

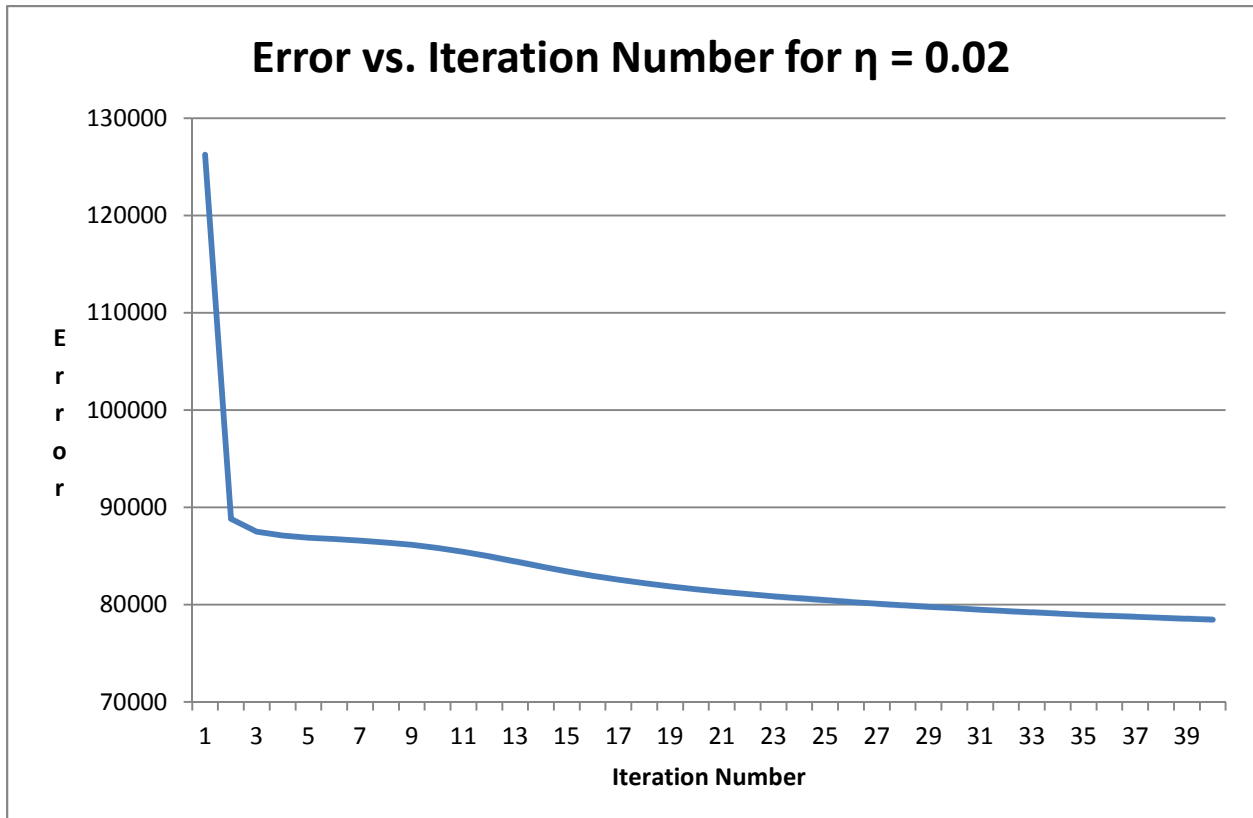
**1(a)**

$$\varepsilon_{iu} = r_{iu} - q_i \cdot p_u^T$$

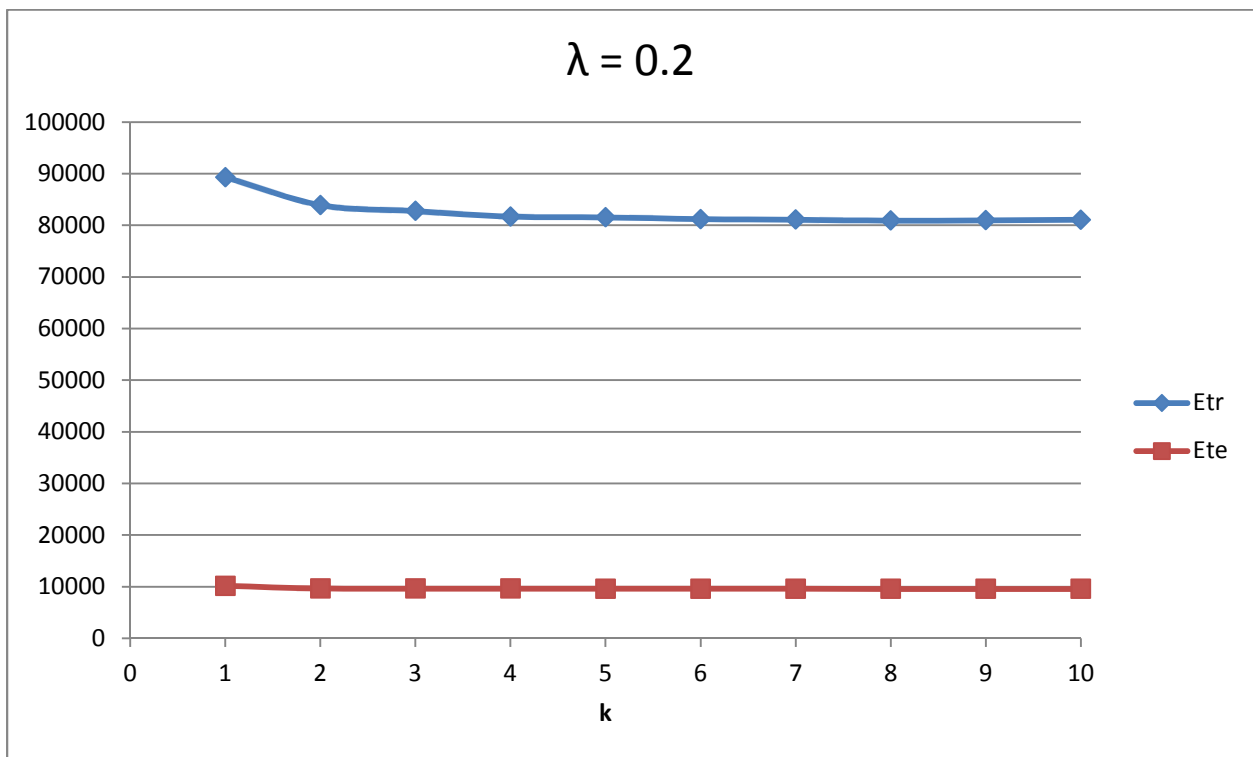
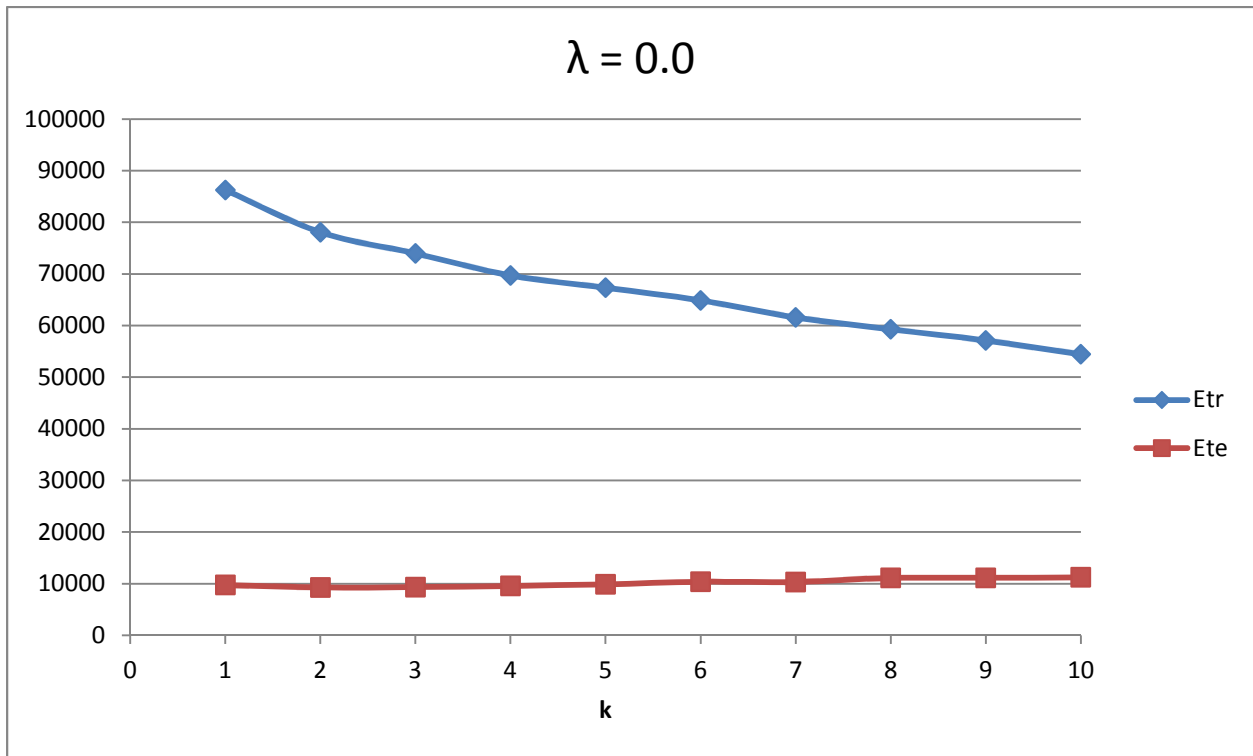
$$q_i = q_i + \eta(\varepsilon_{iu}p_u - \lambda q_i)$$

$$p_u = p_u + \eta(\varepsilon_{iu}q_i - \lambda p_u)$$

**1(b)**



**1(c)**



The following statements are valid (true):

- B: Regularization decreases the test error for  $k \geq 5$
- D: Regularization increases the training error for all (or almost all)  $k$ .
- H: Regularization decreases overfitting.

