

# Ivan Kharitonov

Moscow

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ipkharitonov@gmail.com

[github.com/neer201](https://github.com/neer201)

[LinkedIn](#)

+7(916)785-71-11



I am interested in automotive and robotics areas and looking for a software developer / research engineer position in the self-driving industry.

## Education

2008 – 2014	<b>MS + BS</b> (electrical engineering) at <b>Bauman Moscow State Technical University</b>
2016	Data Mining in Action course (open ML course at MIPT)
2017 – 2019	<b>Yandex School of Data Analysis</b> – Computer Science track
2019, 2021	Summer school "Control, Information, Optimization"
2020	Waymo workshop for FSG Academy - <a href="#">certificate</a>
2021	Third HSE-Yandex autumn school on generative models - <a href="#">info</a>

## Teaching

spring 2019, 2020, 2021 Yandex DA school	TEACHING ASSISTANT FOR THE COURSE PRACTICAL RL Provided help and read seminars with hw checkups in HSE and YSDA
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## Professional Experience

Aug 2020 – now <b>Sberbank</b> <b>Sberautotech</b>	<b>SOFTWARE ENGINEER - PERCEPTION TEAM</b> <ul style="list-style-type: none"><li>Implemented models for point-cloud based object detection task.</li></ul> <b>SOFTWARE ENGINEER - PREDICTION TEAM</b> <ul style="list-style-type: none"><li>Multi-object tracking – solve object tracking problem using random finite set statistics.</li></ul> Developed python library for tracking scenarios and multi-object tracking algorithms. Using: <code>numpy</code> , <code>scipy</code> , <code>mpl</code> , <code>torch-torchscript</code> , <code>hydra</code> , <code>ROS2</code> , <code>Docker</code> , <code>Python</code> , <code>gitlab-CI</code>
Jul 2015 – Nov 2017 <b>FSUE NAMI</b> <b>Central Scientific Research Automotive Institute – Information and Intelligent Systems Center</b>	<b>RESEARCH ENGINEER AT SELF-DRIVING DEPARTMENT (<a href="#">SHUTTLE PROJECT</a>)</b> <ul style="list-style-type: none"><li>Implemented perception models for object detection task – collecting/generating training data, optimizing the model design, model implementation (Caffe DL framework) and evaluation.</li></ul> <b>SOFTWARE DEVELOPER (CONTROL SYSTEMS) AT TRANSMISSION CONTROL SYSTEMS DEPARTMENT (<a href="#">AURUS PROJECT</a>)</b> <ul style="list-style-type: none"><li>System identification – created plant models for some vehicle mechanism, such that gearbox clutch hydraulic actuator.</li><li>Implemented basic software layer for automotive microcontroller (C, Simulink, Altium Designer) from scratch.</li><li>Designed and implemented a controller for hydraulic actuators with further improving quality metrics and decreasing system setting time.</li><li>Decreased calibration time by developing automated calibration procedure of control system parameters and tested control algorithms on the testbench.</li></ul> Using: <code>MATLAB</code> , <code>Simulink</code> , <code>Vector CANAPE</code>

Mar 2013 – Aug 2015 <b>BMSTU</b> Bauman Moscow State Technical University	HARDWARE AND TELEMETRY ENGINEER ON <a href="#">AN FSAE TEAM</a> . Participated in international engineering competition FSAE as a member of the university racing team. Responsibilities: hardware and software development, sponsorship and partnership management. Achievements: <ul style="list-style-type: none"> <li>Released projects: MS thesis – using RTK navigation for telemetry, F1-like steering wheel with integrated LCD, wireless telemetry module, signals expansion module by reverse-engineering the race ECU CANbus protocol.</li> <li>Received positive feedback from judges on the design event with good score.</li> <li>Established sponsorship contracts with several companies. As a result, we were granted new equipment.</li> </ul>
Feb 2012 – Jul 2013 <b>Crypto LLC</b> Systems integrator	ENGINEER AT SYSTEM INTEGRATION DEPARTMENT. <ul style="list-style-type: none"> <li>Adapted the product to the customer by adding fault tolerance setup.</li> <li>Integrated the monitoring tool (Zabbix) with a data management system.</li> </ul>
May 2009 – Feb 2012 <b>PJSC VimpelCom</b>	TEST ENGINEER. The Vimpelcom's <a href="#">pilot project</a> - TV provider for mobile phones. <ul style="list-style-type: none"> <li>Monitoring of the head and base stations (DVB-H) and 2nd level technical support.</li> </ul>

## Generall Skills

Programming	Python (numpy, scipy, pytorch, jax, pytest, poetry, nox) MATLAB, C++
Base tools	git, ssh, unix, latex , Docker, dvc
Other tools	CI/CD (github actions), ROS2, xpra
Engineering tools	Altium Designer, Solidworks, LabView, Simulink, Vector software (CANape)
Speaking	Russian – Native, English – B2

## Activities

Formula Student	DESIGN JUDGE <a href="#">FSAE AI UK</a> 2020 DESIGN JUDGE BAY CHIEF Formula Student Russia 2020 DESIGN JUDGE (DRIVERLESS - PERCEPTION) <a href="#">Formula Student Germany</a> 2021 DESIGN JUDGE BAY CHIEF Formula Student Russia 2021
Motorsport	FLAG MARSHAL 2020 Formula One Sochi Gran Prix , 2020 Russian Circuit Racing Series SCRUTINEERING, DATA ANALYSIS 2021 Russian Circuit Racing Series SCRUTINEERING 2021 Russian Hot Hatch Club Championship SCRUTINEERING F2/F3 2021 Formula One Sochi Gran Prix
Sports	road bicycle racing, boxing
Other activities	organized reading club about robotics and self-driving at BMSTU