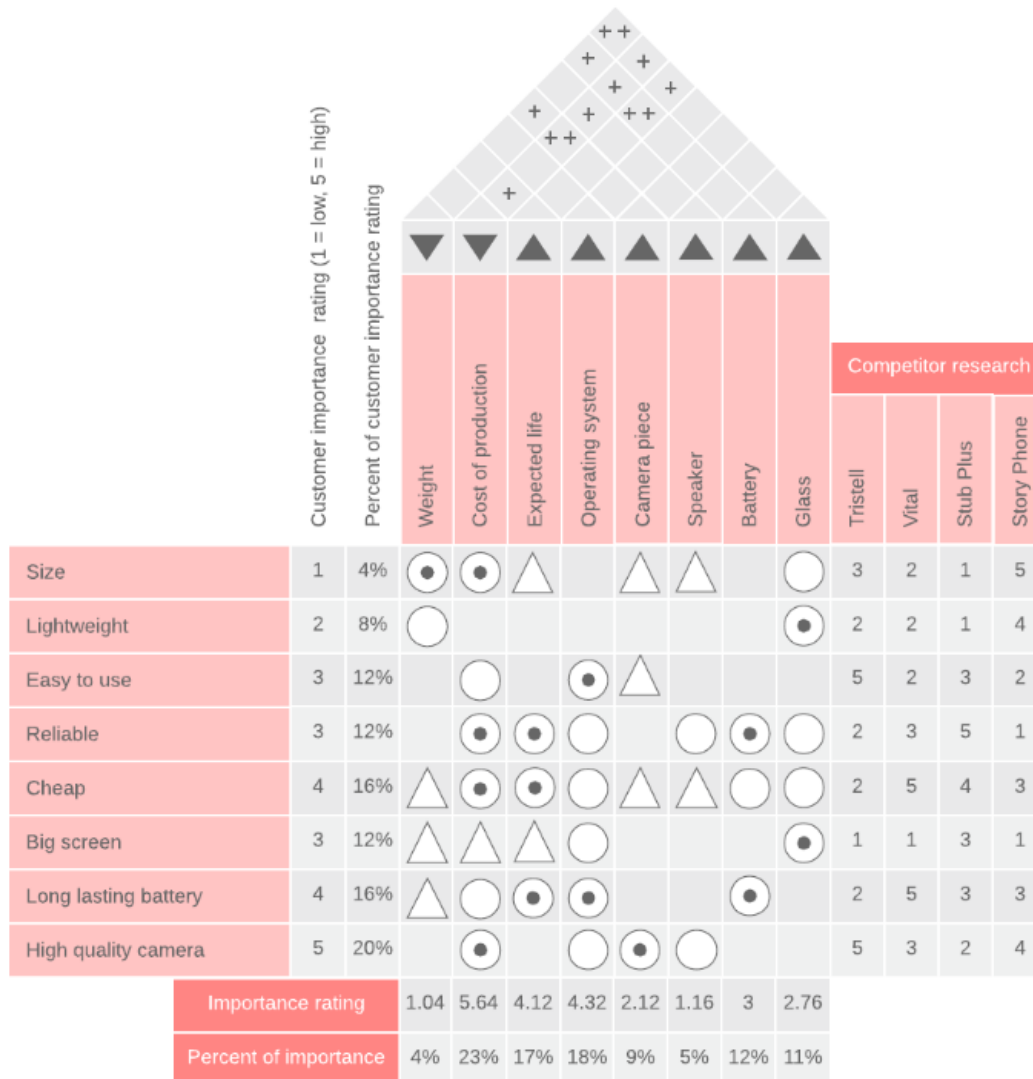
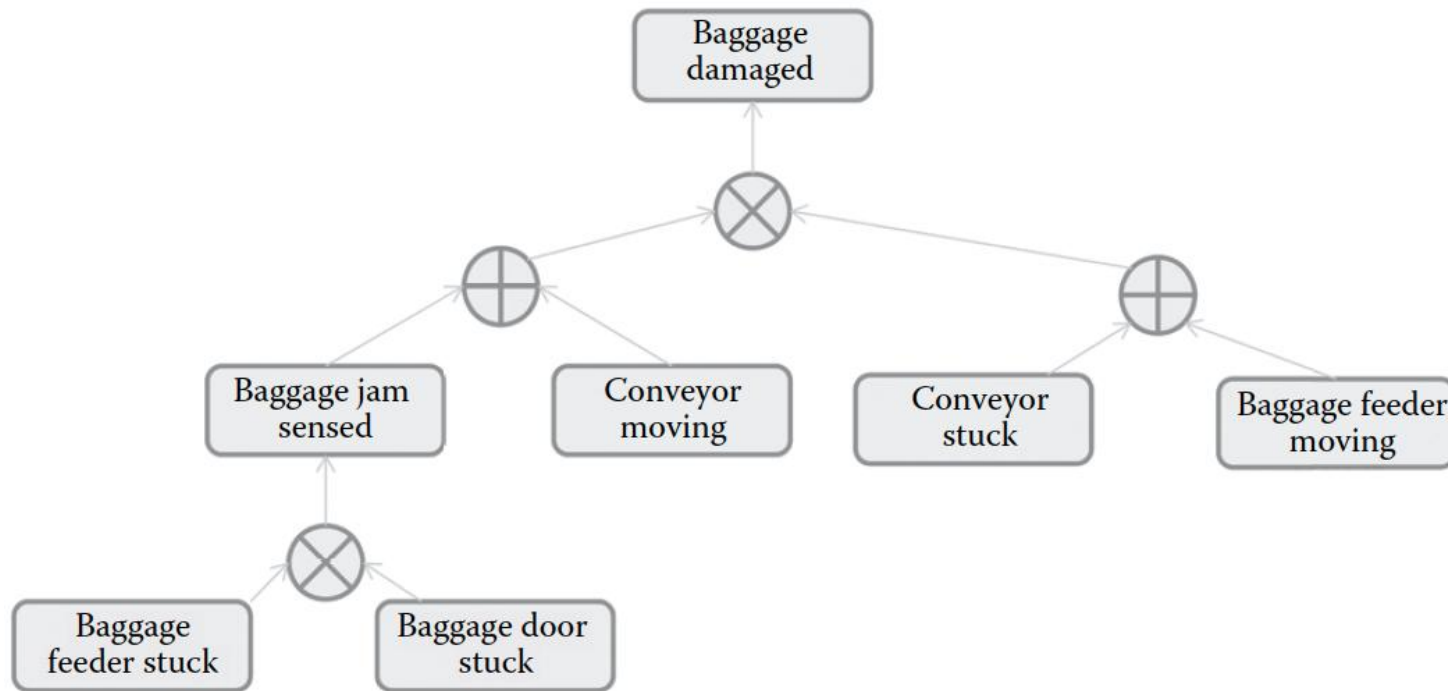


# Lecture Recap



Relationship matrix		
●	Strong	9
○	Medium	3
△	Weak	1
	No assignment	0

Correlation matrix	
++	Strong positive
+	Positive
-	Negative
--	Strong negative
	Not correlated



- The fault tree leads us to write the following raw requirements:
  - If a baggage jam is sensed, then the conveyor shall not move.
  - If the baggage feeder is stuck, then the conveyor shall not move.
  - If the baggage door is stuck, then the conveyor shall not move.
  - If the conveyor is stuck, then the baggage feeder should not move.

U

O

W

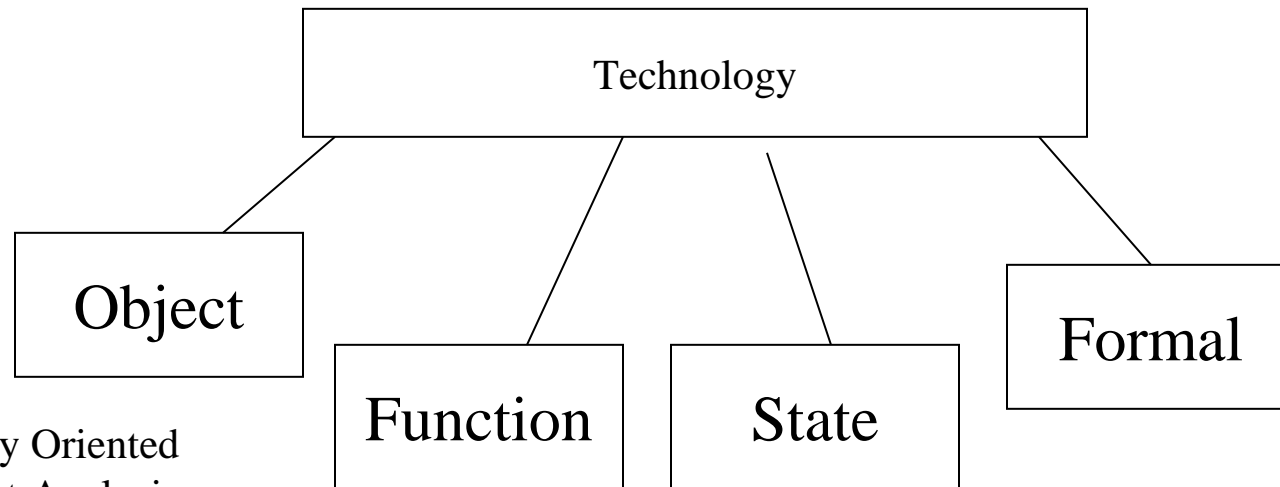
# Software Requirements, Specifications and Formal Methods

Dr. Shixun Huang



UNIVERSITY  
OF WOLLONGONG  
AUSTRALIA

# Methods for Requirements Engineering



- Ontology Oriented Requirement Analysis
- Concurrent Design Approach for Real-time System

- **Dataflow diagrams**
- **Sequence diagrams**
- Decision table
- Process specification
- Specification and Description Graphs
- Structure Analysis and Design Technique diagrams

- **Finite State Machine**
- **Petri nets**
- State chart

- **Petri nets** Constraint Satisfaction Problem
- Vienna Development Method
- **Z notation**



# Requirement Modeling Strategies

- One approach, called *structured analysis*, considers data and the processes that transform the data as separate entities.
  - Processes that manipulate data objects are modeled in a manner that shows how they transform data as data objects flow through the system.
- Another approach, called *object-oriented analysis*, focuses on
  - The definition of classes and
  - Relationship between them.



# Functional (Structural) Analysis (Data-flow modeling)

Data-flow approaches use data-flow diagrams (DFD) to graphically represent the external entities, processes, data-flow, and data stores.



# Data Flow Diagram

A diagram that specifies the processes (also referred as bubbles, transforms, transitions, activities, operations) and flow of data between them is called a Data Flow Diagram (DFD).

A DFD exhibits possible forms of information flow in a system, storage locations for data, and transformations of data as it flows through a system.



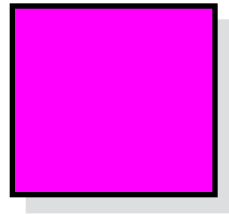
# The Flow Model

Every computer-based system is an information transform ....

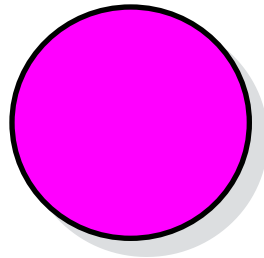




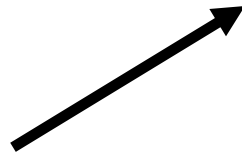
# Flow Modeling Notation



**external entity**



**process**



**data flow**



**data store**



# External Entity



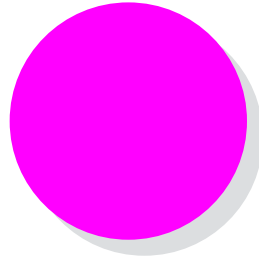
**A producer or consumer of data**

*Examples: a person, a device, a sensor*

*Data must always originate from somewhere  
and must always be sent to somewhere*



# Process

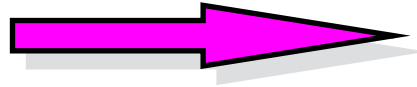


**A data transformer (changes input to output)**

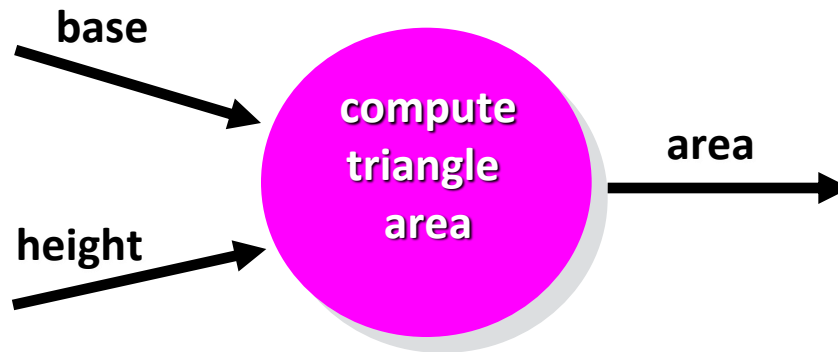
Examples: *compute taxes, determine area, format report, display graph*

*Data must always be processed in some way to achieve system function*

# Data Flow



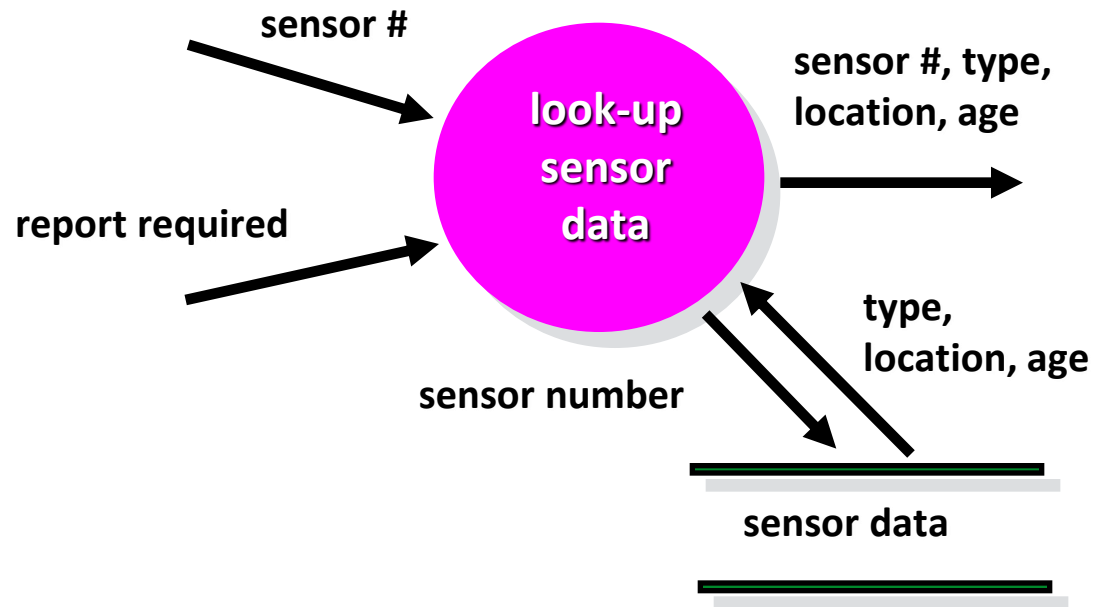
**Data flows through a system, beginning as input and transformed into output.**



# Data Stores



Data is often stored for later use.



# Data Flow Diagram: Guidelines

- all icons must be labeled with meaningful names
- the DFD evolves through a number of levels of detail
- always begin with a context level diagram (also called level 0)
- always show external entities at level 0
- always label data flow arrows
- do not represent procedural logic



# Constructing a DFD—Step I

- review user scenarios and/or the data model to isolate data objects and use a grammatical parse to determine “operations”
- determine external entities (producers and consumers of data)
- create a level 0 DFD



# Level 0: Context level data-flow diagram

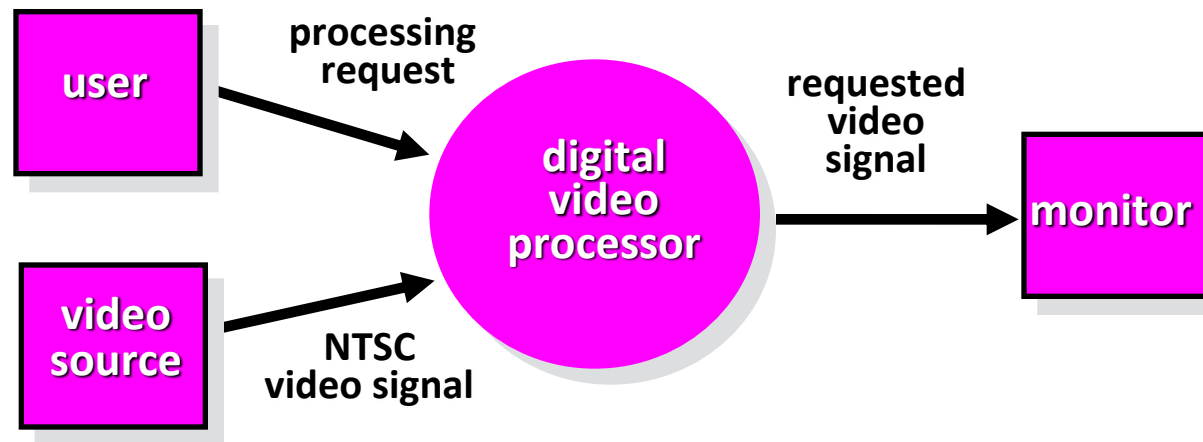
- The analyst represents the `target` system at its context level. It is also called parent-DFD.
- A context level DFD is a high-level diagram (omitting all but essential details) consisting of **a single bubble (process)**.

