

UNIVERSITY OF HOUSTON

NOTES

**COSC 6364**  
**Advanced Numerical Analysis**

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# Chapter 1

## Matrix-Vector Multiplication

We interpret a matrix-vector multiplication  $\mathbf{b} = A\mathbf{x}$  as follows: if  $\mathbf{b} = A\mathbf{x}$ , then  $\mathbf{b}$  is a linear combination of columns of  $A$ . In particular, letting  $\mathbf{a}_i$  denote the  $i^{\text{th}}$  column of  $A$  and  $x_i$  the  $i^{\text{th}}$  element of  $\mathbf{x}$ , we can write this equation as

$$\begin{aligned} \mathbf{b} &= [\mathbf{a}_1 \mid \mathbf{a}_2 \mid \dots \mid \mathbf{a}_n] \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \\ &= x_1\mathbf{a}_1 + x_2\mathbf{a}_2 + \dots + x_n\mathbf{a}_n \end{aligned}$$

A matrix product  $B = AC$  can be interpreted as: each column of  $B$  is a linear combination of the columns of  $A$ . Write:

$$\begin{aligned} AC &= \underbrace{\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}}_{m \times n} \underbrace{\begin{bmatrix} c_{11} & c_{12} & \dots & c_{1k} \\ c_{21} & c_{22} & \dots & c_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ c_{n1} & c_{n2} & \dots & c_{nk} \end{bmatrix}}_{n \times k} \\ B &= \underbrace{[\mathbf{b}_1 \mid \mathbf{b}_2 \mid \dots \mid \mathbf{b}_k]}_{m \times k} \end{aligned}$$

Then column  $\mathbf{b}_i$  is just

$$\begin{aligned} \mathbf{b}_i &= \begin{bmatrix} a_{11}c_{1i} + a_{12}c_{2i} + \dots + a_{1n}c_{ni} \\ a_{21}c_{1i} + a_{22}c_{2i} + \dots + a_{2n}c_{ni} \\ \vdots \\ a_{m1}c_{1i} + a_{m2}c_{2i} + \dots + a_{mn}c_{ni} \end{bmatrix} \\ &= c_{1i} \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix} + c_{2i} \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{bmatrix} + \dots + c_{ni} \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{bmatrix} \\ &= c_{1i}\mathbf{a}_1 + c_{2i}\mathbf{a}_2 + \dots + c_{ni}\mathbf{a}_n \end{aligned}$$



## Chapter 2

# Practice Quizzes

### Quiz 1

1. Given a matrix that is both triangular and unitary, is it non-diagonal?

**Solution.** A triangular, unitary matrix must be diagonal. To see this, consider an upper-triangular, normal matrix<sup>1</sup>,  $A$ . Write

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ 0 & a_{22} & a_{23} & \dots & a_{2n} \\ 0 & 0 & a_{33} & \dots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & a_{nn} \end{bmatrix}$$

$$A^* = \begin{bmatrix} \overline{a_{11}} & 0 & 0 & \dots & 0 \\ \overline{a_{12}} & \overline{a_{22}} & 0 & \dots & 0 \\ \overline{a_{13}} & \overline{a_{23}} & \overline{a_{33}} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \overline{a_{1n}} & \overline{a_{2n}} & \overline{a_{3n}} & \dots & \overline{a_{nn}} \end{bmatrix}$$

Consider the 1<sup>st</sup> diagonal element of  $AA^*$ , written explicitly:

$$(AA^*)_{11} = a_{11}\overline{a_{11}} + a_{12}\overline{a_{12}} + \dots + a_{1n}\overline{a_{1n}}$$

And similarly for  $A^*A$ :

$$(A^*A)_{11} = \overline{a_{11}}a_{11}$$

These two values must be equal, forcing

$$a_{12}\overline{a_{12}} + \dots + a_{1n}\overline{a_{1n}} = 0$$

However,  $z\overline{z} = |z|^2$  is strictly non-negative, hence these values must be identically 0. In particular, this means the first row of  $A$  is

$$[a_{11} \quad 0 \quad 0 \quad \dots \quad 0]$$

The same argument applies for each row of the matrix  $A$ .

