

Applied Time Series Econometrics

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Forecast evaluation

- Last time we made two (very similar) forecasts from two different models for one time series.
- Previously we have already compared candidate models in terms of their forecasting accuracy.
- To do it, we calculate pseudo real-time forecasts for the periods for which we have the data available and compute the measures of accuracy.



Series to compare

- For employment in manufacturing series:

```
empl_manuf <- read_csv("empl_manuf.csv")
empl <- ts(empl_manuf, start = c(1992, 1), freq = 12)
train = window(empl, end = c(2001,12))
fit1 <- Arima(train, order = c(3,2,4),
              seasonal = c(0,0,1))
fore1 <- forecast(fit1, h = 24)
fit2 <- auto.arima(train)
fore2 <- forecast(fit1, h = 24)
options(digits = 3)
accuracy(fore1, empl)
accuracy(fore2, empl)
```

Accuracy measures

##		ME	RMSE	MAE	MPE	MAPE	MASE
##	Training set	-0.0149	0.818	0.498	-0.000115	0.362	0.0563
##	Test set	-1.8850	2.470	2.002	-1.847460	1.953	0.2263

##		ME	RMSE	MAE	MPE	MAPE	MASE
##	Training set	-0.00506	0.86	0.504	0.00397	0.363	0.0569
##	Test set	-1.94594	2.50	2.036	-1.90467	1.986	0.2301

Comparison with baseline alternatives

- Sometimes we are interested in comparing the forecast given by an econometric model with a simple benchmark.
- The main question here: is it reasonable to spend time on a relatively complicated model if a simple alternative has a similar forecasting performance?
- What are these useful simple alternatives that may play a role of a benchmark?

Simple forecasting models (1)

Average method

- A forecast of all future values is equal to mean of historic data $\{y_1, \dots, y_T\}$.
- Forecasts:

$$\hat{y}_{T+h|T} = \bar{y} = \frac{1}{T} \sum_{i=1}^T y_i$$

- It is a forecast using a WN with a constant model: $y_t = \mu + \nu_t$

Naïve method

- A forecast is equal to the last observed value.
- Forecasts:

$$\hat{y}_{T+h|T} = y_T$$

- It is a forecast using a random walk model: $y_t = y_{t-1} + \nu_t$

Simple forecasting models (2)

Seasonal naïve method

- A forecast is equal to the last value from the same season
- Forecasts:

$$\hat{y}_{T+h|T} = y_{T+h-km},$$

where m is a seasonal period and $k = \lfloor (h-1)/m \rfloor + 1$, where $\lfloor \cdot \rfloor$ means an integer part

- It is a forecast using a seasonal random walk model:

$$y_t = y_{t-m} + \nu_t$$

Simple forecasting models(3)

Drift method

- A forecast is equal to the last value plus the average change
- Forecasts are:

$$\begin{aligned}y_{T+h,T} &= y_T + \frac{h}{T-1} \sum_{t=2}^T (y_t - y_{t-1}) = \\ &= y_T + \frac{h}{T-1} (y_T - y_1)\end{aligned}$$

- Equivalent to extrapolating a line between the first and the last observations.
- It is a forecast using a random walk with drift model:

$$y_t = \mu + y_{t-1} + \nu_t$$

Simple forecasts: codes

Mean forecast:

```
meanf(x, h = 12)
```

Naïve forecast

```
naive(x, h = 12)  
rwf(x, h = 12)
```

Seasonal naïve forecast

```
snaive(x, h=12)
```

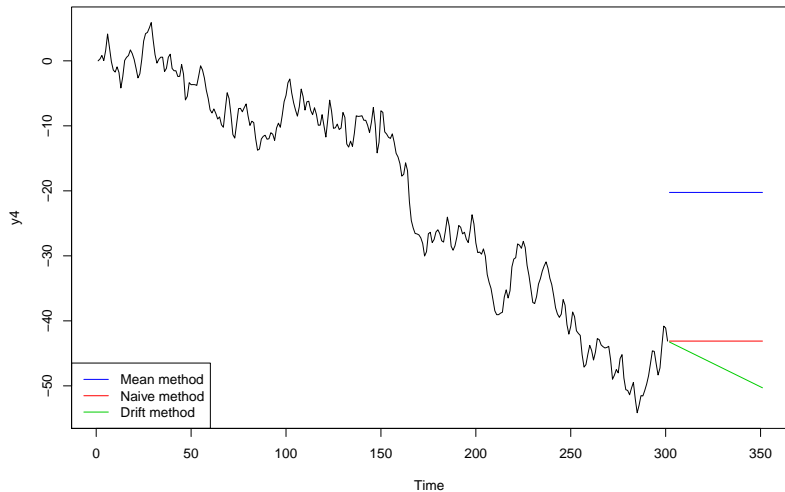
Drift forecast

```
rwf(x, drift = TRUE, h=12)
```

