



Source: <http://www.bbb3viz.com>

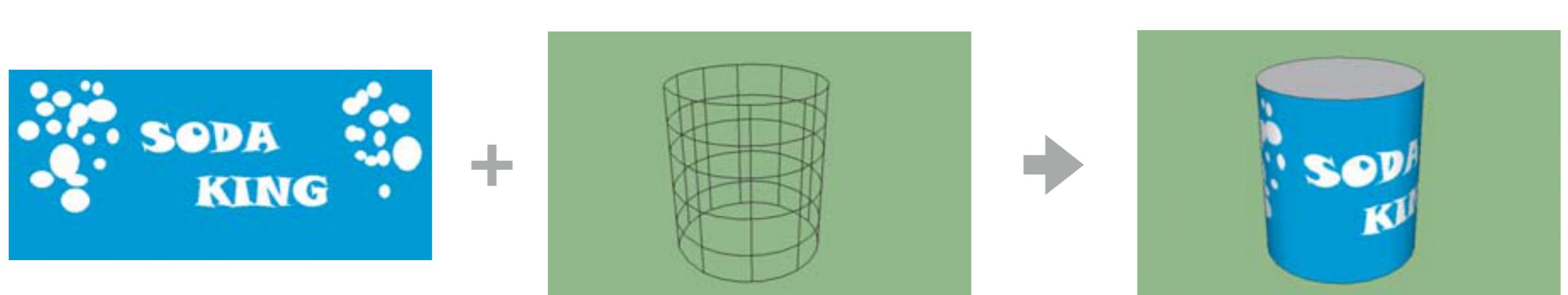
# Texture Mapping

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Introduction to Computer Graphics  
CSE 533/333

# Texture

- Objects have variation in reflectance across the surface
- A common technique to handle such variations is to store the reflectance as a function or a pixel-based image and “map” it onto a surface



Source: Kefei Lei

# Texture

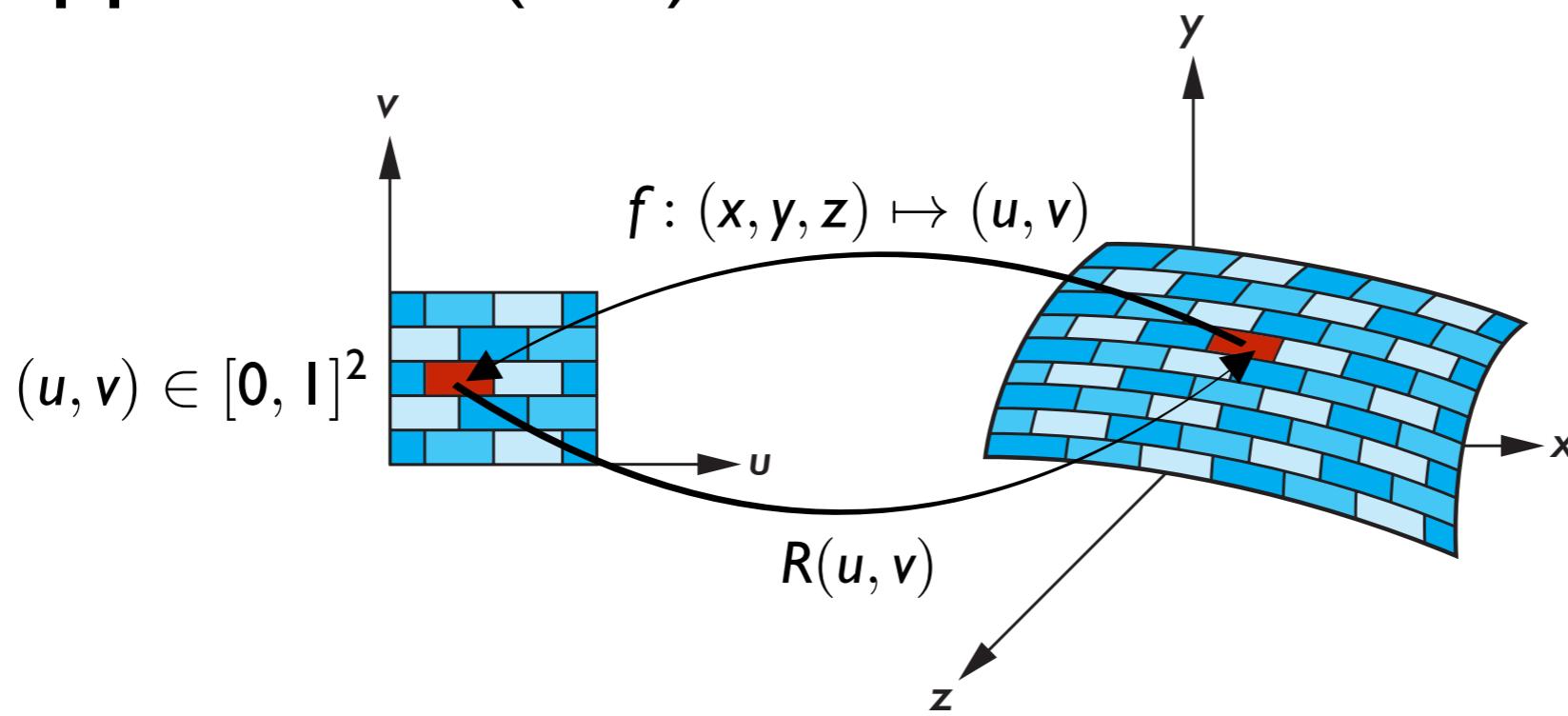
- The function or image is called *Texture*
- The process of controlling reflectance properties is called *texture mapping*



Source: Alec Jacobson, <http://alecjacobson.com>

# 2D Texture Mapping

- For 2D texture mapping, a local coordinate system called  $uv$  is used to create reflectance  $R(u, v)$
- During texture mapping, each surface point  $(x, y, z)$  is mapped to a  $(u, v)$  coordinate to color it with  $R(u, v)$



# Texture Mapping on Sphere

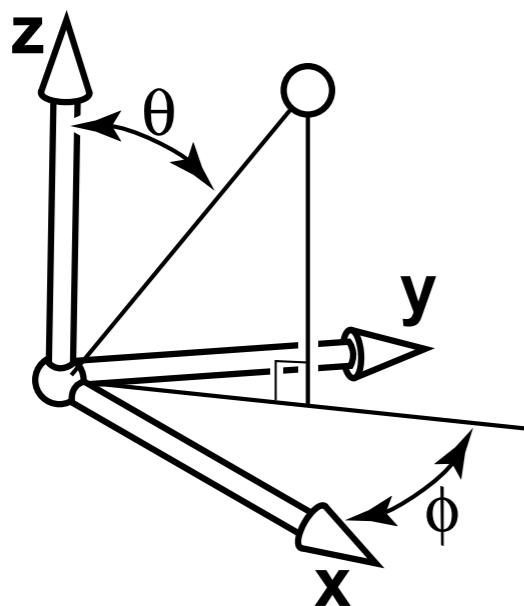
## Example

- To map  $(u, v)$  onto a sphere, we first compute spherical coordinates
- For a sphere with radius  $R$  and centre  $(x_c, y_c, z_c)$

$$x = x_c + R \cos\phi \sin\theta$$

$$y = y_c + R \sin\phi \sin\theta$$

$$z = z_c + R \cos\theta$$



$$\theta = \arccos \left( \frac{z - z_c}{R} \right),$$

$$\phi = \text{arctan2} (y - y_c, x - x_c)$$

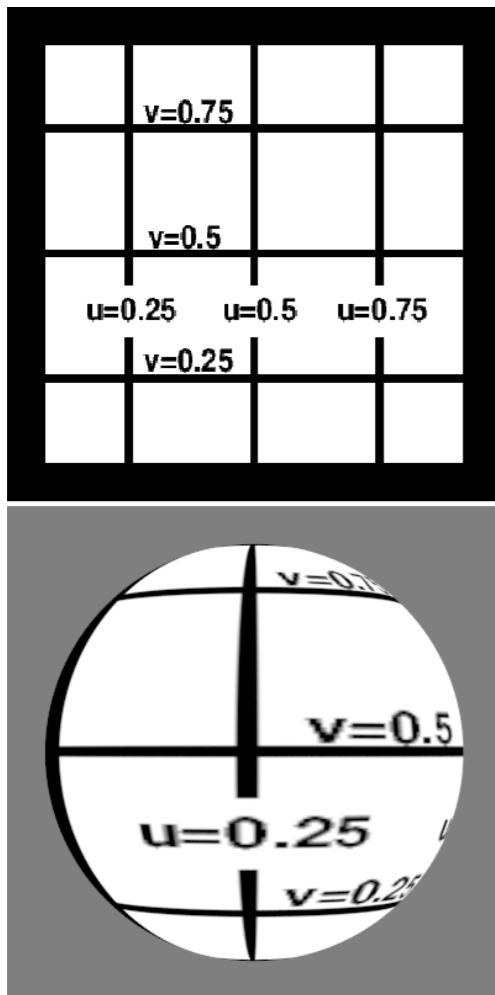
$$\theta \in [0, \pi]$$

$$\phi \in [-\pi, \pi]$$

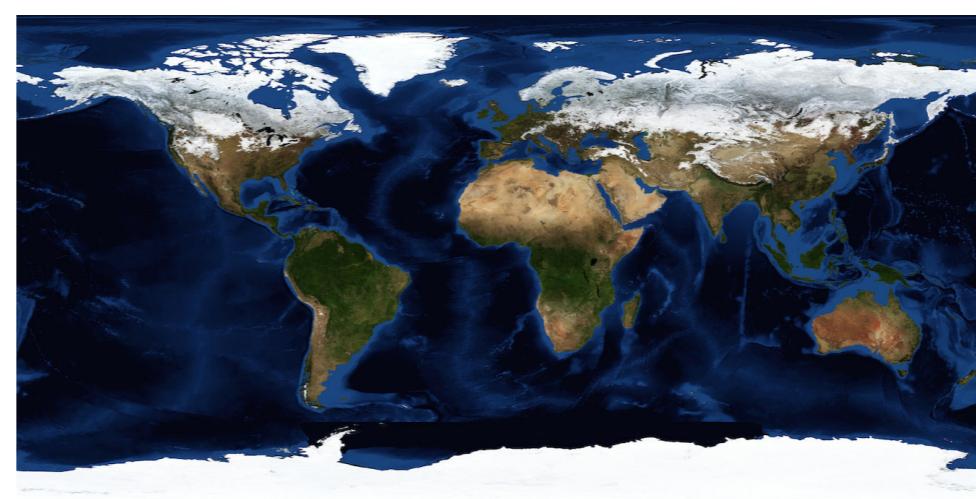
# Texture Mapping on Sphere

## Example

Required mapping:



$$u = \frac{\phi}{2\pi},$$
$$v = \frac{\pi - \theta}{\pi}$$



# Texture Mapping on Triangle

## Example

- For surfaces represented by triangle meshes, texture coordinates are defined by storing  $(u, v)$  coordinates at each vertex
- At any point  $(\beta, \gamma)$  inside a triangle, the  $(u, v)$  coordinate is interpolated as

