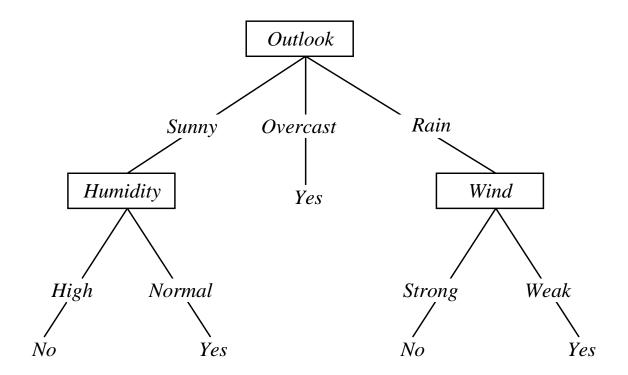
# Decision Tree for PlayTennis



### **Decision Trees**

#### Decision tree representation:

- Each internal node tests an attribute
- Each branch corresponds to attribute value
- Each leaf node assigns a classification

### How would we represent:

- $\bullet \land, \lor, XOR$
- $\bullet \ (A \land B) \lor (C \land \neg D \land E)$
- $\bullet M \text{ of } N$

### When to Consider Decision Trees

- Instances describable by attribute-value pairs
- Target function is discrete valued
- Disjunctive hypothesis may be required
- Possibly noisy training data

#### Examples:

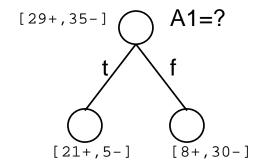
- Equipment or medical diagnosis
- Credit risk analysis
- Modeling calendar scheduling preferences

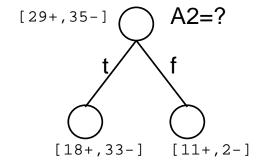
### Top-Down Induction of Decision Trees

#### Main loop:

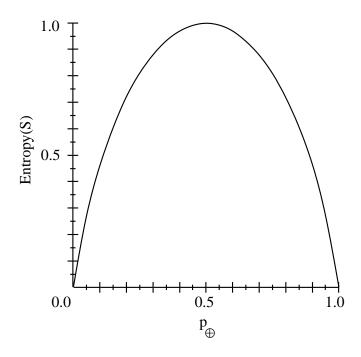
- 1.  $A \leftarrow$  the "best" decision attribute for next node
- 2. Assign A as decision attribute for node
- 3. For each value of A, create new descendant of node
- 4. Sort training examples to leaf nodes
- 5. If training examples perfectly classified, Then STOP, Else iterate over new leaf nodes

#### Which attribute is best?





### Entropy



- $\bullet$  S is a sample of training examples
- $p_{\oplus}$  is the proportion of positive examples in S
- $p_{\ominus}$  is the proportion of negative examples in S
- $\bullet$  Entropy measures the impurity of S

$$Entropy(S) \equiv -p_{\oplus} \log_2 p_{\oplus} - p_{\ominus} \log_2 p_{\ominus}$$

### Entropy

Entropy(S) =expected number of bits needed to encode class  $(\oplus \text{ or } \ominus)$  of randomly drawn member of S (under the optimal, shortest-length code)

### Why?

Information theory: optimal length code assigns  $-\log_2 p$  bits to message having probability p.

So, expected number of bits to encode  $\oplus$  or  $\ominus$  of random member of S:

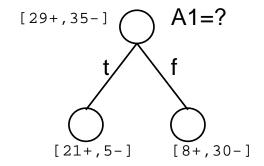
$$p_{\oplus}(-\log_2 p_{\oplus}) + p_{\ominus}(-\log_2 p_{\ominus})$$

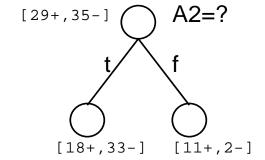
$$Entropy(S) \equiv -p_{\oplus} \log_2 p_{\oplus} - p_{\ominus} \log_2 p_{\ominus}$$

