

# Simulation Step 5D Parcels

July 7, 2024

## 1 Prelude

```
[1]: import matplotlib.pyplot as plt
import pulp
import math
import random
import pandas as pd
import numpy as np
import simpy
```

## 2 Utilities

### 2.1 Points and Distances

```
[2]: def dist(p1, p2):
    (x1, y1) = p1
    (x2, y2) = p2
    return int(math.sqrt((x1-x2)**2+(y1-y2)**2))
```

### 2.2 PlotMap

```
[3]: def label(i):
    return (label(i//26-1)+chr(65+i%26)) if i>25 else chr(65+i)
```

```
[4]: def plotMap(G, T=[], P=[], w=None,
    style='r-o', lw=1, ms=3,
    styleT='go', msT=3,
    styleP='b-o', lwP=2, msP=3,
    stylePT='go', msPT=7,
    styleW='ro', msW=9,
    text=None, grid=False, labels=False, scale=False):

    V, E = G

    def round_down(x, level): return (x//level)*level
    def round_up(x, level): return (x//level+1)*level
```

```

xmin = round_down(min([ x for (x, _) in V ]), 100)
xmax = round_up(max([ x for (x, _) in V ]), 100)
ymin = round_down(min([ y for (_, y) in V ]), 100)
ymax = round_up(max([ y for (_, y) in V ]), 100)
dx = xmax-xmin
dy = ymax-ymin
yoffset = (ymax-ymin)//10

fig = plt.gcf()
fig.set_size_inches(4, 4)
plt.xlim(xmin, xmax)
plt.ylim(ymin-yoffset, ymax)

if not grid:
    plt.axis('off')

for e in E:
    p1, p2 = e
    plt.plot( [ p1[0], p2[0] ],
              [ p1[1], p2[1] ],
              style, lw=lw, ms=ms)

if scale:
    # plot 1000m scale
    ybar = ymin-0.9*yoffset
    D = [ (xmin, ybar+50), (xmin, ybar), (xmin+1000, ybar), (xmin+1000,
↪ybar+50) ]
    plt.plot( [ d[0] for d in D ], [ d[1] for d in D ], 'k-', lw=0.5)
    plt.text(xmin+500, ymin-0.7*yoffset, '1000m' ,
↪horizontalalignment='center', size=8)

if labels:
    for i in range(len(V)):
        x, y = V[i]
        plt.text(x+0.0150*dx, y-0.0350*dy, label(i), size=8)

for t in T:
    plt.plot( [ t[0] ], [ t[1] ],
              styleT, ms=msT)

plt.plot( [ p[0] for p in P ],
          [ p[1] for p in P ],
          styleP, lw=lwP, ms=msP)

for p in P:
    if p in T:
        plt.plot( [ p[0] ], [ p[1] ],
                  stylePT, ms=msPT)

```

```

if w is not None:
    plt.plot( [ w[0] ], [ w[1] ],
              styleW, ms=msW)
if text is not None:
    plt.text(xmax, ymin-0.7*yoffset, text, horizontalalignment='right',
↪size=8)
if grid:
    plt.grid()
plt.show()

```

## 2.3 Add Targets

```

[5]: def addTarget(M, T):
    V, E = M
    E = E.copy()
    V = V.copy()
    for t in T:
        minD = math.inf
        minE = None
        for e in E:
            P, Q = e
            distT = dist(P, t)+dist(t, Q)-dist(P, Q)
            if distT < minD:
                minD = distT
                minE = e
        P, Q = minE
        E.remove( (P, Q) )
        E.append( (P, t) )
        E.append( (t, Q) )
        V.append(t)
    return V, E

```

## 2.4 Generate Central Warehouse Location

```

[6]: from statistics import median

def generateWarehouseLocation(M):
    V, _ = M
    xc = median([ x for (x, y) in V ])
    yc = median([ y for (x, y) in V ])
    cloc = (xc, yc)
    minloc = V[0]
    mindist = dist(minloc, cloc)
    for i in range(1, len(V)):
        d = dist(V[i], cloc)
        if d < mindist:
            minloc = V[i]

```

```
mindist = dist(V[i], cloc)
return minloc
```

## 2.5 Time Handling

**Convention:** In this project we measure simulation time in seconds. The simulation will start at 0:00. Time related methods will be added as they are needed.

timestamp(t) generates a timestamp string in the form [dd] hh:mm:ss.d

```
[7]: def timestamp(t):
    t = round(t, 1)
    day = int(t)//(24*3600)
    t = t - day*24*3600
    hour = int(t)//3600
    t = t - hour*3600
    mins = int(t)//60
    t = t - mins*60
    secs = int(t)
    t = int(round((t-secs)*10,1))
    return f"[{day:2d}] {hour:02d}:{mins:02d}:{secs:02d}.{t:1d}"
```

```
[8]: timestamp(24*3600*3+17*3600+615.1)
```

```
[8]: '[ 3] 17:10:15.1'
```

```
[9]: timestamp(24*3600*12+3*3600+122.1)
```

```
[9]: '[12] 03:02:02.1'
```

```
[10]: def day(now):
    return int(now//(24*3600))
```

```
[11]: def nextHour(env, hour):
    beginningOfDay = int(env.now//(24*3600))*24*3600
    timeOfDay = env.now-beginningOfDay
    if hour*3600 > timeOfDay:
        return hour*3600 - timeOfDay
    else:
        return hour*3600 + 24*3600 - timeOfDay
```

## 2.6 Plotting Routines

```
[68]: import scipy.stats as stats

def histPlot(data, title="", xlabel="",
             discrete=False, width=None, height=None):
```

```

minx = min(data)
maxx = max(data)
      = np.mean(data)
      = np.std(data)

fig = plt.figure()
fig.set_figwidth(width if width is not None else 4)
fig.set_figheight(height if height is not None else 2.5)
ax = fig.gca()

if discrete:
    bins = [ i for i in range(maxx+1) ]
    hist=plt.hist(data, bins=bins, density=True)
else:
    hist=plt.hist(data, density=True)
plt.xlabel(xlabel)
plt.ylabel('Density')
plt.title(title)

if discrete:
    poisson=stats.poisson( )
    x = [ i for i in range(maxx+1) ]
    y =[ poisson.pmf(i) for i in range(maxx+1) ]
    ax.plot(x, y, lw=1, color='red')
else:
    x = np.linspace(minx, maxx, 100)
    y = [ stats.norm(loc= , scale= ).pdf(p) for p in x]
    ax.plot(x, y, lw=1, color='red')

ax.axvline(x= , color='red')
maxy = max(max(y), max(hist[0]))
ax.text(maxx, maxy,
        f'={:2.2f}\n={:2.2f}',
        ha='right', va='top',
        color='red', fontsize=12)

ax.grid(True)
plt.show()

def dailyPlot(data,
              title="", ylabel="",
              width=None, height=None):

    days = len(data)

    fig = plt.figure()
    fig.set_figwidth(width if width is not None else 6)

```

```

fig.set_figheight(height if height is not None else 2)

ax = fig.gca()
diff = (max(data)-min(data))*0.1
ymin = int(math.floor(min(data)-diff))
ymax = int(math.ceil(max(data)+diff))
ax.set_xlim(-0.5, days-1+0.5)
ax.set_ylim(ymin, ymax)
ax.grid(True)

ms = 2 if len(data)>=100 else 3
lw = 0.5 if len(data)>=100 else 1

x = np.arange(0, len(data))
y = np.array([ y for y in data ])
b, m = np.polynomial.polynomial.polyfit(x, y, 1)

plt.plot(x, y, 'bo-', linewidth=lw, markersize=ms)
plt.plot(x, m*x+b, 'r-')

plt.xlabel('Day')
plt.ylabel(ylabel)
plt.title(title)
plt.show()

```

### 3 Finding Shortest Path (as before)

```

[13]: def pathLength(P):
        return 0 if len(P)<=1 else \
            dist(P[0], P[1])+pathLength(P[1:])

```

```

[14]: def shortestPath(M, A, B):

    def h(p):
        return pathLength(p)+dist(p[-1],B)

    # candidates C are pairs of the path so far and
    # the heuristic function of that path,
    # sorted by the heuristic function, as maintained by
    # insert function
    def insert(C, p):
        hp = h(p)
        c = (p, hp)
        for i in range(len(C)):
            if C[i][1]>hp:
                return C[:i]+[c]+C[i:]

```

```

    return C+[c]

V, E = M
assert(A in V and B in V)
C = insert([], [A])

while len(C)>0:
    # take the first candidate out of the list of candidates
    path, _ = C[0]
    C = C[1:]
    if path[-1]==B:
        return path
    else:
        for (x, y) in E:
            if path[-1]==x and y not in path:
                C = insert(C, path+[y])
            elif path[-1]==y and x not in path:
                C = insert(C, path+[x])

return None

```

## 4 Finding Short Delivery Route (as before)

### 4.1 Greedy Algorithm

```

[15]: def FW(M):

    V, E = M

    n = len(V)
    d = [ [ math.inf for j in range(n) ] for i in range(n) ]
    p = [ [ None for j in range(n) ] for i in range(n) ]

    for (A, B) in E:
        a = V.index(A)
        b = V.index(B)
        d[a][b] = d[b][a] = dist(A, B)
        p[a][b] = [A, B]
        p[b][a] = [B, A]

    for i in range(n):
        d[i][i] = 0
        p[i][i] = [V[i]]

    for k in range(n):
        for i in range(n):
            for j in range(n):
                dk = d[i][k] + d[k][j]

```

```

        if d[i][j] > dk:
            d[i][j] = dk
            p[i][j] = p[i][k][:-1] + p[k][j]

    return d, p

```

```

[16]: def createLoopG(M, T, timing=False):

    def makeLoop(L, V, P):
        loop = []
        for i in range(len(L)-1):
            A = L[i]
            B = L[i+1]
            a = V.index(A)
            b = V.index(B)
            sub = P[a][b]
            loop += sub if len(loop)==0 else sub[1:]
        return loop

    if timing:
        start_time = time.time()
        last_time = time.time()

    V, E = M
    D, P = FW(M)    # note these are the distances between all vertices in M
    ↪ (and T)
    W = T[0]
    customers = T[1:]
    if len(T)==1:
        L = T
    elif len(T)<=3:
        L = T + [T[0]]
    else:
        L = T[:3]+[T[0]]
        T = T[3:]
        while len(T)>0:
            minExt = math.inf
            minInd = None
            selInd = None
            for k in range(len(T)):
                C = T[k]
                c = V.index(C)
                for i in range(0, len(L)-1):
                    A = L[i]
                    B = L[i+1]
                    a = V.index(A)
                    b = V.index(B)

```



```

        ext = D[a][c] + D[c][b] - D[a][b]
        if ext < minExt:
            minExt, minInd, selInd = ext, i+1, k
    L = L[:minInd]+[T[selInd]]+L[minInd:]
    T = T[:selInd]+T[selInd+1:]

if timing:
    print(f"createLoopG:    {time.time()-start_time:6.2f}s")

return makeLoop(L, V, P)