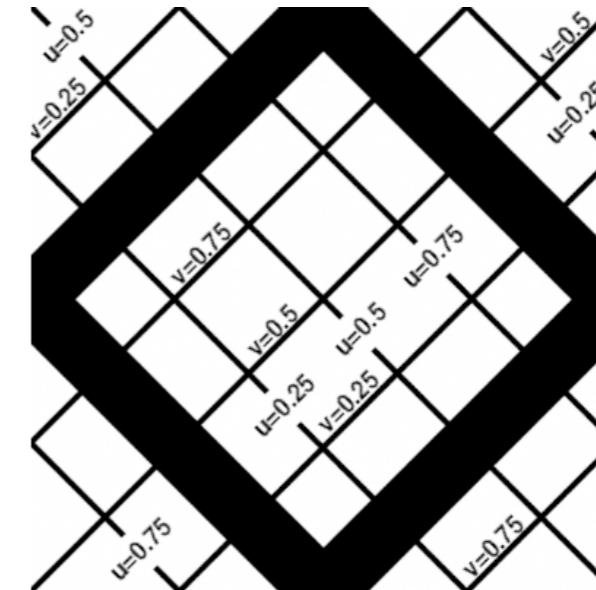
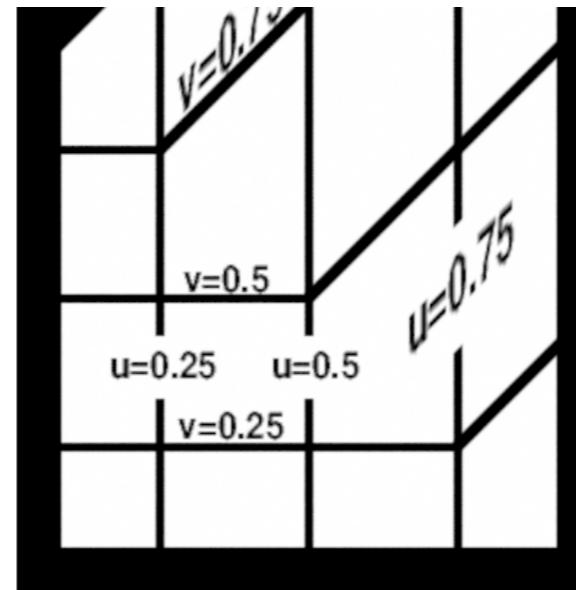
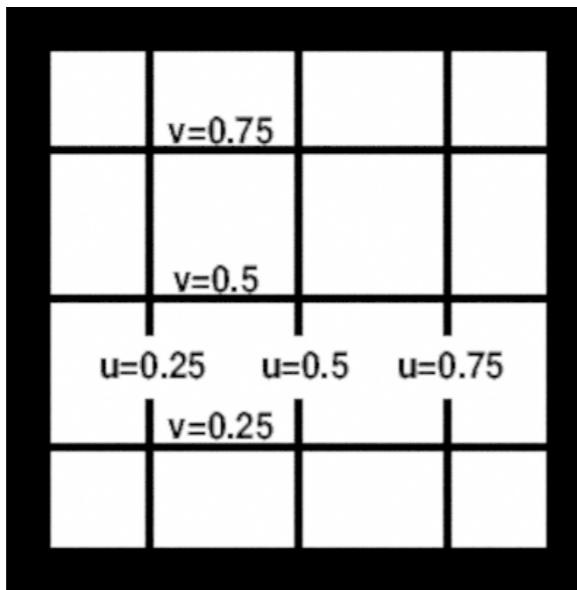
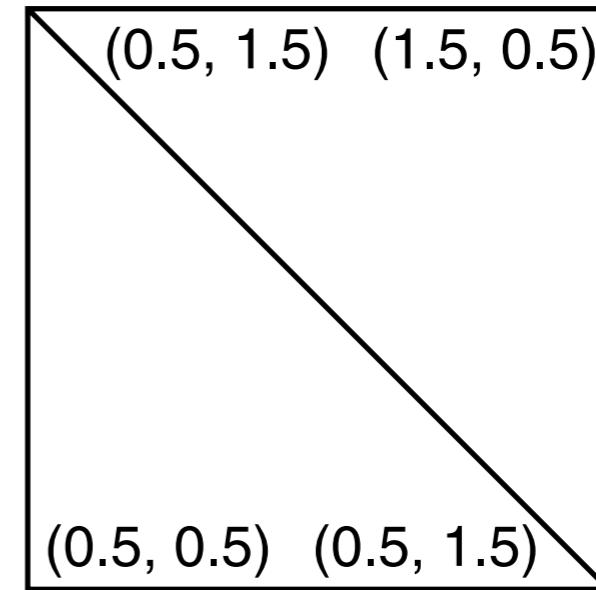
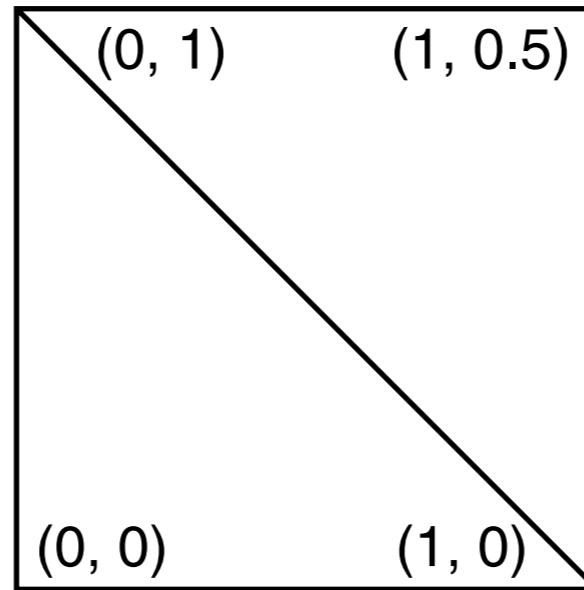
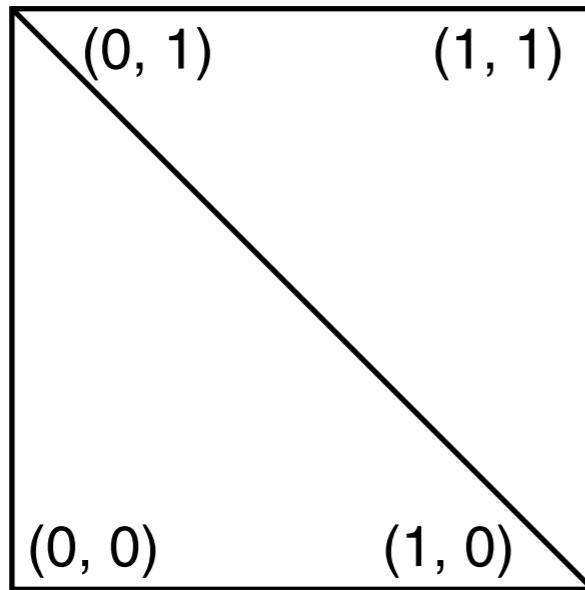
$$u(\beta, \gamma) = (1 - \beta - \gamma)u_b + \beta u_a + \gamma u_c$$

$$v(\beta, \gamma) = (1 - \beta - \gamma)v_b + \beta v_a + \gamma v_c$$

where  $a$ ,  $b$ , and  $c$  are vertices of the triangle

# Texture Mapping on Triangle

Example



# Perspective-correct Textures

- Accounts for the actual 3D positions of vertices
- Screen space interpolation will result in distortions

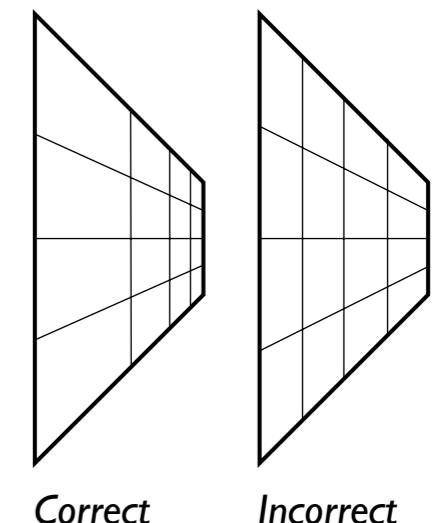
$$f_x = (1 - \alpha) \frac{x_0}{w_0} + \alpha \frac{x_1}{w_1}$$

- Perspective correct interpolation:

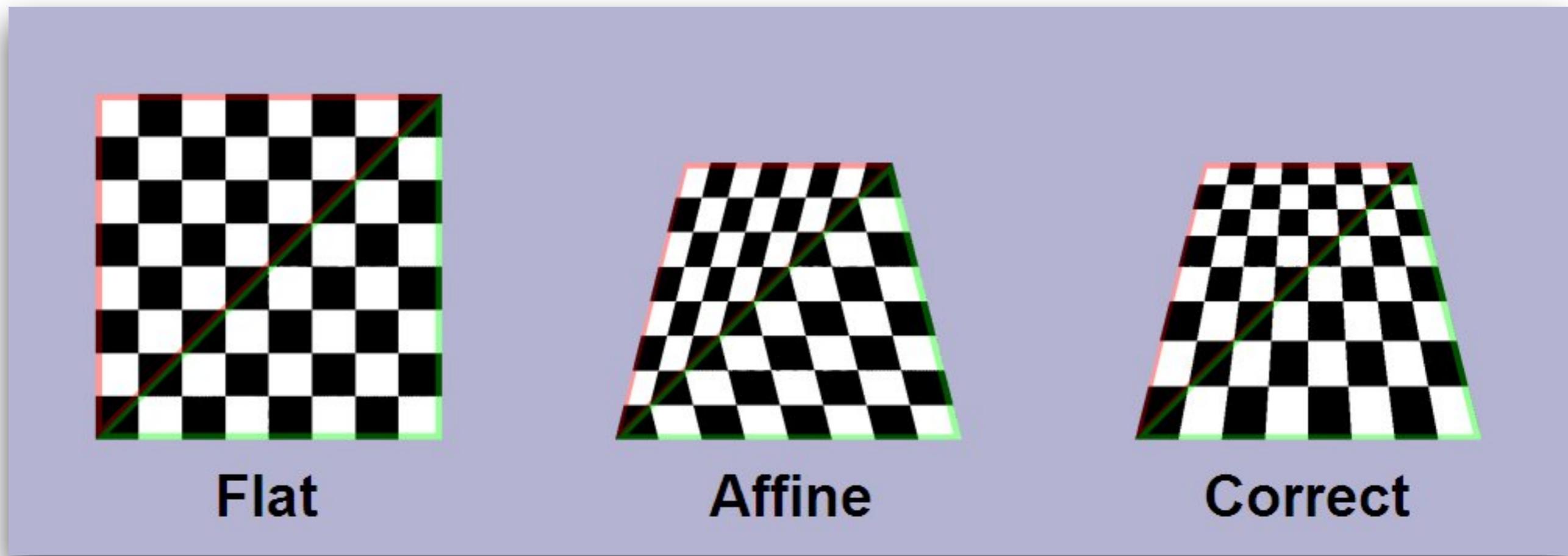
$$f_x = \frac{(1 - \beta)x_0 + \beta x_1}{(1 - \beta)w_0 + \beta w_1}$$

- Post perspective, use:

$$\alpha = \frac{\beta w_1}{\beta w_1 + (1 - \beta)w_0}$$



# Perspective-correct Textures



Source: Wikipedia

# Texture Coordinates

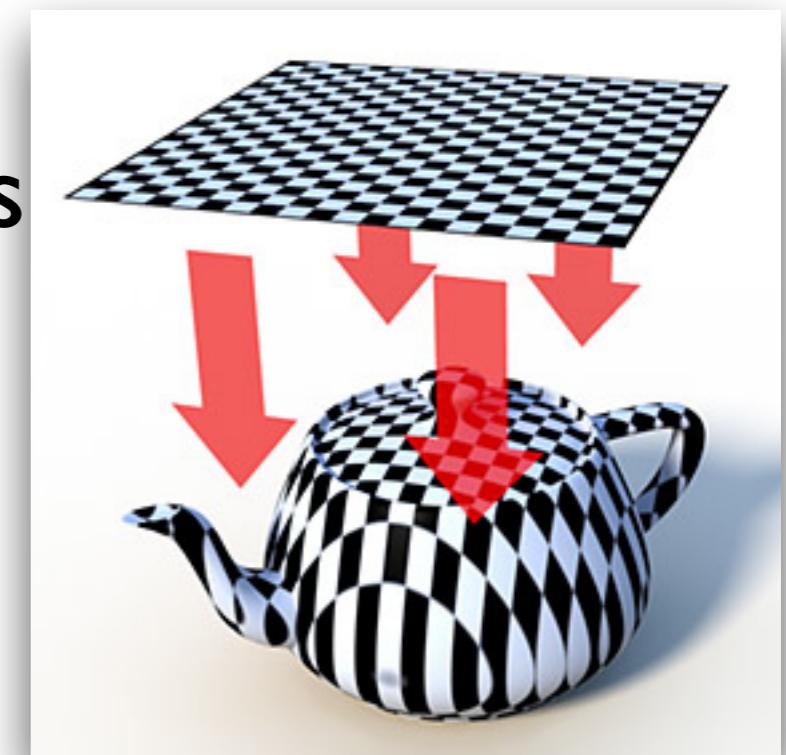
- How do we specify the mapping from an object to texture space?
- We want the following properties:
  - **Piecewise linear** (in order to use interpolation hardware)
  - **Invertible** (go back-forth b/w texture space and surface)
  - **Easy to compute**

# Common Texture Mappings

- Linear/planar/hyperplanar projection
- Cylindrical
- Spherical
- Piecewise-linear or piecewise-bilinear on a plane from explicit per-vertex texture coordinates (UV)
- Normal-vector projection onto a sphere

# Planar Texturing

- Similar to the notion of a movie projector
- Associated image is projected orthographically onto the surface
- Great for flat or nearly flat surfaces



Source: Modo; Luxology, LLC

# Cylindrical Texturing

- The object is surrounded by a large cylinder
- Project from the axis through the object to cylinder
- Great for objects that have some central axis
- If point  $(x, y, z)$  projects to  $(r, \theta, z)$  in cylindrical coordinates, we assign  $(\theta, z)$  texture coordinates

$$u = \frac{\theta}{2\pi}, v = \text{clamp}\left(\frac{z}{z_{max}}, -1, +1\right)$$

$$\text{clamp}(x, a, b) = \begin{cases} x & \text{if } a \leq x \leq b \\ a & \text{if } x < a \\ b & \text{if } x > b. \end{cases}$$

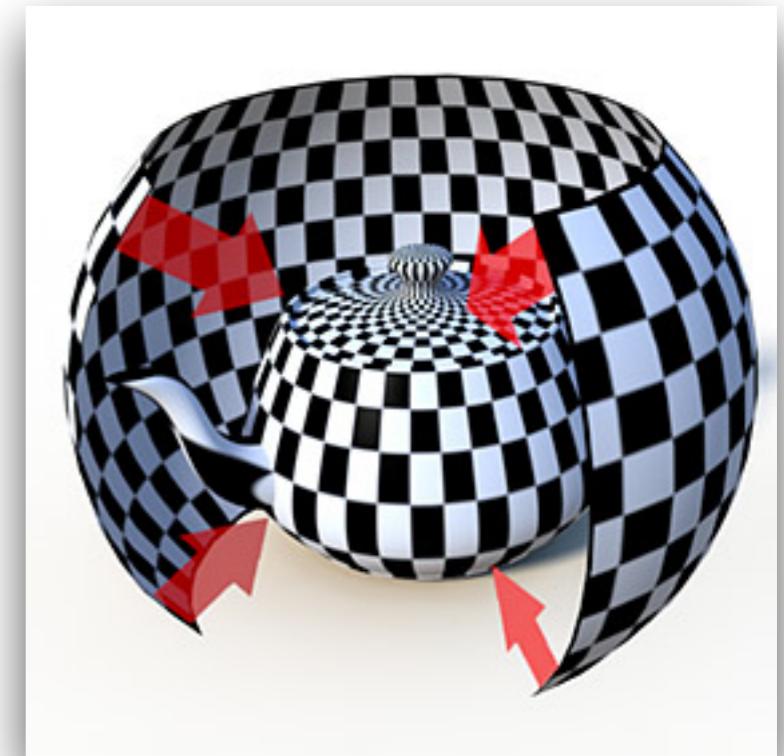


Source: Modo; Luxology, LLC

# Spherical Texturing

- The object is surrounded by a large sphere
- Project from the centre to through the object to sphere
- Great for blobby objects
- If point  $(x, y, z)$  projects to  $(r, \theta, \phi)$  in spherical coordinates, we assign  $(\theta, \phi)$  texture coordinates