The aim of the context level data-flow diagram is to view the system as an unexplored `black box`, and to direct the focus of the analysis on the type of the data-flows that **enter the system from the source and those that travel from the system to their destination.**





# Level 0 DFD Example



# Constructing a DFD— Step II

- Write a narrative describing the transform
- Parse to determine next level transforms
- “Balance” the flow to maintain data flow continuity
- Develop a level 1 DFD
- Use a 1:5 (approx.) expansion ratio



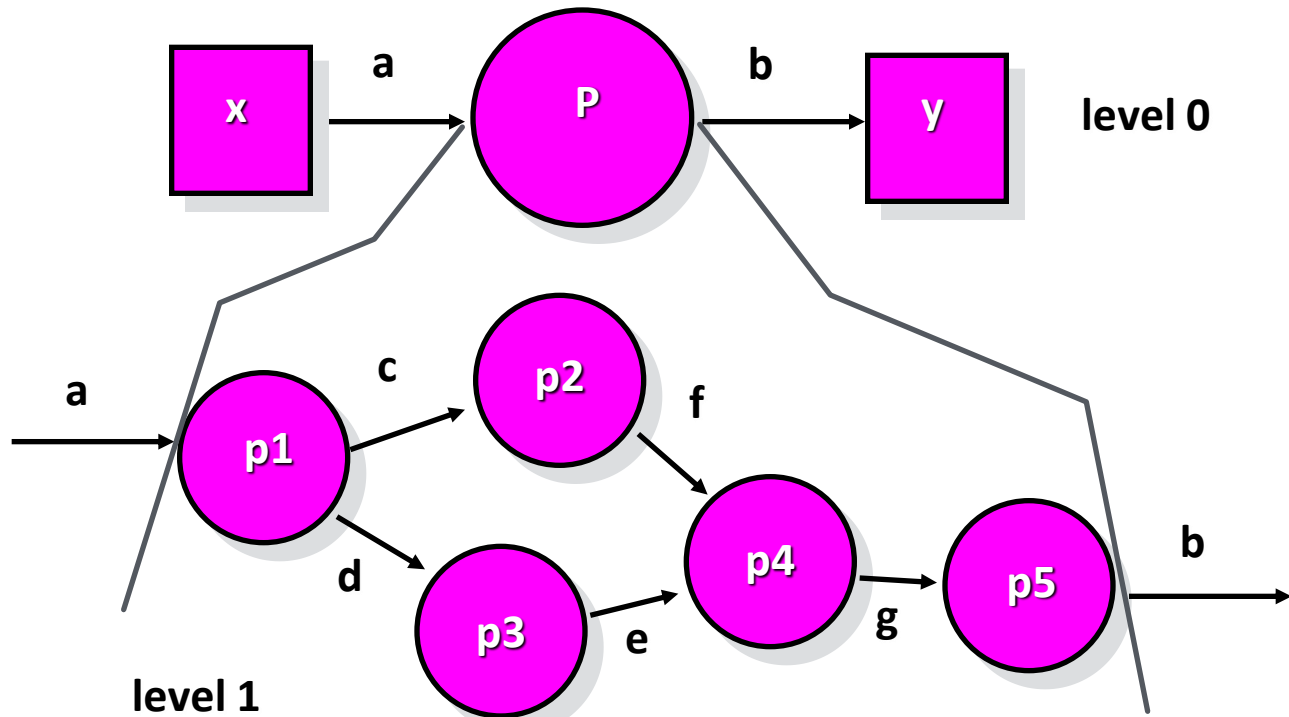
# Level 1 of the data-flow diagram

Level 1 of the data-flow diagram is constructed by decomposing the top-level system bubble into **sub-systems**.

The level 1 is also called child-DFD. Each bubble represents a potential sub-system through further decomposition.

The decomposition can be repeated for bubbles inside the child-DFD until dataflow for a software process is understood.

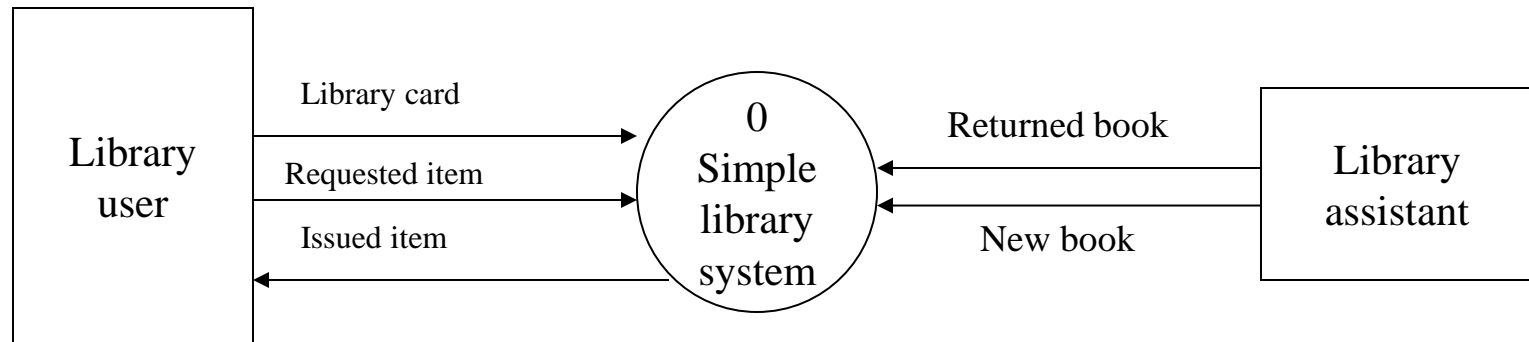
# The Data Flow Hierarchy



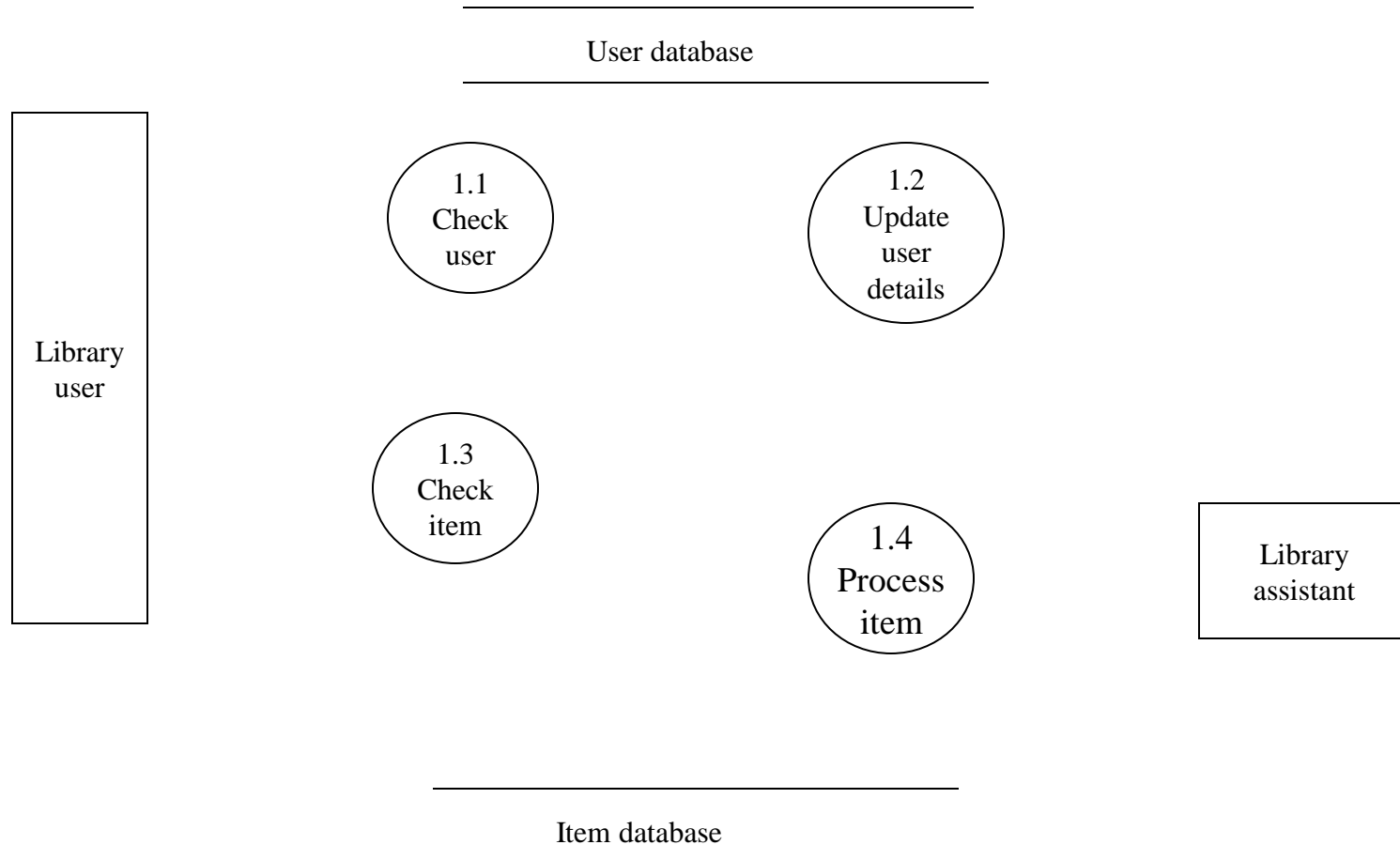
# Flow Modelling Notes

- Each bubble is refined until it does just one thing
- The expansion ratio decreases as the number of levels increase
- Most systems require between 3 and 7 levels for an adequate flow model
- A single data flow item (arrow) may be expanded as levels increase (data dictionary provides information)

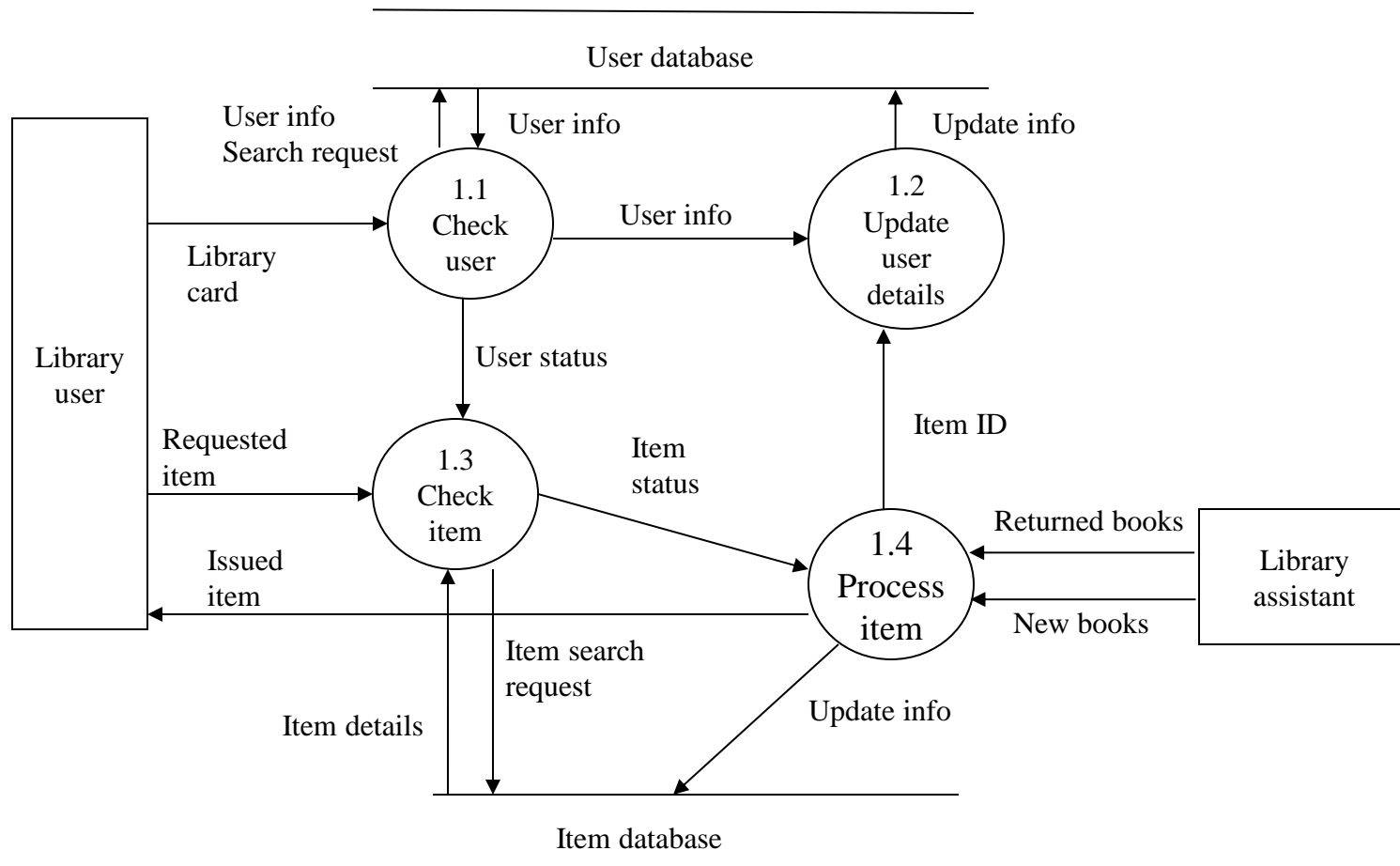
# Example: the context-level (level 0) data-flow diagram for simple library system



# Level 1 of the Data-flow diagram for the simple library system



# Level 1 of the Data-flow diagram for the simple library system



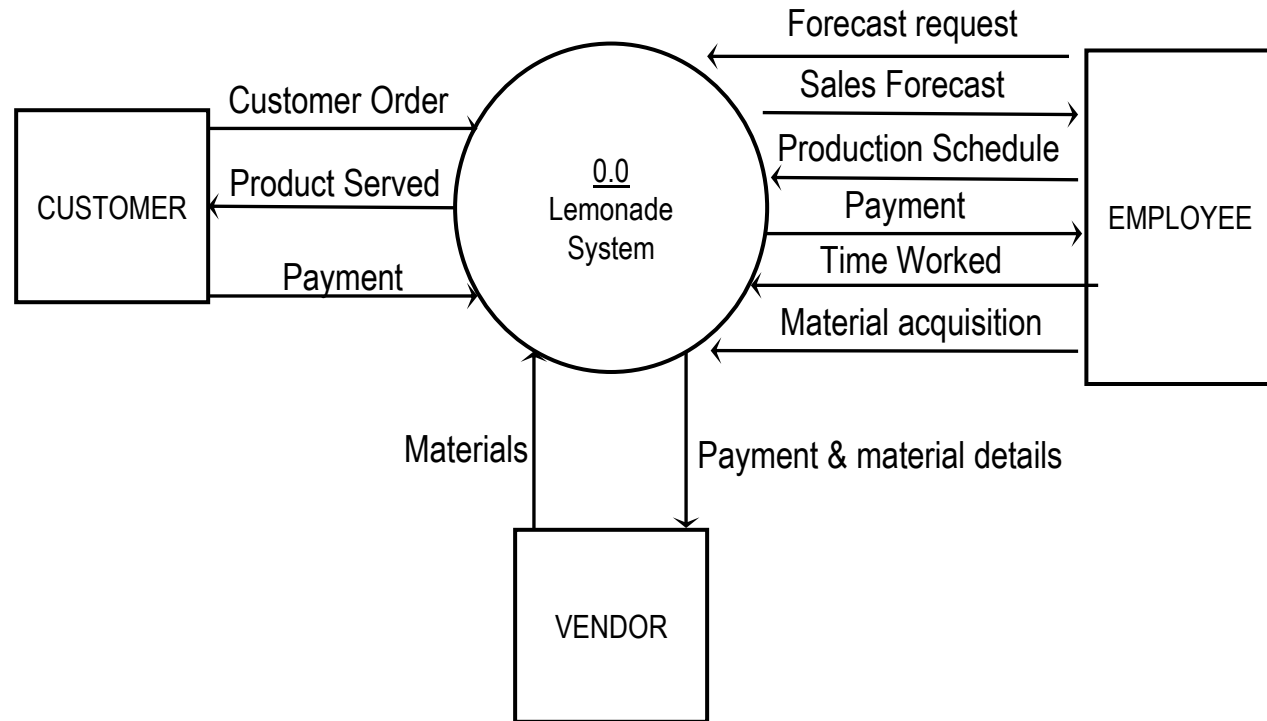


# Example: a lemonade system (Level 0)

Create a context level diagram identifying the sources and sinks (users).

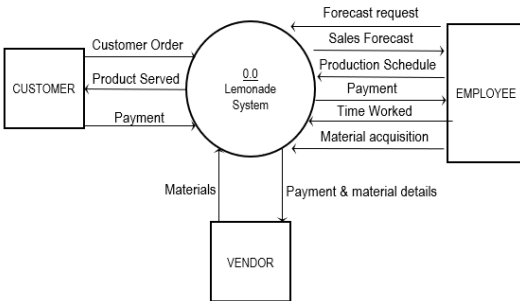


## Context Level DFD



# Example: a lemonade system (Level 1)

Context Level DFD



Create a level 1 diagram identifying the logical subsystems that may exist.

