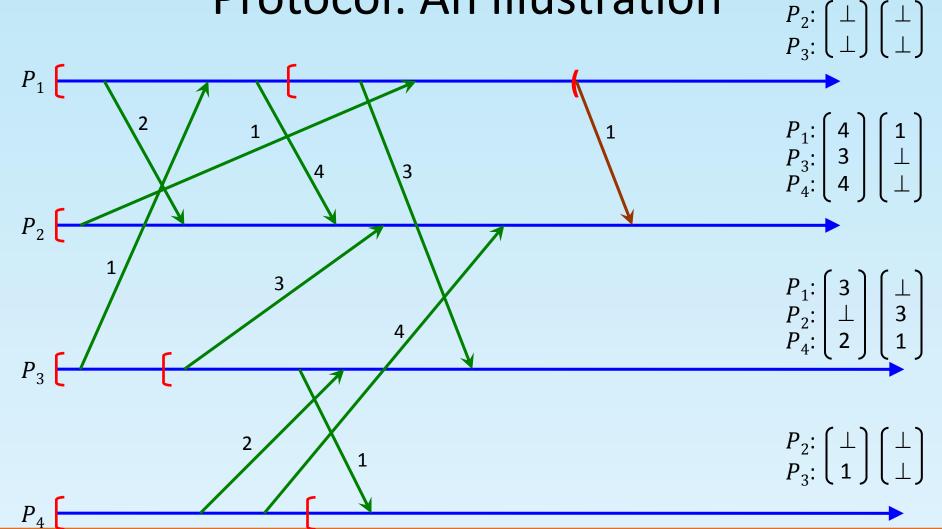


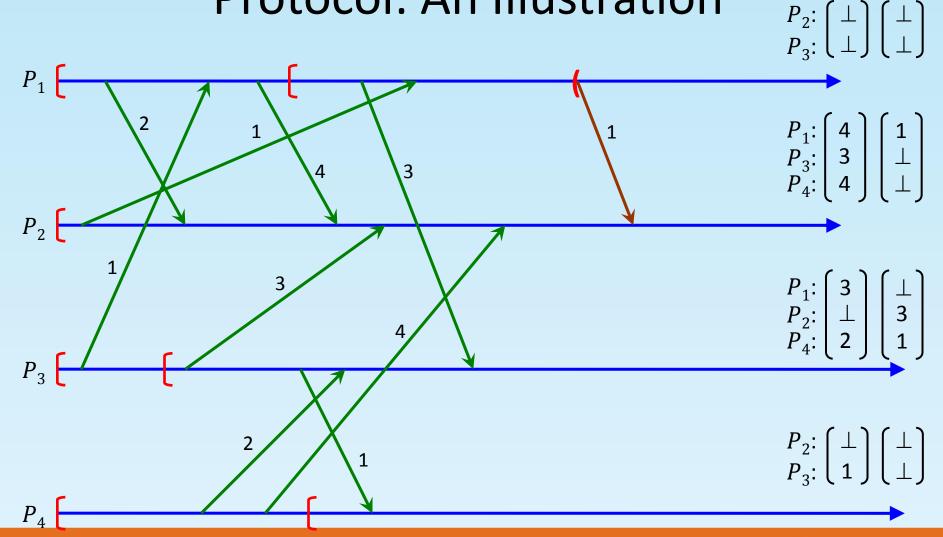


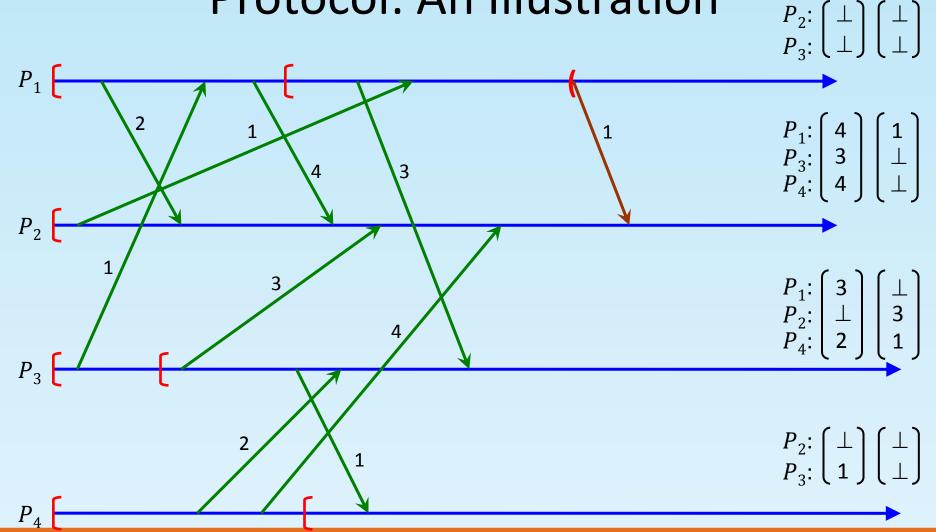


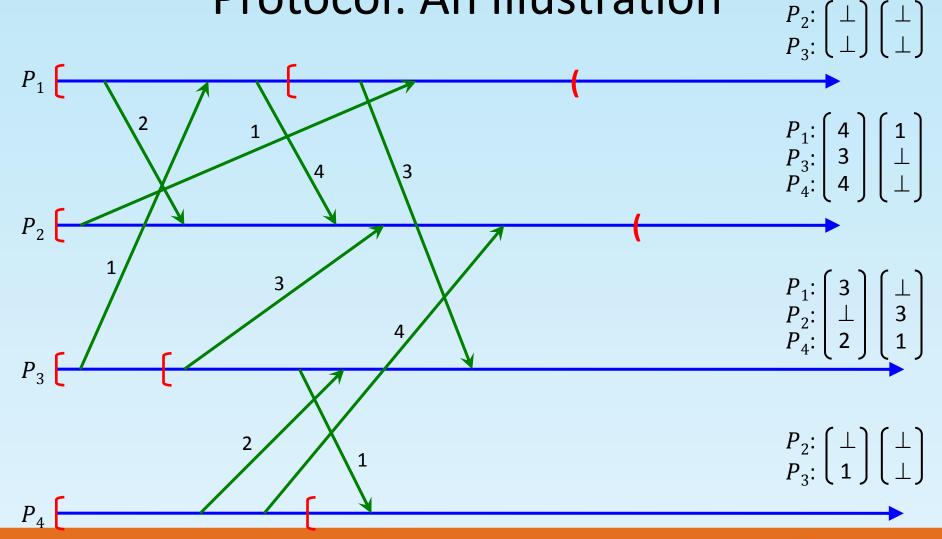


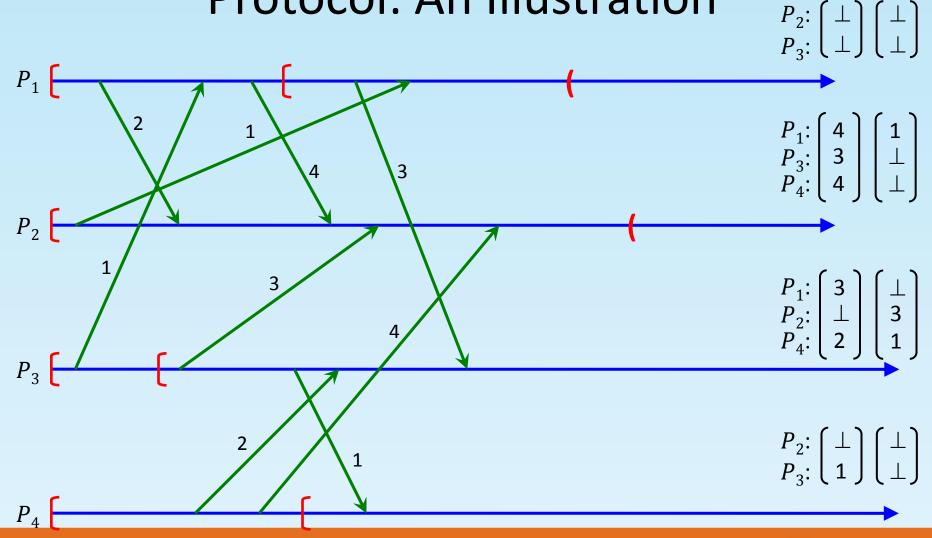


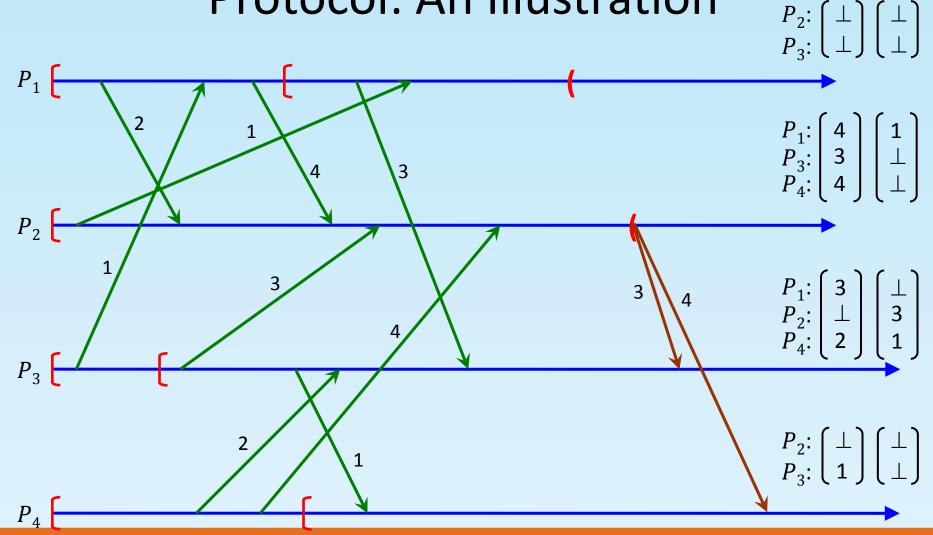


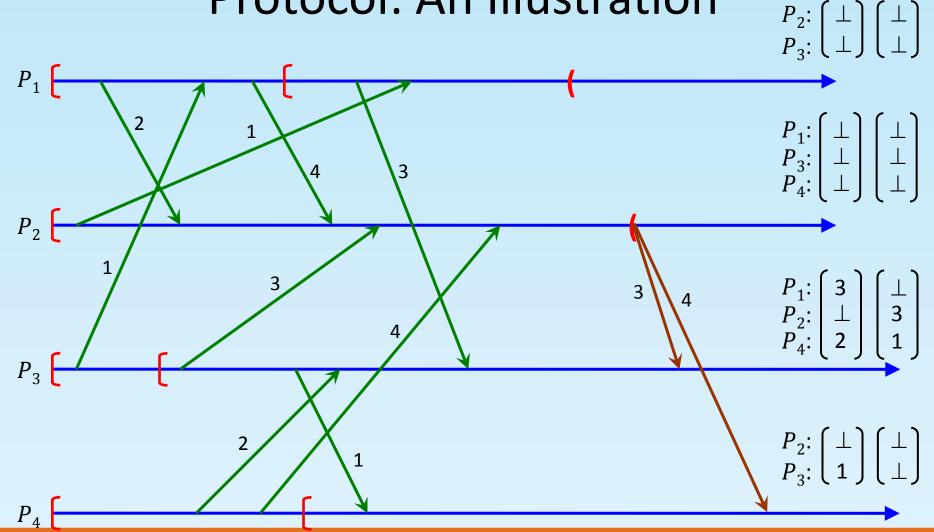


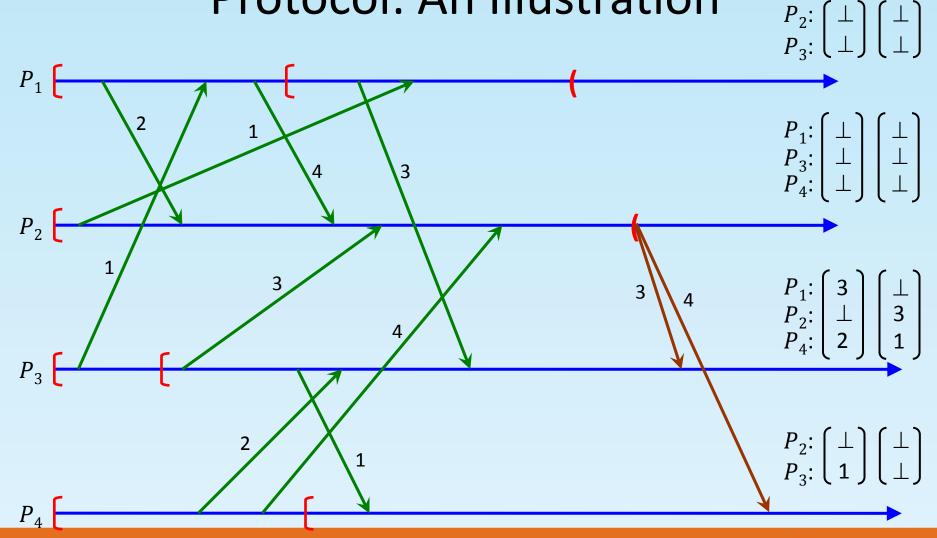


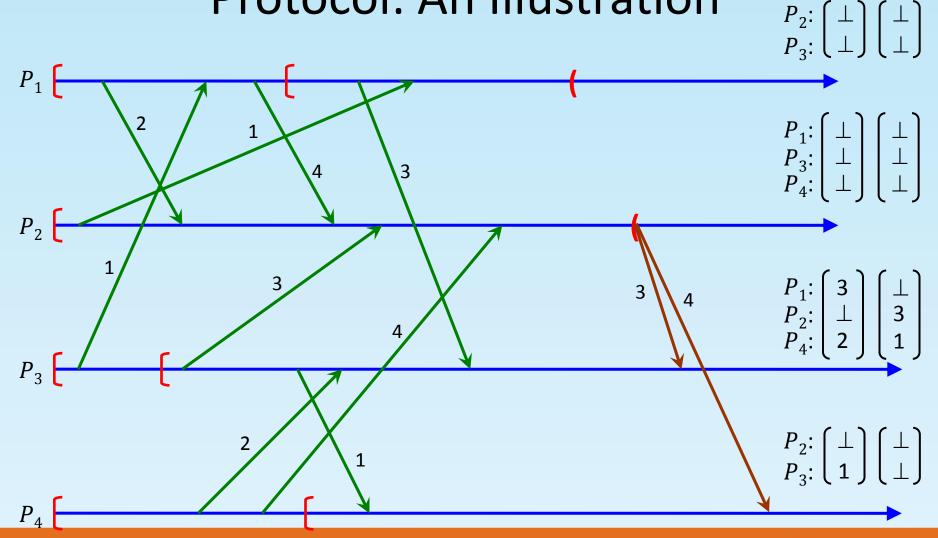


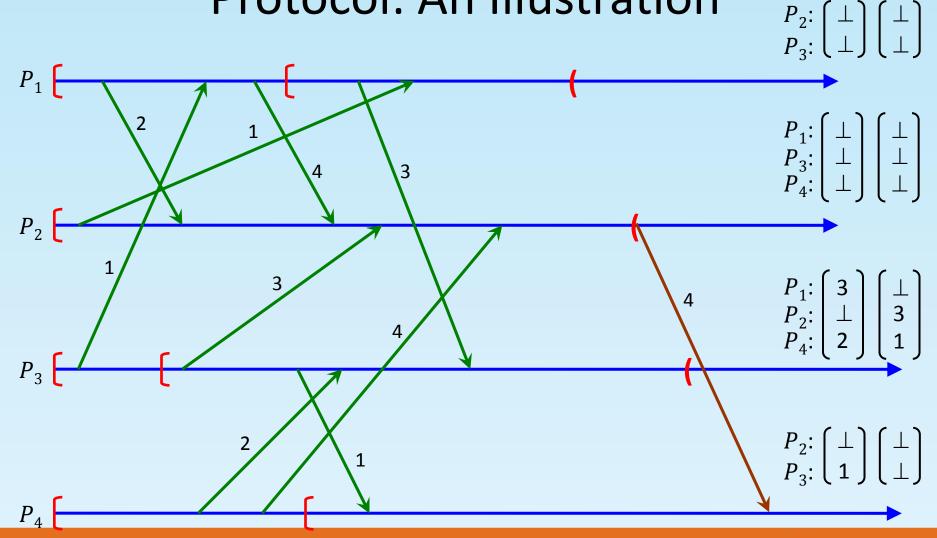


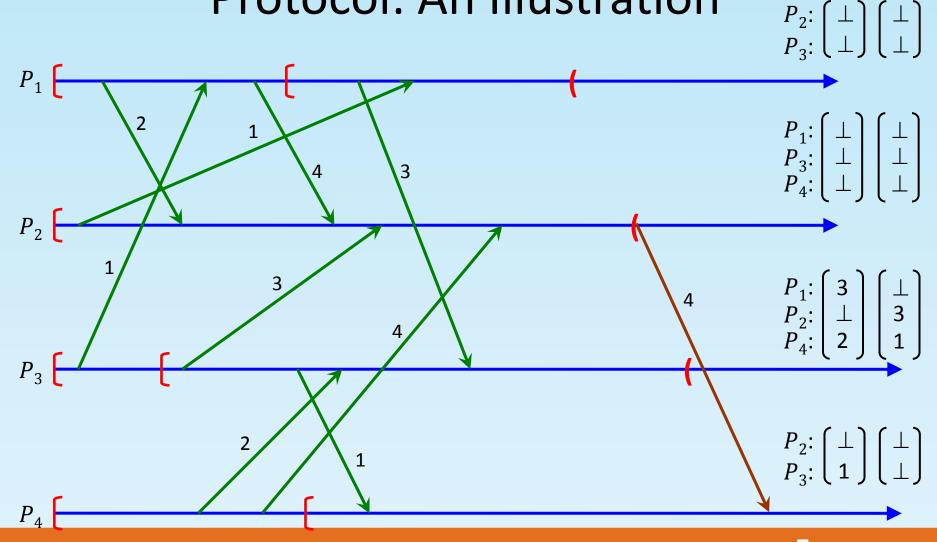


