Updates: Friday, Mar 18, 2022  
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**Updates:**

0. Updated Planner – weekly goals- status

1. Current: Open,   
 Our approach: Closed – Euclidean dist., creating new planner, new files, Modifing functions and codes, code not working, currently in debugging stage: ~3000 line code and multiple files.  
  
2. Talked to Chintan to undersstand his approach of geodesic implementation.  
Discuss his approach vs our appraoch  
  
3. Geodesic meshing random node numbering:   
 - Creates nodes and assigns random numbering  
 -finding out a way to create graph of nodes and coordinates