The other statements (A, C, E, F, G, and I) are invalid (false).

## **2(a)**

$r$  and  $r^k$  are defined as follows:

$$r = \beta M r + \frac{(1-\beta)}{n} 1^T \quad (2.a.1)$$

$$r^k = \beta M r^{k-1} + \frac{(1-\beta)}{n} 1^T \quad (2.a.2)$$

We will now solve for  $\|r - r^k\|_1$  using equations (2.a.1) and (2.a.2).

$$\begin{aligned} & \|r - r^k\|_1 \\ & \left\| \left( \beta M r + \frac{(1-\beta)}{n} 1^T \right) - \left( \beta M r^{k-1} + \frac{(1-\beta)}{n} 1^T \right) \right\|_1 \\ & \|(\beta M)(r - r^{k-1})\|_1 \\ & \|(\beta M)^k \left( r - \frac{1}{n} 1^T \right)\|_1 \\ & \|r - r^k\|_1 = \beta^k \|M^k \left( r - \frac{1}{n} 1^T \right)\|_1 \end{aligned} \quad (2.a.3)$$

Because we know that  $r^k$  is column stochastic  $\forall k \geq 0$ , we know that:

$$\|r^k\|_1 = 1, \forall k \geq 0 \quad (2.a.4)$$

If we set  $\beta = 1$  in equation (2.a.2), which is within our bounds for  $\beta$ , then we have the following:

$$r^k = Mr^{k-1}$$

$$\|r^k\|_1 = \|Mr^{k-1}\|_1 \quad (2.a.5)$$

It follows from equation (2.a.5) that the matrix multiplication of  $M$  times any given  $r^{k-1}$  cannot change the 1-norm of  $r^{k-1}$ . It follows that:

$$\|M^k r\|_1 = 1 \quad (2.a.6)$$

$\frac{1}{n} 1^T$  is by definition column stochastic, therefore:

$$\left\| \frac{1}{n} 1^T \right\|_1 = 1$$

By the same reasoning we used to derive equation (2.a.6), it follows that:

$$\left\| M^k \frac{1}{n} 1^T \right\|_1 = 1 \quad (2.a.7)$$

From equation (2.a.3), we know:

$$\begin{aligned} \|r - r^k\|_1 &= \beta^k \left\| M^k \left( r - \frac{1}{n} 1^T \right) \right\|_1 \\ \|r - r^k\|_1 &= \beta^k \left\| M^k r - M^k \frac{1}{n} 1^T \right\|_1 \leq \beta^k \|M^k r\|_1 + \beta^k \left\| M^k \frac{1}{n} 1^T \right\|_1 \end{aligned} \quad (2.a.8)$$

Substituting equations (2.a.6) and (2.a.7) into (2.a.8), we obtain:

$$\|r - r^k\|_1 \leq \beta^k * 1 + \beta^k * 1 = 2\beta^k$$

$$\|r - r^k\|_1 \leq 2\beta^k$$

## **2(b)**

From part 2(a) we know that the  $L_1$  error is bounded as follows:

$$\|r - r^k\|_1 \leq 2\beta^k$$

$$2\beta^k \leq \delta$$

$$\beta^k \leq \frac{\delta}{2}$$

$$\log_{\beta}(\beta^k) \leq \log_{\beta}\left(\frac{\delta}{2}\right)$$

$$k \leq \frac{\log\left(\frac{\delta}{2}\right)}{\log(\beta)}$$

$$k \leq \frac{-\log\left(\frac{\delta}{2}\right)}{-\log(\beta)}$$

$$k \leq \frac{-\log\left(\frac{\delta}{2}\right)}{\log\left(\frac{1}{\beta}\right)}$$

$$k \leq O\left(\frac{1}{\log\left(\frac{1}{\beta}\right)}\right)$$

Thus, the number of power iterations (k) that we need to perform to guarantee the  $L_1$  error is less than a constant  $\delta$  is on the order of  $\frac{1}{\log\left(\frac{1}{\beta}\right)}$ .

m is the number of edges in our graph. Therefore m corresponds to the number of non-zero elements in M. This means that each power iteration requires  $O(m)$  operations.

So, to guarantee the  $L_1$  error is less than a constant  $\delta$  the number of operations we need to perform is as follows:

$$O(km) \leq O\left(\frac{m}{\log\left(\frac{1}{\beta}\right)}\right)$$

The running time is on the order of the number of operations. As such the running time to guarantee the  $L_1$  error is less than a constant  $\delta$  is  $O\left(\frac{m}{\log\left(\frac{1}{\beta}\right)}\right)$ .

## **2(c)**

Let  $\tilde{p}_j^i$  represent the fraction of random walks that start at node  $i$  and end at node  $j$ .

We can express the estimation  $\tilde{r}_j$  obtained by the MC algorithm as a function of  $\tilde{p}_j^i$  as follows:

$$\tilde{r}_j = \frac{1}{n} \sum_{i=1}^n \tilde{p}_j^i$$

The expected value of  $\tilde{r}_j$  is therefore defined as follows:

$$E[\tilde{r}_j] = E\left[\frac{1}{n} \sum_{i=1}^n \tilde{p}_j^i\right]$$

$\frac{1}{n} \sum_{i=1}^n \tilde{p}_j^i$  is equivalent to the probability of ending at node  $j$  starting from a *random* node. In other words:

$$\frac{1}{n} \sum_{i=1}^n \tilde{p}_j^i = r_j$$

Where  $r_j$  is the probability of ending at node  $j$  produced by the PageRank algorithm. Therefore:

$$E[\tilde{r}_j] = E\left[\frac{1}{n} \sum_{i=1}^n \tilde{p}_j^i\right] = E[r_j] = r_j$$

## **2(d)**

Let the random variable  $K$  represent the number of steps of any of the individual random walks. The probability of a random walk continuing from a given node is  $\beta$  and the probability of a random walk ending at a given node is  $1 - \beta$ . This is simply a sequence of Bernoulli trials with probability of “success” (ending the random walk) of  $1 - \beta$ . Thus we can represent  $K$  as follows:

$$P(K = k) = \beta^{k-1}(1 - \beta)$$

As you can see,  $K$  follows a geometric distribution with  $p = 1 - \beta$ . The expected value of a geometric distribution is well known as  $\frac{1}{p}$ . It follows that:

$$E[K] = \frac{1}{1 - \beta}$$

In the MC algorithm we simulate  $nR$  random walks. Therefore the expected running time is as follows:

$$O(nR * E[K]) = O\left(\frac{nR}{1 - \beta}\right)$$

## **2(e)**

### PageRank

Time Elapsed = 00:00:00.0915033

### MC Algorithm

R = 1:

Time Elapsed = 00:00:00.0000252

Average Error (Top 10) = 0.00640663222420862

Average Error (Top 30) = 0.00480184089326871

Average Error (Top 50) = 0.00393012276692224

Average Error (Top 100) = 0.0028437844810428

R = 3:

Time Elapsed = 00:00:00.0001017

Average Error (Top 10) = 0.00407329889087529

Average Error (Top 30) = 0.00230528124835267

Average Error (Top 50) = 0.00185090881125131

Average Error (Top 100) = 0.00149015695379502

R = 5:

Time Elapsed = 00:00:00.0001674

Average Error (Top 10) = 0.00280723868805303

Average Error (Top 30) = 0.00199048241770075

Average Error (Top 50) = 0.00171602213055849

Average Error (Top 100) = 0.00129368788756991

## **3(a)**

A0 = eye(3);

B0 = eye(5);

A1 = A0;

$A1(1,2) = C1 * (B0(2,2)+B0(2,4)+B0(3,2)+B0(3,4)+B0(5,2)+B0(5,4)) / (3*2);$

$A1(2,1) = A1(1,2);$

$A1(1,3) = C1 * (B0(2,1)+B0(4,1)) / (3*1);$

$A1(3,1) = A(1,3);$   
 $A1(2,3) = C1 * (B0(2,1)+B0(4,1)) / (2*1);$   
 $A1(3,2) = A(2,3);$

$B1 = B0;$   
 $B1(1,2) = C2 * (A0(3,1)+A0(3,2)) / (1*2);$   
 $B1(2,1) = B1(1,2);$   
 $B1(1,3) = C2 * (A0(3,1)) / (1*1);$   
 $B1(3,1) = B1(1,3);$   
 $B1(1,4) = C2 * (A0(3,2)) / (1*1);$   
 $B1(4,1) = B1(1,4);$   
 $B1(1,5) = C2 * (A0(3,1)) / (1*1);$   
 $B1(5,1) = B1(1,5);$   
 $B1(2,3) = C2 * (A0(1,1)+A0(2,1)) / (2*1);$   
 $B1(3,2) = B1(2,3);$   
 $B1(2,4) = C2 * (A0(1,2)+A0(2,2)) / (2*1);$   
 $B1(4,2) = B1(2,4);$   
 $B1(2,5) = C2 * (A0(1,1)+A0(2,1)) / (2*1);$   
 $B1(5,2) = B1(2,5);$   
 $B1(3,4) = C2 * (A0(1,2)) / (1*1);$   
 $B1(4,3) = B1(3,4);$   
 $B1(3,5) = C2 * (A0(1,1)) / (1*1);$   
 $B1(5,3) = B1(3,5);$   
 $B1(4,5) = C2 * (A0(2,1)) / (1*1);$   
 $B1(5,4) = B1(4,5);$

