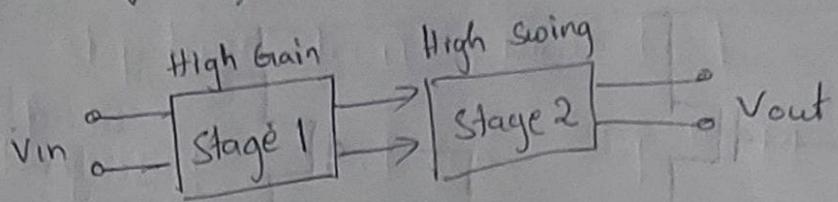
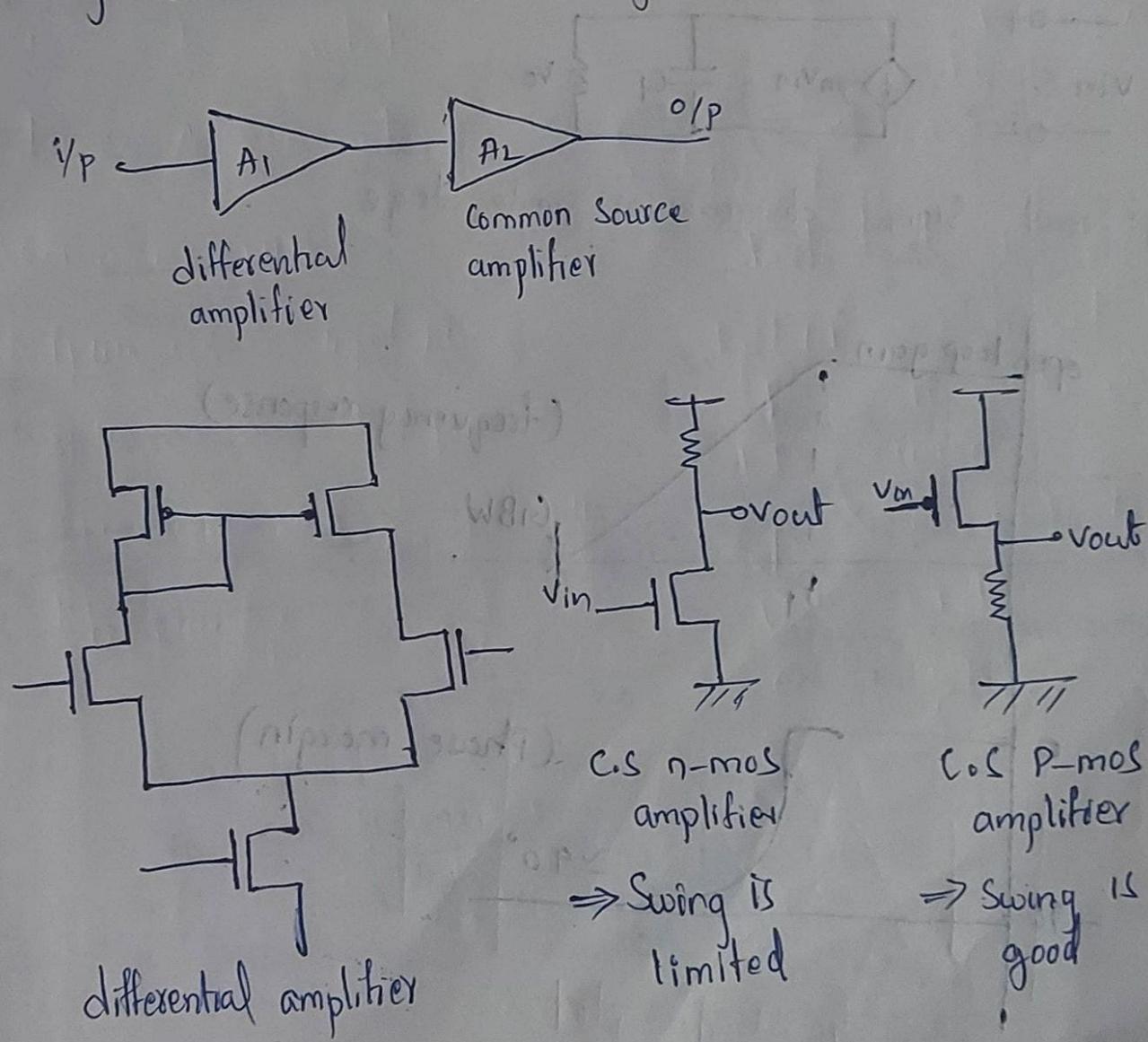


Two stages of amp



- ⇒ Two-stage op. amp consist of first stage providing a high gain and the second providing large swing
- ⇒ The first stage incorporates various amplifier topologies, but the second stage is typically configured as a simple common source stage to allow maximum output swings. (maximum output swing \Rightarrow maximum output voltage)



