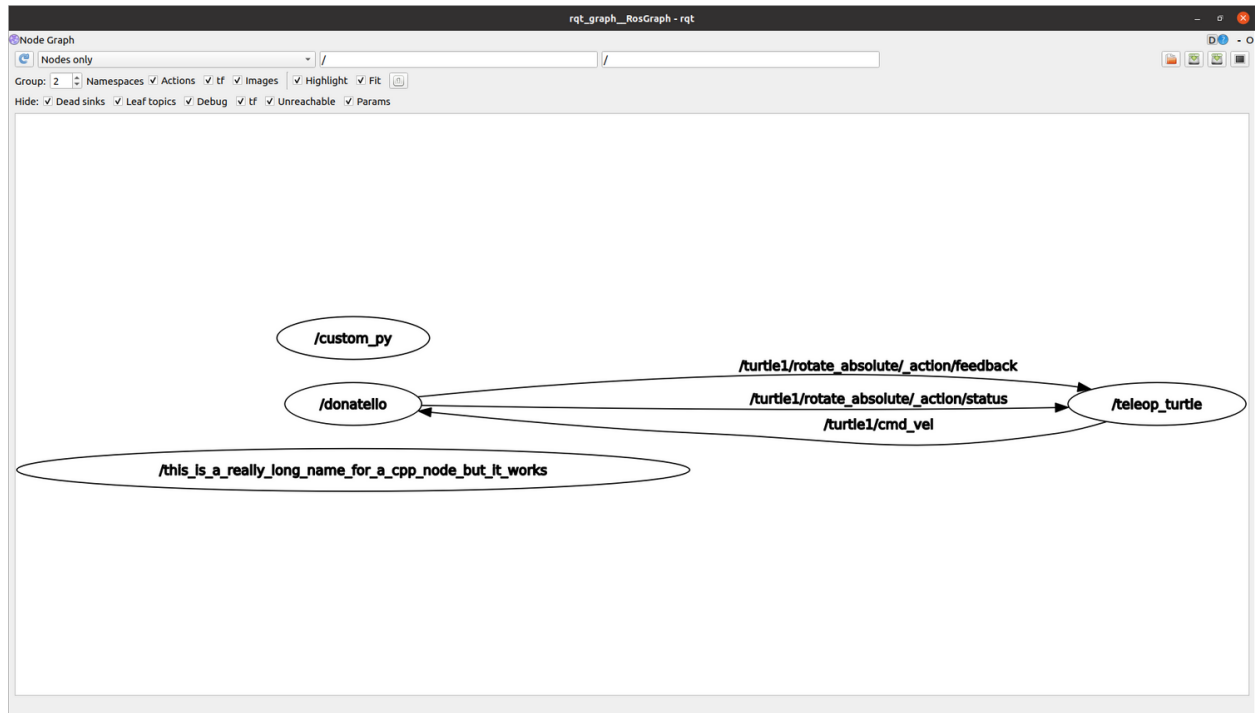


Activity 001 - ROS2 Nodes and Tools

Here's a quick challenge for you. I have run some nodes with different names, and here is what I see with `rqt_graph`.



Your goal here is to get the same.

For that you'll need to start 4 nodes, including those that you created before (the Python and the Cpp ones), and 2 nodes from the Turtlesim package.

No need to write any code here, you just have to start the nodes from your terminal, using the appropriate commands.