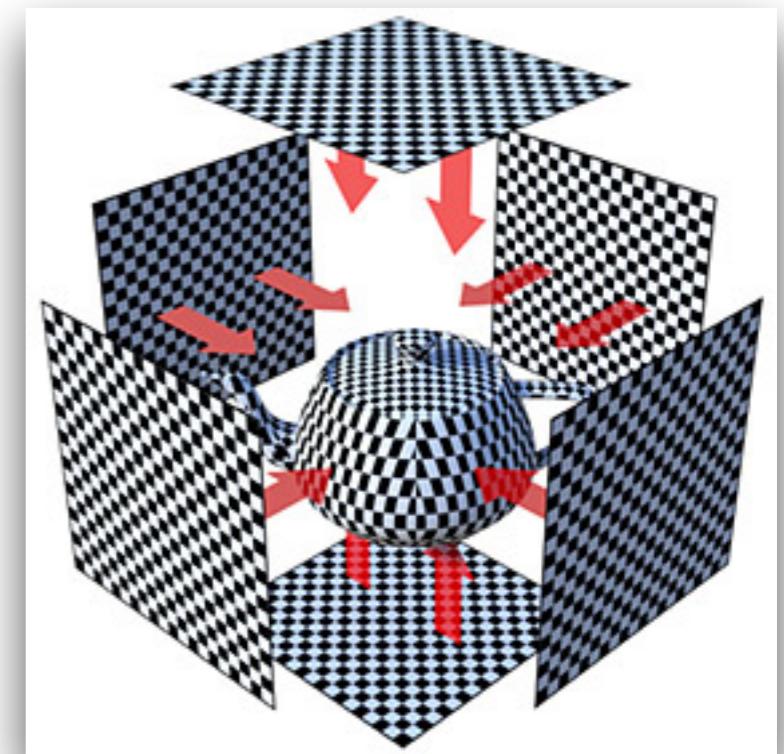
$$u = \frac{\phi}{2\pi}, v = \frac{\pi - \theta}{\pi}$$



Source: Modo; Luxology, LLC

# Box Texturing

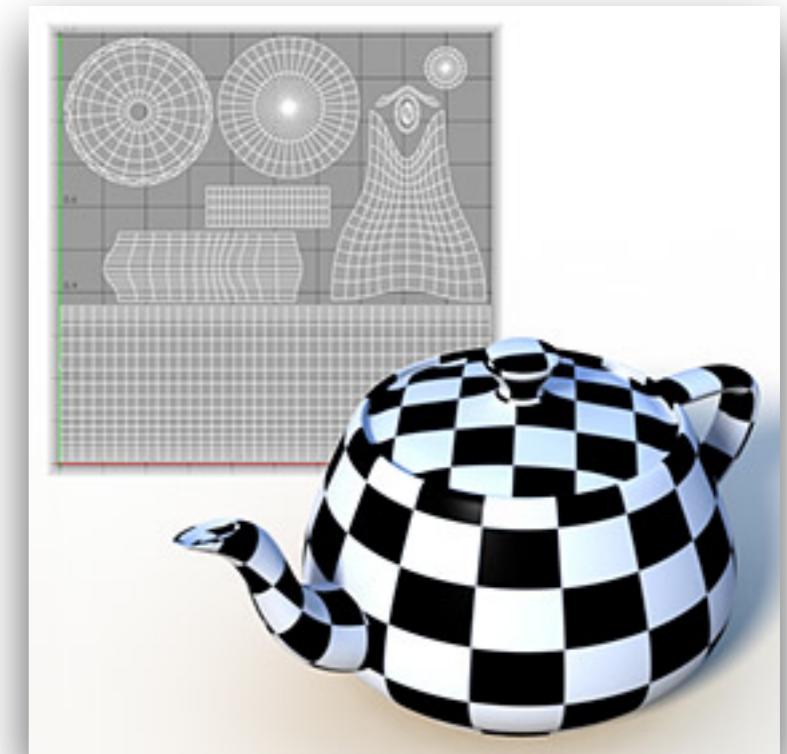
- The texture is *planar* projected through a surface from all six directions (like an inward facing cube)
- Great for cube shaped objects



Source: Modo; Luxology, LLC

# UV Texturing

- Piecewise-linear or piecewise-bilinear on a plane from explicit per-vertex texture coordinates (UV)
- Most common, but needs texture coord. assignment
- At least four ways:
  - Per vertex assignment
  - Texture parameterization
  - Breaking surface into patches
  - Have an artist “paint” the texture

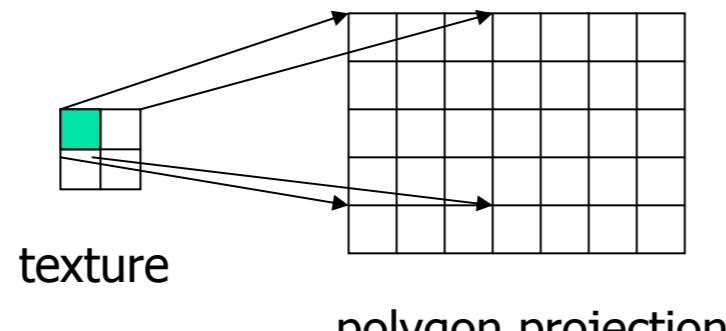


Source: Modo; Luxology, LLC

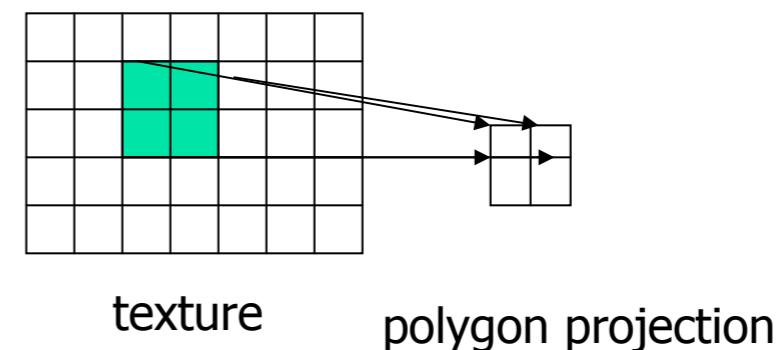
# Texture Filtering

- During texture mapping, one pixel on a textured surface may not correspond to one texel
- Insufficient or incorrect filtering shows up as blockiness/jaggies
- Different correspondence between texel & pixel:
  - Each texel maps onto more than one pixel (*magnification*)
  - Each texel maps exactly onto one pixel
  - Each texel maps onto less than one pixel (*minification*)

