Kyle Hatch

✉ kyle.hatch@tri.global • 🌐 khatch31.github.io

EDUCATION

Stanford University   **Stanford, CA**
M.S. in Computer Science   *Graduated: June 2023*
Artificial Intelligence Track   *GPA: 4.05*
Coterminal Master's Program

Stanford University   **Stanford, CA**
B.S. with honors in Computer Science   *Graduated: June 2022*
Artificial Intelligence Track   *GPA: 3.78*

Honors/Awards
Completed undergraduate CS Honors thesis.

RESEARCH EXPERIENCE

Research Focuses: Robot Learning, Reinforcement Learning, Generative Models

Toyota Research Institute (TRI)
AI Resident in the Large Behavior Models (LBM) Division   *July 2023 – Present*

Research focuses on leveraging diffusion models and vision-language-action models (VLAs) for robotic manipulation. Led a project on using image and video diffusion models to generate subgoals for robotic manipulation tasks. First-author publication under review at the IEEE International Conference on Robotics and Automation (ICRA) 2025. Current research involves co-training VLAs with action prediction and video prediction objectives to transfer knowledge from Internet video data to robot agents. Developed key skills including working with large-scale diffusion and transformer-based models, and structuring data loaders and models for multi-node, distributed training.

Stanford IRIS Lab – Prof. Chelsea Finn
Undergraduate/Master's student   *October 2020 — June 2023*

Research focused on robotics-oriented offline reinforcement learning. Three first/co-first-author publications:

- D5RL: a benchmark to evaluate offline RL and offline-to-online fine-tuning methods on visually diverse, realistic, simulated robotics tasks. Co-first-author publication at the Reinforcement Learning Conference (RLC) 2024.
- MOTO: a model-based reinforcement learning method designed for efficient offline-to-online fine-tuning for vision-based manipulation tasks. Co-first-author publication in the Conference on Robot Learning (CoRL) 2023.
- LAEO: an offline reinforcement learning method using contrastive learning for data without reward labels. First-author publication in the Learning for Dynamics & Control Conference (L4DC) 2023.

Stanford Intelligent Systems Laboratory (SISL) – Prof. Mykel Kochenderfer
Undergraduate student   *June 2019 — March 2021*

Research focused on using machine learning and reinforcement learning techniques to improve collision avoidance in autonomous vehicles and unmanned aerial vehicles (UAVs). Two first/co-first-author publications:

- A method to learn 3D velocity maps from radar data for autonomous vehicles. Co-first-author

publication in the IEEE International Conference on Intelligent Robots and Systems (IROS) 2021.
- ○ A collision avoidance system for autonomous drones using monocular vision and deep reinforcement learning. First-author publication in the American Institute of Aeronautics and Astronautics (AIAA) SciTech Forum 2021.

Johns Hopkins University Applied Physics Laboratory (APL)

Research Intern   *June 2020 — May 2021*

Developed a reinforcement learning-based method to autonomously respond to cybersecurity threats on industrial control systems. Second author publication in the IEEE/IFIP International Conference on Dependable Systems and Networks Workshops (DSN-W), 2022.

Stanford Network Analysis Project (SNAP) – Prof. Jure Leskovec

Undergraduate student   *September 2019 — June 2020*

Conducted research on using graph convolutional networks to predict interactions between microbes in the human gastrointestinal tract.

PUBLICATIONS

Please see my Google Scholar profile for a complete list of publications.

Published/Accepted

Hatch, K., Balakrishna, A., Mees, O., Nair, S., Wulfe, B., Itkina, M., Eysenbach, B., Levine, S., Kollar, T., and Burchfiel, B., "GHIL-Glue: Hierarchical Control with Filtered Subgoal Images," *IEEE International Conference on Robotics and Automation (ICRA)*, 2025. PDF   Website

Kolev, V.*, Rafailov, R.*, **Hatch, K. B.,** Wu, J., and Finn, C., "Efficient Imitation Learning with Conservative World Models," *Learning for Dynamics & Control Conference (L4DC)*, 2024. PDF

Rafailov, R.*, **Hatch, K. B.*,** Singh, A., Smith, L., Kumar, A., Kostrikov, I., Hansen-Estruch, P., Kolev, V., Ball, P., Wu, J., Finn, C., and Levine, S., "D5RL: Diverse Datasets for Data-Driven Deep Reinforcement Learning," *Reinforcement Learning Conference (RLC)*, 2024. PDF

Rafailov, R.*, **Hatch, K. B.*,** Kolev, V., Martin, J., Phielipp, M., and Finn, C., "MOTO: Offline to Online Fine-tuning for Model-Based Reinforcement Learning," *Conference on Robot Learning (CoRL)*, 2023. PDF   Website

Hatch, K. B., Eysenbach, B., Yu, T., Rafailov, R., Salakhutdinov, R., Levine, S., and Finn, C., "Contrastive Example-Based Control," *Learning for Dynamics & Control Conference (L4DC)*, 2023. PDF   Website

Zhou, G., Dean, V., Srirama, M. K., Rajeswaran, A., Pari, J., **Hatch, K. B.,** Jain, A., Yu, T., Abbeel, P., Pinto, L., Finn, C., and Gupta, A., "Train Offline, Test Online: A Real Robot Learning Benchmark," *IEEE International Conference on Robotics and Automation (ICRA)*, 2023. PDF   Website

Mern, J., **Hatch, K.,** Silva, R., Hickert, C., Sookoor, T., and Kochenderfer, M. J., "Autonomous Attack Mitigation for Industrial Control Systems," *IEEE/IFIP International Conference on Dependable Systems and Networks Workshops (DSN-W)*, 2022, pp. 28–36. PDF

Senanayake, R.*, **Hatch, K.*,** Zheng, J., and Kochenderfer, M. J., "3D Radar Velocity Maps for Uncertain Dynamic Environments," *IEEE International Conference on Intelligent Robots and Systems (IROS)*, 2021. PDF   Presentation

Hatch, K., Mern, J., and Kochenderfer, M. J., "Obstacle Avoidance Using a Monocular Camera," *American Institute of Aeronautics and Astronautics (AIAA) SciTech Forum*, 2021. PDF   Presentation

*denotes equal contribution

OUTREACH

Breakthrough Silicon Valley (BTSV)   **San Jose, CA**
Volunteer tutor   *November 2023 – April 2024*

Provided homework support to high school students who are on track to becoming first-generation college students. Primarily assisted with mathematics.

East Palo Alto Stanford Academy (EPASA)   **Stanford, CA**
Volunteer tutor   *October 2018 – March 2020*

Provided homework support to seventh and eighth grade students from low-income backgrounds in mathematics and English, and helped students to develop effective study skills.

Stanford 1st Ward Volunteer Tutoring Program   **Stanford, CA**
Volunteer tutor   *September 2017 – June 2019*

Provided homework support to K-12 students in mathematics, reading, and English.

SKILLS

Machine Learning Frameworks	JAX, PyTorch, Tensorflow 2.0
Cloud Computing	Amazon SageMaker
Reinforcement Learning Tools	deepmind-acme, TF-Agents, RLkit, JAXRL
Simulation Tools	MuJoCo, Microsoft AirSim
Programming Languages	Python, C++