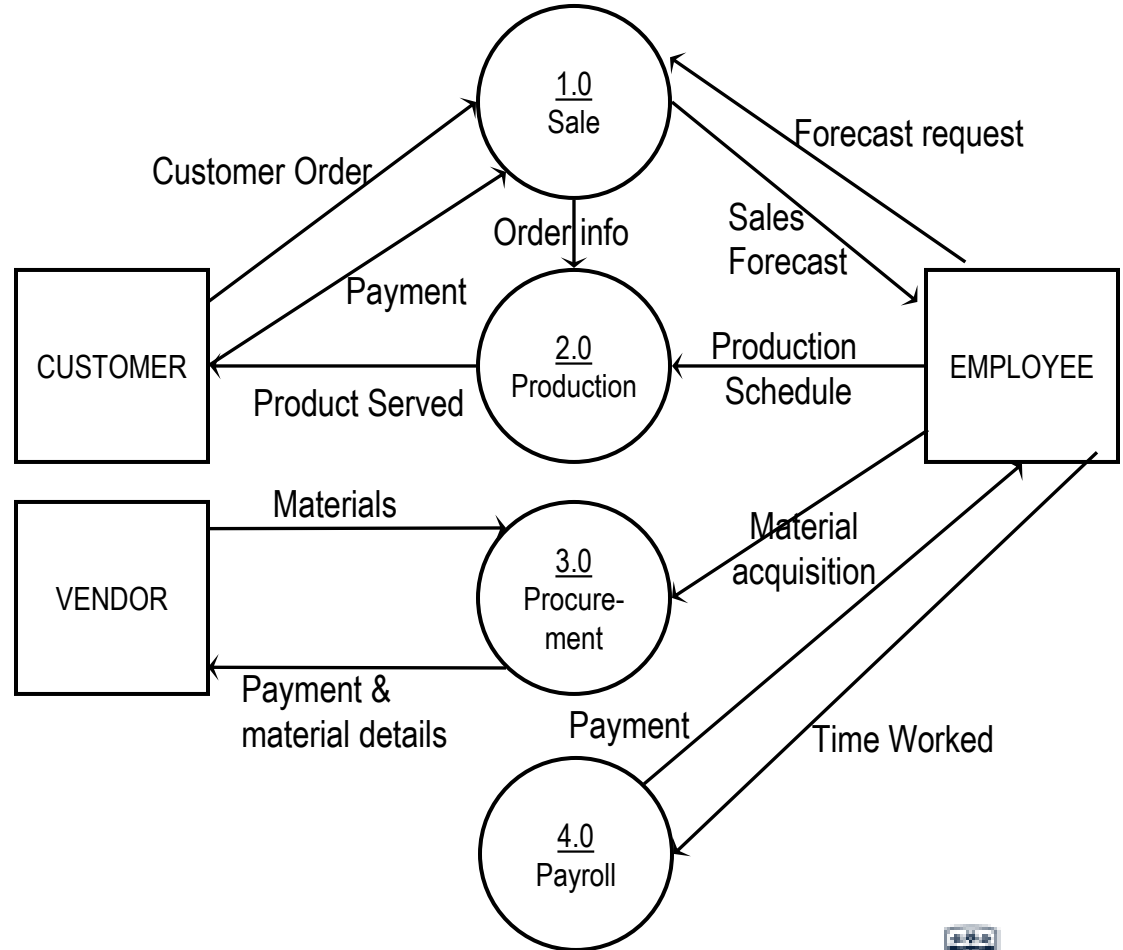
Customer Order  
Collect Payment  
Sales forecast

Produce Product  
Store Product  
Serve Product

Order Raw Materials  
Pay for Raw Materials

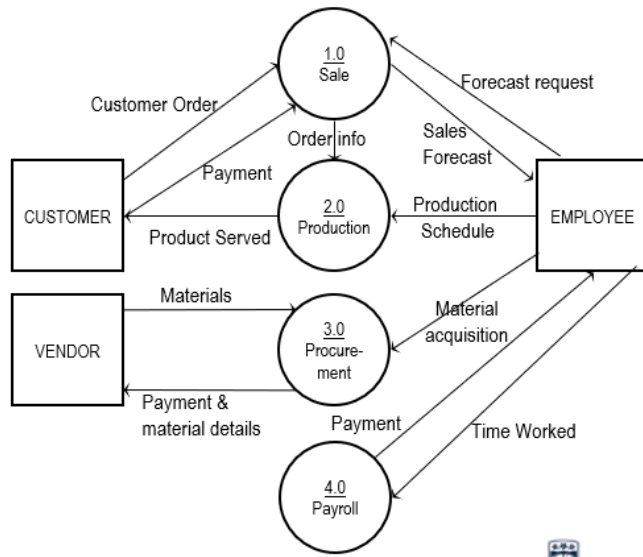
Pay for Labor

Level 1 DFD

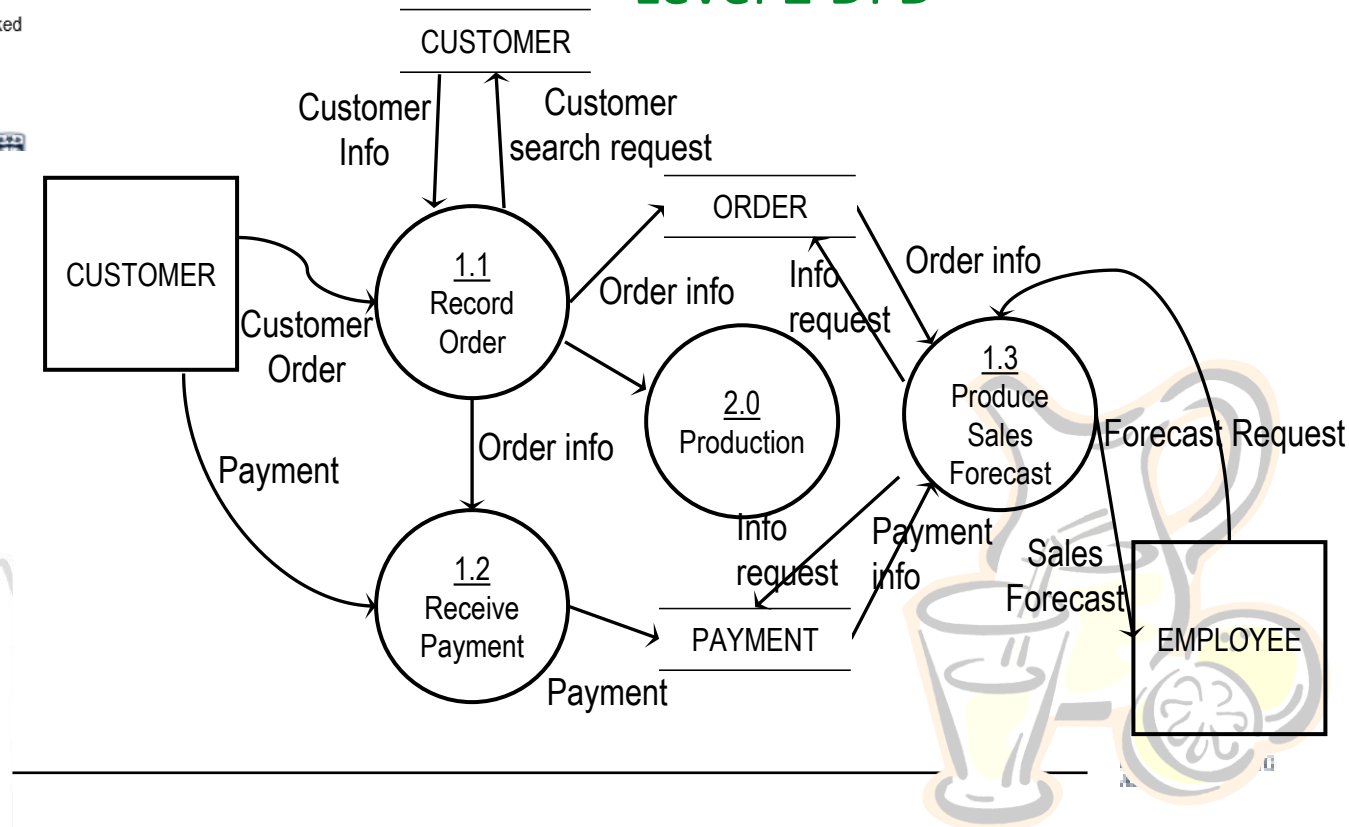


# Example: a lemonade system (Level 2)

Level 1 DFD



Level 2 DFD



Customer Order  
Collect Payment  
Sales forecast

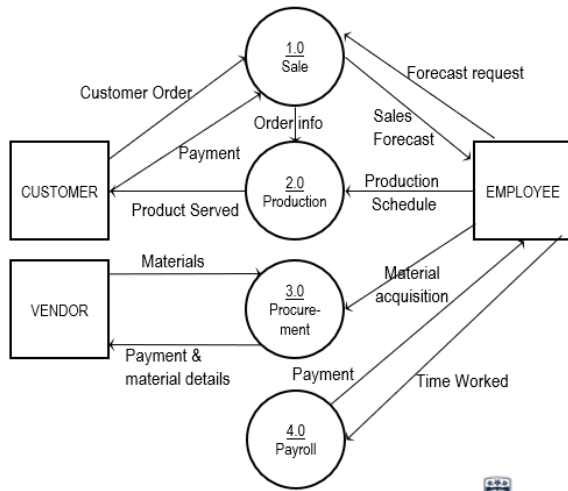
Produce Product  
Store Product  
Serve Product

Order Raw Materials  
Pay for Raw Materials

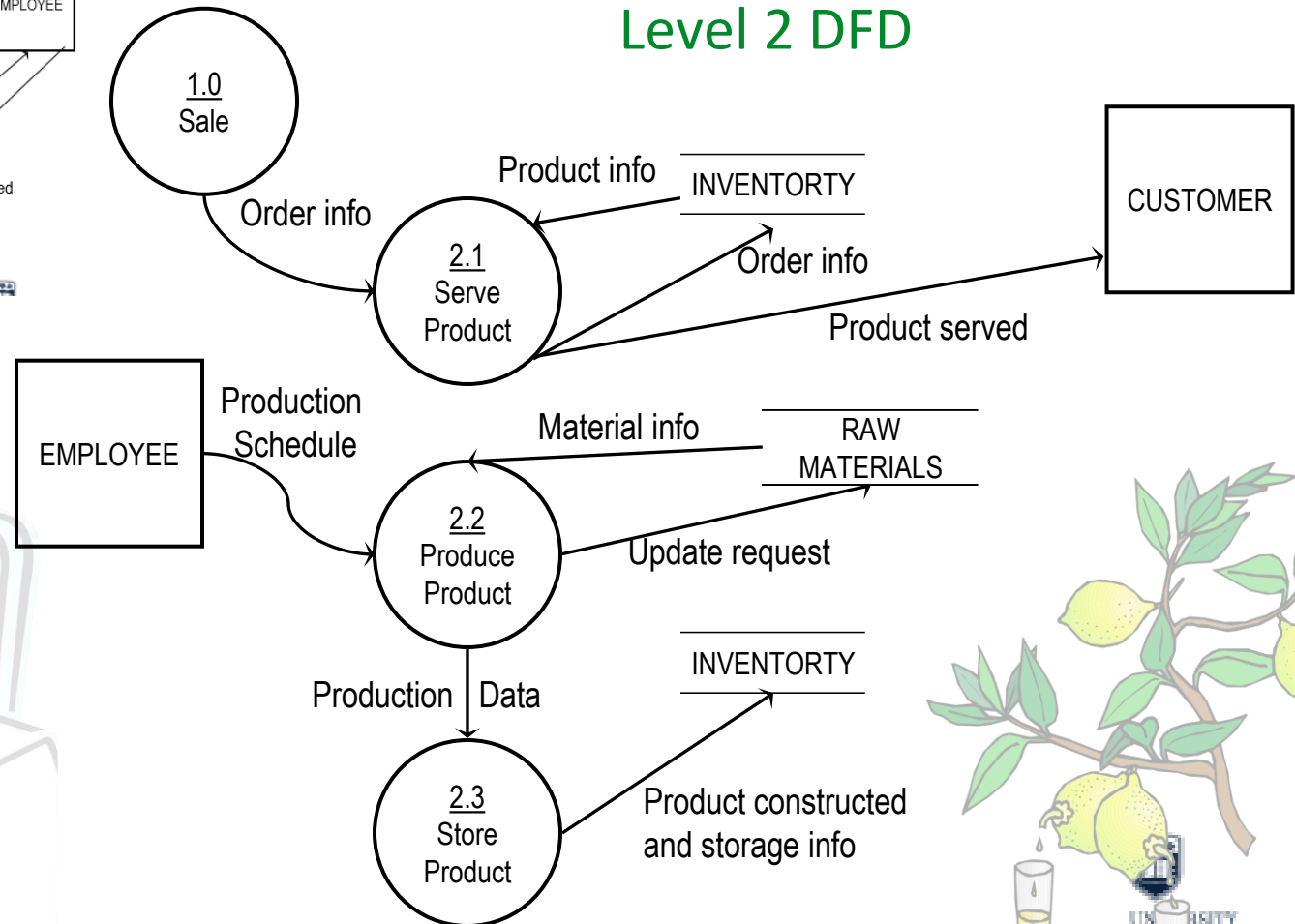
Pay for Labor

# Example: a lemonade system (Level 2)

Level 1 DFD



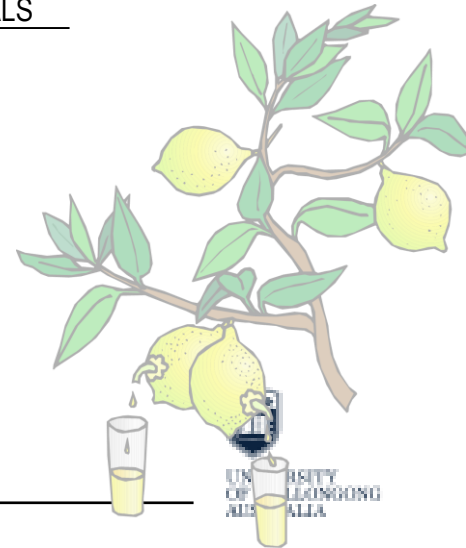
Level 2 DFD



Customer Order  
Collect Payment  
Sales forecast

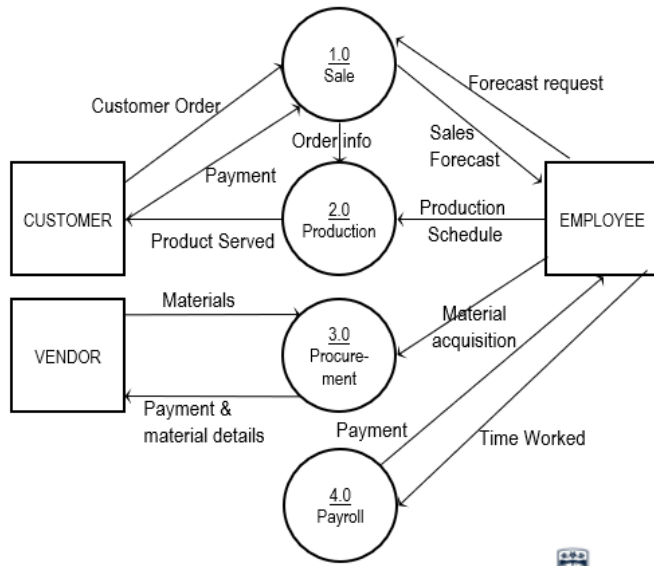
Produce Product  
Store Product  
Serve Product

Order Raw Materials  
Pay for Raw Materials  
Pay for Labor



# Creating Data Flow Diagrams

Level 1 DFD



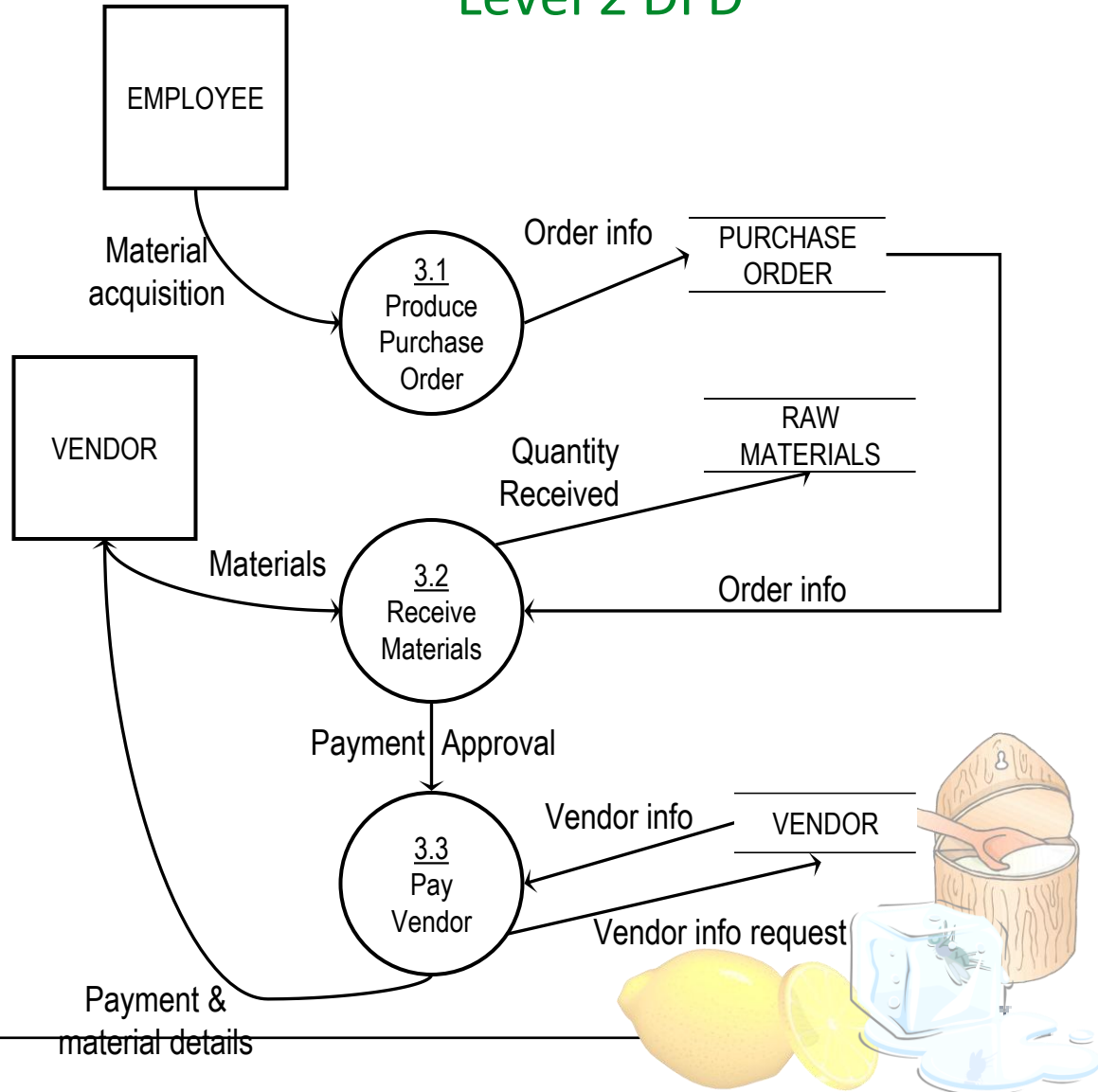
Customer Order  
Collect Payment  
Sales forecast