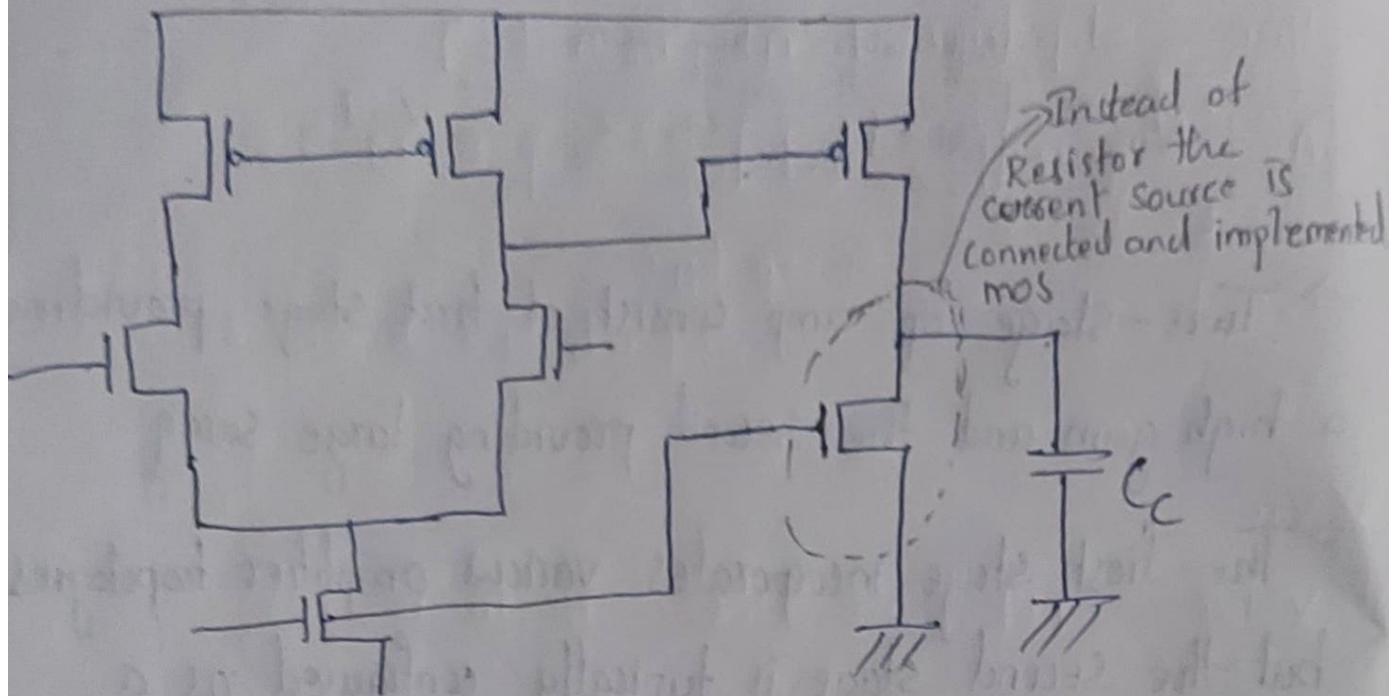


fig: Two-stage op amp small signal

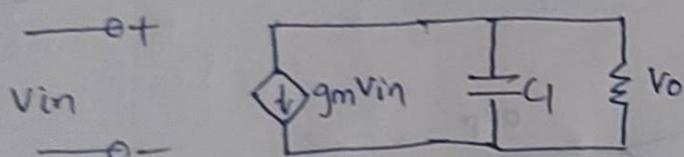


fig: Small Signal diagram of single stage

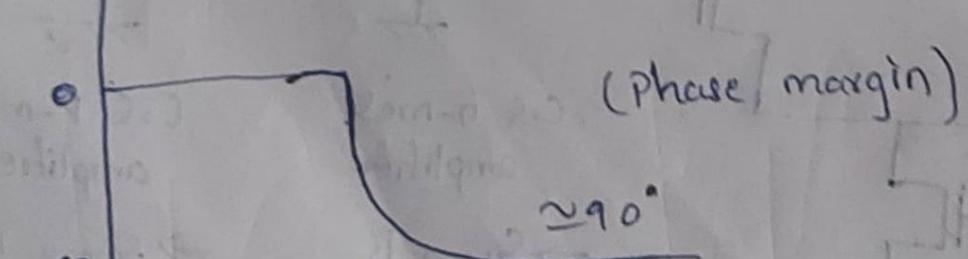
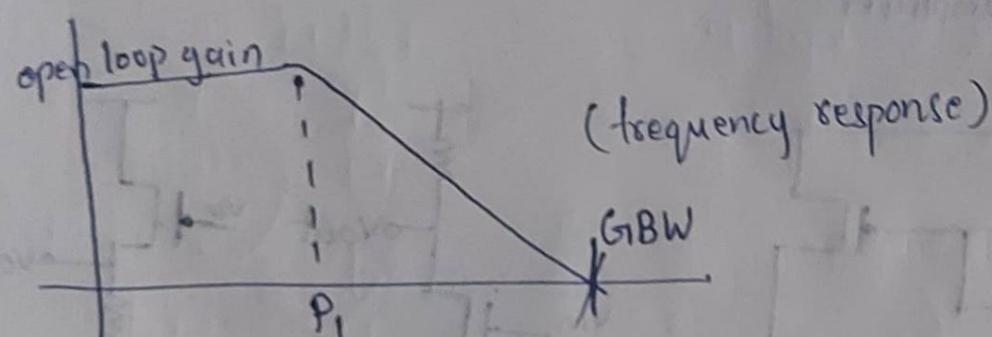


fig: Bode plot

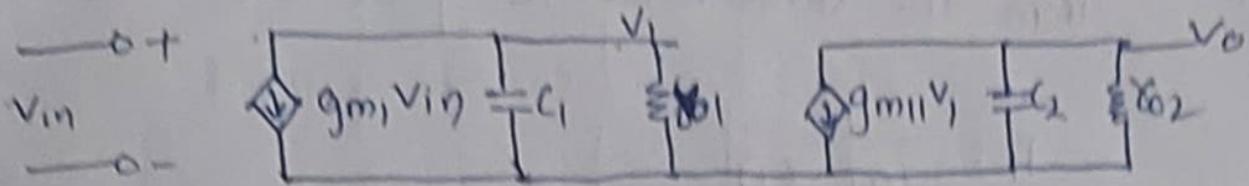


fig: Small signal diagram of two stage op amp

$$P_1 = \frac{1}{\tau_{o1} C_1}$$

$$P_2 = \frac{1}{\tau_{o2} C_2}$$

First stage output (v_1):

At node v_1 , impedance is

$$z_1 = \left(\frac{1}{\tau_{o1}} \right) \parallel \left(\frac{1}{j\omega C_1} \right)$$

$$= \frac{1}{\tau_{o1} + j\omega C_1}$$

So,

$$v_1 = g_{m1} \cdot v_{in} \cdot z_1$$

$$\boxed{v_1 = g_{m1} \cdot v_{in} / (\tau_{o1} + j\omega C_1)}$$

Second stage output (v_o):

At node v_o :

$$z_2 = \left(\frac{1}{\tau_{o2}} \right) \parallel \left(\frac{1}{j\omega C_2} \right)$$

$$= \frac{1}{\tau_{o2} + j\omega C_2}$$

So,

$$v_o = g_{m2} \cdot v_1 \cdot z_2$$

$$\boxed{v_o = g_{m2} \cdot v_1 / (\tau_{o2} + j\omega C_2)}$$

Sub v_1 in v_o

$\therefore g_{m1}, g_{m2}$ are transconductances of stages

$$v_o = g_{m2} \left[\frac{g_{m1} \cdot v_{in}}{(\tau_{o1} + j\omega C_1)} \right] \cdot \left[\frac{1}{\tau_{o2} + j\omega C_2} \right]$$

