

Logistic Regression

- is a supervised machine learning classification model use to predict the probability of a class (usually a binary outcome like yes/no, spam/not spam, disease/no disease, churn/not churn).
- even the name say regression it is actually a classification, not prediction of continuous values.
- This converts values into probability between 0 & 1

When NOT to use

- The relationship is non-linear (deep patterns, image classification, NLP \rightarrow use NN, CNN)
- Data has too many features without regularization (Suffers from Overfitting)
- We need class prediction with complex decision boundaries.
(KNN, Trees, SVM, Random Forest may work better)

The Cost Function $J(\theta)$

$$J(\theta) = -\frac{1}{m} \sum_{i=1}^m [y_i \log(h_\theta(x_i)) + (1-y_i) \log(1-h_\theta(x_i))]$$

Instead of MSE like linear Regression), logistic regression use Log loss $J(\theta)$

- This ensures model penalizes wrong confident predictions heavily.

Note \Rightarrow This is also called Binary Cross-Entropy Loss
or (Log loss or negative log-likelihood).

- Going forward every formula we derive will be 1st & 2nd derivative of this Cost function $J(\theta)$

Now let see the derivative.

data $(x^{(i)}, y^{(i)})$ for $i = 1, \dots$

$x^{(i)} \in \mathbb{R}^n$, $y^{(i)} \in \{0, 1\}$

- parameters (weights): $\theta \in \mathbb{R}^n$

or Logistic regression model \Rightarrow

$$y^{(i)} = h_{\theta}(x^{(i)}) = \sigma(\theta^T x^{(i)})$$

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

interpretation:

$$P(y^{(i)} = 1 | x^{(i)}; \theta) = h_{\theta}(x^{(i)})$$

$$P(y^{(i)} = 0 | x^{(i)}; \theta) = 1 - h_{\theta}(x^{(i)})$$

1. Likelihood & Cost function.

$$P(y^{(i)} | x^{(i)}; \theta) = \begin{cases} h_{\theta}(x^{(i)}) & y^{(i)} = 1 \\ 1 - h_{\theta}(x^{(i)}) & y^{(i)} = 0 \end{cases}$$

we can combine this to

$$P(y^{(i)} | x^{(i)}; \theta) = [h_{\theta}(x^{(i)})]^{y^{(i)}} \cdot [1 - h_{\theta}(x^{(i)})]^{1-y^{(i)}}$$

For all m sample (assuming independence)

$$\mathcal{L}(\theta) = \prod_{i=1}^m P(y^{(i)} | x^{(i)}; \theta)$$

$$= \frac{\prod_{i=1}^m [h_{\theta}(x^{(i)})]^{y^{(i)}} \cdot [1 - h_{\theta}(x^{(i)})]^{1-y^{(i)}}}{\prod_{i=1}^m}$$

\prod = Product
 \sum = Sum

to convert the \prod to \sum we have to use \log

→ we usually maximize log-likelihood:

$$\begin{aligned} l(\theta) &= \log \mathcal{L}(\theta) = \\ &\sum_{i=1}^m \left[y^{(i)} \log h_{\theta}(x^{(i)}) + (1-y^{(i)}) \log (1-h_{\theta}(x^{(i)})) \right] \end{aligned}$$

- In ML style, we define cost function as negative average log-likelihood:
 means we will multiply $-\frac{1}{m}$ in the function

$$J(\theta) =$$

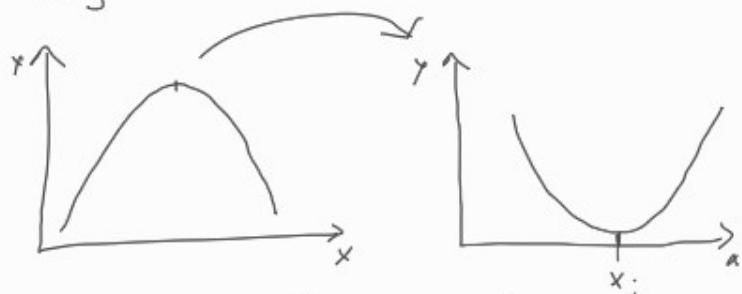
$$-\frac{1}{m} \sum_{i=1}^m [y^{(i)} \log h_\theta(x^{(i)}) + (1-y^{(i)}) \log (1-h_\theta(x^{(i)}))]$$

why we put $-\frac{1}{m}$

there are 2 reason.

