

SC.2) Proposition: For $T \in \mathcal{L}(V)$, if $V = \text{null } T \oplus \text{range } T$, then T must be diagonalizable.

Counterexample: If V is not finite dimensional, then T cannot be diagonalizable.

Let $V = \mathbb{F}^{\infty}$. Let the standard basis for V be e_1, e_2, \dots e.g. $e_1 = (1, 0, 0, \dots)$

Let $v \in V : v = a_1 e_1 + a_2 e_2 + a_3 e_3 + a_4 e_4 + \dots$

Let $Tv = a_3 e_3 + a_4 e_4 + \dots$

Hence $\text{null } T = \text{span}(e_1, e_2)$

$\text{range } T = \text{span}(e_3, e_4, e_5, \dots)$

$\text{null } T \oplus \text{range } T = V$.

But $\text{range } T$ is infinite dimensional $\Rightarrow V$ is infinite dimensional
 $\Rightarrow T$ cannot be diagonalized.

□.

SC.1) Suppose $T \in \mathcal{L}(V)$ is diagonalizable

Then let e_1, \dots, e_n be the basis such that $M(T)$ is diagonal.

Hence e_1, \dots, e_n are eigenvectors of T .

$Te_k = \lambda_k e_k$ for all $k=1, \dots, n$.

We know that e_1, \dots, e_n are linearly independent.

For the vectors $Te_k = \lambda_k e_k$ where $\lambda_k \neq 0$, $e_k \in \text{range } T$.

Alternatively, for vectors $Te_k = \lambda_k e_k$ where $\lambda_k = 0$, $e_k \in \text{null } T$.

Hence all vectors e_1, \dots, e_n can be partitioned into two sets: $\text{range } T$ and $\text{null } T$.

No vector in e_1, \dots, e_n exists in both $\text{range } T$ and $\text{null } T$.

Since e_1, \dots, e_n form a basis in V , this also means that
 $\text{range } T \cap \text{null } T = \{0\}$.

Hence we showed that e_1, \dots, e_n which forms a basis of V can be partitioned into $\text{range } T$ and $\text{null } T$, with $\text{range } T \cap \text{null } T = \{0\}$

$\Rightarrow V = \text{null } T \oplus \text{range } T$.

□.

5C.8) $T \in \mathcal{L}(\mathbb{F}^5)$

$\dim E(B, T) = 4 \Rightarrow$ there exists a linearly independent list of vectors v_1, v_2, v_3, v_4 such that

$$T v_k = 8 v_k \text{ for } k=1, \dots, 4.$$

Suppose $T - 2I$ is not invertible, then 2 is an eigenvalue. Let v_5 be the eigenvector corresponding to 2.

Hence v_5 is independent of v_1, \dots, v_4 , thus v_1, \dots, v_5 form a basis of \mathbb{F}^5 .

Using the fundamental thm of linear maps,

$$\begin{aligned} \dim \mathbb{F}^5 &= \dim \text{range } T + \dim \text{null } T \\ 5 &= \dim \text{range } T + \dim \text{null } T. \end{aligned}$$

Since v_1, \dots, v_5 are all eigenvectors of T with non-zero eigenvalues, and v_1, \dots, v_5 also forms the basis of \mathbb{F}^5 ,

$$\text{null } T = \{0\}.$$

$$\text{Hence } V = E(B, T) + E(2, T)$$

$\Rightarrow T$ does not have eigenvalue with value 6

and $T - 6I$ is injective.

The same argument applies for the case where 6 is an eigenvalue of T , instead of 2.

Hence either $T - 2I$ or $T - 6I$ is invertible

□

5C.14) $T \in \mathcal{L}(\mathbb{C}^3)$ s.t. $\exists v_1, v_2$ where $T v_1 = 6 v_1$
 $T v_2 = 7 v_2$

and T does not have a diagonal matrix.

$$\text{Let } T(x, y, z) = (6x, 7y, 6z + y)$$

$$M(T) = \begin{bmatrix} 6 & 0 & 0 \\ 0 & 7 & 1 \\ 0 & 0 & 6 \end{bmatrix}$$

$$T v = \lambda v$$

$$6x = \lambda x \Rightarrow 6 \text{ can be an eigenvalue}$$

$$7y = \lambda y \Rightarrow 7 \text{ can be an eigenvalue}$$

$$6z + y = \lambda z$$

$$y = (\lambda - 6)z$$

T is not diagonalizable since there are only 2 eigenvectors of T .

□

8C.8) $TE \mathcal{L}(V)$. T is invertible iff constant term in minimal polynomial of T is non-zero.

Pf.: Assuming that T is invertible,

By lemma 5.27, T must have an upper triangular matrix w.r.t some basis. Since T is invertible, by lemma 5.30, the entries along the diagonals of the matrix must be non-zero.

Hence there must exist $\dim V$ eigenvectors for T , since by lemma 5.32, the entries in the diagonals of the upper triangular representation of T are the eigenvalues.

By lemma 6.4a, the eigenvalues must be the roots of the minimal polynomial.

Since none of the eigenvalues of V are non-zero, zero cannot be a root of the minimal polynomial.

Thus there must exist a constant term in the minimal polynomial so zero cannot be a root. \square

Now, assume that the minimal polynomial has a non-zero constant term.


Then by the fundamental theorem of algebra, there exists a root in the minimal polynomial.