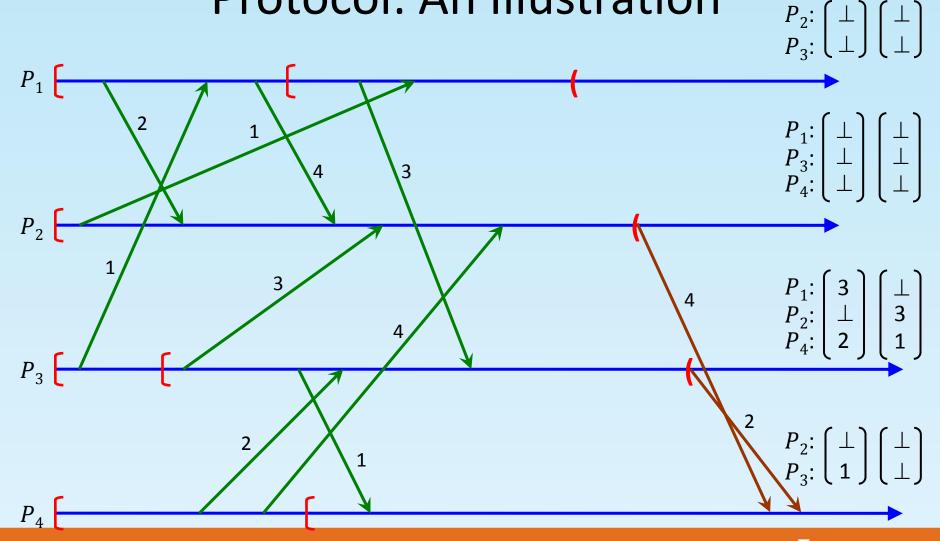


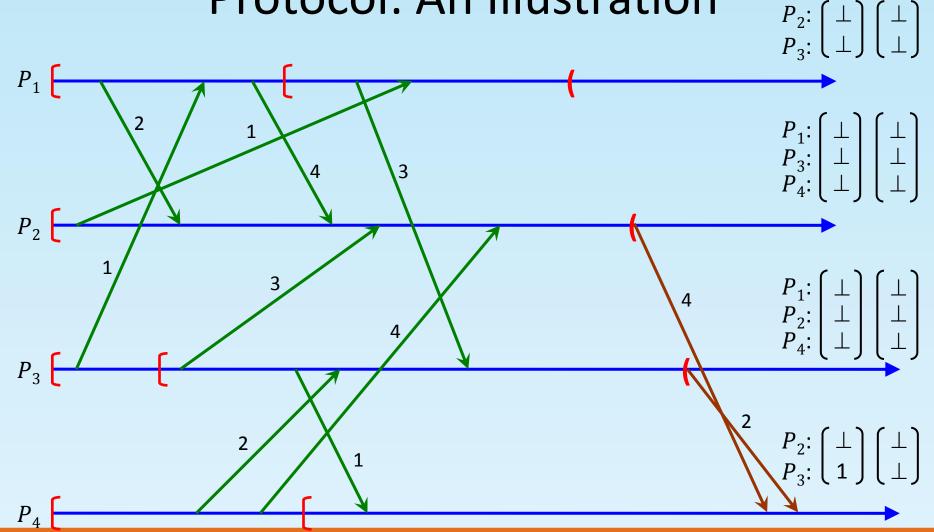


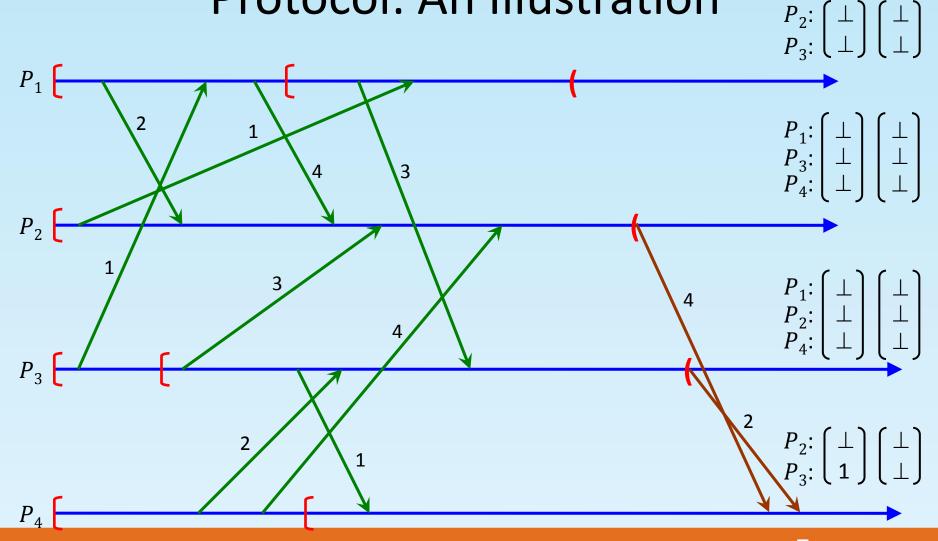


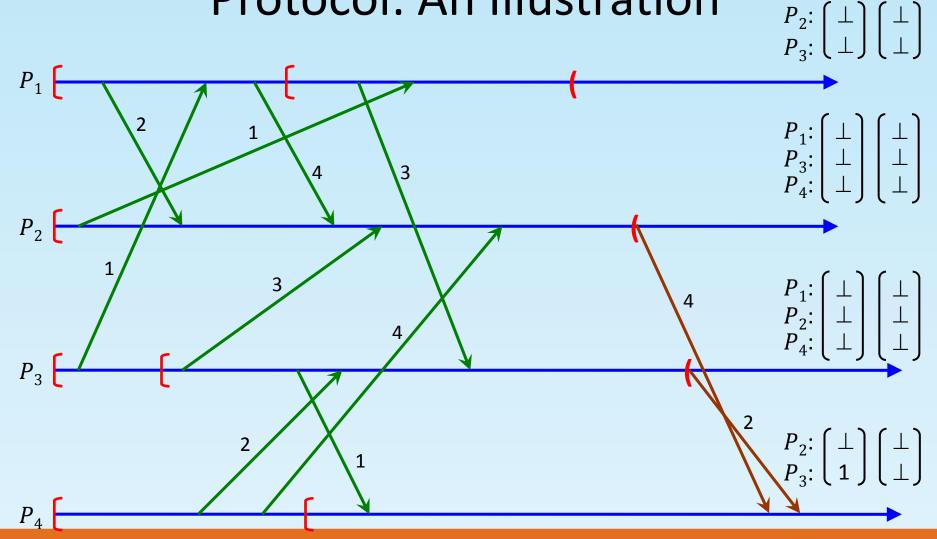


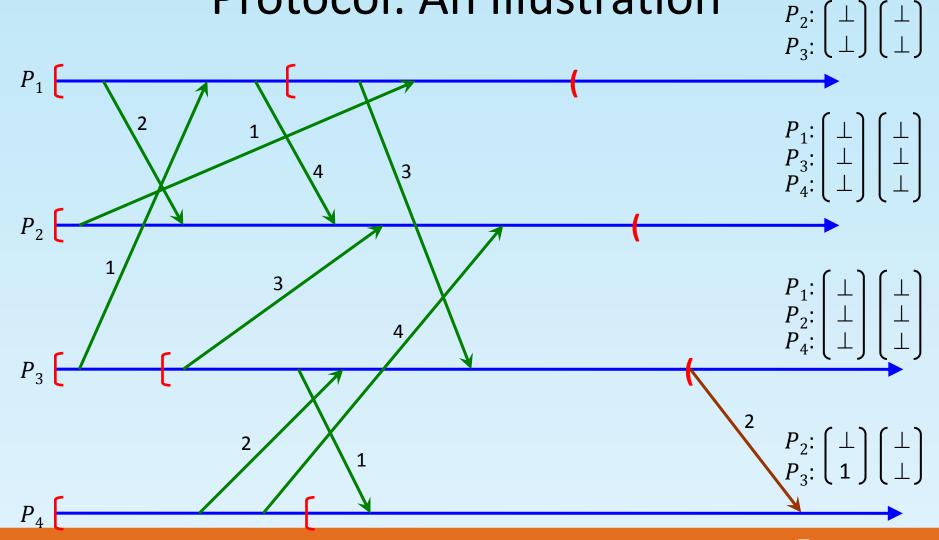


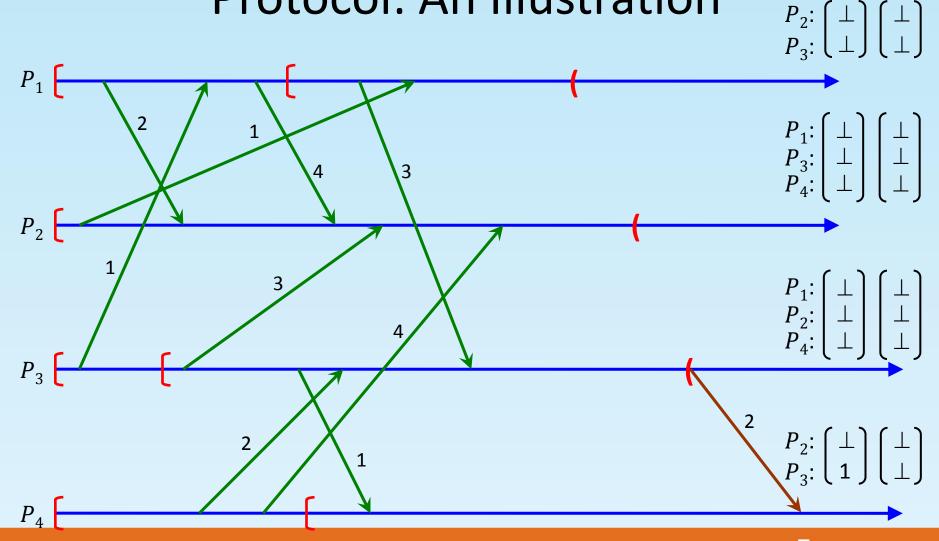


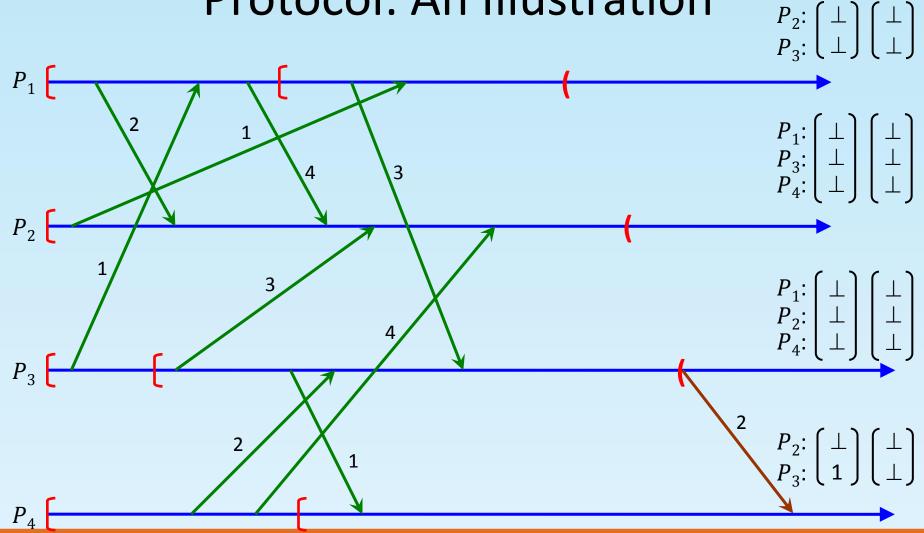


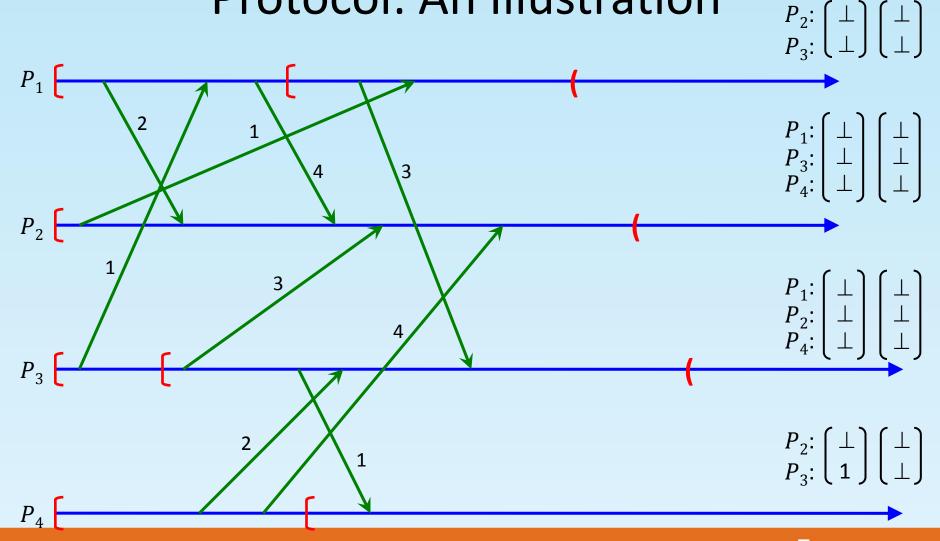


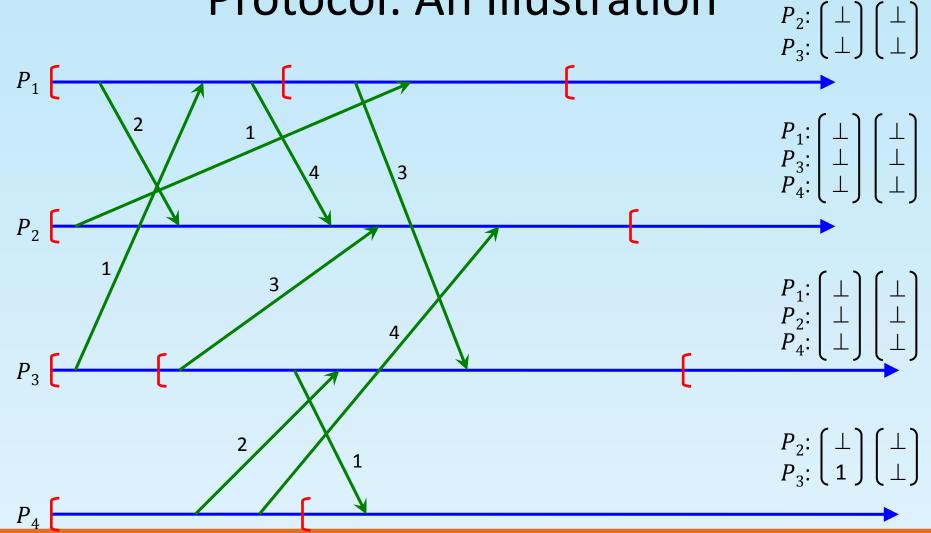


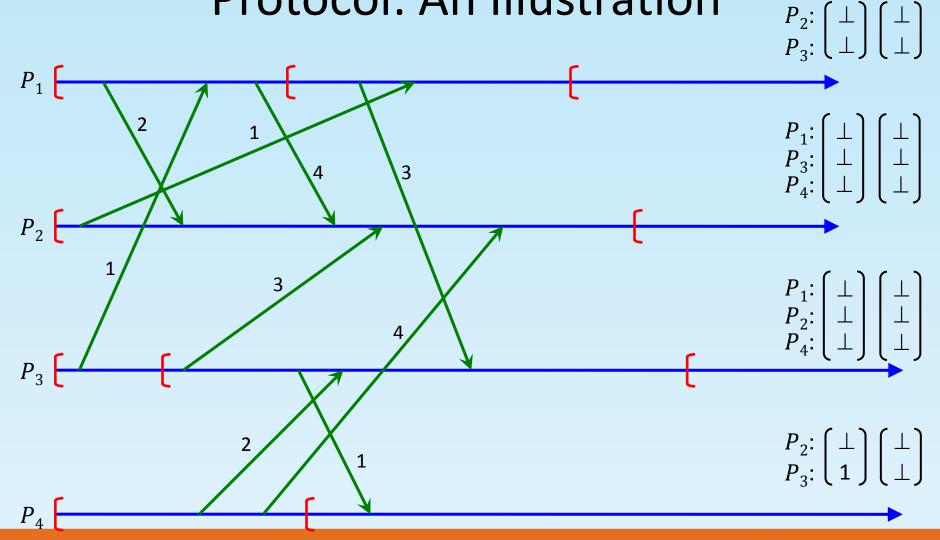












#### Koo and Toueg's Recovery Protocol

- Only permanent checkpoints are used in recovery
- Consists of two phases
  - First Phase:
    - Processes agree to roll back if they can
      - A process after agreeing to roll back stops its execution until the second phase completes
  - Second Phase:
    - If all required processes agree to roll back in the first phase,
       then they restart their execution from the last checkpoint
    - Otherwise, processes resume their execution from their current point



