

3-COMPLEXITY ANALYSIS OF ALGORITHMS



Topics

- Time and Space
- Size of input
- Characteristic Operations
- Exact values for time. Is it practical?
- Best, Average and Worst cases
- Constant time
- Linear time
- Example: Array Subset Problem
- Simplifying Formulae
- Big-O Notation

Time and space

- To **analyze** an algorithm means:
 - ▣ developing a formula for predicting *how fast* an algorithm is, based on the *size of the input* (**time complexity**), and/or
 - ▣ developing a formula for predicting *how much memory* an algorithm requires, based on the *size of the input* (**space complexity**)
- Usually **time** is our biggest concern
 - ▣ Most algorithms require a fixed amount of space

What does “size of the input” mean?

- If we are **searching** an array, the “**size**” of the input could be the **size of the array**
- If we are **merging two arrays**, the “**size**” could be the **sum of the two array sizes**
- If we are computing the **n^{th}** Fibonacci number, or the **n^{th}** factorial, the “size” is **n**
- We choose the “size” to be a parameter that determines the actual time (or space) required
 - ▣ It is *usually* obvious what this parameter is
 - ▣ Sometimes we need two or more parameters

Characteristic operations

- In computing time complexity, one good approach is to **count characteristic operations**
 - What a “**characteristic operation**” is depends on the particular problem
 - If searching, it might be comparing two values
 - If sorting an array, it might be:
 - comparing two values
 - swapping the contents of two array locations
 - both of the above
 - Sometimes we just look at how many times the *innermost loop* is executed

Exact values

- It is sometimes possible, *in assembly language*, to compute *exact* time and space requirements
 - ▣ We know exactly how many bytes and how many cycles each machine instruction takes
 - ▣ For a problem with a known sequence of steps (factorial, Fibonacci), we can determine how many instructions of each type are required
- However, often the exact sequence of steps cannot be known in advance
 - ▣ The steps required to sort an array depend on the actual numbers in the array (which we do not know in advance)

Higher-level languages

- In a higher-level language (such as Java), we *do not* know how long each operation takes
 - Which is faster, $x < 10$ or $x \leq 9$?
 - We don't know exactly what the compiler does with this
 - The compiler almost certainly optimizes the test anyway (replacing the slower version with the faster one)
- In a higher-level language we *cannot* do an exact analysis
 - Our timing analyses will use *major* oversimplifications
 - Nevertheless, we can get some very useful results

Average, best, and worst cases

- Usually we would like to find the *average* time to perform an algorithm
- However,
 - ▣ Sometimes the “average” isn’t well defined
 - Example: Sorting an “average” array
 - Time typically depends on how out of order the array is
 - How out of order is the “average” unsorted array?
 - ▣ Sometimes finding the average is too difficult
- Often we have to be satisfied with finding the *worst* (longest) time required
 - ▣ Sometimes this is even what we want (say, for time-critical operations)
- The *best* (fastest) case is seldom of interest

Constant time

- *Constant time* means there is some constant k such that this operation always takes k nanoseconds
- A Java statement takes constant time if:
 - ▣ It does not include a loop
 - ▣ It does not include calling a method whose time is unknown or is not a constant
- If a statement involves a choice (*if* or *switch*) among operations, each of which takes constant time, we consider the statement to take constant time
 - ▣ This is consistent with *worst-case analysis*

Linear time

- We may not be able to predict to the nanosecond how long a Java program will take, but do know *some* things about timing:

```
for (i = 0, j = 1; i < n; i++) {  
    j = j * i;  
}
```

- This loop takes time $k*n + c$, for some constants k and c

k : How long it takes to go through the loop once
(the time for $j = j * i$, plus loop overhead)

n : The number of times through the loop
(we can use this as the “size” of the problem)

c : The time it takes to initialize the loop

- The total time $k*n + c$ is *linear in* n

Constant time is (usually)

■ better than linear time ■

- Suppose we have two algorithms to solve a task:
 - Algorithm A takes 5000 time units
 - Algorithm B takes $100*n$ time units
- Which is better?
 - Clearly, algorithm B is better if our problem size is small, that is, if $n < 50$
 - Algorithm A is better for larger problems, with $n > 50$
 - So B is better on small problems that are quick anyway
 - But A is better for large problems, *where it matters more*
- We usually care most about very large problems
 - But not always!