So the overall transfer function

$$\frac{v_o}{v_{in}} = \frac{(g_{m1} \cdot g_{m2})}{(\tau_{o1} + j\omega C_1)(\tau_{o2} + j\omega C_2)}$$

from the denominator the poles are

$$P_1 = \frac{1}{(\infty_1 \cdot C_1)}$$

$$P_2 = \frac{1}{(\infty_2 C_2)}$$

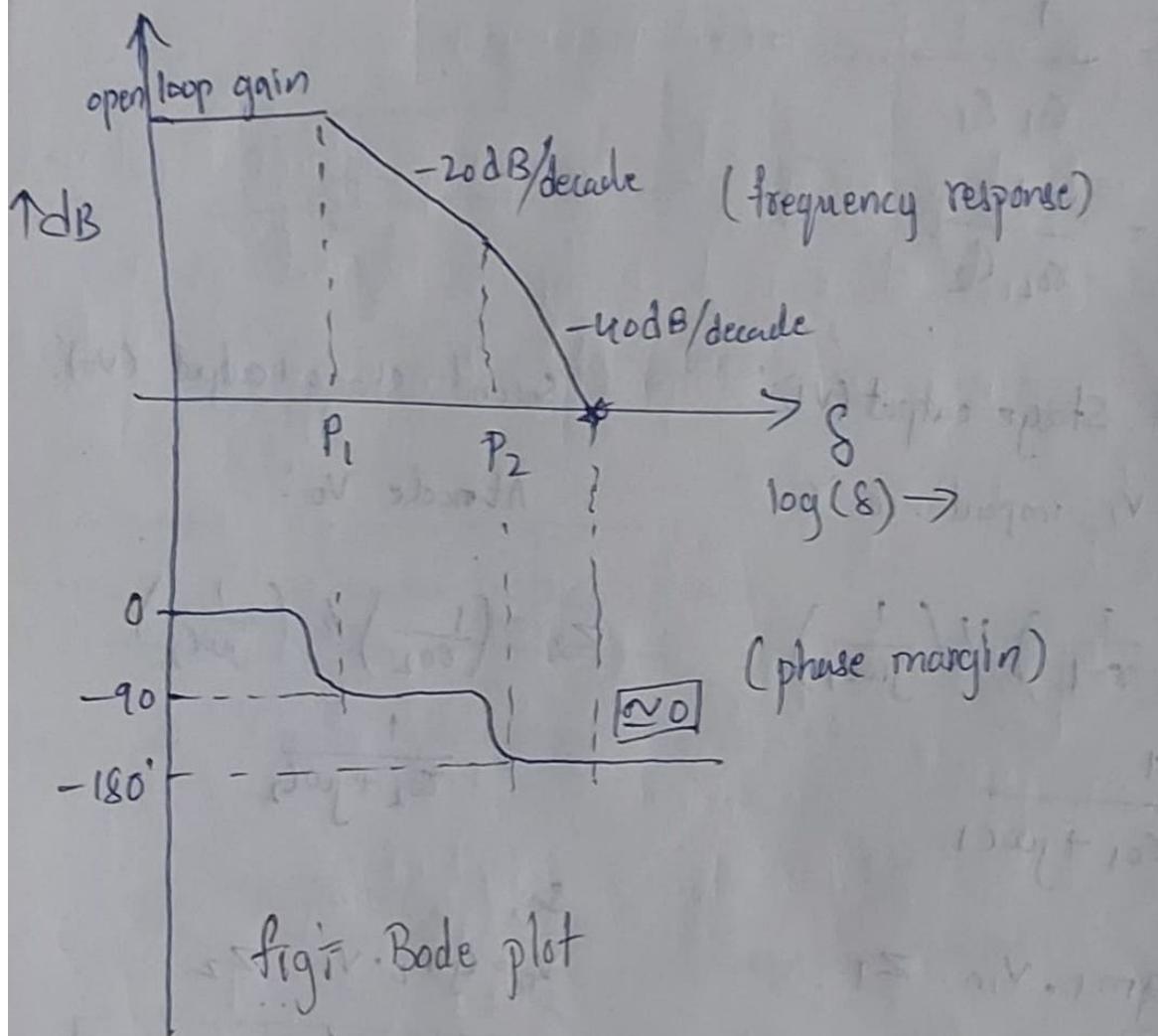


fig: Bode plot

\Rightarrow minimum phase margin required is 45°

\Rightarrow If it is 60° or more it is very good

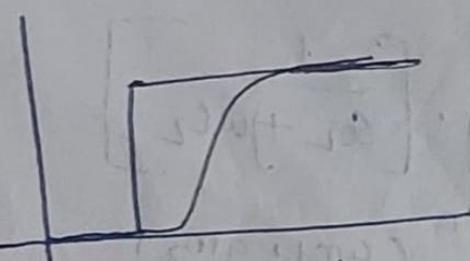


fig: for very good phase margin

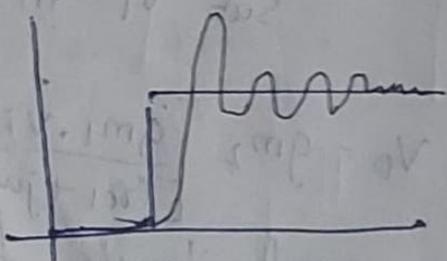
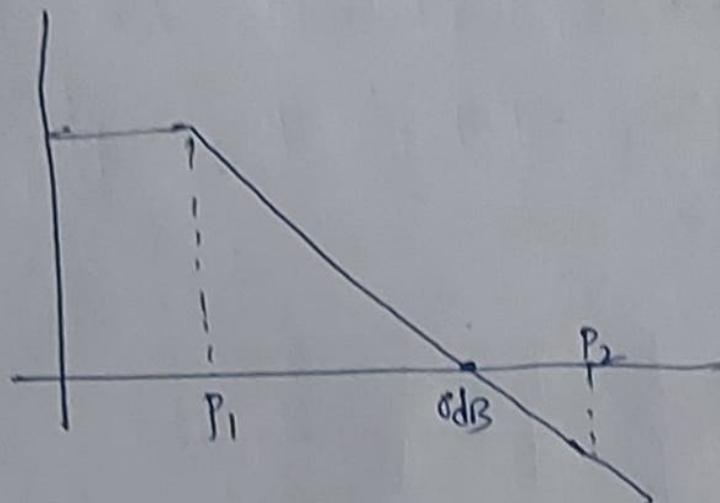


fig: for not good phase margin

⇒ Here P_1 considered as dominant pole in this the
Pole P_1 move backward



⇒ Something that comes after ω_{dB} will not have any
effect so ignore that thing