```

## 5 Finding Optimal Delivery Route

### 5.1 Iterative Integer Programming

```

[17]: def createTables(M, T):

    def reverse(P):
        return [ P[-i] for i in range(1,len(P)+1) ]

    def index(x, L):
        for i in range(len(L)):
            if x==L[i]:
                return i
        return None

    n = len(T)
    d = [ [ math.inf for t in T ] for t in T ]
    p = [ [ None for t in T ] for t in T ]
    for i in range(n):
        d[i][i] = 0
        p[i][i] = [ T[i] ]
    for i in range(n):
        for j in range(n):
            if p[i][j] is None:
                s = shortestPath(M, T[i], T[j])
                d[i][j] = d[j][i] = pathLength(s)
                p[i][j] = s
                p[j][i] = reverse(s)
                for m in range(len(s)-1):
                    smi = index(s[m], T)
                    if smi is None:
                        continue
                    for l in range(m+1, len(s)):
                        sli = index(s[l], T)
                        if sli is None:
                            continue

```

```

        sub = s[m:l+1]
        if p[smi][sli] is None:
            p[smi][sli] = sub
            p[sli][smi] = reverse(sub)
            d[smi][sli] = d[sli][smi] = pathLength(sub)

    return d,p

```

```

[18]: def roundtrips(x, n):

    def isElem(x, l):
        for i in range(len(l)):
            if l[i]==x:
                return True
        return False

    def startpoint(trips):
        for i in range(n):
            for t in trips:
                if isElem(i, t):
                    break
            else:
                return i

    def totalLength(trips):
        s=0
        for i in range(0, len(trips)):
            s += len(trips[i])-1
        return s

    trips = []
    while totalLength(trips)<n:
        start = startpoint(trips)
        trip = [ start ]
        i = start
        while len(trip) < n-totalLength(trips):
            for j in range(0, n):
                if pulp.value(x[i][j])==1:
                    trip.append(j)
                    i=j
                    break
            if pulp.value(x[trip[-1]][start])==1:
                trip.append(start)
                break
        trips.append(trip)
    return sorted(trips, key=lambda t: len(t), reverse=True)

```

```

[19]: import time

def createLoop(M, T, timing=False):

    if timing:
        start_time = last_time = time.time()

    D, P = createTables(M, T)    # These are the distances between customers and
    ↪warehouse only

    if timing:
        print(f"createTables: {time.time()-start_time:6.2f}s")
        last_time = time.time()

    n = len(T)
    # create variables
    x = pulp.LpVariable.dicts("x", ( range(n), range(n) ),
                              lowBound=0, upBound=1, cat=pulp.LpInteger)

    # create problem
    prob = pulp.LpProblem("Loop",pulp.LpMinimize)
    # add objective function
    prob += pulp.lpSum([ D[i][j]*x[i][j]
                        for i in range(n) for j in range(n) ])

    # add constraints
    constraints=0
    for j in range(n):
        prob += pulp.lpSum([ x[i][j] for i in range(n) if i!=j ]) ==1
        constraints += n
    for i in range(n):
        prob += pulp.lpSum([ x[i][j] for j in range(n) if i!=j ]) ==1
        constraints += n
    for i in range(n):
        for j in range(n):
            if i!=j:
                prob += x[i][j]+x[j][i] <= 1
                constraints += 1

def cycles(k, n):
    if k==1:
        return [ [i] for i in range(0,n) ]
    else:
        sc=cycles(k-1, n)
        all=[]
        for c in sc:
            for i in range(0,n):
                if c.count(i)==0:
                    all.append(c+[i])

```

```

        return all

    for k in range(3, 4):
        cycs=cycles(k,n)
        for c in cycs:
            c.append(c[0])
            prob+=pulp.lpSum([ x[c[i]][c[i+1]] for i in range(0,k)]) <= k-1
            constraints += 1

    # initialise solver
    solvers = pulp.listSolvers(onlyAvailable=True)
    solver = pulp.getSolver(solvers[0], msg=0, timeLimit=2)
    res = prob.solve(solver)

    if timing:
        print(f"Solver:           {time.time()-last_time:6.2f}s {constraints:6,d}␣
↪Constraints")
        last_time = time.time()

    trips = roundtrips(x, n)
    while len(trips)>1:
        longest = max([ len(t) for t in trips ])
        for t in trips:
            if len(t)<longest:
                prob += pulp.lpSum([ x[t[i]][t[i+1]] + x[t[i+1]][t[i]]
                                     for i in range(0,len(t)-1) ]) <=␣
↪len(t)-2
                constraints += 1
            else:
                longest = math.inf

        res = prob.solve(solver)

        if timing:
            print(f"Solver:           {time.time()-last_time:6.2f}s {constraints:
↪6,d} Constraints")
            last_time = time.time()

        trips = roundtrips(x, n)
        trip = trips[0]
        # print(trip)
        loop = []
        for k in range(len(trip)-1):
            sub = P[trip[k]][trip[k+1]]
            loop += sub if len(loop)==0 else sub[1:]

    if timing:

```

```

        print(f"createLoop:      {time.time()-start_time:6.2f}s")

    return loop

```

## 6 Class Recorder

We will use a class Recorder as a reference point for capturing data during the simulation. There will be only one recorder. It will be created at the beginning of every simulation run. Every entity will carry a reference to the Recorder.

```

[20]: import time

class Recorder:

    def __init__(self, env, M, W, C, D, days,
                  log=False, plot=False, timing=False):
        self.env = env
        self.M = M
        self.W = W
        self.C = C
        self.D = D

        self.parcels = sum([ len(d) for d in D ])
        self.days = days
        self.log = log
        self.plot = plot

        # create a data frame for time records per working day
        self.daily = pd.DataFrame()
        self.daily['begin work at'] = [None]*days
        self.daily['end work at'] = [None]*days
        self.daily['tour length'] = [None]*days
        self.daily['parcels arrived'] = [0]*days
        self.daily['parcels out for delivery'] = [0]*days
        self.daily['parcels returned from delivery'] = [0]*days
        self.daily['parcels delivered'] = [0]*days
        self.daily['parcels left over'] = [None]*days

        self.parcel = pd.DataFrame()
        self.parcel['arrived at'] = [None]*self.parcels
        self.parcel['delivered at'] = [None]*self.parcels

    def trace(self, event):
        if self.log:
            print(timestamp(self.env.now), event)

```

```

def recordDriverBeginsWork(self):
    self.trace("Driver arrives for work")
    self.daily.at[day(self.env.now), 'begin work at'] = int(round(self.env.
↪now))

def recordDriverEndsWork(self):
    self.trace("Driver goes home")
    self.daily.at[day(self.env.now), 'end work at'] = int(round(self.env.
↪now))

def recordTourLength(self, length):
    self.daily.at[day(self.env.now), 'tour length'] = int(length)

def recordParcelArrived(self, parcel):
    today = day(self.env.now)
    self.daily.at[today, 'parcels arrived'] += 1
    self.parcel.at[parcel.i, 'arrived at'] = today

def recordParcelOutForDelivery(self, parcel):
    self.daily.at[day(self.env.now), 'parcels out for delivery'] += 1

def recordParcelReturnedFromDelivery(self, parcel):
    self.daily.at[day(self.env.now), 'parcels returned from delivery'] += 1

def recordParcelDelivered(self, parcel):
    today = day(self.env.now)
    self.daily.at[today, 'parcels delivered'] += 1
    self.parcel.at[parcel.i, 'delivered at'] = today

def recordParcelsLeftOver(self, n):
    self.trace(f"{n:d} parcels left over for next day")
    self.daily.at[day(self.env.now), 'parcels left over'] = n

def finish(self):
    # simulation is finished for good
    # by removing the simulation environment we can
    # pickle recorder
    self.env = None
    self.daily['working time'] = (self.daily['end work at']-self.
↪daily['begin work at'])//60
    self.daily['cost'] = self.daily['working time'].apply(lambda x: max(60,
↪x*30/60))
    self.daily['cost'] += 0.08/1000*self.daily['tour length']
    self.parcel['delivery time'] = self.parcel['delivered at']-self.
↪parcel['arrived at']

def histWorkingTime(self):

```

```

        histPlot(self.daily['working time'],
                  xlabel='Working Time [min]',
                  title=f'Daily Working Time ({self.days:d} days)')

    def plotWorkingTime(self):
        dailyPlot(self.daily['working time'],
                  ylabel='Working Time [min]',
                  title=f'Daily Working Time ({self.days:d} days)')

    def histTourLength(self):
        histPlot(self.daily['tour length'],
                  xlabel='Tour Length [m]',
                  title=f'Daily Tour Length ({self.days:d} days)')

    def plotTourLength(self):
        dailyPlot(self.daily['tour length'],
                  ylabel='Tour Length [m]',
                  title=f'Daily Tour Length ({self.days:d} days)')

    def histDailyCost(self):
        histPlot(self.daily['cost'],
                  xlabel='DailyCost [€]',
                  title=f'Daily Cost ({self.days:d} days)')

    def plotDailyCost(self):
        dailyPlot(self.daily['cost'],
                  ylabel='Daily Cost [€]',
                  title=f'Daily Cost ({self.days:d} days)')

    def histParcelsArrived(self):
        histPlot(self.daily['parcels arrived'], discrete=True,
                  xlabel='Parcels Arrived',
                  title=f'Parcels Arrived Daily ({self.days:d} Days)')

    def plotParcelsArrived(self):
        dailyPlot(self.daily['parcels arrived'],
                  ylabel='Number of Parcels',
                  title=f'Parcels Arrived Daily ({self.days:d} Days)')

    def histParcelsOutForDelivery(self):
        histPlot(self.daily['parcels out for delivery'], discrete=True,
                  xlabel='Parcels Arrived',
                  title=f'Parcels Daily out for Delivery ({self.days:d} Days)')

    def plotParcelsOutForDelivery(self):
        dailyPlot(self.daily['parcels out for delivery'],
                  ylabel='Number of Parcels',

```

```

        title=f'Parcels Daily out for Delivery ({self.days:d} Days)')

    def histParcelsReturnedFromDelivery(self):
        histPlot(self.daily['parcels returned from delivery'], discrete=True,
                  xlabel='Parcels Arrived',
                  title=f'Parcels Daily Returned From Delivery ({self.days:d}
↪Days)')

    def plotParcelsReturnedFromDelivery(self):
        dailyPlot(self.daily['parcels returned from delivery'],
                  ylabel='Number of Parcels',
                  title=f'Parcels Daily Returned From Delivery ({self.days:d}
↪Days)')

    def histParcelsDelivered(self):
        histPlot(self.daily['parcels delivered'], discrete=True,
                  xlabel='Left-Over Parcels',
                  title=f'Parcels Delivered Daily ({self.days:d} Days)')

    def plotParcelsDelivered(self):
        dailyPlot(self.daily['parcels delivered'],
                  ylabel='Number of Parcels',
                  title=f'Parcels Delivered Daily ({self.days:d} Days)')

    def histParcelsLeftOver(self):
        histPlot(self.daily['parcels left over'], discrete=True,
                  xlabel='Left-Over Parcels',
                  title=f'Parcels Daily Left-Overs ({self.days:d} Days)')

    def plotParcelsLeftOver(self):
        dailyPlot(self.daily['parcels left over'],
                  ylabel='Number of Parcels',
                  title=f'Parcels Daily Left-Overs ({self.days:d} Days)')

    def histParcelDeliveryTime(self):
        histPlot(self.parcel['delivery time'], discrete=True,
                  xlabel='Days',
                  title=f'Parcel Delivery Time in Days ({self.parcels:3,d}
↪Parcels)')