### Koo and Toueg's Recovery Protocol: Details

- Consider processes  $P_i$  and  $P_j$  that are neighbors
- Definition of last\_label\_senti[j]:
  - Let m be the last message that  $P_i$  sent to  $P_j$  before its last permanent checkpoint

$$last\_label\_senti[j] \triangleq \begin{cases} label \text{ of } m, & m \text{ exists} \\ \bot, & m \text{ does not exist} \end{cases}$$

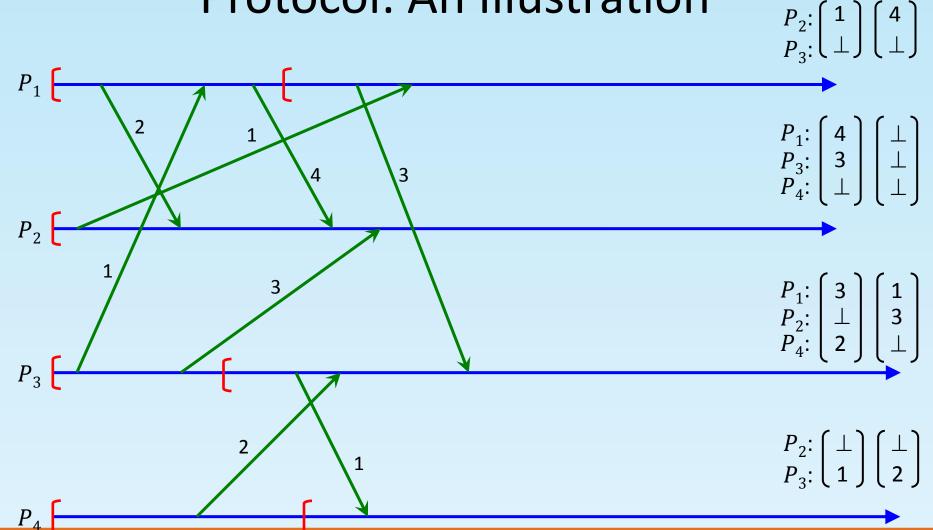


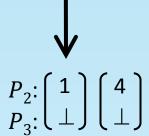
## Koo and Toueg's Recovery Protocol: Details (Contd.)

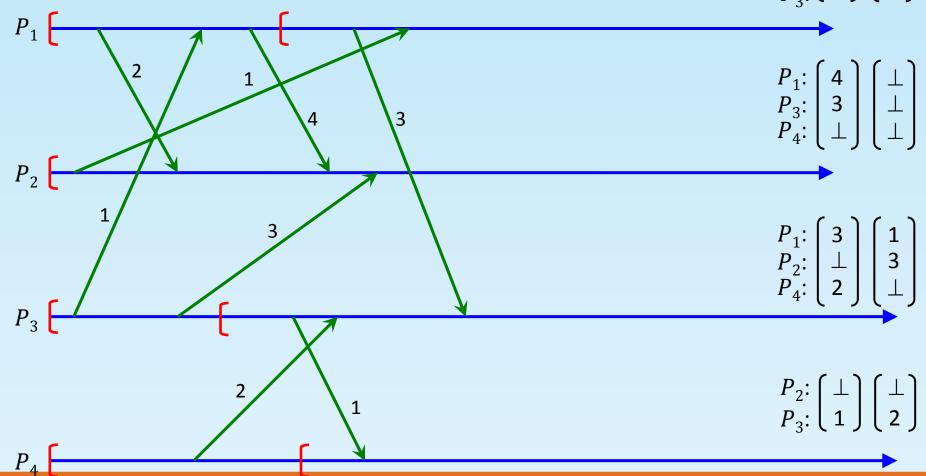
- Assume that  $P_i$  has agreed to roll back:
  - $-P_i$  requests  $P_j$  to roll back sends  $last\_label\_senti[j]$  to  $P_i$
  - $-P_i$  agrees to roll back if:

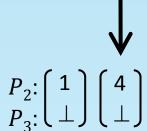
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last_label_rcvdj[i] > last_label_senti[j]
```

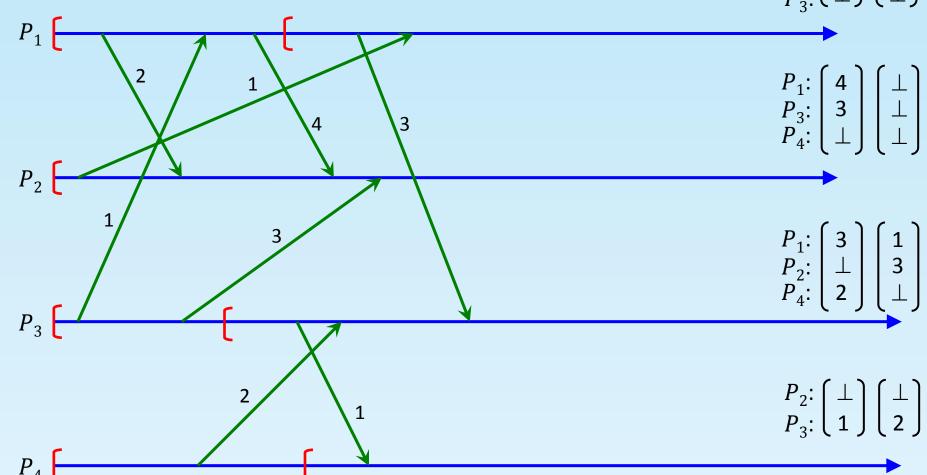


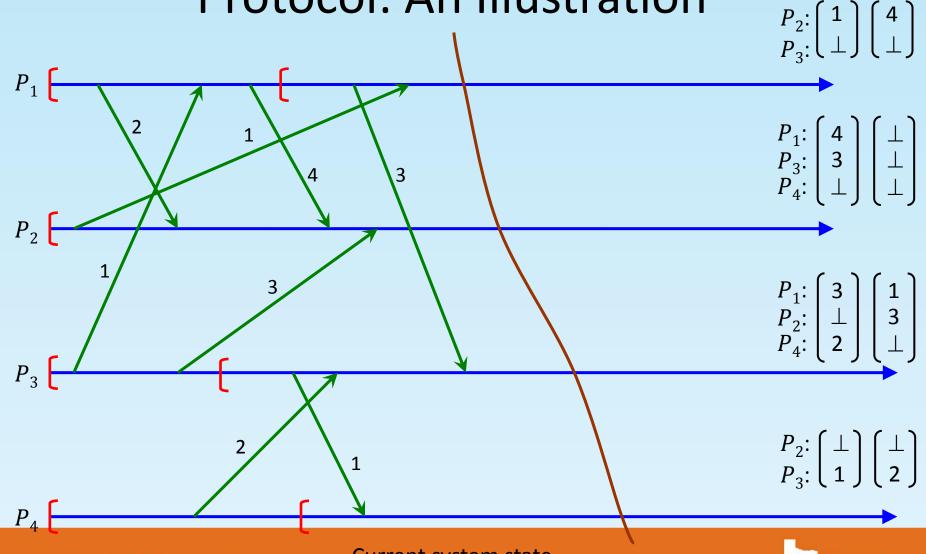




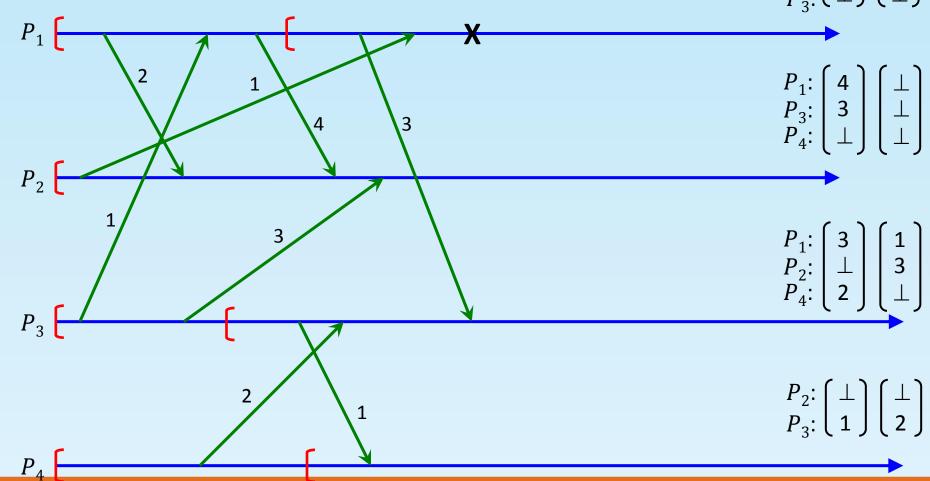


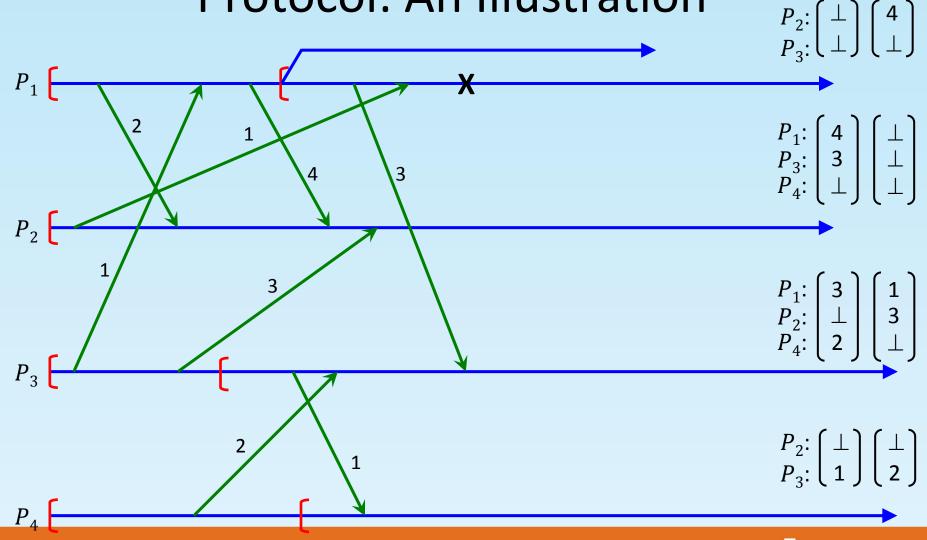


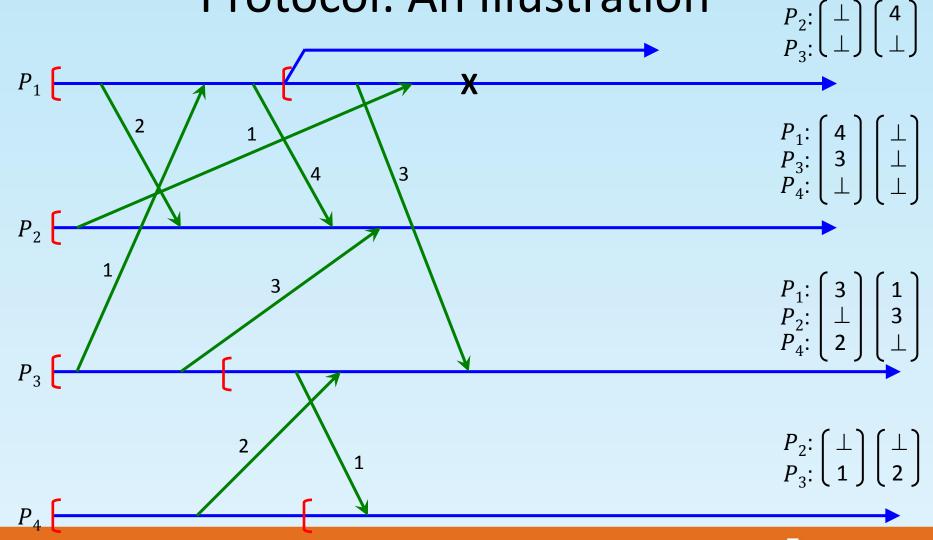


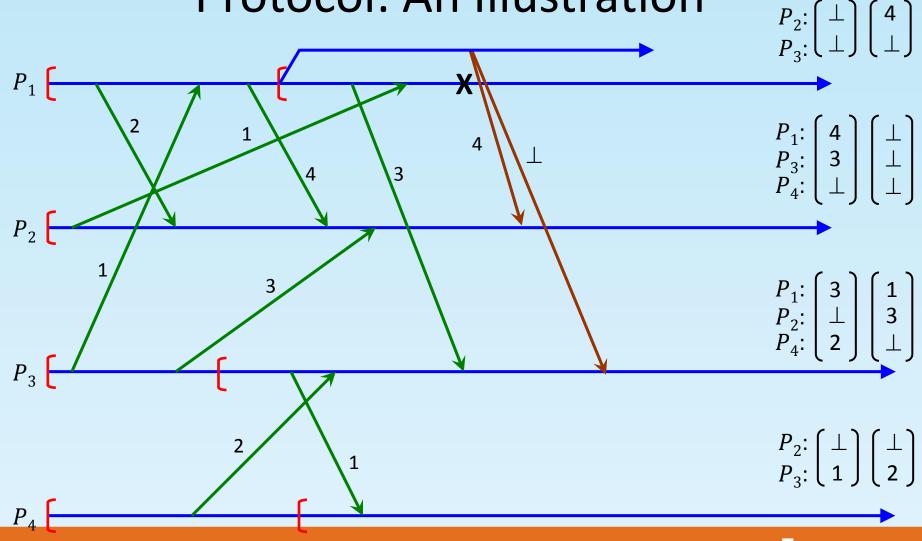


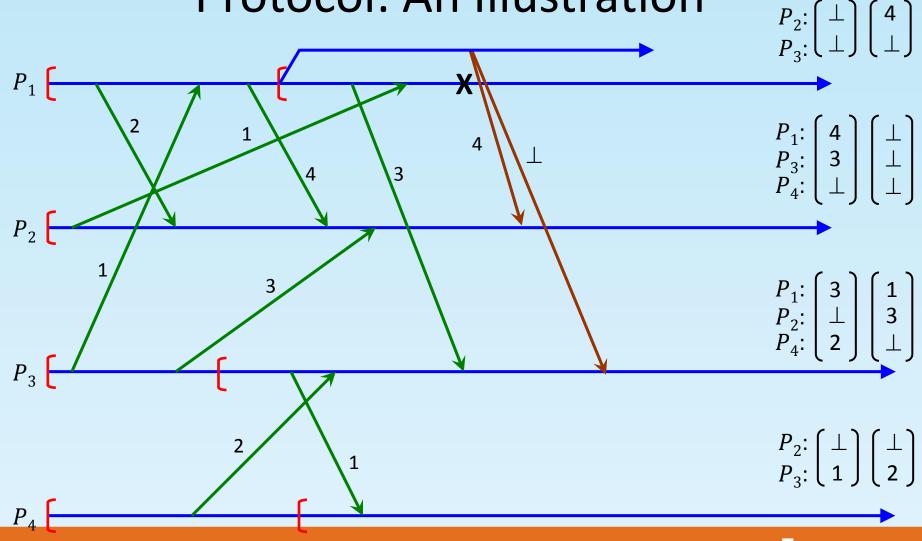


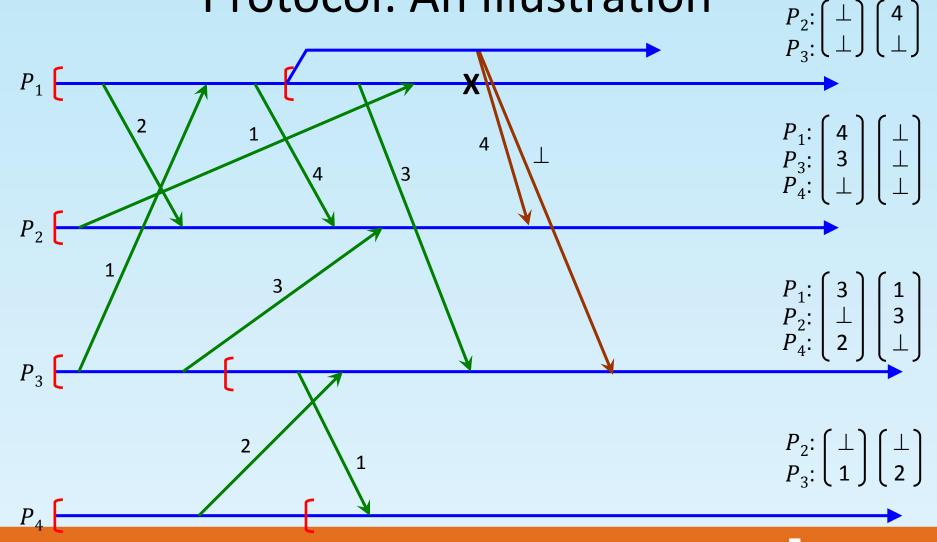


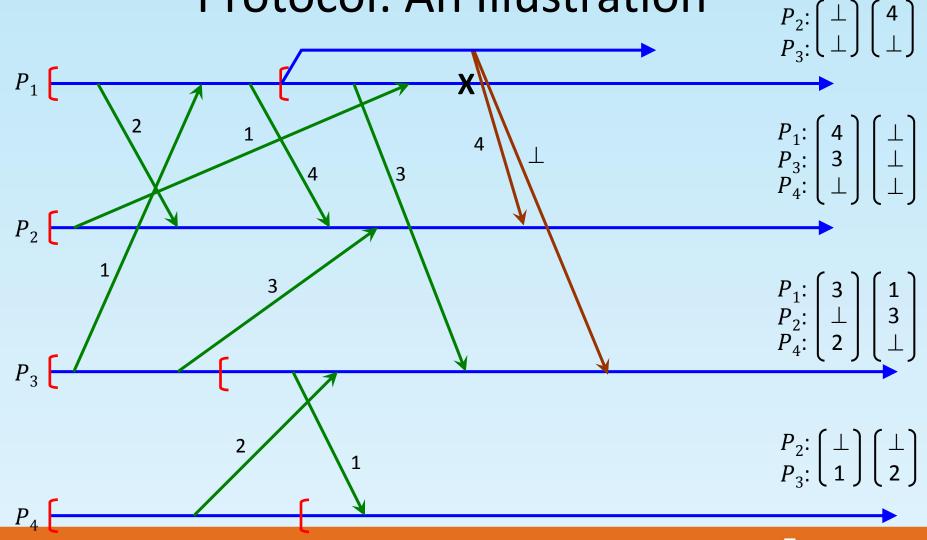


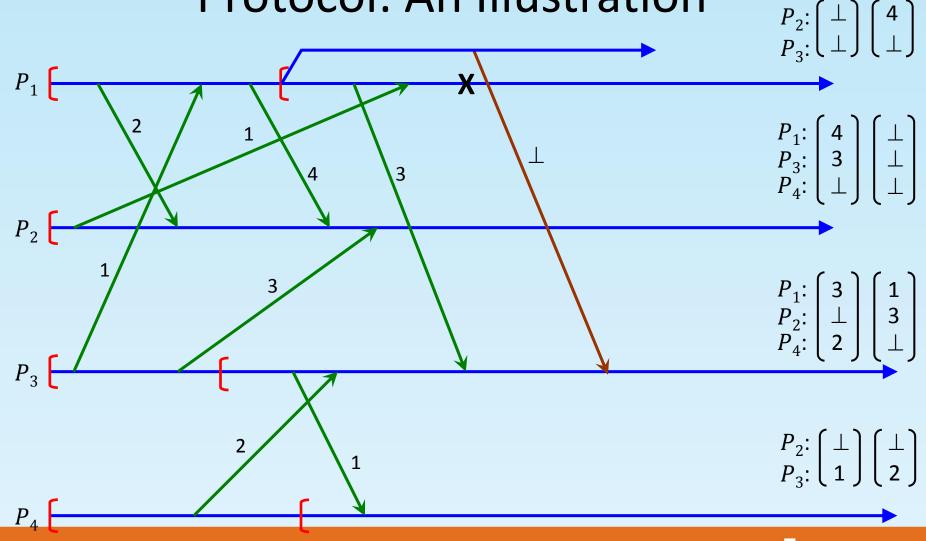


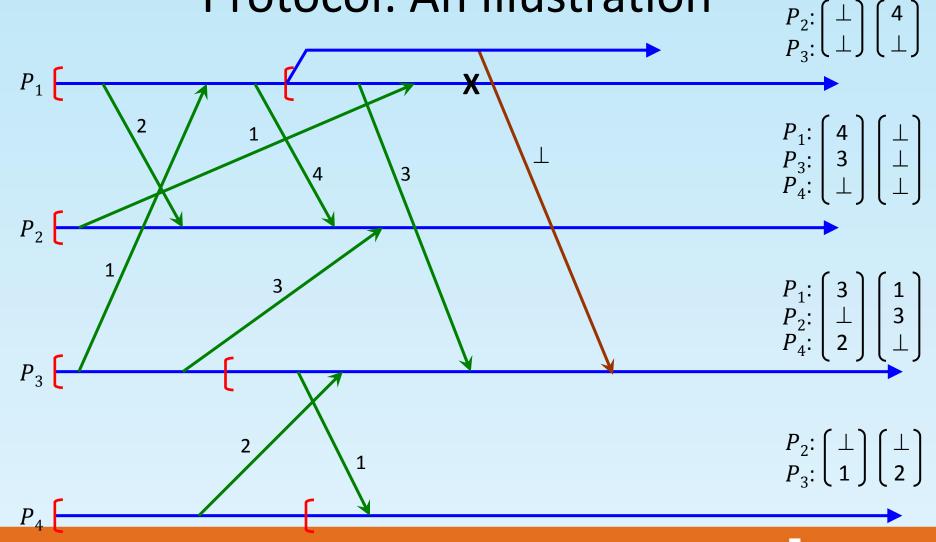


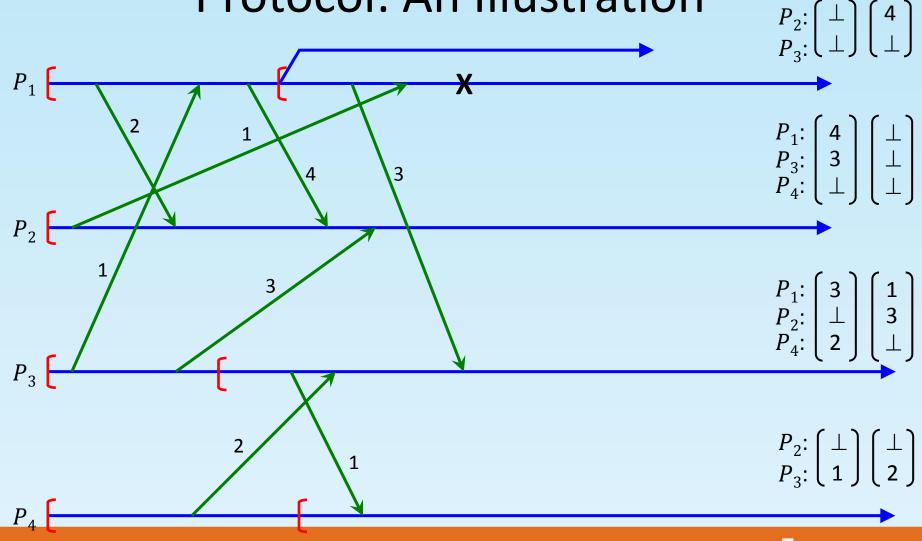


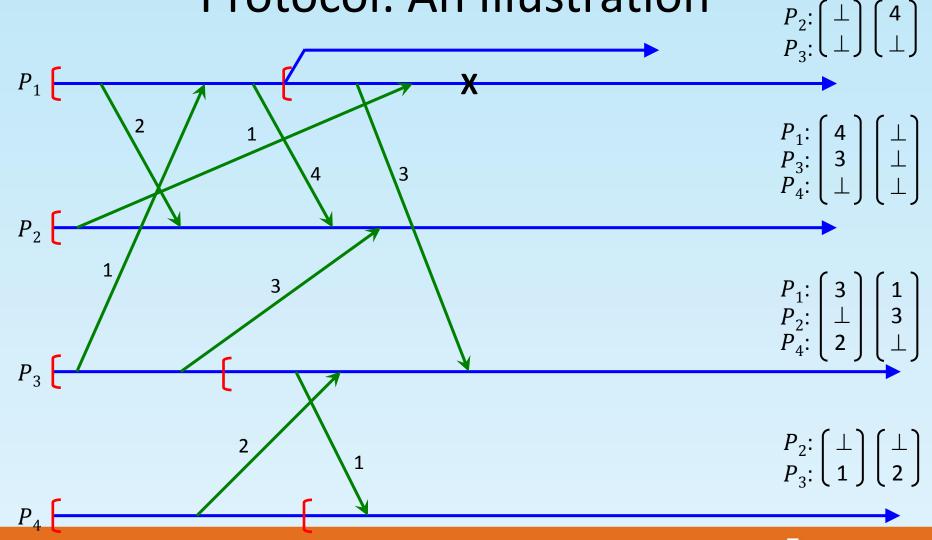


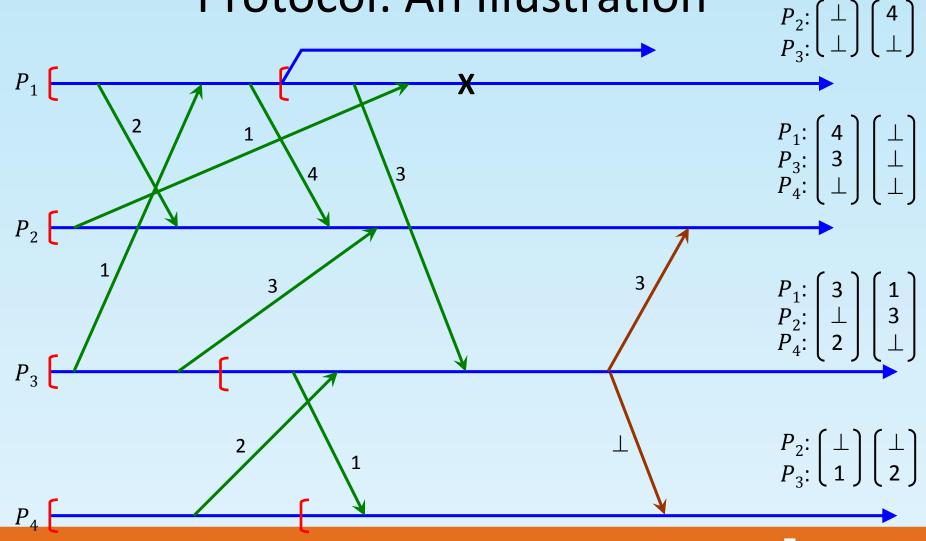


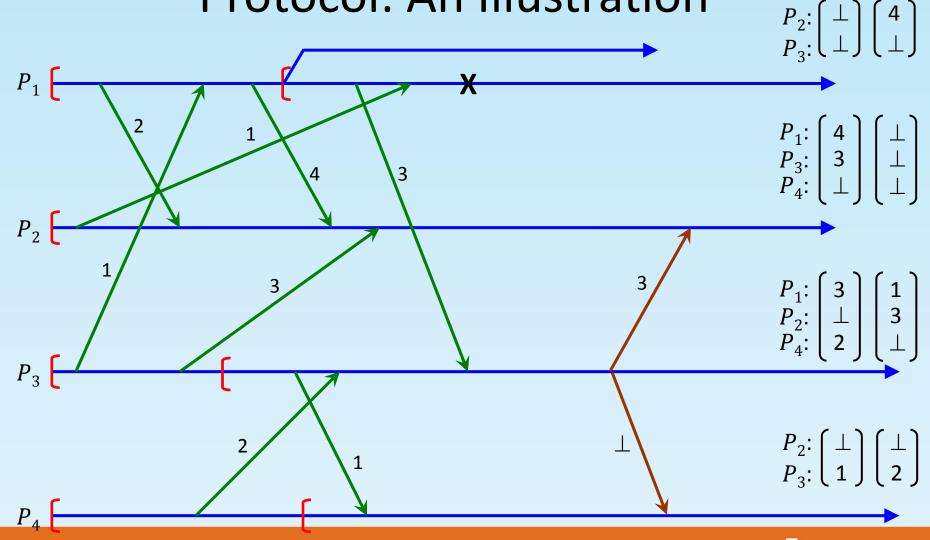


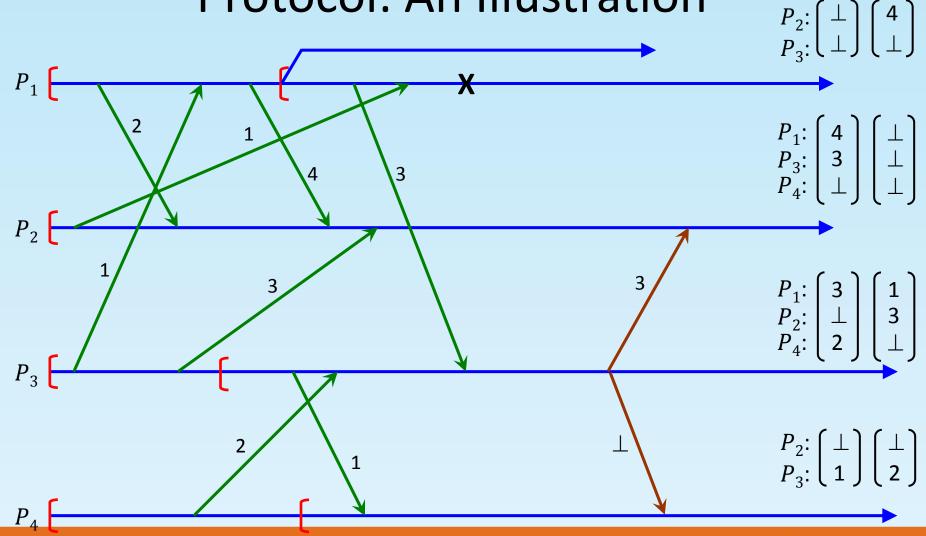


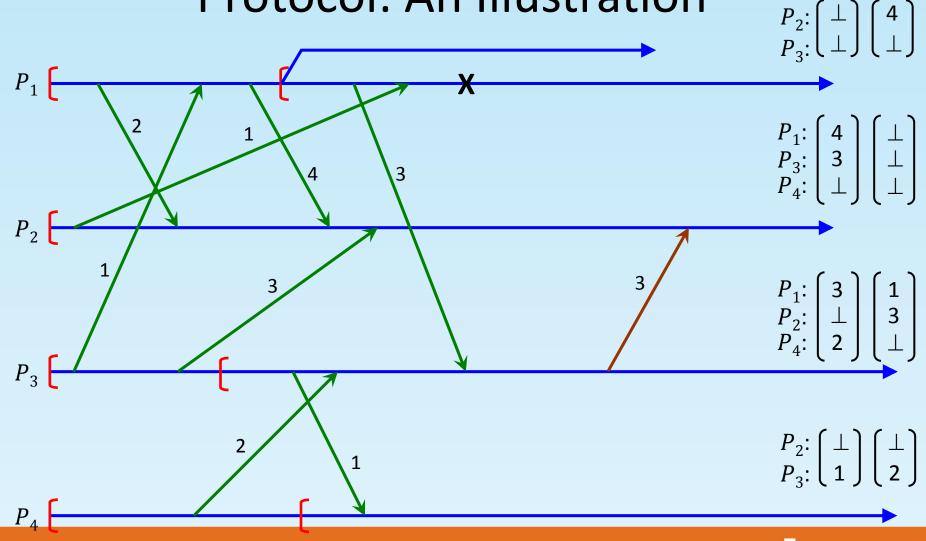