The array subset problem

- Suppose you have two sets, represented as unsorted arrays:

```
int[] sub = { 7, 1, 3, 2, 5 };  
int[] super = { 8, 4, 7, 1, 2, 3, 9 };
```

and you want to test whether every element of the first set (**sub**) also occurs in the second set (**super**):

```
System.out.println(subset(sub, super));
```

- (The answer in this case should be **false**, because **sub** contains the integer **5**, and **super** doesn't)
- We are going to write method **subset** and compute its time complexity (how fast it is)
- Let's start with a helper function, **member**, to test whether one number is in an array

member

```
static boolean member(int x, int[] a) {  
    int n = a.length;  
    for (int i = 0; i < n; i++) {  
        if (x == a[i]) return true;  
    }  
    return false;  
}
```

- If x is *not* in a , the loop executes n times, where $n = a.length$
 - ▣ This is the *worst case*
- If x is in a , the loop executes $n/2$ times *on average*
- Either way, linear time is required: $k*n+c$

subset

- ```
static boolean subset(int[] sub, int[] super) {
 int m = sub.length;
 for (int i = 0; i < m; i++)
 if (!member(sub[i], super) return false;
 return true;
}
```
- The loop (and the call to **member**) will execute:
  - ▣ **m = sub.length** times, if **sub** is a subset of **super**
    - This is the worst case, and therefore the one we are most interested in
  - ▣ Fewer than **sub.length** times (but we don't know how many)
    - We would need to figure this out in order to compute *average* time complexity
- The worst case is a linear number of times through the loop
- But the loop body doesn't take constant time, since it calls **member**, which takes linear time

# Analysis of array subset algorithm

- We've seen that the loop in subset executes  $m = \text{sub.length}$  times (in the worst case)
- Also, the loop in subset calls `member`, which executes in time linear in  $n = \text{super.length}$
- Hence, the execution time of the array subset method is  $m * n$ , along with assorted constants
  - ▣ We go through the loop in `subset`  $m$  times, calling `member` each time
  - ▣ We go through the loop in `member`  $n$  times
  - ▣ If  $m$  and  $n$  are similar, this is roughly quadratic, i.e.,  $n^2$

# What about the constants?

- An added constant,  $f(n)+c$ , becomes less and less important as  $n$  gets larger
- A constant multiplier,  $k*f(n)$ , does *not* get less important, but...
  - ▣ Improving  $k$  gives a *linear* speedup (cutting  $k$  in half cuts the time required in half)
  - ▣ Improving  $k$  is usually accomplished by careful code optimization, not by better algorithms
  - ▣ We aren't that concerned with *only* linear speedups!
- Bottom line: ***Forget the constants!***



# Simplifying the formulae

- Throwing out the constants is one of *two* things we do in analysis of algorithms
  - ▣ By throwing out constants, we simplify  $12n^2 + 35$  to just  $n^2$
- Our timing formula is a polynomial, and may have terms of various orders (constant, linear, quadratic, cubic, etc.)
  - ▣ We usually discard all but the *highest-order* term
    - We simplify  $n^2 + 3n + 5$  to just  $n^2$

# Big O notation

- Big-O notation, does not give actual figures for running time, but it shows how the running time is affected by the number of items.
- When we have a polynomial that describes the time requirements of an algorithm, we simplify it by:
  - Throwing out all **but** the highest-order term
  - Throwing out all the constants
- If an algorithm takes  $12n^3+4n^2+8n+35$  time, we simplify this formula to just  $n^3$
- We say the algorithm requires  $O(n^3)$  time
  - We call this Big O notation
  - (More accurately, it's Big  $\Omega$ )

# Big O for subset algorithm

- Recall that, if  $n$  is the size of the set, and  $m$  is the size of the (possible) subset:
  - We go through the loop in  $\text{subset } m$  times, calling  $\text{member}$  each time
  - We go through the loop in  $\text{member } n$  times
- Hence, the actual running time should be  $k \cdot (m \cdot n) + c$ , for some constants  $k$  and  $c$
- We say that subset takes  $O(m \cdot n)$  time