```

## 7 Class Customer

```

[21]: class Customer:

    def __init__(self, rec, id, location):
        self.rec = rec

```



```

        self.id = id
        self.location = location
        self.atHome = True
        self.answersDoor = False
        self.parcelsReceived = []
        rec.env.process(self.process())

def __str__(self):
    return f"Customer {self.id:d} at {str(self.location):s}"

def leaveHouse(self):
    assert(self.atHome and not self.answersDoor)
    # self.rec.trace(str(self)+" leaves house")
    self.atHome = False

def returnHome(self):
    assert(not self.atHome)
    # self.rec.trace(str(self)+" returns home")
    self.atHome = True

def answerDoor(self):
    if self.atHome:
        answerTime = random.expovariate(1/AVERAGE_TIME_ANSWER_DOOR)
        if answerTime < WAIT_TIME_IF_CUSTOMER_DOESNT_ANSWER_DOOR:
            yield self.rec.env.timeout(answerTime)
            self.rec.trace(str(self)+" answers door")
            self.answersDoor = True
        else:
            yield self.rec.env.
↪ timeout(WAIT_TIME_IF_CUSTOMER_DOESNT_ANSWER_DOOR)
            self.rec.trace(str(self)+" to slow to answer the door")
            self.answersDoor = False
    else:
        yield self.rec.env.timeout(WAIT_TIME_IF_CUSTOMER_DOESNT_ANSWER_DOOR)
        self.rec.trace(str(self)+" not at home")
        self.answersDoot = False

def acceptParcel(self, parcel):
    assert(self.answersDoor)
    self.parcelsReceived += [parcel]
    self.rec.trace(str(self)+" accepts "+str(parcel))
    self.rec.recordParcelDelivered(parcel)

def signOff(self):
    assert(self.answersDoor)
    self.rec.trace(str(self)+" signs off")
    self.answersDoor = False

```

```

def process(self):
    yield self.rec.env.timeout(nextHour(self.rec.env, 8))
    while day(self.rec.env.now)<self.rec.days:
        # in a refinement we may use random times
        self.leaveHouse()
        returnTime = 22 if random.random()<CUSTOMER_NOT_AT_HOME else 18
        yield self.rec.env.timeout(nextHour(self.rec.env, returnTime))
        self.returnHome()
        yield self.rec.env.timeout(nextHour(self.rec.env, 8))

```

## 8 Class Parcel

Parcels follow through a sequence of states: - processing - in transit (from manufacture to distribution centre) - arrived in distribution centre - ready for delivery - out for delivery - customer not present - returned to distribution centre - delivered

```

[22]: class Parcel:

    def __init__(self, rec, i, day, cust):
        self.rec = rec
        self.i = i
        self.arrival = day
        self.cust = cust
        self.status = [ ] # status record and
        self.timing = [ ] # timing

    def __str__(self):
        return f"Parcel {self.i:d} for cust {self.cust.id:d}"

    def index(self):
        return self.i

    def destination(self):
        return self.cust.location

    def __reg(self, state):
        self.status += [ state ]
        self.timing += [ self.rec.env.now ]
        self.rec.trace(str(self)+" "+state)

    def arrivedAtDeliveryCentre(self):
        self.__reg('arr at delivery centre')
        self.rec.recordParcelArrived(self)

    def outForDelivery(self):
        self.__reg('out for delivery')

```

```

        self.rec.recordParcelOutForDelivery(self)

    def returnFromDelivery(self):
        self.__reg('return from delivery')
        self.rec.recordParcelReturnedFromDelivery(self)

```

## 9 Class Driver

```

[23]: class Driver:

    def __init__(self, rec, DC):
        self.rec = rec
        self.DC = DC
        self.location = None
        self.parcels = None
        self.tour = None
        self.rec.env.process(self.process())

    # activity
    def __drive(self, target):
        assert(self.tour[0] == self.location)
        while self.location != target:
            d = dist(self.location, self.tour[1])
            yield self.rec.env.timeout(d / AVERAGE_SPEED)
            self.location = self.tour[1]
            self.tour = self.tour[1:]
        assert(self.tour[0] == self.location == target)

    def arriveForWork(self):
        self.location = self.DC.W
        self.parcels = []
        self.returns = []
        self.tour = [ self.DC.W ]
        # self.rec.trace("Driver arrives for work")
        self.rec.recordDriverBeginsWork()

    def goesHome(self):
        self.location = None
        self.parcels = None
        self.returns = None
        self.tour = None
        # self.rec.trace("Driver goes home")
        self.rec.recordDriverEndsWork()

    def leaveForDelivery(self, tour, parcels, addresses):

```

```

self.tour, self.parcels = tour, parcels
self.rec.trace(f"Driver leaves for delivery "
               f"of {len(parcels):d} parcels "
               f"to {len(addresses):d} customers")
self.rec.trace(f"Length of delivery tour: {pathLength(tour):,d}m")
if self.rec.plot:
    plotMap(self.rec.M, T=addresses, P=tour, w=tour[0],
            text=f"Day {day(self.rec.env.now):d}:, {pathLength(tour):
↪,d}m")

def process(self):
    yield self.rec.env.timeout(nextHour(self.rec.env, 18))
    while day(self.rec.env.now)<self.rec.days:
        self.arriveForWork()
        tour, parcels, addresses = self.DC.sendForDelivery()
        if len(parcels)==0:
            self.rec.trace("Nothing to do today")
            self.rec.recordTourLength(0)
        else:
            yield self.rec.env.timeout(PREP_TIME_PER_PARCEL*len(parcels))
            self.rec.recordTourLength(pathLength(tour))
            self.leaveForDelivery(tour, parcels, addresses)
            while len(self.parcels)>0:
                # drive to customer
                custLocation = self.parcels[0].destination()
                cust = self.parcels[0].cust
                self.rec.trace("Driver drives to "+str(cust))
                yield from self.__drive(custLocation)
                self.rec.trace("Driver arrived at "+str(cust))
                # call at customer
                yield from cust.answerDoor()

            if cust.answersDoor:
                while len(self.parcels)>0 and \
                    custLocation == self.parcels[0].destination():
                    cust.acceptParcel(self.parcels[0])
                    yield self.rec.env.timeout(random.expovariate(1/10))
                    self.parcels = self.parcels[1:]
                cust.signOff()
                yield self.rec.env.timeout(random.expovariate(1/10))
            else:
                while len(self.parcels)>0 and \
                    custLocation == self.parcels[0].destination():
                    self.returns += [self.parcels[0]]
                    self.parcels = self.parcels[1:]

    # return to delivery centre

```

```

        self.rec.trace("Driver returns to delivery centre")
        yield from self.__drive(self.DC.W)
        self.rec.trace("Driver arrived at delivery centre")

        for parcel in self.returns:
            self.DC.returnFromDelivery(parcel)
            yield self.rec.env.timeout(RETURN_TIME_PER_PARCEL)

        self.rec.recordParcelsLeftOver(len(self.DC.parcels)+len(self.DC.
↪leftOver))

        yield self.rec.env.timeout(600)

        self.goesHome()

        yield self.rec.env.timeout(nextHour(self.rec.env, 18))

```

## 10 Class Delivery Centre

```

[24]: class DeliveryCentre:

    def __init__(self, rec, M, W, limit):
        self.rec = rec
        self.M = M
        self.W = W
        self.limit = limit

        self.leftOver = []      # list of parcels
        self.parcels = []       # list of parcels scheduled for delivery
        self.dest = []          # list of unique customer destinations
        self.tour = [self.W]    # tour planned for delivery

    def __accept(self, parcel):
        custLoc = parcel.destination()
        if custLoc not in self.dest:
            MT = addTargets(self.M, self.dest + [custLoc])
            SH = createLoopG(MT, [self.W] + self.dest + [custLoc])
            if pathLength(SH)<self.limit:
                self.parcels.append(parcel)
                self.dest += [custLoc]
                self.tour = SH
            else:
                self.leftOver.append(parcel)
        else:
            self.parcels.append(parcel)

```

```

def acceptParcel(self, parcel):
    parcel.arrivedAtDeliveryCentre()
    self.__accept(parcel)

def sendForDelivery(self):
    parcels = []
    tour = self.tour
    addresses = []

    # pick parcels in sequence to be delivered
    for i in range(1, len(tour)-1):
        dest = tour[i]
        for p in self.parcels:
            if p.destination() == dest and p not in parcels:
                parcels += [p]
                p.outForDelivery()
            if dest not in addresses:
                addresses += [dest]

    # arrange the left overs for next day
    L = self.leftOver
    self.tour = [self.W]
    self.parcels = []
    self.leftOver = []
    self.dest = []
    for p in L:
        self.__accept(p)

    return tour, parcels, addresses

def returnFromDelivery(self, parcel):
    parcel.returnFromDelivery()
    self.__accept(parcel)

def getInventory(self):
    return len(self.parcels)+len(self.leftOver)

```

## 11 Simulation

### 11.1 Parameters from Specification

The proportion of customers that for whatever are not at home or return home late

```
[25]: CUSTOMER_NOT_AT_HOME = 0.5 # 10%
```

The maximum bike range. This is passed as parameter to the Delivery Centre and taken into account for the daily tour planning

[26]: BIKE\_RANGE = 40000

The time required for driving is based on the distance between way points at an average speed of 15km/h.

[27]: AVERAGE\_SPEED = 15/3.6

The **cumulative preparation time** (route planning and sorting of the parcels in the delivery order and packing the cargo-bike) is assumed to be 50 sec per parcel to be delivered.

[28]: PREP\_TIME\_PER\_PARCEL = 50

**Additional assumption:** The time to **process returned parcels** in the delivery centre is 30 sec per parce.

[29]: RETURN\_TIME\_PER\_PARCEL = 30

The average time to answer the door.

