

Lecture 3

Singular Value Decomposition

NLA Chapter 4 & 5

What, why, and how?

- What: Singular Value Decomposition (SVD) is a matrix factorization that make every matrix like a diagonal matrix.
- Why:
 - Conceptual: a powerful device to link many concepts together: rank, 2-norm, F-norm, trace, ... In general, a great device for proving and understanding! (When facing a problem, ask yourself “what if I take an SVD of the matrix?”)
 - Practical: SVD leads to the most **accurate** algorithm for solving linear system/least square problem; **optimal** low-rank matrix approximation; computing the 2-norm; ...
- How: have to defer the computation of SVD to later lectures on eigenvalues (QR algorithms) and iterative methods (Lanczos/Arnoldi iteration).
 - QR algorithm is probably the pinnacle of (classic) NLA! Very reliable, fast, and beautiful algorithm to compute eigen/singular value/vectors.

SVD– The Swiss Army Knife...



Source: <https://www.amazon.com/dp/B001DZTJRQ>

Geometric Intuition

- The image of the unit sphere (S) under any $m \times n$ matrix is a hyperellipse (AS).
- Hyperellipse in \mathbb{R}^m is a unit sphere stretched by some factors $\sigma_1, \sigma_2, \dots, \sigma_m$ in some **orthogonal** directions $u_1, u_2, \dots, u_m \in \mathbb{R}^m$ (unit vectors).
- The vectors $\{\sigma_1 u_1, \sigma_2 u_2, \dots, \sigma_m u_m\}$ the principal semiaxes of the hyperellipse, with length $\sigma_1, \sigma_2, \dots, \sigma_m$.
- Singular values: the stretch factors $\sigma_1, \sigma_2, \dots, \sigma_m$
- n left singular vectors: $u_1, u_2, \dots, u_m \in \mathbb{R}^m$
- n right singular vectors: preimages of principal semiaxes of AS, $v_1, v_2, \dots, v_m \in \mathbb{R}^m$, i.e. $Au_i = \sigma_i v_i$ ($i = 1, \dots, n$)