1. The -ve sign make it minimization problem

if you remember in Linear Regression
 we were reducing the cost function gradually
 but now the log-likelihood is a maximizing
 function



so just by putting -ve we are converting
 maximizing problem to minimizing problem
 making the math simpler.

\rightarrow -ve \Rightarrow Maxe minimizing equivalent to maximum - likelihood.

2. The $\frac{1}{m}$ makes the cost scale-independent
(average)

- if we don't divide by m , the loss would grow simply because we have more data - not because the model is better or worse.

Example:-

with 10 sample cost ≈ 50

with 10000 identical sample cost $\approx 5^{10000}$ misleading

→ By dividing with $\frac{1}{m}$

we take the mean loss per sample, so:

- the cost remains consistent no matter how many sample we have.

- the gradient became stable and easier to tune with learning rate.

- Training behavior predictable across data size.

$\frac{1}{m} \Rightarrow$ Make the cost an average loss per sample.

2. Derive Gradient $\nabla_{\theta} J(\theta)$

we will differentiate $J(\theta)$ w.r.t each component θ_j .

- 1st write for a single-sample loss:

$$J^{(i)}(\theta) = - \left[y^{(i)} \log h_{\theta}(x^{(i)}) + (1-y^{(i)}) \log (1-h_{\theta}(x^{(i)})) \right]$$

then with multiple sample it will be come

$$J(\theta) = \frac{1}{m} \sum_{i=1}^m J^{(i)}(\theta)$$

- The derivative will be.

$$\frac{\partial J(\theta)}{\partial \theta_j} = \frac{1}{m} \sum_{i=1}^m \frac{\partial J^{(i)}(\theta)}{\partial \theta_j}$$

So now let focus on one sample $J^{(i)}$

2.1 Derivative of Single-Sample loss

Recall

$$h_{\theta}(x^{(i)}) = \sigma(\theta^T x^{(i)}) = \sigma(z^{(i)})$$

$$z^{(i)} = \theta^T x^{(i)} = \sum_{k=1}^n \theta_k x_k^{(i)}$$

$$-\left[y^{(i)} \log h_{\theta}(x^{(i)}) + (1-y^{(i)}) \log (1-h_{\theta}(x^{(i)})) \right]$$

using the chain rule

$$\frac{d}{du} \log(u) = \frac{1}{u} \quad \frac{d}{dx} \log(f(x)) = \frac{1}{f(x)} \frac{df(x)}{dx}$$

$$\text{if } h = h_{\theta}$$

$$\frac{\partial}{\partial \theta_j} (y \log(h)) = y \cdot \frac{1}{h} \cdot \frac{\partial h}{\partial \theta_j} = \frac{y}{h} \frac{\partial h}{\partial \theta_j}$$

$$\begin{aligned} \frac{\partial J^{\psi}}{\partial \theta_j} &= - \left[\frac{y^{(i)}}{h_{\theta}(x^{(i)})} \frac{\partial h_{\theta}(x^{(i)})}{\partial \theta_j} \right. \\ &\quad \left. + (1-y^{(i)}) \frac{1}{1-h_{\theta}(x^{(i)})} \left(-\frac{\partial h_{\theta}(x^{(i)})}{\partial \theta_j} \right) \right] \end{aligned}$$

Simplify signs:

$$\frac{\partial J^{(i)}}{\partial \theta_j} = - \frac{\partial h_{\theta}(x^{(i)})}{\partial \theta_j} \left[\frac{y^{(i)}}{h_{\theta}(x^{(i)})} - \frac{1-y^{(i)}}{1-h_{\theta}(x^{(i)})} \right]$$

Now we need $\frac{\partial h_{\theta}(x^{(i)})}{\partial \theta_j}$

2.2 Derivative of sigmoid

$$h_{\theta}(x^{(i)}) = \sigma(z^{(i)}) = \frac{1}{1 + e^{-z^{(i)}}}$$

We know:

$$\frac{d\sigma(z)}{dz} = \sigma(z)(1 - \sigma(z))$$

So

$$\begin{aligned} \frac{\partial h_{\theta}(x^{(i)})}{\partial \theta_j} &= \frac{d\sigma(z^{(i)})}{dz^{(i)}} \cdot \frac{\partial z^{(i)}}{\partial \theta_j} = \\ &= \sigma(z^{(i)})(1 - \sigma(z^{(i)})) \cdot x_j^{(i)} \\ &= h_{\theta}(x^{(i)}) \underbrace{(1 - h_{\theta}(x^{(i)}))}_{\text{---}} x_j^{(i)} \end{aligned}$$