[30]: AVERAGE\_TIME\_ANSWER\_DOOR = 40

[31]: WAIT\_TIME\_IF\_CUSTOMER\_DOESNT\_ANSWER\_DOOR = 60

## 11.2 Generate Input Data

```
[32]: def generateDeliveries(p, C, days, seed=0):
    ## p is the average number of parcels per day per customer
    ## C is the number of customers to be served
    ## days is the number of days for which data are to be generated.
    random.seed(seed)
    deliveries = [ [ ] for _ in range(days) ]
    for c in range(C):
        arr = 0
        while True:
            arr += random.expovariate(p)
            day = int(arr)
            if day >= days:
                break
            deliveries[day].append(c)
    return deliveries
```

## 11.3 Simulation Routine

```
[33]: def simulation(M, W, C, p=0.2, days=10, seed=0,
    log=False, plot=False, timing=False):

    random.seed(seed)
    D = generateDeliveries(p, len(C), days, seed)
```

```

env = simpy.Environment()
rec = Recorder(env, M, W, C, D, days,
               log=log, plot=plot, timing=timing)

print(f"Simulating delivery of {sum([len(d) for d in D]):d} parcels "
      f"over {len(D):d} days to {len(C):d} customers")

CUSTOMERS = []
for i in range(len(C)):
    CUSTOMERS.append(Customer(rec, i, C[i]))

DC = DeliveryCentre(rec, M, W, BIKE_RANGE)
Z = Driver(rec, DC)
PARCELS = []

def parcelGeneratorProcess(env, rec, D, C):
    for day in range(len(D)):
        yield env.timeout(nextHour(env, 17.00))
        for c in D[day]:
            cust = CUSTOMERS[c]
            parcel = Parcel(rec, len(PARCELS), day, cust)
            PARCELS.append(parcel)
            DC.acceptParcel(parcel)

env.process(parcelGeneratorProcess(env, rec, D, C))
env.run()

rec.finish()

if DC.getInventory()>0:
    print(f"Delivery Centre Inventory: {DC.getInventory():d} parcels")

return rec

```

## 11.4 Test Statistics

### 11.4.1 Using Simple Data

```

[34]: import pickle
      with open('simpleData.pickled', 'rb') as f:
          M, C = pickle.load(f)

```

```

[35]: W = generateWarehouseLocation(M)

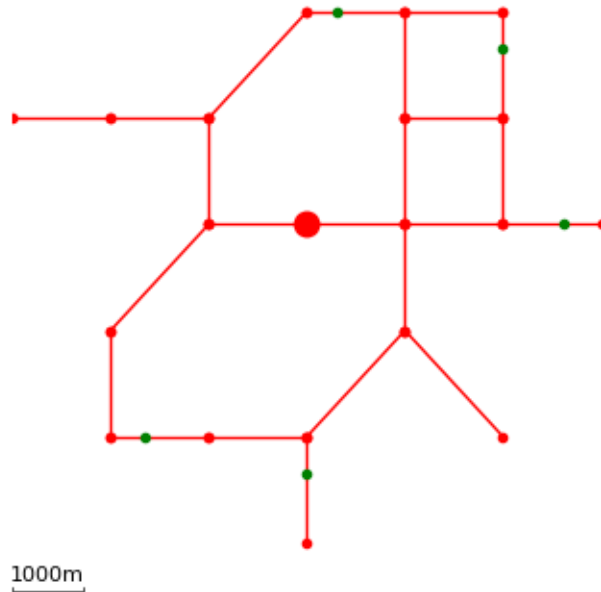
```

```

[36]: plotMap(M, T=C, w=W, scale=True)

```





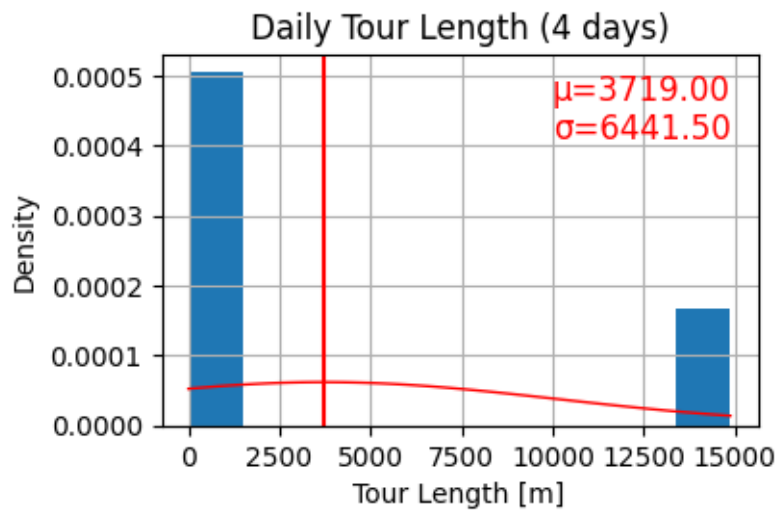
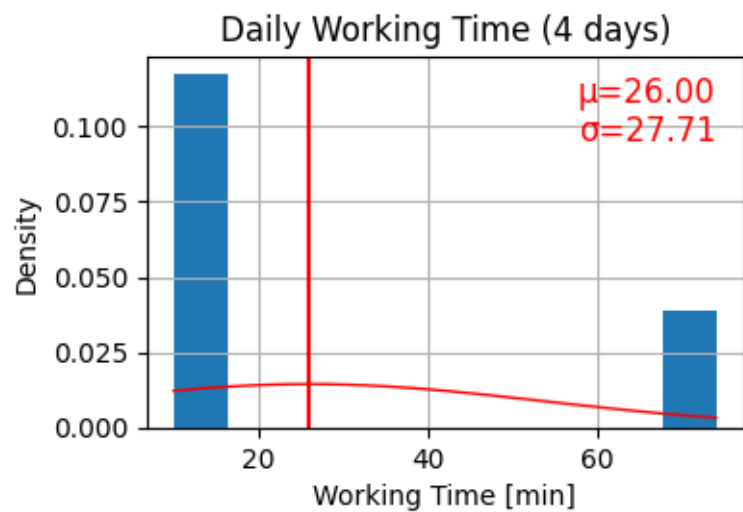
```
[37]: rec1 = simulation(M, W, C, p=0.15, days=4, log=True)
```

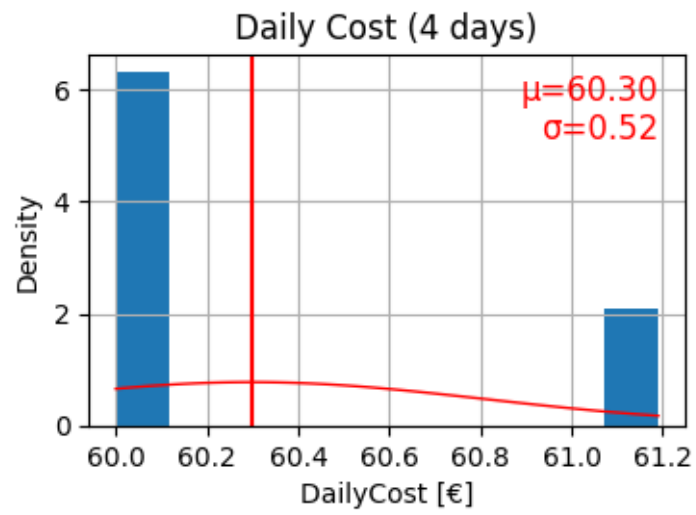
Simulating delivery of 2 parcels over 4 days to 5 customers

```
[ 0] 18:00:00.0 Driver arrives for work
[ 0] 18:00:00.0 Nothing to do today
[ 0] 18:00:00.0 0 parcels left over for next day
[ 0] 18:10:00.0 Driver goes home
[ 1] 18:00:00.0 Driver arrives for work
[ 1] 18:00:00.0 Nothing to do today
[ 1] 18:00:00.0 0 parcels left over for next day
[ 1] 18:10:00.0 Driver goes home
[ 2] 18:00:00.0 Driver arrives for work
[ 2] 18:00:00.0 Nothing to do today
[ 2] 18:00:00.0 0 parcels left over for next day
[ 2] 18:10:00.0 Driver goes home
[ 3] 17:00:00.0 Parcel 0 for cust 2 arr at delivery centre
[ 3] 17:00:00.0 Parcel 1 for cust 4 arr at delivery centre
[ 3] 18:00:00.0 Driver arrives for work
[ 3] 18:00:00.0 Parcel 0 for cust 2 out for delivery
[ 3] 18:00:00.0 Parcel 1 for cust 4 out for delivery
[ 3] 18:01:40.0 Driver leaves for delivery of 2 parcels to 2 customers
[ 3] 18:01:40.0 Length of delivery tour: 14,876m
[ 3] 18:01:40.0 Driver drives to Customer 2 at (4929, 7300)
[ 3] 18:22:21.0 Driver arrived at Customer 2 at (4929, 7300)
[ 3] 18:23:21.0 Customer 2 at (4929, 7300) not at home
[ 3] 18:23:21.0 Driver drives to Customer 4 at (8167, 4500)
[ 3] 18:47:30.2 Driver arrived at Customer 4 at (8167, 4500)
```

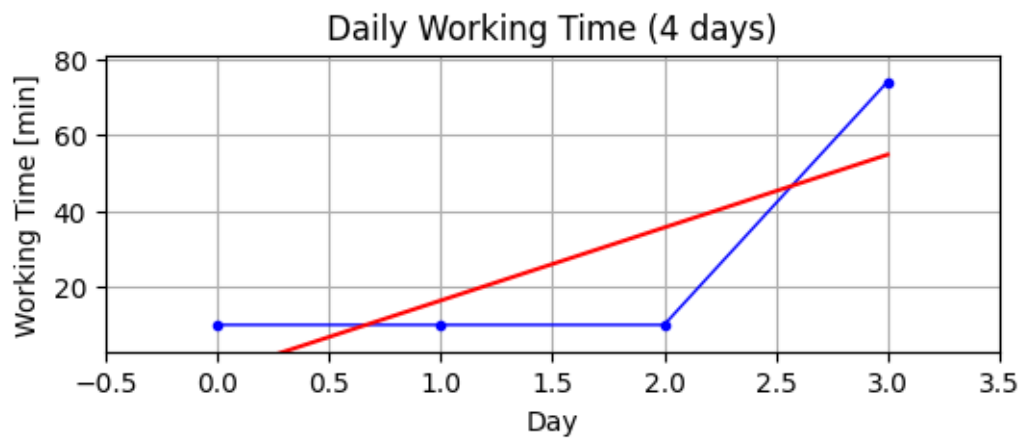
```
[ 3] 18:48:07.9 Customer 4 at (8167, 4500) answers door
[ 3] 18:48:07.9 Customer 4 at (8167, 4500) accepts Parcel 1 for cust 4
[ 3] 18:48:32.3 Customer 4 at (8167, 4500) signs off
[ 3] 18:49:06.3 Driver returns to delivery centre
[ 3] 19:03:46.4 Driver arrived at delivery centre
[ 3] 19:03:46.4 Parcel 0 for cust 2 return from delivery
[ 3] 19:04:16.4 1 parcels left over for next day
[ 3] 19:14:16.4 Driver goes home
Delivery Centre Inventory: 1 parcels
```

