SER 321 B Session

SI Session

Thursday, April 11th 2024

7:00 pm - 8:00 pm MST

Agenda

Concurrency Constructs

Deadlock Examples and Solutions

Distributed Structures

SI Session Expectations

Thanks for coming to the **SER 321** SI session. We have a packed agenda and we are going to try to get through as many of our planned example problems as possible. This session will be recorded and shared with others.

- If after this you want to see additional examples, please visit the drop-in tutoring center.
- We will post the link in the chat now and at the end of the session.
 - tutoring.asu.edu
- Please keep in mind we are recording this session and it will be made available for you to review 24-48 hours after this session concludes.
- Finally, please be respectful to each other during the session.

Interact with us:

Zoom Features



Zoom Chat

- Use the chat feature to interact with the presenter and respond to presenter's questions.
- Annotations are encouraged

Can we name some concurrency structures?

Atomic Operations & Variables

Locks

Semaphores

Monitors

Atomic Operations & Variables

Recall registers...

Ensures updates are immediately visible for the local copy in each thread

```
int main() {
    int w = 5;
    printf("Calculated: %d\n", z);
```

```
main:
           %rbp
    pushq
           %rsp, %rbp
    movq
           $48, %rsp
    call
           main
   movl
           $5, -4(%rbp)
   movl
           $12, -8(%rbp)
           -4(%rbp), %eax
   movl
    addl
           $7, %eax
   movl
           %eax, -12(%rbp)
   movl
           -8(%rbp), %edx
    movl
           -12(%rbp), %eax
    addl
           %edx, %eax
    movl
           %eax, -16(%rbp)
   movl
           -16(%rbp), %eax
    movl
           %eax, %edx
    leag
            .LCO(%rip), %rax
           %rax, %rcx
    movq
    call
           printf
    movl
           $0, %eax
           $48, %rsp
    addq
           %rbp
    popq
    ret
```

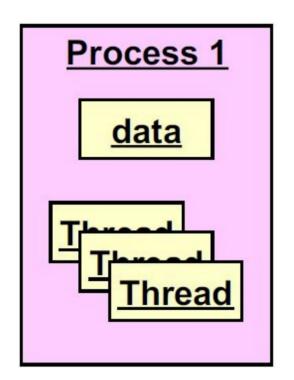
Atomic Operations & Variables

Recall registers...

Ensures updates are immediately visible for the local copy in each thread

Thread X

Copy of Data



The *shared* data variable is only updated if needed

Pros and Cons?

Locks



Acquire the Lock



Open & Enter

Close & Lock

Release the Lock



Unlock & Exit

How am I different from a lock?

Semaphores





More than one stall!

Acquire Lock



Open & Enter

Close & Lock

Semaphores support *more than one* acquirer

Release Lock



Unlock & Exit

When would that be beneficial?

Pros and Cons?

Monitors



You lock the main door instead!



Acquire Lock

Open & Enter

Close & Lock

Covers the entire object

Release Lock



Unlock & Exit

NetworkDeadlock

SER 321 Threading Pitfalls

As the project name implies, we encounter a **deadlock**.

But what happened?

```
class SockServer {
   public static void main (String args[]) throws Exception {
                                                                Server
       ServerSocket serv = new ServerSocket( port: 8888);
       Socket sock = serv.accept();
       ObjectInputStream in = new ObjectInputStream(sock.getInputStream());
       ObjectOutputStream out = new ObjectOutputStream(sock.getOutputStream())
       String s = (String) in.readObject();
       System.out.println("Received " + s);
       out.writeObject("Back at you");
       System.out.println("Received " + s);
       in.close();
```

```
PS C:\ASU\SER321\examples_repo\ser321examples\Threads\NetworkDeadlock> gradle server
<=======---> 75% EXECUTING [1m 33s]
> :server
```

```
PS C:\ASU\SER321\examples_repo\ser321examples\Threads\NetworkDeadlock> gradle client
Starting a Gradle Daemon, 1 busy and 1 stopped Daemons could not be reused, us e --status for details
<-----> 75% EXECUTING [53s]
> :client
```

Deadlock

How can we fix this?