Example: code

```
set.seed(500)
y4 <- arima.sim(model = list(order = c(4,1,4),
ar = c(0.3, -0.4,0,-0.2), ma = c(0.8,0,0,0.5),
mean = 2), n = 300)
for1 <- meanf(y4, h = 50)
for2 <- naive(y4, h = 50)
for3 <- rwf(y4, drift = TRUE, h = 50)
plot(y4, xlim = c(1,350))
lines(for1$mean,col = 4)
lines(for2$mean, col = 2)
lines(for3$mean, col = 3)
legend("bottomleft",lty=1,col=c(4,2,3),
      legend=c("Mean method","Naive method","Drift method"))
```

Simple forecasts: a graph

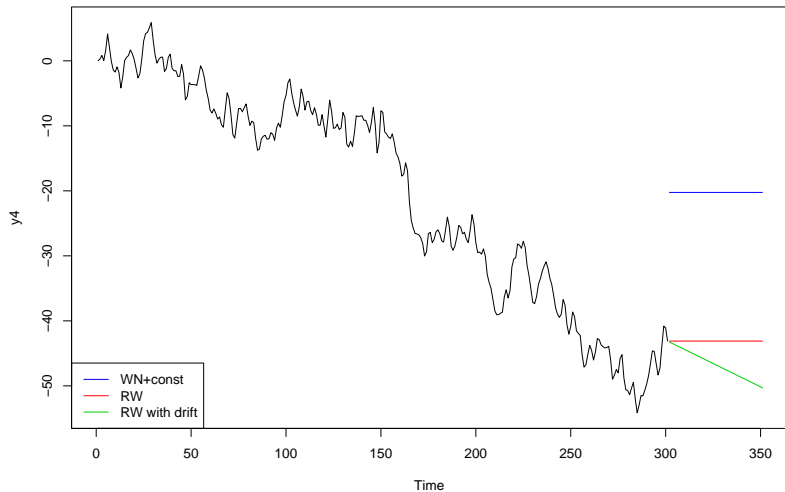


Simple forecasts: an alternative code

Sure, the same forecasts can be obtained by fitting an ARIMA model.

```
fit1 <- Arima(y4, order = c(0,0,0), include.constant = TRUE)
fit2 <- Arima(y4, order = c(0,1,0))
fit3 <- Arima(y4, order = c(0,1,0), include.drift = TRUE)
fore1 <- forecast(fit1, h = 50)
fore2 <- forecast(fit2, h = 50)
fore3 <- forecast(fit3, h = 50)
plot(y4, xlim = c(1,350))
lines(fore1$mean, col = 4)
lines(fore2$mean, col = 2)
lines(fore3$mean, col = 3)
legend("bottomleft", lty=1, col=c(4,2,3),
      legend=c("WN+const", "RW", "RW with drift"))
```

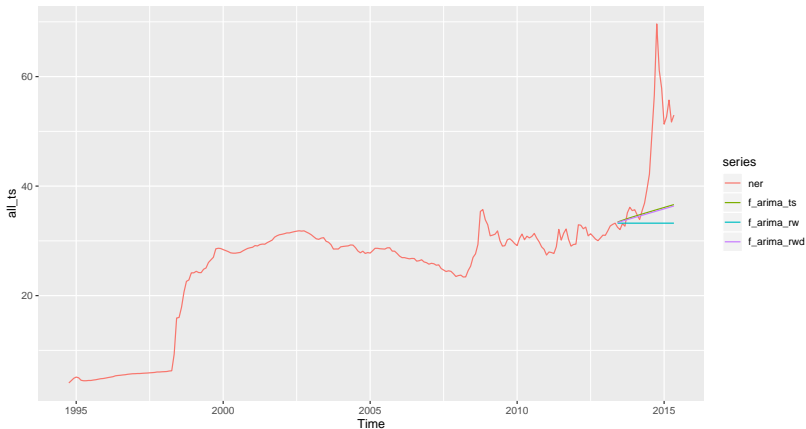
The same graph from the alternative code.