#### Results after iteration 1

A1 =

1.0000	0.1333	0
0.1333	1.0000	0
0	0	1.0000

B1 =

1.0000	0	0	0	0
0	1.0000	0.4000	0.4000	0.4000
0	0.4000	1.0000	0	0.8000
0	0.4000	0	1.0000	0



0 0.4000 0.8000 0 1.0000

### Results after iteration 2

A2 =

1.0000	0.2933	0
0.2933	1.0000	0
0	0	1.0000

B2 =

1.0000	0	0	0	0
0	1.0000	0.4533	0.4533	0.4533
0	0.4533	1.0000	0.1067	0.8000
0	0.4533	0.1067	1.0000	0.1067
0	0.4533	0.8000	0.1067	1.0000

### Results after iteration 3

A3 =

1.0000	0.3431	0
0.3431	1.0000	0
0	0	1.0000

B3 =

1.0000	0	0	0	0
0	1.0000	0.5173	0.5173	0.5173
0	0.5173	1.0000	0.2347	0.8000
0	0.5173	0.2347	1.0000	0.2347
0	0.5173	0.8000	0.2347	1.0000

### Results

The requested results after three iterations are as follows:

$$S_A(camera, phone) = A3(1, 2) = 0.3431$$

$$S_A(camera, printer) = A3(1, 3) = 0$$

### **3(b)**

In the summation, we should multiply the similarities by its weights. We should also normalize by dividing by the sum of the weights.

$$s_A(X, Y) = \frac{C_1}{\sum_{i=1}^{|O(X)|} W(X, O_i(X)) * \sum_{j=1}^{|O(Y)|} W(Y, O_j(Y))} \sum_{i=1}^{|O(X)|} \sum_{j=1}^{|O(Y)|} [W(X, O_i(X)) * W(Y, O_j(Y)) * s_A(O_i(X), O_j(Y))]$$

$$s_B(X, Y) = \frac{C_2}{\sum_{i=1}^{|I(X)|} W(I_i(X), X) * \sum_{j=1}^{|I(Y)|} W(I_j(Y), Y)} \sum_{i=1}^{|I(X)|} \sum_{j=1}^{|I(Y)|} [W(X, I_i(X)) * W(Y, I_j(Y)) * s_A(I_i(X), I_j(Y))]$$

### **3(c)**

#### Details for Iteration 1 of $K_{2,1}$

A0 = eye(2);

B0 = eye(1);

A1 = A0;

A1(1,2) = C1 \* (B0(1,1)) / (1\*1);

A1(2,1) = C1 \* (B0(1,1)) / (1\*1);

B1 = B0;

#### Similarity Scores for $K_{2,1}$

A1 =

1.0000	0.8000
0.8000	1.0000

B1 =

1

A2 =

1.0000	0.8000
0.8000	1.0000

B2 =

1

A3 =

1.0000	0.8000
0.8000	1.0000

B3 =

1

#### Details for Iteration 1 of $K_{2,2}$

A0 = eye(2);

B0 = eye(2);

A1 = A0;

A1(1,2) = C1 \* (B0(1,2)+B0(2,1)) / (2\*2);

A1(2,1) = A1(1,2);

B1 = B0;

B1(1,2) = C2 \* (A0(1,2)+A0(2,1)) / (2\*2);

B1(2,1) = B1(1,2);

#### Similarity Scores for $K_{2,2}$

A1 =

1.0000	0.4000
--------	--------

0.4000 1.0000

B1 =

1.0000 0.4000  
0.4000 1.0000

A2 =

1.0000 0.5600  
0.5600 1.0000

B2 =

1.0000 0.5600  
0.5600 1.0000

A3 =

1.0000 0.6240  
0.6240 1.0000

B3 =

1.0000 0.6240  
0.6240 1.0000

#### How the Similarity Scores for $K_{2,1}$ and $K_{2,2}$ compare after 3 Iterations

The similarity score  $A3(1,2)$  for  $K_{2,1}$  is higher than the similarity  $A3(1,2)$  score for  $K_{2,2}$  by 0.176.

#### **3(d)**

We use the same formulas we came up with in part 3(b), but change the weigh formula  $W(X, Y)$  to count the number of neighbors that nodes X and Y share.

We know that this similarity score would never be greater than 1 because we normalize in part 3(b) by dividing by the sum of the weights.

### **3(e)**

$s_A(x, y)$  is the probability of the two random walkers starting at x and y ending at the same node.

### **4(a)(i)**

We assume the following:

$$|A(S)| < \frac{\epsilon}{1+\epsilon} |S| \quad (4.a.1)$$

$$|S \setminus A(S)| = |S| - |A(S)| \quad (4.a.2)$$

Applying equation (4.a.1) to equation (4.a.2), we obtain:

$$\begin{aligned} |S \setminus A(S)| &= |S| - |A(S)| \geq |S| - \frac{\epsilon}{1+\epsilon} |S| = |S| \left(1 - \frac{\epsilon}{1+\epsilon}\right) = |S| \left(\frac{1}{1+\epsilon}\right) \\ |S \setminus A(S)| &\geq |S| \left(\frac{1}{1+\epsilon}\right) \end{aligned} \quad (4.a.3)$$

Remember that  $A(S)$  is defined as follows:

$$A(S) = \{i \in S \mid \deg_S(i) \leq 2(1+\epsilon)\rho(S)\}$$

Therefore  $S \setminus A(S)$  contains the elements in S that are not in A(S), specifically:

$$S \setminus A(S) = \{i \in S \mid \deg_S(i) > 2(1+\epsilon)\rho(S)\} \quad (4.a.4)$$

We can calculate the density  $\rho(S)$  as follows. Note that by summing the degree of each node we are double counting each edge, which is why the denominator below contains  $2|S|$ .

$$\rho(S) = \frac{\sum_{i \in S} \deg_S(i)}{2|S|} = \frac{\sum_{i \in A(S)} \deg_S(i) + \sum_{i \in S \setminus A(S)} \deg_S(i)}{2|S|}$$

$$\rho(S) = \frac{\sum_{i \in A(S)} \deg_S(i)}{2|S|} + \frac{\sum_{i \in S \setminus A(S)} \deg_S(i)}{2|S|} \quad (4.a.5)$$

Applying equations (4.a.3) and (4.a.4) to equation (4.a.5), we obtain:

$$\begin{aligned} \rho(S) &= \frac{\sum_{i \in A(S)} \deg_S(i)}{2|S|} + \frac{\sum_{i \in S \setminus A(S)} \deg_S(i)}{2|S|} > \frac{\sum_{i \in A(S)} \deg_S(i)}{2|S|} + \frac{|S| \left( \frac{1}{1+\epsilon} \right) 2(1+\epsilon)\rho(S)}{2|S|} \\ \rho(S) &> \frac{\sum_{i \in A(S)} \deg_S(i)}{2|S|} + \rho(S) \end{aligned}$$

Clearly,  $\rho(S)$  cannot be larger than  $\rho(S)$  plus a positive constant. Therefore, our assumption in equation (4.a.1) must be wrong. We therefore conclude the following:

$$|A(S)| \geq \frac{\epsilon}{1+\epsilon} |S|$$

#### **4(a)(ii)**

$$|S \setminus A(S)| = |S| - |A(S)| \geq |S| - \frac{\epsilon}{1+\epsilon} |S| = |S| \left( 1 - \frac{\epsilon}{1+\epsilon} \right) = |S| \left( \frac{1}{1+\epsilon} \right)$$

It follows that at every iteration, the result gets smaller by at least  $\frac{1}{1+\epsilon}$ .

Therefore, in the worst case the algorithm will terminate in at most  $\log_{1+\epsilon}(n)$  iterations.