SER 321

Concurrency Structures

What happened??

```
PS C:\ASU\SER321\examples_repo\ser321examples\Threads\Deadlock> gradle run
Starting a Gradle Daemon (subsequent builds will be faster)

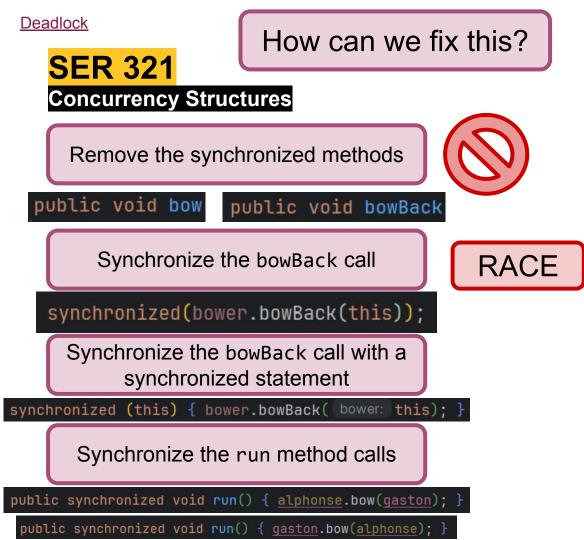
> Task :run
Alphonse: Gaston has bowed to me!
Gaston: waiting to bow back
Gaston: Alphonse has bowed to me!
Alphonse: waiting to bow back
<========---> 75% EXECUTING [18s]
> :run
```

```
public class Deadlock {
    static class Friend {
       private final String name;
       public Friend(String name) { this.name = name; }
       public String getName() { return this.name; }
       public synchronized void bow(Friend bower) {
            System.out.format("%s: %s"
                    + " has bowed to me!%n",
                    this.name, bower.getName());
            System.out.format("%s: waiting to bow back%n", bower.getName());
            bower.bowBack( bower: this);
       public synchronized void bowBack(Friend bower) {
            System.out.format("%s: waiting", this.name);
            System.out.format("%s: %s"
                    + " has bowed back to me!%n",
                    this.name, bower.getName());
   public static void main(String[] args) {
        final Friend alphonse =
                new Friend( name: "Alphonse");
        final Friend gaston =
                new Friend( name: "Gaston");
        new Thread(new Runnable() {
            public void run() { alphonse.bow(gaston); }
       }).start();
        new Thread(new Runnable() {
           public void run() { gaston.bow(alphonse); }
       }).start();
```

```
Deadlock
                         How can we fix this?
    SER 321
    Concurrency Structures
      Remove the synchronized methods
  public void bow
                      public void bowBack
        Synchronize the bowBack call
    synchronized(bower.bowBack(this));
     Synchronize the bowBack call with a
           synchronized statement
synchronized (this) { bower.bowBack( bower: this); }
       Synchronize the run method calls
public synchronized void run() { alphonse.bow(gaston); }
```

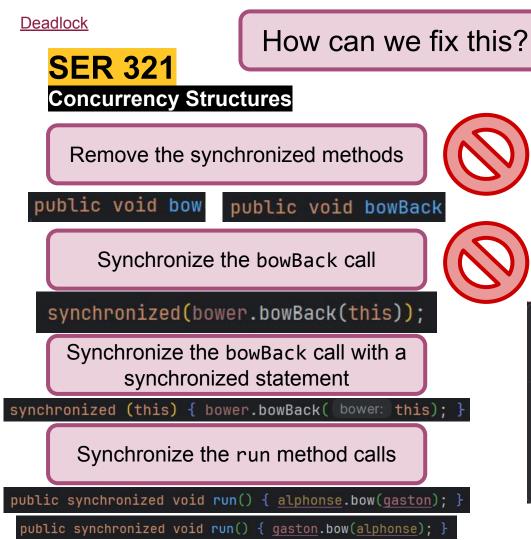
public synchronized void run() { gaston.bow(alphonse); }

```
public class Deadlock {
    static class Friend {
        private final String name;
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                    this.name, bower.getName());
            System.out.format("%s: waiting to bow back%n", bower.getName());
            bower.bowBack( bower: this);
        public synchronized void bowBack(Friend bower) {
            System.out.format("%s: waiting", this.name);
            System.out.format("%s: %s"
                    + " has bowed back to me!%n",
                    this.name, bower.getName());
    public static void main(String[] args) {
        final Friend alphonse =
                new Friend( name: "Alphonse");
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        new Thread(new Runnable() {
            public void run() { alphonse.bow(gaston); }
        }).start();
       new Thread(new Runnable() {
            public void run() { gaston.bow(alphonse); }
       }).start();
```



```
static class Friend {
> Task :run
Alphonse: Gaston has bowed to me!
Gaston: waiting to bow back
Gaston: Alphonse has bowed to me!
Alphonse: waiting to bow back
Alphonse: waiting
Alphonse: Gaston has bowed back to me!
Gaston: waiting
Gaston: Alphonse has bowed back to me!
          + " has bowed back to me!%n",
> Task :run
Alphonse: Gaston has bowed to me!
Gaston: waiting to bow back
Gaston: waiting
Gaston: Alphonse has bowed back to me!
Gaston: Alphonse has bowed to me!
Alphonse: waiting to bow back
Alphonse: waiting
Alphonse: Gaston has bowed back to me!
```