Application: a nominal exchange rate

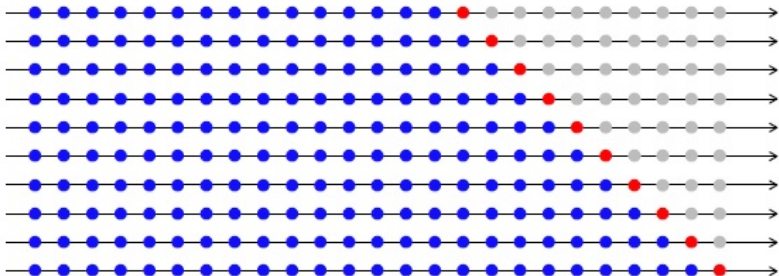
(see code)

```
autoplot(all_ts)
```



Cross-validation

- Cross-validation is very popular in time-series analysis as it allows the researcher not to lose some potentially important information.



Cross-validation algorithm

Assume k is the minimum number of observations for a training set.

- Select k , take $i = 0$ and use observations $1, 2, \dots, k + i$ to estimate model. Compute error on forecast for time $k + i + h$ as made in period $k + i$.
- Repeat for $i = 1, \dots, T - h - k$ where T is total number of observations.
- Compute accuracy measures over all errors for a given h .

Also called rolling forecasting origin because the origin ($k + i$) at which forecast is based rolls forward in time.

Cross-validation example

We can do the cross validation with the `tsCV()` function from the `forecast` package.

```
# It is necessary to create a forecasting function first
fore_arima_212 <- function(y, h) {
  model <- Arima(y, order = c(2, 1, 2),
                 include.drift = TRUE)
  forecast <- forecast(model, h)
  return(forecast)
}
errors_cv <- tsCV(ner, fore_arima_212, h = 1)
errors_cv
```

NB! The forecasting errors are returned by the `tsCV()` function

Multivariate analysis: introduction

- A natural extension of the of the univariate ARMA class of models is one in which y_t represents a vector of n time series. Let Φ_i and Ψ_i be $(n \times n)$ matrices:

$$\Phi_i = \begin{pmatrix} \phi_{i,1,1} & \cdots & \phi_{i,1,n} \\ \vdots & \ddots & \vdots \\ \phi_{i,n,1} & \cdots & \phi_{i,n,n} \end{pmatrix} \quad \Psi_i = \begin{pmatrix} \psi_{i,1,1} & \cdots & \psi_{i,1,n} \\ \vdots & \ddots & \vdots \\ \psi_{i,n,1} & \cdots & \psi_{i,n,n} \end{pmatrix}$$

where $\phi_{i,j,k}$ is the autoregressive parameter at lag i in equation j on variable k and $\psi_{i,j,k}$ is the corresponding moving-average parameter.

Multivariate model classification(1)

- The multivariate analogue of the ARMA(p,q) model is the vector ARMA (VARMA(p,q)):

$$y_t = \mu + \sum_{i=1}^p \Phi_i y_{t-i} + v_t + \sum_{i=1}^q \Psi_i v_{t-i}, \quad v_t \sim iidN(0, \Omega),$$

where v_t is an n -dimensional disturbance vector with zero mean vector, μ is a n -dimensional vector, and $(n \times n)$ covariance matrix Ω and $\{\mu, \Phi_1, \dots, \Phi_p, \Psi_1, \dots, \Psi_q, \Omega\}$ are unknown parameters.

Multivariate model classification(2)

Using lag operators, the $VARMA(p, q)$ class of model is represented as:

$$\Phi_p(L)y_t = \mu + \Psi_q(L)v_t, \quad v_t \sim iid(0, \Omega),$$

where:

$$\begin{aligned}\Phi_p(L) &= I - \Phi_1 L - \Phi_2 L^2 - \dots - \Phi_p L^p \\ \Psi_q(L) &= I - \Psi_1 L - \Psi_2 L^2 - \dots - \Psi_q L^q\end{aligned}$$

are matrix polynomials in the lag operator L .

Vector autoregression (VAR)

An important special case of the VARMA model is one in which there are p autoregressive lags and no moving average lags, $q = 0$. This special case is a $VAR(p)$ model:

$$y_t = \mu + \Phi_1 y_{t-1} + \cdots + \Phi_p y_{t-p} + v_t$$

Properties

- Each variable is expressed as a function of its own lags and the lags of all the other variables in the system.
- The lag structure on all variables in all equations is the same.

! This is a reduced-form VAR. We will discuss a structural VAR models later.