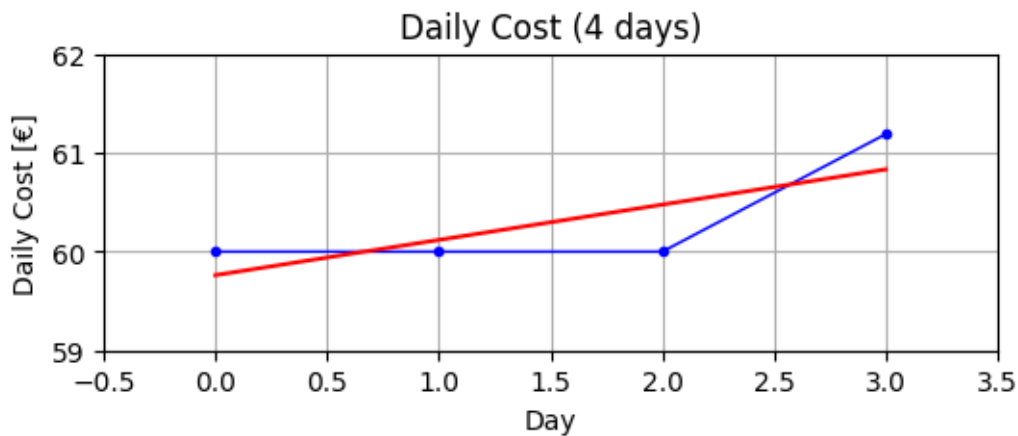
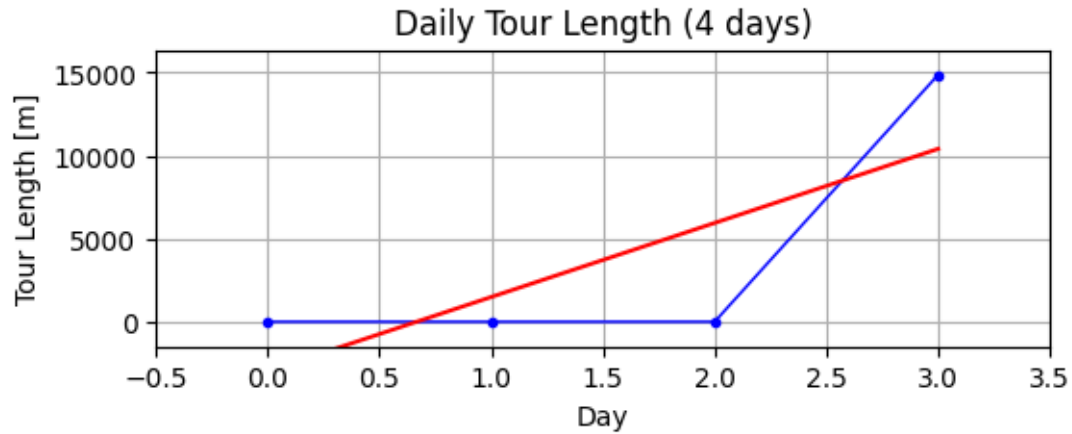
```
[38]: rec1.histWorkingTime()
      rec1.histTourLength()
      rec1.histDailyCost()
```





```
[39]: rec1.plotWorkingTime()  
      rec1.plotTourLength()  
      rec1.plotDailyCost()
```

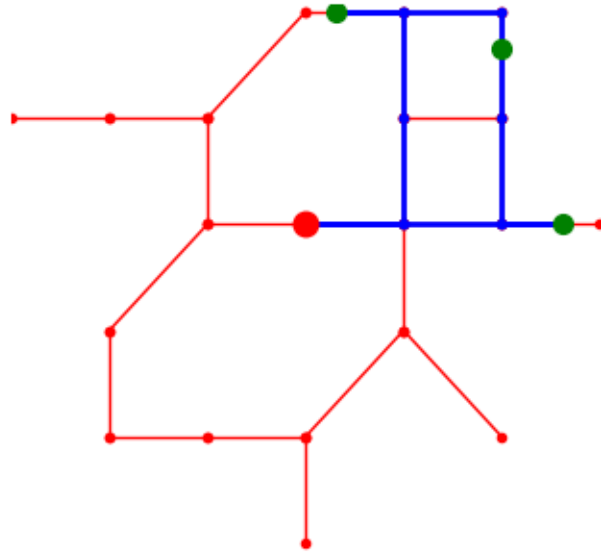




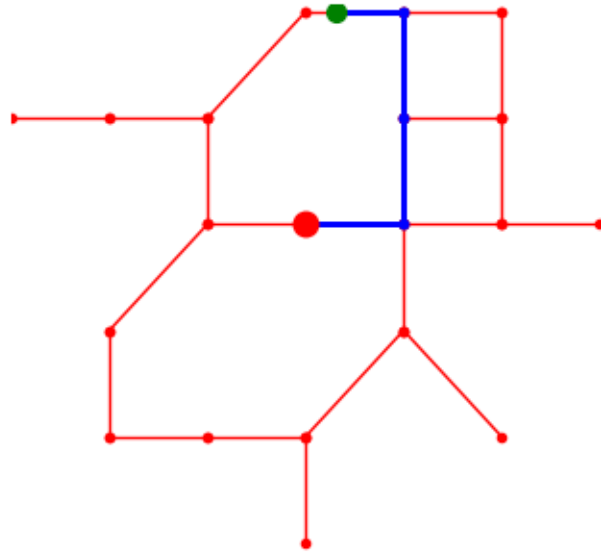
```
[40]: rec2 = simulation(M, W, C, p=0.3, days=4, log=True, plot=True)
```

Simulating delivery of 5 parcels over 4 days to 5 customers

```
[ 0] 18:00:00.0 Driver arrives for work
[ 0] 18:00:00.0 Nothing to do today
[ 0] 18:00:00.0 0 parcels left over for next day
[ 0] 18:10:00.0 Driver goes home
[ 1] 17:00:00.0 Parcel 0 for cust 2 arr at delivery centre
[ 1] 17:00:00.0 Parcel 1 for cust 3 arr at delivery centre
[ 1] 17:00:00.0 Parcel 2 for cust 4 arr at delivery centre
[ 1] 18:00:00.0 Driver arrives for work
[ 1] 18:00:00.0 Parcel 0 for cust 2 out for delivery
[ 1] 18:00:00.0 Parcel 1 for cust 3 out for delivery
[ 1] 18:00:00.0 Parcel 2 for cust 4 out for delivery
[ 1] 18:02:30.0 Driver leaves for delivery of 3 parcels to 3 customers
[ 1] 18:02:30.0 Length of delivery tour: 14,876m
```

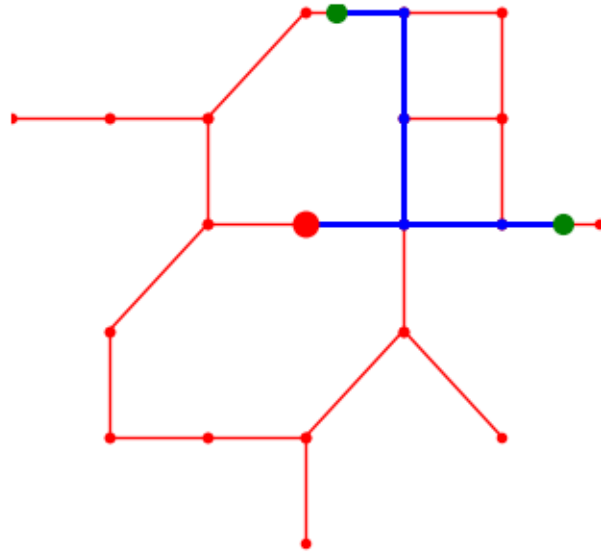


```
[ 1] 18:02:30.0 Driver drives to Customer 2 at (4929, 7300)
[ 1] 18:23:11.0 Driver arrived at Customer 2 at (4929, 7300)
[ 1] 18:23:25.9 Customer 2 at (4929, 7300) answers door
[ 1] 18:23:25.9 Customer 2 at (4929, 7300) accepts Parcel 0 for cust 2
[ 1] 18:23:39.0 Customer 2 at (4929, 7300) signs off
[ 1] 18:24:01.9 Driver drives to Customer 3 at (7300, 6825)
[ 1] 18:35:24.9 Driver arrived at Customer 3 at (7300, 6825)
[ 1] 18:36:11.0 Customer 3 at (7300, 6825) answers door
[ 1] 18:36:11.0 Customer 3 at (7300, 6825) accepts Parcel 1 for cust 3
[ 1] 18:36:17.4 Customer 3 at (7300, 6825) signs off
[ 1] 18:36:18.5 Driver drives to Customer 4 at (8167, 4500)
[ 1] 18:49:04.5 Driver arrived at Customer 4 at (8167, 4500)
[ 1] 18:49:27.3 Customer 4 at (8167, 4500) answers door
[ 1] 18:49:27.3 Customer 4 at (8167, 4500) accepts Parcel 2 for cust 4
[ 1] 18:49:36.8 Customer 4 at (8167, 4500) signs off
[ 1] 18:50:01.2 Driver returns to delivery centre
[ 1] 19:04:41.3 Driver arrived at delivery centre
[ 1] 19:04:41.3 0 parcels left over for next day
[ 1] 19:14:41.3 Driver goes home
[ 2] 17:00:00.0 Parcel 3 for cust 2 arr at delivery centre
[ 2] 18:00:00.0 Driver arrives for work
[ 2] 18:00:00.0 Parcel 3 for cust 2 out for delivery
[ 2] 18:00:50.0 Driver leaves for delivery of 1 parcels to 1 customers
[ 2] 18:00:50.0 Length of delivery tour: 10,342m
```



Day 2:, 10,342m

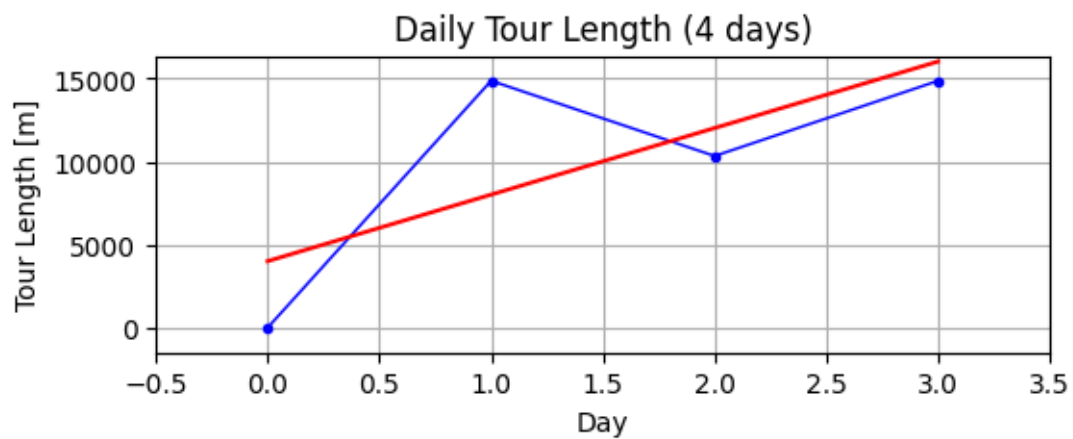
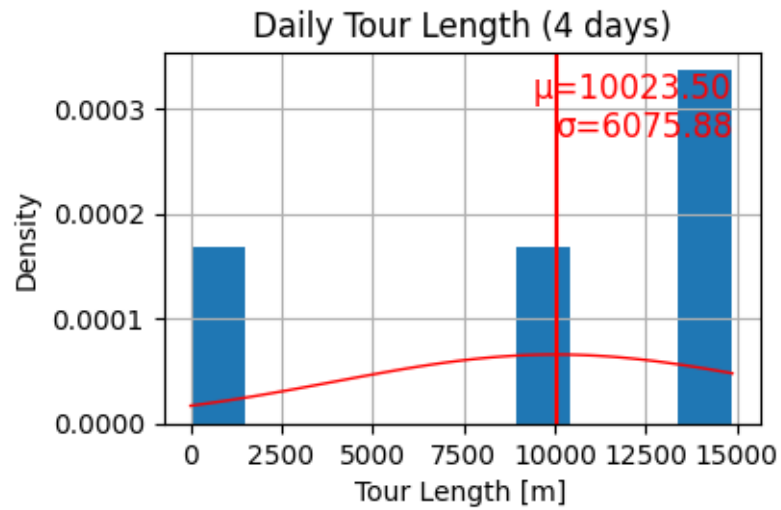
```
[ 2] 18:00:50.0 Driver drives to Customer 2 at (4929, 7300)
[ 2] 18:21:31.0 Driver arrived at Customer 2 at (4929, 7300)
[ 2] 18:22:31.0 Customer 2 at (4929, 7300) not at home
[ 2] 18:22:31.0 Driver returns to delivery centre
[ 2] 18:43:12.1 Driver arrived at delivery centre
[ 2] 18:43:12.1 Parcel 3 for cust 2 return from delivery
[ 2] 18:43:42.1 1 parcels left over for next day
[ 2] 18:53:42.1 Driver goes home
[ 3] 17:00:00.0 Parcel 4 for cust 4 arr at delivery centre
[ 3] 18:00:00.0 Driver arrives for work
[ 3] 18:00:00.0 Parcel 3 for cust 2 out for delivery
[ 3] 18:00:00.0 Parcel 4 for cust 4 out for delivery
[ 3] 18:01:40.0 Driver leaves for delivery of 2 parcels to 2 customers
[ 3] 18:01:40.0 Length of delivery tour: 14,876m
```



Day 3: 14,876m

```
[ 3] 18:01:40.0 Driver drives to Customer 2 at (4929, 7300)
[ 3] 18:22:21.0 Driver arrived at Customer 2 at (4929, 7300)
[ 3] 18:23:05.2 Customer 2 at (4929, 7300) answers door
[ 3] 18:23:05.2 Customer 2 at (4929, 7300) accepts Parcel 3 for cust 2
[ 3] 18:23:05.2 Customer 2 at (4929, 7300) signs off
[ 3] 18:23:12.0 Driver drives to Customer 4 at (8167, 4500)
[ 3] 18:47:21.1 Driver arrived at Customer 4 at (8167, 4500)
[ 3] 18:48:21.1 Customer 4 at (8167, 4500) not at home
[ 3] 18:48:21.1 Driver returns to delivery centre
[ 3] 19:03:01.2 Driver arrived at delivery centre
[ 3] 19:03:01.2 Parcel 4 for cust 4 return from delivery
[ 3] 19:03:31.2 1 parcels left over for next day
[ 3] 19:13:31.2 Driver goes home
Delivery Centre Inventory: 1 parcels
```

```
[41]: rec2.histTourLength()
      rec2.plotTourLength()
```

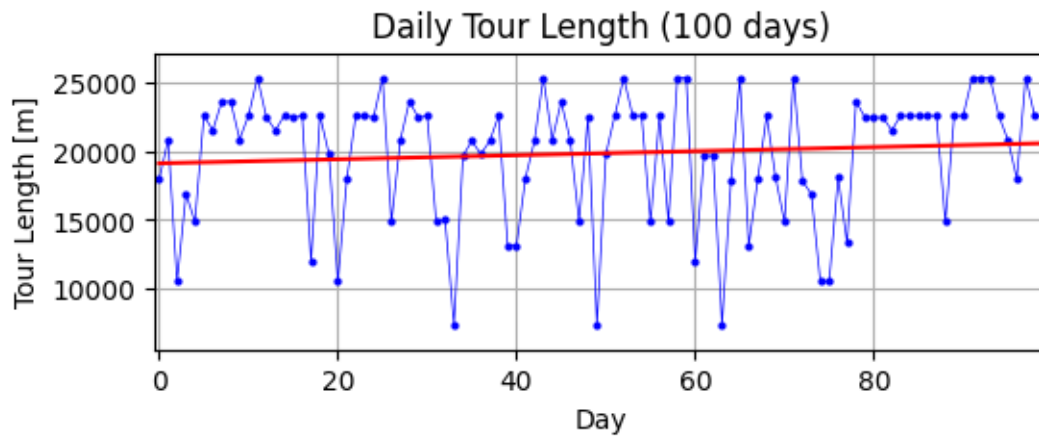
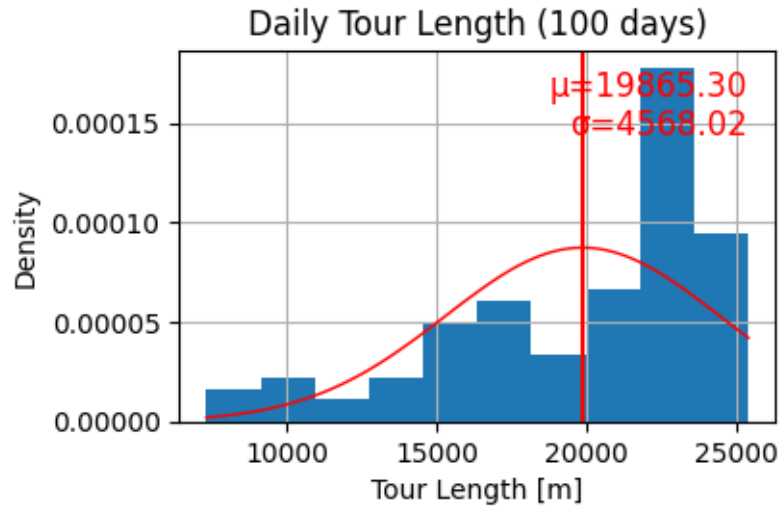


```
[42]: rec3 = simulation(M, W, C, p=0.6, days=100)
```

Simulating delivery of 289 parcels over 100 days to 5 customers  
Delivery Centre Inventory: 16 parcels

```
[43]: rec3.histTourLength()  
rec3.plotTourLength()
```





### 11.4.2 Using Test Data

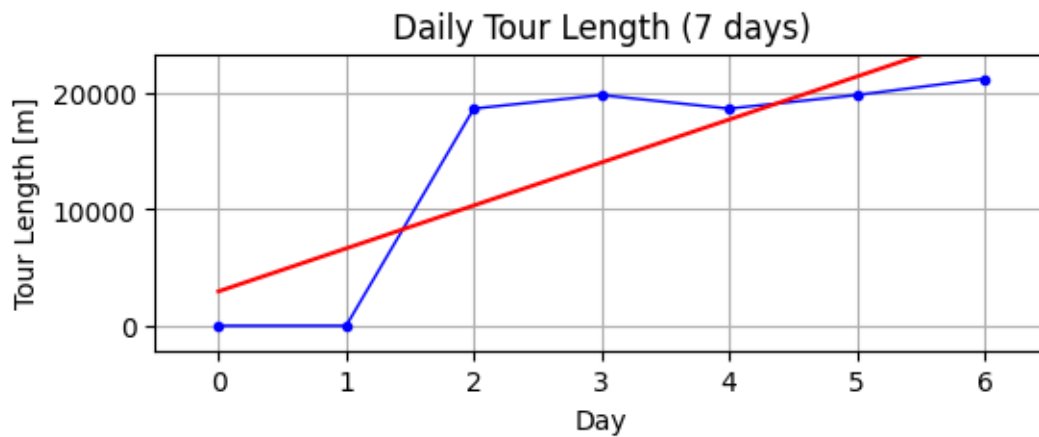
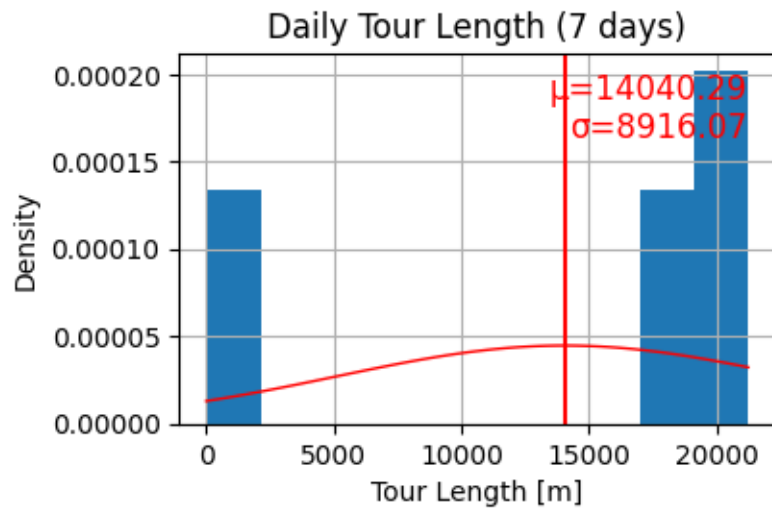
```
[44]: import pickle
      with open('testData.pickled', 'rb') as f:
          MX, CX = pickle.load(f)
```

```
[45]: WX = generateWarehouseLocation(MX)
```

```
[46]: rec4 = simulation(MX, WX, CX, p=0.15, days=7)
```

Simulating delivery of 14 parcels over 7 days to 20 customers  
Delivery Centre Inventory: 6 parcels

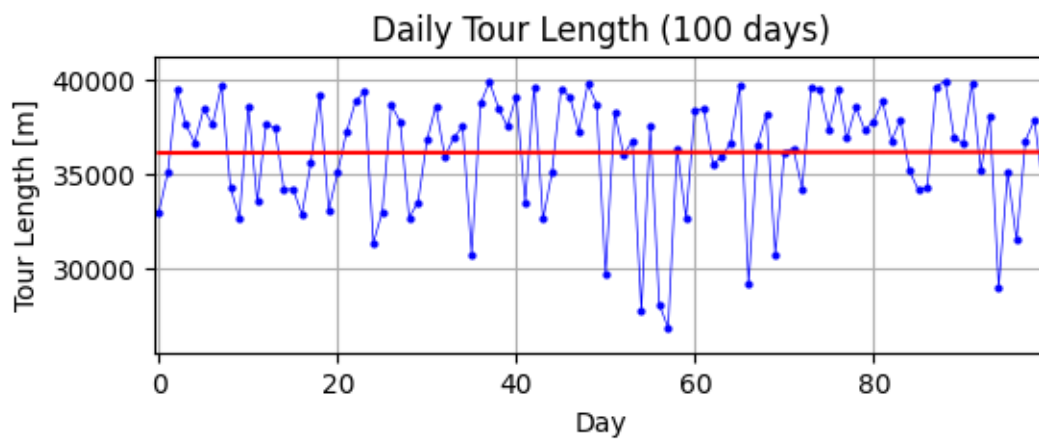
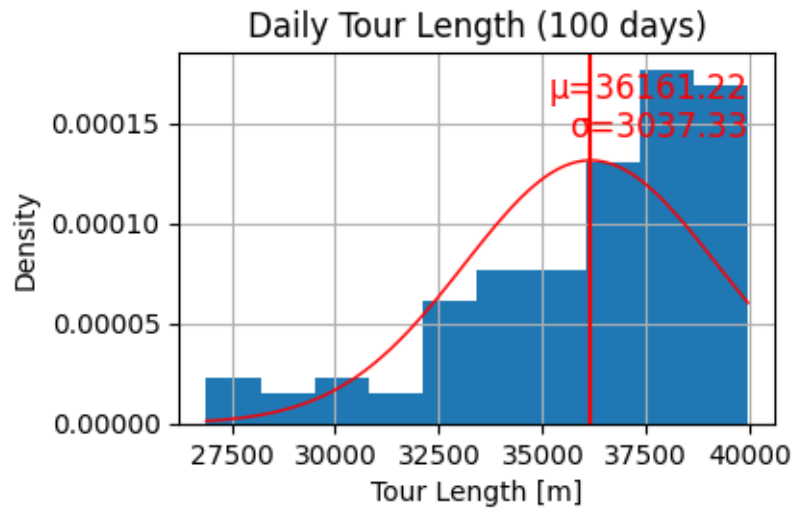
```
[47]: rec4.histTourLength()
rec4.plotTourLength()
```



```
[48]: rec5 = simulation(MX, WX, CX, p=1.2, days=100)
```

Simulating delivery of 2342 parcels over 100 days to 20 customers  
 Delivery Centre Inventory: 69 parcels

```
[49]: rec5.histTourLength()
rec5.plotTourLength()
```

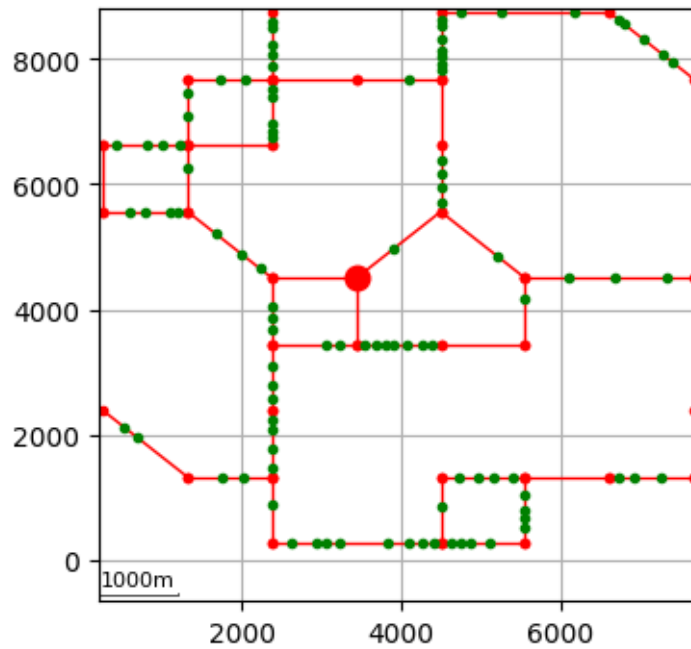


### 11.4.3 Using Full Data

```
[50]: import pickle
      with open('data.pickled', 'rb') as f:
          MM, CC = pickle.load(f)
```

```
[51]: WW = generateWarehouseLocation(MM)
```

```
[52]: plotMap(MM, T=CC, w=WW, scale=True, grid=True)
```

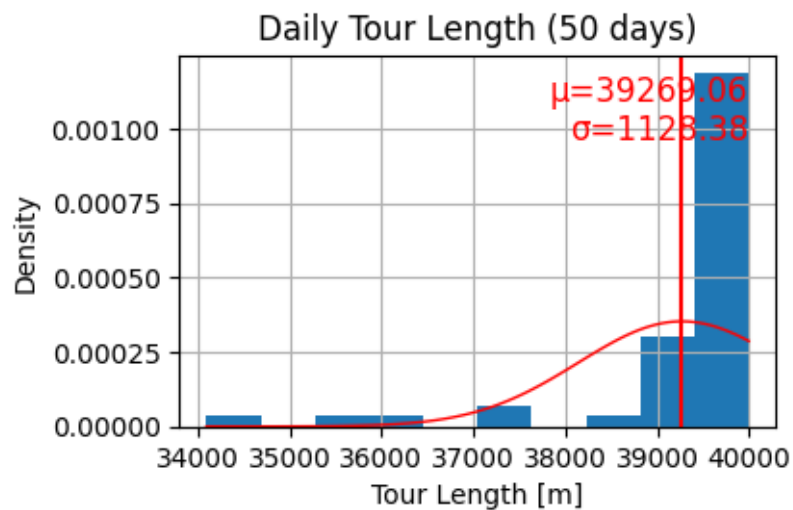


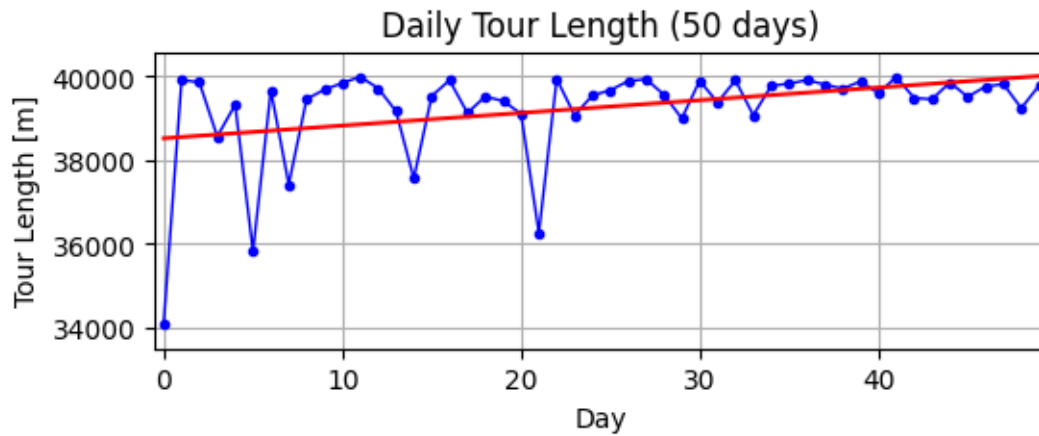
```
[53]: rec6 = simulation(MM, WW, CC, p=0.15, days=50)
```

Simulating delivery of 761 parcels over 50 days to 100 customers  
 Delivery Centre Inventory: 47 parcels

```
[54]: rec6.histTourLength()  

rec6.plotTourLength()
```

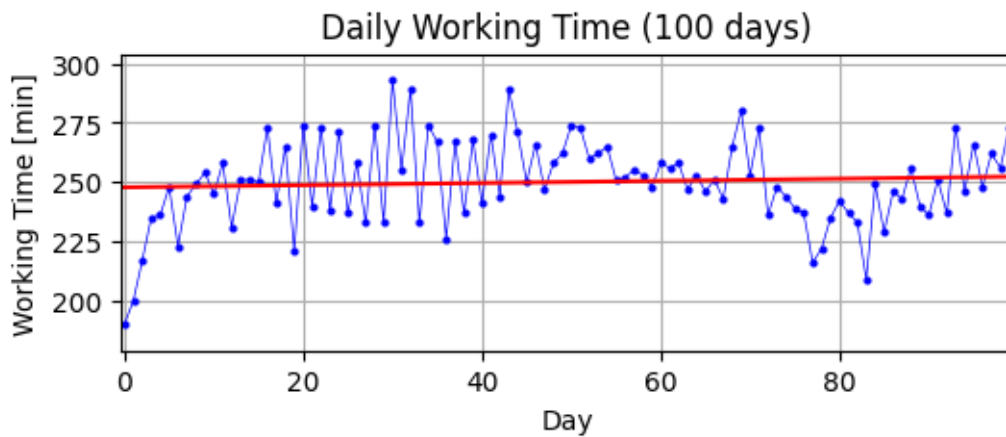


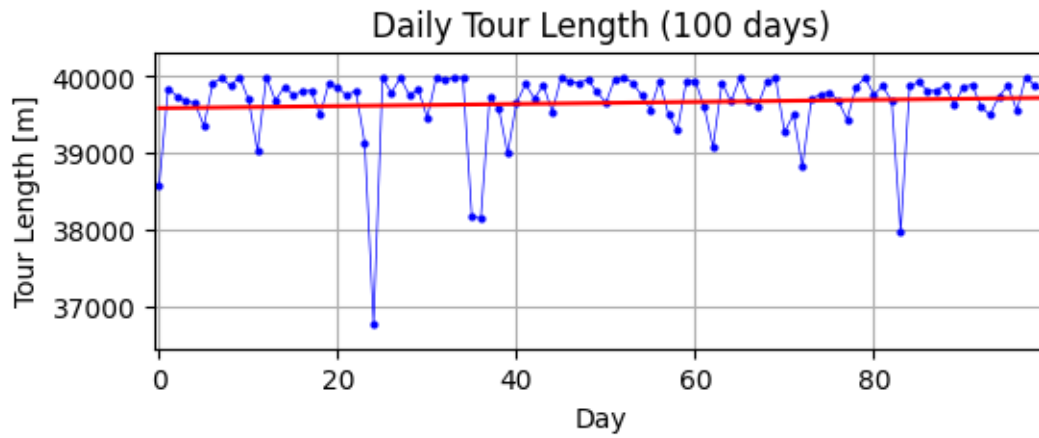


```
[55]: rec7 = simulation(MM, WW, CC, p=0.20, days=100)
```

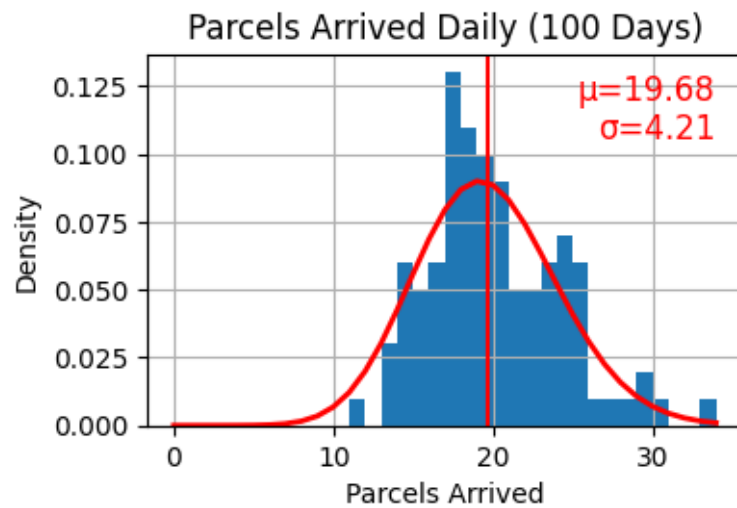
Simulating delivery of 1968 parcels over 100 days to 100 customers  
 Delivery Centre Inventory: 65 parcels

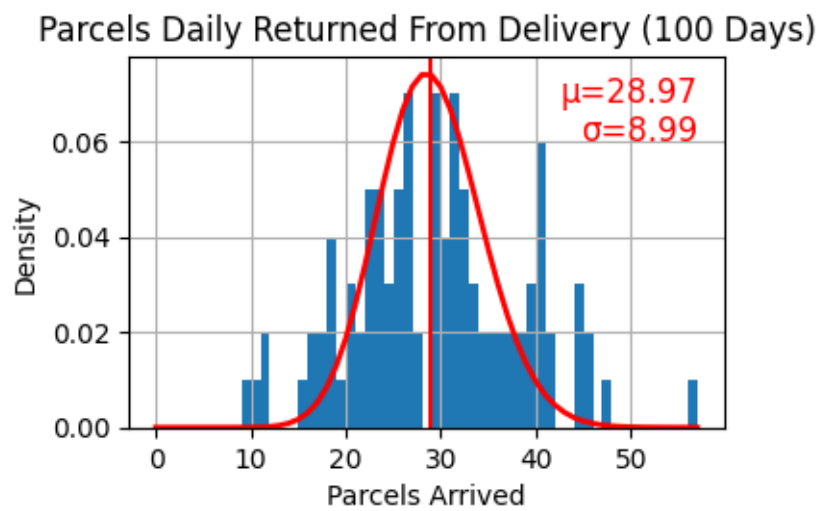
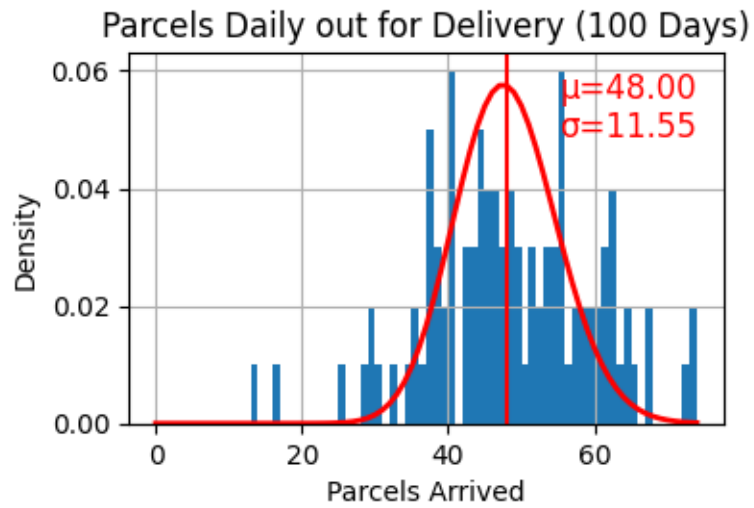
```
[56]: rec7.plotWorkingTime()  
rec7.plotTourLength()
```

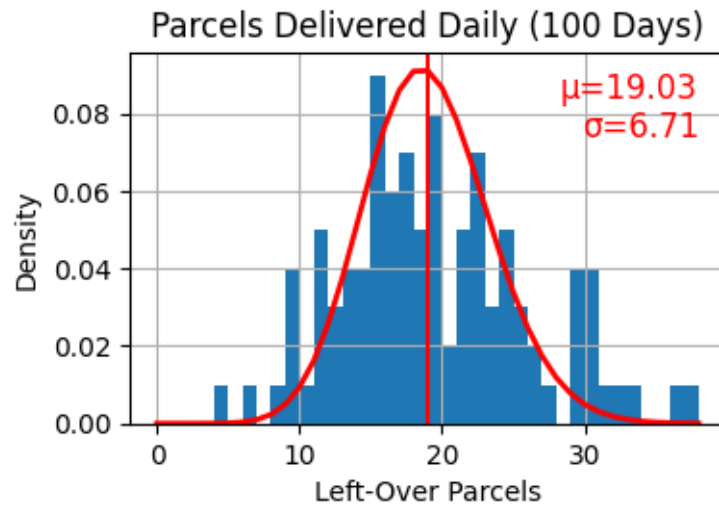




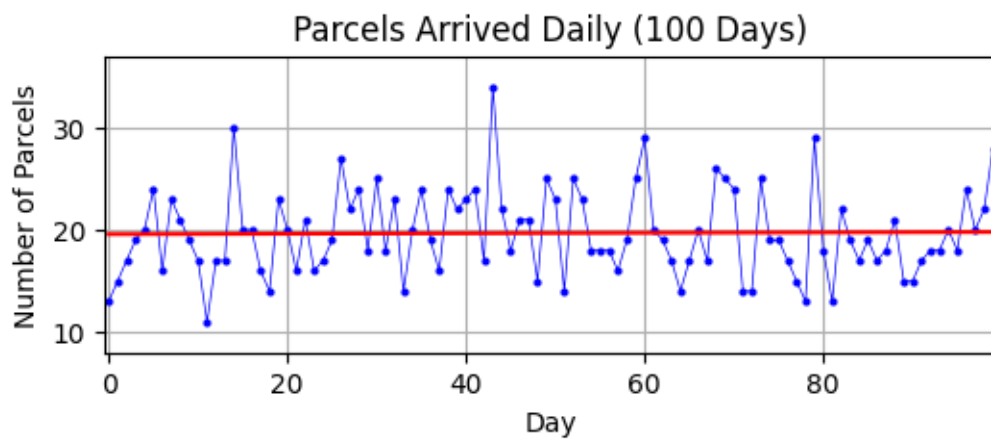
```
[64]: rec7.histParcelsArrived()
      rec7.histParcelsOutForDelivery()
      rec7.histParcelsReturnedFromDelivery()
      rec7.histParcelsDelivered()
```



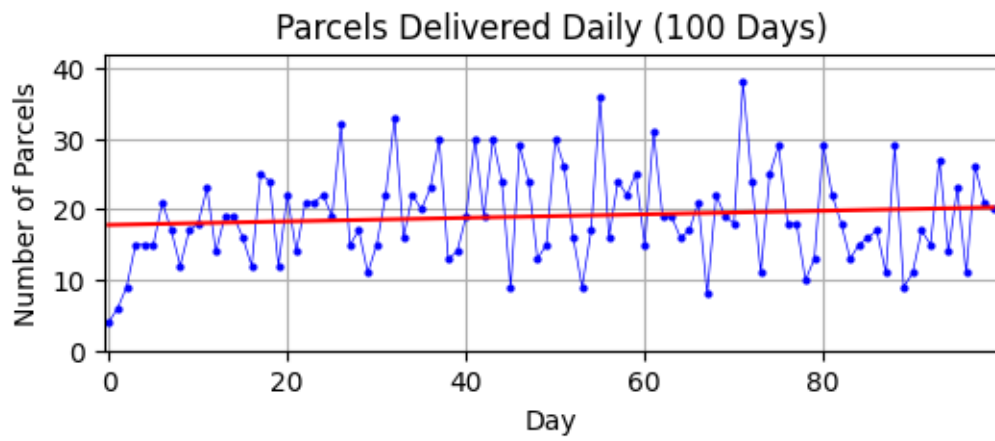
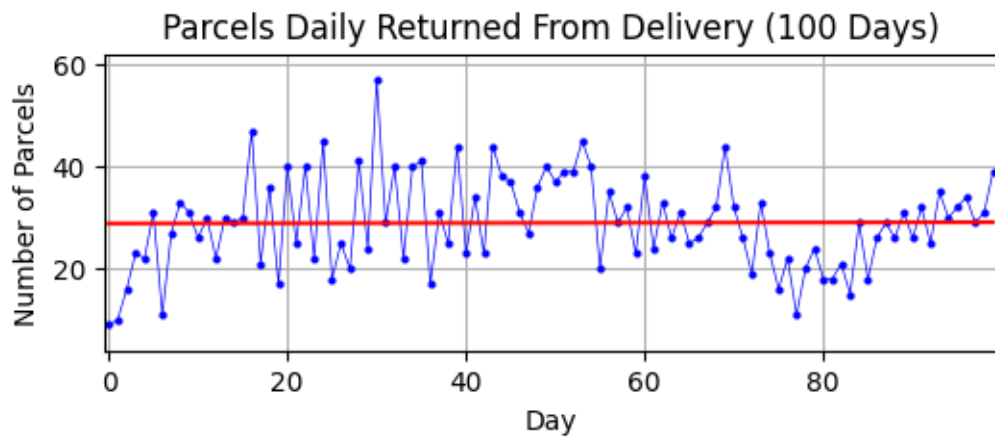
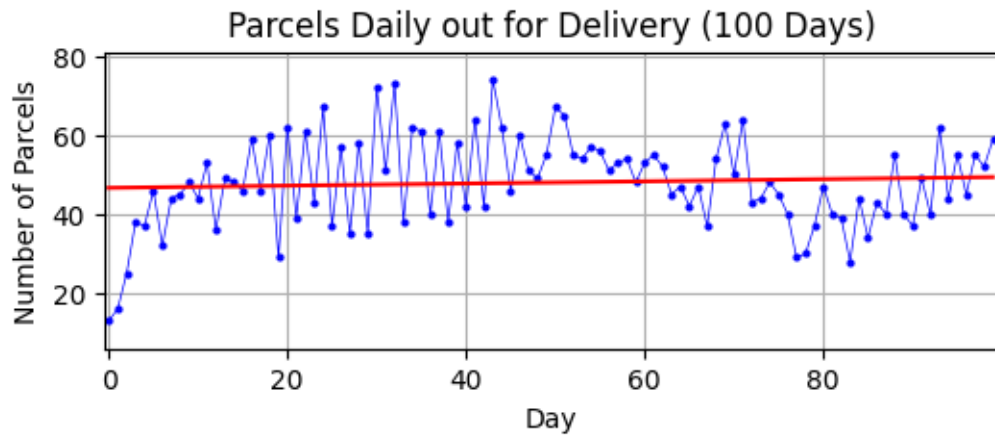




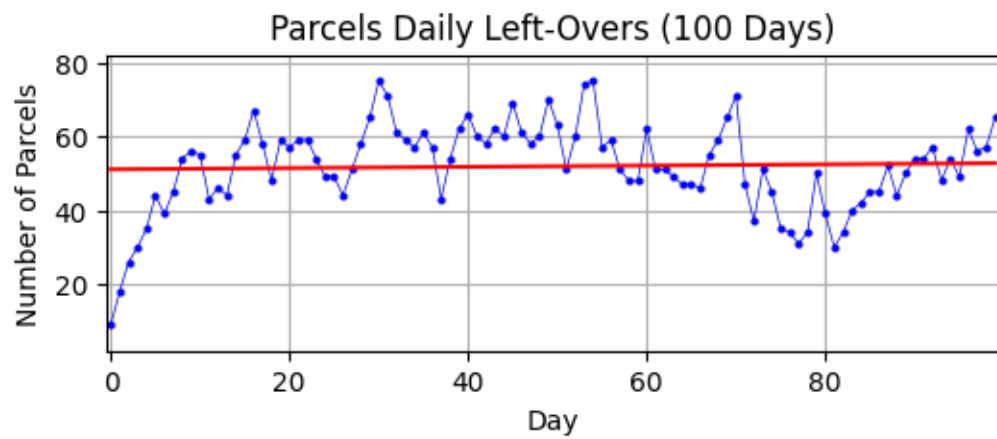
```
[65]: rec7.plotParcelsArrived()
      rec7.plotParcelsOutForDelivery()
      rec7.plotParcelsReturnedFromDelivery()
      rec7.plotParcelsDelivered()
```



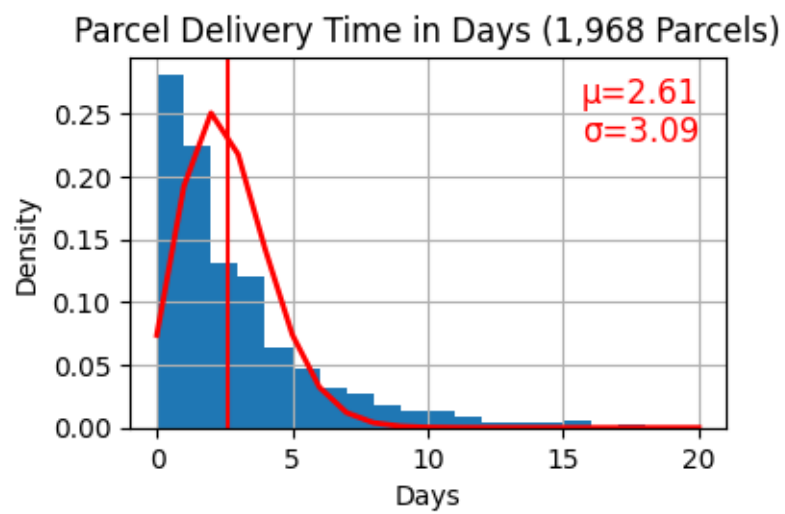




```
[66]: rec7.plotParcelsLeftOver()
```



```
[67]: rec7.histParcelDeliveryTime()
```



```
[ ]:
```