public class Deadlock {



```
public class Deadlock {
              static class Friend {
                  private final String name;
                  public Friend(String name) { this.name = name; }
                  public String getName() { return this.name; }
                  public synchronized void bow(Friend bower) {
                      System.out.format("%s: %s"
                              + " has bowed to me!%n",
                              this.name, bower.getName());
                      System.out.format("%s: waiting to bow back%n", bower.getName());
                      bower.bowBack( bower: this);
                  public synchronized void bowBack(Friend bower) {
                      System.out.format("%s: waiting", this.name);
                      System.out.format("%s: %s"
                              + " has bowed back to me!%n",
                        Object
© Deadlock.Friend
public void bowBack(
     @NotNull > Deadlock.Friend bower
Carrier Deadlock.main
                  }).start();
```

Deadlock

How can we fix this?

SER 321

Concurrency Structures

Remove the synchronized methods



public class Deadlock {

static class Friend {

private final String name;

> Task :run

public String getName() { return this.name; }

public void bow

public void bowBack

Synchronize the bowBack call



synchronized(bower.bowBack(this));

Synchronize the bowBack call with a synchronized statement



synchronized (this) { bower.bowBack(bower: this);

Synchronize the run method calls



public synchronized void run() { alphonse.bow(gaston); } public synchronized void run() { gaston.bow(alphonse); }

Gaston: waiting Gaston: Alphonse has bowed back to me! Gaston: Alphonse has bowed to me! Alphonse: waiting to bow back Alphonse: waiting Alphonse: Gaston has bowed back to me! Deprecated Gradle features were used in You can use '--warning-mode all' to show See https://docs.gradle.org/7.4.2/userg BUILD SUCCESSFUL in 1s 2 actionable tasks: 2 executed

Alphonse: Gaston has bowed to me!

Gaston: waiting to bow back



RECAP

Atomic Operations & Locks

YOU control the locks directly

Semaphores

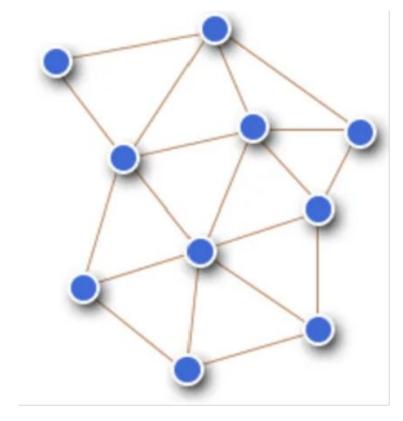
Locks

Monitors

Locks managed for you



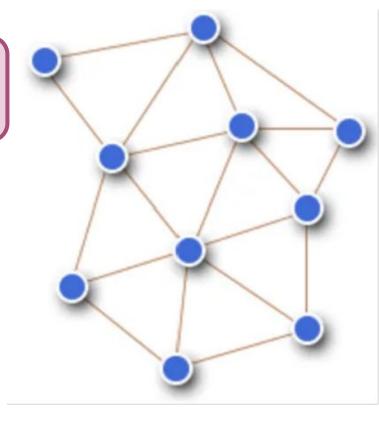
What do we mean by "Distributed Systems" or "Distributed Algorithms"?



