Math 266: Autonomous equation and population dynamics

Long Jin

Purdue, Spring 2018

Autonomous equation

An autonomous equation is a differential equation which only involves the unknown function y and its derivatives, but not the variable t explicitly.

Autonomous equation

An autonomous equation is a differential equation which only involves the unknown function y and its derivatives, but not the variable t explicitly.

In particular, a first order autonomous equation is of the form

$$\frac{dy}{dt} = f(y).$$

Example: f(y) = ay - b, the equation for a falling object and the population of field mice.

Autonomous equation

An autonomous equation is a differential equation which only involves the unknown function y and its derivatives, but not the variable t explicitly.

In particular, a first order autonomous equation is of the form

$$\frac{dy}{dt}=f(y).$$

Example: f(y) = ay - b, the equation for a falling object and the population of field mice.

Such equations are always separable:

$$\frac{dy}{f(y)} = dt \Rightarrow \int \frac{dy}{f(y)} = t + C.$$

However, the solutions are often implicit.

Basic properties of solutions

For solutions y = y(t) to the autonomous equation

$$y' = f(y)$$
.

Basic properties of solutions

For solutions y = y(t) to the autonomous equation

$$y'=f(y).$$

Translation invariance

If y = y(t) is a solution, then so is $\widetilde{y}(t) = y(t + a)$ where a is any number:

- ▶ Algebraically, in the formula for solutions $\int \frac{dy}{f(y)} = t + C$, this means changing the arbitrary constants.
- Geometrically, the direction field does not depend on t. Therefore it is invariant under translation and so does the graph of the solutions.

Basic properties of solutions

For solutions y = y(t) to the autonomous equation

$$y' = f(y)$$
.

Translation invariance

If y = y(t) is a solution, then so is $\widetilde{y}(t) = y(t + a)$ where a is any number:

- ▶ Algebraically, in the formula for solutions $\int \frac{dy}{f(y)} = t + C$, this means changing the arbitrary constants.
- Geometrically, the direction field does not depend on t. Therefore it is invariant under translation and so does the graph of the solutions.

Equilibrium solutions

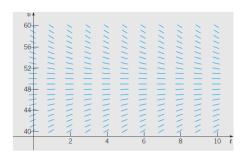
A constant function $y(t) \equiv y_0$ is a solution if and only if $f(y_0) = 0$. Such numbers y_0 are often called **critical points**.



An old example through dfield

We recall the first example of falling objects

$$\frac{dv}{dt} = 9.8 - \frac{1}{5}v$$



The only equilibrium solution is $v(t) \equiv 49$.

Non-equilibrium solutions

From now on, in the autonomous equation

$$y' = f(y)$$

we assume that f and f' are both continuous, so we have local existence and uniqueness of solutions. (Recall the bad example: $f(y) = y^{1/3}$.)

Non-equilibrium solutions

From now on, in the autonomous equation

$$y' = f(y)$$

we assume that f and f' are both continuous, so we have local existence and uniqueness of solutions. (Recall the bad example: $f(y) = y^{1/3}$.)

- A non-equilibrium solution is confined in a region where either f is always positive or f is always negative.
- Monotonicity: All non-equilibrium solutions are either always increasing (f(y) > 0) or decreasing (f(y) < 0).
- Limits: As $t \to \pm \infty$, each non-equilibrium solution either converges to an equilibrium solution or infinity (maybe in finite time).

Population dynamics

As examples, we study some basic models in population dynamics of a single species. Without interaction with other species, the change of the population y=y(t) can be assumed to only depend on the population itself:

$$\frac{dy}{dt}=f(y).$$

Population dynamics

As examples, we study some basic models in population dynamics of a single species. Without interaction with other species, the change of the population y = y(t) can be assumed to only depend on the population itself:

$$\frac{dy}{dt} = f(y).$$

- ▶ Thomas Robert Malthus 1798: growth rate
- ▶ Pierre Franois Verhulst 1838: logistic model
- ► Critical threshold, etc.





