Course 2: Supervised Learning



Summary

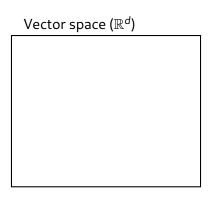
Last session

- 1 Al definition
- 2 Applications
- 3 Deep learning
- Open issues

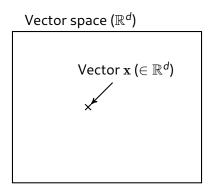
Today's session

- Learning from labeled examples
- Challenges of supervised learning

Notations

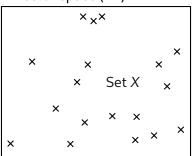


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Vector space (\mathbb{R}^d)



Definition

Supervised learning methods use **labels** $\hat{\mathbf{y}}$ associated with examples \mathbf{x} to learn a function f such as $\hat{\mathbf{y}} \approx f(\mathbf{x})$, with the aim of **generalizing** (\neq memorizing) to unlabeled examples.

x:



ŷ: "cat"

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Goal of supervised learning: learning the mapping function f()

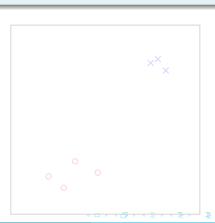




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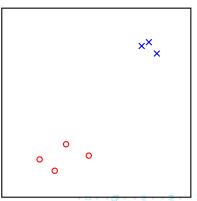
- Classification (y is categorical)
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 - Pattern recognition,
 - Prediction...



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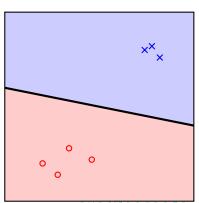
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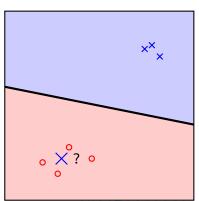
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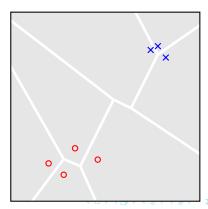
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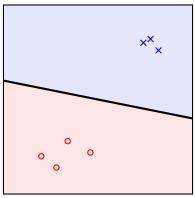
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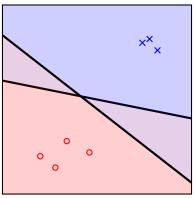
An ill-defined problem

- An infinity of potential solutions, one must be the "best one" but is unreachable,
- ⇒ requires **priors or constraints**.



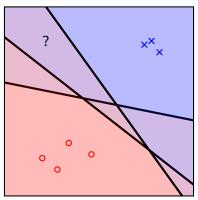
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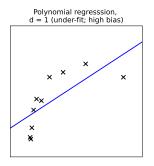


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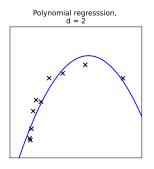
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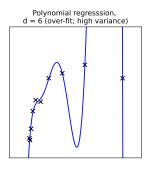
- A simple solution that almost matches is better than a complex one that fully matches,
- Mimicking is not learning: overfitting problem.



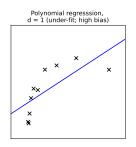
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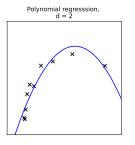


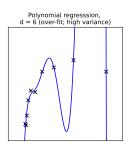
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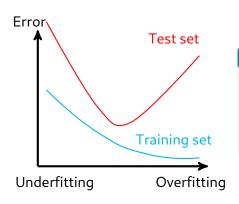






Bias/variance trade-off

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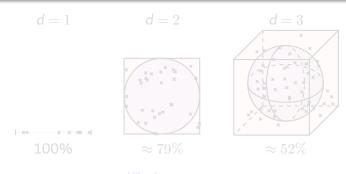


Crossvalidation

- To detect overfitting, split training dataset in two parts:
 - A first part is used to train,
 - 2 A second part is used to validate,

Curse of dimensionality

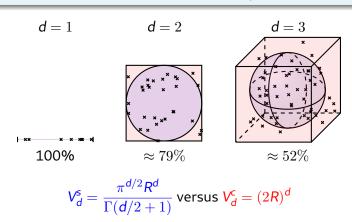
- Geometry is not intuitive in high dimension,
- Efficient methods in 2D are not necessarily still valid.