VAR(1) model: example

A trivariate ($n = 3$) VAR model with one lag VAR(1) is:

$$y_{1,t} = \mu_1 + \phi_{1,1,1}y_{1,t-1} + \phi_{1,1,2}y_{2,t-1} + \phi_{1,1,3}y_{3,t-1} + v_{1,t}$$

$$y_{2,t} = \mu_2 + \phi_{1,2,1}y_{1,t-1} + \phi_{1,2,2}y_{2,t-1} + \phi_{1,2,3}y_{3,t-1} + v_{2,t}$$

$$y_{3,t} = \mu_3 + \phi_{1,3,1}y_{1,t-1} + \phi_{1,3,2}y_{2,t-1} + \phi_{1,3,3}y_{3,t-1} + v_{3,t}$$

Example: matrix notation

In matrix notation, the model becomes:

$$\begin{pmatrix} y_{1,t} \\ y_{2,t} \\ y_{3,t} \end{pmatrix} = \begin{pmatrix} \mu_1 \\ \mu_2 \\ \mu_3 \end{pmatrix} + \begin{pmatrix} \phi_{1,1,1} & \phi_{1,1,2} & \phi_{1,1,3} \\ \phi_{1,2,1} & \phi_{1,2,2} & \phi_{1,2,3} \\ \phi_{1,3,1} & \phi_{1,3,2} & \phi_{1,3,3} \end{pmatrix} \begin{pmatrix} y_{1,t-1} \\ y_{2,t-1} \\ y_{3,t-1} \end{pmatrix} + \begin{pmatrix} v_{1,t} \\ v_{2,t} \\ v_{3,t} \end{pmatrix}$$

or, more compactly,

$$y_t = \mu + \Phi_1 y_{t-1} + v_t$$

The model contains:

- 3 intercepts
- 9 autoregressive parameters
- 6 parameters in the covariance matrix

Stability condition

A formal statement of stability The n -dimensional variable y_t is stable provided that the roots of the polynomial $|\Phi_p(z)| = 0$ lie outside the unit circle ($|\cdot|$ denotes the determinant of the matrix).

$$y_t = \mu + \Phi_1 y_{t-1} + \Phi_2 y_{t-2} + v_t$$

Example:

$$\Phi_1 = \begin{pmatrix} 1.279 & -0.355 \\ 0.002 & 1.234 \end{pmatrix} \quad \Phi_2 = \begin{pmatrix} -0.296 & 0.353 \\ 0.007 & -0.244 \end{pmatrix}$$

The polynomial $|I - \Phi_1 z - \Phi_2 z^2| = 0$

$$\left| \begin{pmatrix} 1 - 1.279z + 0.296z^2 & 0.355z - 0.353z^2 \\ -0.002z - 0.007z^2 & 1 + 1.234z + 0.244z^2 \end{pmatrix} \right| = 0$$

Solution

The equation may be written as:

$$(1 - 1.279z + 0.296z^2)(1 + 1.234z + 0.244z^2) - (0.355z - 0.353z^2)(-0.002z - 0.007z^2) = 0$$

The roots are:

$$z_1 = 4.757$$

$$z_2 = 2.874$$

$$z_3 = 1.036$$

$$z_2 = 1.011$$

Because $|z_i| > 1 \quad \forall i$ both processes are jointly stable.

- The parameters of VARMA (exactly as ARMA) models are estimated by maximum likelihood method.
- For the important special case where there are no moving average terms, it is shown that the ML estimates are obtained by OLS.
- In R, we estimate VAR(p) models with the VAR() function from the vars package.
- But there are two decisions to make before using the software:
 - * How many variables to include (k)?
 - * What should be the order of the model (p)?

How many variables? Be reasonable!

- The number of coefficients to be estimated in VAR per equation is $1 + pn$, so the total number of parameters to estimate is:

$$\text{Number of parameters} = n(1 + pn)$$

Example: $n = 5$, $p = 3$ so the total number of parameters to estimate is equal to 80.

The more coefficients to be estimated the larger the estimation error entering the forecast.

Conclusion: In practice it is usual to keep n small and include only variables that are correlated to each other and therefore useful in forecasting each other.

- ① Martin, V., Hurn, S., and HarriS,D. (2013) Econometric Modelling with Time Series: Specification, Estimating and Testing, New York, Cambridge University Press
- ② Hyndman, R. J. and Athanasopoulos, G. (2013) Forecasting: principles and practice, Otexts
- ③ Lütkepohl, H., and Krätzig, M. (2004) Applied Time Series Econometrics, New York, Cambridge University Press