

Kyle Hatch

✉ kyle.hatch@tri.global • 🌐 [khatch31.github.io](https://github.com/khatch31)

EDUCATION

Stanford University

M.S. in Computer Science
Artificial Intelligence Track
Coterminal Master's Program

Stanford, CA
Graduated: June 2023
GPA: 4.05

Stanford University

B.S. with honors in Computer Science
Artificial Intelligence Track

Stanford, CA
Graduated: June 2022
GPA: 3.78

Honors/Awards

Completed undergraduate CS Honors thesis.

RESEARCH EXPERIENCE

Research Focuses: Robot Learning, Reinforcement Learning, Foundation Models

Toyota Research Institute (TRI)

AI Resident in the Machine Learning Division

July 2023 – Present

Research focuses on leveraging foundation models for robot learning. Lead a project on utilizing language-conditioned image and video diffusion models to generate subgoals for robotic manipulation tasks. Currently working on developing vision-language-action models (VLAs) for robotic manipulation. Learned key skills for large-scale robot learning, such as structuring data loaders and models for multi-node, distributed training, and using large-scale computing platforms.

Stanford IRIS Lab – Prof. Chelsea Finn

Undergraduate/Master's student

October 2020 — June 2023

Worked on addressing three key limitations in scaling offline reinforcement learning methods to realistic robot applications: 1) learning from play data/autonomously collected robot data without reward labels 2) pre-training on offline data and then fine-tuning online 3) developing realistic simulated benchmarks. Three first/co-first author publications:

- D5RL: a benchmark to evaluate offline RL and offline-to-online fine-tuning methods on visually diverse, realistic, simulated robotics tasks. Co-first author on paper under review at the International Conference on Learning Representations (ICLR) 2024.
- MOTO: a model-based reinforcement learning method designed for efficient offline-to-online fine-tuning for vision-based manipulation tasks. Co-first author on paper in the Conference on Robot Learning (CoRL) 2023.
- LAEO: an offline reinforcement learning method using contrastive learning for data without reward labels. First author on paper in the Learning for Dynamics & Control Conference (L4DC) 2023.

Stanford Intelligent Systems Laboratory (SISL) – Prof. Mykel Kochenderfer

Undergraduate student

June 2019 — March 2021

Worked on using machine learning and reinforcement learning techniques to improve collision avoidance in autonomous vehicles and unmanned aerial vehicles UAVs. Two first/co-first author publications:

- A method to learn 3D velocity maps from radar data for autonomous vehicles. Co-first author on

- paper in the IEEE International Conference on Intelligent Robots and Systems (IROS) 2021.
- A collision avoidance system for autonomous drones using monocular vision and deep reinforcement learning. First author on paper in the American Institute of Aeronautics and Astronautics (AIAA) SciTech Forum 2021.

Johns Hopkins University Applied Physics Laboratory (APL)

Research Intern

June 2020 — May 2021

Developed a reinforcement learning-based method to autonomously respond to cybersecurity threats on industrial control systems. Second author on paper in the International Conference on Dependable Systems and Networks (DSN'22), 2022.

Stanford Network Analysis Project (SNAP) – Prof. Jure Leskovec

Undergraduate student

September 2019 — June 2020

Conducted research on using graph convolutional networks to predict interactions between microbes in the human gastrointestinal tract.

PUBLICATIONS

Published/Accepted

Rafailov, R.*, **Hatch, K. B.***, Kolev, V., Martin, J., Phielipp, M., and Finn, C., "MOTO: Offline to Online Fine-tuning for Model-Based Reinforcement Learning," *Conference on Robot Learning (CoRL)*, 2023.

[PDF](#) [Website](#)

Hatch, K. B., Eysenbach, B., Yu, T., Rafailov, R., Salakhutdinov, R., Levine, S., and Finn, C., "Contrastive Example-Based Control," *Learning for Dynamics & Control Conference (L4DC)*, 2023. [PDF](#) [Website](#)

Rafailov, R.*, **Hatch, K. B.***, Singh, A., Smith, L., Kumar, A., Kostrikov, I., Hansen-Estruch, P., Kolev, V., Ball, P., Wu, J., Finn, C., and Levine, S., "D5RL: Diverse Datasets for Data-Driven Deep Reinforcement Learning," *Reinforcement Learning Conference (RLC)*, 2024. [PDF](#)

Zhou, G., Dean, V., Srirama, M. K., Rajeswaran, A., Pari, J., **Hatch, K. B.**, Jain, A., Yu, T., Abbeel, P., Pinto, L., Finn, C., and Gupta, A., "Train Offline, Test Online: A Real Robot Learning Benchmark," *2023 IEEE International Conference on Robotics and Automation (ICRA)*, 2023. [PDF](#) [Website](#)

Mern, J., **Hatch, K.**, Silva, R., Hickert, C., Sookoor, T., and Kochenderfer, M. J., "Autonomous Attack Mitigation for Industrial Control Systems," *International Conference on Dependable Systems and Networks (DSN'22)*, 2022. [PDF](#)

Senanayake, R.*, **Hatch, K.***, Zheng, J., and Kochenderfer, M. J., "3D Radar Velocity Maps for Uncertain Dynamic Environments," *IEEE International Conference on Intelligent Robots and Systems (IROS)*, 2021.

[PDF](#) [Presentation](#)

Hatch, K., Mern, J., and Kochenderfer, M. J., "Obstacle Avoidance Using a Monocular Camera," *American Institute of Aeronautics and Astronautics (AIAA) SciTech Forum*, 2021. [PDF](#) [Presentation](#)

Under Review

Hatch, K., Balakrishna, A., Mees, O., Nair, S., Wulfe, B., Itkina, M., Eysenbach, B., Levine, S., Kollar, T., and Burchfiel, B., "GHIL-Glue: Hierarchical Control with Filtered Subgoal Images," *2025 IEEE International Conference on Robotics and Automation (ICRA)*, 2025.

***denotes equal contribution**

OUTREACH

Breakthrough Silicon Valley (**BTSV**)

Volunteer tutor

San Jose, CA

November 2023 – April 2024

Provide homework support to high school students who are on track to becoming first-generation college students. Primarily assist with mathematics.

East Palo Alto Stanford Academy (**EPASA**)

Volunteer tutor

Stanford, CA

October 2018 – March 2020

Provided homework support to seventh and eighth grade students from low-income backgrounds in mathematics and English, and helped students to develop effective study skills.

Stanford 1st Ward Volunteer Tutoring Program

Volunteer tutor

Stanford, CA

September 2017 – June 2019

Provided homework support to K-12 students in mathematics, reading, and English.

SKILLS

Machine Learning Frameworks

JAX, Pytorch, Tensorflow 2.0

Cloud Computing

Amazon SageMaker

Reinforcement Learning Tools

deepmind-acme, TF-Agents, RLkit, JAXRL

Simulation Tools

Mujoco, Microsoft AirSim

Programming Languages

Python, C++