Produce Product  
Store Product  
Serve Product

Order Raw Materials  
Pay for Raw Materials

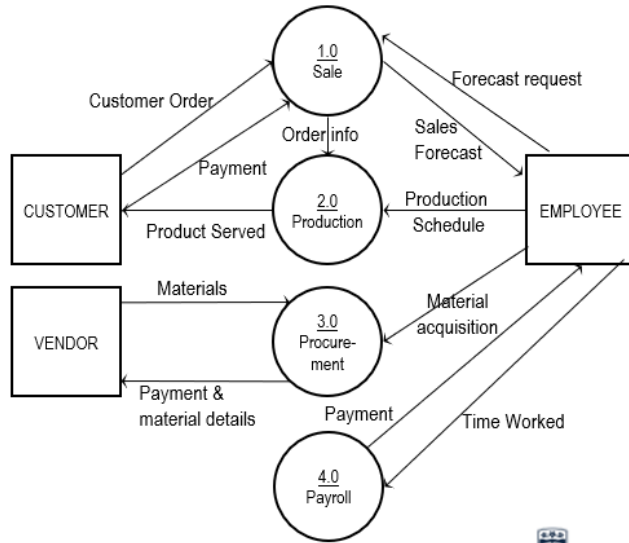
Pay for Labor

Level 2 DFD



# Creating Data Flow Diagrams

Level 1 DFD



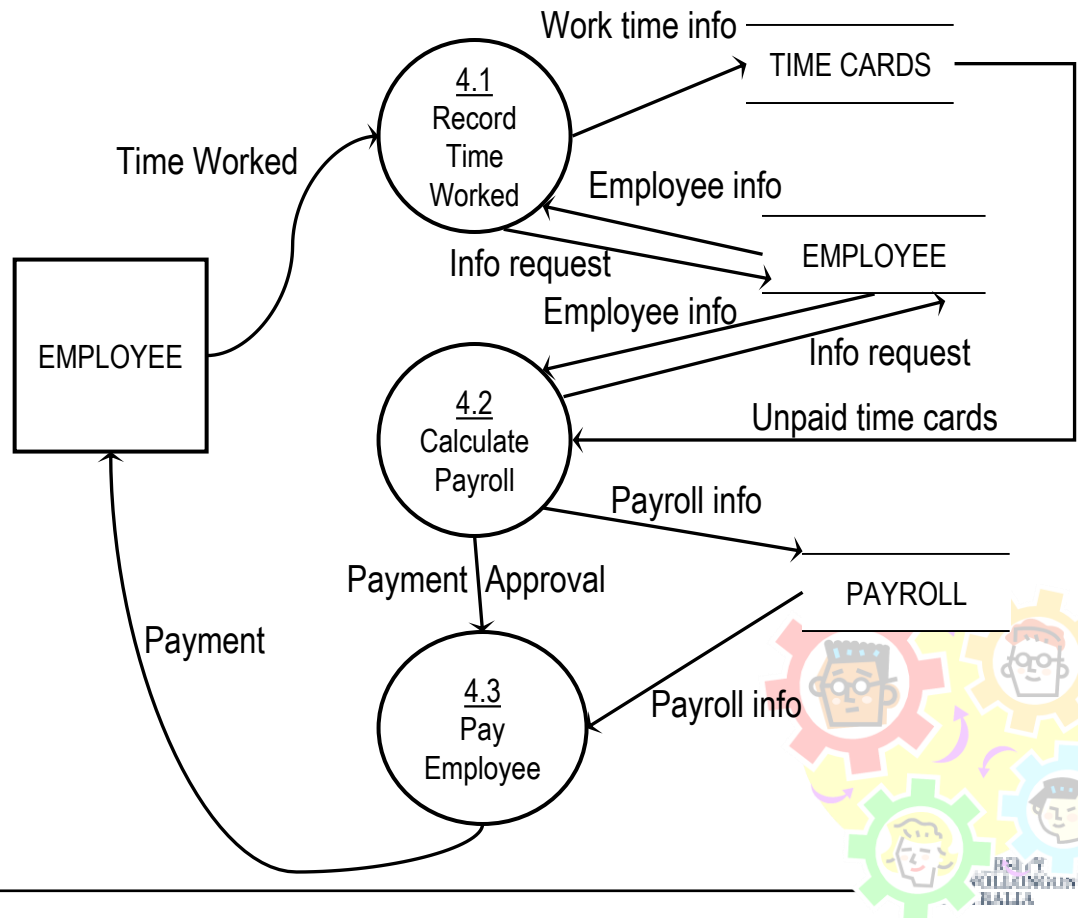
Customer Order  
Collect Payment  
Sales forecast

Produce Product  
Store Product  
Serve Product

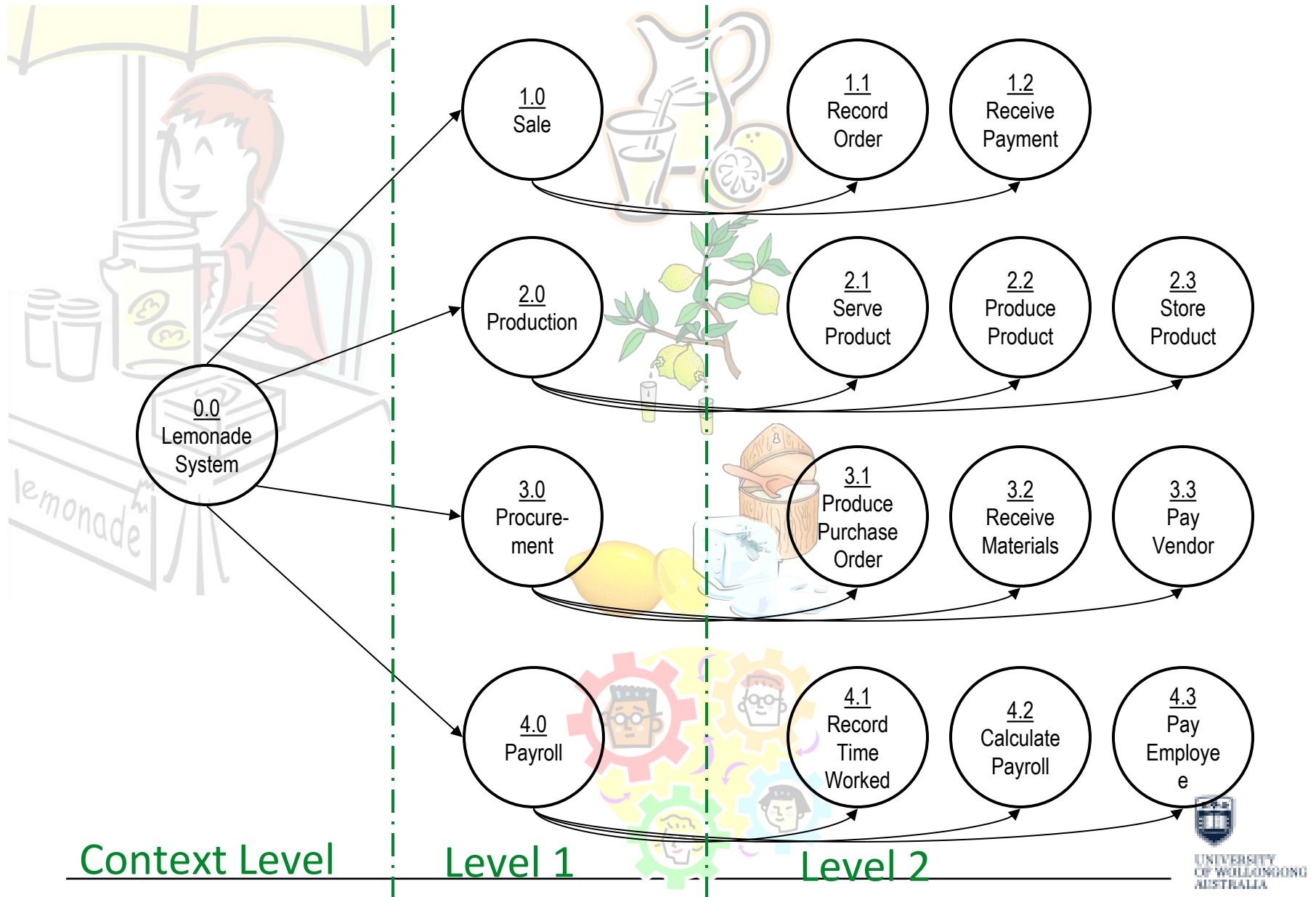
Order Raw Materials  
Pay for Raw Materials

Pay for Labor

Level 2 DFD



# Process Decomposition





# Data Dictionary

- A data dictionary stores information about data items found in a DFD.
- A data dictionary supplies information such as a data typing, required accuracy of data useful to designers and implementers.
- A data dictionary can be used to check the completeness and consistency of DFDs.





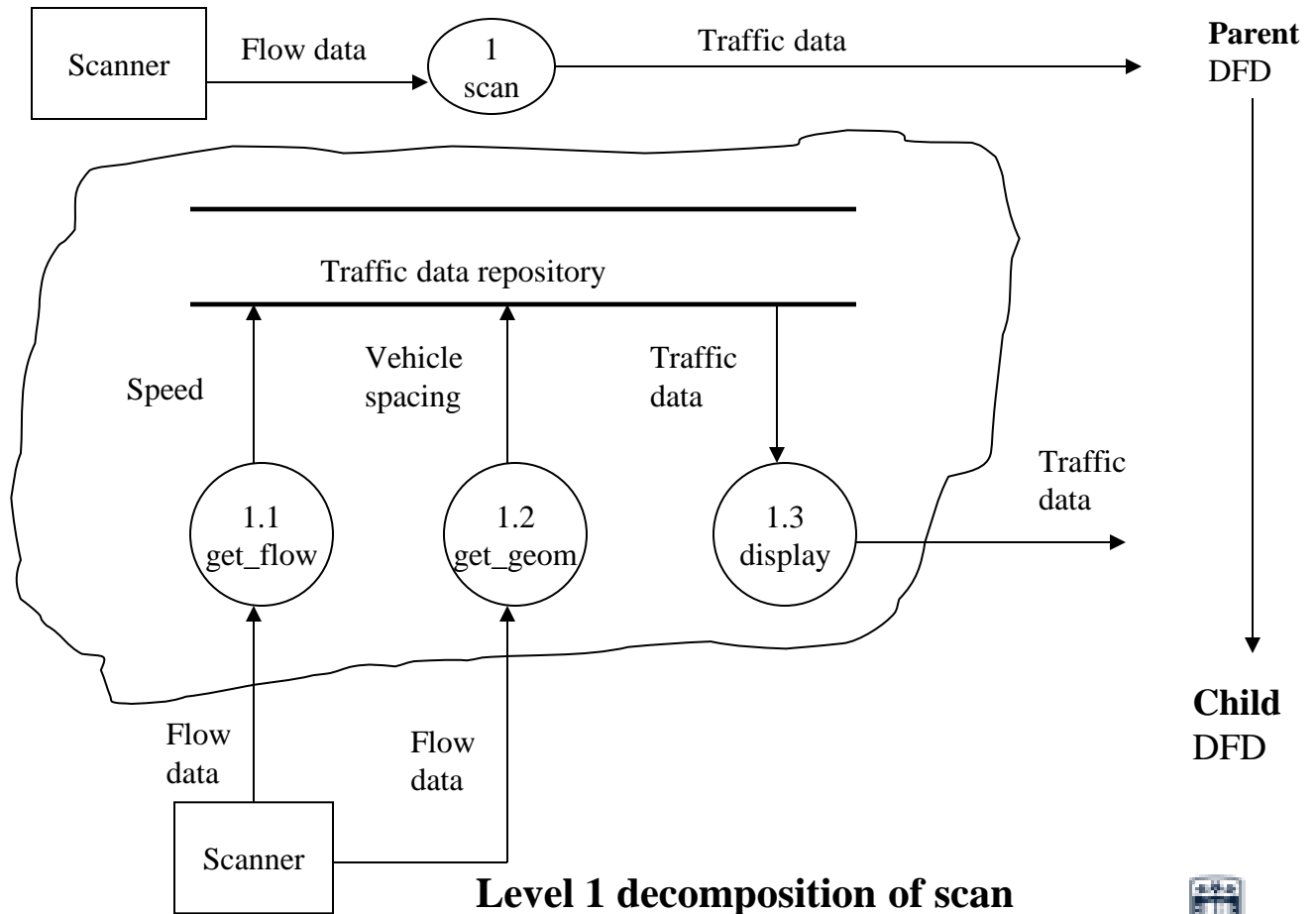
# Data Dictionary Features

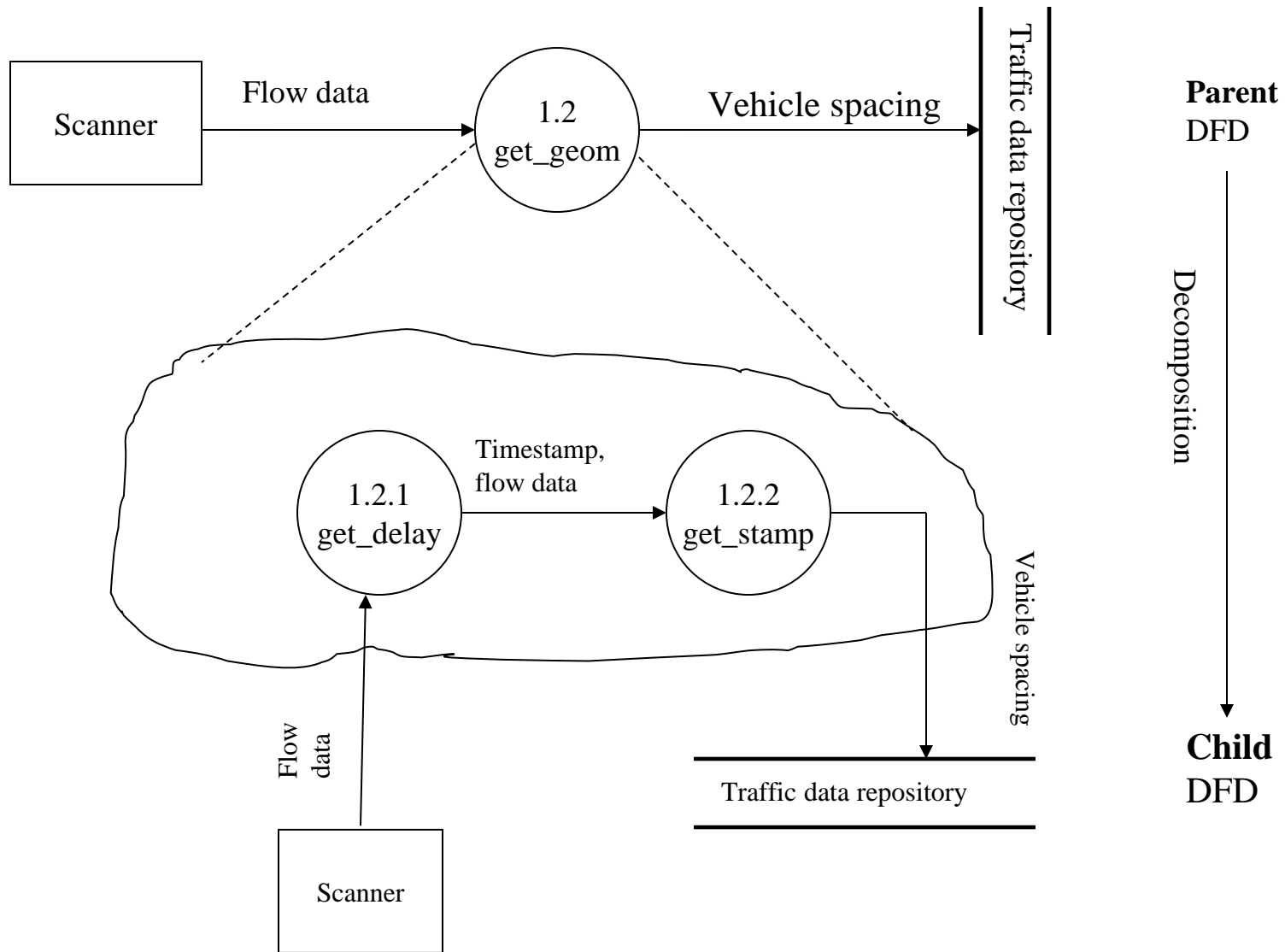
## Information Stored

## Explanation

Name	Identifies data item
Alias	Identifies other names, abbreviations used to identify a data item
Data structure (type)	Type of data (e.g. integer, queue)
Description	data description with more details
Duration (begins)	Life span of data (when created)
Accuracy	High, medium, low accuracy
Range of values	Allowable values of data item
Data flows	Identifies process that generate/receive data