If  $A$  is lower-triangular, then  $B = A^*$  is upper-triangular, and  $B$  is diagonal, by the above argument, hence  $A$  is diagonal.  $\square$

2. Can the absolute value of an eigenvalue of a unitary matrix be 1?

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<sup>1</sup>A normal matrix is one which satisfies  $AA^* = A^*A$ . Clearly, every unitary matrix is normal.

**Solution.** Clearly, the answer is yes. Take  $A = I_n$  and note that it has characteristic equation  $(1 - \lambda)^n = 0$ , which has eigenvalues of 1. However, the stronger result is that *all* eigenvalues of a unitary matrix have modulus 1:

Consider some unitary matrix  $A$ , i.e.,  $A$  satisfies  $AA^* = A^*A = I$ , and any eigenvalue,  $\lambda$ . We have

$$A\mathbf{x} = \lambda\mathbf{x}$$

for some vector  $\mathbf{x}$ . Taking the conjugate transpose of both sides gives

$$\mathbf{x}^* A^* = \bar{\lambda} \mathbf{x}^*$$

Multiplying these equations yields

$$\begin{aligned} (\mathbf{x}^* A^*) (A\mathbf{x}) &= (\bar{\lambda} \mathbf{x}^*) (\lambda \mathbf{x}) \\ \mathbf{x}^* (A^* A) \mathbf{x} &= \lambda \bar{\lambda} \mathbf{x}^* \mathbf{x} \\ \mathbf{x}^* \mathbf{x} &= \lambda \bar{\lambda} \mathbf{x}^* \mathbf{x} \end{aligned}$$

This forces  $\lambda \bar{\lambda} = |\lambda|^2 = 1$ . □

3. If  $W$  is an arbitrary nonsingular matrix, then is the function  $\|\cdot\|_W$  defined by  $\|\mathbf{x}\|_W = \|W\mathbf{x}\|$  (weighted norm) a vector norm?

**Solution.** In order for  $\|\cdot\|_W$  to be a vector norm, it must satisfy:

1.  $\|\mathbf{u} + \mathbf{v}\|_W \leq \|\mathbf{u}\|_W + \|\mathbf{v}\|_W$  (triangle inequality)
2.  $\|c\mathbf{u}\|_W = |c| \|\mathbf{u}\|_W$  (scalable/homogenous)
3. if  $\|\mathbf{u}\|_W = 0$  then  $\mathbf{u} = \mathbf{0}$  (positivity)

2 and 3 are obvious. To see 1, note that

$$\begin{aligned} \|\mathbf{u} + \mathbf{v}\|_W &= \|W(\mathbf{u} + \mathbf{v})\| \\ &= \|W\mathbf{u} + W\mathbf{v}\| \\ &\leq \|W\mathbf{u}\| + \|W\mathbf{v}\| \text{ by the triangle inequality} \\ &= \|\mathbf{u}\|_W + \|\mathbf{v}\|_W \end{aligned}$$

Thus,  $\|\cdot\|_W$  is a vector norm. □

4. If  $E$  is an outer product  $E = \mathbf{u}\mathbf{v}^*$ , then  $\|E\|_2 = \|\mathbf{u}\|_2 \|\mathbf{v}\|_2$ . Is the same true for the Frobenius norm, i.e.,  $\|E\|_F = \|\mathbf{u}\|_F \|\mathbf{v}\|_F$ ?