2.3 plug back

$$\frac{\partial J^{(i)}}{\partial \theta_j} = -h(x^{(i)}) \left(1 - h(x^{(i)}) \right) x_j^{(i)} \left[\frac{y^{(i)}}{n(x^{(i)})} - \frac{1 - y^{(i)}}{1 - h(x^{(i)})} \right]$$

now simplify inside the bracket:

$$\frac{y^{(i)}}{n(x^{(i)})} - \frac{1 - y^{(i)}}{1 - h(x^{(i)})} = \frac{y^{(i)}(1 - h) - h(1 - y^{(i)})}{h(1 - h)}$$

$$= \frac{y^{(i)} - y^{(i)}h - h + y^{(i)}h}{n - h^2}$$

$$\frac{y^{(i)}}{n} - \frac{1 - y^{(i)}}{1 - h} = \boxed{\frac{x^{(i)} - h}{n(1 - h)}}$$

now plugging this back

$$\frac{\partial J^{(i)}}{\partial \theta_j} = -h(x^{(i)}) \left(1 - h(x^{(i)}) \right) x_j^{(i)} \cdot \frac{y^{(i)} - h(x^{(i)})}{h(n^{(i)}) \left(1 - h(x^{(i)}) \right)}$$

$$= -x_j^{(i)} (y^{(i)} - h(x^{(i)})) \cdot$$

$$\frac{\partial J^{(i)}}{\partial \theta_j} = -(y^{(i)} - h(x^{(i)})) x_j^{(i)} = \boxed{(h(x^{(i)}) - y^{(i)}) x_j^{(i)}}$$

2.1 Average over all sample.

$$\frac{\partial J(\theta)}{\partial \theta_j} = \frac{1}{m} \sum_{i=1}^m (h(x^{(i)}) - y^{(i)}) x_j^{(i)}$$

vector form

Let

$$x \in \mathbb{R}^{mn} \quad (\text{rows} = \text{sample})$$

$$\hat{y} = h(x) = \sigma(x\theta) \in \mathbb{R}^m$$

$$y \in \mathbb{R}^m$$

Then

$$\nabla_{\theta} J(\theta) = \frac{1}{m} x^T (\hat{y} - y)$$

This is the core gradient formula used in

• Batch gradient descent/accout

• mini-batch / SGD

• Newton's method / IRLS as the first order term

3. Update the Cost function

Now in this step we need to $\stackrel{1}{\text{decide}}$ which cost function is best suited for us or our model.

- we have

1. Batch gradient decent / accent

2. Mini-batch & SGD

3. Newton's method / IRLS as the $\stackrel{1}{\text{order}} \frac{d}{dx}$

I will only look into

3.1 Batch gradient decent / accent

→ in gradient method we add a learning rate
then + with calculated gradient

General formula

$$\theta := \theta \pm \alpha \nabla_{\theta} J(\theta)$$

$$= \theta \pm \alpha \left[\frac{1}{m} X^T (y - \hat{y}) \right]$$

+ → accent

- → decent

3.2 Newton's Method

(faster, uses Hessian) input sample
 $x_{m \times n}, x^T_{n \times m}$

$$\theta = \theta - H^{-1} \nabla J(\theta) \quad W_{m \times m} = \text{diagonal matrix}$$

where

$$H = \frac{1}{m} x^T W x, \quad \nabla J(\theta) = \frac{1}{m} x^T (\bar{y} - y)$$

Let understand hessian

for now let just forget $\frac{1}{m}$ cause it just average out to a individual sample.

$$\text{so } x^T W x$$

let say

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, \quad W = \begin{bmatrix} w_1 & 0 & 0 \\ 0 & w_2 & 0 \\ 0 & 0 & w_3 \end{bmatrix} \quad \rightarrow \text{Hessian}$$

$$w_i = \bar{y}^{(i)}(1 - y^{(i)}) \quad \bar{y}^{(i)} = h_\theta(x^{(i)})$$

Then $x^T W X =$

$$\begin{bmatrix} x^{(1)} & x^{(2)} & x^{(3)} \end{bmatrix} \begin{bmatrix} \omega^{(1)} & 0 & 0 \\ 0 & \omega^{(2)} & 0 \\ 0 & 0 & \omega^{(3)} \end{bmatrix} \begin{bmatrix} x^{(1)} \\ x^{(2)} \\ x^{(3)} \end{bmatrix}$$