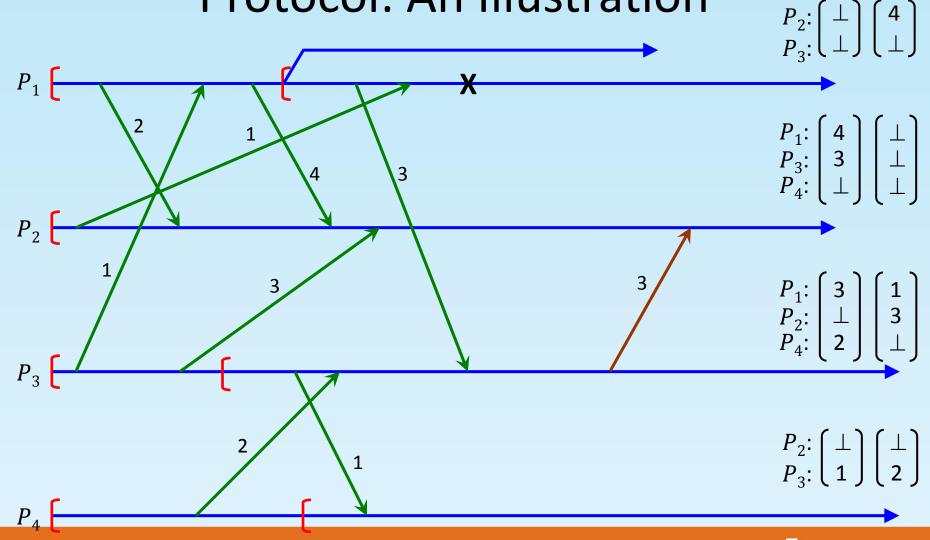


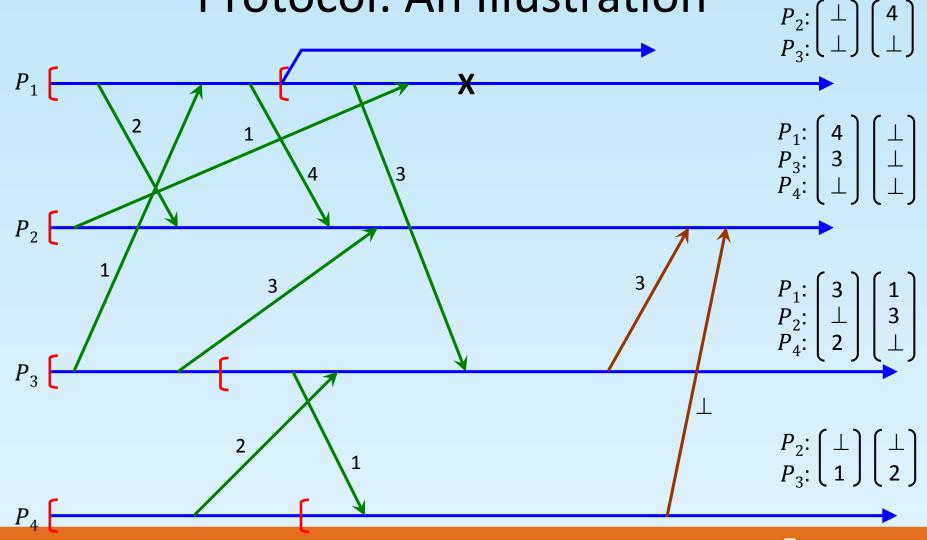


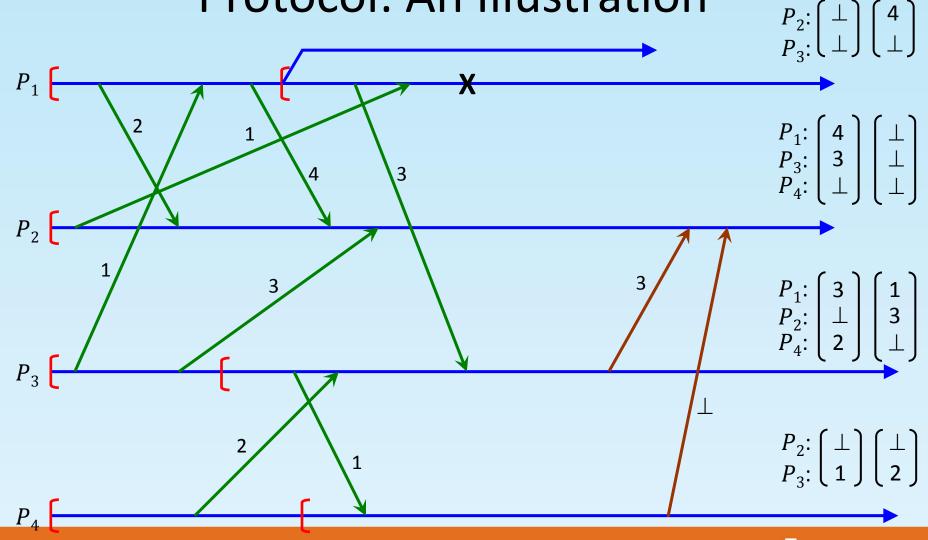


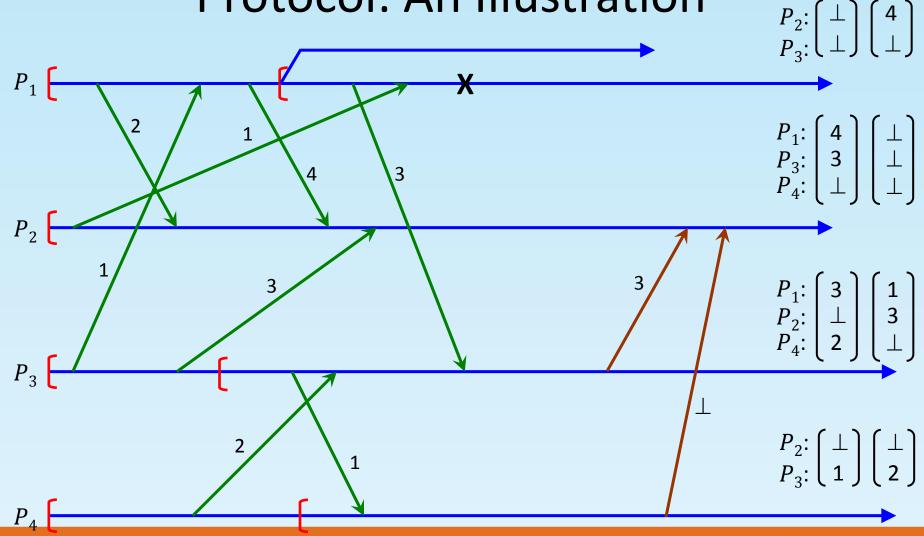


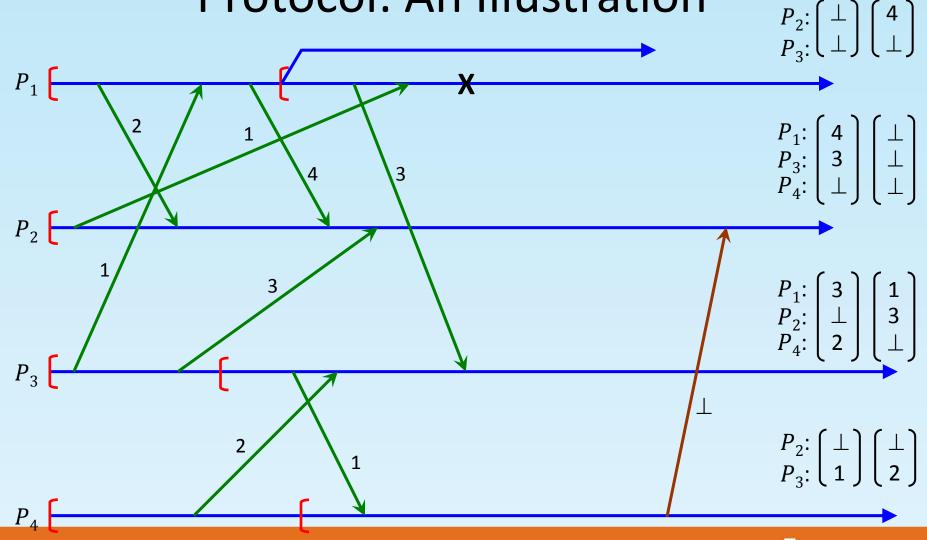


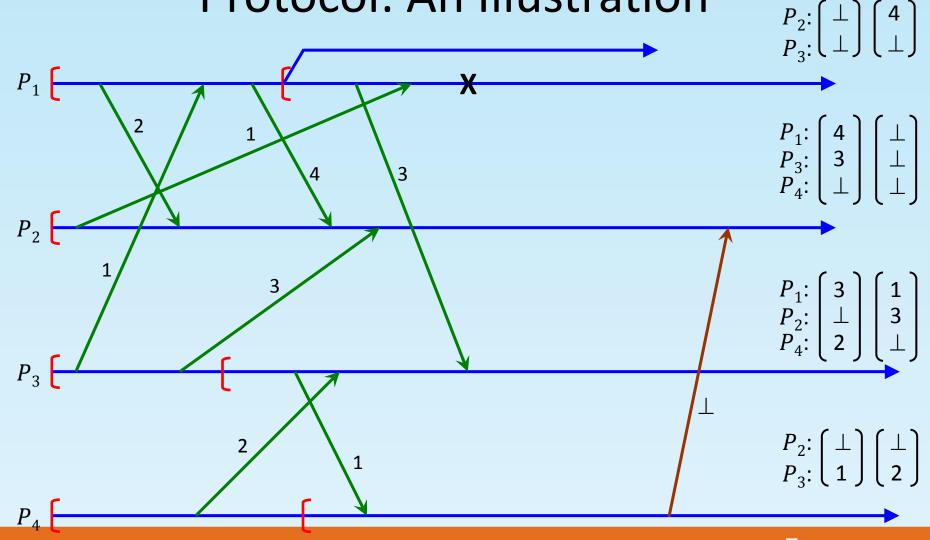


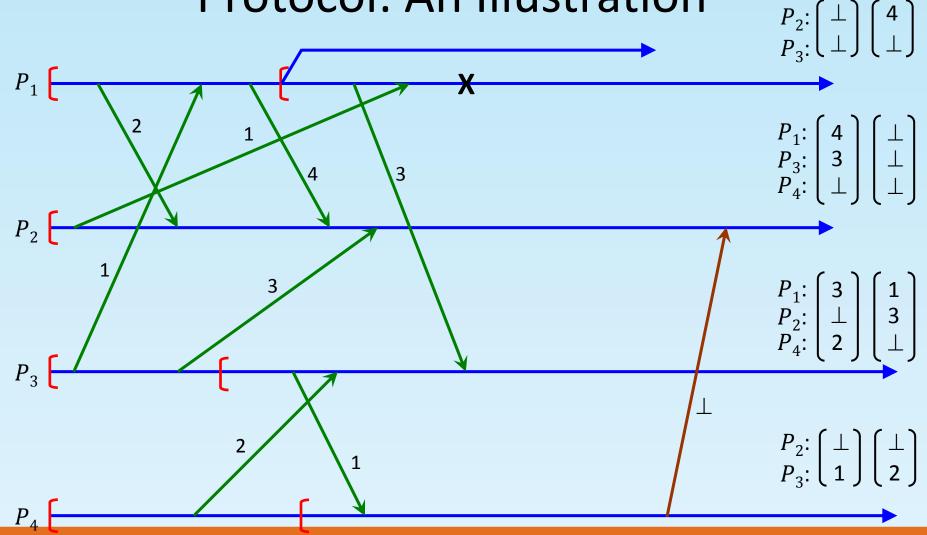


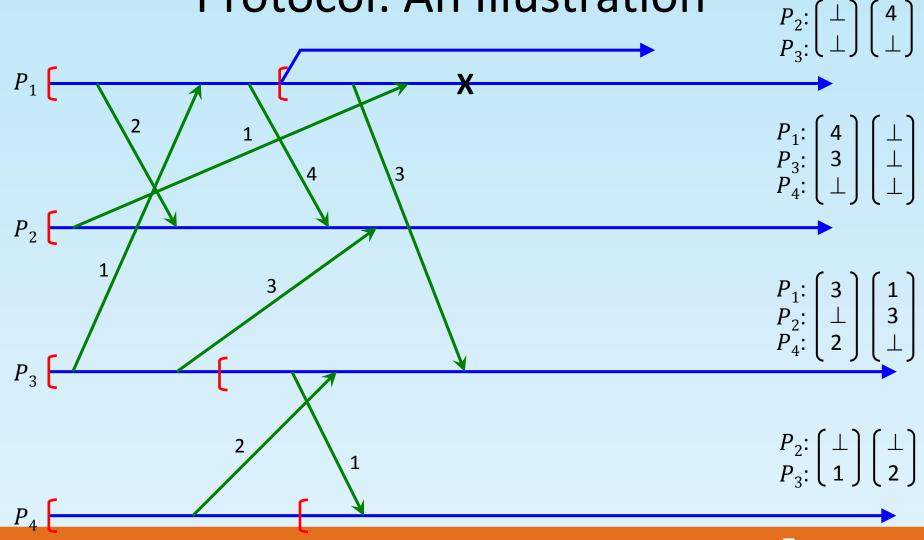


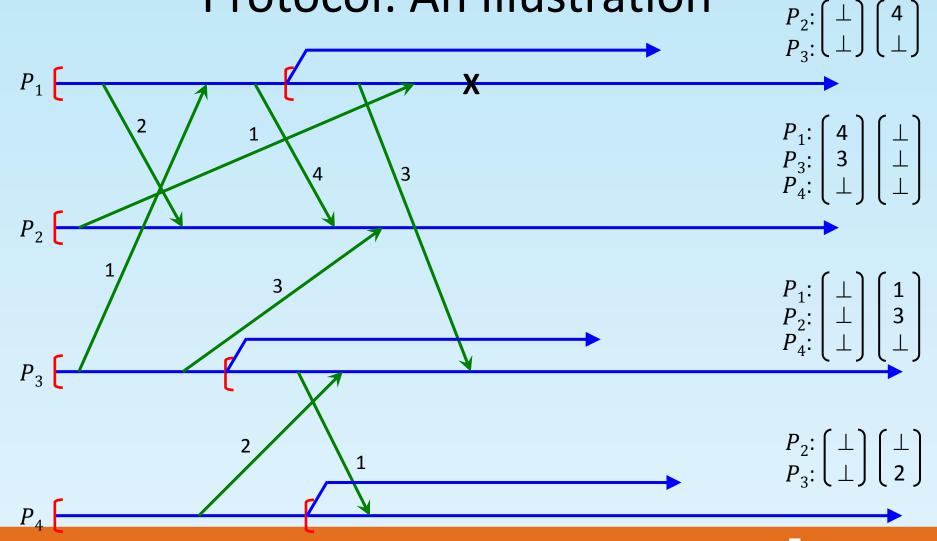


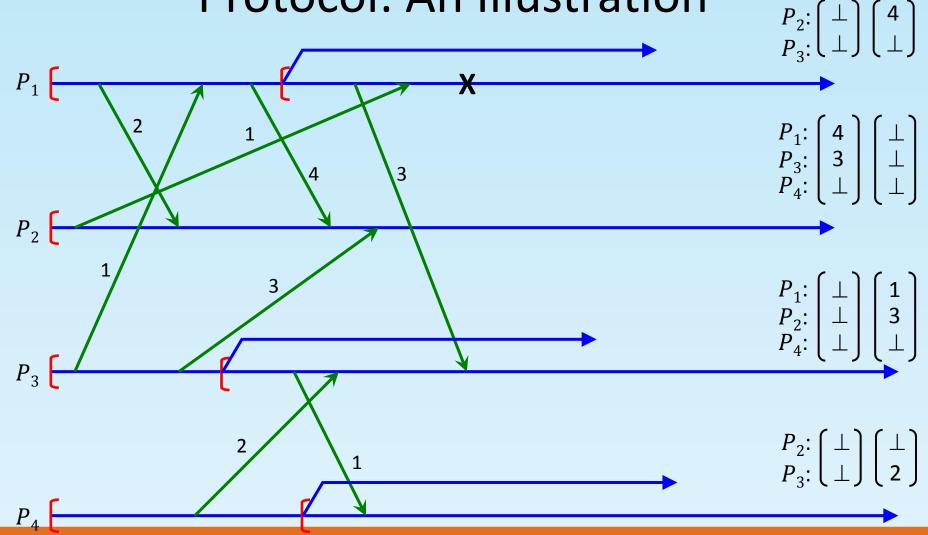


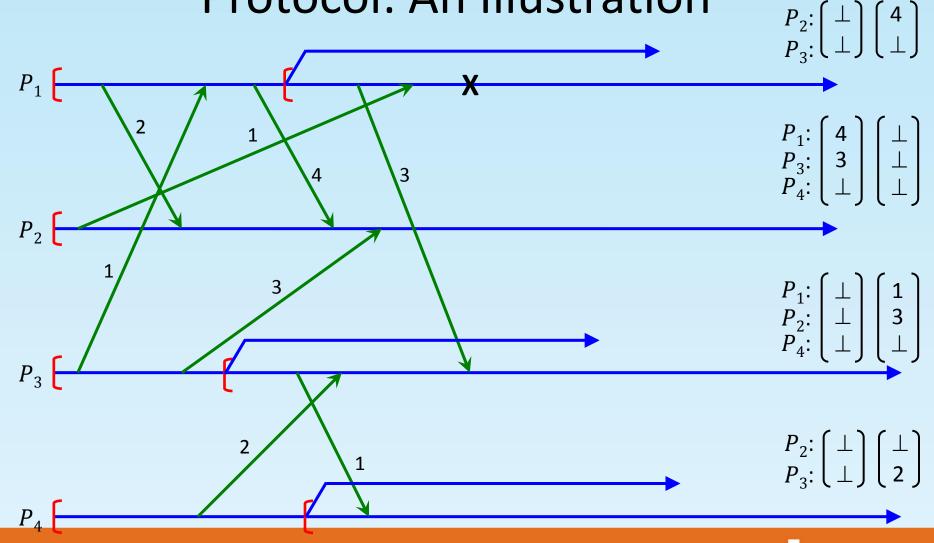












#### Outline

- Overview
- Main Issues
- Checkpointing and Recovery Protocols
  - Koo and Toueg's Protocol
  - Juang and Venkatesan's Protocol



#### Juang and Venkatesan's Checkpointing Protocol

- A process takes a checkpoint every time it executes a communication event
  - Checkpoints are taken in volatile storage
  - Periodically checkpoints in volatile storage are flushed to stable storage