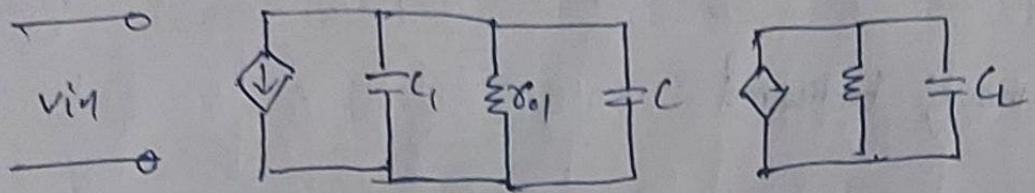
⇒ P_1 is the dominant pole

⇒ This processes is called compensation

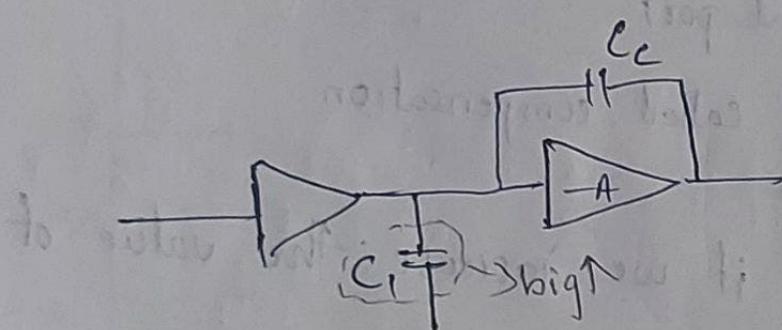
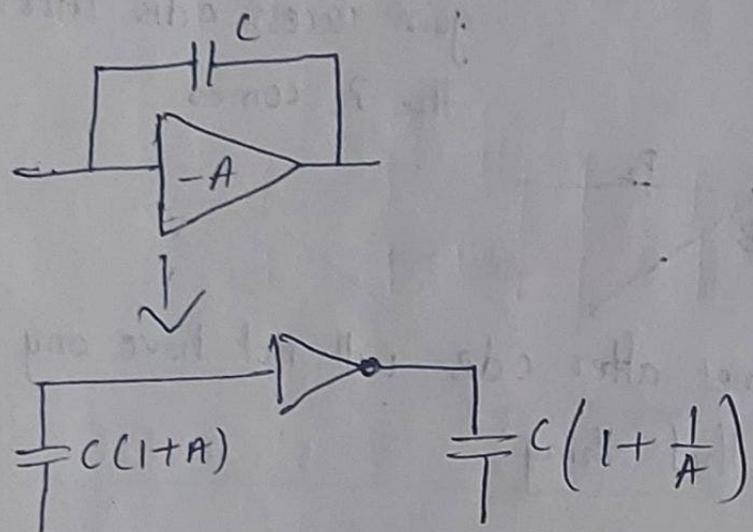
In $P_1 = \frac{1}{\omega_{01} C_1}$ if we increase the value of
 C_1 then we can move the Pole P_1 towards
left

The P_1 becomes $P_1 = \frac{1}{\omega_{01} C_1}$
 $= \frac{1}{\omega_{01} (C_1 + C)}$ → big value

⇒ here the C is what we added the value
to move pole towards left.

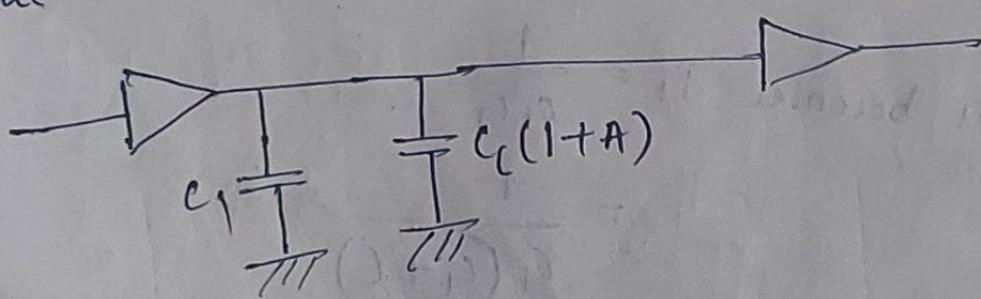


Miller effect



We use miller effect to get higher capacitance

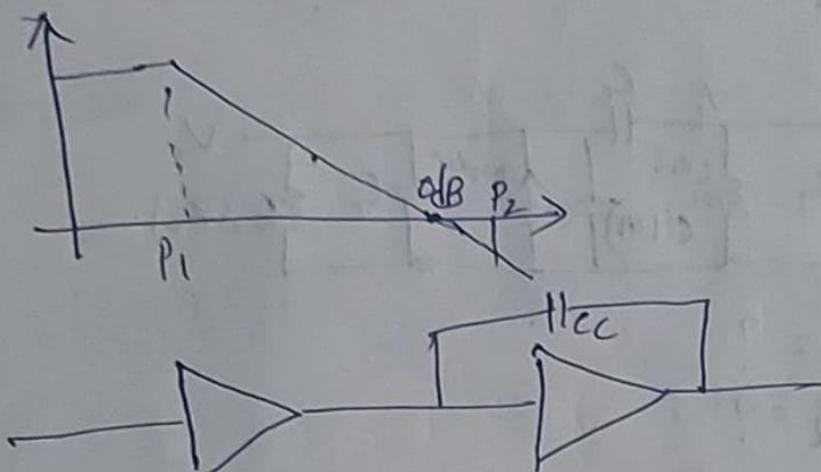
Value



$$Q_1 = \frac{1}{R_1 [C_C + C_1(1+A)]}$$

⇒ After the miller effect is introduced the C_1 value will be high this results the P_1 to move towards left this is known as compensation