# Can we justify Big O notation?

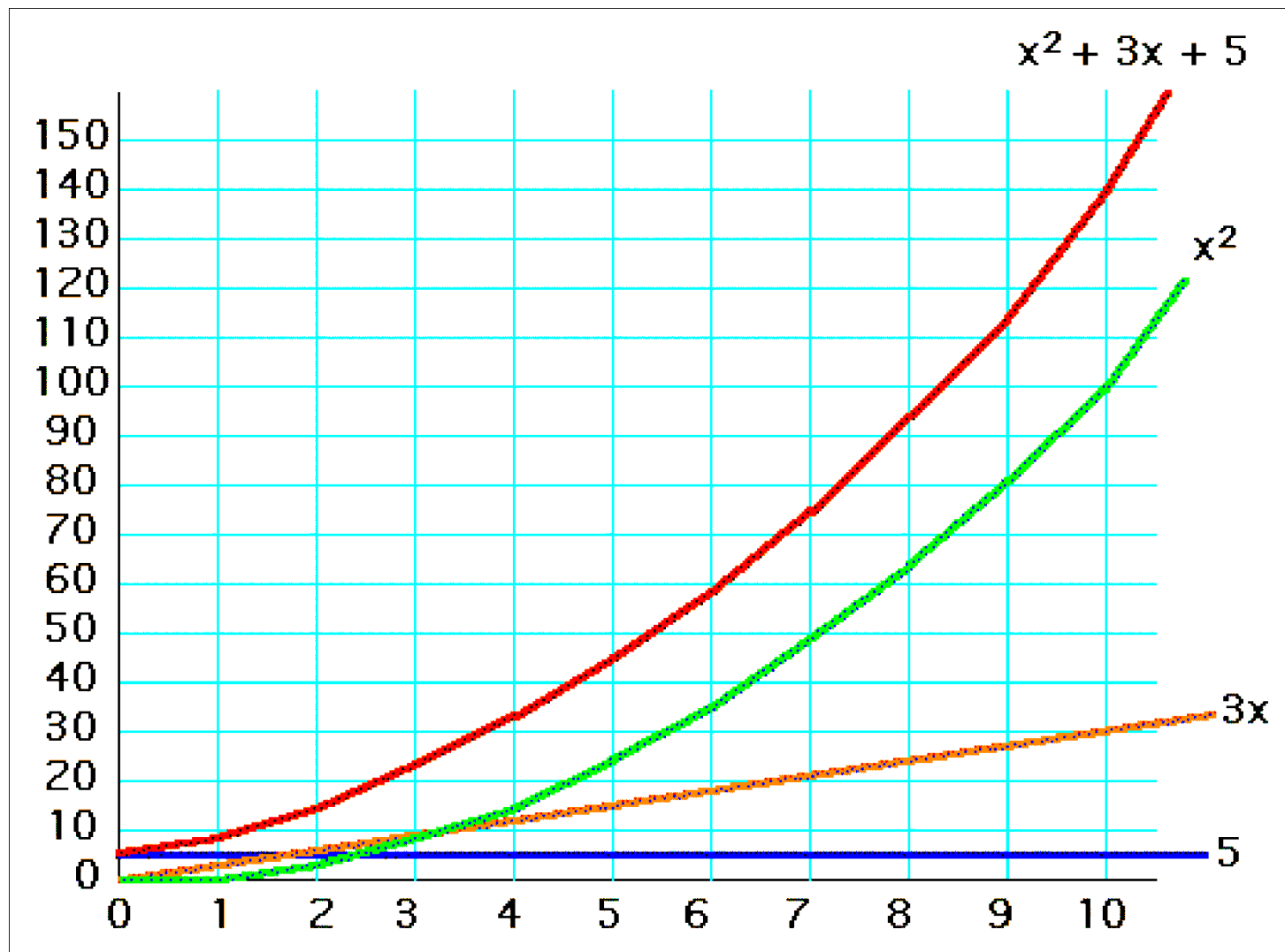
- Big O notation is a *huge* simplification; can we justify it?

- It only makes sense for *large* problem sizes
- **For sufficiently large problem sizes, the highest-order term swamps all the rest!**