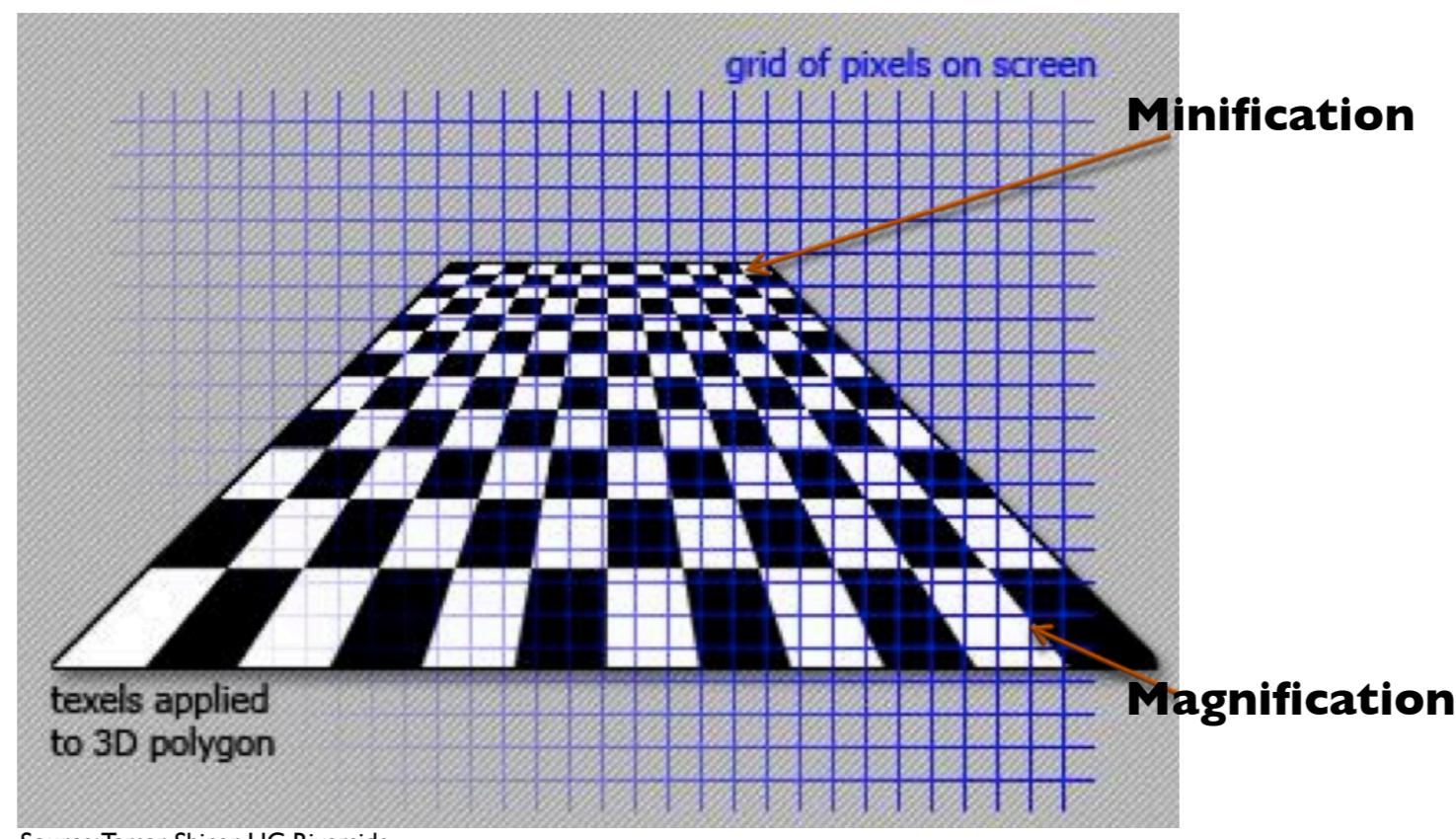
# Texture Filtering



*Magnification*



*Minification*



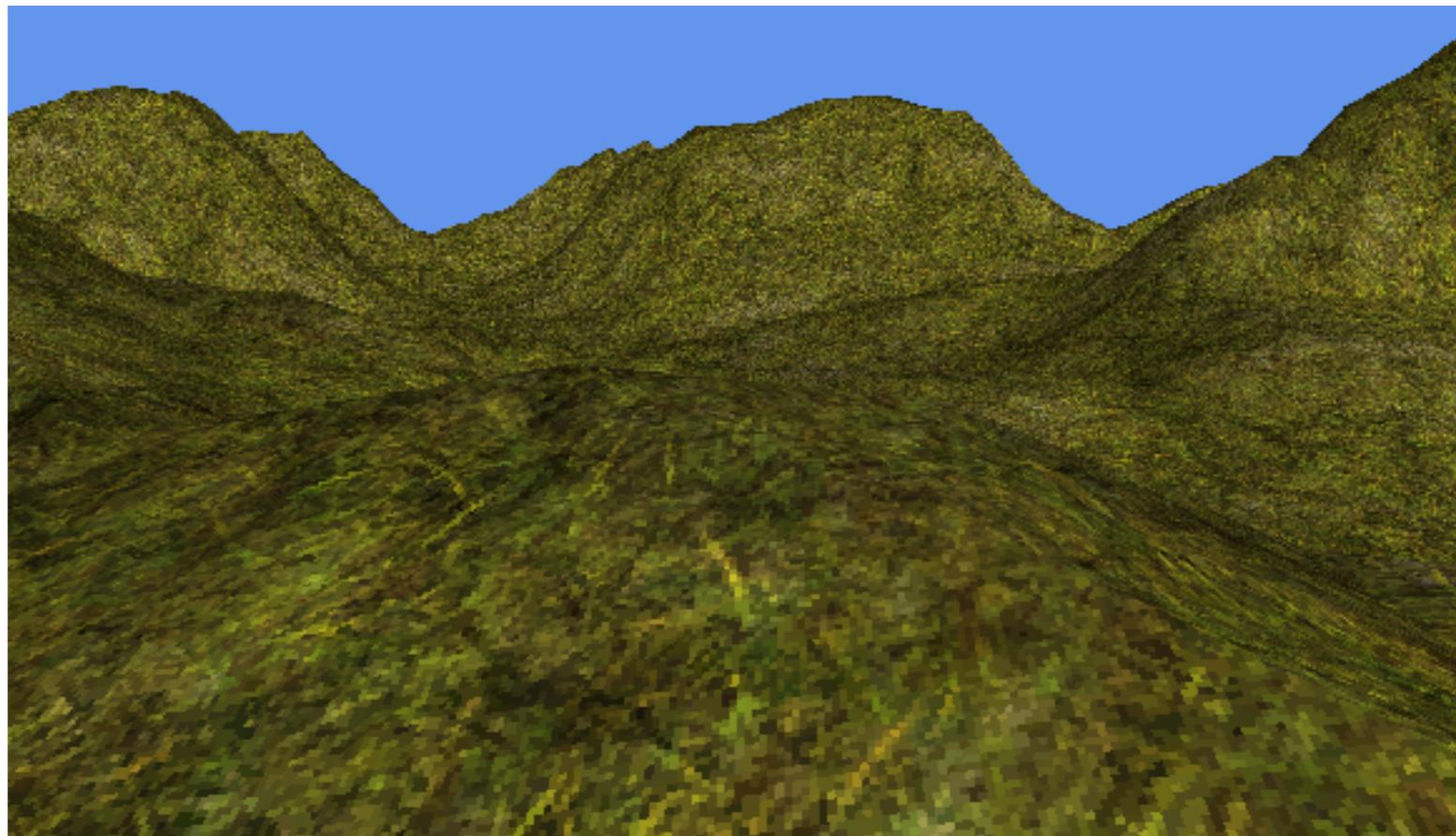
Source: Tamar Shinar, UC Riverside

# Texture Filtering Modes

- Nearest Neighbour
- Bilinear filtering
- Mipmapping
- Anisotropic

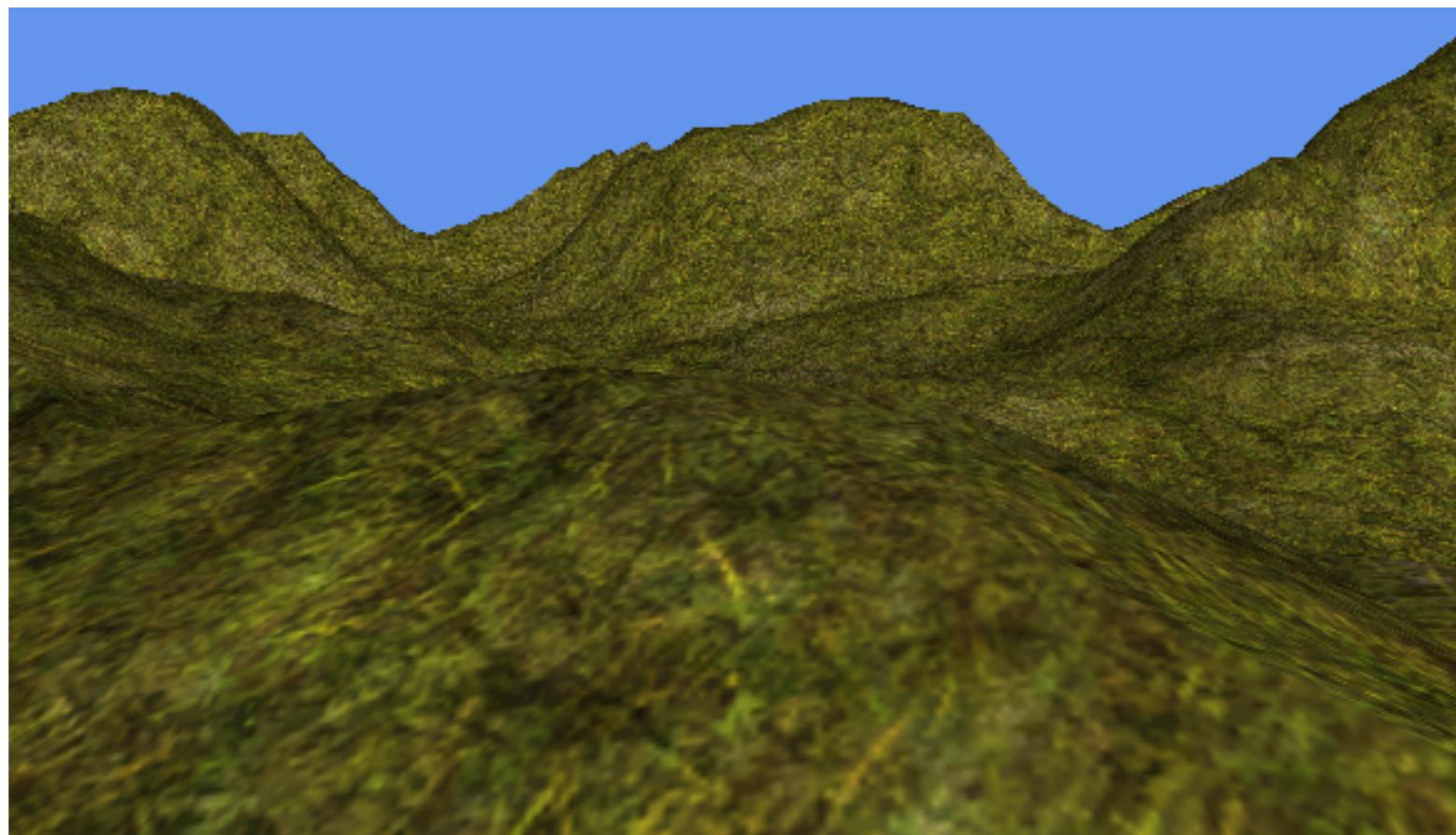
# Nearest Neighbour

- For each destination pixel, round to the closest matching location in the source pixel grid and return its value



# Bi-linear

- For each destination pixel, locate closest matching source pixel grid and interpolate between four neighbouring values in source



# Mipmapping

- A mipmap is a pre-calculated copy of an image that has been shrunk to a lower resolution using a high quality filtering algorithm



Source: Texturing and Lighting in OpenGL, J.V. Oosten

Original = 256x256

Mip 1 = 128x128

Mip 2 = 64x64

Mip 3 = 32x32

Mip 4 = 16x16

Mip 5 = 8x8

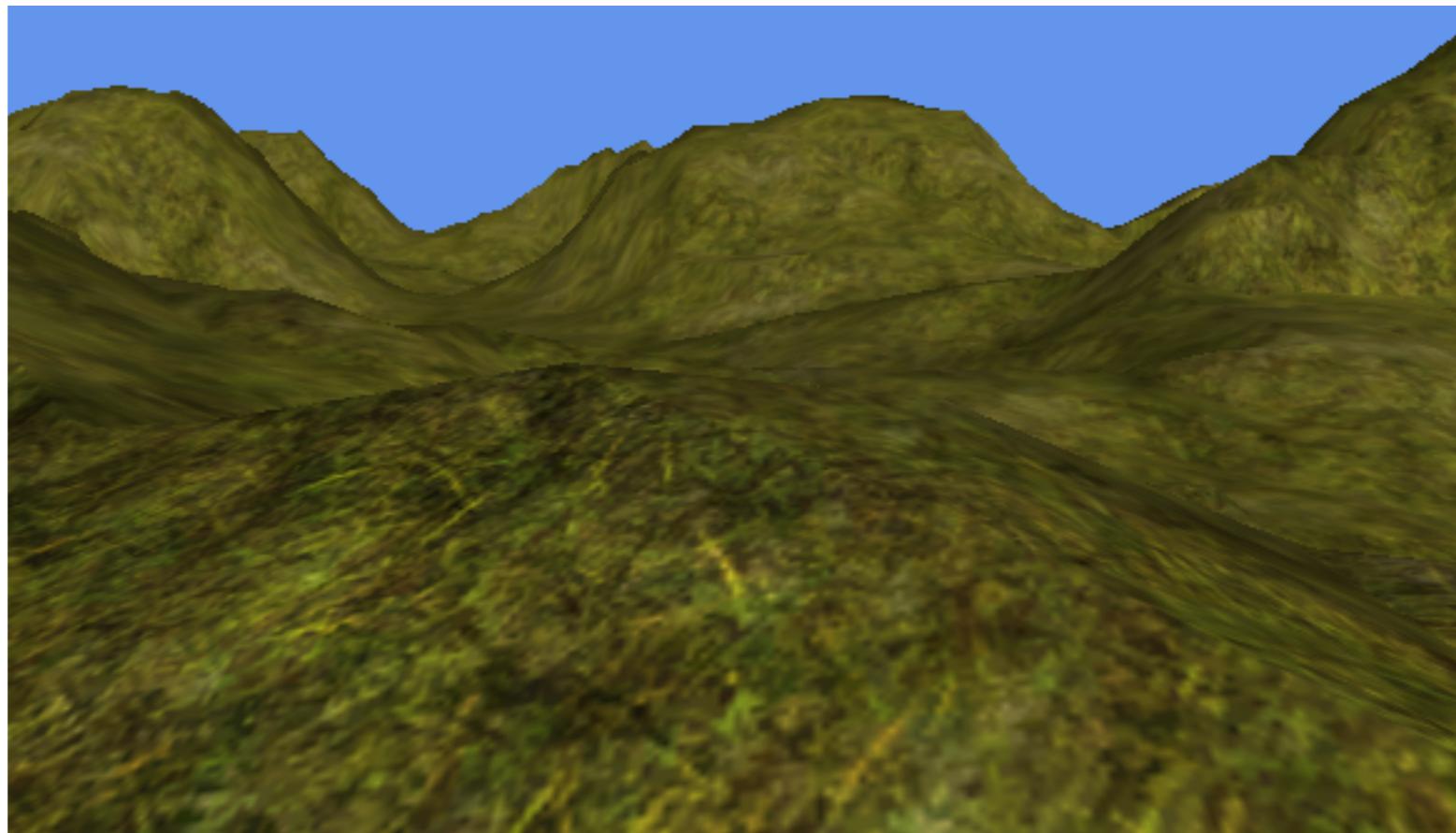
Mip 6 = 4x4

Mip 7 = 2x2

Mip 8 = 1x1

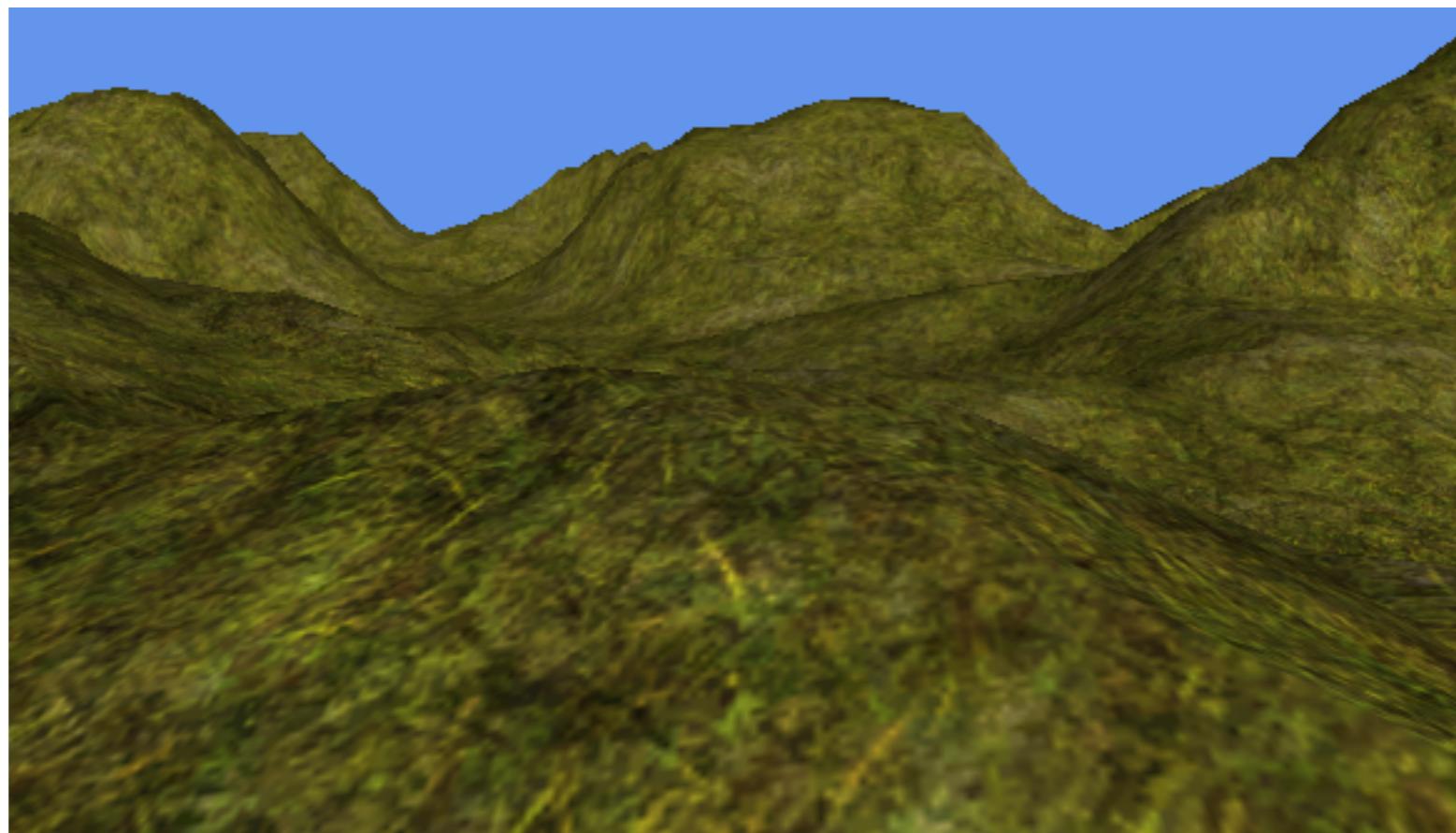
# Mipmapping

- Either nearest-neighbour or bilinear filtering may be combined with mip-map filtering