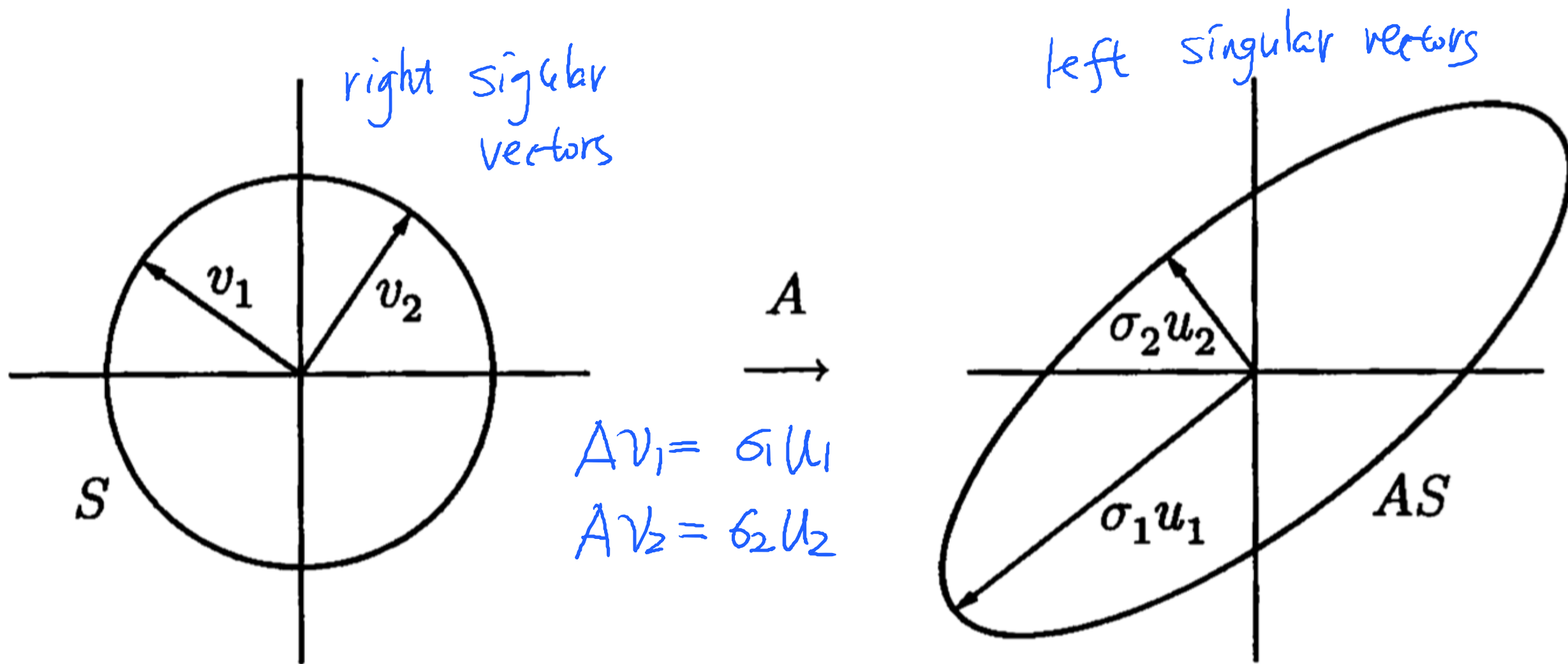


Figure 4.1. *SVD of a 2×2 matrix.*

Reduced SVD (1)

- The matrix $A \in \mathbb{R}^{m \times n}$ maps right singular vectors to stretched left singular vectors

$$Av_i = \sigma_i u_i, i = 1, 2, \dots, n$$

- Put it in the matrix form (remember the linear combination interpretation of matrix-vector multiplication?)

$$\begin{bmatrix} A \end{bmatrix} \begin{bmatrix} v_1 & v_2 & \cdots & v_n \end{bmatrix} = \begin{bmatrix} u_1 & u_2 & \cdots & u_n \end{bmatrix} \begin{bmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_n \end{bmatrix},$$

$$AV = \hat{U} \hat{\Sigma}$$

Reduced SVD (2)

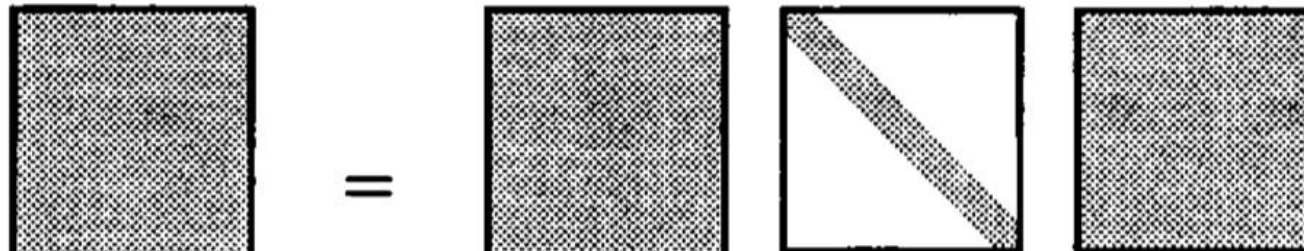
- Matrix form:

$$AV = \hat{U}\hat{\Sigma}$$

- Note that V is unitary, we have

$$A = \hat{U}\hat{\Sigma}V^T$$

Reduced SVD ($m \geq n$)