# Example: Three levels of data-flow diagrams for Scanner in a navigation system

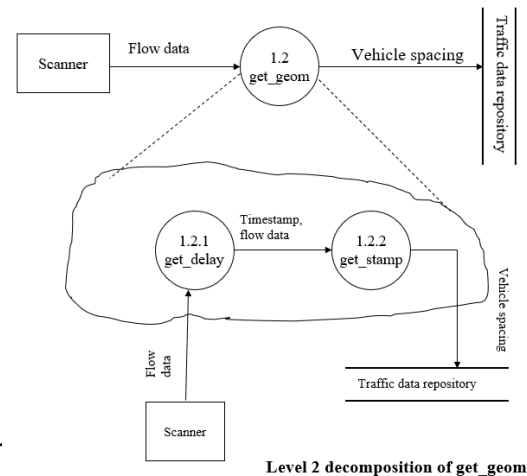
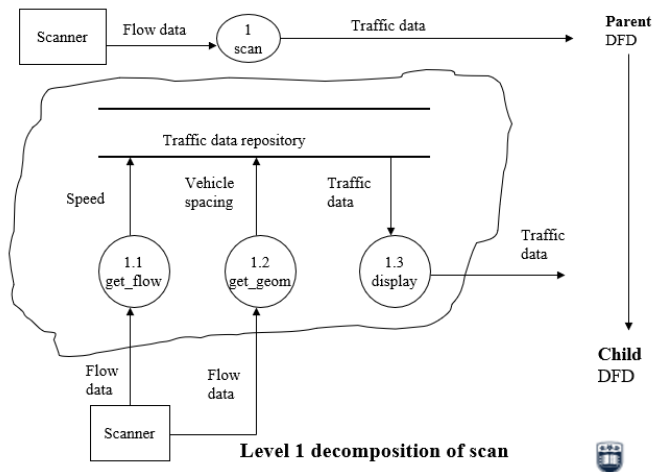




**Level 2 decomposition of `get_geom`**

# Sample Data Dictionary

Name	Type	About	Range	Accuracy	Data Flows
Speed	Real	Average Vehicle speed	$0 \leq \text{speed} \leq 60 \text{ mph}$	$\pm 0.01$	<b>get_flow</b>
Vehicle spacing	Real	Average vehicle spacing	$0 \leq \text{speed} \leq 1000 \text{ ft}$	$\pm 0.01$	<b>get_geom</b>
Flow data location	String	Traffic location	$10 \leq \text{speed} \leq 30$	Not specified	<b>get_geom, get_flow</b>
Flow data volume	Integer	Current traffic volume	$0 \leq \text{volume} \leq 4000/\text{hr}$	Not specified	<b>get_geom, get_flow</b>
Time	String	Date and time	20 characters	Not specified	<b>get_timestamp</b>



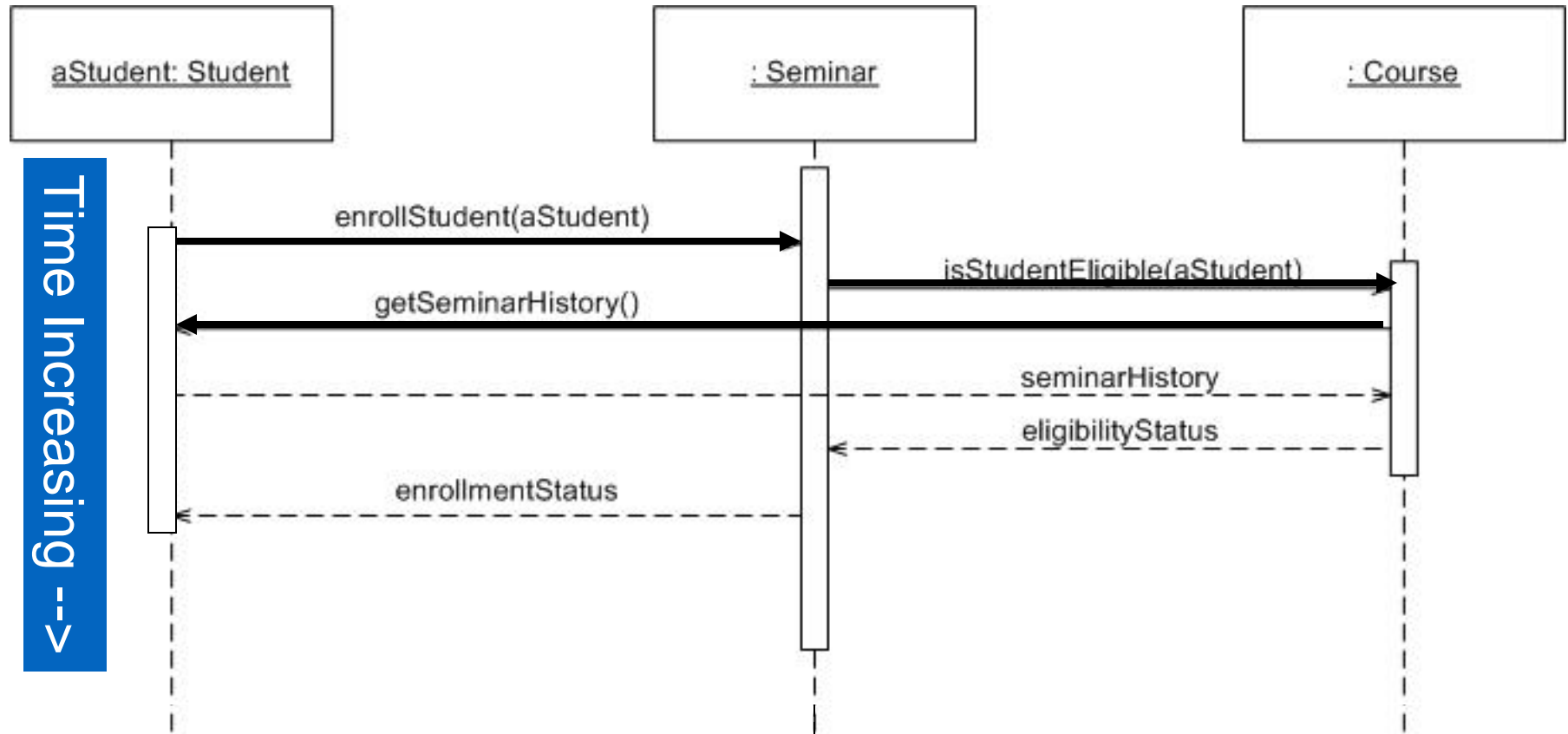
# Sequence Diagrams

- Describe the flow of messages, events, actions between objects
- Show concurrent processes and activations
- Show time sequences that are not easily depicted in other diagrams
- Typically used during analysis and design to document and understand the logical flow of your system

Emphasis on time ordering!



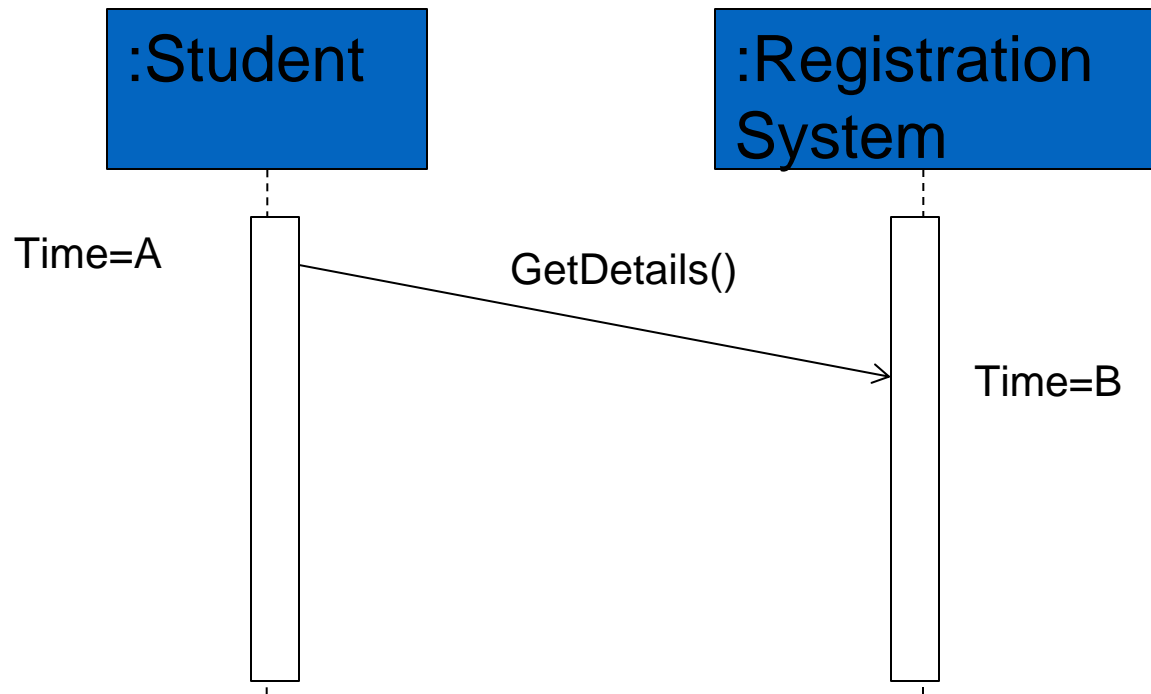
# Sequence Diagram



horizontal lines indicate instantaneous actions. Additionally if ActivityA happens before ActivityB, ActivityA must be above activity A

**Lower = Later!**

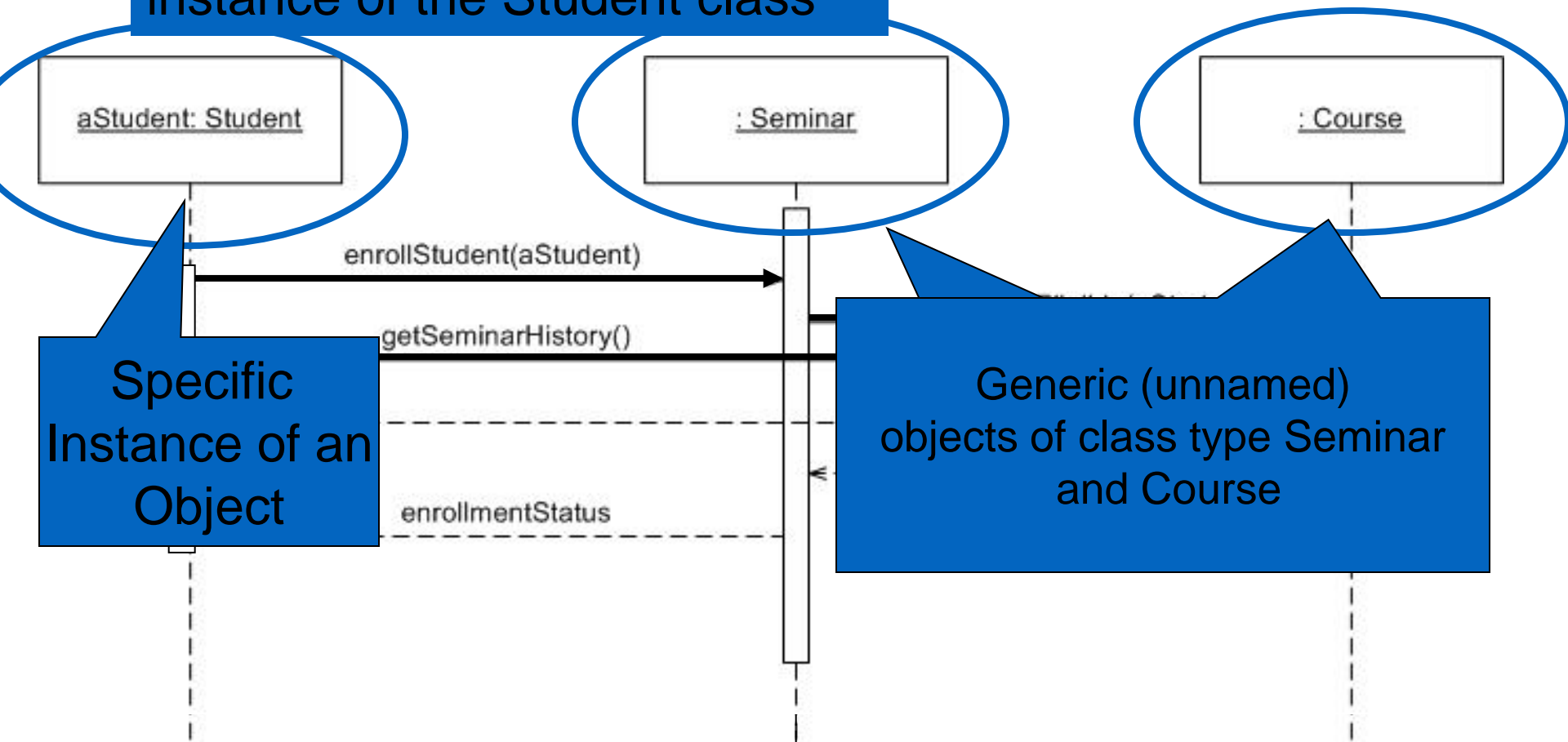
# Diagonal Lines



- What does this mean?