⇒ The P_2 will be after 0dB avoid the P_1



$$P_1 = \frac{1}{R_{O1} [C_1 + C_C (1+A)]}$$

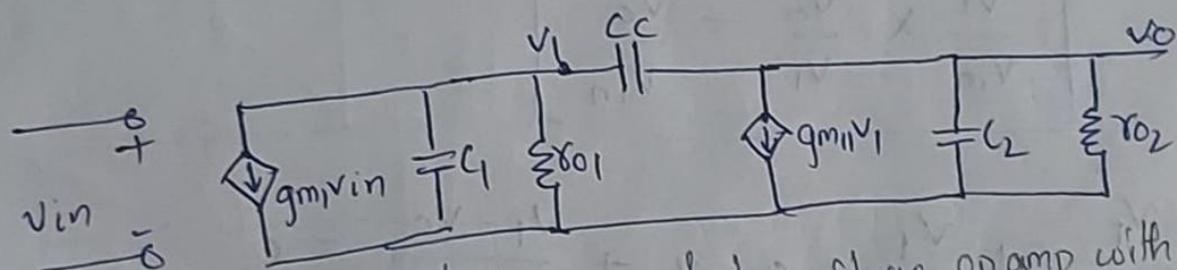
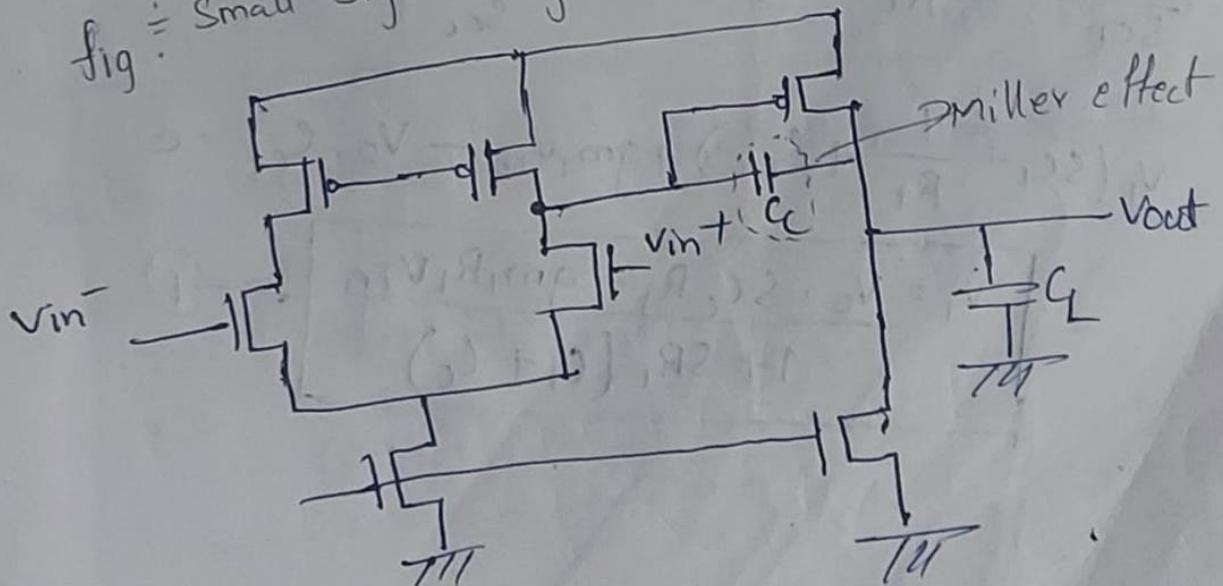


fig. = Small signal diagram of two stage opamp with cc

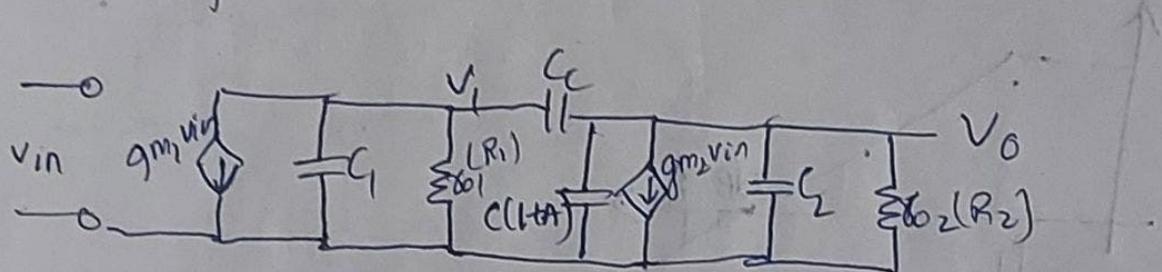


Before we go to exact design we should know the few parameters that are:

→ phase margin (Poles, zeroes, GBW etc--)

→ slew rate

→ swing limits



$$P_1 = ?$$

$$P_2 = ?$$

$$GBW = ?$$

$$P.m = ?$$

$$\left[\frac{V_1}{V_{in}} \times \frac{V_o}{V_1} = \frac{V_o}{V_{in}} \right]$$

$$\frac{V_1}{\frac{1}{SC_1}} + \frac{V_1}{R_1} + g_{m1}V_{in} + \frac{V_1 - V_o}{\frac{1}{SC_C}} = 0$$

$$V_1 \left(SC_1 + \frac{1}{R_1} + SC_C \right) + g_{m1}V_{in} - V_o \cdot SC_C = 0$$

$$\boxed{V_1 = \frac{V_o \cdot SC_C R_1 - g_{m1} R_1 V_{in}}{1 + SR_1 (C_1 + C_C)}} \quad ①$$

$$\frac{V_o}{\frac{1}{SC_2}} + \frac{V_o}{R_2} + g_{m_2} V_1 + \frac{V_o - V_1}{SC_1} = 0$$

$$V_o \left[S(C_2 + C_C) + \frac{1}{R_2} \right] = V_1 (S C_C - g_{m_2}) \quad \text{--- (2)}$$

Substitute eq (1) in eq (2)

$$V_o \left[S(C_2 + C_C) + \frac{1}{R_2} \right] = \frac{(V_o \cdot SC_C R_1 - g_{m_1} R_1 V_{in})(S C_C - g_{m_2})}{1 + S(C_1 + C_C) R_1}$$

$$V_o \left[S(C_2 + C_C) R_2 + 1 \right] [1 + S(C_1 + C_C) R_1] = (V_o \cdot SC_C R_1 - g_{m_1} R_1 V_{in})(S C_C - g_{m_2})$$

$$\boxed{\frac{V_o}{V_{in}} = \frac{g_{m_1} R_1 g_{m_2} R_2 \left(1 - \frac{S C_C}{g_{m_2}}\right)}{S^2 \left[R_1 R_2 (C_1 C_2 + C_1 C_C + C_2 C_C) + S \left[R_2 (C_C + C_2) + R_1 (C_C + C_1) + C_C g_{m_2} R_1 R_2 \right] + 1 \right]}}$$