#### **4(b)(i)**

We assume the following:

$$\text{Let node } x \in S \text{ such that } \deg_{S^*}(x) < \rho^*(G) \quad (4.b.1)$$

$$\rho(S^* \setminus \{x\}) = \frac{|E[S^*]| - \deg_{S^*}(x)}{|S^*| - 1} \quad (4.b.2)$$

Because  $\deg_{S^*}(x) < \rho^*(G)$  it follows that we can rewrite equation (4.b.1) as:

$$\rho(S^* \setminus \{x\}) = \frac{|E[S^*]| - \deg_{S^*}(x)}{|S^*| - 1} > \frac{|E[S^*]| - \rho^*(G)}{|S^*| - 1} \quad (4.b.3)$$

We know by definition that  $\rho^*(G) = \max_{S \subseteq V} \{\rho(S)\}$ . Because  $S^*$  is the densest subgraph of  $G$  it follows that:

$$\rho^*(G) = \rho(S^*) \quad (4.b.4)$$

Applying equation (4.b.4) to equation (4.b.3), we obtain:

$$\rho(S^* \setminus \{x\}) > \frac{|E[S^*]| - \rho(S^*)}{|S^*| - 1} = \frac{|E[S^*]| - \frac{|E[S^*]|}{|S^*|}}{|S^*| - 1} = \frac{|E[S^*]|}{|S^*|} = \rho^*(G)$$

However,  $\rho(S^* \setminus \{x\})$  cannot be greater than  $\rho^*(G)$  because  $\rho^*(G) = \max_{S \subseteq V} \{\rho(S)\}$ . As such, our assumption is wrong and we have proved the following:

$$\deg_{S^*}(v) \geq \rho^*(G), \forall v \in S$$

#### **4(b)(ii)**

We are given  $v \in S^* \cap A(S)$

Recall that the definition of  $A(S)$  is:

$$A(S) = \{i \in S \mid \deg_S(i) \leq 2(1 + \epsilon)\rho(S)\}$$

Because  $v \in A(S)$ , we know that:

$$\deg_S(v) \leq 2(1 + \epsilon)\rho(S) \quad (2.b.5)$$

We showed in 4(b)(i) that:

$$\deg_S(v) < \rho^*(G) \quad (2.b.6)$$

Combining equations (2.b.5) and (2.b.6) we obtain:

$$2(1 + \epsilon)\rho(S) \geq \deg_S(v) \geq \rho^*(G)$$

$$2(1 + \epsilon)\rho(S) \geq \rho^*(G)$$

**4(b)(iii)**

In part 4(b)(ii) we showed:

$$2(1 + \epsilon)\rho(S) \geq \rho^*(G)$$

$$\rho(S) \geq \frac{\rho^*(G)}{2(1+\epsilon)} \quad (2.b.7)$$

The algorithm is designed to find an induced subgraph  $\tilde{S}$  of  $G$  whose density isn't much smaller than  $\rho^*(G)$ . Thus:

$$\rho(\tilde{S}) \geq \rho(S). \quad (2.b.8)$$

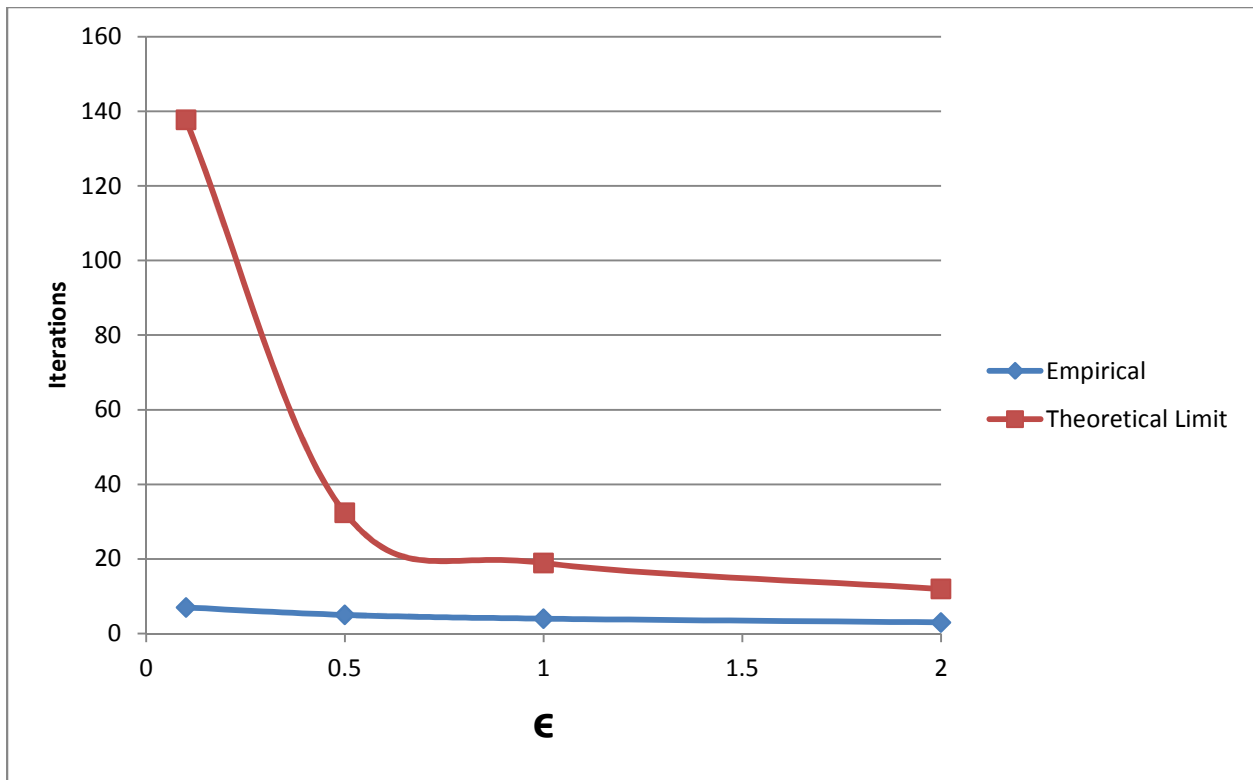
Combining equations (2.b.7) and (2.b.8), we obtain:

$$\rho(\tilde{S}) \geq \rho(S) \geq \frac{\rho^*(G)}{2(1 + \epsilon)}$$

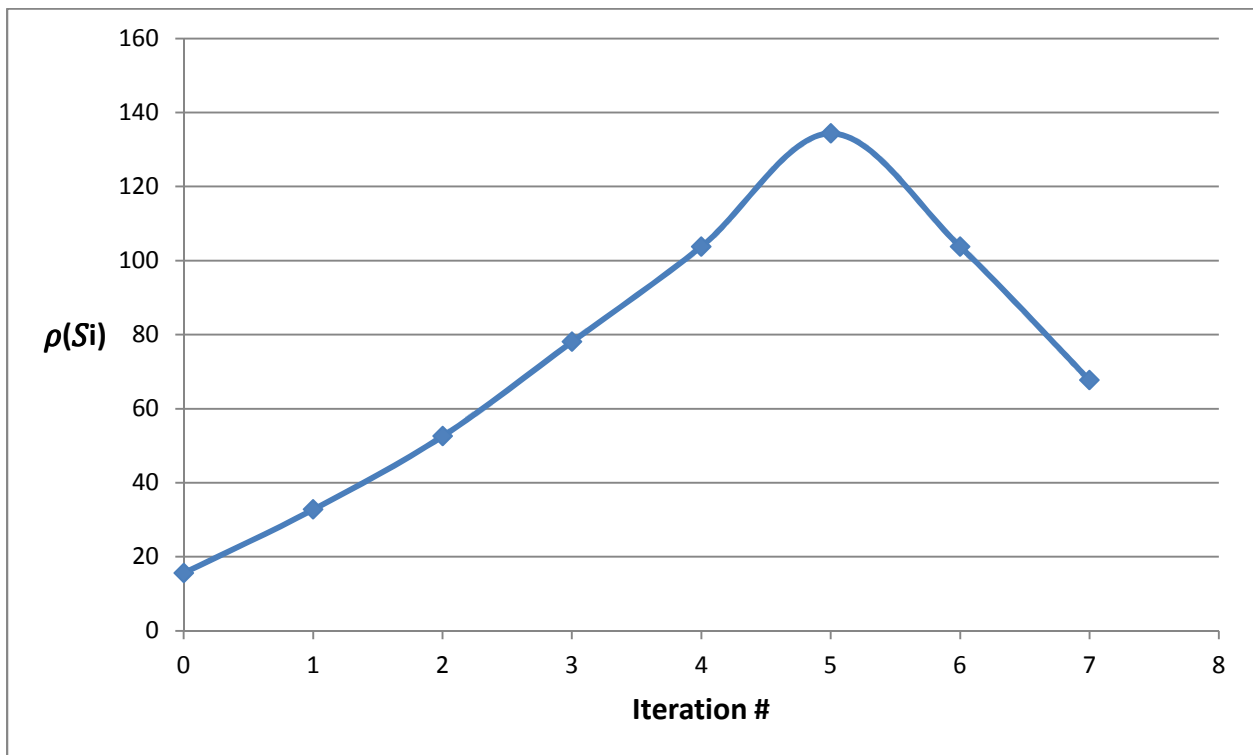
$$\rho(\tilde{S}) \geq \frac{\rho^*(G)}{2(1 + \epsilon)}$$