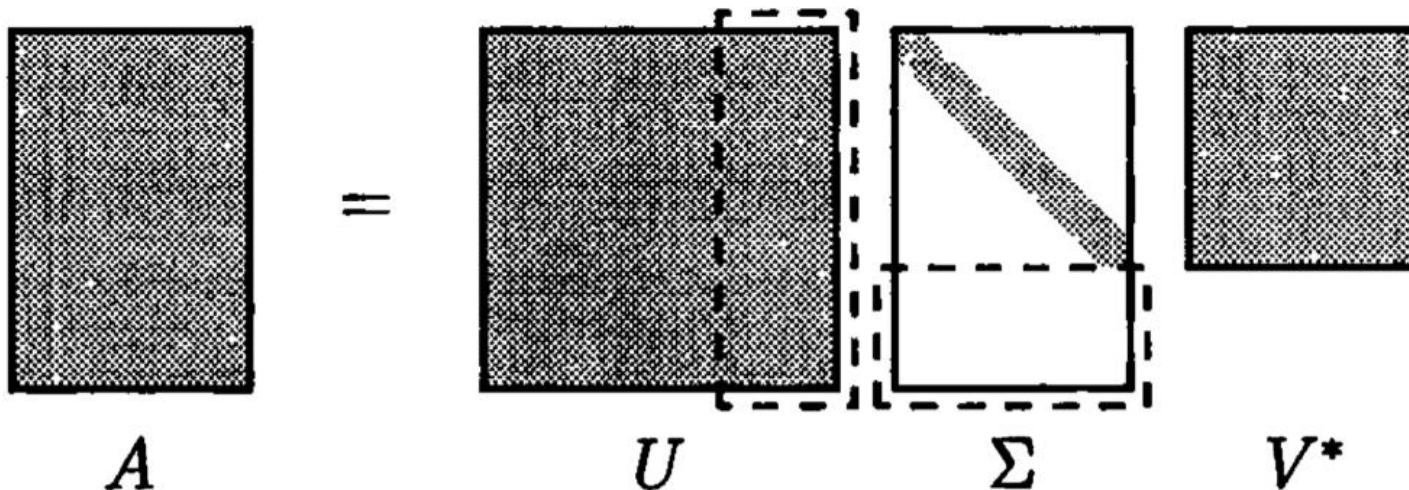


The diagram illustrates the Reduced SVD decomposition $A = \hat{U}\hat{\Sigma}V^*$. It shows four matrices arranged horizontally, separated by an equals sign. The first matrix, labeled A , is a tall rectangle. The second matrix, labeled \hat{U} , is a tall rectangle. The third matrix, labeled $\hat{\Sigma}$, is a square with a diagonal line. The fourth matrix, labeled V^* , is a square.

Full SVD

- Let's make the matrix \hat{U} orthogonal!
Extend the orthonormal columns of \hat{U} to full $m \times m$ unitary matrix U .
Extend the $\hat{\Sigma}$ with zeros at the bottom to maintain equality...
- Why bother? (now we allow any rank of A)

Full SVD ($m \geq n$)



Formal definition of SVD

For **any** matrix (we focus on real ones) $A \in \mathbb{R}^{m \times n}$, a singular value decomposition (SVD) of A is a factorization

$$A = U\Sigma V^*$$

where

$U \in \mathbb{R}^{m \times m}$ is orthogonal,

$V \in \mathbb{R}^{n \times n}$ is orthogonal,

$\Sigma \in \mathbb{R}^{m \times n}$ is diagonal.

SVD exists and is unique!

The diagonal entries of Σ are non-negative and sorted in decreasing order:

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_p \geq 0, \quad p = \min\{m, n\}$$

SVD: every matrix is diagonal...

If you look at it with proper basis (singular vectors) for domain/range spaces.

Whenever we have

$$b = Ax$$

We have

$$b' = \Sigma x'$$

If the SVD of A is

$$A = U\Sigma V$$

And we express vectors x, b in the basis of columns of V, U :

$$b' = U^* b, x' = V^* x$$

SVD vs. Eigenvalue Decomposition

Eigenvalue decomposition: if square matrix A is non-singular and non-defective, then it has eigenvalue decomposition:

$$A = X\Lambda X^{-1}$$

Where X matrix has the eigen vectors as columns, and Λ is a diagonal matrix with the eigenvalues on its diagonal.

Differences with SVD:

- SVD always exists, EVD only when A square & non-defective
- SVD have orthogonal bases where EVD not necessarily (but when A is symmetric, then X is orthogonal!)
- SVD is helpful when dealing with A itself or its inverse; EVD is helpful dealing with powers of X (X^n , $n=1,2,\dots$)
- Computational of SVD depends on EVD:

$$A = U\Sigma V^*$$

$$A^*A = V^*\Sigma^2V$$

$$AA^* = U\Sigma^2U^*$$

Matrix Properties via SVD

- Assumptions:
 - $A \in \mathbb{R}^{m \times n}$
 - $p = \min\{m, n\}$
 - r is the number of non-zero singular values of A
 - $\langle x, y, z \rangle$ means the space spanned by vectors x, y, z
- T5.1: The rank of A is r (the number of non-zero singular values)

- T5.2: $\text{range}(A) = \langle u_1, u_2, \dots, u_r \rangle$, $\text{null}(A) = \langle v_{r+1}, v_{r+2}, \dots, v_n \rangle$
(hint: A looks like diagonal matrix under SVD...)

- T5.3: $\|A\|_2 = \sigma_1$ and $\|A\|_F = \sqrt{\sigma_1^2 + \sigma_2^2 + \dots + \sigma_r^2}$
(hint: again, A looks like diagonal; orthogonal transformations conserve 2/F norm)

- T5.4: The non-zero singular values of A are the square roots of the non-zero eigenvalues of AA^* or A^*A
- T5.5: if A is symmetric, then the singular values of A are the absolute values of eigenvalues of A .