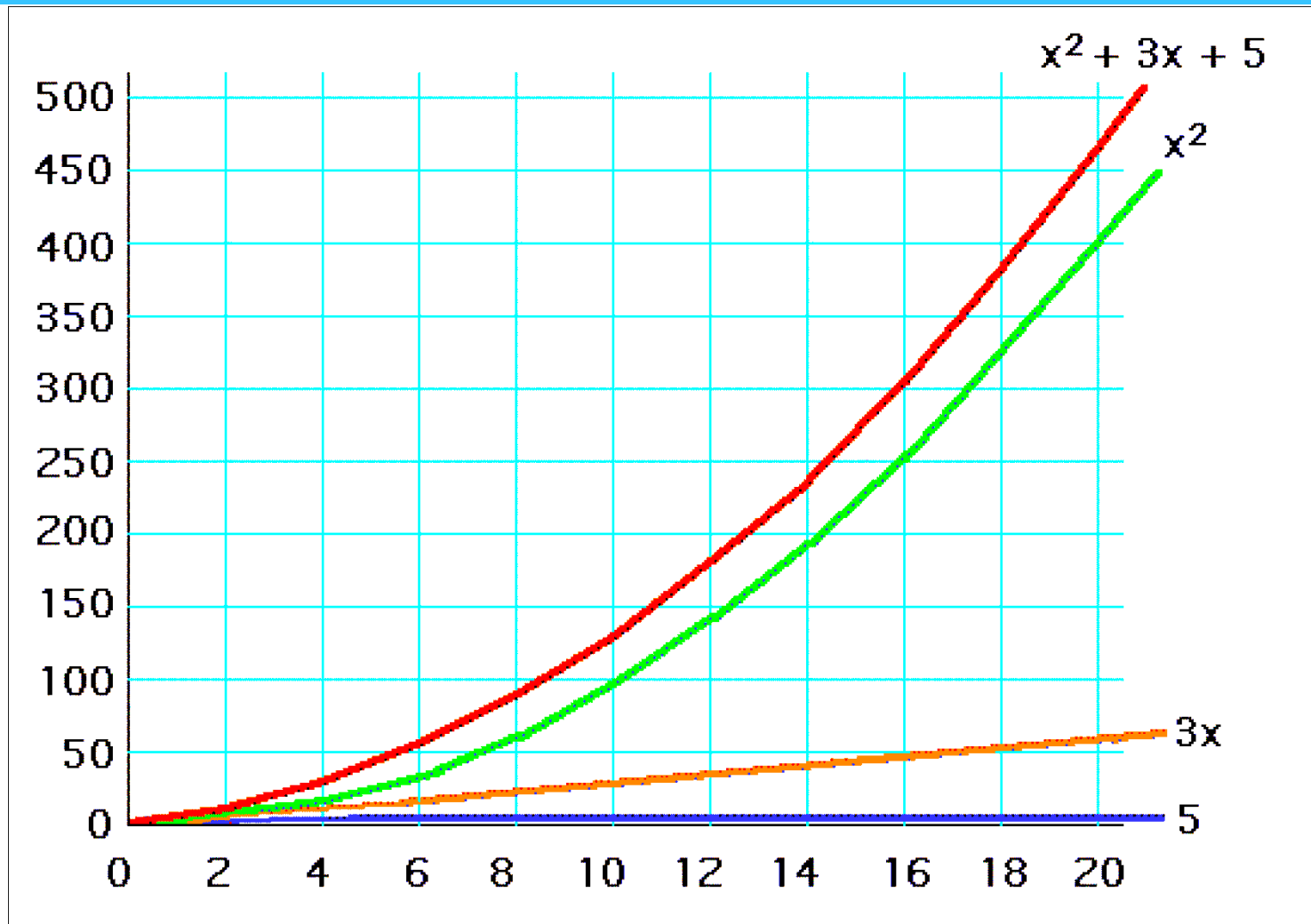
- Consider  $R = x^2 + 3x + 5$  as  $x$  varies:

|               |                 |                     |         |                      |
|---------------|-----------------|---------------------|---------|----------------------|
| $x = 0$       | $x^2 = 0$       | $3x = 0$            | $5 = 5$ | $R = 5$              |
| $x = 10$      | $x^2 = 100$     | $3x = 30$           | $5 = 5$ | $R = 135$            |
| $x = 100$     | $x^2 = 10000$   | $3x = 300$          | $5 = 5$ | $R = 10,305$         |
| $x = 1000$    | $x^2 = 1000000$ | $3x = 3000$         | $5 = 5$ | $R = 1,003,005$      |
| $x = 10,000$  | $x^2 = 10^8$    | $3x = 3 \cdot 10^4$ | $5 = 5$ | $R = 100,030,005$    |
| $x = 100,000$ | $x^2 = 10^{10}$ | $3x = 3 \cdot 10^5$ | $5 = 5$ | $R = 10,000,300,005$ |

