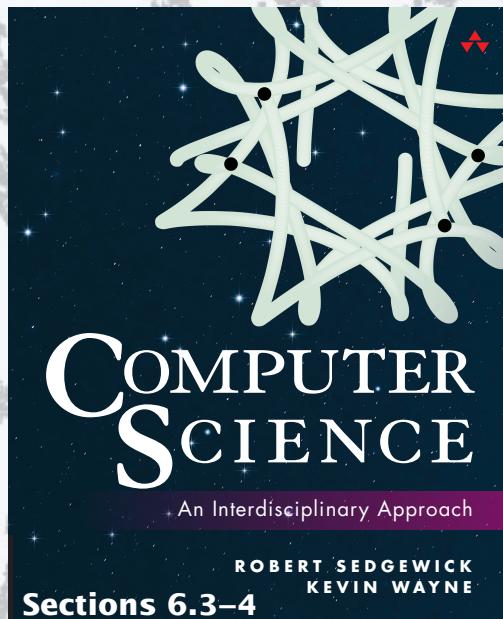


COMPUTER SCIENCE
SEGEWICK / WAYNE

PART II: ALGORITHMS, MACHINES, and THEORY



<http://introcs.cs.princeton.edu>

20. Central Processing Unit

20. CPU

- **Overview**
- Bits, registers, and memory
- Program counter
- Components and connections

Let's build a computer!

CPU = Central Processing Unit

Computer

Display

Touchpad

Battery

Keyboard

...

CPU (difference between a TV set and a computer)

Previous lecture

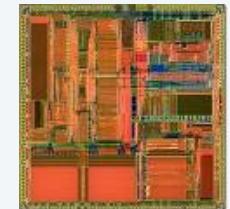
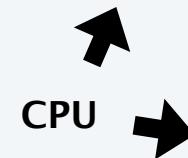
Combinational circuits

ALU (calculator)

This lecture

Sequential circuits with *memory*

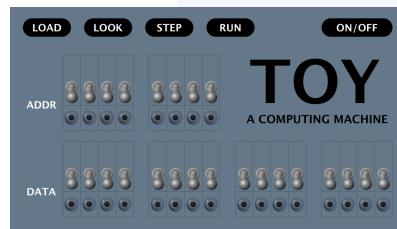
CPU (computer)



A smaller computing machine: TOY-8

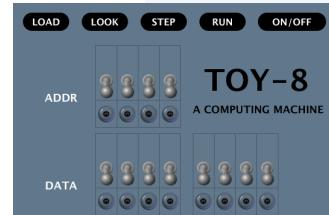
TOY instruction-set architecture.

- 256 16-bit words of memory.
- 16 16-bit registers.
- 1 8-bit program counter.
- 2 instruction types.
- 16 instructions.



TOY-8 instruction-set architecture.

- 16 8-bit words of memory.
- 1 8-bit register.
- 1 4-bit program counter.
- 1 instruction type.
- 8 instructions.



Type 1 instruction

opcode	Rd	Rs	Rt

4 bits to specify one of 16 registers

Type 2 instruction

opcode	Rd	addr

8 bits to specify one of 256 memory words

TOY-8 instruction

opcode	addr

3 bits to specify one of 8 instructions

4 bits to specify one of 16 memory words

always 0
(future expansion of memory or instruction set)

Purpose of TOY-8. Illustrate CPU circuit design for a "typical" computer.

TOY-8 reference card

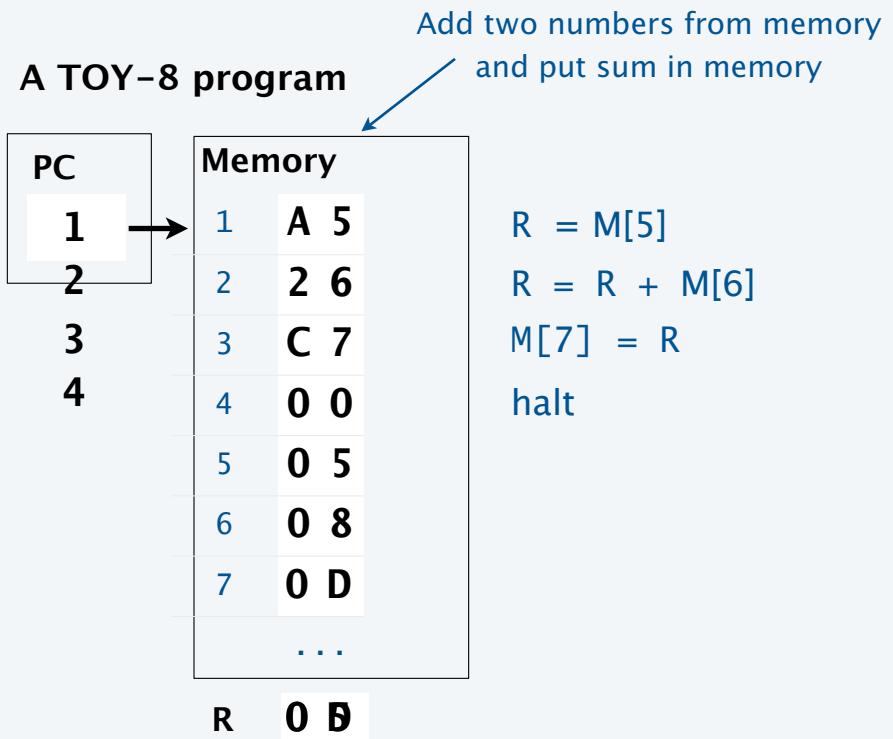
opcode	addr
	0

opcode	operation	pseudo-code
0	halt	halt
2	add	$R = R + M[\text{addr}]$
4	bitwise and	$R = R \& M[\text{addr}]$
6	bitwise xor	$R = R \wedge M[\text{addr}]$
8	load addr	$R = \text{addr}$
A	load	$R = M[\text{addr}]$
C	store	$M[\text{addr}] = R$
E	branch zero	if ($R == 0$) PC = addr

ZERO $M[0]$ is always 0.

