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Final Project: Analysis Document

Inserting into a BST versus a Hash Table

Data Analysis Graphs

Analysis and Summation

Concrete Real-World Example

Data Structure Selection

Removing from a Vector at the Front versus the Back

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Searching a Vector, DLL, SLL, BST, and Hash Table

Data Analysis Graphs

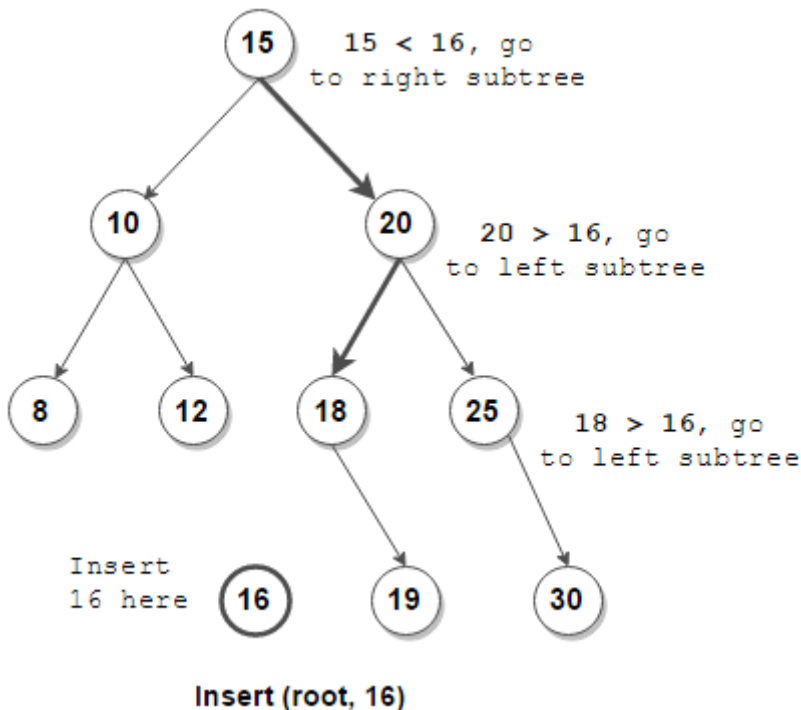
Analysis and Summation

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Analysis and Summation

In computer science, a **binary tree** is a tree data structure in which each node has at most two children, which are referred to as the *left child* and the *right child*. A recursive definition using just set theory notions is that a (non-empty) binary tree is a tuple (L, S, R) , where L and R are binary trees or the empty set and S is a singleton set containing the root.^[1] Some authors allow the binary tree to be the empty set as well.^[2]

From a graph theory perspective, binary (and K-ary) trees as defined here are arborescences. A binary tree may thus be also called a **bifurcating arborescence**^[3]—a term which appears in some very old programming books,^[4] before the modern computer science terminology prevailed. It is also possible to interpret a binary tree as an undirected, rather than a directed graph, in which case a binary tree is an ordered, rooted tree.^[5] Some authors use **rooted binary tree** instead of *binary tree* to emphasize the fact that the tree is rooted, but as defined above, a binary tree is always rooted.^[6] A binary tree is a special case of an ordered K-ary tree, where K is 2.

In mathematics, what is termed *binary tree* can vary significantly from author to author. Some use the definition commonly used in computer science,^[7] but others define it as every non-leaf having exactly two children and don't necessarily order (as left/right) the children either.