$$y = x^2 + 3x + 5, \text{ for } x=1..10$$



$$y = x^2 + 3x + 5, \text{ for } x=1..20$$



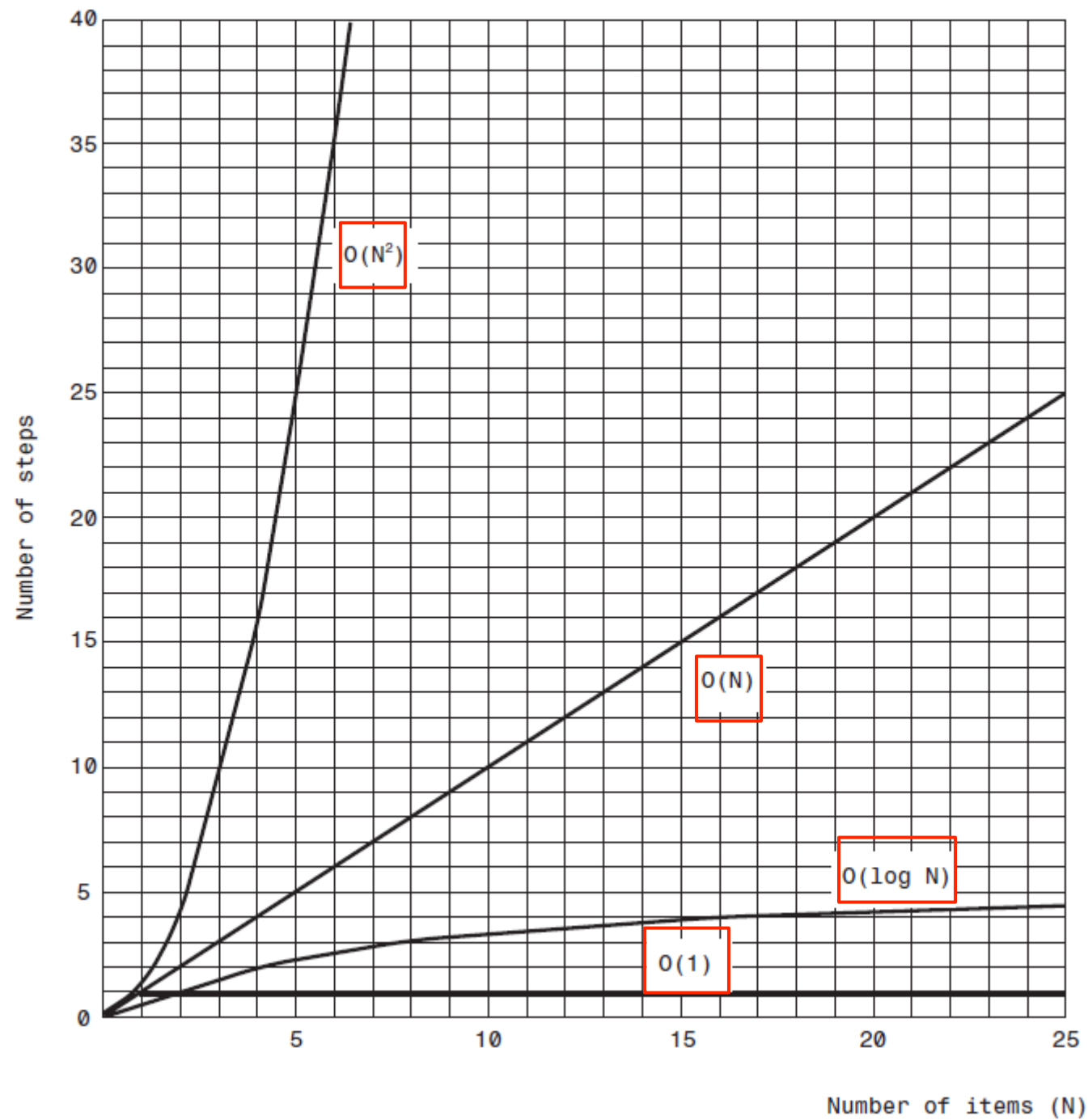
# Common time complexities

**BETTER**



**WORSE**

- |                                        |                  |
|----------------------------------------|------------------|
| <input type="checkbox"/> $O(1)$        | constant time    |
| <input type="checkbox"/> $O(\log n)$   | log time         |
| <input type="checkbox"/> $O(n)$        | linear time      |
| <input type="checkbox"/> $O(n \log n)$ | log linear time  |
| <input type="checkbox"/> $O(n^2)$      | quadratic time   |
| <input type="checkbox"/> $O(n^3)$      | cubic time       |
| <input type="checkbox"/> $O(2^n)$      | exponential time |





# Running times in Big-O notation

Linear Search ?

Binary Search ?

Insertion in unordered array ?

Insertion in ordered array ?

Deletion in unordered array ?

Deletion in ordered array ?

**TABLE 2.5** Running Times in Big O Notation

| Algorithm                    | Running Time in Big O Notation |
|------------------------------|--------------------------------|
| Linear search                | $O(N)$                         |
| Binary search                | $O(\log N)$                    |
| Insertion in unordered array | $O(1)$                         |
| Insertion in ordered array   | $O(N)$                         |
| Deletion in unordered array  | $O(N)$                         |
| Deletion in ordered array    | $O(N)$                         |

# The End