$$\begin{bmatrix} x^{(1)} & x^{(2)} & x^{(3)} \end{bmatrix} \begin{bmatrix} \omega^{(1)} x^{(1)} \\ \omega^{(2)} x^{(2)} \\ \omega^{(3)} x^{(3)} \end{bmatrix}$$

$$\begin{aligned} x^T D x &= x^{(1)}(\omega^{(1)} x^{(1)}) + x^{(2)}(\omega^{(2)} x^{(2)}) + x^{(3)}(\omega^{(3)} x^{(3)}) \\ &= \omega^{(1)}(x^{(1)})^2 + \omega^{(2)}(x^{(2)})^2 + \omega^{(3)}(x^{(3)})^2 \end{aligned}$$

$$\begin{aligned} x^T D x &= \sum \omega^{(i)} (x^{(i)})^2 \\ H &= \frac{1}{m} \left[\sum \omega^{(i)} (x^{(i)})^2 \right] \end{aligned}$$

so this when we have only one feature in our data set now for multiple feature.

- Let's move the i down for fun

$$\left[\sum \omega^{(i)} (x^{(i)})^2 \right] = \sum \omega_i x_i^2$$

so

$$x^T w x = \begin{pmatrix} \sum \omega_1 x_{11}^2 & \sum \omega_1 x_{12}^2 & \dots & \sum \omega_m x_{m1}^2 \\ \sum \omega_1 x_{12} x_{11} & \sum \omega_1 x_{12}^2 & \dots & \sum \omega_m x_{m2}^2 \\ \vdots & & & \\ \sum \omega_m x_{m1} x_{m1} & & & \sum \omega_m x_m^2 \end{pmatrix}$$

which boil down to

$$H = \frac{1}{m} \sum_{i=1}^m \omega_i x_{ij} x_{ik} \quad \omega = \bar{y}(1-\bar{y}) \\ j \& k = 1 \text{ to } m$$

So finally let take a step back and
recall

$$J(\theta) = -\frac{1}{m} \sum_{i=1}^m \left[y^{(i)} \log(\hat{y}^{(i)}) + (1-y^{(i)}) \log(1-\hat{y}^{(i)}) \right]$$

where

$$\hat{y}^{(i)} = h_\theta(x^{(i)}) = \sigma(x^{(i)T}\theta) = \frac{1}{1+e^{-x_i^T\theta}}$$

The First derivative \rightarrow Gradient

$$\nabla_\theta J(\theta) = \frac{1}{m} x^T (\hat{y} - y)$$

$$\hat{y} = \sigma(x\theta)$$

& used in gradient descent/accen

$$\theta = \theta \pm \alpha \frac{1}{m} x^T (\hat{y} - y)$$

Taking 2nd derivative \rightarrow Hessian

$$H(\theta) = \nabla_\theta^2 J(\theta) = \frac{1}{m} x^T w(\theta) x$$

where $w(\theta) = \text{diag}(\hat{y}_i (1-\hat{y}_i))$

Newton's Method Update Rule

$$\theta = \theta - H(\theta)^{-1} \nabla_{\theta} J(\theta)$$

\Rightarrow

$$\theta = \theta - \left(\frac{1}{m} x^T w x \right)^{-1} \left(\frac{1}{m} x^T (\bar{y} - y) \right)$$

$$= \theta - \cancel{\alpha} \left(x^T w x \right)^{-1} \cancel{\frac{1}{\cancel{\alpha}}} \left(x^T (\bar{y} - y) \right)$$

$$\boxed{\theta = \theta - \left(x^T w x \right)^{-1} \cdot x^T (\bar{y} - y)}$$

$$\underbrace{\quad}_{A} \qquad \underbrace{\quad}_{g} \rightarrow \text{gradient}$$

Math Example:→

Manually showing every arithmetic step by using
Newton's Method.

Data set $m = 6$, $d = 3$ with intercept.

for row $i=1 \dots 6$, each $\mathbf{x}_i = [1, x_{i1}, x_{i2}]$

x_0	x_1	x_2	y	$x_0 = \text{intercept}$
1	2	1	0	$x_1, x_2 = \text{feature}$
1	3	1	0	$y = \text{result.}$
1	2	2	0	
1	3	2	0	
1	6	5	1	—
1	7	8	1	—

we run Newton's method with initial $\theta^{(0)} = [0, 0, 0]^T$

$$\cdot z_i = \theta^T x_i$$

$$\cdot h_i = \sigma(z_i) = 1/(1 + e^{-z_i}) = \bar{y}$$

$$\cdot w_i = h_i(1 - h_i) \rightarrow \text{for the diagonals.}$$

$$\cdot \text{Gradient: } g = x^T(y - \bar{y})$$

$$\cdot \text{Hessian: } \nabla^2 l(\theta) = -x^T W x, \text{ we form } A = x^T W x$$

$$\cdot \text{Solve } A \Delta \theta = g$$

$$\cdot \text{ update } \theta \leftarrow \theta + \Delta \theta$$

Iteration 1 (initial $\theta^0 = [0, 0, 0]$)