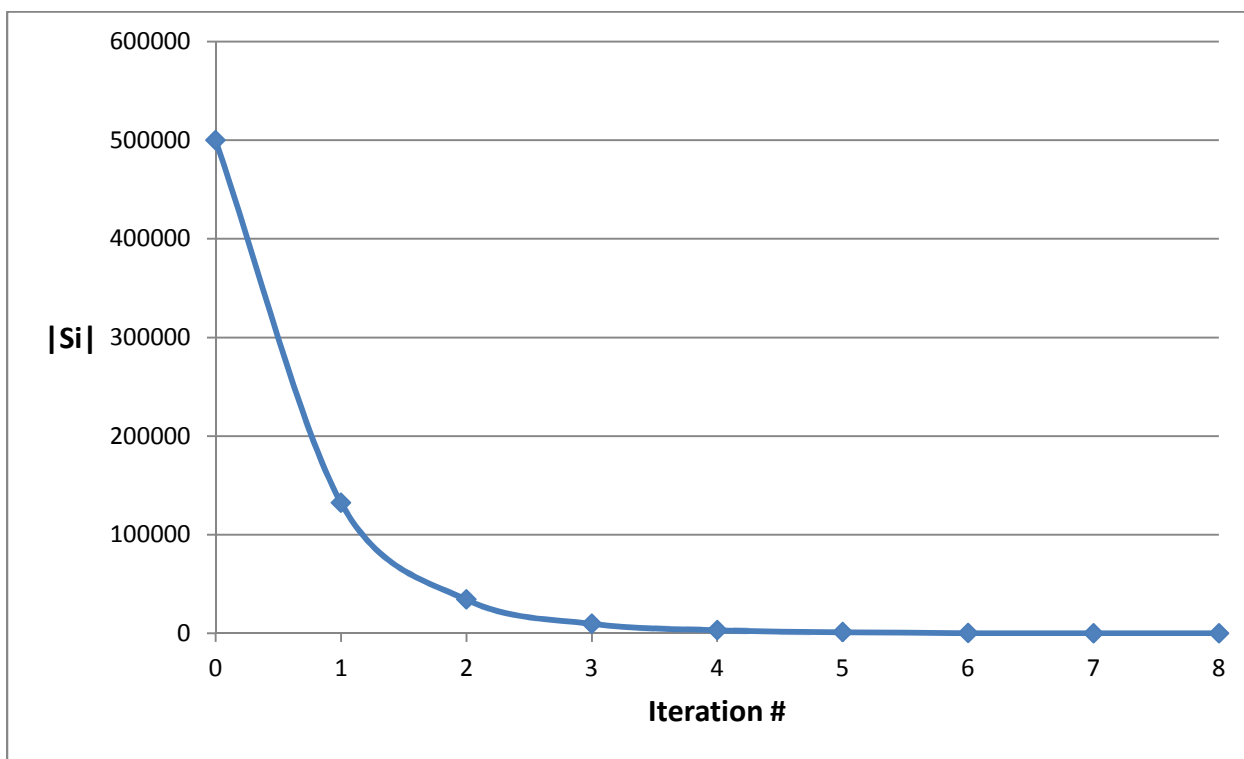
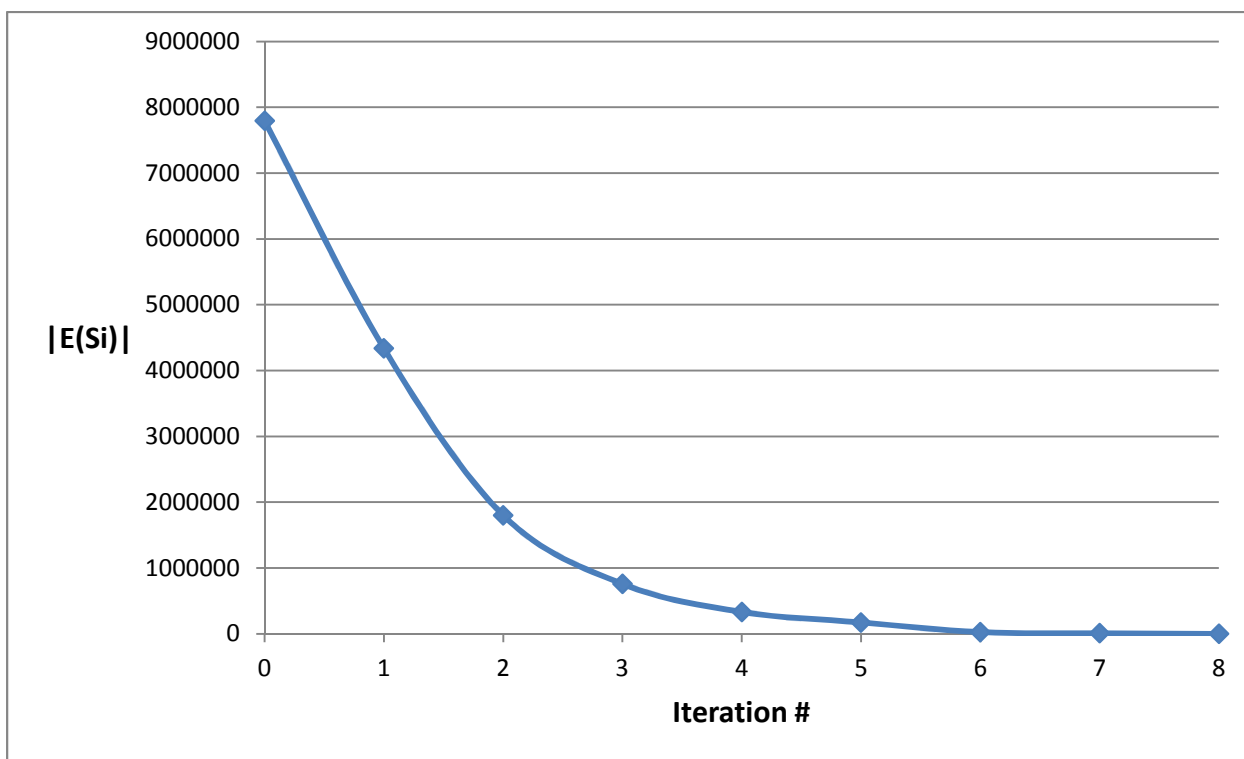
**4(c)(i)**