Concrete Real-World Example

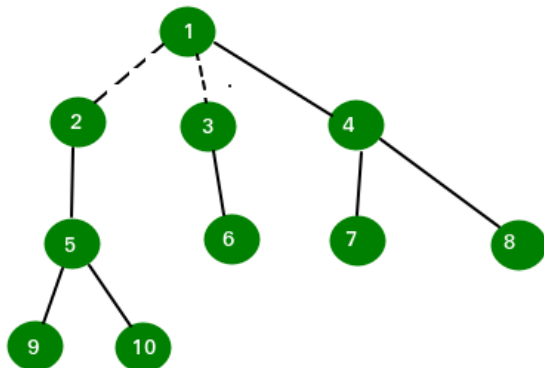
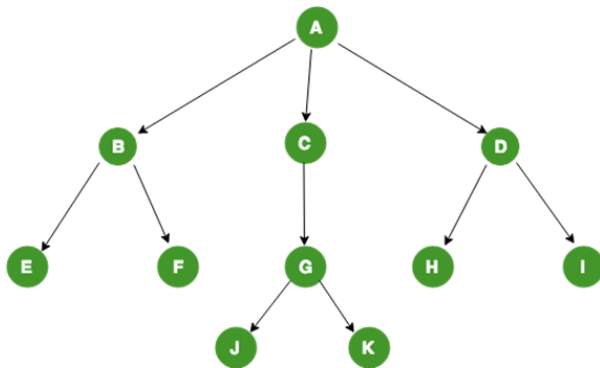
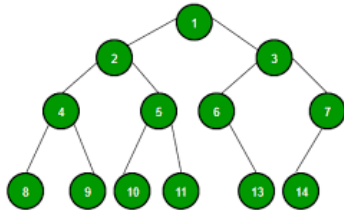
- First, as a means of accessing nodes based on some value or label associated with each node.^[9] Binary trees labelled this way are used to implement binary search trees and binary heaps, and are used for efficient searching and sorting. The designation of non-root nodes as left or right child even when there is only one child present matters in some of these applications, **in particular**, it is significant in binary search trees.^[10] However, the arrangement of particular nodes into the tree is not part of the conceptual information. For example, in a normal binary search tree the placement of nodes depends almost entirely on the order in which they were added, and can be re-arranged (for example by balancing) without changing the meaning.
- Second, as a representation of data with a relevant bifurcating structure. In such cases, the particular arrangement of nodes under and/or to the left or right of other nodes is part of the information (that is, changing it would change the meaning). Common examples occur with Huffman coding and **cladograms**. **The everyday** division of documents into chapters, sections, paragraphs, and so on is an analogous example with n-ary rather than binary trees.

Data Structure Selection

A binary tree is a **tree-type non-linear data structure** with a maximum of two children for each parent. Every node in a binary tree has a left and right reference along with the data element. The node at the top of the **hierarchy of a tree** is called the root node. The nodes that hold other sub-nodes are the parent nodes

Removing from a Vector at the Front versus the Back

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Analysis and Summation

To actually define a binary tree in general, we must allow for the possibility that only one of the children may be empty. An artifact, which in some textbooks is called an *extended binary tree* is needed for that purpose. An extended binary tree is thus recursively defined as:^[11]

- the empty set is an extended binary tree
- if T_1 and T_2 are extended binary trees, then denote by $T_1 \bullet T_2$ the extended binary tree obtained by adding a root r connected to the left to T_1 and to the right to T_2 ^[clarification needed where did the 'r' go in the $T_1 \bullet T_2$ symbol] by adding edges when these sub-trees are non-empty.

Another way of imagining this construction (and understanding the terminology) is to consider instead of the empty set a different type of node—for instance square nodes if the regular ones are circles.

Concrete Real-World Example

A binary tree is a rooted tree that is also an ordered tree (a.k.a. plane tree) in which every node has at most two children. A rooted tree naturally imparts a notion of levels (distance from the root), thus for every node a notion of children may be defined as the nodes connected to it a level below. Ordering of **these children** (e.g., by drawing them on a plane) makes it possible to distinguish a left child from a right child.^[13] But this still doesn't distinguish between a node with left but not a right child from a one with right but no left child.

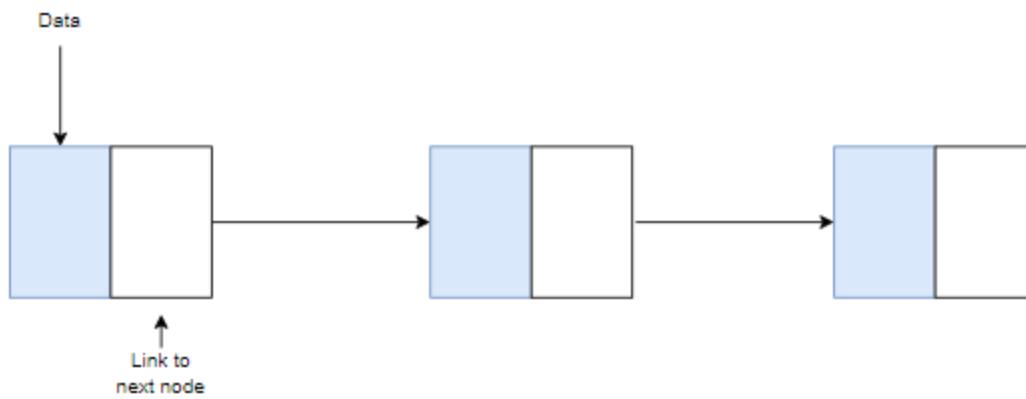
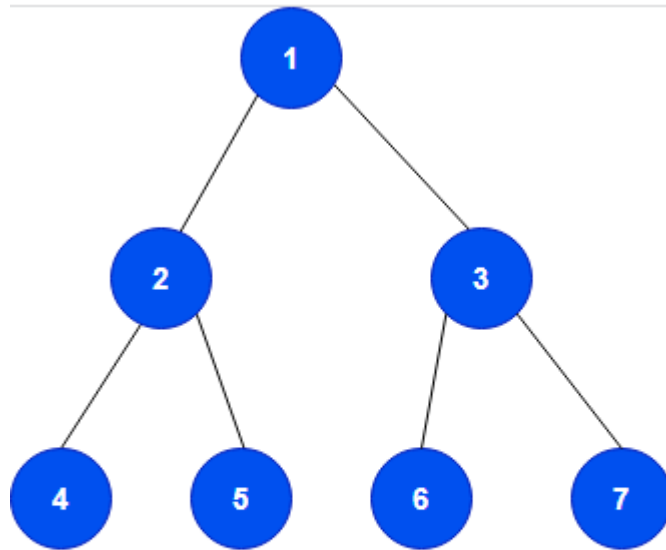
The necessary distinction can be made by first partitioning the edges, i.e., defining the binary tree as triplet (V, E_1, E_2) , where $(V, E_1 \cup E_2)$ is a rooted tree (equivalently arborescence) and $E_1 \cap E_2$ is empty, and also requiring that for all $j \in \{1, 2\}$ every node has at most one E_j child.^[14] A more informal **way of making the** distinction is to say, quoting the Encyclopedia of Mathematics, that "every node has a left child, a right child, neither, or both" and to specify that these "are all different" binary trees

