

# Kyle Hatch

✉ [kbhatch@usc.edu](mailto:kbhatch@usc.edu) • 🌐 [khatch31.github.io](https://khatch31.github.io)

## EDUCATION

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**University of Southern California**

*PhD in Computer Science*

**Los Angeles, CA**

*Expected graduation: May 2030*

**Stanford University**

*M.S. in Computer Science*

**Stanford, CA**

*Graduated: June 2023*

**Stanford University**

*B.S. with honors in Computer Science*

**Stanford, CA**

*Graduated: June 2022*

## RESEARCH EXPERIENCE

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**Research Focuses:** Robot Learning, Reinforcement Learning, Generative Models

**University of Southern California (USC)**

*PhD student (co-advised by Yue Wang and Daniel Seita)*

*August 2025 – Present*

Current research focuses on using human video data and generative models to increase the generalization capacity of robot agents.

**Toyota Research Institute (TRI)**

*AI Resident in the Large Behavior Models (LBM) Division*

*July 2023 – August 2025*

Developed a method to use image and video generative models to guide robotic manipulation policies, leading to a first-author publication in ICRA 2025.

**Stanford IRIS Lab – Prof. Chelsea Finn**

*Undergraduate/Master's student*

*October 2020 — June 2023*

Led/co-led three projects on robotics-oriented offline reinforcement learning. First-author/co-first author publications in CoRL 2023, L4DC 2023, and RLC 2024.

**Stanford Intelligent Systems Laboratory (SISL) – Prof. Mykel Kochenderfer**

*Undergraduate student*

*June 2019 — March 2021*

Led/co-led two projects on using machine learning and reinforcement learning for collision avoidance in unmanned aerial vehicles (UAVs). First-author/co-first-author publications in IROS 2021 and AIAA SciTech Forum 2021.

## SELECTED PUBLICATIONS

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Please see my [Google Scholar](#) profile for a complete list of publications.

**Hatch, K.**, Balakrishna, A., Mees, O., Nair, S., Wulfe, B., Itkina, M., Eysenbach, B., Levine, S., Kollar, T., and Burchfiel, B., "GHIL-Glue: Hierarchical Control with Filtered Subgoal Images," *IEEE International Conference on Robotics and Automation (ICRA)*, 2025. [PDF](#) [Website](#)

Kolev, V.\*, Rafailov, R.\*, **Hatch, K. B.**, Wu, J., and Finn, C., "Efficient Imitation Learning with Conser-

vative World Models," *Learning for Dynamics & Control Conference (L4DC)*, 2024. [PDF](#)

Rafailov, R.\*, **Hatch, K. B.\***, Singh, A., Smith, L., Kumar, A., Kostrikov, I., Hansen-Estruch, P., Koley, V., Ball, P., Wu, J., Finn, C., and Levine, S., "D5RL: Diverse Datasets for Data-Driven Deep Reinforcement Learning," *Reinforcement Learning Conference (RLC)*, 2024. [PDF](#)

Rafailov, R.\*, **Hatch, K. B.\***, Koley, V., Martin, J., Phielipp, M., and Finn, C., "MOTO: Offline to Online Fine-tuning for Model-Based Reinforcement Learning," *Conference on Robot Learning (CoRL)*, 2023. [PDF](#) [Website](#)

**Hatch, K. B.**, Eysenbach, B., Yu, T., Rafailov, R., Salakhutdinov, R., Levine, S., and Finn, C., "Contrastive Example-Based Control," *Learning for Dynamics & Control Conference (L4DC)*, 2023. [PDF](#) [Website](#)

Senanayake, R.\*, **Hatch, K.\***, Zheng, J., and Kochenderfer, M. J., "3D Radar Velocity Maps for Uncertain Dynamic Environments," *IEEE International Conference on Intelligent Robots and Systems (IROS)*, 2021. [PDF](#) [Presentation](#)

**Hatch, K.**, Mern, J., and Kochenderfer, M. J., "Obstacle Avoidance Using a Monocular Camera," *American Institute of Aeronautics and Astronautics (AIAA) SciTech Forum*, 2021. [PDF](#) [Presentation](#)

\*denotes equal contribution

## SKILLS

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Machine Learning Frameworks	PyTorch, JAX, Tensorflow 2.0
Programming Languages	Python, C++
Cloud Computing	Amazon SageMaker
Reinforcement Learning Tools	deepmind-acme, TF-Agents, RLkit, JAXRL

## OUTREACH

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### Breakthrough Silicon Valley ([BTSV](#))

San Jose, CA

Volunteer tutor

November 2023 – April 2024

Provided homework support to high school students who are on track to becoming first-generation college students. Primarily assisted with mathematics.

### East Palo Alto Stanford Academy ([EPASA](#))

Stanford, CA

Volunteer tutor

October 2018 – March 2020

Provided homework support to seventh and eighth grade students from low-income backgrounds in mathematics and English, and helped students to develop effective study skills.

### Stanford 1st Ward Volunteer Tutoring Program

Stanford, CA

Volunteer tutor

September 2017 – June 2019

Provided homework support to K-12 students in mathematics, reading, and English.