Malthus: exponential growth

The hypothesis of Malthus is very simple: the growth of the population is proportional to the population itself.

$$\frac{dy}{dt} = ry.$$

Malthus: exponential growth

The hypothesis of Malthus is very simple: the growth of the population is proportional to the population itself.

$$\frac{dy}{dt} = ry.$$

- r > 0 is the growth rate, often appears as the birth rate subtract the death rate.
- ▶ With initial value $y(0) = y_0 > 0$, the solution is an exponential function $y(t) = y_0 e^{rt}$.

Malthus: exponential growth

The hypothesis of Malthus is very simple: the growth of the population is proportional to the population itself.

$$\frac{dy}{dt} = ry.$$

- r > 0 is the growth rate, often appears as the birth rate subtract the death rate.
- With initial value $y(0) = y_0 > 0$, the solution is an exponential function $y(t) = y_0 e^{rt}$.
- ▶ In a limited time period and ideal situation (abundance of food, no change of environment, etc.), the model is observed to be quite accurate.
- ▶ But obviously, it cannot go on forever. Limitation of food, space, etc.

Verhulst replaces the constant growth rate r by a function h(y):

$$\frac{dy}{dt}=h(y)y$$

Verhulst replaces the constant growth rate r by a function h(y):

$$\frac{dy}{dt} = h(y)y$$

Here the function h = h(y) should satisfy

Natural growth for small population: When y is close to 0, h(y) should be close to the natural growth rate r.

Verhulst replaces the constant growth rate r by a function h(y):

$$\frac{dy}{dt} = h(y)y$$

Here the function h = h(y) should satisfy

- Natural growth for small population: When y is close to 0, h(y) should be close to the natural growth rate r.
- ▶ Increasing competition: When y increases, h(y) should decrease.

Verhulst replaces the constant growth rate r by a function h(y):

$$\frac{dy}{dt} = h(y)y$$

Here the function h = h(y) should satisfy

- Natural growth for small population: When y is close to 0, h(y) should be close to the natural growth rate r.
- ▶ Increasing competition: When y increases, h(y) should decrease.
- ▶ Overpopulation: when y is very large, h(y) should be negative.

Verhulst replaces the constant growth rate r by a function h(y):

$$\frac{dy}{dt} = h(y)y$$

Here the function h = h(y) should satisfy

- Natural growth for small population: When y is close to 0, h(y) should be close to the natural growth rate r.
- ▶ Increasing competition: When y increases, h(y) should decrease.
- ▶ Overpopulation: when y is very large, h(y) should be negative.

The simplest example for such a function is a linear function

$$h(y) = r - ay = r(1 - \frac{y}{K}).$$

Now we consider the solutions to the logistic equation

$$\frac{dy}{dt}=f(y):=ry(1-\frac{y}{K}).$$

Now we consider the solutions to the logistic equation

$$\frac{dy}{dt}=f(y):=ry(1-\frac{y}{K}).$$

There are two equilibrium solutions:

$$y(t) \equiv 0, \quad y(t) \equiv K$$

Now we consider the solutions to the logistic equation

$$\frac{dy}{dt}=f(y):=ry(1-\frac{y}{K}).$$

There are two equilibrium solutions:

$$y(t) \equiv 0, \quad y(t) \equiv K$$

For other solutions

- ▶ If 0 < y < K, then y' = f(y) > 0 and thus y is increasing
- ▶ If y > K, then y' = f(y) < 0 and thus y is decreasing

Now we consider the solutions to the logistic equation

$$\frac{dy}{dt}=f(y):=ry(1-\frac{y}{K}).$$

There are two equilibrium solutions:

$$y(t) \equiv 0, \quad y(t) \equiv K$$

For other solutions

- ▶ If 0 < y < K, then y' = f(y) > 0 and thus y is increasing
- ▶ If y > K, then y' = f(y) < 0 and thus y is decreasing
- ▶ In both cases, the solution converges to K as $t \to \infty$. The equilibrium solution is said to be **asymptotically stable**.

