

Kyle Hatch

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EDUCATION

University of Southern California

PhD in Computer Science

Los Angeles, CA

Expected graduation: May 2030

Stanford University

M.S. in Computer Science

Stanford, CA

Graduated: June 2023

Stanford University

B.S. with honors in Computer Science

Stanford, CA

Graduated: June 2022

RESEARCH EXPERIENCE

Research Focuses: Robot Learning, Reinforcement Learning, Generative Models

University of Southern California (USC)

PhD student (co-advised by Yue Wang and Daniel Seita)

August 2025 – Present

Current research focuses on using human video data and generative models to increase the generalization capacity of robot agents.

Toyota Research Institute (TRI)

AI Resident in the Large Behavior Models (LBM) Division

July 2023 – August 2025

Developed a method to use image and video generative models to guide robotic manipulation policies, leading to a first-author publication in ICRA 2025.

Stanford IRIS Lab – Prof. Chelsea Finn

Undergraduate/Master's student

October 2020 — June 2023

Led/co-led three projects on robotics-oriented offline reinforcement learning. First-author/co-first author publications in CoRL 2023, L4DC 2023, and RLC 2024.

Stanford Intelligent Systems Laboratory (SISL) – Prof. Mykel Kochenderfer

Undergraduate student

June 2019 — March 2021

Led/co-led two projects on using machine learning and reinforcement learning for collision avoidance in unmanned aerial vehicles (UAVs). First-author/co-first-author publications in IROS 2021 and AIAA SciTech Forum 2021.

SELECTED PUBLICATIONS

Please see my [Google Scholar](#) profile for a complete list of publications.

Hatch, K., Balakrishna, A., Mees, O., Nair, S., Wulfe, B., Itkina, M., Eysenbach, B., Levine, S., Kollar, T., and Burchfiel, B., "GHIL-Glue: Hierarchical Control with Filtered Subgoal Images," *IEEE International Conference on Robotics and Automation (ICRA)*, 2025. [PDF](#) [Website](#)

Kolev, V.*, Rafailov, R.* **Hatch, K. B.**, Wu, J., and Finn, C., "Efficient Imitation Learning with Conser-

vative World Models," *Learning for Dynamics & Control Conference (L4DC)*, 2024. [PDF](#)

Rafailov, R.* **Hatch, K. B.***, Singh, A., Smith, L., Kumar, A., Kostrikov, I., Hansen-Estruch, P., Kolev, V., Ball, P., Wu, J., Finn, C., and Levine, S., "D5RL: Diverse Datasets for Data-Driven Deep Reinforcement Learning," *Reinforcement Learning Conference (RLC)*, 2024. [PDF](#)

Rafailov, R.* **Hatch, K. B.***, Kolev, V., Martin, J., Phielipp, M., and Finn, C., "MOTO: Offline to Online Fine-tuning for Model-Based Reinforcement Learning," *Conference on Robot Learning (CoRL)*, 2023. [PDF](#) [Website](#)

Hatch, K. B., Eysenbach, B., Yu, T., Rafailov, R., Salakhutdinov, R., Levine, S., and Finn, C., "Contrastive Example-Based Control," *Learning for Dynamics & Control Conference (L4DC)*, 2023. [PDF](#) [Website](#)

Senanayake, R.* **Hatch, K.***, Zheng, J., and Kochenderfer, M. J., "3D Radar Velocity Maps for Uncertain Dynamic Environments," *IEEE International Conference on Intelligent Robots and Systems (IROS)*, 2021. [PDF](#) [Presentation](#)

Hatch, K., Mern, J., and Kochenderfer, M. J., "Obstacle Avoidance Using a Monocular Camera," *American Institute of Aeronautics and Astronautics (AIAA) SciTech Forum*, 2021. [PDF](#) [Presentation](#)

*denotes equal contribution

SKILLS

Machine Learning Frameworks PyTorch, JAX, Tensorflow 2.0

Programming Languages Python, C++, Julia

Cloud Computing Amazon SageMaker

Reinforcement Learning Tools deepmind-acme, TF-Agents, RLkit, JAXRL

OUTREACH

Breakthrough Silicon Valley (BTSV)

San Jose, CA

Volunteer tutor

November 2023 – April 2024

Provided homework support to high school students who are on track to becoming first-generation college students. Primarily assisted with mathematics.

East Palo Alto Stanford Academy (EPASA)

Stanford, CA

Volunteer tutor

October 2018 – March 2020

Provided homework support to seventh and eighth grade students from low-income backgrounds in mathematics and English, and helped students to develop effective study skills.

Stanford 1st Ward Volunteer Tutoring Program

Stanford, CA

Volunteer tutor

September 2017 – June 2019

Provided homework support to K-12 students in mathematics, reading, and English.