This root cannot be 0 since the minimal polynomial has a nonzero constant term. Since the roots of the minimal polynomial are the eigenvalues of T , and 0 is not an eigenvalue of T , $\text{null } T = \{0\}$ and T is invertible. \square

Q1) Example of $T \in \mathcal{L}(\mathbb{R}^3)$ whose minimal polynomial is $(x+2)^2$.

$$T(x, y, z) = (-2x, -2y, -2y-2z)$$

$$\begin{aligned}(T+2)^2 &= (T+2)(T+2)v \\&= (T+2)(Tv+2v) \\&= (T+2)(Tv + (2x, 2y, 2z)) \\&= (T+2)[(-2x, -2y, -2y-2z) + (2x, 2y, 2z)] \\&= (T+2)(0, 0, -2y) \\&= (0, 0, 4y) + (0, 0, -4y) \\&= (0, 0, 0).\end{aligned}$$

$\Rightarrow T(x, y, z) = (-2x, -2y, -2y-2z)$
has the minimal polynomial $(x+2)^2$ 

b) Minimal polynomial: $(x^2+1)(x-3)^2$
 $\Rightarrow i, -i, 3$ are eigenvalues.

$$T = \begin{bmatrix} i & & & \\ & -i & & \\ & & 3 & \\ & & & 3 \end{bmatrix} \quad T^2 = \begin{bmatrix} -1 & & & \\ & -1 & & \\ & & 9 & \\ & & & 9 \end{bmatrix} \quad T^2+1 = \begin{bmatrix} 0 & & & \\ & 0 & & \\ & & 10 & \\ & & & 10 \end{bmatrix}$$

$$T-3 = \begin{bmatrix} i-3 & & & \\ & -i-3 & & \\ & & 0 & \\ & & & 0 \end{bmatrix} \quad (T-3)^2 = \begin{bmatrix} -1-6i+9 & & & \\ & -1+6i+9 & & \\ & & 0 & \\ & & & 0 \end{bmatrix} = \begin{bmatrix} 8-6i & & & \\ & 8+6i & & \\ & & 0 & \\ & & & 0 \end{bmatrix}$$

$$(T-3)^2(T^2+1) = \begin{bmatrix} 8-6i & & & \\ & 8+6i & & \\ & & \ddots & \\ & & & 10 \end{bmatrix} \begin{bmatrix} 10 & & & \\ & 10 & & \\ & & 6 & \\ & & & 10 \end{bmatrix} = \begin{bmatrix} 0 & & & \\ & \ddots & & \\ & & 0 & \\ & & & 0 \end{bmatrix}$$

$$x=1 \Rightarrow T = \begin{bmatrix} i & & & \\ & -i & & \\ & & 3 & \\ & & & 3 \end{bmatrix} \text{ has minimal polynomial } (x^2+1)(x-3)^2$$

$$\Rightarrow T(x, y, z, a, b) = (ix, -iy, 3z, 3a, a+3b)$$

Suppose $T(x, y, z, a, b) = (ix, -iy, 3z, 3a, a+3b)$; prove that $(x^2+1)(x-3)^2$ is a minimal polynomial.

Pf: $T^2(x, y, z, a, b) = (-x, -y, 9z, 9a, 3a+3a+9b)$
 $= (-x, -y, 9z, 9a, 6a+9b)$

$$(T^2+1)(x, y, z, a, b) = (0, 0, 10z, 10a, 6a+10b)$$

$$(T-3)(x, y, z, a, b) = (ix-3x, -iy-3y, 0, 0, a)$$

$$(T-3)^2(x, y, z, a, b) = (i(ix-3x)-3(ix-3x), \dots, 0, 0, 0)$$

$$(T-3)^2(T^2+1)(x, y, z, a, b) = (0, 0, 0, 0, 0)$$

$\Rightarrow (x-3)^2(x^2+1)$ is a minimal polynomial. ✓

1) a) eigenvalues: -2
b) $i, -i, 3$

2) $T = \begin{bmatrix} 2 & & & \\ & 3 & & \\ & & 3 & \\ & & & 3 \end{bmatrix}$

$$T \cdot v = \lambda \cdot v$$

$$T \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} 2a \\ 3b + d \\ 3c \\ 3d \end{bmatrix} = \begin{bmatrix} \lambda a \\ \lambda b \\ \lambda c \\ \lambda d \end{bmatrix}$$

$$\begin{aligned} 2a &= \lambda a \\ 3b + d &= \lambda b \\ 3c &= \lambda c \\ 3d &= \lambda d \end{aligned} \Rightarrow \text{eigenvalues: } (2, 3, 3, 3)$$

Characteristic polynomial: $(x-2)(x-3)^3 = 0$

Factors of $(x-2)(x-3)^3$:

$$(x-2) \Rightarrow T - 2I \Rightarrow \begin{bmatrix} 0 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix} \times$$

$$(x-3) \Rightarrow T - 3I \Rightarrow \begin{bmatrix} -1 & & & \\ & 0 & & \\ & & 0 & \\ & & & 0 \end{bmatrix} \times$$

$$(x-2)(x-3) \Rightarrow \begin{bmatrix} 0 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix} \begin{bmatrix} -1 & & & \\ & 0 & & \\ & & 0 & \\ & & & 0 \end{bmatrix} = \begin{bmatrix} 0 & & & \\ & 0 & & \\ & & 0 & \\ & & & 0 \end{bmatrix} \times$$

$$(x-3)^2 \Rightarrow \begin{bmatrix} 1 & & & \\ & 0 & & \\ & & 0 & \\ & & & 0 \end{bmatrix} \times$$

$$(x-3)^2(x-2) \Rightarrow \begin{bmatrix} 0 & & & \\ & 0 & & \\ & & 0 & \\ & & & 0 \end{bmatrix} \Rightarrow (x-3)^2(x-2) \text{ is minimal polynomial } \square$$