  - A process loses checkpoints in its volatile storage when it fails
  - Other processes (that did not fail) still have access to checkpoints in volatile storage



#### Juang and Venkatesan's Recovery Protocol

- Each process maintains two vectors with one entry for every neighbor:
  - SENT: stores the number of messages sent to each neighbor so far
  - RCVD: stores the number of messages received from each neighbor so far



## Juang and Venkatesan's Recovery Protocol (Contd.)

• Consider a collection of checkpoints, one from each process  $P_1, P_2, ..., PN$ , given by:

$$ckpt_1, ckpt_2, ..., ckpt_N$$

• Checkpoints form a consistent global state if, for each pair of neighbors  $P_i$  and  $P_j$ , the following holds:

$$SENT(ckpt_i)[j] \geq RCVD(ckpt_i)[i]$$

- Otherwise,  $P_j$ 's state is inconsistent with that of  $P_i$ 
  - The inconsistency can be removed by rolling back  $P_i$



## Juang and Venkatesan's Recovery Protocol (Contd.)

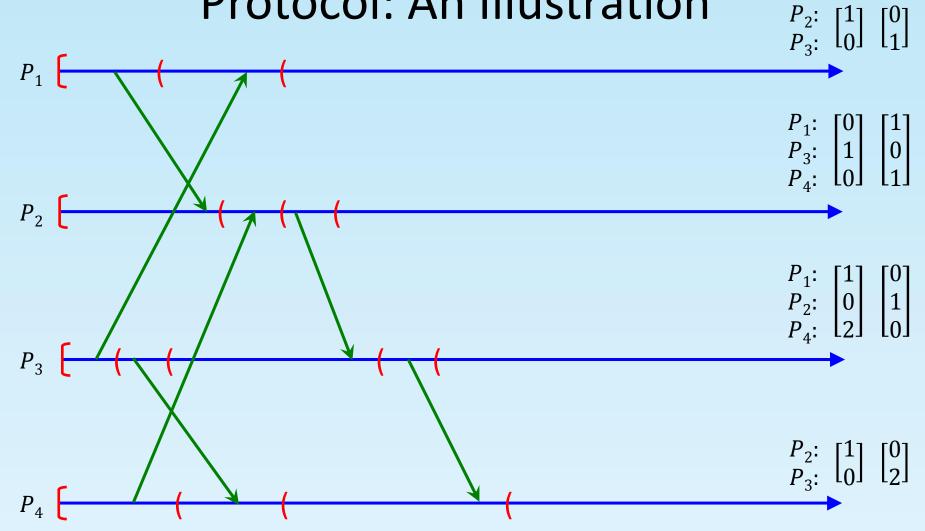
- All processes participate in recovery
  - Failed process, on restarting, rolls back to its last stable checkpoint and instructs all processes to start recovery using flooding
- Recovery protocol executes in iterations
- In each iteration, every process sends to each of its neighbors the number of messages it has sent to it as per the current state
  - A process rolls back if its state is inconsistent with that of its neighbor. It rolls back to its latest checkpoint (volatile or stable) that removes the inconsistency

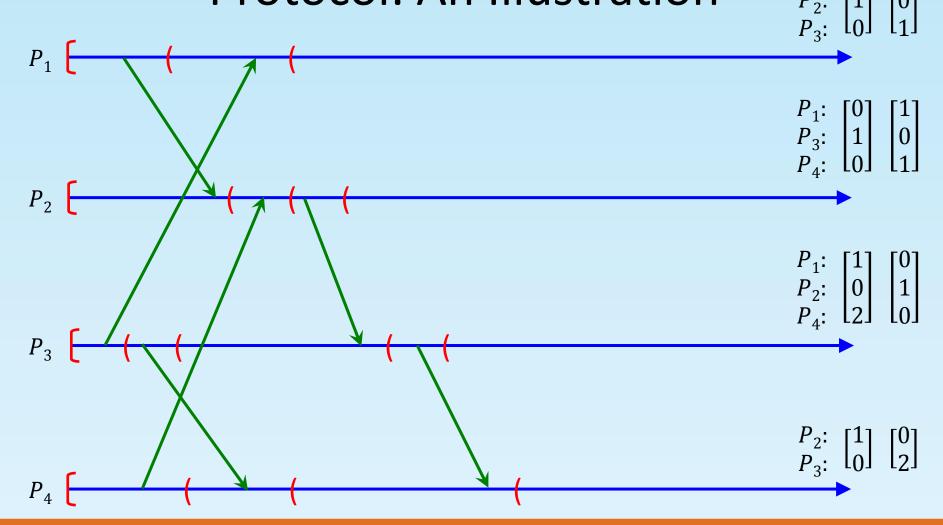


### Juang and Venkatesan's Recovery Protocol (Contd.)

- Let N denote the number of processes in the system
  - The system is guaranteed to be in a consistent state after N-1 iterations







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