For two pole system the standard transfer function

$$\boxed{\frac{V_o}{V_{in}} = \frac{A_{DC} \left(1 - \frac{S}{2}\right)}{\left(1 + \frac{S}{P_1}\right) \left(1 + \frac{S}{P_2}\right)}}$$

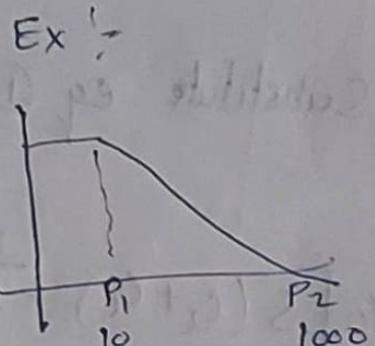
After expanding denominator it becomes

$$= \frac{Apc \left(1 - \frac{s}{2} \right)}{1 + s \left(\frac{1}{P_1} + \frac{1}{P_2} \right) + s^2 \left(\frac{1}{P_1 P_2} \right)}$$

$$s \left(\frac{1}{P_1} + \frac{1}{P_2} \right) \approx s \frac{1}{P_1}$$

$$\text{Coefficient of } (s) \Rightarrow \frac{1}{P_1}$$

$$\text{Coefficient of } (s^2) \Rightarrow \frac{1}{P_1 \cdot P_2}$$



$$\frac{1}{P_1} + \frac{1}{P_2} \approx \frac{1}{P_1}$$

$$P_1 = \frac{1}{R_2(C_c + C_2) + R_1(C_c + C_1) + g m_2 R_1 R_2 C_c}$$

small \therefore neglected

$0.1 + 0.001$
neglect this

$$P_1 \approx \frac{1}{g m_2 R_1 R_2 C_c}$$

$$P_1 P_2 = \frac{1}{R_1 R_2 (C_1 C_2 + C_1 C_c + C_2 C_c)}$$

$$P_2 = \frac{1}{R_1 R_2 [C_1 C_2 + C_1 C_c + C_2 C_c]} \frac{g m_2 R_2 R_1 C_c}{}$$

$$P_2 = \frac{g m_2 C_c}{C_1 C_2 + C_1 C_c + C_2 C_c} \approx \frac{g m_2 C_c}{C_2 C_c}$$

neglected

$$P_2 \simeq \frac{g m_2}{C_C}$$

what comes in denominator of 'S' term is zero

$$Z = \frac{g m_2}{C_C}$$

$\therefore Z \Rightarrow \text{zero}$

$P_1 \Rightarrow \text{Pole 1}$

$P_2 \Rightarrow \text{Pole 2}$

In A_{DC} all the S are '0'