# Anisotropic

- Recognises when a texture is being scaled differently in different directions, and takes a larger number of samples to compensate



# Texture Synthesis

Procedural texture: little program that computes colour as a function of  $x, y, z$ :

$$f(x, y, z) \mapsto \text{color}$$

- Fourier-like texture
- Perlin noise
- Reaction-diffusion textures
- Data driven texture synthesis



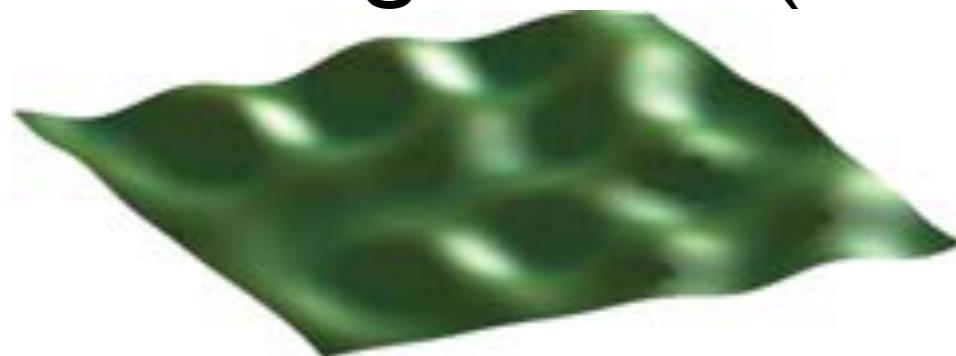
Source: Procedural wood texture, Blender

# Fourier-like Synthesis

- Displacement function

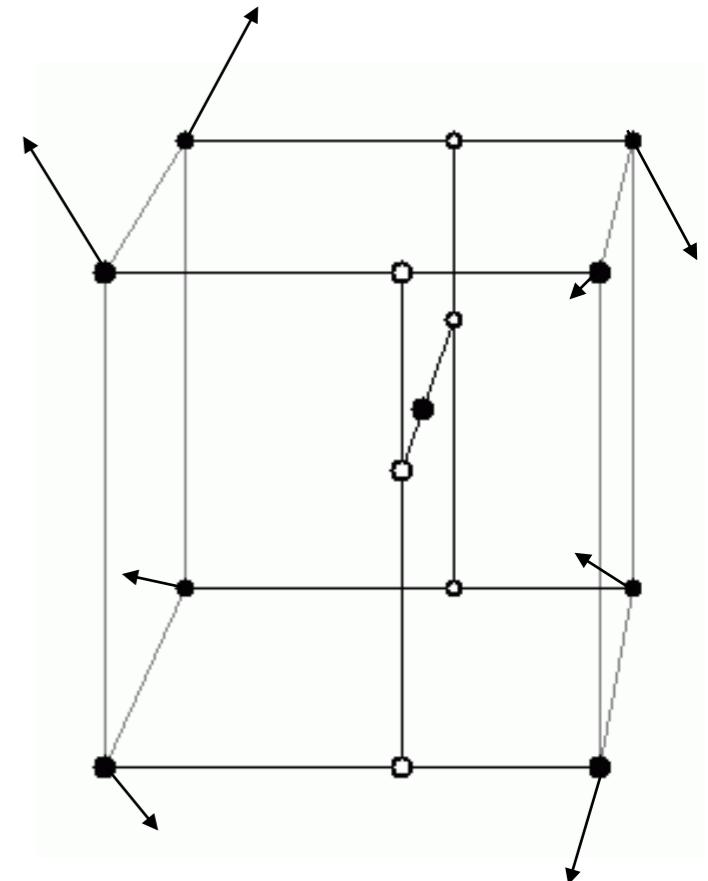
$$d(x, y) = \sum_{i=0}^{n-1} c_i \cos(a_i x + b_i y + c)$$

- $(a_i, b_i)$  chosen randomly from annular region in the plane:  $r^2 \leq a_i^2 + b_i^2 \leq R^2$
- Could be used for representing cloud density (in 3D), placement of vegetation (2D, with threshold)



# Perlin Noise

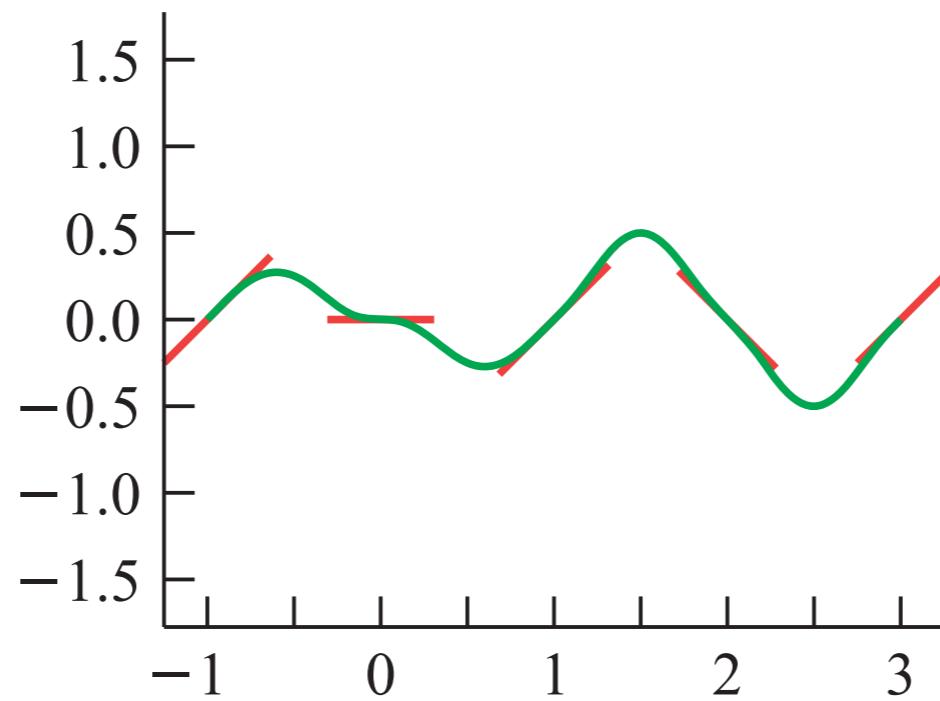
- Perlin (1985, 2002)
- Cube lattice
- Zero value at vertices
- Pseudo-random gradient at vertices
- Splines to interpolate the values at arbitrary 3D points



# 1D Noise

Example

- Zero at integer locations
- Pseudo-random gradient at integer locations
- Interpolate at any location



# Perlin Noise

For a point  $p(x, y, z)$  in the grid

$$n(x, y, z) = \sum_{i=\lfloor x \rfloor}^{\lfloor x \rfloor + 1} \sum_{j=\lfloor y \rfloor}^{\lfloor y \rfloor + 1} \sum_{k=\lfloor z \rfloor}^{\lfloor z \rfloor + 1} \Omega_{ijk}(x - i, y - j, z - k)$$

$$\Omega_{ijk}(u, v, w) = \omega(u)\omega(v)\omega(w)(\Gamma_{ijk} \cdot (u, v, w))$$

$$\omega(t) = \begin{cases} 2|t|^3 - 3|t|^2 + 1 & \text{if } |t| < 1, \\ 0 & \text{otherwise} \end{cases}$$

# Perlin Noise

$\Gamma_{ijk}$  is a random unit vector for the lattice point  
 $(x, y, z) = (i, j, k)$

We can use a pseudorandom table for that:

$$\Gamma_{ijk} = G(\phi(i + \phi(j + \phi(k))))$$

Here,  $G$  is a precomputed array of  $n$  random unit vectors and  $\phi(i) = P[i \bmod n]$

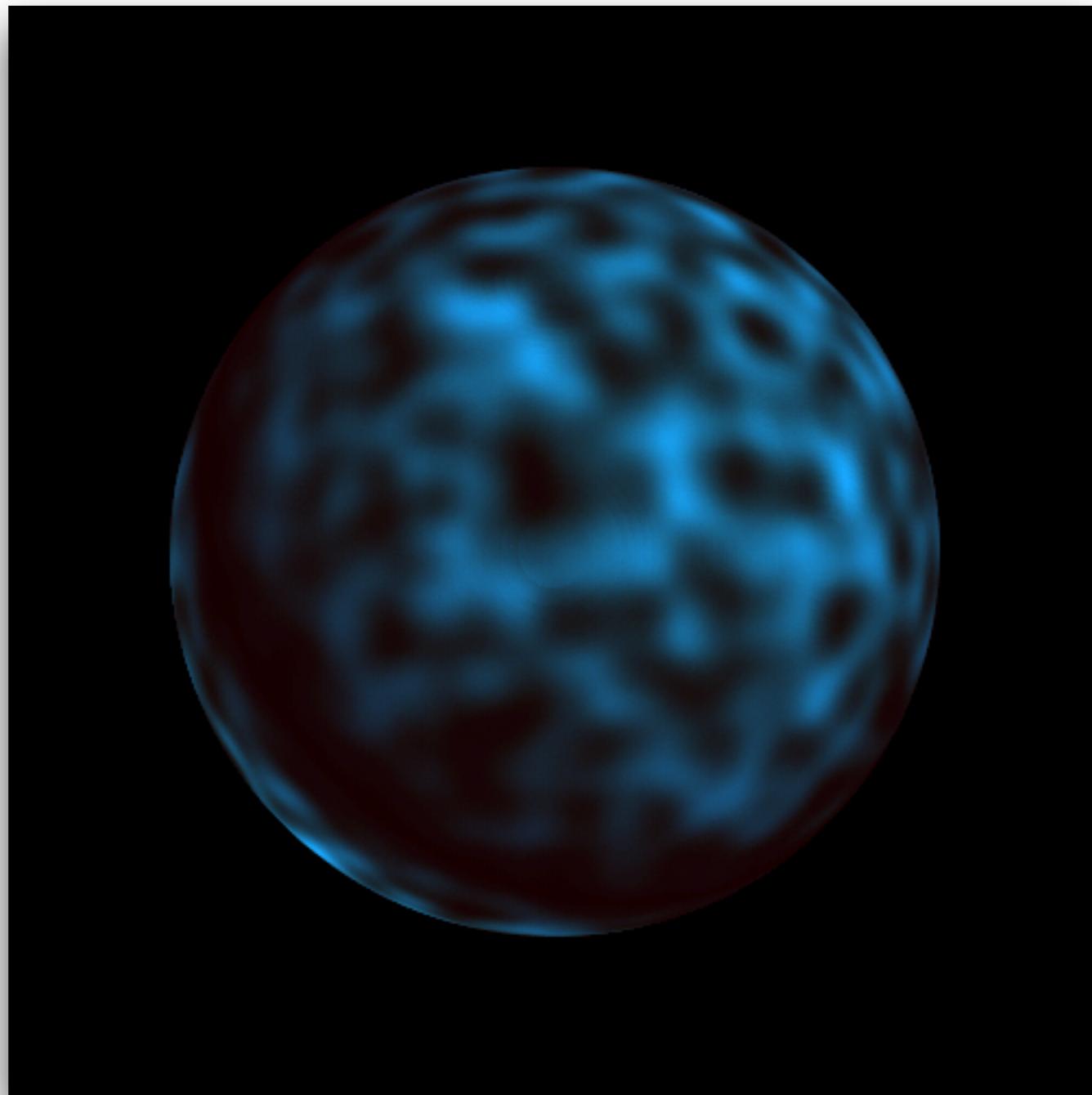
$P$  is an array of length  $n$  containing a permutation of the integers 0 to  $n-1$

E.g.:  $n=256$  works well.