Low rank approximations

- Alternative form of SVD (the sum of rank-1):

$$A = U\Sigma V^* = \sum_{i=1}^r \sigma_i u_i v_i^*$$

- Thus, SVD decomposes a matrix A as the sum of r rank-1 matrices.
- What's special about this decomposition is that:

The partial sum captures as much energy of A as possible

SVD gives optimal low-rank approximation

Theorem 5.8. *For any ν with $0 \leq \nu \leq r$, define*

$$A_\nu = \sum_{j=1}^{\nu} \sigma_j u_j v_j^*;$$

if $\nu = p = \min\{m, n\}$, define $\sigma_{\nu+1} = 0$. Then

$$\|A - A_\nu\|_2 = \inf_{\substack{B \in \mathbb{C}^{m \times n} \\ \text{rank}(B) \leq \nu}} \|A - B\|_2 = \sigma_{\nu+1}.$$

Example Application of SVD

- Image compression. We have a 512x512 pixels Lena picture as a 512x512 matrix A

rank=10



rank=20



rank=40



rank=80

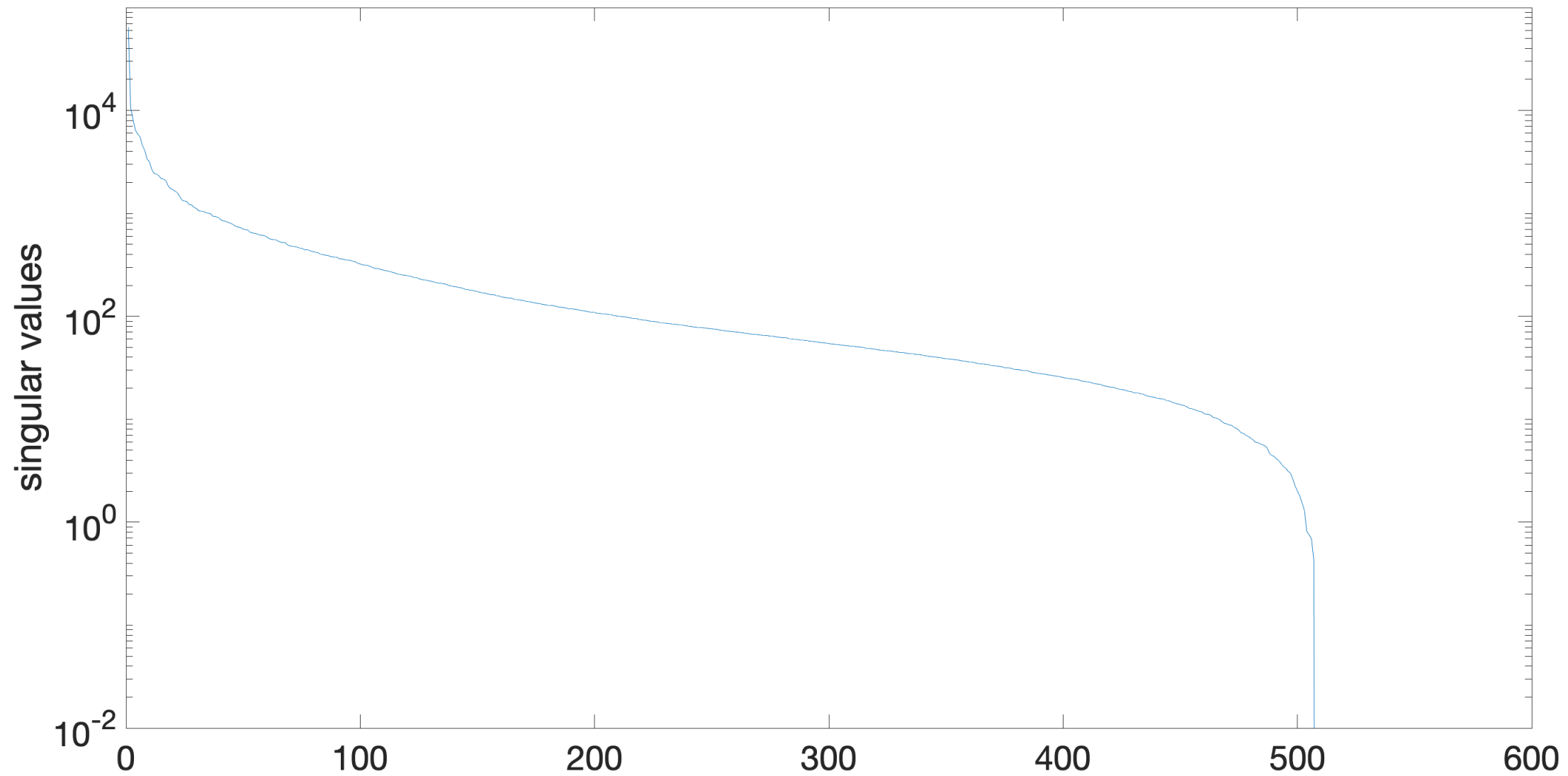


rank=160



rank=512





Applications in Data Science

- Semantic Analysis
- Collaborative filtering/recommendation (Netflix Prize!)
- Pseudo-inverse (used for least square problem)
- Data compression
- Principal component analysis
- ...