

Q no 1

Given points

$$(1, 3), (2, 7), (-1, 1)$$

$$(x_0, y_0), (x_1, y_1), (x_2, y_2)$$

Now

we have the standard form

Given by

$$P_n(x) = a_0 + a_1x + \dots + a_nx^n$$

since we only have 3 points,
our standard form will be

$$P_2(x) = a_0 + a_1x + a_2x^2 \text{ where } a_0, a_1, \text{ \& } a_2 \text{ are to be determined.}$$

Now,

$$P_2(x_0) = a_0 + a_1x_0 + a_2x_0^2 = y_0$$

$$P_2(x_1) = a_0 + a_1x_1 + a_2x_1^2 = y_1$$

$$P_2(x_2) = a_0 + a_1x_2 + a_2x_2^2 = y_2$$

Then, we can obtain,

$$M = \begin{bmatrix} 1 & x_0 & x_0^2 \\ 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \end{bmatrix}, \quad a = \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix}$$

$$Ma = \begin{bmatrix} y_0 \\ y_1 \\ y_2 \end{bmatrix}$$

we can solve the above equation to obtain a ,

Hence, a_2

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 1 & -1 & 1 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 7 \\ 1 \end{bmatrix}$$

$$\text{or, } \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Hence, $p_2(x) = 1 + x + x^2$ is required

system of polynomial of degree 2.

Again writing the polynomial in terms of Lagrange interpolants $L_k(x)$

Now,

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we have,

$$P_n(x) = y_0 L_0(x) + y_1 L_1(x) + \dots + y_n L_n(x)$$

For our case,

$$P_2(x) = y_0 L_0(x) + y_1 L_1(x) + y_2 L_2(x)$$

Solving for Lagrange interpolants,

where,

$$\begin{aligned} L_0(x) &= \frac{(x-x_1)(x-x_2)}{(x_0-x_1)(x_0-x_2)} \\ &\Rightarrow \frac{(x-2)(x+1)}{(1-2)(2+1)} \\ &= \frac{x^2 - x - 2}{-2} \end{aligned}$$

$$\begin{aligned} L_1(x) &= \frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)} \\ &= \frac{(x-1)(x+1)}{(2-1)(2+1)} = \frac{x^2 - 1}{3} \end{aligned}$$

$$L_2(x) = \frac{(x-x_0)(x-x_1)}{(x_2-x_0)(x_2-x_1)} = \frac{x^2 - 3x + 2}{6}$$

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putting back to original equation.

$$P_2(x) = \frac{3(x^2 - x - 2)}{-2} + \frac{7(x^2 - 1)}{3} + \frac{(x^2 - 3x + 2)}{6}$$

$$\Rightarrow x^2 \left(-\frac{3}{2} + \frac{7}{3} + \frac{1}{6} \right) + x \left(\frac{3}{2} - \frac{1}{2} \right) +$$

$$\frac{6}{2} - \frac{7}{3} + \frac{1}{3}$$

$$\Rightarrow x^2 + x + 1$$

Hence, Both methods are giving the same polynomial system of degree 2.

Qno 3problem 3Given data set

k	0	1	2	3
x_k	0.1	0.3	0.5	0.7
y_k	1.1	1.25	1.17	1.31

Solution

we have,

$$Q_{i,J}(x) = \frac{(x - x_{i-J}) Q_{i,J-1}(x) - (x - x_i) Q_{i-1,J-1}(x)}{x_i - x_{i-J}}$$

$J = 1, 2, \dots, i$ and $0 \leq J \leq i$

where, $Q_{i,J}(x)$ is degree- J interpolating polynomial on the $(J+1)$ positions

Now, $Q_{k,0}(x) = y_k$, so

$$\begin{aligned} Q_{0,0}(x) &= y_0 = 1.1 \\ Q_{1,0}(x) &= y_1 = 1.25 \\ Q_{2,0}(x) &= y_2 = 1.17 \\ Q_{3,0}(x) &= y_3 = 1.31 \end{aligned}$$

Again Using recursive point wise evaluation of the interpolation polynomials:

Q_i The approximation are:

$$Q_{2,1}(0.45) = \frac{(0.45 - 0.3)(1.17) - (0.45 - 0.5)(1.25)}{0.5 - 0.3}$$

where
 $(Q_{i,j-1})(x) = 1.17$

$Q_{i-1,j-1}(x) = 1.25$

$$\Rightarrow \frac{0.238}{0.2}$$

$$\Rightarrow 1.19$$

$$Q_{3,1}(0.45) = \frac{(0.45 - 0.5)(1.31) - (0.45 - 0.7)(1.17)}{0.7 - 0.5}$$

$$\approx \frac{0.227}{0.2}$$

$$\approx 1.135$$

$$Q_{2,2}(0.45) = \frac{(0.45 - 0.1)(1.19) - (0.45 - 0.5)(1.362)}{0.5 - 0.1}$$

$Q_{1,1}(0.45)$ is
calculated
in
next page.

$$\Rightarrow \frac{0.4846}{0.4}$$

$$\Rightarrow 1.211$$

$$Q_{3,2}(0.45) = \frac{(0.45 - 0.3)(1.135) - (0.45 - 0.7)(1.19)}{0.7 - 0.3}$$

$$= \frac{0.46775}{0.4}$$

$$\Rightarrow 1.169$$

$$Q(1,1)(0.45) = \frac{(0.45 - 0.1)(1.25) - (0.45 - 0.3)(1.1)}{0.3 - 0.1}$$

$$= \frac{0.2725}{0.2}$$

$$\Rightarrow 1.362$$

Hence

we have,

$Q(1,1)(0.45)$	1.362
$Q(2,1)(0.45)$	1.19
$Q(3,1)(0.45)$	1.135
$Q(2,2)(0.45)$	1.211
$Q(3,2)(0.45)$	1.167