# Algorithm

- I. Given an input point (say  $p$ )
2. For each of its neighbouring grid points ( $q$ )
  - I. Pick a “pseudo-random” gradient vector ( $g$ )
  - II. Compute linear function (dot product:  $g \cdot (p - q)$ )
3. Take weighted sum, using ease curves
  - I. Interpolate between  $2^3$  values using S-shaped cross-fade curve

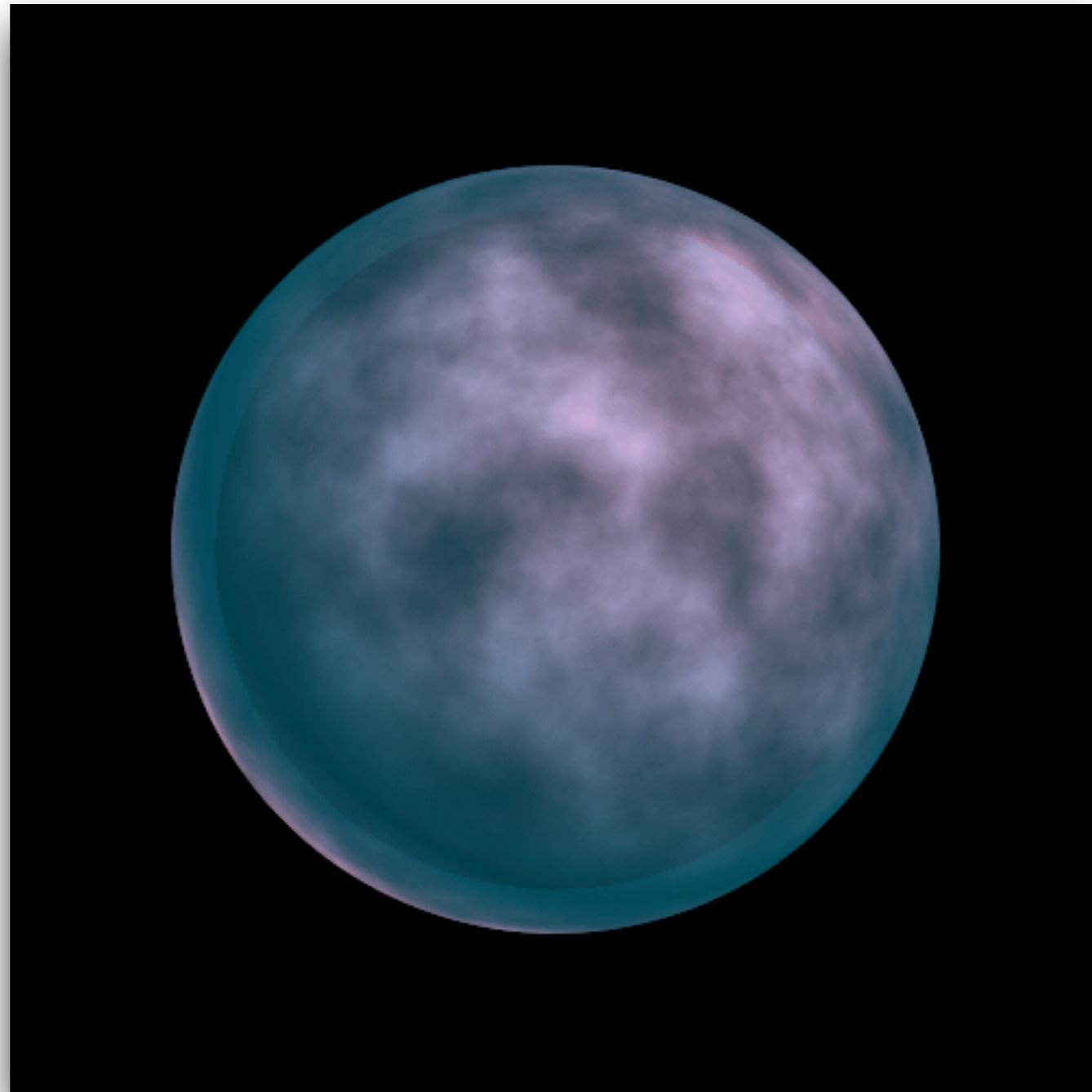
# Noise



Source: Making Noise, Ken Perlin, <http://www.noisemachine.com>

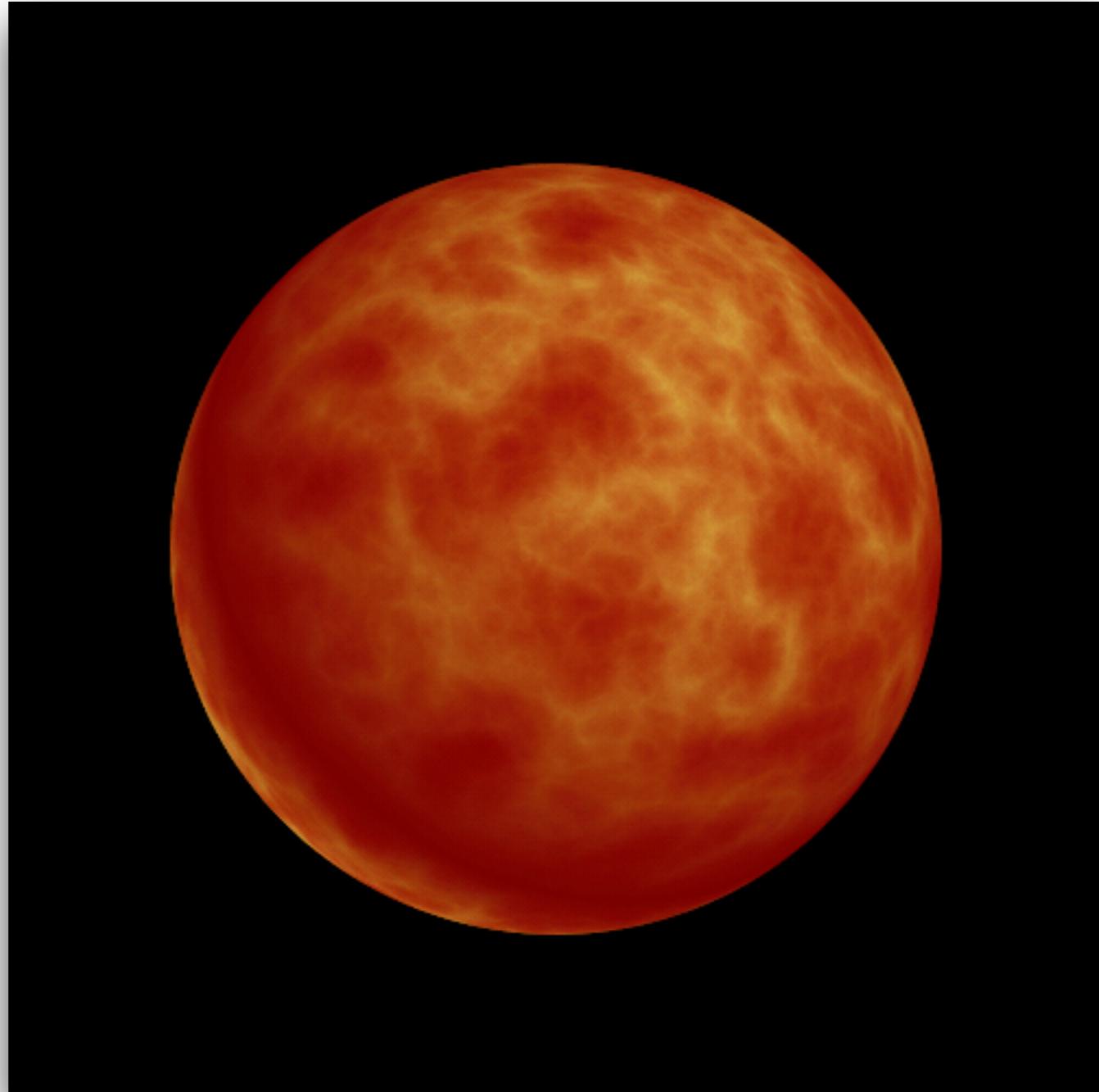
# *Sum $I/f(\text{noise})$*

$\text{noise}(p) + \frac{1}{2} \text{noise}(2p) + \frac{1}{4} \text{noise}(4p) + \dots$



Source: Making Noise, Ken Perlin, <http://www.noisemachine.com>

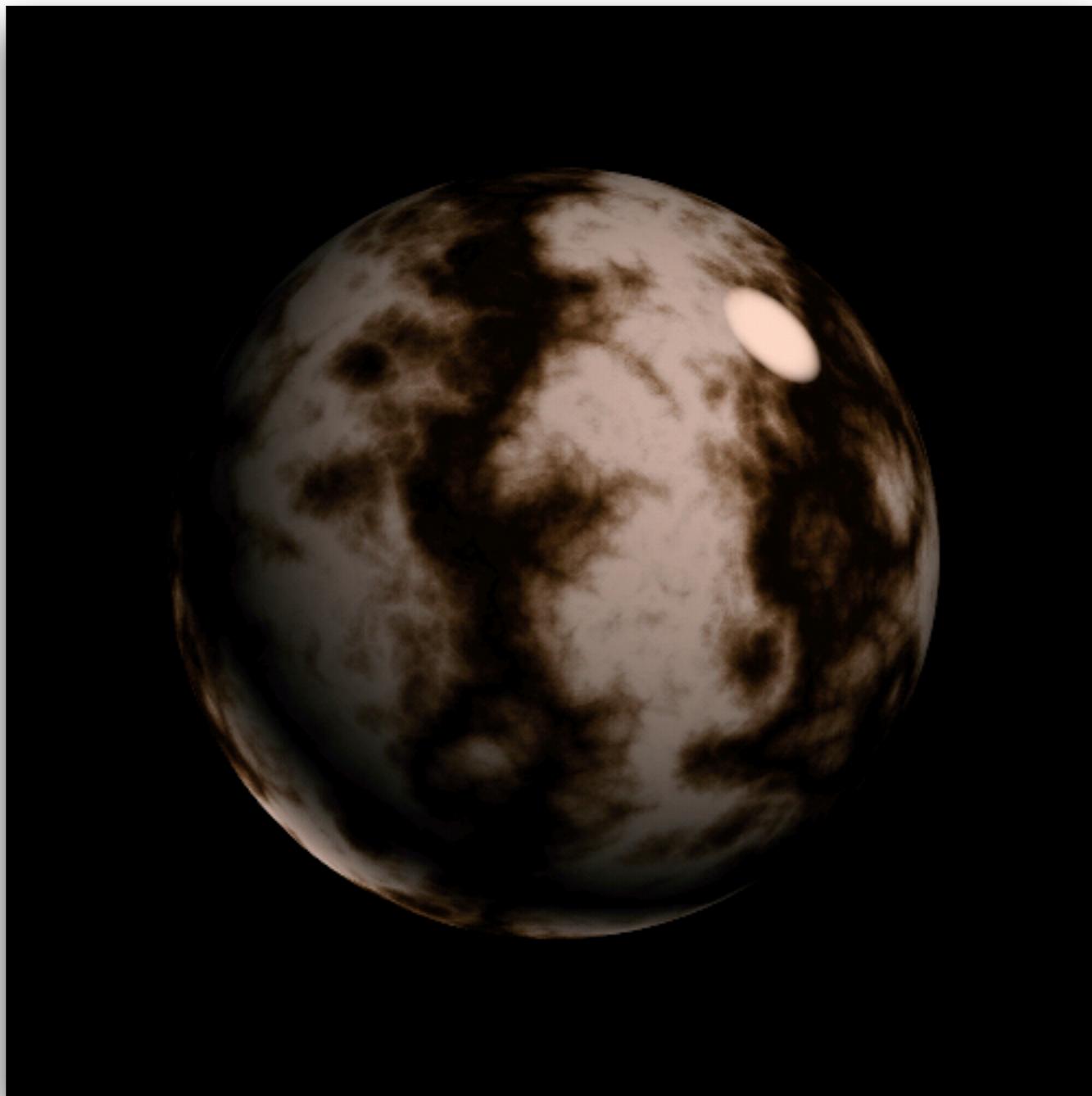
# $\text{Sum } I / f(|\text{noise}|)$

$$|\text{noise}(p)| + 1/2 |\text{noise}(2p)| + 1/4 |\text{noise}(4p)| + \dots$$


Source: Making Noise, Ken Perlin, <http://www.noisemachine.com>

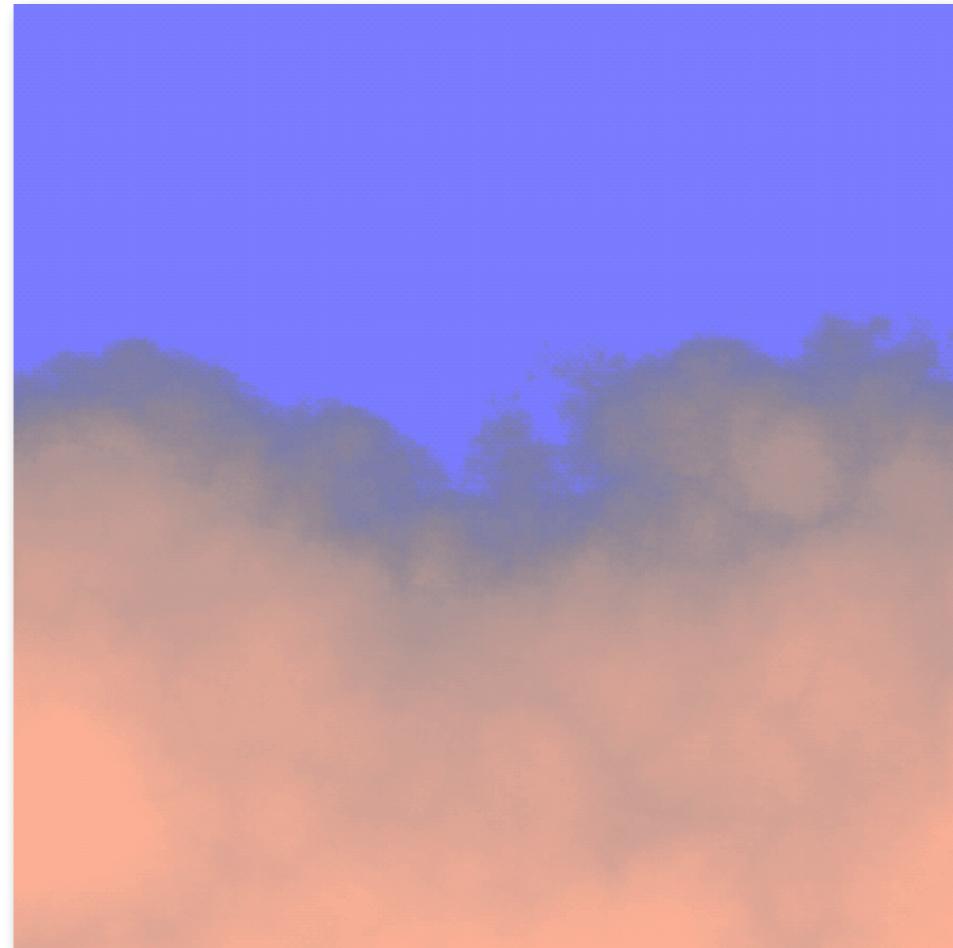
# $\text{Sin}(x + \sin l/f(|\text{noise}|))$