so we get

$$A_{DC} = g m_1 R_1 g m_2 R_2$$

$$GBW = DC\text{gain} \times P_1$$

$$= \frac{g m_1 R_1 g m_2 R_2 \times 1}{g m_2 R_1 R_2 C_C}$$

$$GBW = \frac{g m_1}{C_C}$$

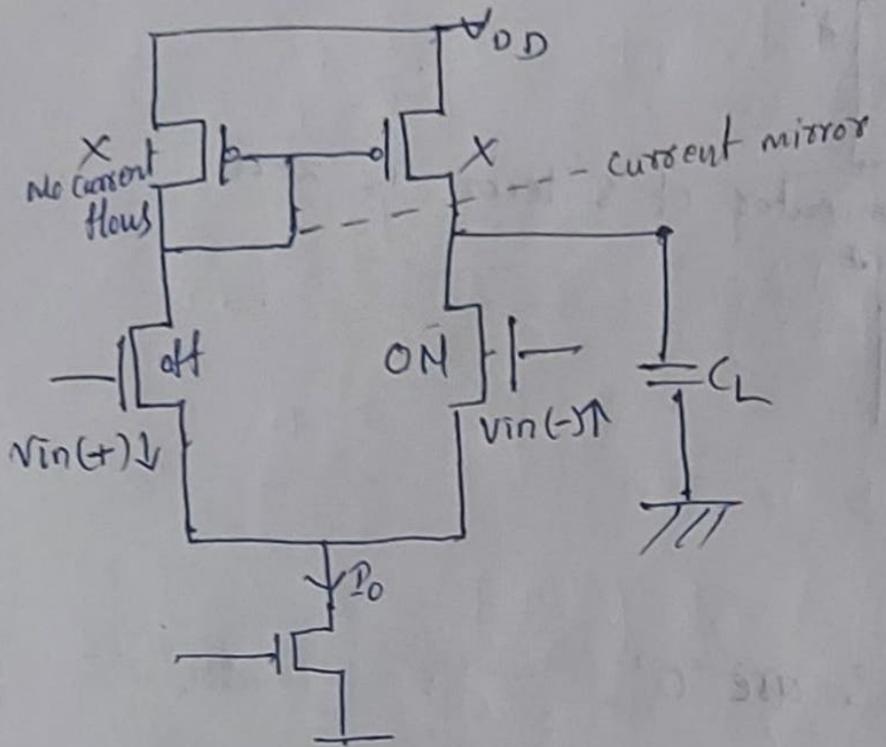
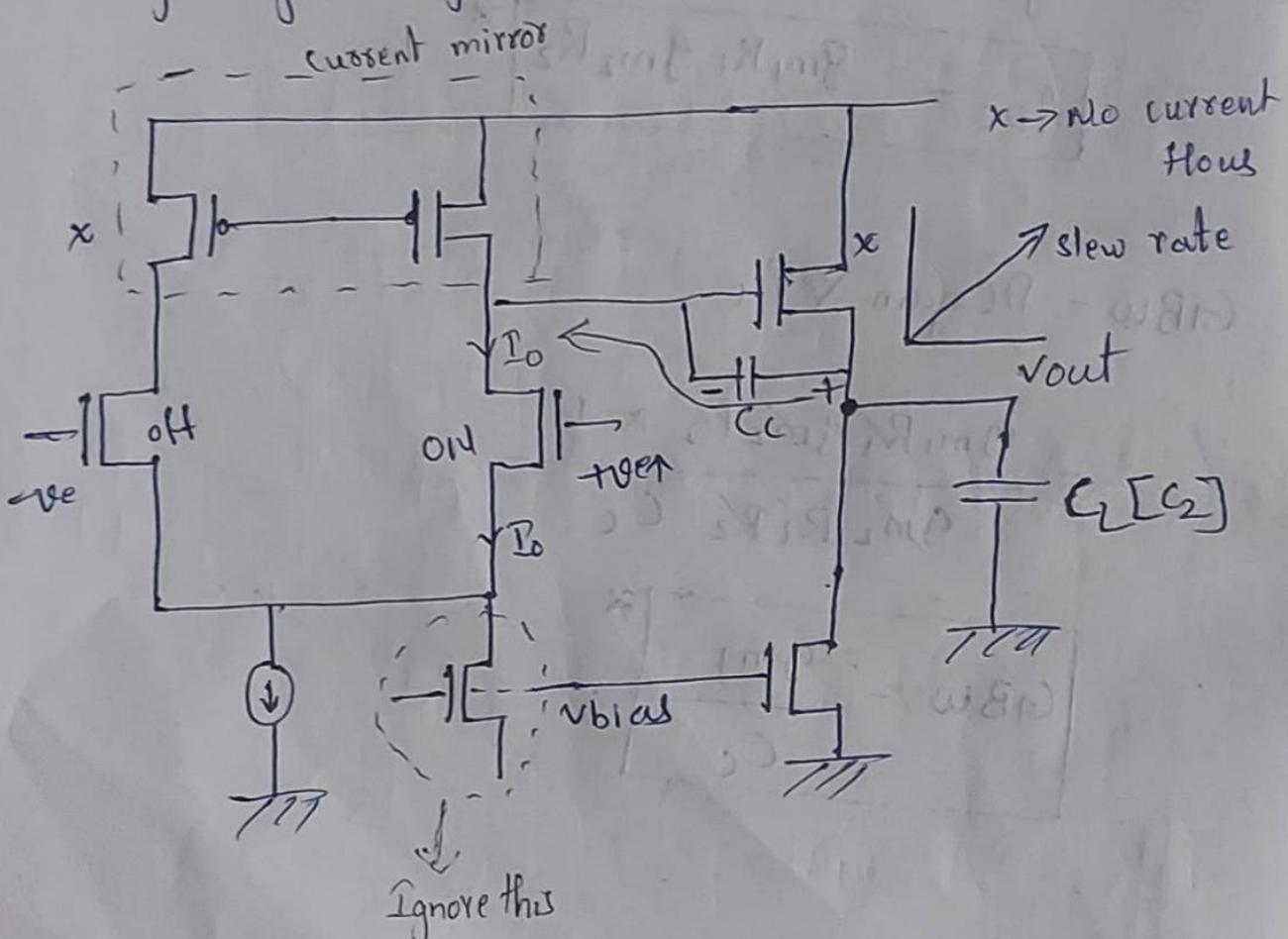
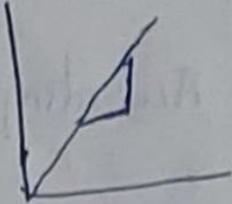


Fig: Single Stage op-amp

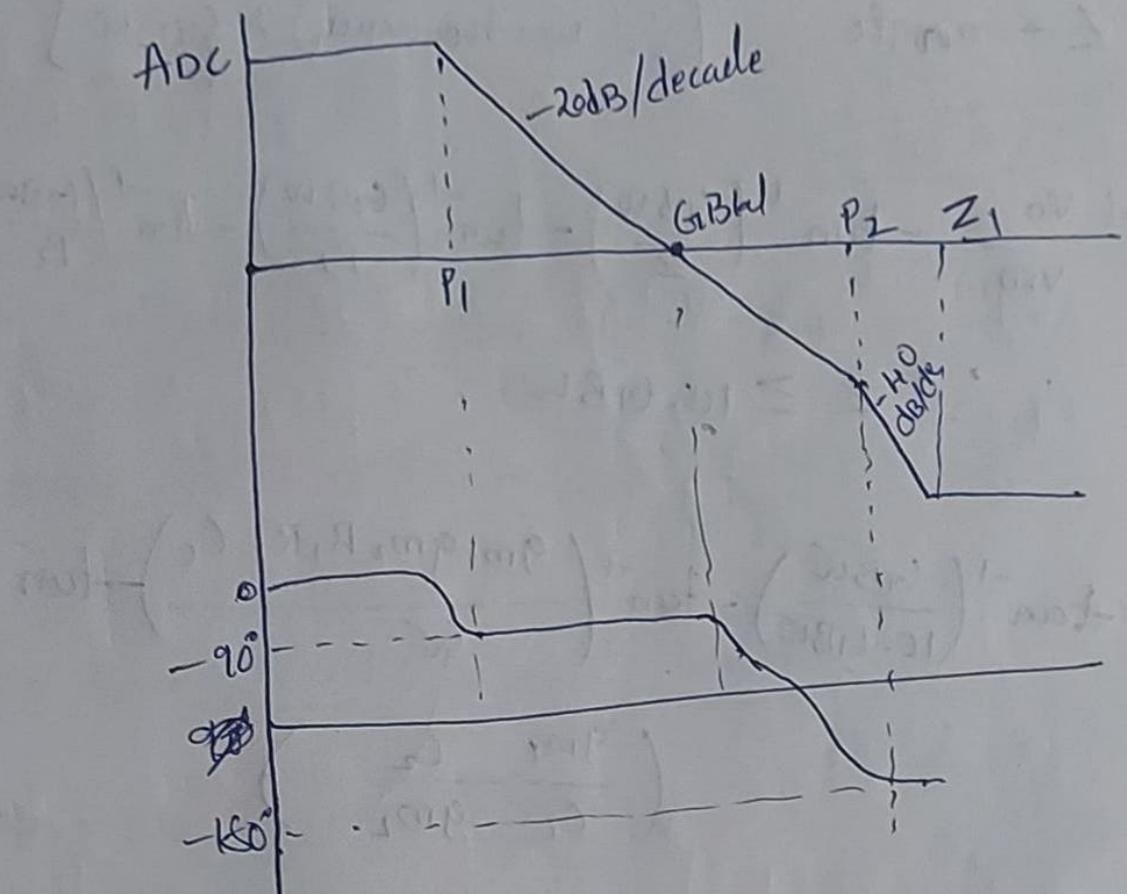


$C_C \rightarrow$ controls the current

$$S_R = \frac{T_o}{C_C}$$



Phase Margin



⇒ We should ensure that the phase margin should be 45° or more

⇒ To increase phase margin we move P2 towards right side

$$|Z| \geq 10, GIBW \quad ①$$

According to the standard transfer function

$$\angle \frac{V_o}{V_{in}} = -\tan^{-1}\left(\frac{\omega}{z}\right) - \tan^{-1}\left(\frac{\omega}{P_1}\right) - \tan^{-1}\left(\frac{\omega}{P_2}\right)$$