**Solution.** Write  $\mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix}$  and  $\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$ . Then

$$\begin{aligned} E &= \mathbf{u}\mathbf{v}^* \\ &= \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} \begin{bmatrix} \overline{v_1} & \overline{v_2} & \dots & \overline{v_n} \end{bmatrix} \\ &= \begin{bmatrix} u_1 \overline{v_1} & u_1 \overline{v_2} & \dots & u_1 \overline{v_n} \\ u_2 \overline{v_1} & u_2 \overline{v_2} & \dots & u_2 \overline{v_n} \\ \vdots & \vdots & \ddots & \vdots \\ u_n \overline{v_1} & u_n \overline{v_2} & \dots & u_n \overline{v_n} \end{bmatrix} \end{aligned}$$

We therefore have

$$\begin{aligned}
 \|E\|_F &= \sqrt{\sum_{i=1}^n \sum_{j=1}^n |u_i \overline{v_j}|^2} \\
 &= \sqrt{\sum_{i=1}^n \sum_{j=1}^n |u_i|^2 |\overline{v_j}|^2} \\
 &= \sqrt{\sum_{i=1}^n \sum_{j=1}^n |u_i|^2 |v_j|^2}
 \end{aligned}$$

And further

$$\begin{aligned}
 \|\mathbf{u}\|_F \|\mathbf{v}\|_F &= \left( \sqrt{\sum_{i=1}^n |u_i|^2} \right) \left( \sqrt{\sum_{i=1}^n |v_i|^2} \right) \\
 &= \sqrt{\left( \sum_{i=1}^n |u_i|^2 \right) \left( \sum_{i=1}^n |v_i|^2 \right)} \\
 &= \sqrt{\sum_{i=1}^n \sum_{j=1}^n |u_i|^2 |v_j|^2} \\
 &= \|E\|_F
 \end{aligned}$$

□

## Quiz 2

1. What is the SVD of  $\begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$ ?
2. Suppose  $A$  is an  $m \times n$  matrix and  $B$  is the  $n \times m$  matrix obtained by rotating  $A$  ninety degrees clockwise on paper (not exactly a standard mathematical transformation). Do  $A$  and  $B$  have the same singular values?
3. Two matrices,  $A, B \in \mathbb{R}^{m \times m}$  are unitarily equivalent if  $A = QBQ^*$  for some unitary  $Q \in \mathbb{R}^{m \times m}$ . Is it true that  $A$  and  $B$  are unitarily equivalent if and only if they have the same singular values?
4. Given  $A \in \mathbb{R}^{m \times n}$  with  $m \geq n$  and  $A$  has full rank, is  $A^*A$  nonsingular?





# Glossary

## basis

A **basis** of a vector space is a set of linearly independent vectors that spans the entire space.

## column rank

The dimension of the vector space spanned by the columns of a matrix.

## dimension

The size of a basis of a vector space. Equivalently, the greatest number of linearly independent vectors, or the least number of vectors which spans the vector space (see also: rank).

## eigenvalue

A scalar  $\lambda$  such that  $A\mathbf{x} = \lambda\mathbf{x}$  for non-zero  $\mathbf{x}$ .

## eigenvector

A non-zero vector  $\mathbf{x}$  such that  $A\mathbf{x} = \lambda\mathbf{x}$  for some scalar  $\lambda$ .

## Frobenius norm

$$\|\mathbf{x}\|_F = \left( \sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2 \right)^{\frac{1}{2}}$$

## full rank

An  $m \times n$  matrix has **full rank** when its rank is equal to  $\min(m, n)$ .

## induced norm

A set of vectors  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$  is linearly independent of the only solution to the equation

$$c_1\mathbf{x}_1 + c_2\mathbf{x}_2 + \dots + c_n\mathbf{x}_n$$

description

## $\infty$ -norm

$$\|\mathbf{x}\|_\infty = \max_{1 \leq i \leq m} |x_i|$$

## inner product

The **inner product** of  $\mathbf{u}$  and  $\mathbf{v}$  is  $\mathbf{u}^T \mathbf{v}$ . Also called the dot product.

## kernel

The set of all vectors that satisfy  $A\mathbf{x} = \mathbf{0}$  (see also: nullspace).