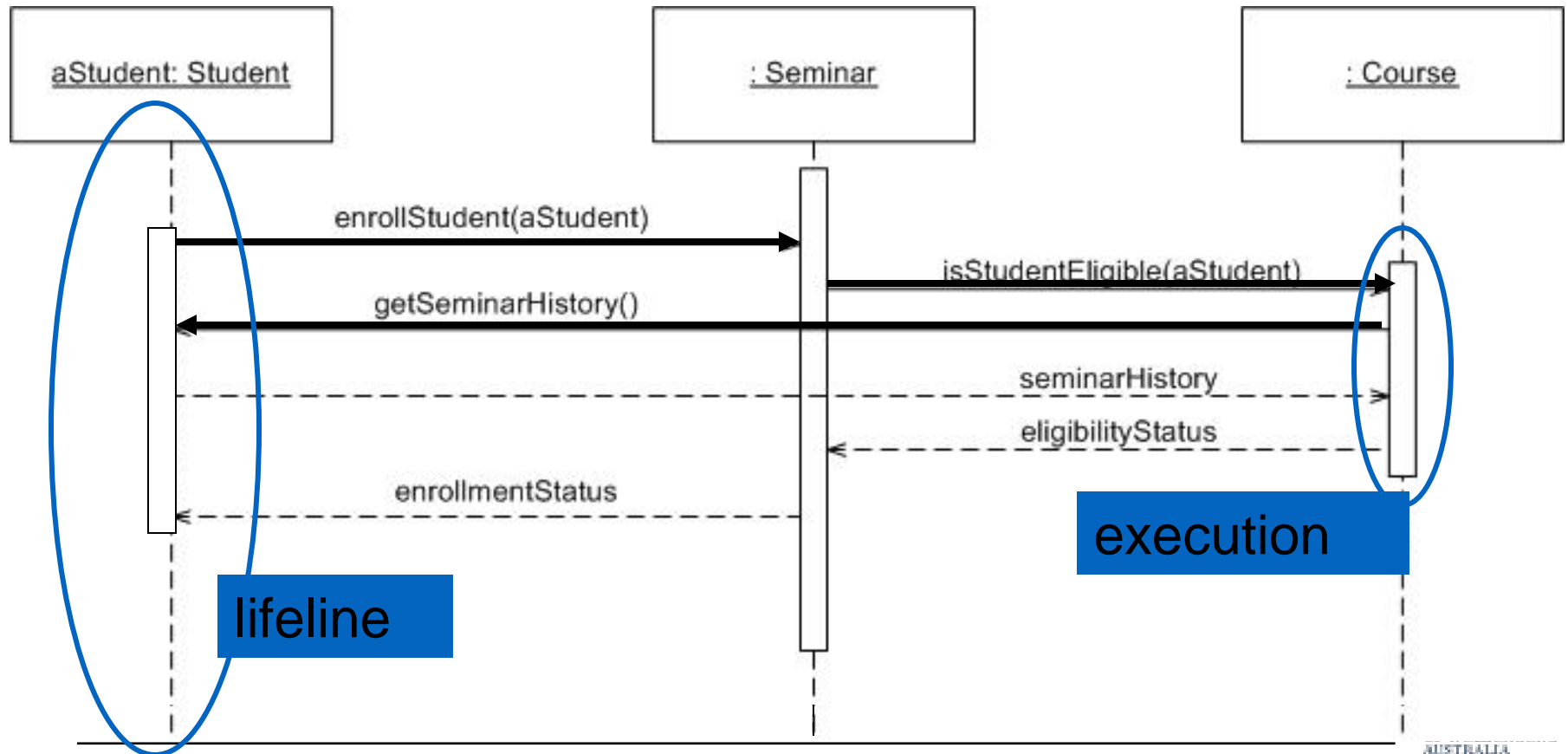
# Components

Objects: aStudent is a specific instance of the Student class

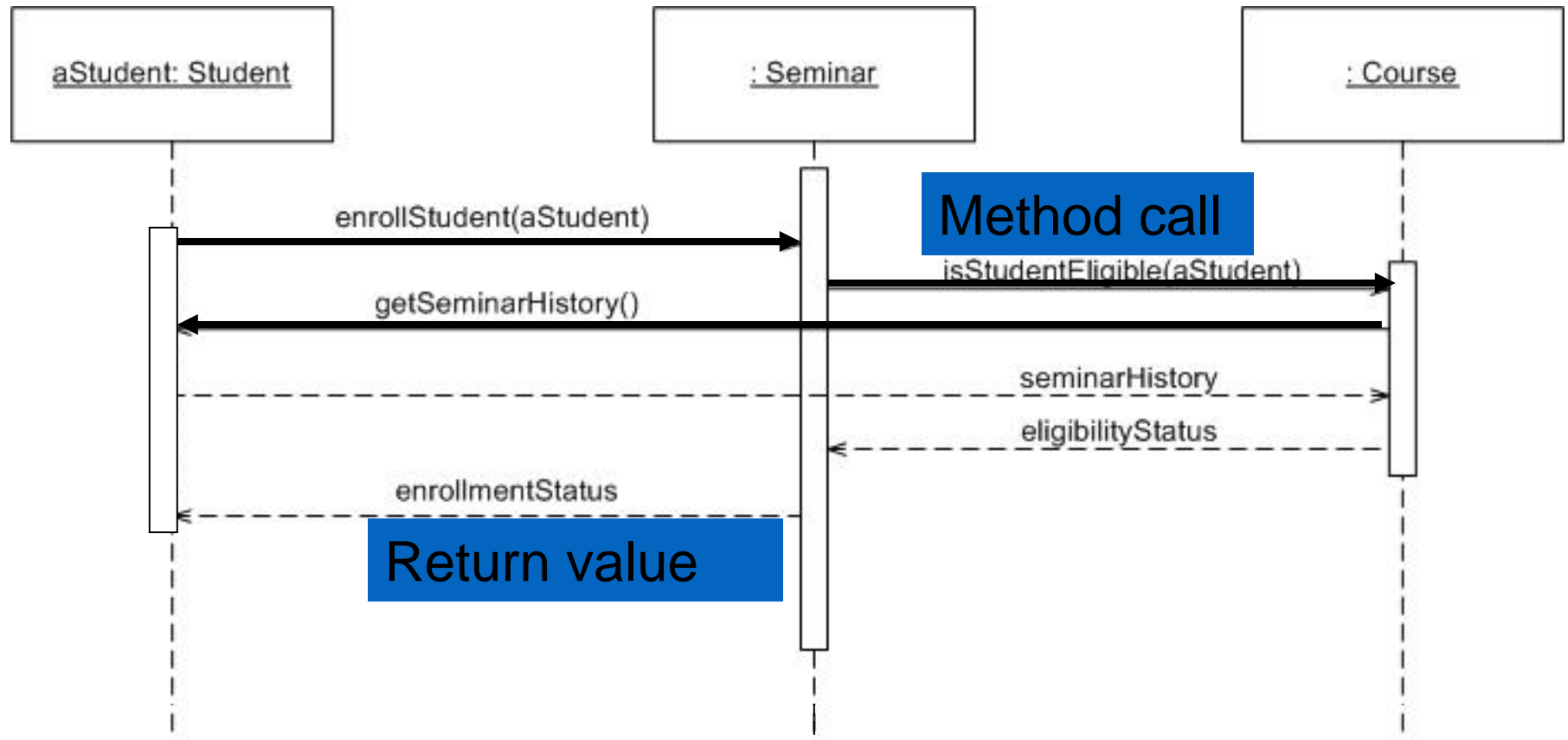




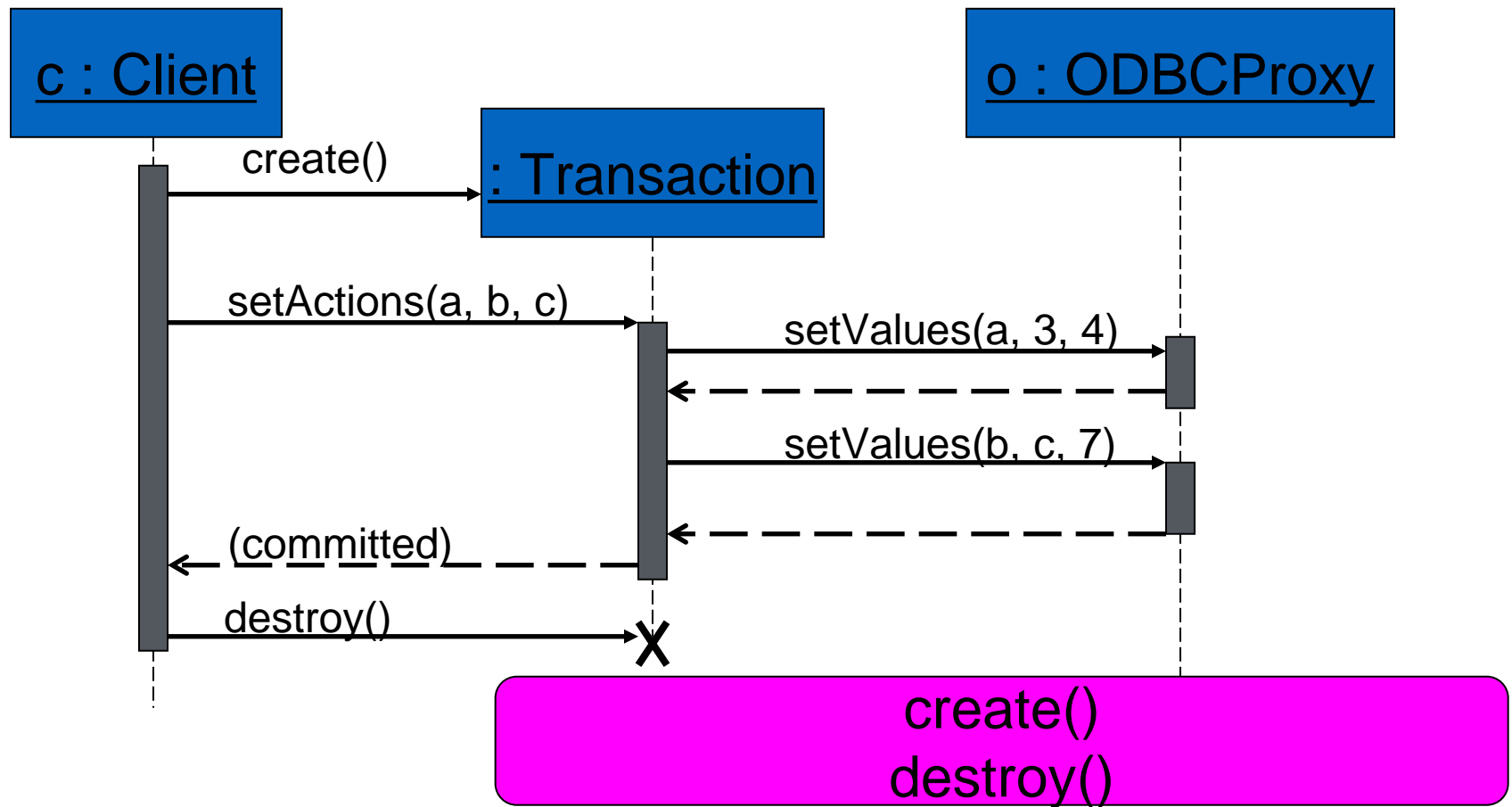
# Components



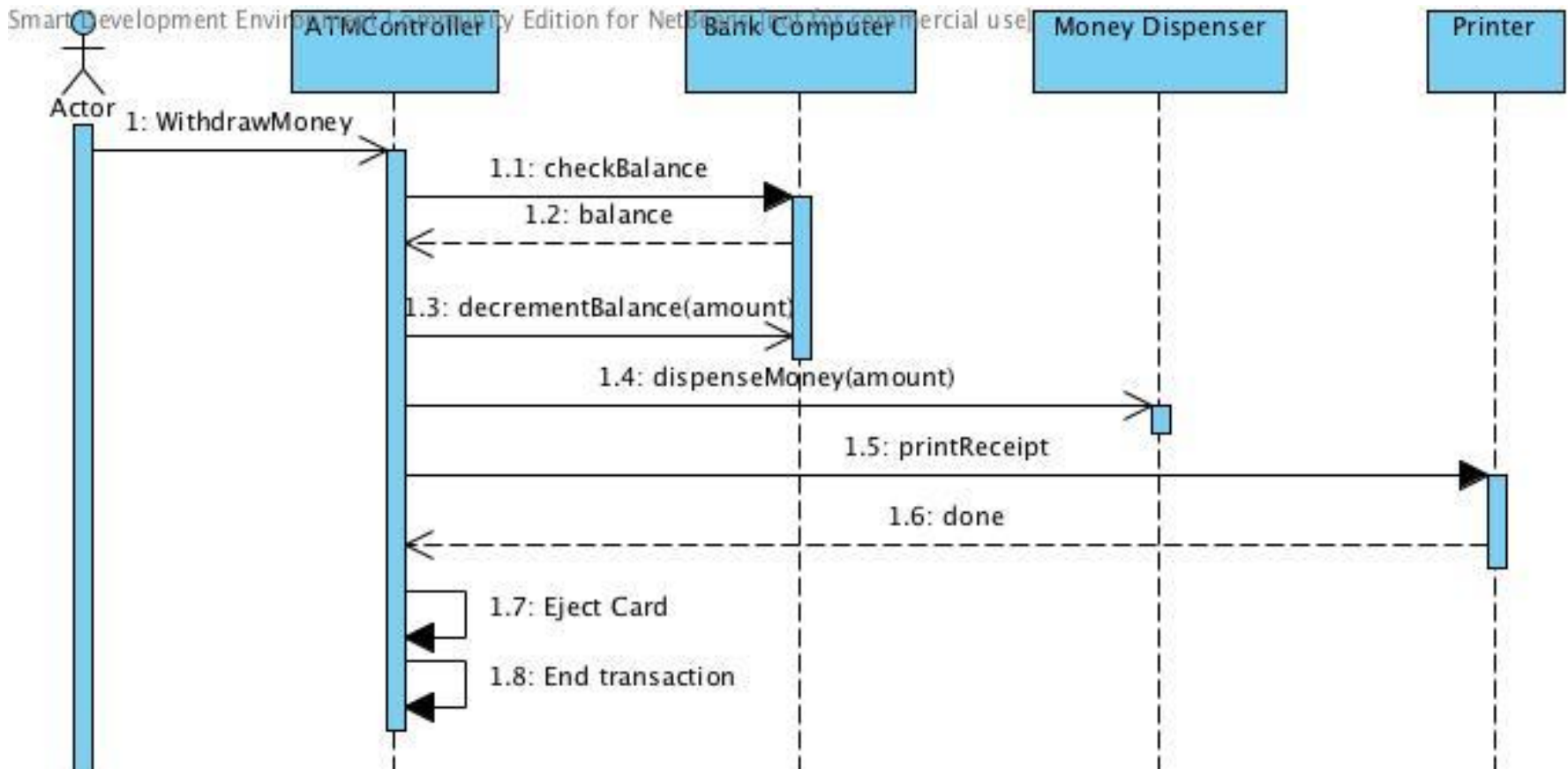
# Components



# Components



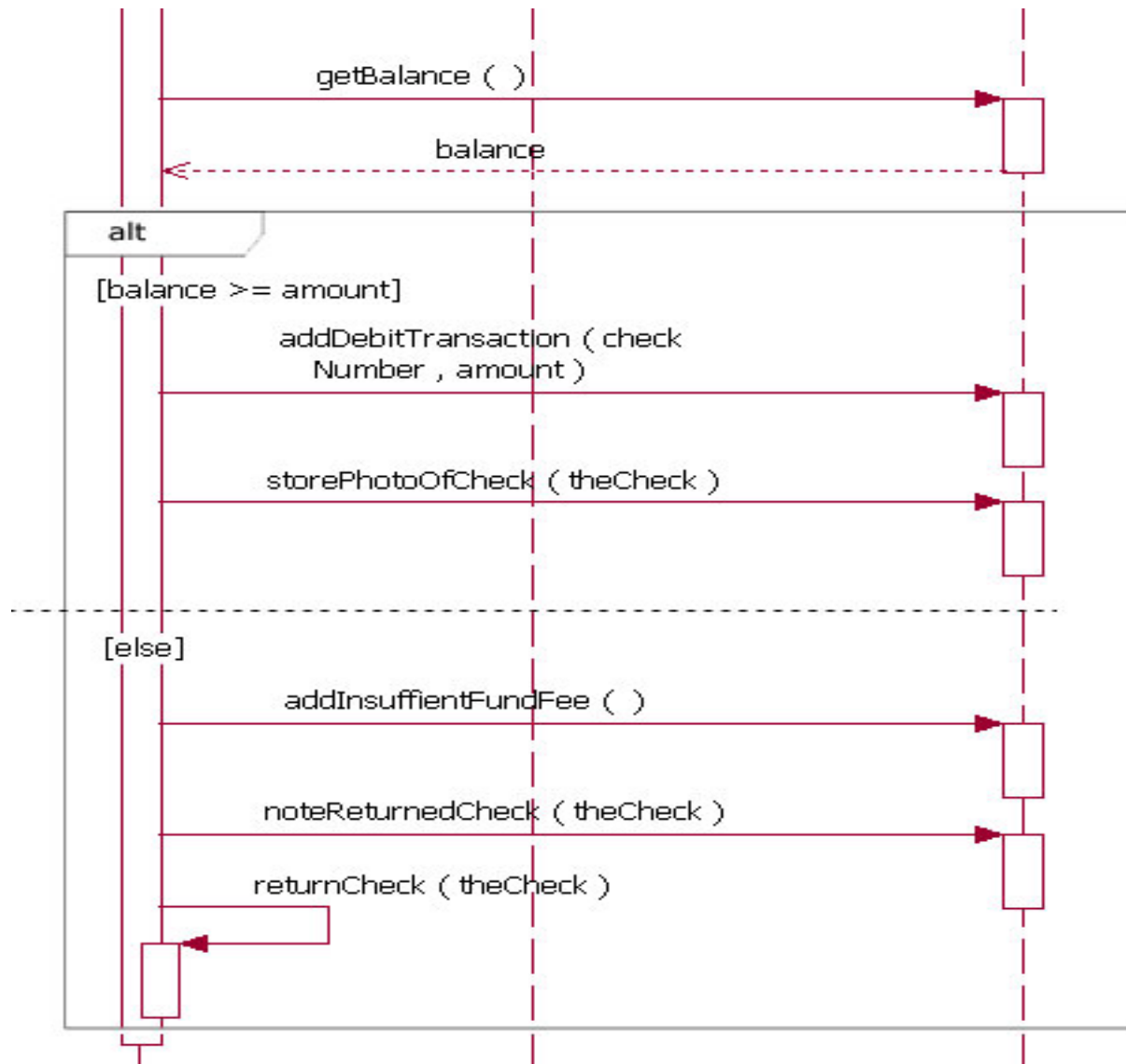
# Async Message Example



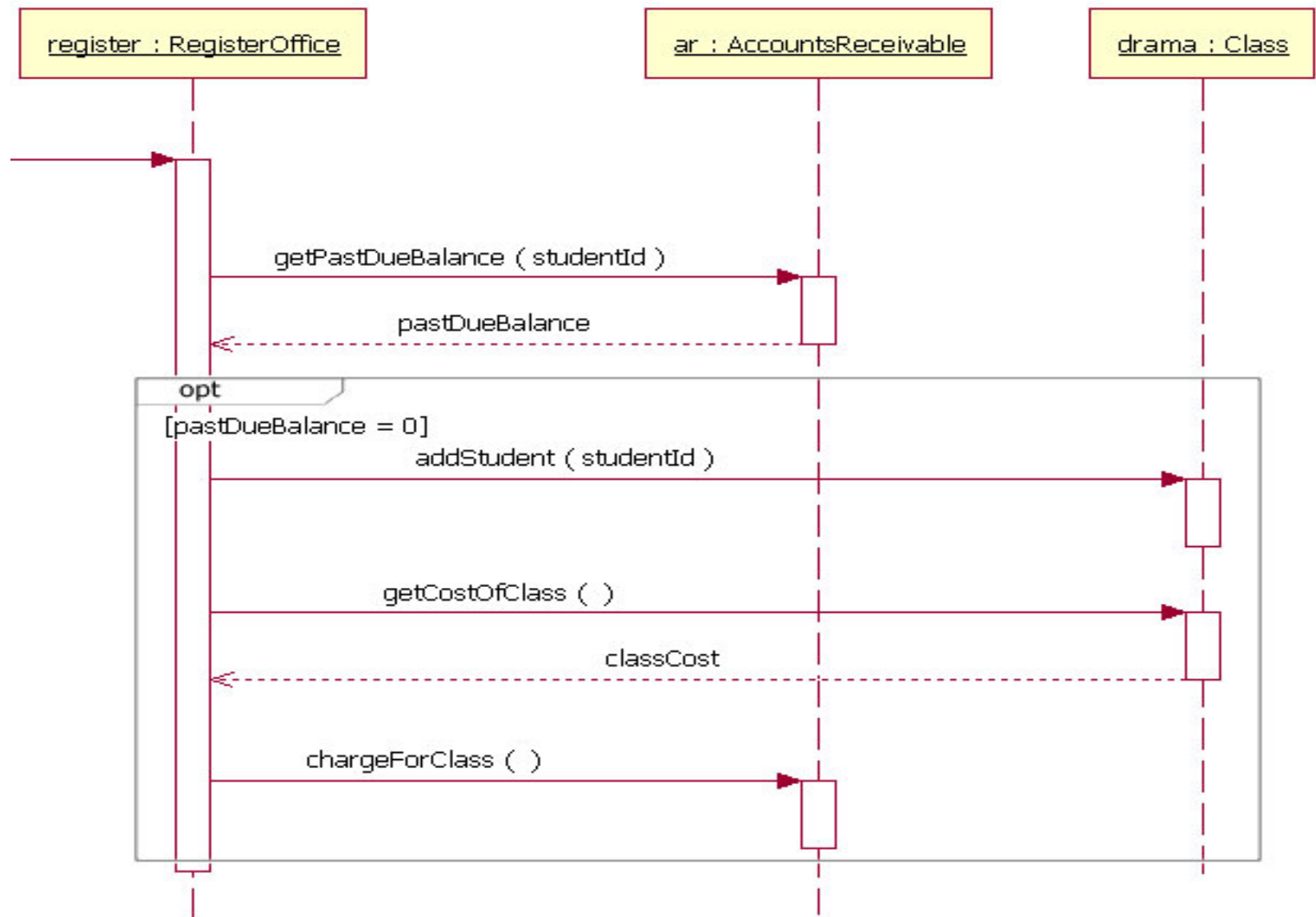
There are problems here... what are they?