Now we consider the solutions to the logistic equation

$$\frac{dy}{dt}=f(y):=ry(1-\frac{y}{K}).$$

There are two equilibrium solutions:

$$y(t) \equiv 0, \quad y(t) \equiv K$$

For other solutions

- ▶ If 0 < y < K, then y' = f(y) > 0 and thus y is increasing
- ▶ If y > K, then y' = f(y) < 0 and thus y is decreasing
- ▶ In both cases, the solution converges to K as $t \to \infty$. The equilibrium solution is said to be **asymptotically stable**.

The number K is often called the **saturation level** or the **environment carrying capacity**.

Second derivative and inflection points

By chain rule and the equation itself, we have

$$\frac{d^2y}{dt^2} = \frac{d}{dt}(f(y)) = f'(y)\frac{dy}{dt} = f'(y)f(y).$$

Here
$$f'(y) = r(1 - \frac{2y}{K})$$
, so

- ▶ If 0 < y < K/2, then y'' > 0 and y is convex
- ▶ If K/2 < y < K, then y'' < 0 and y is concave
- If y > K, then y'' > 0 and y is convex

Second derivative and inflection points

By chain rule and the equation itself, we have

$$\frac{d^2y}{dt^2} = \frac{d}{dt}(f(y)) = f'(y)\frac{dy}{dt} = f'(y)f(y).$$

Here $f'(y) = r(1 - \frac{2y}{K})$, so

- ▶ If 0 < y < K/2, then y'' > 0 and y is convex
- ▶ If K/2 < y < K, then y'' < 0 and y is concave
- ▶ If y > K, then y'' > 0 and y is convex

To sum up, for the initial value problem

$$\frac{dy}{dt} = ry(1 - \frac{y}{K}), \quad y(0) = y_0 > 0.$$

- ▶ If $0 < y_0 < K$, then the solution is increasing with a single inflection point when y = K/2 where it changes from convex to concave.
- ▶ If $y_0 > K$, then the solution is decreasing and convex.



Graphs and the phase line

It is easier to summarize the analysis with the following graphs.

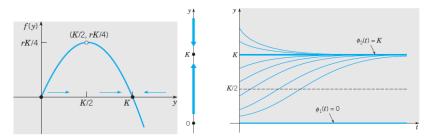


Figure: Left: Graph of f = f(y); Middle: phase line; Right: the graphs of the solutions y = y(t)

On the **phase line**, a dot represents an equilibrium solution while on other parts we use arrows to describe the monotonicity of solutions.

For the logistic model, we can find the solution in explicit form:

$$\frac{dy}{dt} = ry(1 - \frac{y}{K}), \quad y(0) = y_0 > 0.$$

For the logistic model, we can find the solution in explicit form:

$$\frac{dy}{dt}=ry(1-\frac{y}{K}), \quad y(0)=y_0>0.$$

Separate t and y:

$$\frac{dy}{y(1-y/K)} = rdt \quad \Rightarrow \quad \int \frac{dy}{y(1-y/K)} = rt + c$$

For the logistic model, we can find the solution in explicit form:

$$\frac{dy}{dt}=ry(1-\frac{y}{K}), \quad y(0)=y_0>0.$$

Separate t and y:

$$\frac{dy}{y(1-y/K)} = rdt \quad \Rightarrow \quad \int \frac{dy}{y(1-y/K)} = rt + c$$

Calculate the integral by partial fraction:

$$\frac{1}{y(1-y/K)} = \frac{1}{y} + \frac{1/K}{1-y/K}, \quad \int \frac{dy}{y(1-y/K)} = \ln|y| - \ln\left|1 - \frac{y}{K}\right|$$

For the logistic model, we can find the solution in explicit form:

$$\frac{dy}{dt}=ry(1-\frac{y}{K}), \quad y(0)=y_0>0.$$

Separate t and y:

$$\frac{dy}{y(1-y/K)} = rdt \quad \Rightarrow \quad \int \frac{dy}{y(1-y/K)} = rt + c$$