Step-1 - $z \& h$

$$\text{Since } \theta^{(0)} = 0,$$

$$z = \sum \theta X$$

$$z_1 = 0 \times 1 + 0 \times 2 + 0 \times 1 = 0$$

$$z_2, z_3, z_4, z_5, z_6 = 0$$

Now h

$$h_i = \sigma(z_i) = \sigma(0) = \frac{1}{1 + e^{-0}} = \frac{1}{1+1} = \frac{1}{2}$$

$$h_i = 0.5$$

Step-2 ω

$$\omega_i = h_i(1-h_i) = 0.5 \times 0.5 = 0.25$$

$$(y - h) = \begin{bmatrix} 0 - 0.5 \\ 0 - 0.5 \\ 0 - 0.5 \\ 0 - 0.5 \\ 0 - 1 \\ 0 - 1 \end{bmatrix} = [-0.5, -0.5, -0.5, -0.5, 0.5, 0.5]$$

$$\text{Step-3 - gradient } g = x^T(y - h) = \nabla_{\theta} J(\theta)$$

$$g_0 = \sum_i^{x_0} 1 \cdot (y_i - h_i) = \sum (y - h)$$

$$= (-0.5) + (-0.5) + (-0.5) + (-0.5) \\ + 0.5 + 0.5 = -1.0$$

$$g_i = \sum_i x_{ii} (y_i - h_i)$$

$$\Rightarrow 2 \cdot (-0.5) = -1.0$$

$$3 \cdot (-0.5) = -1.5$$

$$2 \cdot (0.5) = 1.0$$

$$3 \cdot (-0.5) = -1.5$$

$$6 \cdot (0.5) = 3.0$$

$$7 \cdot (0.5) = \underline{\underline{3.5}}$$

$$\text{Sum} = 1.5$$

$$g_2 = 1 \cdot (-0.5) + 1 \cdot (-0.5) + 2 \cdot (0.5) + 2 \cdot (0.5) + 5 \cdot (0.5) + 8 \cdot (0.5) \\ = 3.5$$

$$\text{So } g = \nabla_{\theta} J(\theta) = \begin{bmatrix} -1.0 \\ 1.5 \\ 3.5 \end{bmatrix}$$

$$\text{Step - 4 } A = \mathbf{x}^T \mathbf{w} \mathbf{x}$$

$$\text{for } w_i, w_i = h_i (1-h_i)$$

$$W = \begin{bmatrix} 0.25 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0.25 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0.25 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0.25 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0.25 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0.25 \end{bmatrix}$$

$$A_{ij} = \sum_i x_{ij} w_i x_{ik} \quad \text{where } w_i = 0.25$$

$$A = \mathbf{x}^T \mathbf{w} \mathbf{x} = \begin{bmatrix} 1.5 & 5.75 & 4.75 \\ 5.75 & 27.75 & 25.25 \\ 4.75 & 25.25 & 24.75 \end{bmatrix}$$

$$\text{Step 5 } A \Delta \theta : g \Rightarrow \Delta \theta = A^{-1} g$$

$$A = \begin{bmatrix} 1.5 & 5.75 & 4.75 \\ 5.75 & 27.75 & 25.25 \\ 4.75 & 25.25 & 24.75 \end{bmatrix} \quad \begin{bmatrix} -1.0 \\ 1.5 \\ 3.5 \end{bmatrix} = \begin{bmatrix} -4.1142 \dots \\ 0.82857 \dots \\ 0.08571 \dots \end{bmatrix}$$

Step 6 update θ

$$\theta^{(1)} = \theta^{(0)} + \Delta\theta = \begin{bmatrix} 6 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} -4.1142 \dots \\ 0.82857 \dots \\ 0.08571 \dots \end{bmatrix} = \begin{bmatrix} -4.1142 \dots \\ 0.82857 \dots \\ 0.08571 \dots \end{bmatrix}$$

Now we will repeat the 6 steps again and again