$\sin(x + |\text{noise}(p)| + l/2 |\text{noise}(2p)| + l/4 |\text{noise}(4p)| + \dots)$



Source: Making Noise, Ken Perlin, <http://www.noisemachine.com>

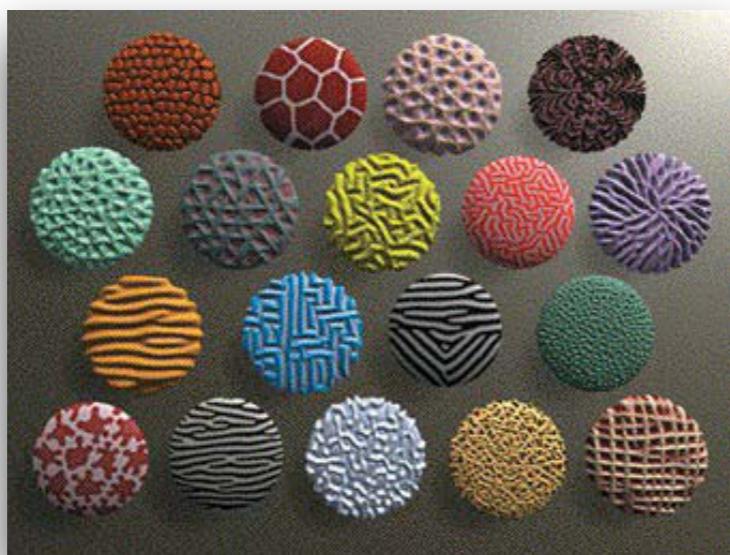
# Flame and Clouds



Source: Making Noise, Ken Perlin, <http://www.noisemachine.com>

# Reaction-diffusion Textures

- Turing (1952), Turk (1991), Kass & Witkin (1991)
- Simulating formation of patterns in nature (leopard spots, snake scales)
- Patterns evolve through *diffusion* and *reaction*



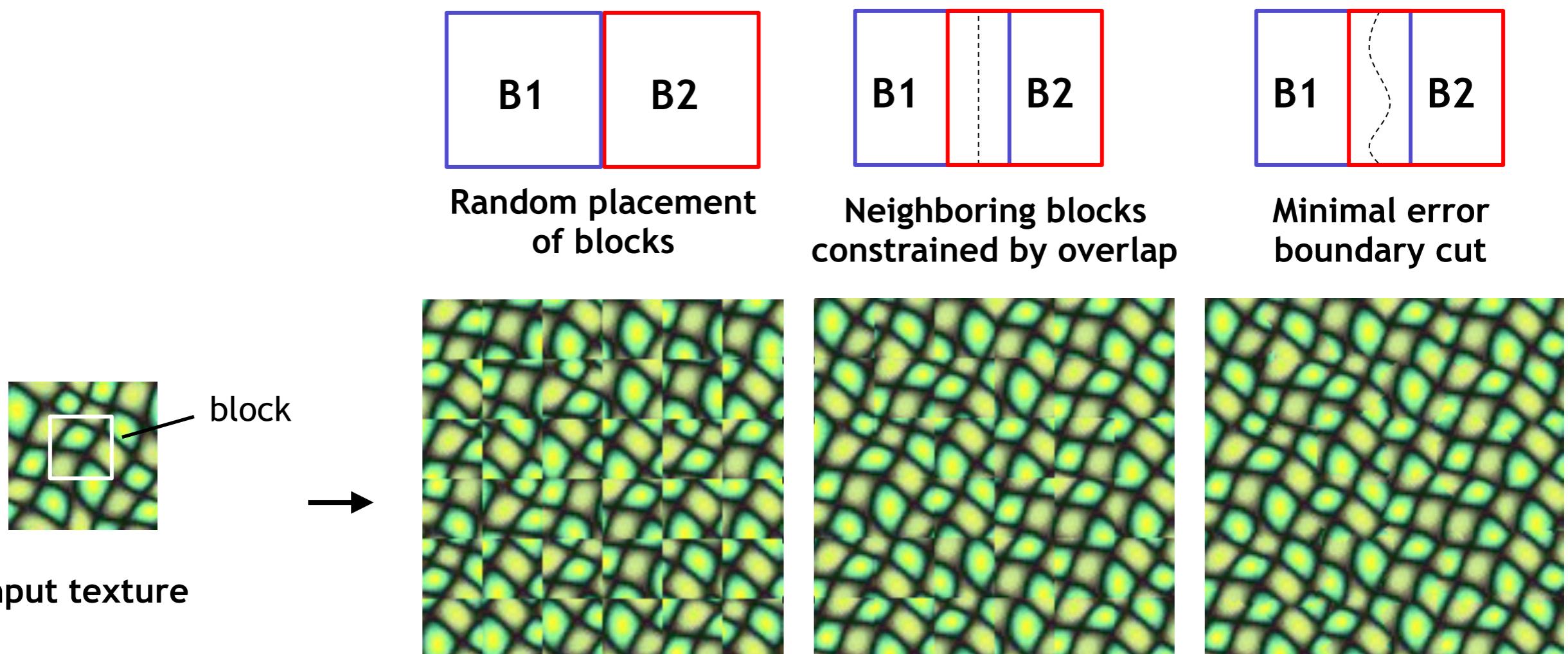
Source: Kass and Witkin



Source: Greg Turk

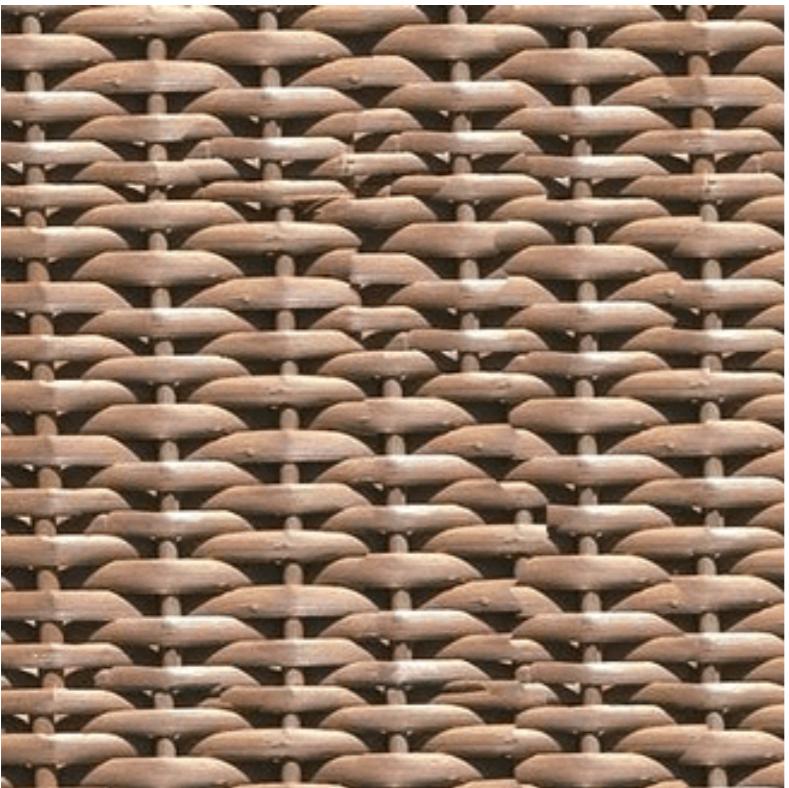
# Data-driven Texture

- Efros (2001): Synthesise a large texture (*target*) from a small sample texture (*source*)



Source: Image Quilting for Texture Synthesis and Transfer, Alexei A. Efros and William T. Freeman

# Data-driven Texture



Source: Image Quilting for Texture Synthesis and Transfer, Alexei A. Efros and Willian T. Freeman

# Other Discrete Techniques

- Bump mapping
- Normal Mapping
- Displacement mapping
- Environment mapping

# Bump Mapping

- Textures may as well be used to alter the surface detail by changing the surface normal
- This gives an illusion of fine-scale geometry
- A *bump map* perturbs the surface normal (Blinn, 1978) using a height map
  - Compute normal of height map at a point using finite difference method
  - Add this normal to the geometric normal and normalise

# Bump Mapping

- Let  $p(u, v)$  be a point on the a parameterised surface. The normal  $n$  is given by:

$$n = \frac{p_u \times p_v}{|p_u \times p_v|}$$

- Let the displacement be given by the function **bump** or **displacement function**  $d(u, v)$
- Displaced surface can be written as:

$$p' = p + d(u, v)n$$

# Bump Mapping

- Displaced normal is given by:

$$n' = p'_u \times p'_v$$

- Computing partial derivatives:

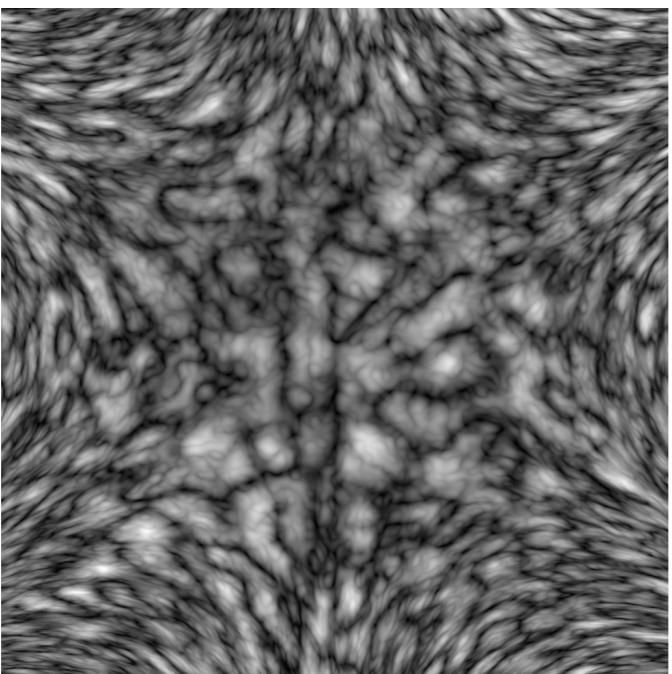
$$p'_u = p_u + \frac{\partial d}{\partial u} n + d(u, v) n_u,$$

$$p'_v = p_v + \frac{\partial d}{\partial v} n + d(u, v) n_v$$

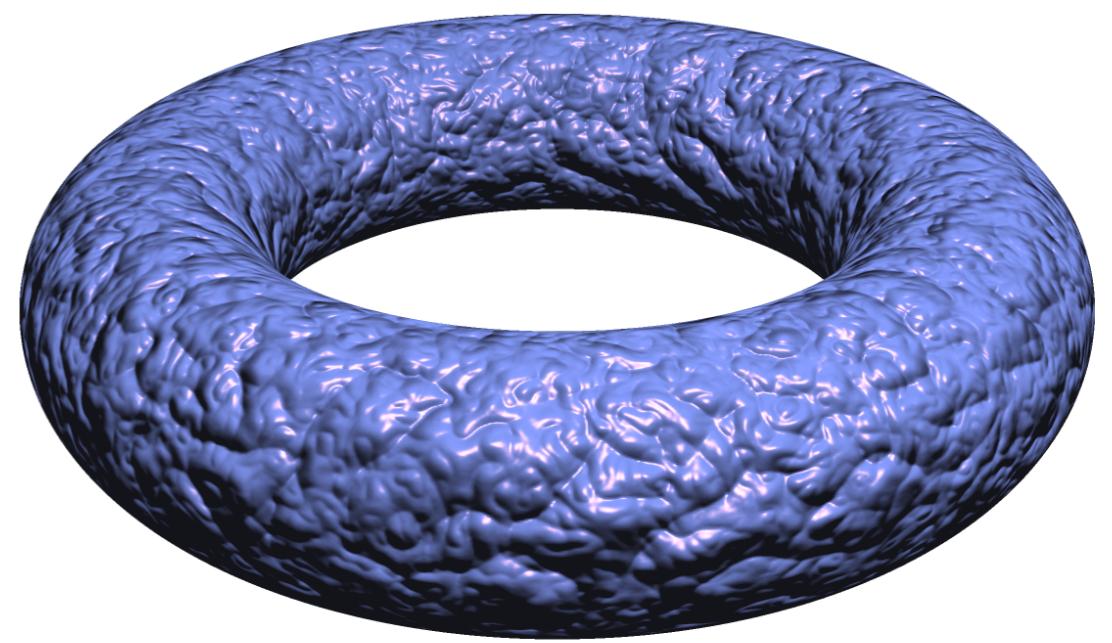
- For small  $d$ , the perturbed normal is given by:

$$n' \approx n + \frac{\partial d}{\partial u} n \times p_v + \frac{\partial d}{\partial v} n \times p_u$$

