CERVO Delivery API V2

Register new order
For register new order in CERVO delivery system.

Action	POST	
URL	https://carvo.isoft4is.com/apis/v2/order	
Header	Authorization: Bearer WlhGWUtWT2Y2cTZhZ	
Body	<pre>"address": "address Of the customer", "lng": 34.266593, "lat":31.279708, "id": 2011, "order_id": "2011", "date": "2023-04-28 14:40", "customer": "Testing customer", "mobile": "+966599000111", "price": 1.2, "payment": "CASH", "ispaid": "PAID", "callback": "", "status": 1, "notes": "", "storelat": 31.277202, "storelng": 34.268996 }</pre>	
	 Id refer to the system id from your system side (Systematic, unique) order_id refer to visible id printer & driver can reference with store All data required expected to be left blank 	
Response (Success)	200 OK	
	99999The body content the id of cervo system id	
Response (Error)	400,500 { "Customer is required ," }	

Get order data

For return the details of order.

Action	GET		
URL	https://carvo.isoft4is.com/apis/v2/order		
Header	Authorization: Bearer WlhGWUtWT2Y2cTZhZ		
	id	25	
		Id refer to the system id from cervo system side (Systematic, unique)	
Response (Success)	200 OK		
, , ,	{		
	"DriverName": "Fo	t testing",	
	"DriverMobile": "599000111",		
	"Status": 6,		
	"OrderStatus": [
	{		
	"Status":		
	"Date": "	2023-04-29 10:44"	
	},		
	{		
	"Status":		
		2023-04-29 10:44"	
	}, { "Status": 6,		
		2023-04-29 10:44"	
	}		
],		
	"tracking": "http	S://"	
	}		
Response (Error)	400		

Cancel order

For cancel the order from store side

Action	GET	
URL	https://carvo.isoft4is.com/apis	s/v2/cancelorder
Header	Authorization: Bearer WlhGWUtWT2Y2cTZhZ	
	id	25

		Id refer to the system id from cervo system side (Systematic, unique)
Response (Success)	200 OK	
Response (Error)	400	

Status codes

Code	Notes
1	New
2	Accepted by driver
3	Order on hand
4	Completed
5	Canceled by driver
0	Canceled

Callback parameters

Params	Notes
order_id	Order id of your system
driver_name	Driver name
driver_mobile	Driver mobile
order_status	Order status
cancel	Reasons of cancelation
tracking	Url of driver tracking