```
Warning: Location E:\dang hoc\TT [KT]\bai tap\bai 5 specified for a File or
Folder is invalid.
Warning: Location E:\dang hoc\TT [KT]\bai tap specified for a File or Folder is
>> Calculator
T 01 =
[\cos(t1), -\sin(t1), 0, L1]
[\sin(t1), \cos(t1), 0, 0]
                 0, 1, d1]
[ 0,
                  0, 0, 1]
[
      Ο,
T 12 =
[\cos(t2), -\sin(t2), 0, 0]
[ 0, 0, -1, 0]
[\sin(t2), \cos(t2), 0, 0]
[ 0,
             0, 0, 1]
T 23 =
[\cos(t3), -\sin(t3), 0, L2]
[\sin(t3), \cos(t3), 0, 0]
     0,
                  0, 1, 0]
Γ
       Ο,
                  0, 0, 1]
[
T 34 =
[ 1, 0, 0, L3]
[0, 1, 0, 0]
[ 0, 0, 1, 0]
[ 0, 0, 0, 1]
T 04 =
[\cos(t1) \cdot \cos(t2) \cdot \cos(t3) - \cos(t1) \cdot \sin(t2) \cdot \sin(t3), - \cos(t1) \cdot \cos(t2) \cdot \sin(t3) - \cos \checkmark
(t1) * cos(t3) * sin(t2), sin(t1), L1 - L3* (cos(t1) * sin(t2) * sin(t3) - cos(t1) * cos(t2) 
(t3) + L2*cos(t1)*cos(t2)]
[\cos(t_2) \cdot \cos(t_3) \cdot \sin(t_1) - \sin(t_1) \cdot \sin(t_2) \cdot \sin(t_3), - \cos(t_2) \cdot \sin(t_1) \cdot \sin(t_3) - \cos \checkmark
                                       L2*cos(t2)*sin(t1) - L3*(sin(t1)*sin(t2)*sin(t3) 
(t3) * sin(t1) * sin(t2), -cos(t1),
-\cos(t2)*\cos(t3)*\sin(t1))
                   cos(t2)*sin(t3) + cos(t3)*sin(t2),
                                                                              cos(t2)*cos ¥
(t3) - \sin(t2) * \sin(t3),
                             0,
                                                               d1 + L3*(cos(t2)*sin(t3) + \checkmark
cos(t3)*sin(t2)) + L2*sin(t2)
```

```
0, Ľ
[
Ο,
             0, Ľ
11
Tx =
 \texttt{L1 - L3*}(\cos{(\texttt{t1})} * \sin{(\texttt{t2})} * \sin{(\texttt{t3})} - \cos{(\texttt{t1})} * \cos{(\texttt{t2})} * \cos{(\texttt{t3})}) + \texttt{L2*} \cos{(\texttt{t1})} * \cos{(\texttt{t2})} 
Ty =
sin(t1)*(L3*cos(t2 + t3) + L2*cos(t2))
Tz =
d1 + L3*sin(t2 + t3) + L2*sin(t2)
T_nx =
Px*cos(t1) - L1*cos(t1) + Py*sin(t1)
T_ny =
Py*cos(t1) + L1*sin(t1) - Px*sin(t1)
T nz =
Pz - d1
T mx =
L3*cos(t2 + t3) + L2*cos(t2)
T_my =
0
T_mz =
L3*sin(t2 + t3) + L2*sin(t2)
```

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