

- ① Clean Image denoted by $I(x, y)$
 Additive Noise denoted by $N(x, y)$
 where noise is 0-mean gaussian distribution
 with $\text{std} = \sigma$.

$$I_{\text{noisy}}(x, y) = I(x, y) + N(x, y)$$

$$\text{PDF of noise} = P_N(n) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{n^2}{2\sigma^2}}$$

- we need to find PDF of $I_{\text{noisy}}(i)$; which is sum of two random variables $P_N(n)$ [Noise Random Var], $P_I(i)$ [Clean Image Random Var]
- for any intensity value; PDF of noisy image is convolution of PDF of clean image and PDF of noise.
- let PDF of clean image intensity be $P_I(i)$; noise be $P_{I_{\text{noisy}}}(i)$

$$(a) \quad P_{I_{\text{noisy}}}(i) = \int_{-\infty}^{\infty} P_I(i) P_N(i_{\text{noisy}} - i) di \quad ; \quad P_{I_{\text{noisy}}}(x) = P_I(x) * P_N(x)$$

* → convolution

- (b) In Image Processing, Gaussian Smoothing involves convolution an image with a Gaussian kernel to reduce noise or details.
- In context of PDF of noisy image ⇒ Convolution with $P_N(n)$ effectively "spread out" or "smooths" the intensity values;
- ⇒ Thus; adding gaussian noise to an image has same effect on its intensity distribution as performing Gaussian blur.

① (c) uniform noise distribution

PDF of $N(x, y)$ is $P_N(n)$

$$P_N(n) = \begin{cases} \frac{1}{2r} & \text{if } -r \leq n \leq r \\ 0 & \text{otherwise} \end{cases}$$

$$I_{\text{noisy}} = I(x, y) + N(x, y)$$

⇒ PDF of noisy image: $P_{I_{\text{noisy}}}(i_{\text{noisy}})$

$$P_{I_{\text{noisy}}}(i_{\text{noisy}}) = P_N(i_{\text{noisy}}) * P_I(i_{\text{noisy}})$$

$$\left[P_{I_{\text{noisy}}}(i_{\text{noisy}}) = \int_{-\infty}^{\infty} P_N(i_{\text{noisy}} - i) \cdot P_I(i) di \right]$$

→ $P_N(i_{\text{noisy}} - i)$ is non-zero only for
 $i_{\text{noisy}} - r \leq i \leq i_{\text{noisy}} + r$

⇒ Convolution with a uniform distribution has effect of Box Blurring or Rectangular smoothing where intensity values spreads uniformly over the range r .
