CSC591/791: Spatial and Temporal Data Mining

Homework 2.

Released on: 02/03, Due on: 02/17, 11:45 pm

Student Names (including all group members): Student IDs(including all group members):

## Notes:

• Most questions are open-ended, so please craft an answer based on your reading/understanding.

- Some questions require reading papers and web resources. Likewise, you can discuss with fellow students. Whatever the case, answers should always be your own
- You should always **cite** the source of all materials if they are used in your answer/solution/program. You may even cite urls.
- Answers should be precise and concise.
- PDF is the only accepted format. Embed all images/tables/graphs into your single pdf.
- Use Moodle for discussion in a way that does not violate academic integrity policies.

- **Q1**. (30 points) For given satellite image (ilk-3b-1024.tif; 3-dimensional RGB, 1024x1024), do the following in RGB space:
  - (a) K-Means Clustering
  - (b) Model-based Clustering (GMM)
  - (c) Compare (a) and (b) on the following criteria:
    - a. Finding optimal clusters
    - b. Visualizing the clustered image (mark each cluster with different color) with the optimal number of clusters you have found
    - c. Quality of results in terms of visual agreement with thematic classes (e.g., buildings, roads, waters, grass, trees, ...)

## Hints:

- First, randomly sample (say 5% of) the image and use those samples to generate a model
- Use the model to predict cluster labels for all pixels in the image
- Change the color of pixels based on cluster assignment to visualize results
- You can use python/R and existing libraries
- You can read GeoTiff (and tons of other formats) images into R using "rgdal" and python using "gdal" libraries
- **Q2**. (30 points) For given spatial dataset (cancer-data.csv), which contains x and y coordinates (in kilometers) with spatial resolution of 100 meters, do spatial clustering (DBSCAN). Through visual exploration, choose appropriate parameters for DBSCAN clustering. Answer the following:
  - Report parameters
  - Generate plot for raw data
  - Generate plot for cluster results (mark each cluster with different color; mark noise points with separate color or symbol)

## Hints:

- You can use any freely available implementations, but DBSCAN clustering in R (in "fpc" package) may be the easiest one.
- **Q3**. (20 points) Compare and contrast C-DBSCAN algorithm [1] and DBCluC algorithm [2]. In addition to similarities and dissimilarities, comment on computational complexity, ease of implementation, ease of use. For each algorithm, list one spatial application that is best suited for the algorithm.
- **Q4.** (20 points) Take a neutral image of your choice (please nothing in poor taste such as political or religious) and perform edge detection by *convolving* (yes, the exact same way Convolutional Neural Nets work) the "Sobel" operator through the image. This is a part of a data scientist's process called feature engineering and these representations are often used as inputs to a subsequent learning task. Show us:
  - Original image
  - X-gradient image (vertical edge detection)
  - Y-gradient image (horizontal edge detection)

## References:

- [1] Carlos Ruiz, et al. C-DBSCAN: Density-Based Clustering with Constraints.
- [2] Osmar R. Zaiane, et al. Clustering Spatial Data in the Presence of Obstacles: a Density-Based Approach.