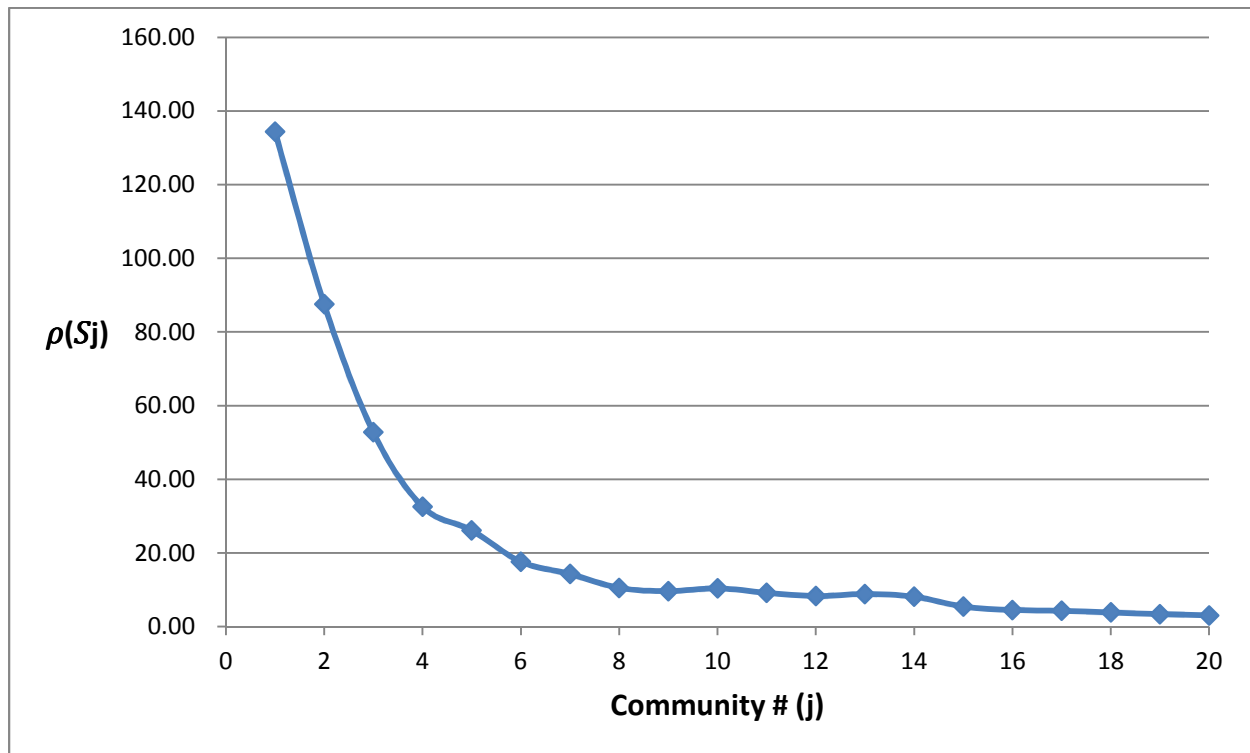


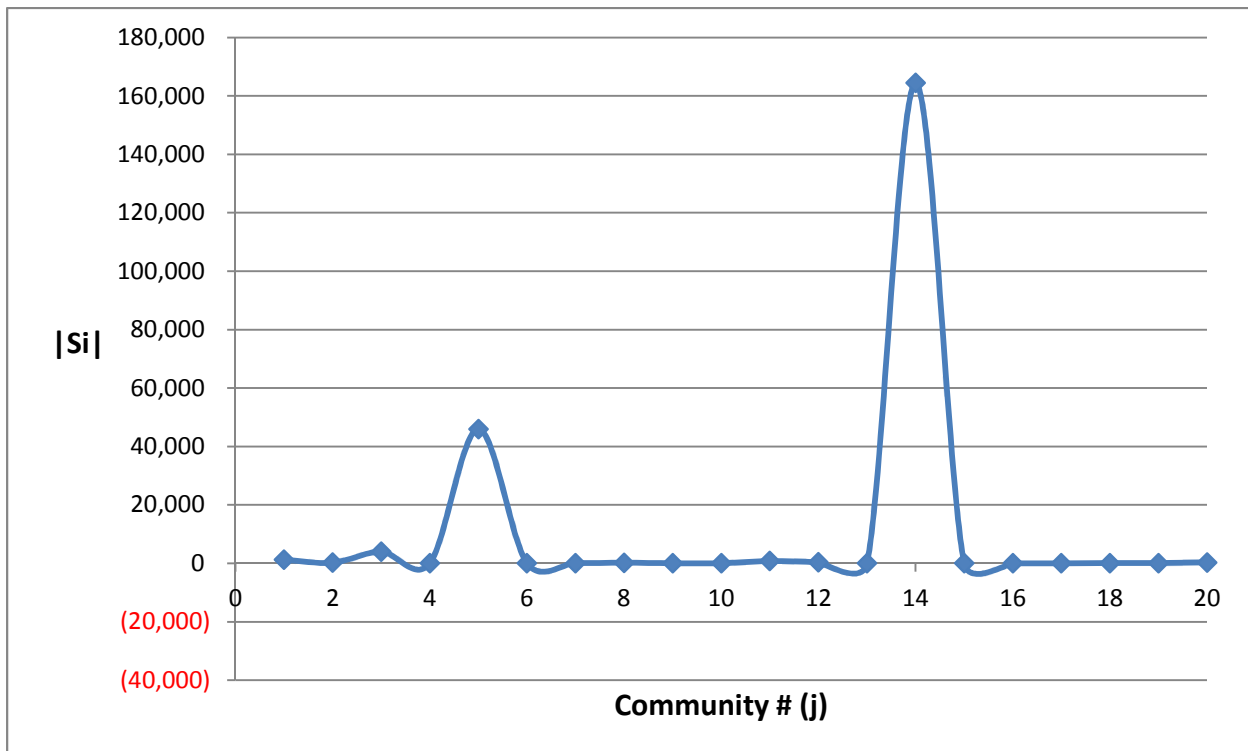
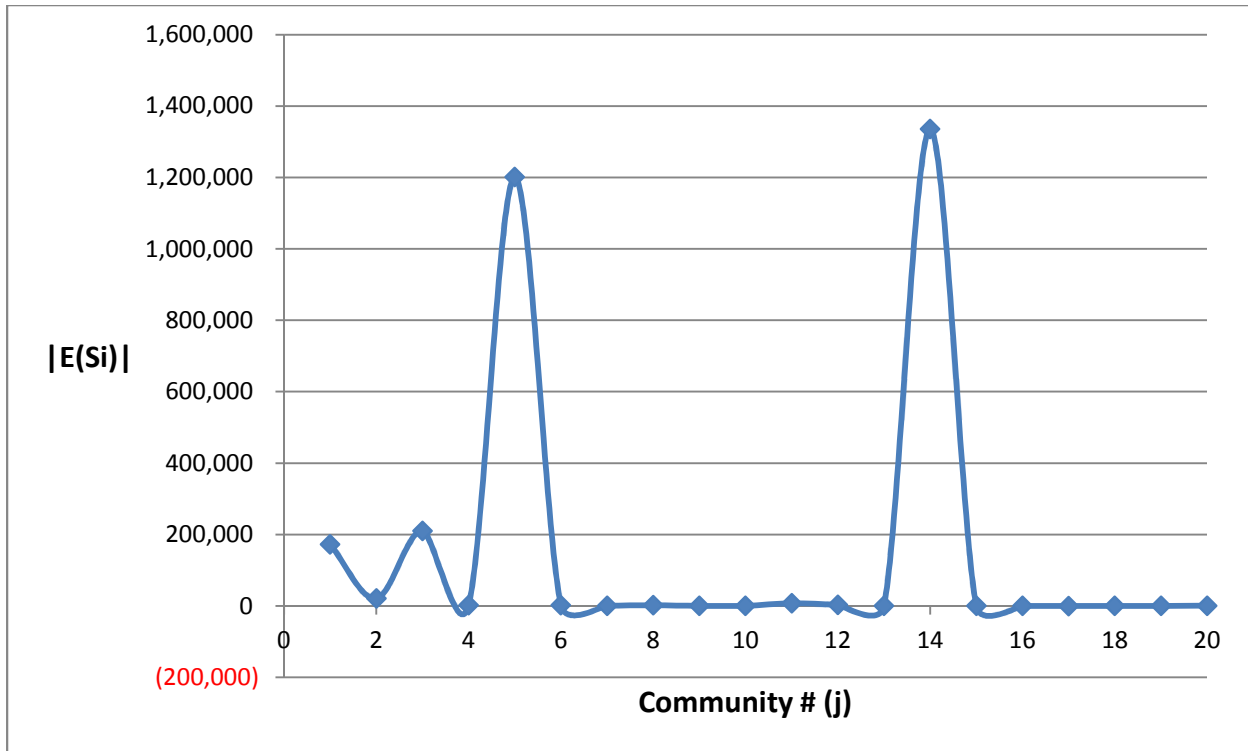
**4(c)(ii)**





**4(c)(iii)**





```

/*
 * Philip Scuderi
 * Stanford University
 * CS246
 * Winter 2013
 * Homework 3
 * Question 1
 */

package HW3_Q1c;

import java.io.*;
import java.util.*;
import Jama.Matrix;

public class StochasticGradientDescent
{
    protected String rTrainingPath, rTestPath;
    protected double lambda, eta, trainingError, regularizationAdjustment;
    protected Matrix p, q;
    protected int m, n, k;

    public static void main(String[] args) throws IOException
    {
        String path = "C:\\Dropbox\\Private\\Stanford\\CS246\\Homeworks\\HW3\\Q1\\";

```

```

String rTrainingFile = "ratings.train.txt";

String rTestFile = "ratings.val.txt";

String rTrainingPath = path + rTrainingFile;

String rTestPath = path + rTestFile;


double eta = 0.03;

int iterations = 40;


double lambda = 0.0;

System.out.println("lambda = " + lambda + ":");

for (int k = 1; k <= 10; k++)
{
    StochasticGradientDescent sgd = new StochasticGradientDescent(eta, lambda, k, rTrainingPath,
rTestPath);

    sgd.Iterate(iterations);

    System.out.println(k + "\t" + sgd.GetTrainingError() + "\t" + sgd.GetTestError());
}

System.out.println();


lambda = 0.2;


System.out.println("lambda = " + lambda + ":");

```

```

for (int k = 1; k <= 10; k++)
{
    StochasticGradientDescent sgd = new StochasticGradientDescent(eta, lambda, k, rTrainingPath,
rTestPath);

    sgd.Iterate(iterations);

    System.out.println(k + "\t" + sgd.GetTrainingError() + "\t" + sgd.GetTestError());

}

System.out.println();
}

```

```

public StochasticGradientDescent(double eta, double lambda, int k, String rTrainingPath, String
rTestPath) throws FileNotFoundException, IOException

```

```

{
    trainingError = regularizationAdjustment = Double.NaN;

    this.lambda = lambda;

    this.k = k;

    this.eta = eta;

    this.rTrainingPath = rTrainingPath;

    this.rTestPath = rTestPath;

    // initialize m and n

    BufferedReader reader = new BufferedReader(new FileReader(rTrainingPath));

    String line;

    while ( (line = reader.readLine()) != null)
    {

```

```

StringTokenizer tokenizer = new StringTokenizer(line);

int u = Integer.parseInt(tokenizer.nextToken());

int i = Integer.parseInt(tokenizer.nextToken());

if (u > n)

    n = u;

if (i > m)

    m = i;
}

reader.close();

Random r = new Random();

// initialize p

p = new Matrix(n, k);

for (int row = 0; row < n; row++)

    for (int col = 0; col < k; col++)

        p.set(row, col, r.nextDouble() * Math.pow(5.0 / (double)k, 0.5));

// initialize q

q = new Matrix(m, k);

for (int row = 0; row < m; row++)

    for (int col = 0; col < k; col++)

```



```

        q.set(row, col, r.nextDouble() * Math.pow(5.0 / (double)k, 0.5));
    }

    public void Iterate(int numIterations) throws FileNotFoundException, IOException
    {
        for (int a = 0; a < numIterations; a++)
        {
            trainingError = 0.0;

            BufferedReader reader = new BufferedReader(new FileReader(rTrainingPath));
            String line;
            while ( (line = reader.readLine()) != null)
            {
                StringTokenizer tokenizer = new StringTokenizer(line);

                int u = Integer.parseInt(tokenizer.nextToken());
                int i = Integer.parseInt(tokenizer.nextToken());
                int Riu = Integer.parseInt(tokenizer.nextToken());

                Matrix Qi = GetRow(q, i-1);
                Matrix Pu = GetRow(p, u-1);

                double Eiu = Riu - DotProduct(Qi, Pu);

                Matrix nextQi = Qi.plus(Pu.times(Eiu).minus(Qi.times(lambda)).times(eta));
            }
        }
    }

```

```

        Matrix nextPu = Pu.plus(Qi.times(Eiu).minus(Pu.times(lambda)).times(eta));

        SetRow(q, i-1, nextQi);

        SetRow(p, u-1, nextPu);

        trainingError += Math.pow(Eiu, 2.0);
    }
    reader.close();

    regularizationAdjustment = 0.0;

    // finish determing the error (determine right side of the equation)
    for (int i = 0; i < m; i++)

        regularizationAdjustment += lambda * Math.pow(GetRow(q, i).norm2(), 2.0);

    for (int u = 0; u < n; u++)

        regularizationAdjustment += lambda * Math.pow(GetRow(p, u).norm2(), 2.0);
    }
}

public double GetError()
{
    return trainingError + regularizationAdjustment;
}