Calculate the integral by partial fraction:

$$\frac{1}{y(1-y/K)} = \frac{1}{y} + \frac{1/K}{1-y/K}, \quad \int \frac{dy}{y(1-y/K)} = \ln|y| - \ln\left|1 - \frac{y}{K}\right|$$

Therefore

$$\frac{y}{1-y/K} = Ce^{rt} \quad \Rightarrow \quad y = \frac{Ce^{rt}}{1+Ce^{rt}/K}.$$

$$\frac{dy}{dt} = ry(1 - \frac{y}{K}), \quad y(0) = y_0 > 0.$$

$$\frac{dy}{dt}=ry(1-\frac{y}{K}), \quad y(0)=y_0>0.$$

In

$$\frac{y}{1 - y/K} = Ce^{rt} \quad \Rightarrow \quad y = \frac{Ce^{rt}}{1 + Ce^{rt}/K}$$

set t = 0, $y = y_0$,

$$y_0 = \frac{C}{1 + C/K} \quad \Rightarrow \quad C = \frac{y_0}{1 - y_0/K}.$$

$$\frac{dy}{dt}=ry(1-\frac{y}{K}), \quad y(0)=y_0>0.$$

In

$$\frac{y}{1 - y/K} = Ce^{rt}$$
 \Rightarrow $y = \frac{Ce^{rt}}{1 + Ce^{rt}/K}$

set t = 0, $y = y_0$,

$$y_0 = \frac{C}{1 + C/K} \quad \Rightarrow \quad C = \frac{y_0}{1 - y_0/K}.$$

Therefore

$$y = \frac{y_0 K}{y_0 + (K - y_0)e^{-rt}}.$$

$$\frac{dy}{dt}=ry(1-\frac{y}{K}),\quad y(0)=y_0>0.$$

In

$$\frac{y}{1 - y/K} = Ce^{rt}$$
 \Rightarrow $y = \frac{Ce^{rt}}{1 + Ce^{rt}/K}$

set t = 0, $y = y_0$,

$$y_0 = \frac{C}{1 + C/K} \quad \Rightarrow \quad C = \frac{y_0}{1 - y_0/K}.$$

Therefore

$$y = \frac{y_0 K}{y_0 + (K - y_0)e^{-rt}}.$$

It is easy to check all the properties that we derived without solving the equation. In particular, as long as $y_0 > 0$,

$$y(t) \to K$$
 as $t \to \infty$.

Logistic functions

The special case K=1 and $y_0=\frac{1}{2}$ gives the so called standard logistic function

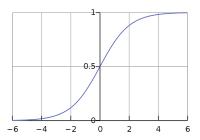
$$y = \frac{1}{1 + e^{-t}} = \frac{e^t}{1 + e^t}$$

Logistic functions

The special case K=1 and $y_0=\frac{1}{2}$ gives the so called standard logistic function

$$y = \frac{1}{1 + e^{-t}} = \frac{e^t}{1 + e^t}$$

whose graph is a "sigmoid" curve (looking like the letter "S").

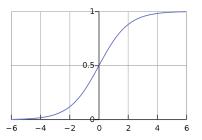


Logistic functions

The special case K=1 and $y_0=\frac{1}{2}$ gives the so called standard logistic function

$$y = \frac{1}{1 + e^{-t}} = \frac{e^t}{1 + e^t}$$

whose graph is a "sigmoid" curve (looking like the letter "S").



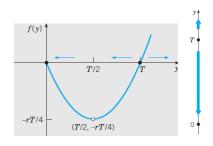
Applications in a range of fields, including artificial neural networks, biology (especially ecology), biomathematics, chemistry, demography, economics, geoscience, mathematical psychology, probability, sociology, political science, linguistics, and statistics.

