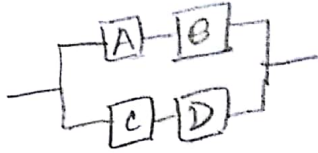


## Task - 2.3

(a)



$$R_s(t) = \prod_{i=1}^N R_i(t)$$

Here,

$$R_A = R_B = R$$

$$R_C = R_D = R$$

$$\text{So, } R_{AB} = R_A \cdot R_B$$

$$\text{again } R_{CD} = R_C \cdot R_D$$



$$R_p(t) = 1 - \prod_{i=1}^N (1 - R_i(t))$$

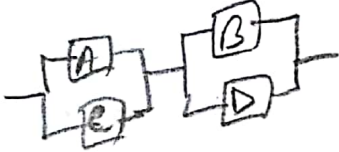
$$\text{So, } R_{sys} = 1 - [(1 - R_{AB})(1 - R_{CD})]$$

$$R_{sys} = 1 - (1 - R_A \cdot R_B)(1 - R_C \cdot R_D) = 1 - (1 - R^2)(1 - R^2)$$

$$= 1 - 1 - R^2 - R^2 + R^4$$

$$R_{sys} = R^4 - 2R^2 = R^2(R^2 - 2)$$

(b)



$$R_p(t) = 1 - \prod_{i=1}^N (1 - R_i(t))$$

Here,

$$R_A = R_C = R$$

$$R_B = R_D = R$$

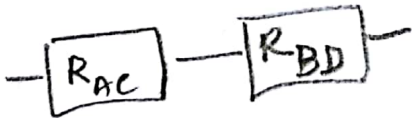
$$R_{p_{AC}} = 1 - (1 - R_A)(1 - R_C) = 1 - (1 - R)(1 - R)$$

$$= 1 - 1 - 2R + R^2$$

$$R_{p_{AC}} = R(R - 2) \quad \text{--- (1)}$$

Similarly,

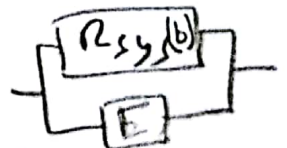
$$R_{p_{BD}} = R(R - 2) \quad \text{--- (2)}$$



$$R_{sys} = R_{p_{AC}} R_{p_{BD}}$$

$$= R(R - 2) \cdot R(R - 2)$$

$$R_{sys} = R^2(R^2 - 4R + 4)$$

(c) From (b)  $\Rightarrow$  we can design system  $\Rightarrow$ 

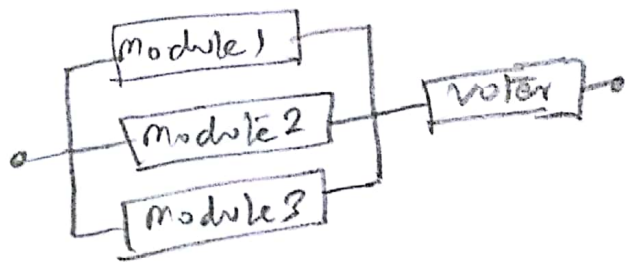
$$R_{sys}(c) = 1 - [(1 - R_{sys}(b))(1 - R_E)]$$

$$= 1 - [(1 - R^2 + 4R^3 - 4R^4)(1 - R)]$$

$$= 1 - [1 - R^4 + 4R^3 - 4R^2 - R + R^5 - 4R^4 + 4R^3]$$

$$R_{sys}(c) = R^4(1 - R^4 + 5R^3 - 8R^2 + 4R)$$

## 1. Formula for the Reliability of TMR:-



cases:

- ① All 3 modules are working
- ② Any 2 modules are working  
2 1 module is failed
- ③ The voter is single-point-of-failure.

Assumption: the voter has a reliability of 1.0.

The TMR reliability is given by:

$$R_{TMR}(t) = R_1(t)R_2(t)R_3(t) + R_1(t)R_2(t)(1-R_3(t)) + R_1(t)R_3(t)(1-R_2(t)) + R_2(t)R_3(t)(1-R_1(t))$$

Now, if  $R_1(t) = R_2(t) = R_3(t) = R(t)$

$$R_{TMR}(t) = R^3(t) + 3R^2(t) - 3R^3(t) = 3R^2(t) - 2R^3(t)$$

## 2. Graph is plotted in Matlab.

TMR system become less reliable than the original system; consisting of a single component,

⇒ system exhausted redundancy, more hardware can possibly fail.

$$R_{TMR}(t) \leq 0.50$$

3) (a) Upper bound for the failure Rate.

Pg - (3).

$$R_{TM}(t) \geq R(t)$$

$$R_v(t) \cdot R_{2:3}(t) \geq R(t) \quad \dots \dots \dots (1)$$

$$R_v(t) \cdot [3R^2(t) - 2R^3(t)] \geq R(t)$$

$$R_v(t) \cdot [3(0.90)^2 - 2(0.90)^3] \geq 0.90$$

$$R_v(t) \cdot (0.972) \geq 0.90$$

$$R_v(t) \geq \frac{0.90}{0.972} \geq 0.93$$

$$e^{-\lambda_v(t)} \geq 0.93$$

$$-\lambda_v(t) \geq \log_e(0.93) \geq -0.0726$$

$$\lambda_v(0.0527) \leq 0.0726$$

$$\lambda_v \leq \frac{0.0726}{0.0527}$$

$$\lambda_v \leq 1.3776$$

$$\boxed{\lambda_v \leq 1.38} \quad (\text{By Round off})$$

3(b) By looking at the solution 3(a) Equation (1) with the increasing value of  $\lambda_v$  at a certain point of time

$$R_v(t) \cdot R_{2:3}(t) < R(t)$$

we can derive

$$\Rightarrow R_v(t) < R(t)$$

$$\Rightarrow e^{-\lambda_v t} < e^{-\lambda t}$$

$$\Rightarrow \boxed{\lambda_v > \lambda}$$

For TM we need

$$R_{2:3}(t) \geq R(t)$$

Where

$\lambda_v$  = Failure Rate of voter.

$\lambda$  = Failure rate of single component.

4.

Explanation for component could be Temporary.

No, the formula not still be correct.

Because in Task 2.5.1 we assume there <sup>are</sup> no component will be fail or one component will be permanently fail.

But Here the TMR system <sup>among</sup> component 1, 2 & 3 will be fail for few time. However after certain point of time <sup>fail</sup> component (1 or 2 or 3) is still going to be working. So, no component fail is permanent. So that is why it is difficult to derive the exact reliability function with Task 2.5.1 formula.