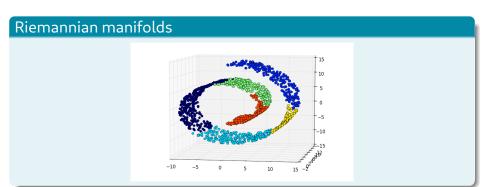


$$V_d^s = \frac{\pi^{a/2}R^a}{\Gamma(d/2+1)}$$
 versus $V_d^c = (2R)^d$

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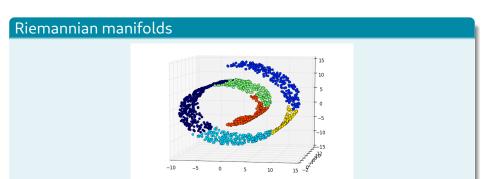












Linear separability and need for embedding









Computation time

Example on ImageNet, simply going through all images:

- $n = 10.000.000, d \approx 1.000.000,$
- ho $pprox 10^{13}$ elementary operations,
- ho pprox 2h45 on a modern processor.

Scalability

- Finding the best solution to a problem would be feasible with unlimited computation time,
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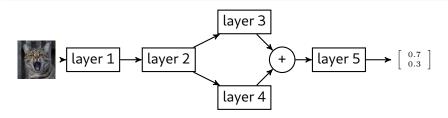
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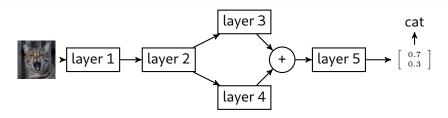
Inputs/outputs

- Often: inputs are raw signals or feature vectors,
- Often: outputs are vectors which highest value indicate the category of the input.



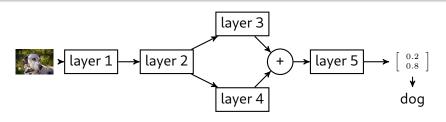
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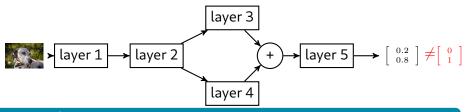
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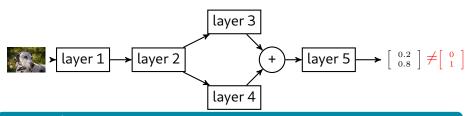


Loss and targets

- Labels are encoded as one-hot-bit vectors and called targets,
- Outputs are **softmaxed**: $\mathbf{y}_i \leftarrow \exp(\mathbf{y}_i) / \sum_i \exp(\mathbf{y}_i)$,
- Loss is typically **cross-entropy**: $-\log(\hat{\mathbf{y}}^{\top}\mathbf{y})$.

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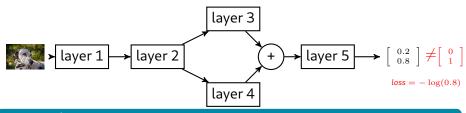


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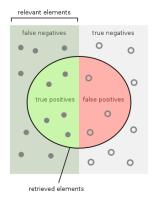


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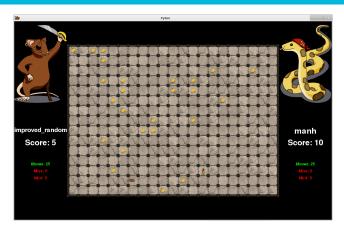
Metrics

In supervised learning: per class metric





Non-symmetric PyRat without walls / mud



Both players follow a deterministic greedy algorithm. Supervised learning - Two tasks

- Lab 2a Predict the outcome of a game from the start configuration.
- Lab 2b Learn the next move using a dataset of winners

Lab Session 2 and assignments for Session 3

Lab Supervised Learning

- Basics of machine learning using sklearn (including new definitions / concepts)
- Tests on PyRat datasets: winner prediction task

Project 1 (P1)

You will choose a supervised learning method. You have to prepare a Jupyter Notebook on this method, including:

- A brief description of the theory behind the method,
- Basic tests on simulated data to show the influence of parameters and hyperparameters
- Tests on PyRat Datasets on the winner prediction task

During Session 3 you will have 7 minutes to present your notebook.