### **Information Gain**

Gain(S, A) =expected reduction in entropy due to sorting on A

$$Gain(S, A) \equiv Entropy(S) - \sum_{v \in Values(A)} \frac{|S_v|}{|S|} Entropy(S_v)$$



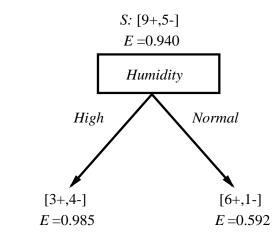


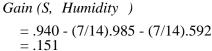
# Training Examples

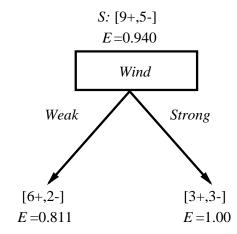
Day	Outlook	Temperature	Humidity	Wind	PlayTennis
D1	Sunny	$\operatorname{Hot}$	High	Weak	No
D2	Sunny	$\operatorname{Hot}$	$\operatorname{High}$	Strong	No
D3	Overcast	$\operatorname{Hot}$	$\operatorname{High}$	Weak	Yes
D4	Rain	Mild	$\operatorname{High}$	Weak	Yes
D5	Rain	Cool	Normal	Weak	Yes
D6	Rain	Cool	Normal	Strong	No
D7	Overcast	Cool	Normal	Strong	Yes
D8	Sunny	Mild	$\operatorname{High}$	Weak	No
D9	Sunny	Cool	Normal	Weak	Yes
D10	Rain	Mild	Normal	Weak	Yes
D11	Sunny	Mild	Normal	Strong	Yes
D12	Overcast	Mild	$\operatorname{High}$	Strong	Yes
D13	Overcast	$\operatorname{Hot}$	Normal	Weak	Yes
D14	Rain	Mild	High	Strong	No

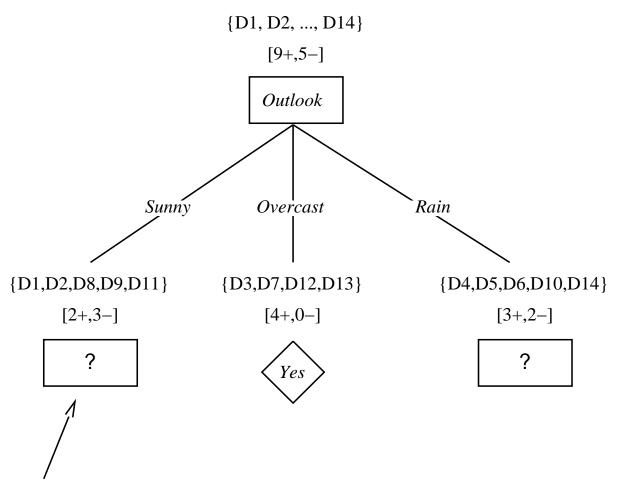
# Selecting the Next Attribute

#### Which attribute is the best classifier?









Which attribute should be tested here?

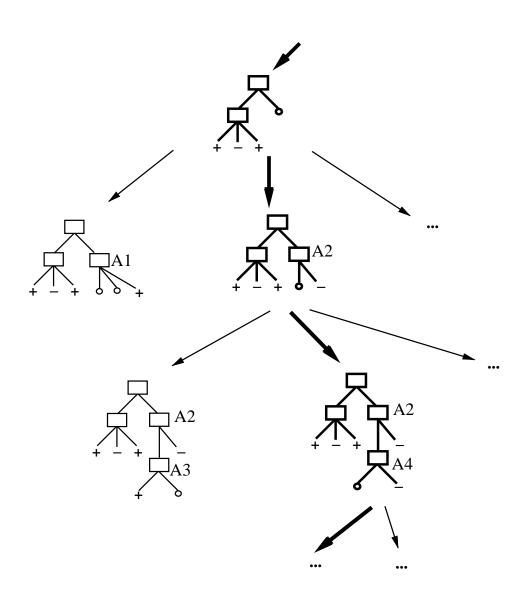
$$S_{sunny} = \{D1,D2,D8,D9,D11\}$$

$$Gain (S_{sunny}, Humidity) = .970 - (3/5) 0.0 - (2/5) 0.0 = .970$$

$$Gain (S_{sunny}, Temperature) = .970 - (2/5) 0.0 - (2/5) 1.0 - (1/5) 0.0 = .570$$