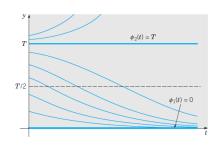
A critical threshold

For certain species, when population is too small, there is a danger that it could go extinct as there are not enough partners to breed new generations. In such cases, we introduce the following model

$$\frac{dy}{dt} = -ry(1 - \frac{y}{T})$$

where T > 0 is the **threshold level**.



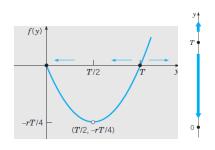


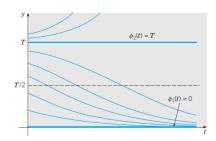
Analyzing the critical threshold

The analysis of

$$\frac{dy}{dt} = f(y) := -ry(1 - \frac{y}{T})$$

is very similar to the logistic model except all the signs are reversed. In this case, the equilibrium solution $y(t) \equiv T$ is said to be **unstable** as both solutions in (0, T) and (T, ∞) diverge from T.





Logistic growth with a threshold

However, from the explicit form of the solution to

$$\frac{dy}{dt} = -ry(1 - \frac{y}{T}), \quad y(0) = y_0$$

given by

$$y = \frac{y_0 T}{y_0 + (T - y_0)e^{rt}}$$

we see that if $y_0 > T$, then $y(t) \to +\infty$ in finite time

$$t \to T_* = \frac{1}{r} \ln \frac{y_0}{y_0 - T}.$$

Logistic growth with a threshold

However, from the explicit form of the solution to

$$\frac{dy}{dt} = -ry(1 - \frac{y}{T}), \quad y(0) = y_0$$

given by

$$y = \frac{y_0 T}{y_0 + (T - y_0)e^{rt}}$$

we see that if $y_0 > T$, then $y(t) \to +\infty$ in finite time

$$t \to T_* = \frac{1}{r} \ln \frac{y_0}{y_0 - T}.$$

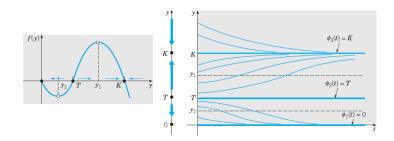
To avoid such behaviors, we combine the logistic model with the critical threshold:

$$\frac{dy}{dt} = -ry(1 - \frac{y}{T})(1 - \frac{y}{K}).$$

Logistic growth with a threshold

$$\frac{dy}{dt} = f(y) := -ry(1 - \frac{y}{T})(1 - \frac{y}{K}).$$

Here r>0 is the natural growth rate; T>0 is the threshold; K>0 is the environment carrying capacity. We assume that K>T.



Equilibrium solutions:

- \triangleright $y(t) \equiv T$ is unstable;
- $y(t) \equiv K$ is asymptotically stable.



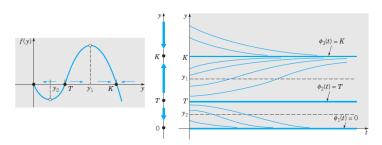
Analyzing logistic growth with a threshold

Equilibrium solutions:

- ▶ $y(t) \equiv T$ is unstable;
- $y(t) \equiv K$ is asymptotically stable.

Other solutions:

- ▶ If initial population is below the threshold, then the species goes extinct: $y(t) \rightarrow 0$.
- ▶ If initial population is above the threshold, then the population tends to the saturation level: $y(t) \rightarrow K$.



Summary

In general, for an autonomous equation

$$y'=f(y)$$

The equilibrium solutions are given by $y(t) \equiv y_0$ where y_0 are solutions to $f(y_0) = 0$.

Classification of equilibrium solution

There are three kinds of equilibrium solutions $y(t) \equiv y_0$:

- ▶ Asymptotically stable: Nearby solutions converge to y_0 .
- ▶ Unstable: Nearby solutions diverge from y_0 .
- ▶ Semistable: On one side, nearby solutions converge to y_0 , while on the other side, they diverge from y_0 .

It is very easy to use phase line to picture these situations.