SER 321 Distributed Systems

Remember that we are operating in *reality*

- Nodes will fail
- Web of nodes will constantly change
- Network is not always reliable
- Latency is always present
- The path traversed changes
- Some resources must be shared
- You need to prevent the pitfalls!
 - No deadlocks
 - No starvation
 - No error states

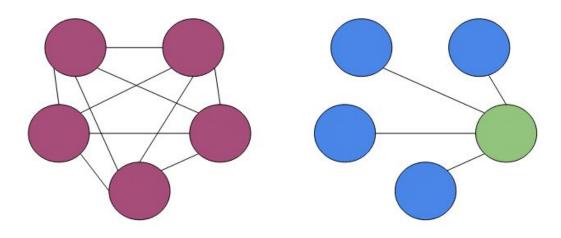




Main and Worker

Peer to Peer

Which is which?

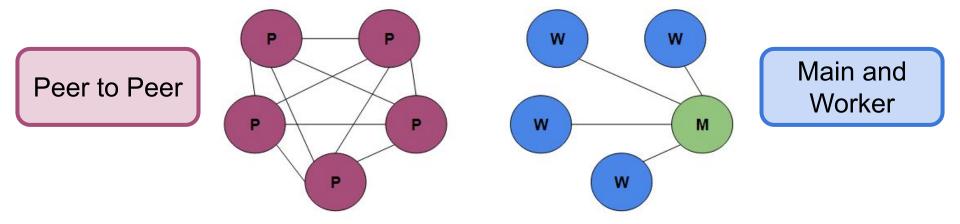




Main and Worker

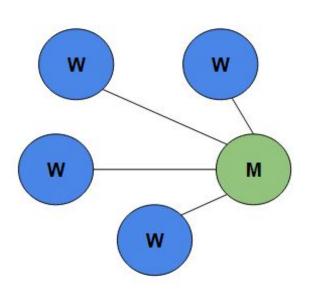
Peer to Peer

Which is which?



SER 321 Distributed Systems

Pros and Cons



Pros:

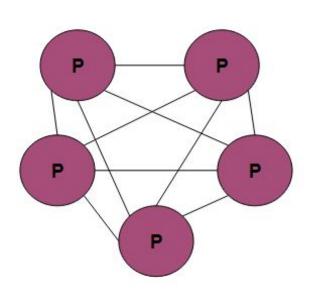
- Straightforward setup
- Logic is centralized
- Communication is linear

Cons:

• Single point of failure

SER 321 Distributed Systems

Pros and Cons



Pros:

- Peers can join or leave as needed
- Robust no single point of failure

Cons:

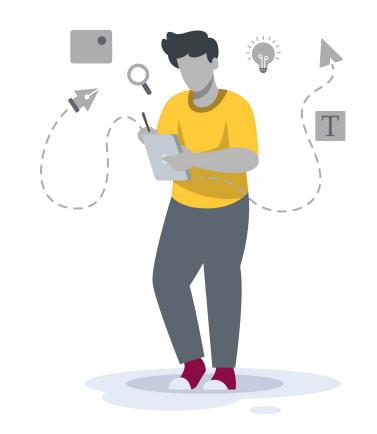
- Communication is complex
- Setup is not as straightforward
- Client connections are handled differently

SER 321 Scratch Space

Questions?

Survey:

http://bit.ly/ASN2324



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Upcoming Events

SI Sessions:

- Sunday, April 14th at 7:00 pm MST
- Monday, April 15th at 7:00 pm MST
- Thursday, April 18th at 7:00 pm MST

Review Sessions:

- Sunday, April 21st at 7:00 pm MST
- Thursday, April 25th Session is cancelled

More Questions? Check out our other resources!

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Access the drop-in queue

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Don't forget to check out the Online Study Hub for additional resources!

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^{*}Available slots for this pilot are limited

Additional Resources

- Course Repo
- Gradle Documentation
- GitHub SSH Help
- Linux Man Pages
- OSI Interactive
- MDN HTTP Docs
 - Requests
 - Responses
- JSON Guide
- org.json Docs
- javax.swing package API
- Swing Tutorials
- <u>Dining Philosophers Interactive</u>
- Austin G Walters Traffic Comparison