$$Gain (S_{sunny}, Wind) = .970 - (2/5) 1.0 - (3/5) .918 = .019$$

# Hypothesis Space Search by ID3



### Hypothesis Space Search by ID3

- Hypothesis space is complete!
  - Target function surely in there...
- Outputs a single hypothesis (which one?)
  - Can't play 20 questions...
- No back tracking
  - Local minima...
- Statistically-based search choices
  - Robust to noisy data...
- Inductive bias: approx "prefer shortest tree"

#### Inductive Bias in ID3

Note H is the power set of instances X

 $\rightarrow$ Unbiased?

Not really...

- Preference for short trees, and for those with high information gain attributes near the root
- Bias is a preference for some hypotheses, rather than a restriction of hypothesis space H
- Occam's razor: prefer the shortest hypothesis that fits the data

#### Occam's Razor

Why prefer short hypotheses?

### Argument in favor:

- Fewer short hyps. than long hyps.
- → a short hyp that fits data unlikely to be coincidence
- $\rightarrow$  a long hyp that fits data might be coincidence

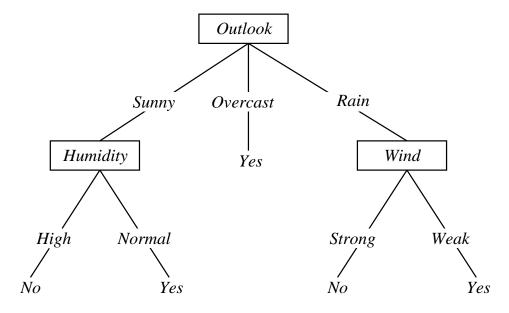
#### Argument opposed:

- There are many ways to define small sets of hyps
- e.g., all trees with a prime number of nodes that use attributes beginning with "Z"
- What's so special about small sets based on *size* of hypothesis??

## Overfitting in Decision Trees

Consider adding noisy training example #15:

Sunny, Hot, Normal, Strong, PlayTennis = NoWhat effect on earlier tree?



## Overfitting

Consider error of hypothesis h over

- training data:  $error_{train}(h)$
- ullet entire distribution  $\mathcal D$  of data:  $error_{\mathcal D}(h)$

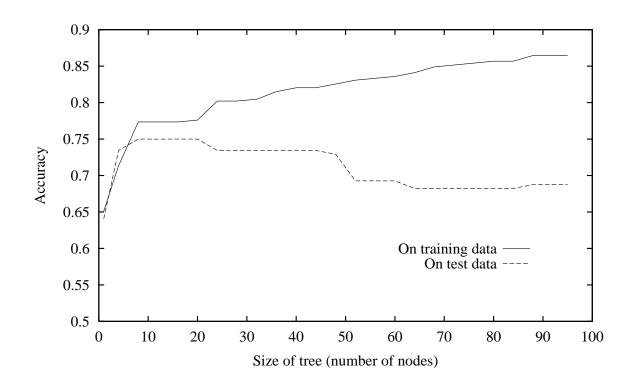
Hypothesis  $h \in H$  overfits training data if there is an alternative hypothesis  $h' \in H$  such that

$$error_{train}(h) < error_{train}(h')$$

and

$$error_{\mathcal{D}}(h) > error_{\mathcal{D}}(h')$$

# Overfitting in Decision Tree Learning



## Avoiding Overfitting

### How can we avoid overfitting?

- stop growing when data split not statistically significant
- grow full tree, then post-prune

#### How to select "best" tree:

- Measure performance over training data
- Measure performance over separate validation data set
- MDL: minimize size(tree) + size(misclassifications(tree))