# Bump Mapping



*Bump map*

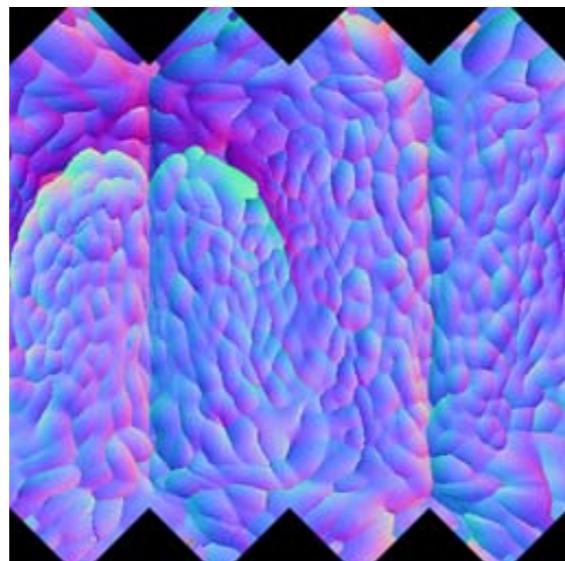


*Bump mapped torus*

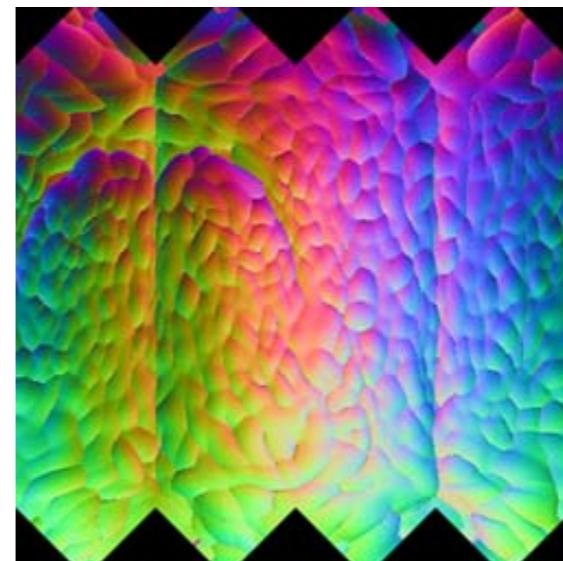
# Normal Mapping

- Instead of computing the normal (as with bump mapping), it is stored in an RGB image
- The R, G, B components correspond to X Y Z coordinates of the surface normal

*Tangent-space normal map*



*Object-space normal map*



Source: Eric Chadwick, <http://wiki.polycount.com>

# Normal Mapping

- Need to accurately compute tangent space

$$m = \frac{n}{|n|},$$

$$t = \frac{p_u}{|p_u|},$$

$$b = m \times t$$

$m$ : normal vector

$t$ : tangent vector

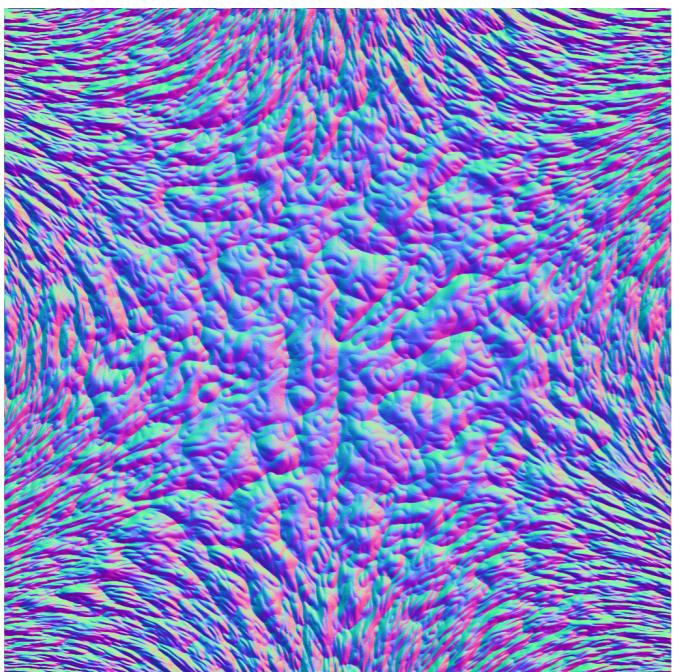
$b$ : binormal vector

- Formulate the rotation matrix

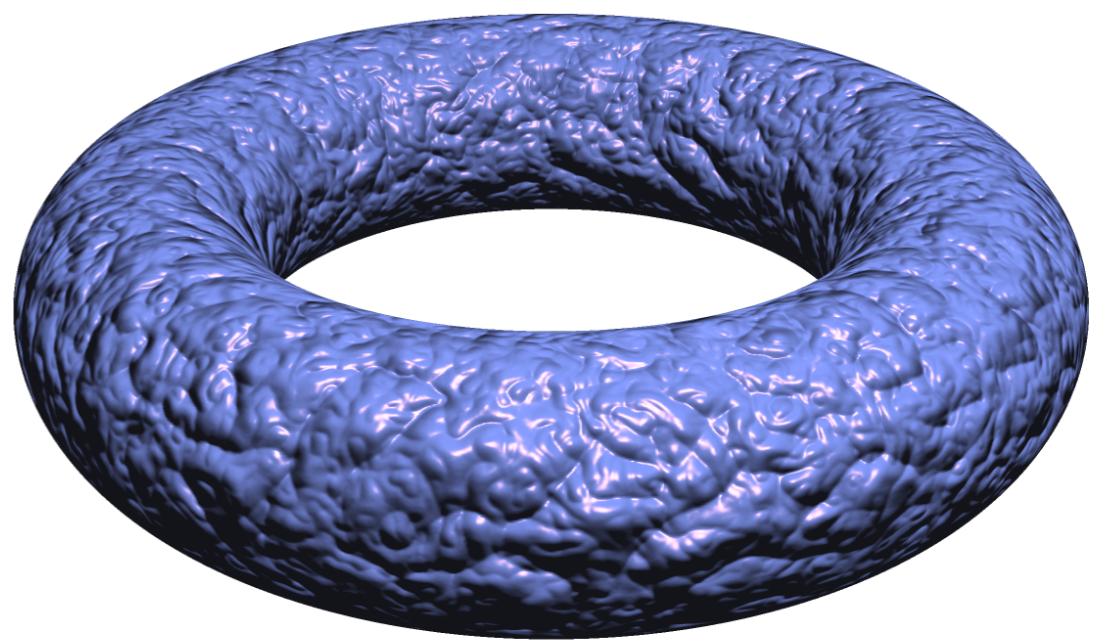
$$M = [t \ b \ m]^T$$

that will convert representations in original space  
to the local tangent space

# Normal Mapping



*Normal map*



*Bump mapped torus*

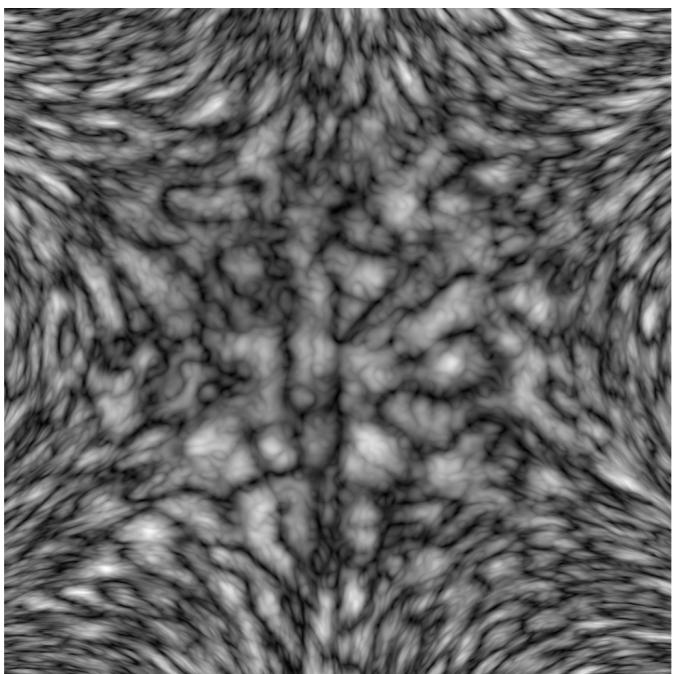
# Displacement Mapping

- Bumps neither cast shadows nor affect the silhouette of the objects
- For more realism, we can apply a *displacement map* that actually changes the geometry

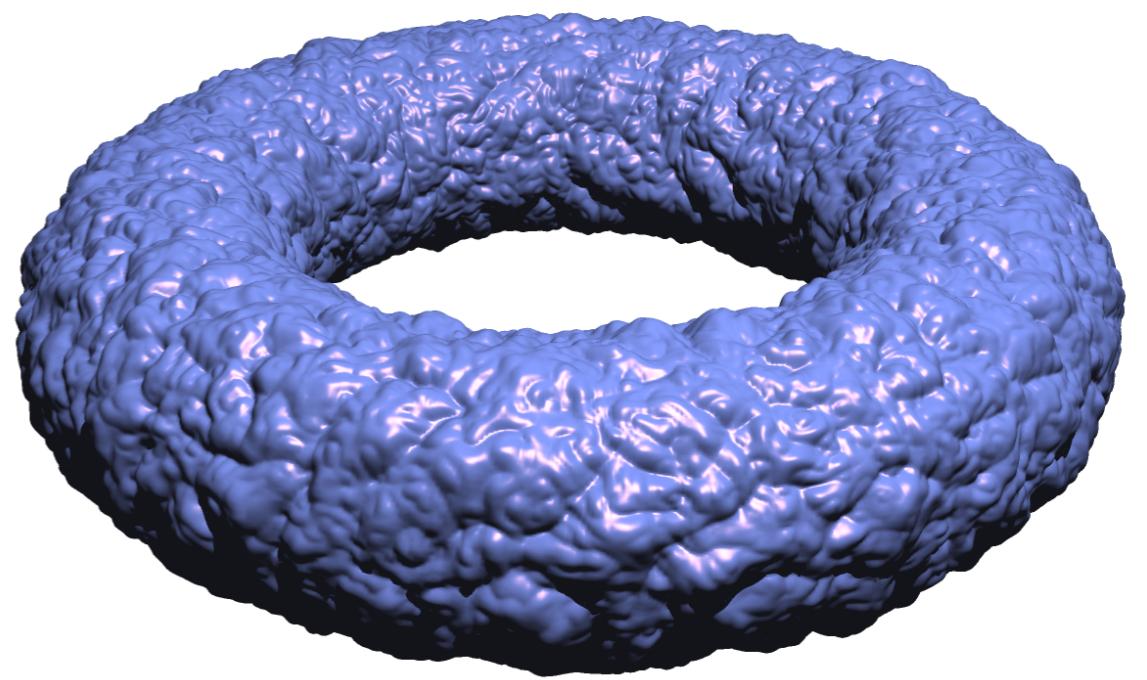
$$p' = p + d(u, v)n$$

- Correct normals to be used during illumination computation

# Displacement Mapping



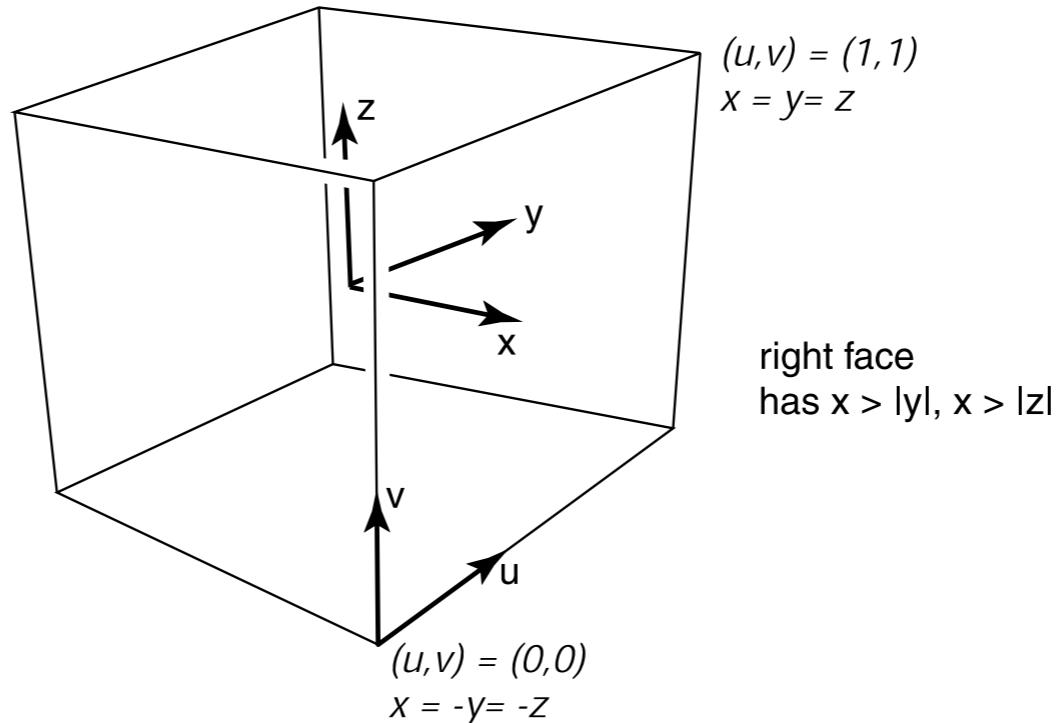
*Displacement map*



*Displacement mapped torus*

# Environment Mapping

- Objects to have specular reflections of the surrounding environment
- The environment is modelled as a box textured with a cube map (comprising six textures)



# Environment Mapping

- With an infinitely large textured cube, return what the reflected rays (from the object surface) see
- For any reflection ray  $a + tb$ , return  $\text{cubemap}(b)$



# Reading

- FCG: II
- CG: 20 (see notes:  
[CG\\_Texture\\_Mapping\\_notes.pdf](#))
- On perspective correct texturing (see notes:  
[perspectiveCorrect.pdf](#))

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ICG: Interactive Computer Graphics, E. Angel, and D. Shreiner, 6th ed.

FCG: Fundamentals of Computer Graphics, P. Shirley, M. Ashikhmin, and S. Marschner, 3rd ed.

CG: Computer Graphics, principles and Practice, J. F. Hughes, et al.