```

```
public double GetTrainingError()
```

```
{
```

```
    return trainingError;
```

```
}
```

```
public double GetTestError() throws FileNotFoundException, IOException
```

```
{
```

```
    double testError = 0.0;
```

```
    BufferedReader reader = new BufferedReader(new FileReader(rTestPath));
```

```
    String line;
```

```
    while ( (line = reader.readLine()) != null)
```

```
    {
```

```
        StringTokenizer tokenizer = new StringTokenizer(line);
```

```
        int u = Integer.parseInt(tokenizer.nextToken());
```

```
        int i = Integer.parseInt(tokenizer.nextToken());
```

```
        int Riu = Integer.parseInt(tokenizer.nextToken());
```

```
        Matrix Qi = GetRow(q, i-1);
```

```
        Matrix Pu = GetRow(p, u-1);
```

```
        double Eiu = Riu - DotProduct(Qi, Pu);
```

```

        testError += Math.pow(Eiu, 2.0);
    }

    reader.close();

    return testError;
}

// only for same size vectors (1 row matrices of the same length)
protected static double DotProduct(Matrix m1, Matrix m2)
{
    double dotProduct = 0.0;

    for (int i = 0; i < m1.getColumnDimension(); i++)
        dotProduct += m1.get(0, i) * m2.get(0, i);

    return dotProduct;
}

protected static void SetRow(Matrix m, int row, Matrix val)
{
    m.setMatrix(row, row, 0, m.getColumnDimension()-1, val);
}

protected static void SetColumn(Matrix m, int column, Matrix val)
{

```

```
        m.setMatrix(0, m.getColumnDimension()-1, column, column, val);
    }

    protected static Matrix GetRow(Matrix m, int row)
    {
        return m.getMatrix(row, row, 0, m.getColumnDimension()-1);
    }

    protected static Matrix GetColumn(Matrix m, int column)
    {
        return m.getMatrix(0, m.getRowDimension()-1, column, column);
    }
}
```

```

/*
 * Philip Scuderi
 * Stanford University
 * CS246
 * Winter 2013
 * Homework 3
 * Question 2
 */

using System;
using System.Collections.Generic;
using System.Linq;
using System.Text;
using System.IO;
using System.Diagnostics;
using Extreme.Mathematics;
using Extreme.Mathematics.LinearAlgebra;

namespace HW3_Q2
{
    class Program
    {
        const string graphPath = "../..graph.txt";
        const int n = 100;
        const int m = 1024;
        const double beta = 0.8;

        static void Main(string[] args)
        {
            // 2(e)
            Console.WriteLine("2(e): PageRank\n-----\n");
            Tuple<Vector, KeyValuePair<int, double>[], TimeSpan> pageRankResults =
PageRank();
            Console.WriteLine("r = " + pageRankResults.Item1);
            Console.WriteLine();
            Console.WriteLine("Time Elapsed = " + pageRankResults.Item3);
            Console.WriteLine();
            Console.WriteLine();

            // 2(f)
            Console.WriteLine("2(f): MC Algorithm\n-----\n");
            Tuple<Vector, KeyValuePair<int, double>[], TimeSpan> rw1 = RandomWalk(1);
            Tuple<Vector, KeyValuePair<int, double>[], TimeSpan> rw3 = RandomWalk(3);
            Tuple<Vector, KeyValuePair<int, double>[], TimeSpan> rw5 = RandomWalk(5);

            Console.WriteLine("R = 1:");
            Console.WriteLine("Time Elapsed = " + rw1.Item3);
            Console.WriteLine("Average Error (Top 10) = " +
AverageErrorTopK(pageRankResults.Item2, rw1.Item1, 10));
            Console.WriteLine("Average Error (Top 30) = " +
AverageErrorTopK(pageRankResults.Item2, rw1.Item1, 30));
            Console.WriteLine("Average Error (Top 50) = " +
AverageErrorTopK(pageRankResults.Item2, rw1.Item1, 50));
            Console.WriteLine("Average Error (Top 100) = " +
AverageErrorTopK(pageRankResults.Item2, rw1.Item1, 100));
            Console.WriteLine();

            Console.WriteLine("R = 3:");

```

```

        Console.WriteLine("Time Elapsed = " + rw3.Item3);
        Console.WriteLine("Average Error (Top 10) = " +
AverageErrorTopK(pageRankResults.Item2, rw3.Item1, 10));
        Console.WriteLine("Average Error (Top 30) = " +
AverageErrorTopK(pageRankResults.Item2, rw3.Item1, 30));
        Console.WriteLine("Average Error (Top 50) = " +
AverageErrorTopK(pageRankResults.Item2, rw3.Item1, 50));
        Console.WriteLine("Average Error (Top 100) = " +
AverageErrorTopK(pageRankResults.Item2, rw3.Item1, 100));
        Console.WriteLine();

        Console.WriteLine("R = 5:");
        Console.WriteLine("Time Elapsed = " + rw5.Item3);
        Console.WriteLine("Average Error (Top 10) = " +
AverageErrorTopK(pageRankResults.Item2, rw5.Item1, 10));
        Console.WriteLine("Average Error (Top 30) = " +
AverageErrorTopK(pageRankResults.Item2, rw5.Item1, 30));
        Console.WriteLine("Average Error (Top 50) = " +
AverageErrorTopK(pageRankResults.Item2, rw5.Item1, 50));
        Console.WriteLine("Average Error (Top 100) = " +
AverageErrorTopK(pageRankResults.Item2, rw5.Item1, 100));
        Console.WriteLine();

        Console.WriteLine();
        Console.WriteLine("Press any key to continue...");
        Console.ReadKey();
    }

    private static double AverageErrorTopK(KeyValuePair<int, double>[]
truePageRankDesc, Vector estimatedPageRank, int k)
    {
        double totalError = 0.0;

        for (int i = 0; i < k; i++)
            totalError += Math.Abs(truePageRankDesc[i].Value -
estimatedPageRank[truePageRankDesc[i].Key]);

        return totalError / ((double)k);
    }

    private static KeyValuePair<int, double>[] ToSortedArrayDesc(double[] d)
    {
        Dictionary<int, double> dictionary = new Dictionary<int, double>(d.Length);

        for (int i = 0; i < d.Length; i++)
            dictionary.Add(i, d[i]);

        return dictionary.OrderByDescending(kvp => kvp.Value).ToArray();
    }

    private static Tuple<Vector, KeyValuePair<int, double>[], TimeSpan>
RandomWalk(int r)
    {
        // for each source node, stores a list of destination nodes
        List<int>[] graph = new List<int>[n];
        for (int i = 0; i < n; i++)
            graph[i] = new List<int>();
    }

```

```

// populate the graph data structure
using (StreamReader reader = new StreamReader(graphPath))
{
    string line;
    while ((line = reader.ReadLine()) != null)
    {
        string[] elements = line.Split();

        int source = int.Parse(elements[0]);
        int destination = int.Parse(elements[1]);

        graph[source - 1].Add(destination);
    }
}

// stores how many times each node is visited in the MC algorithm
int[] visits = new int[n];
for (int i = 0; i < n; i++)
    visits[i] = 0;

Random random = new Random();

Stopwatch stopwatch = new Stopwatch();
stopwatch.Start();

// perform the random walk r times
for (int i = 0; i < r; i++)
{
    // from each node
    for (int j = 0; j < n; j++)
    {
        int currentNode = j + 1;

        do
        {
            // increment the # of times we've visited the current node
            visits[currentNode - 1]++;

            // travel to the next node with P(beta) and exit the random walk
            if (random.NextDouble() < beta)
            {
                // get the next node in the random walk
                if (graph[currentNode - 1].Count == 0)
                    // exit if we hit a dangling node
                    break;
                else
                    // select the next node uniformly at random
                    currentNode = graph[currentNode - 1][random.Next(graph[currentNode - 1].Count)];
            }
            else
                break;
        } while (true);
    }
}

stopwatch.Stop();

```



```

        // calculate Rj, the estimated PageRank
        double[] rj = new double[n];
        for (int i = 0; i < n; i++)
            rj[i] = ((double)visits[i]) * ((1.0 - beta) / ((double)(n * r)));

        // return the results
        return new Tuple<Vector, KeyValuePair<int, double>[],
        TimeSpan>(Vector.Create(rj), ToSortedArrayDesc(rj), stopwatch.Elapsed);
    }

    private static Tuple<Vector, KeyValuePair<int, double>[], TimeSpan> PageRank()
    {
        // create M
        Matrix M = Matrix.Create(n, n);

        // populate M with 1.0 for each edge
        using (StreamReader reader = new StreamReader(graphPath))
        {
            string line;
            while ((line = reader.ReadLine()) != null)
            {
                string[] elements = line.Split();

                int source = int.Parse(elements[0]);
                int destination = int.Parse(elements[1]);

                // increment Mji
                M[destination-1, source-1] += 1.0;
            }
        }

        // make M column stochastic
        for (int i = 0; i < n; i++)
        {
            Vector column = M.GetColumn(i);
            double sum = column.Sum();

            for (int j = 0; j < n; j++)
                column[j] /= sum;
        }

        // create and initialize teleport vector S
        Vector S = Vector.Create(n);
        for (int i = 0; i < n; i++)
            S[i] = 1.0 / (double)n;

        // create and initialize r (r0)
        Vector r = Vector.Create(n);
        for (int i = 0; i < n; i++)
            r[i] = 1.0 / (double)n;

        // time 40 power iterations
        Stopwatch stopwatch = new Stopwatch();
        stopwatch.Start();

        for (int i = 0; i < 40; i++)

```

```

        r = (beta * (M * r)) + ((1 - beta) * S);

        stopwatch.Stop();

        return new Tuple<Vector, KeyValuePair<int, double>[], TimeSpan>(r,
ToSortedArrayDesc(r.ToArray()), stopwatch.Elapsed);
    }
}