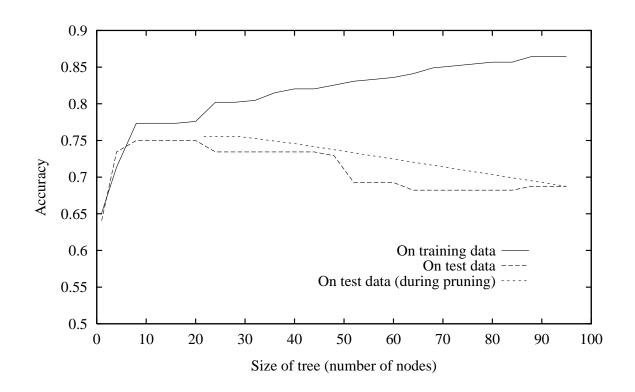
### Reduced-Error Pruning

Split data into training and validation set

Do until further pruning is harmful:

- 1. Evaluate impact on *validation* set of pruning each possible node (plus those below it)
- 2. Greedily remove the one that most improves validation set accuracy
- produces smallest version of most accurate subtree
- What if data is limited?

# Effect of Reduced-Error Pruning

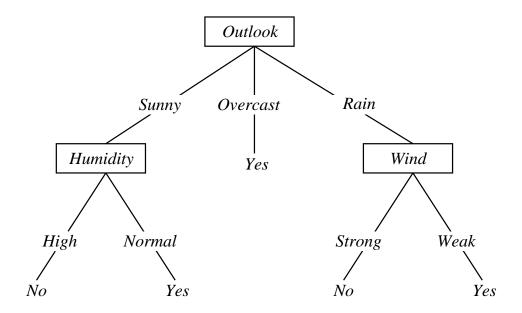


## Rule Post-Pruning

- 1. Convert tree to equivalent set of rules
- 2. Prune each rule independently of others
- 3. Sort final rules into desired sequence for use

Perhaps most frequently used method (e.g., C4.5)

# Converting A Tree to Rules



$$\begin{array}{ll} \text{IF} & (Outlook = Sunny) \land (Humidity = High) \\ \text{THEN} & PlayTennis = No \end{array}$$

$$\begin{array}{ll} \text{IF} & (Outlook = Sunny) \land (Humidity = Normal) \\ \text{THEN} & PlayTennis = Yes \end{array}$$

. . .

### Continuous Valued Attributes

Create a discrete attribute to test continuous

- Temperature = 82.5
- (Temperature > 72.3) = t, f

Temperature:404860728090PlayTennis:NoNoYesYesYesNo

### Attributes with Many Values

#### Problem:

- If attribute has many values, Gain will select it
- Imagine using  $Date = Jun_3_1996$  as attribute

One approach: use GainRatio instead

$$GainRatio(S,A) \equiv \frac{Gain(S,A)}{SplitInformation(S,A)}$$

$$SplitInformation(S, A) \equiv -\sum_{i=1}^{c} \frac{|S_i|}{|S|} \log_2 \frac{|S_i|}{|S|}$$

where  $S_i$  is subset of S for which A has value  $v_i$ 

### Attributes with Costs

#### Consider

- $\bullet$  medical diagnosis, BloodTest has cost \$150
- robotics,  $Width\_from\_1ft$  has cost 23 sec.

How to learn a consistent tree with low expected cost?

One approach: replace gain by

• Tan and Schlimmer (1990)

$$rac{Gain^2(S,A)}{Cost(A)}$$
.

• Nunez (1988)

$$\frac{2^{Gain(S,A)}-1}{(Cost(A)+1)^w}$$

where  $w \in [0, 1]$  determines importance of cost

### Unknown Attribute Values

What if some examples missing values of A? Use training example anyway, sort through tree

- If node n tests A, assign most common value of A among other examples sorted to node n
- $\bullet$  assign most common value of A among other examples with same target value
- ullet assign probability  $p_i$  to each possible value  $v_i$  of A
  - assign fraction  $p_i$  of example to each descendant in tree

Classify new examples in same fashion