## linearly independent

A set of vectors  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$  is linearly independent of the only solution to the equation

$$c_1\mathbf{x}_1 + c_2\mathbf{x}_2 + \dots + c_n\mathbf{x}_n = \mathbf{0}$$

is

$$c_1 = c_2 = \dots = c_n = 0$$

**lower triangular matrix**

A matrix where all entries above the diagonal are zero, i.e.,

$$L = \begin{bmatrix} \ell_{1,1} & 0 & 0 & 0 & 0 \\ \ell_{2,1} & \ell_{2,2} & 0 & 0 & 0 \\ \ell_{3,1} & \ell_{3,2} & \ddots & 0 & 0 \\ \vdots & \vdots & \ddots & \ddots & 0 \\ \ell_{n,1} & \ell_{n,2} & \dots & \ell_{n,n-1} & \ell_{n,n} \end{bmatrix}$$

**non-singular matrix**

A matrix that has an inverse. Equivalently, a matrix with non-zero determinant.

**norm**

A norm is a real-valued function  $\|\cdot\|$  such that

1.  $\|\mathbf{x} + \mathbf{y}\| \leq \|\mathbf{x}\| + \|\mathbf{y}\|$  (triangle inequality)
2.  $\|c\mathbf{x}\| = |c| \|\mathbf{x}\|$
3.  $\|\mathbf{x}\| = 0$  if and only if  $\mathbf{x} = \mathbf{0}$

**nullspace**

The set of all vectors that satisfy  $A\mathbf{x} = \mathbf{0}$  (see also: kernel).

**orthogonal matrix**

A real square matrix  $A$  is orthogonal if  $AA^T = I$ , i.e.,  $A^{-1} = A^T$ .

**orthogonal vectors**

Two vectors  $\mathbf{u}$  and  $\mathbf{v}$  are **orthogonal** if their inner product is 0, i.e., if  $\mathbf{u}^T \mathbf{v} = 0$ .

**outer product**

The matrix produced by the product of a column vector and its transpose, i.e.,  $\mathbf{u}\mathbf{v}^*$

 **$p$ -norm**

$$\|\mathbf{x}\|_p = \left( \sum_{i=1}^n |x_i|^p \right)^{\frac{1}{p}}$$

**range**

The set of all vectors that can be expressed as  $A\mathbf{x}$  for some  $\mathbf{x}$ .

**rank**

The dimension of the vector space spanned by a matrix.

**row rank**

The dimension of the vector space spanned by the rows of a matrix.

**singular matrix**

A matrix that has no inverse. Equivalently, a matrix with 0 determinant.

**singular value**

The diagonal entries of the matrix  $\Sigma$  in the Singular Value Decomposition. Equivalently, a non-negative real number  $\sigma$  is a **singular value** for  $M$  if and only if there exist unit-length vectors  $\mathbf{u}$  and  $\mathbf{v}$  such that

$$\begin{aligned} M\mathbf{u} &= \sigma\mathbf{v} \\ M^*\mathbf{v} &= \sigma\mathbf{u} \end{aligned}$$

**Singular Value Decomposition**

For any  $m \times n$  matrix  $A$ , a **Singular Value Decomposition** (SVD) of  $A$  is a factorization

$$A = U\Sigma V^*$$

where

- $U$  is an  $m \times m$  unitary matrix
- $V$  is an  $n \times n$  unitary matrix
- $\Sigma$  is an  $m \times n$  diagonal matrix with non-negative real numbers on the diagonal

The columns of  $U$  and  $V$  are called the left-singular and right-singular vectors, respectively, and the diagonal entries  $\sigma_{ii}$  of  $\Sigma$  are known as the **singular values**.

**span**

The set of all linear combinations of the columns of a matrix.

**symmetric**

A matrix  $A$  such that  $A = A^T$ .

**unitary matrix**

A square matrix  $Q$  is unitary if  $QQ^* = I$ , i.e.,  $Q^{-1} = Q^*$ .

**upper triangular matrix**

A matrix where all entries below the diagonal are zero, i.e.,

$$U = \begin{bmatrix} u_{1,1} & u_{1,2} & u_{1,3} & \dots & u_{1,n} \\ 0 & u_{2,2} & u_{2,3} & \dots & u_{2,n} \\ 0 & 0 & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \ddots & u_{n-1,n} \\ 0 & 0 & 0 & 0 & u_{n,n} \end{bmatrix}$$



# Acronyms

## **SVD**

Singular Value Decomposition