$\angle \rightarrow$ angle $[\because \omega \text{ (frequency)} = G_B \omega]$

$$\angle \frac{V_o}{V_{in}} = -\tan^{-1}\left(\frac{G_B \omega}{z}\right) - \tan^{-1}\left(\frac{G_B \omega}{P_1}\right) - \tan^{-1}\left(\frac{G_B \omega}{P_2}\right)$$

$$\therefore z \geq 10 \cdot G_B \omega$$

$$= \tan^{-1}\left(\frac{G_B \omega}{10 \cdot G_B \omega}\right) - \tan^{-1}\left(\frac{g_m_1 g_m_2 R_1 R_2 C_C}{C_C}\right) - \tan^{-1}$$

$$\left(\frac{g_m_1}{C_C} \frac{C_2}{g_m_2} \right)$$

$$= -\tan^{-1}\left(\frac{1}{10}\right) - \tan^{-1}(g_m_1 g_m_2 R_1 R_2) - \tan^{-1}\left(\frac{g_m_1 C_2}{C_C g_m_2}\right)$$

$$\angle \frac{V_o}{V_{in}} = -\tan^{-1}\left(\frac{1}{10}\right) - \tan^{-1}(A_{DC}) - \tan^{-1}\left(\frac{G_B \omega}{P_2}\right)$$

$$[\because A_{DC} = g_m_1 g_m_2 R_1 R_2]$$

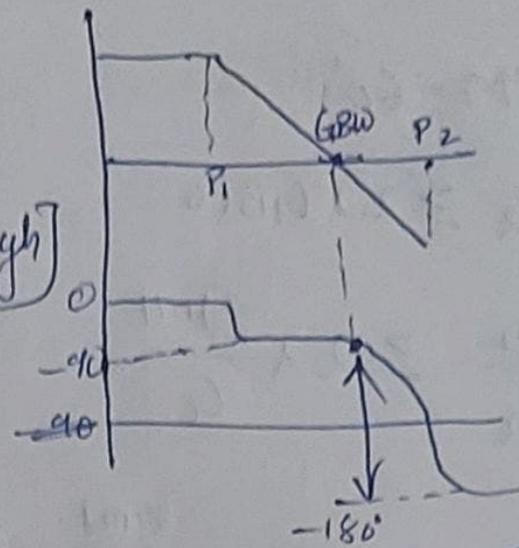
$$\angle \frac{V_o}{V_{in}} = -\tan^{-1}\left(\frac{1}{10}\right) - \tan^{-1}(A_{DC}) - \tan^{-1}\left(\frac{G_B \omega}{P_2}\right)$$

$$-180 + PM = -5.71 - 90^\circ$$

Assume

$$-\tan^{-1}(10000) \quad [\because ADC \text{ is high}]$$

$$\approx 90^\circ$$



$$-180^\circ + PM$$

$$\angle \frac{V_o}{V_{in}} = -\tan^{-1}\left(\frac{1}{10}\right) - \tan^{-1}(ADC) - \tan^{-1}\left(\frac{GBW}{P_2}\right)$$

$$-180^\circ + PM = -5.71 - 90^\circ - \tan^{-1}\left(\frac{GBW}{P_2}\right)$$

$$PM = 180 - 5.71 - 90^\circ - \tan^{-1}\left(\frac{GBW}{P_2}\right)$$

$$PM = 84.29 - \tan^{-1}\left(\frac{GBW}{P_2}\right)$$

$$\text{For } PM = 60^\circ$$

$$60 = 84.29 - \tan^{-1}\left(\frac{GBW}{P_2}\right)$$

Apply tan on b.s

~~$$\tan^{-1}\left(\frac{GBW}{P_2}\right) = \tan(24.29)$$~~

$$\frac{GBW}{P_2} = 0.4513$$

$$P_2 = \frac{GBW}{0.4513}$$

$$P_2 = 2.2 GBW$$

$$P_2 \geq 2.2 GBW$$

$$\text{For } PM = 45^\circ$$

$$45^\circ = 84.29 - \tan^{-1}\left(\frac{GBW}{P_2}\right)$$

$$\tan^{-1}\left(\frac{GBW}{P_2}\right) = 39.29$$

Apply tan on b.s

$$\frac{GBW}{P_2} = 0.8181$$

$$P_2 = \frac{GBW}{0.8181}$$

$$P_2 \geq 1.22 GBW$$

$$P1\eta = 60$$

$$P_2 \geq 2.2 \text{ GBW}$$

$$\frac{g m_2}{c_L} \geq 2.2 \times \frac{g m_1}{c_C}$$

$$\frac{g m_2}{c_L} \geq 2.2 \times \frac{g m_1}{c_C}$$

$$\frac{10 \cdot g m_1}{c_L} \geq 2.2 \times \frac{g m_1}{c_C}$$

$$\frac{10}{c_L} \geq \frac{2.2}{c_C}$$

$$c_L \geq \frac{2.2}{10} c_C$$

$$c_C \geq 0.22 c_L$$

$$\left[\because z = \frac{g m_2}{c_C} \right]$$

$$\left[\because P_2 = \frac{g m_2}{c_L} \right]$$

$$\left[\therefore \text{GBW} = \frac{g m_1}{c_C} \right]$$

Assumed
 $z = 10 \cdot \text{GBW}$

$$\frac{g m_2}{c_C} = 10 \cdot \frac{g m_1}{c_C}$$

$$\boxed{g m_2 = 10 \cdot g m_1}$$