

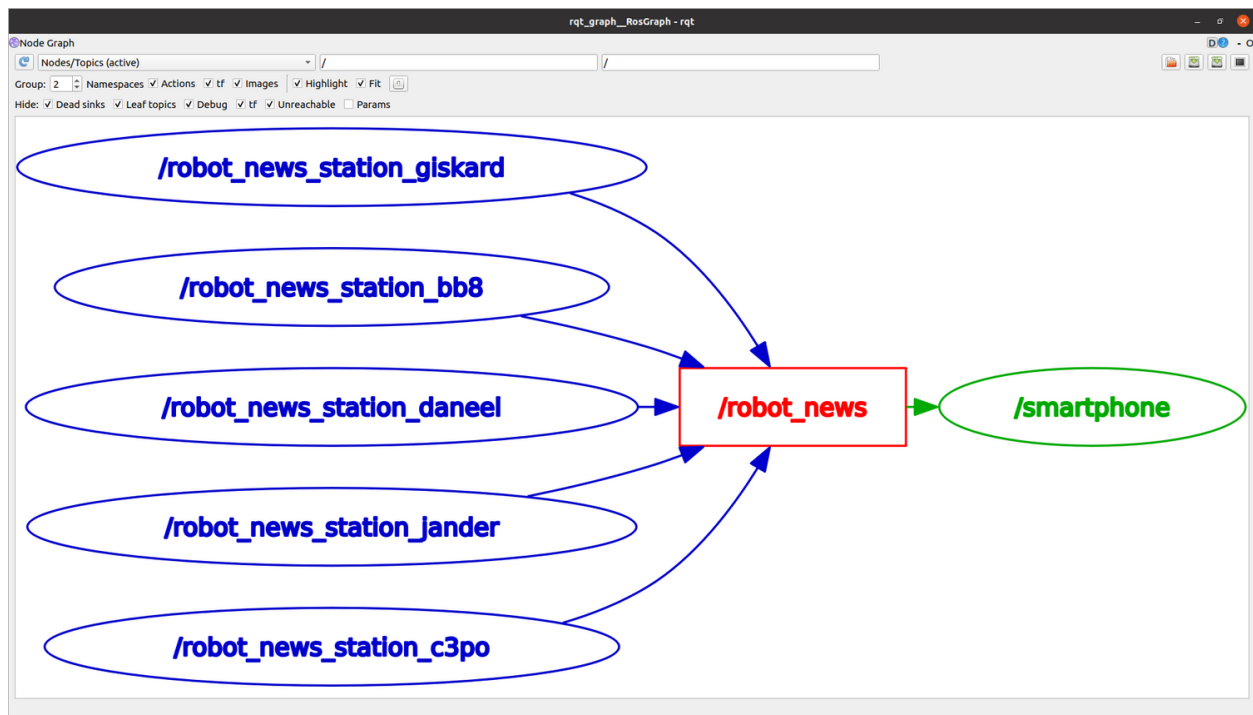
# Activity 006 - ROS2 Launch Files

In this activity you will practice by creating a new launch file, with the nodes that you've already created during this course.

Goal:

- Start 5 “robot\_news\_station” nodes and 1 smartphone node.
- Each “robot\_news\_station” will need a different name, and will publish "Hi, this is <robot\_name> from the Robot News Station!"
- The “smartphone” node gets all the messages from all other nodes.

Here's the graph you should get:



So, no need to create or modify any node here. You just need to create a single launch file to start your (renamed) nodes with parameters.

Bonus point if you find the book/movie reference for all robot names! (shouldn't be too hard)