Sputnik Capstone Test Plan

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Revision History

03/03/16 - Created document (Shan)

03/04/16 - Converted to markdown, proofreading changes (Will)

Introduction

Purpose

The purpose of this document is to outline the essential testing that will be conducted to demonstrate the effectiveness of the Sputnik Capstone project. This test plan is not intended to be inclusive and additional testing procedures will be added if deemed necessary by any of the parties involved in the project.

Testing Procedure

All of the testing described in this document will be carried out by one or more than one member of the Sputnik capstone team. An effort will be made to have the entire group present for as many of the tests as possible.

Recordings of Results, witnessing, and Authorities

The results of all testing conducted in this test plan will be displayed on the project wiki. The tests will be conducted on a pass/fail basis and any tests that do not pass will be noted in the documentation with an explanation as to why they did not pass. No authorities or witnesses outside of the group will be required to be present during testing.

Reference Documents

Design Documentation

The Sputnik Capstone project is composed of two separate modules: The radio module and the control module. The radio module is home to the microcontroller

Figure 1: Phase 1 Low Level Diagram

with integrated radio transceiver (kwox), while the control module is designed to eventually house a radiation hardened watchdog controller that will help reboot the system after debilitating radiation events. For this project, the radiation-hardened components of the control module will be replaced with off-the shelf components to help reduce cost.

Overview

Operational Description

The Portland State Aerospace Society is sponsoring this capstone based on the need for a command, control, and communications system for their CubeSat project. The focus of this capstone will be rapidly prototyping the radio module and the control module. Sputnik will eventually be responsible for long distance communications to and from a 400km low earth orbit, as well as, controlling and communicating with a payload that is housed within the CubeSat. On top of fulfilling these duties, once space bound, it will need to be able to deal with a temperature range of -40C to 50C and radiation events that could cause components to latch up.

Pre-test preparation

Test equipment

The equipment needed for the tests is as follows: * Power Supply sufficient to maintain 1A of current at 3V for approximately 15 minutes * multimeter (voltmeter) * Oscilloscope * USB to micro-USB cable * Logic analyzer

Test setup and calibration

The testing setup will be discussed for each case along with any necessary calibration needed prior to testing.

System tests

10km Radio Communication Test

The radio is fundamental to the functionality of the Sputnik project. It provides the communication channel that will link the satellite to the ground station. Eventually, the radio will need to receive and transmit data over a distance of approximately 400km; however, for this project, a transmission distance of 10km is required. The purpose of this test is to confirm that the radio is capable of

10km transmission and reception. This test will be performed from one radio board to another and the testers will verify the distance covered during the test by collection GPS location data. The test locations will be predetermined based on both convenience and also where the least restricted signal propagation path will occur.

| Test Case Name | 10km Radio Communication | Test ID# | 10k_1.00 | Test Writer | Shan Quinney | Description | The purpose of this test is to ensure that the radio is capable of transmitting and receiving data at this distance. | Tester Information | Name of Tester | Time/Date | Hardware Version | Sputnik radio board version 1.00 | Setup | Determine location A and location B, where there is a minimal distance of 10km between points A and B. Have at least one team member located at location A and at least one other team member located at location B. Each location will have a Sputnik radio board with sufficient power supply. Each location will also have a method to verify GPS and time (cell phone). |

Step	Action	Expected Result	Pass/Fail	Comments
1	Radio at location A is made to transmit data.	at location B confirms receiving data transmitted from location		
2	Radio at location B sends confirmation signal.	at location A confirms receiving data from radio at		

Overall Test Result:

System controller Test

The system controller is the guardian of the system. It is present to ensure that the system is functioning correctly and that if any unintended event causes component latch-up or system errors, the system can be cycled or rebooted to return stability. This control system is the other half of the project. Eventually, this system will consist of a radiation hardened microcontroller (ATMegaS128) with supporting radiation hardened LDO. For the purpose of prototyping, the controller is a standard, off-the-shelf ATMega128 chip.

To test the control system, a method to simulate a latch-up event will be used to trigger the watchdog into action. Outlined is the kwox lock-up test. In this test, the crystal on the kwox will be shorted to cause an error in the radio system. The ATMega should sense that the radio is no longer functioning properly and trigger the reset line on the kwox to initiate a reboot.

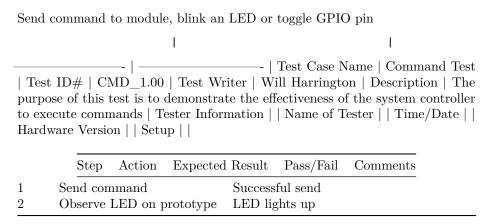
Test | Test ID# | ATM_1.00 | Test Writer | Shan Quinney | Description | The purpose of this test is to demonstrate the effectiveness of the watchdog to restart key system functionality after radiation events. | Tester Information | | Name of Tester | | Time/Date | | Hardware Version | Board Rev.1, Filter Rev.1, Wire antenna | Setup | |

Step	Action	Expected Result	Pass/Fail	Comments
1	Use a metal tool to cause a short across the crystal	The kwox will loose the signal from the crystal.		

Step	Action	Expected Result	Pass/Fail	Comment
2	Probe the UART line be- tween the con- troller and the kwox to deter- mine that the life line signal is lost	The UART line will be free of any signal between the kwox and the controller.		
3	Monitor the con- troller to en- sure that the reset line on the kwox has been acti- vated	The reset line on the kwox will be activated in an effort to reboot the device.		

Overall Test Result:

Command test



Overall Test Result: