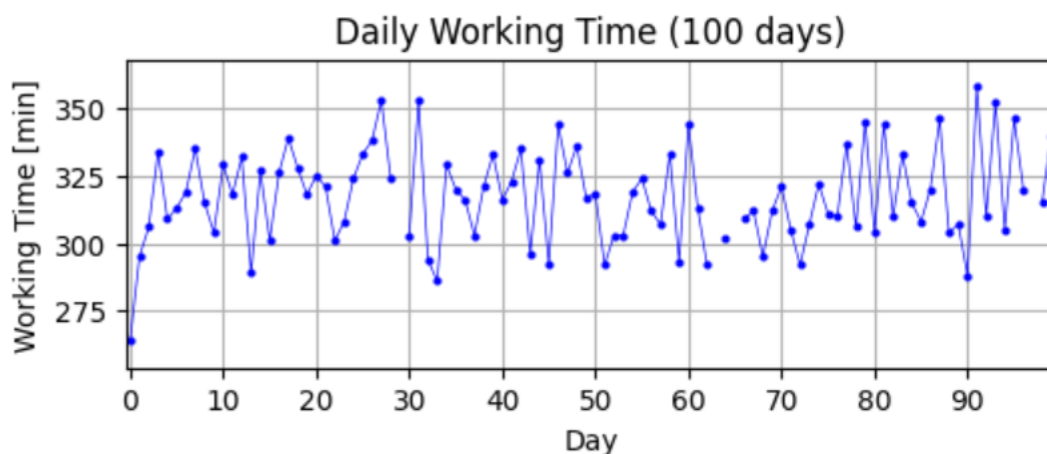


Step 6 Summary

The aim of step 6 is to develop the simulation study. This requires to run a number of larger simulations. As this takes quite a while, the first step is to save the simulation results using the pickle format. This allows us later to reload the Recorder instance of a simulation run and to drill deeper into plots or statistics without the need of a rerun of the simulation.

The first long simulation runs show a strange effect: the working time per day is growing beyond limits. Originally there was a soft working time limit of 3 hours postulated, i.e. the normal parcel delivery time was 18:00-21:00. Minor extensions were accepted. But now it turns out that the delivery time is going past 22:00, which is not acceptable for the customers.



Consequence: A daily working time limit has to be imposed. This means a change to the requirements. And this requires a change to the code.

Change Requirements (Specification):

The daily working time for the driver is intended to be limited to 3 hours. This needs to be taken into account in the route planning. Should the actual delivery process takes longer than originally planned, the driver is required to stop the delivery after 3 hours 20 minutes and return to the delivery centre with some of the remaining parcels still undelivered.

This implies a change to the basic code in class Driver and DeliveryCentre, and hence we have to rerun Step 4 Verification.

Changes to Class Driver

```
def process(self):
    yield self.rec.env.timeout(nextHour(self.rec.env, 18))
    while day(self.rec.env.now) < self.rec.days:
        self.arriveForWork()

    ## chnge to deal with time limit
    startTime = self.rec.env.now

    tour, parcels, addresses = self.DC.sendForDelivery()
    if len(parcels) == 0:
        self.rec.trace("Nothing to do today")
        self.rec.recordTourLength(0)
    else:
        yield self.rec.env.timeout(PREP_TIME_PER_PARCEL * len(parcels))
        self.rec.recordTourLength(pathLength(tour))
        self.leaveForDelivery(tour, parcels, addresses)
        while len(self.parcels) > 0:

            ## change to deal with time limit
            currentTime = self.rec.env.now
            if currentTime - startTime >= self.DC.timeLimit:
                self.rec.trace("Timelimit reached")
                while len(self.parcels) > 0:
                    self.returns += [self.parcels[0]]
                    self.parcels = self.parcels[1:]
                break

            # drive to customer
            custLocation = self.parcels[0].destination()
            cust = self.parcels[0].cust
            self.rec.trace("Driver drives to " + str(cust))
            yield from self.__drive(custLocation)
            self.rec.trace("Driver arrived at " + str(cust))
            # call at customer
            yield from cust.answerDoor()

            if cust.answersDoor:
                while len(self.parcels) > 0 and \
                    custLocation == self.parcels[0].destination():
                    cust.acceptParcel(self.parcels[0])
                    yield self.rec.env.timeout(random.expovariate(1/10))
                    self.parcels = self.parcels[1:]
                cust.signOff()
                yield self.rec.env.timeout(random.expovariate(1/10))
            else:
                while len(self.parcels) > 0 and \
                    custLocation == self.parcels[0].destination():
                    self.returns += [self.parcels[0]]
                    self.parcels = self.parcels[1:]

            # return to delivery centre
            self.rec.trace("Driver returns to delivery centre")
            yield from self.__drive(self.DC.W)
            self.rec.trace("Driver arrived at delivery centre")

        for parcel in self.returns:
            self.DC.returnFromDelivery(parcel)
            yield self.rec.env.timeout(RETURN_TIME_PER_PARCEL)

    self.rec.recordParcelsLeftOver(len(self.DC.parcels) + len(self.DC.leftOver))

    yield self.rec.env.timeout(600)

    self.goesHome()

    yield self.rec.env.timeout(nextHour(self.rec.env, 18))
```

Changes to Class DeliveryCentre

```
class DeliveryCentre:

    def __init__(self, rec, M, W, limit, timeLimit):
        self.rec = rec
        self.M = M
        self.W = W
        self.limit = limit

        self.timeLimit = timeLimit

        self.leftOver = []    # list of parcels
        self.parcels = []     # list of parcels scheduled for delivery
        self.dest = []        # list of unique customer destinations
        self.tour = [self.W]  # tour planned for delivery

    def __accept(self, parcel):
        custLoc = parcel.destination()

        ## chnge to deal with time limit estimate
        timeEstimate = \
            len(self.parcels)*(PREP_TIME_PER_PARCEL + AVG_TIME_HANOVER) \
            + len(self.dest)*(AVG_TIME_ANSWER_DOOR + AVG_TIME_SIGNOFF)

        if custLoc not in self.dest:
            MT = addTargets(self.M, self.dest + [custLoc])
            SH = createLoopG(MT, [self.W] + self.dest + [custLoc])

            ## chnge to deal with time limit estimate
            if pathLength(SH) < self.limit and \
                timeEstimate + pathLength(SH)/AVG_SPEED + \
                PREP_TIME_PER_PARCEL + AVG_TIME_ANSWER_DOOR + \
                AVG_TIME_HANOVER + AVG_TIME_SIGNOFF <= self.timeLimit:

                self.parcels.append(parcel)
                self.dest += [custLoc]
                self.tour = SH
            else:
                self.leftOver.append(parcel)

        ## chnge to deal with time limit estimate
        elif timeEstimate + pathLength(self.tour)/AVG_SPEED + \
            PREP_TIME_PER_PARCEL + AVG_TIME_HANOVER <= self.timeLimit:
            self.parcels.append(parcel)
        else:
            self.leftOver.append(parcel)
```