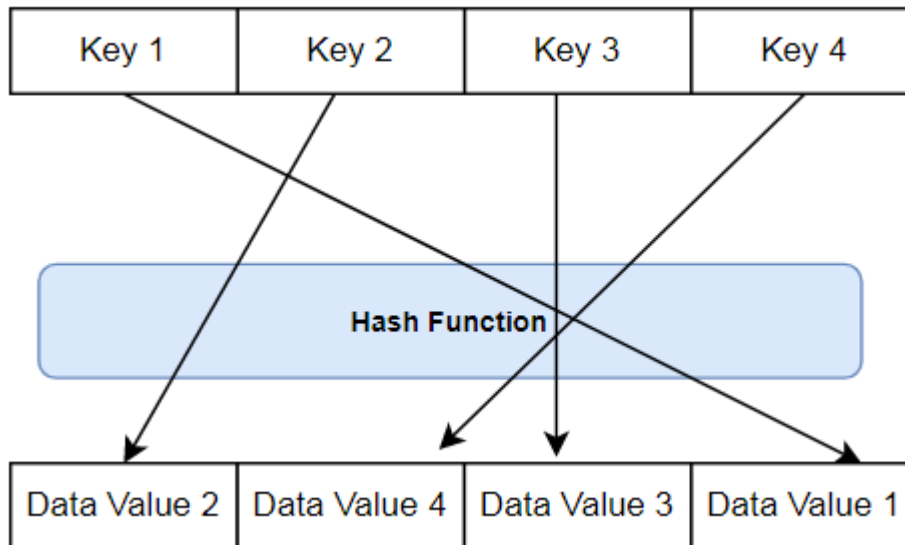
Data Structure Selection

The **Tournament tree** is a complete binary tree with n external nodes and $n - 1$ internal nodes. The external nodes represent the players, and the internal nodes are representing the winner of the match between the **two players. This** tree is also known as Selection tree. There are some properties of Tournament trees

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Analysis and Summation

A **binary tree** is a hierarchical tree-based data structure in which each node has at most **two children**. The root node is the topmost node of a binary tree, while the left and right nodes are called left and **right children, respectively**. Furthermore, the links between nodes are known as branches, while a node without children is called a leaf node.

In a binary tree, a single node will **contain a data** value and a link to each of the child nodes. The following operations can be performed on binary trees: insertion, searching, and deletion. These operations can be executed in time.

Concrete Real-World Example

A few benefits to using linked lists are:

- Nodes can be easily deleted and inserted.
- A linked list can be easily implemented in most programming languages.

On the contrary, some limitations of linked lists are:

- Nodes **must always be** accessed sequentially, which is time consuming.
- The pointers used in linked lists require additional memory.

Data Structure Selection

Consequently, some major benefits of using hash tables are:

- Insert, delete and search operations are very fast and can be done in time.

- Hash tables can store large amounts of data.

Conversely, some limitations of using hash tables are:

- Hash functions tend to produce duplicate keys, which cause problems with storing data values, known as collisions.
- Good hash functions that produce distinct keys are expensive and difficult to implement.

proposal

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