```

```

% Philip Scuderi
% Stanford University
% Winter 2013
% CS 246
% Homework 3
% Question 3

function [] = Q3
    M = [0 1 1 0 1; 0 1 0 1 0; 1 0 0 0 0];
    [M_A1,M_B1] = Iterate(M,1);
    M_A1 %#ok<*NOPRT>
    M_B1
    [M_A2,M_B2] = Iterate(M,2);
    M_A2
    M_B2
    [M_A3,M_B3] = Iterate(M,3);
    M_A3
    M_B3

    K21 = [1; 1];
    [K21_A1,K21_B1] = Iterate(K21,1);
    K21_A1
    K21_B1
    [K21_A2,K21_B2] = Iterate(K21,2);
    K21_A2
    K21_B2
    [K21_A3,K21_B3] = Iterate(K21,3);
    K21_A3
    K21_B3

    K22 = [1 1; 1 1];
    [K22_A1,K22_B1] = Iterate(K22,1);
    K22_A1
    K22_B1
    [K22_A2,K22_B2] = Iterate(K22,2);
    K22_A2
    K22_B2
    [K22_A3,K22_B3] = Iterate(K22,3);
    K22_A3
    K22_B3
end

function [A,B]=Iterate(M,k)
    A = eye(size(M,1));
    B = eye(size(M,2));
    for i=1:k
        nextA = NextA(M,A,B);
        nextB = NextB(M,A,B);
        A = nextA;
        B = nextB;
    end
end

function A1=NextA(M,A0,B0)
    A1 = A0;
    for i=1:length(A0)

```

```

        for j=1:length(A0)
            if i~=j
                A1(i,j) = Sa(M,i,j,B0);
                A1(j,i) = A1(i,j);
            end
        end
    end
end

function B1=NextB(M,A0,B0)
    B1 = B0;
    for i=1:length(B0)
        for j=1:length(B0)
            if i~=j
                B1(i,j) = Sb(M,i,j,A0);
                B1(j,i) = B1(i,j);
            end
        end
    end
end

function a=Sa(M,X,Y,B)
    C1 = 0.8;
    a = 0.0;
    for i=1:sum(O(M,X))
        for j=1:sum(O(M,Y))
            a = a + B(IdxIthNonZeroElement(i, O(M,X)), IdxIthNonZeroElement(j,
O(M,Y)));
        end
    end
    a = a * (C1 / (sum(O(M,X)) * sum(O(M,Y))));
end

function b=Sb(M,X,Y,A)
    C2 = 0.8;
    b = 0.0;
    for i=1:sum(I(M,X))
        for j=1:sum(I(M,Y))
            b = b + A(IdxIthNonZeroElement(i, I(M,X)), IdxIthNonZeroElement(j,
I(M,Y)));
        end
    end
    b = b * (C2 / (sum(I(M,X)) * sum(I(M,Y))));
end

function O=O(M,X)
    O = M(X,:);
end

function I=I(M,X)
    I = M(:,X);
end

function IdxIthNonZeroElement=IdxIthNonZeroElement(i, OX)
    IdxIthNonZeroElement = 0;
    count = 0;

```

```
for j=1:length(OX)
    if OX(j)~=0
        count = count + 1;
        if count == i
            IdxIthNonZeroElement = j;
        end
    end
end
end
end
```

```

/*
 * Philip Scuderi
 * Stanford University
 * CS246
 * Winter 2013
 * Homework 3
 * Question 4
 */

using System;
using System.Collections.Generic;
using System.Linq;
using System.Text;
using System.IO;
using System.Diagnostics;

namespace HW3_Q4
{
    class Program
    {
        static void Main(string[] args)
        {
            Stopwatch stopwatch = new Stopwatch();
            stopwatch.Start();

            Q4 q4 = new Q4("../livejournal-undirected.txt");

            // 4(c)(i)
            Console.WriteLine("epsilon\ti");
            foreach (double epsilon in (new double[] { 0.1, 0.5, 1.0, 2.0 }))
                Console.WriteLine("{0}\t{1}", epsilon, q4.FindInducedSubgraph(epsilon,
true).Item2.Count - 1);

            // 4(c)(ii)
            Console.WriteLine("\ni\tp(Si)\t|E(Si)|\t|Si|");
            int i = 0;
            foreach (Tuple<double, int, int> r in q4.FindInducedSubgraph(0.05,
true).Item2)
                Console.WriteLine("{0}\t{1}\t{2}\t{3}", i++, r.Item1, r.Item2, r.Item3);

            // 4(c)(iii)
            List<Tuple<ISet<int>, IList<Tuple<double, int, int>>>> results = new
List<Tuple<ISet<int>, IList<Tuple<double, int, int>>>>(20);
            for (int j = 0; j < 20; j++)
            {
                var resultJ = q4.FindInducedSubgraph(0.05);
                results.Add(resultJ);
                q4.DeleteVertices(resultJ.Item1);
            }

            Console.WriteLine("\nj\tp(Si)\t|E(Si)|\t|Si|");
            for (int j = 0; j < 20; j++)
            {
                int numInducedEdges = q4.NumInducedEdges(results[j].Item1);
                int sizeOfS = results[j].Item1.Count;
                double rho = ((double)numInducedEdges) / ((double)sizeOfS);
                Console.WriteLine("{0}\t{1}\t{2}\t{3}", j+1, rho, numInducedEdges,
sizeOfS);
            }
        }
    }
}

```

```

    }

    stopwatch.Stop();

    Console.WriteLine("\n\nTotal Time = {0}\nPress any key to continue...",
stopwatch.Elapsed);
    Console.ReadKey();
}

}

public class Q4
{
    protected HashSet<int> V;
    protected string graphPath;

    public Q4(string graphPath)
    {
        this.graphPath = graphPath;
        V = new HashSet<int>();

        using (StreamReader reader = new StreamReader(graphPath))
        {
            string line;
            while ((line = reader.ReadLine()) != null)
            {
                string[] elements = line.Split();

                int v1 = int.Parse(elements[0]);
                int v2 = int.Parse(elements[1]);

                V.Add(v1);
                V.Add(v2);
            }
        }

        public void DeleteVerticies(ISet<int> S)
        {
            V.ExceptWith(S);
        }

        public Tuple<ISet<int>, IList<Tuple<double, int, int>>>
FindInducedSubgraph(double epsilon, bool resultsPerIteration = false)
        {
            // the results at each iteration: p(Si), |E(Si)|, and |Si|
            List<Tuple<double, int, int>> iterativeResults = null;

            if (resultsPerIteration)
                iterativeResults = new List<Tuple<double, int, int>>();

            HashSet<int> S = new HashSet<int>(V);
            HashSet<int> tildeS = new HashSet<int>(V);

            while (S.Count != 0)
            {
                if (resultsPerIteration)
                {
                    if (iterativeResults.Count == 0)

```

```

        // track iterative results at iteration 0, i.e., before we begin
        iterativeResults.Add(new Tuple<double, int, int>(Rho(S),
NumInducedEdges(S), S.Count));
    }

    //  $A(S) := \{i \in V \mid \deg_S(i) \leq 2(1+\epsilon)p(S)\}$ 
    HashSet<int> AS = A(S, epsilon);

    //  $S \leftarrow S \setminus A(S)$ 
    S.ExceptWith(AS);

    // if  $p(S) > p(\tilde{S})$ 
    if (Rho(S) > Rho(tildeS))
    {
        //  $\tilde{S} \leftarrow S$ 
        tildeS = new HashSet<int>(S);
    }

    if (resultsPerIteration)
    {
        // track the results at the end of each iteration ( $i = 1, 2, \dots$ )
        iterativeResults.Add(new Tuple<double, int, int>(Rho(S),
NumInducedEdges(S), S.Count));
    }
}

return new Tuple<ISet<int>, IList<Tuple<double, int, int>>>(tildeS,
iterativeResults);
}

protected HashSet<int> A(HashSet<int> S, double epsilon)
{
    HashSet<int> A = new HashSet<int>();

    Dictionary<int, int> degS = deg(S);
    double rhoS = Rho(S);

    foreach (int i in S)
        if (degS[i] <= 2.0 * (1.0 + epsilon) * rhoS)
            A.Add(i);

    return A;
}

protected Dictionary<int, int> deg(HashSet<int> S)
{
    Dictionary<int, int> degS = new Dictionary<int, int>(S.Count);

    foreach (int i in S)
        degS.Add(i, 0);

    using (StreamReader reader = new StreamReader(graphPath))
    {
        string line;
        while ((line = reader.ReadLine()) != null)
        {
            string[] elements = line.Split();

```



```

        int v1 = int.Parse(elements[0]);
        int v2 = int.Parse(elements[1]);

        if (S.Contains(v1) && S.Contains(v2))
        {
            degS[v1]++;
            degS[v2]++;
        }
    }
}

return degS;
}

public int NumInducedEdges(ISet<int> S)
{
    int inducedEdgeCount = 0;

    using (StreamReader reader = new StreamReader(graphPath))
    {
        string line;
        while ((line = reader.ReadLine()) != null)
        {
            string[] elements = line.Split();

            int v1 = int.Parse(elements[0]);
            int v2 = int.Parse(elements[1]);

            if (S.Contains(v1) && S.Contains(v2))
                ++inducedEdgeCount;
        }
    }

    return inducedEdgeCount;
}

public double Rho(ISet<int> S)
{
    return ((double)NumInducedEdges(S)) / ((double)S.Count);
}
}

```