- Synchronous message
- Asynchronous message
- - - - - Return message

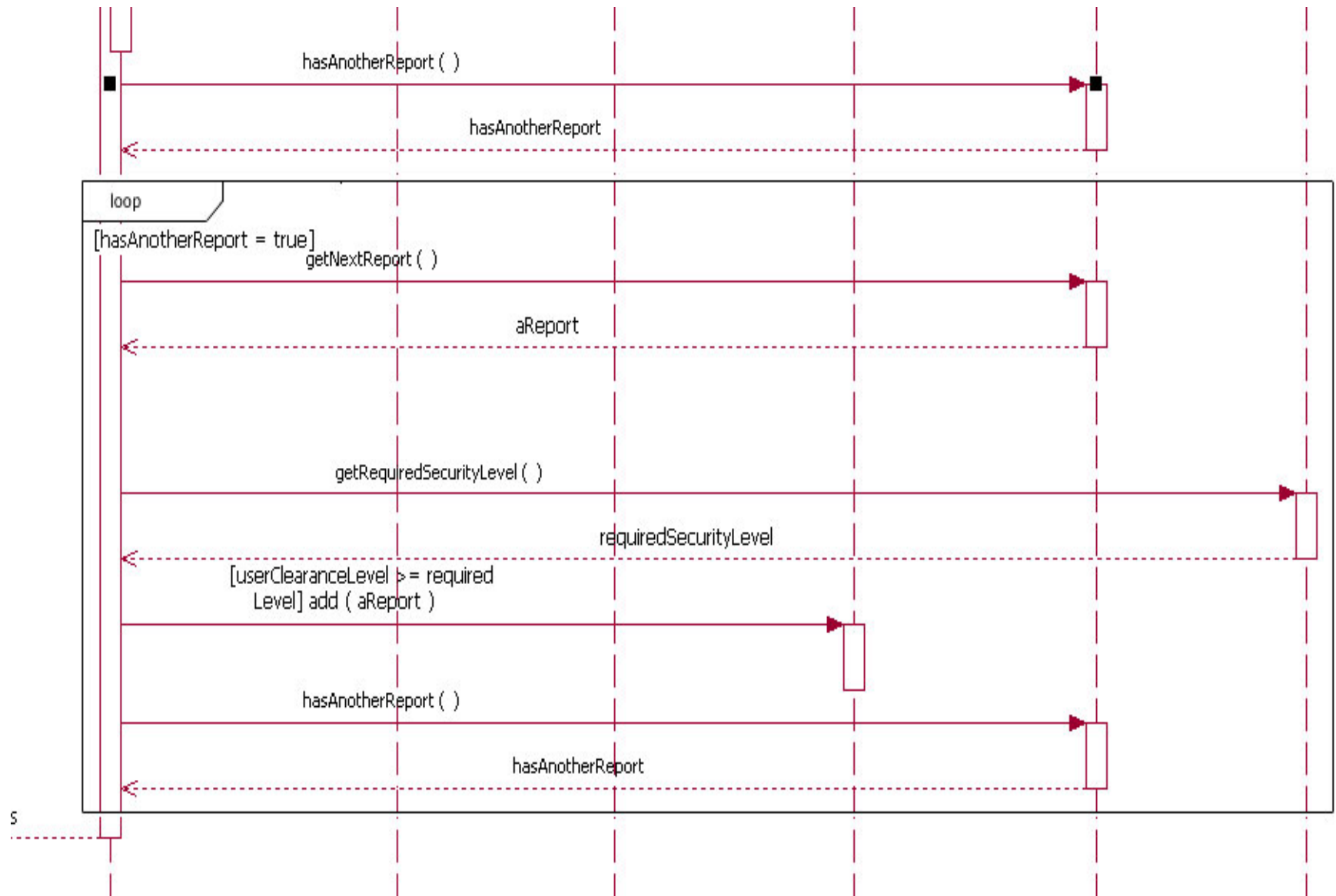
# Components: alt/else



# Components: option



# Components: loop



# Finite State Machines (FSM)

At its lowest level, observable behavior of a system can be described with Finite State Machines (FSMs), which are special cases of automata (abstract machine).

The state of a system can be determined by checking the value of one or more state variables.

Suppose that a system might have state variable  $q_1, q_2, q_3, q_4$  with values from the set {waiting, reading, writing, searching}. The possible state sequence for the system might be:

waiting → reading → searching → writing → waiting  
(state  $q_1$ )      ( $q_2$ )      ( $q_3$ )      ( $q_4$ )      ( $q_1$ )



# Moore and Mealy FSMs

Two types of finite state machines differ in the output logic:

- **Moore FSM:**

- outputs depend only on the current state

- **Mealy FSM:**

- outputs depend on the current state and the inputs

Mealy is more general

# Definition of a finite-state machine

A finite-state machine  $M$  is defined by a five-tuple  $(Q, F, q_0, S, \delta)$  where

- $Q$  is a finite set of states  $\{q_0, q_1, q_2, \dots, q_n\}$
- $F$  is a subset of final (accepting) state of  $Q$
- $q_0$  is a single start state in  $Q$
- $S$  is an input/output alphabet
- $\delta: Q \times S \rightarrow Q$  maps the current input and current state into the next state

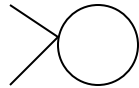


# Notation FSM diagrams

State



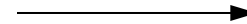
Start state



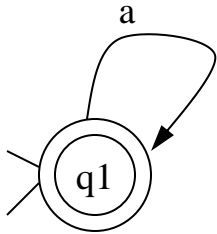
Final state



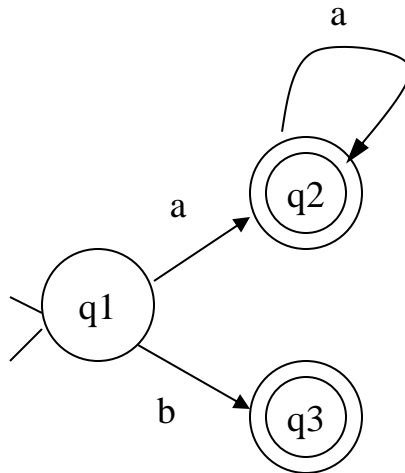
Transition



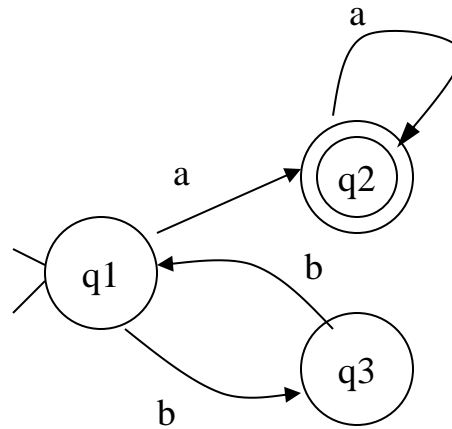
# Sample finite-state machines



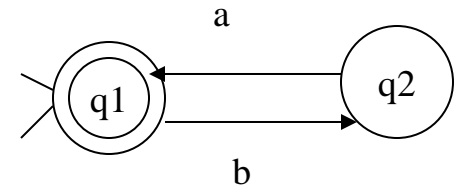
(a) accepts  
a, aa, aaa, ...



(b) accepts b or  
a, aa, aaa, aaaa, ...

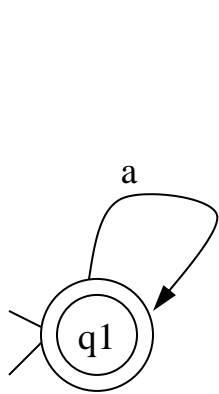


(c) accepts  
bba, bbba, ..., or  
a, aa, aaa, aaaa, ...

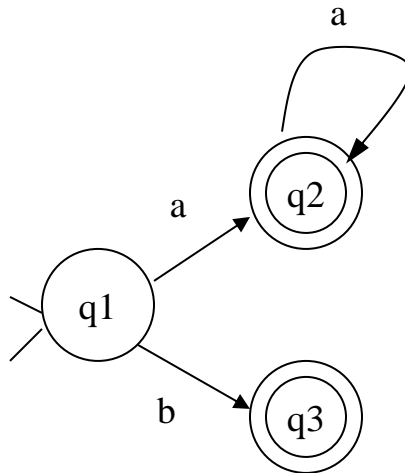


(d) accepts  
ba, baba, ...

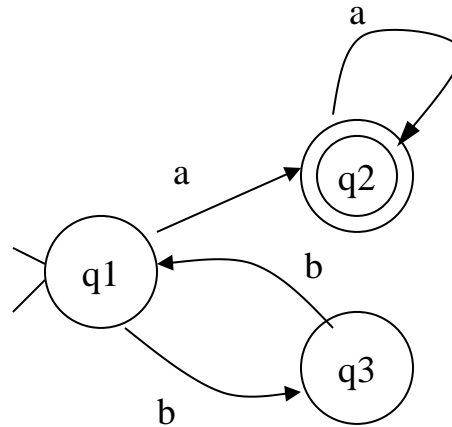
# Sample finite-state machines



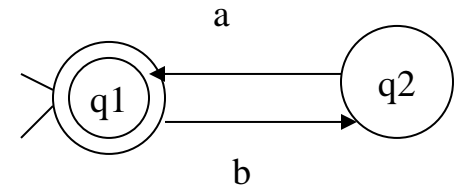
(a) accepts  
a, aa, aaa, ...



(b) accepts b or  
a, aa, aaa, aaaa, ...



(c) accepts  
bba, bbba, ..., or  
a, aa, aaa, aaaa, ...



(d) accepts  
ba, baba, ...

A finite-state machine  $M$  is defined by a five-tuple  $(Q, F, q_0, S, \delta)$  where

- $Q$  is a finite set of states  $\{q_0, q_1, q_2, \dots, q_n\}$
- $F$  is a subset of final (accepting) state of  $Q$
- $q_0$  is a single start state in  $Q$
- $S$  is an input/output alphabet
- $\delta: Q \times S \rightarrow Q$  maps the current input and current state into the next state

# State table

The behaviors of FSMs can be represented in a table form. For example, a complete representation of the behavior of machine (b) is given in the following table.

State \ Input		
	a	b
q1	q2	q3
q2	q2	$\Phi$
q3	$\Phi$	$\Phi$

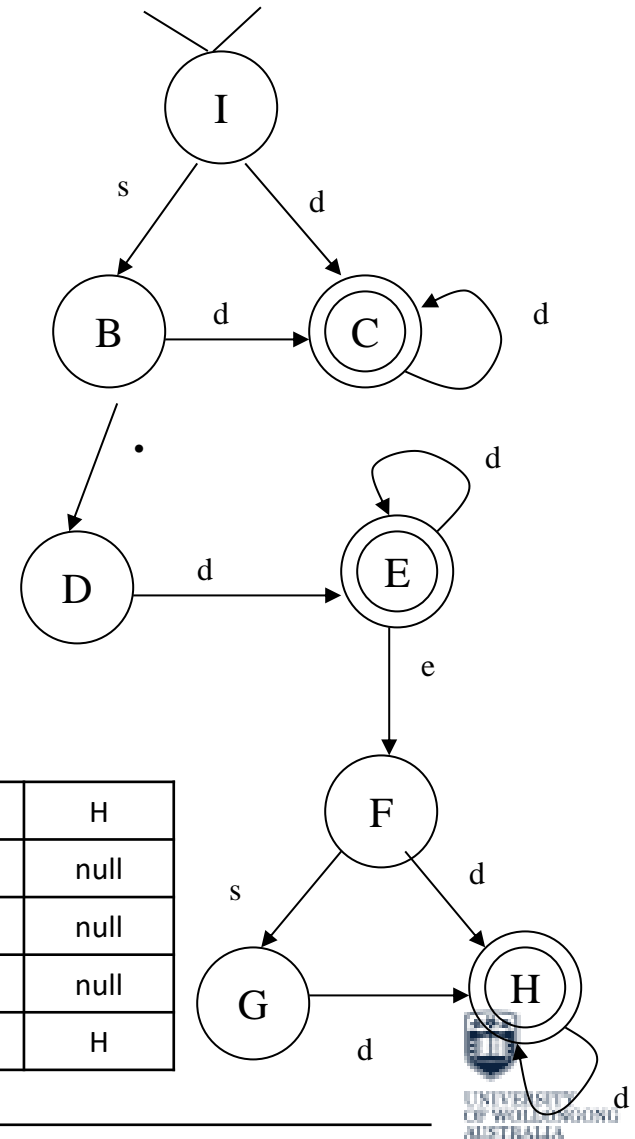
**Example:** Use FSM to give the specification of numeric constants as accepted by the Pascal programming language

Inputs:  $S = \{s, ., e, d\}$

States:  $Q = \{I, B, C, D, E, F, G, H\}$

Final states:  $F = \{C, E, H\}$

Initial state:  $q_0 = I$

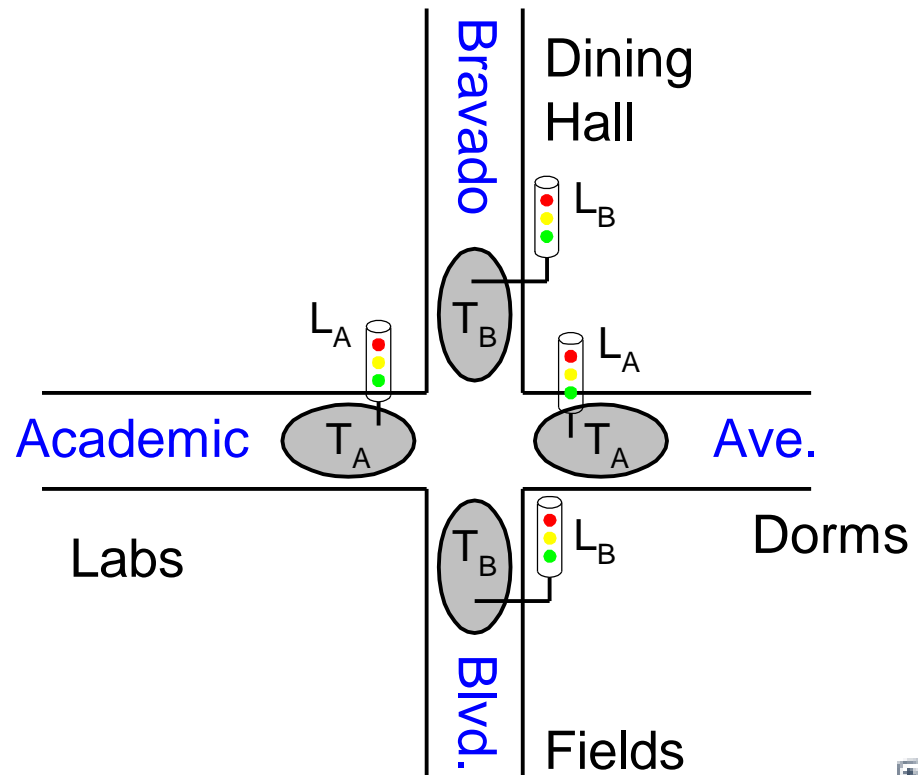


State Table

	I	B	C	D	E	F	G	H
s	B	null	null	null	null	G	null	null
.	null	D	null	null	null	null	null	null
e	null	null	null	null	F	null	null	null
d	C	C	C	E	E	H	H	H

# FSM Example

- Traffic light controller
  - Traffic sensors:  $T_A$ ,  $T_B$  (TRUE when there's traffic)
  - Lights:  $L_A$ ,  $L_B$



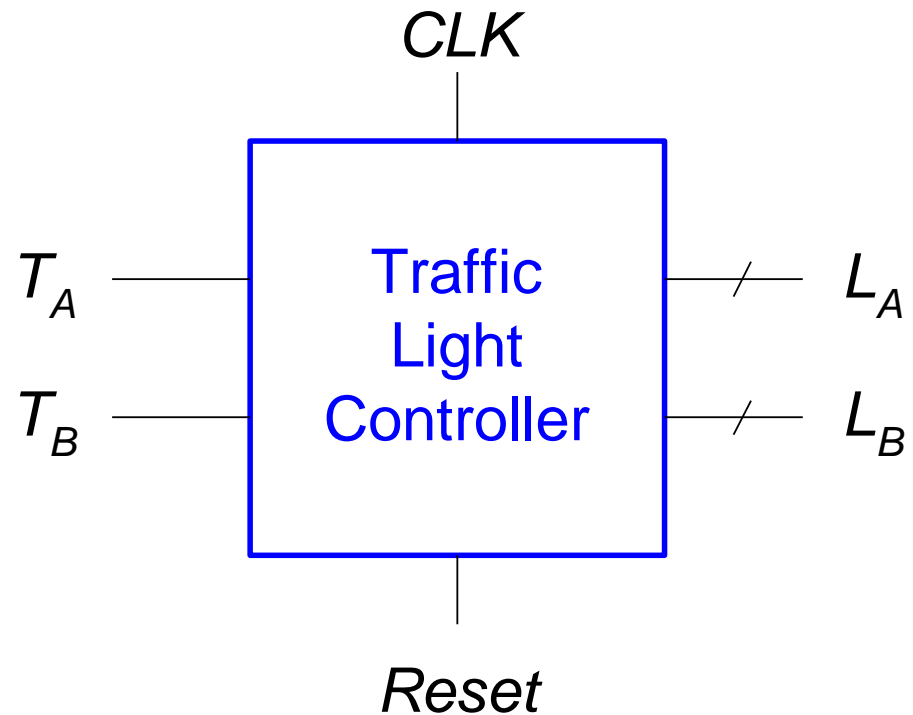


# FSM Black Box

\* Inputs:

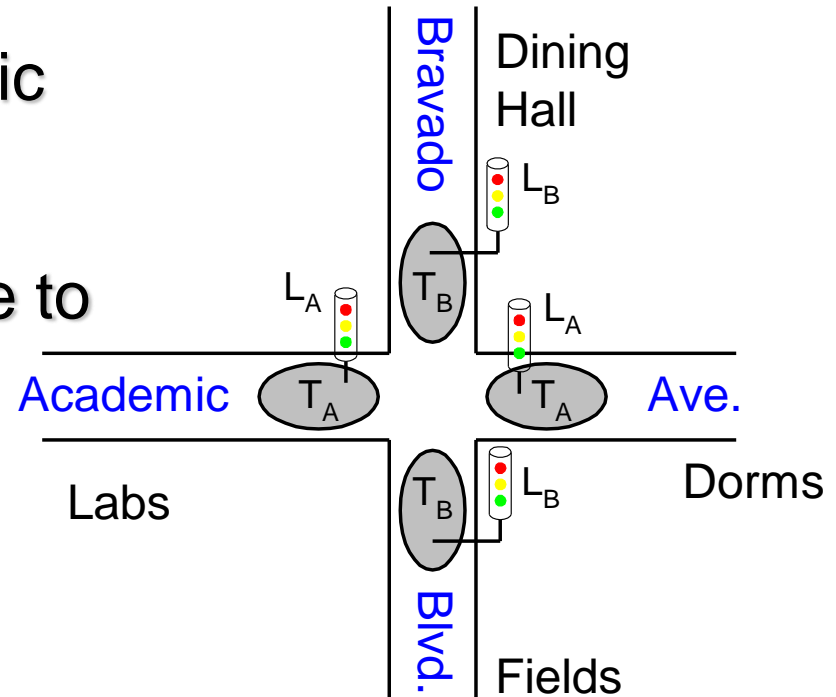
● CLK, Reset,  $T_A$ ,  $T_B$

\* Outputs:  $L_A$ ,  $L_B$



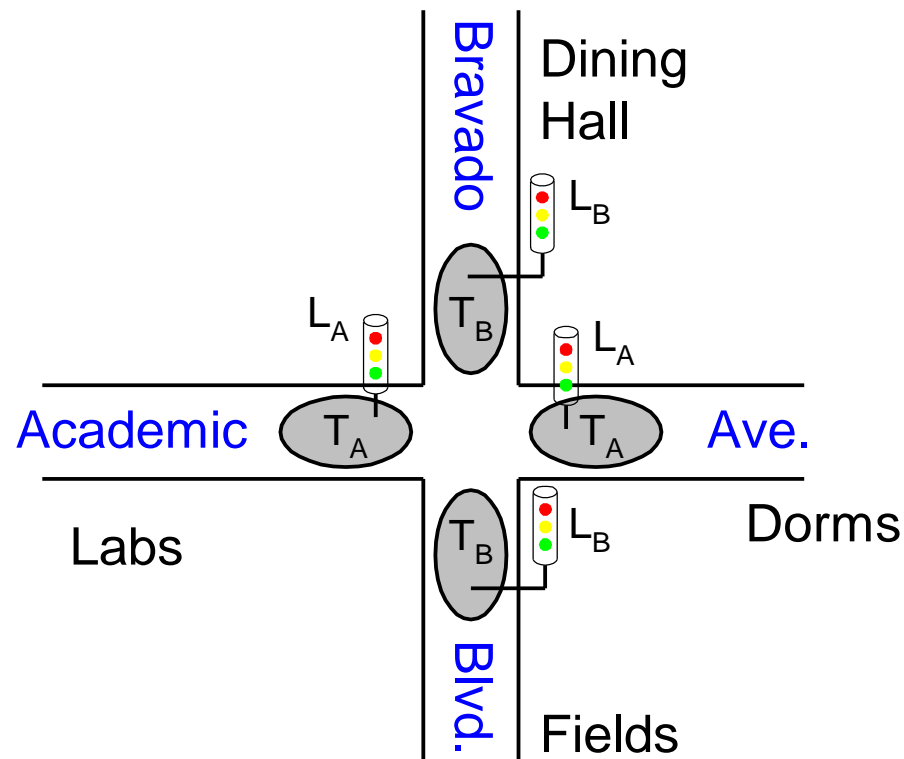
# Design Simple FSM

- When *reset*,  $L_A$  is green and  $L_B$  is red
- As long as traffic on Academic ( $T_A$  high), keep  $L_A$  green
- When  $T_A$  goes low, sequence to traffic on Bravado
- Follow same algorithm for Bravado
- Let's say clock period is 5 sec (time for yellow light)



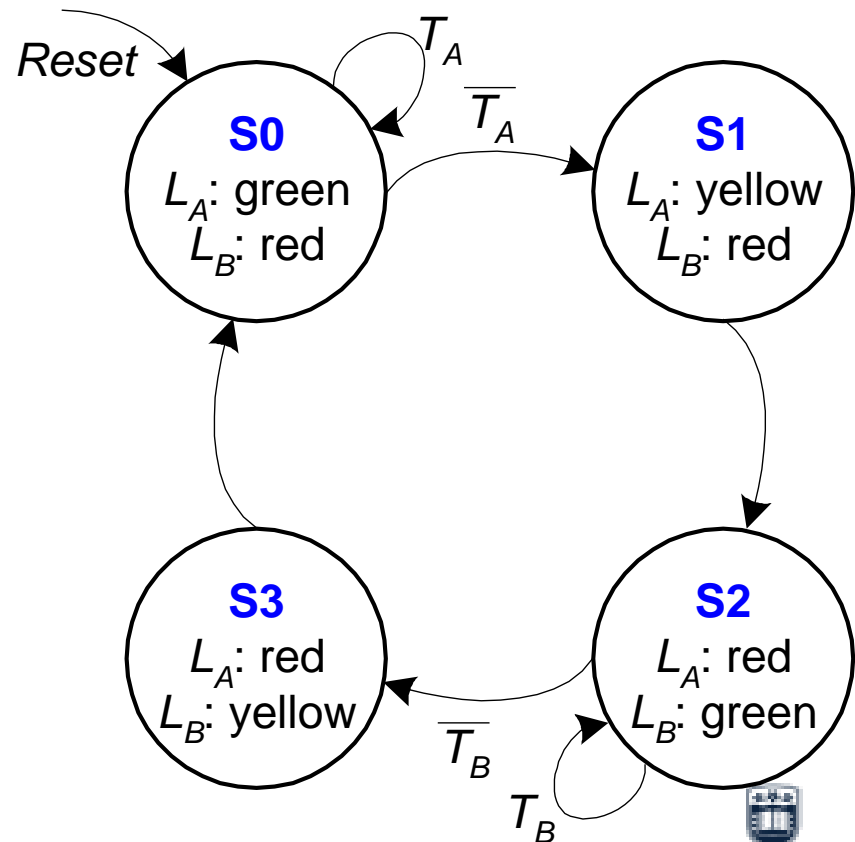
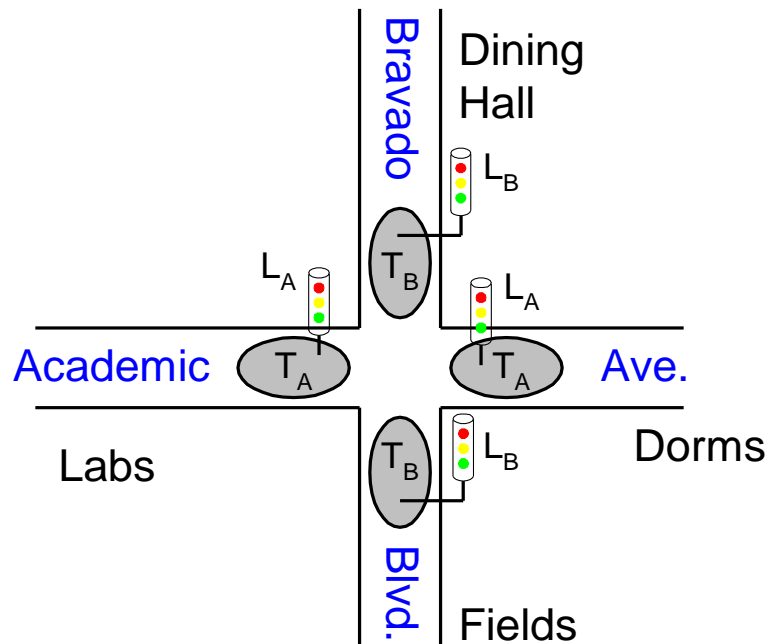
# States

- What sequence do the traffic lights follow?
  - Reset → State 0,  $L_A$  is green and  $L_B$  is red
  - Next (on board)?



# State Transition Diagram

- **Moore FSM: outputs labeled in each state**
- **States: Circles**
- **Transitions: Arcs**



# State Transition Table

Current State $S$	Inputs		Next State $S'$
	$T_A$	$T_B$	
S0	0	X	S1
S0	1	X	S0
S1	X	X	S2
S2	X	0	S3
S2	X	1	S2
S3	X	X	S0



# FSM Encoded State Transition Table

State	Encoding
S0	00
S1	01
S2	10
S3	11

Current State		Inputs		Next State	
$S_1$	$S_0$	$T_A$	$T_B$	$S'_1$	$S'_0$
0	0	0	X	0	1
0	0	1	X	0	0
0	1	X	X	1	0
1	0	X	0	1	1
1	0	X	1	1	0
1	1	X	X	0	0

Current State	Inputs		Next State
$S$	$T_A$	$T_B$	$S'$
S0	0	X	S1
S0	1	X	S0
S1	X	X	S2
S2	X	0	S3
S2	X	1	S2
S3	X	X	S0

$$S'_1 = S_1(XOR)S_0$$

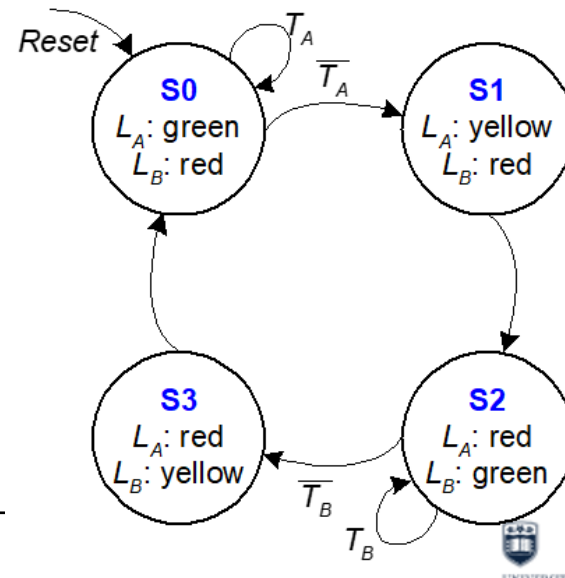
$$S'_0 = \overline{S_0}\overline{S_1} \overline{T_A}(OR) \overline{S_0}S_1\overline{T_B}$$

# FSM Output Table

Output	Encoding
green	00
yellow	01
red	10

Current State		Outputs			
$S_1$	$S_0$	$L_{A1}$	$L_{A0}$	$L_{B1}$	$L_{B0}$
0	0	0	0	1	0
0	1	0	1	1	0
1	0	1	0	0	0
1	1	1	0	0	1

State	Encoding
S0	00
S1	01
S2	10
S3	11



$$L_{A1} = S_1$$

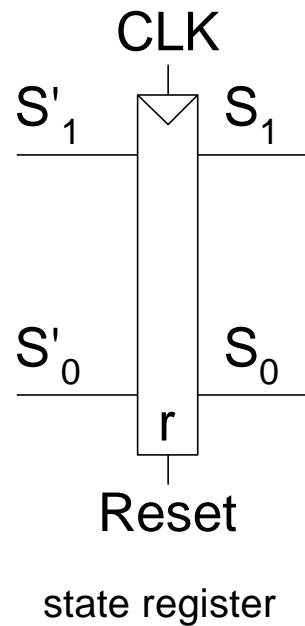
$$L_{A0} = \overline{S_1}S_0$$

$$L_{B1} = \overline{S_1}$$

$$L_{B0} = S_1S_0$$



# FSM Schematic: State Register



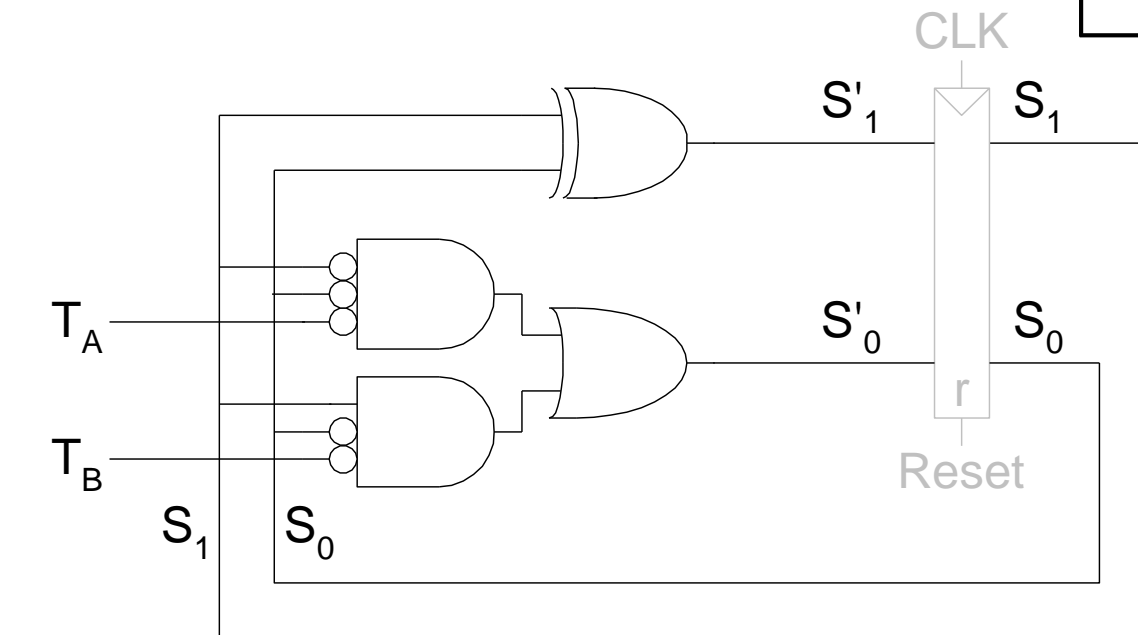


# Next State Logic

$$S'_1 = S_1(XOR)S_0$$

$$S'_0 = \overline{S_0}\overline{S_1} \overline{T_A}(\text{OR}) \overline{S_0}S_1\overline{T_B}$$

Current State		Inputs		Next State	
$S_1$	$S_0$	$T_A$	$T_B$	$S'_1$	$S'_0$
0	0	0	X	0	1
0	0	1	X	0	0
0	1	X	X	1	0
1	0	X	0	1	1
1	0	X	1	1	0
1	1	X	X	0	0



inputs — next state logic — state register

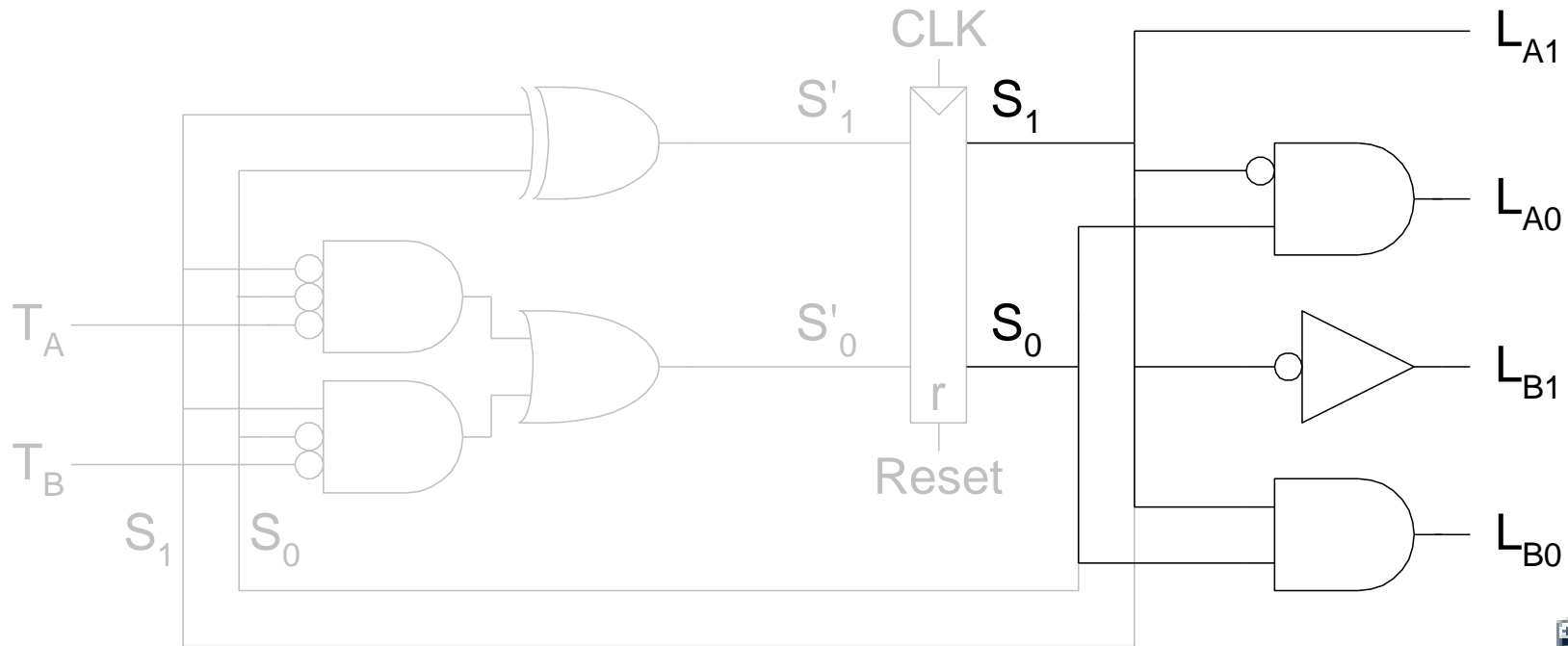
# Output Logic

$$L_{A1} = S_1$$

$$L_{A0} = \overline{S_1} S_0$$

$$L_{B1} = \overline{S_1}$$

$$L_{B0} = S_1 S_0$$



inputs

next state logic

state register

output logic

outputs



UNIVERSITY  
OF WOLLONGONG  
AUSTRALIA