STANDARD INPUT Load from $M[F]$.

STANDARD OUTPUT Store to $M[F]$.



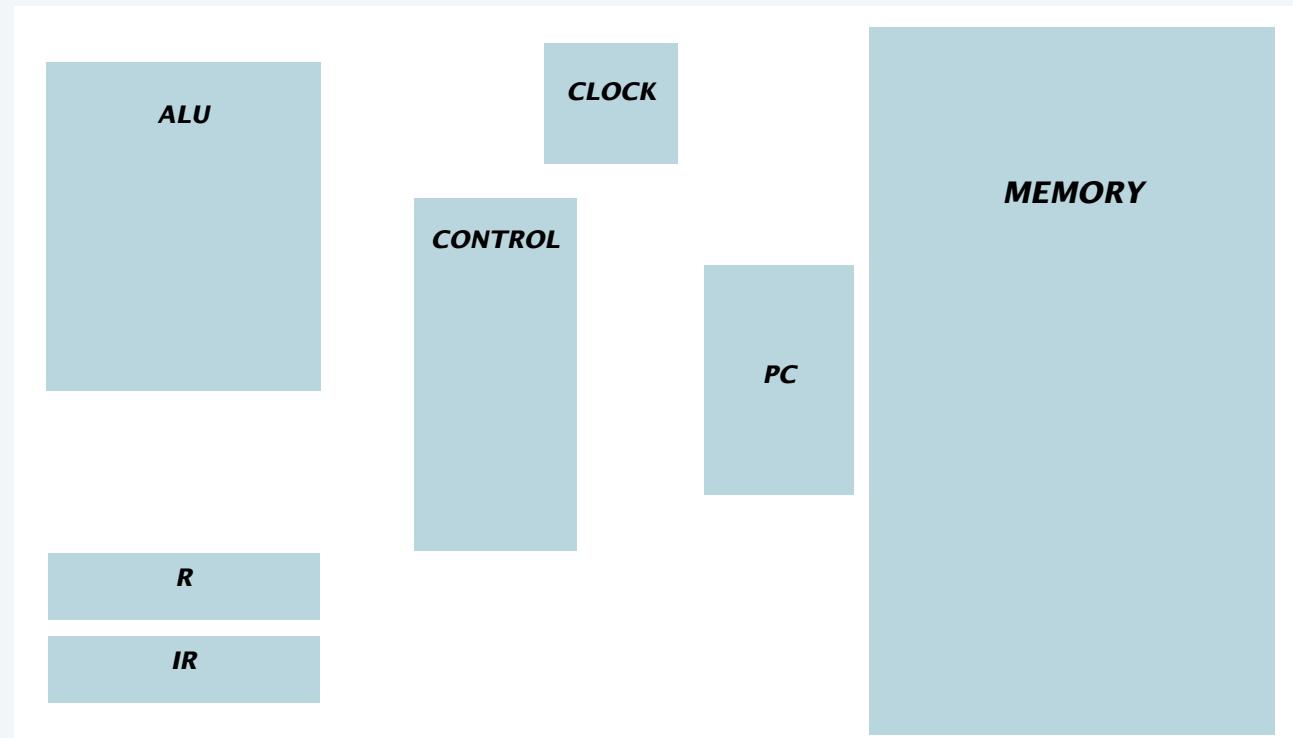
Challenge for the bored:

Write Fibonacci seq, add numbers on stdin, ...

CPU circuit components for TOY-8

TOY-8 CPU

- ALU (adder, AND, XOR)
- Memory
- Register (R)
- PC
- IR
- *Control*
- *Clock*



Goal. Complete CPU circuit for TOY-8 (same design extends to TOY and to your computer).

Review: Components, busses, and control lines

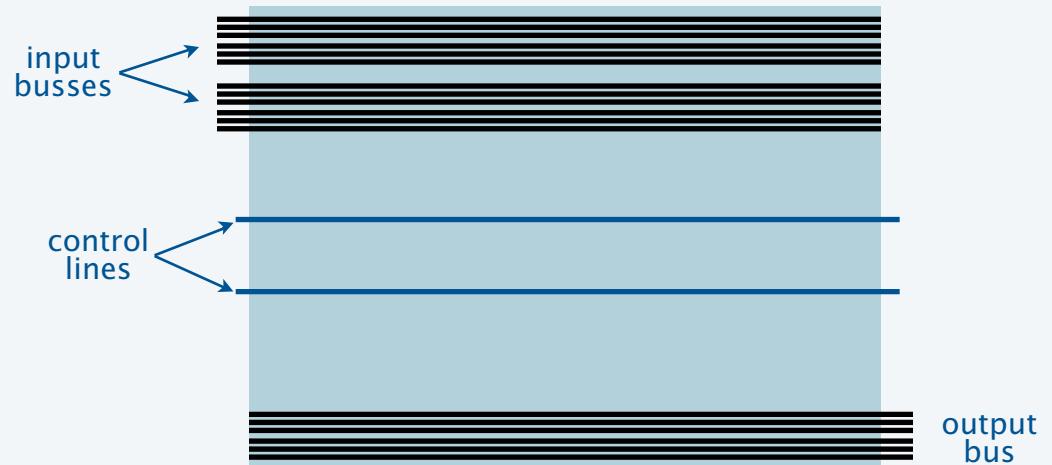
Basic design of our circuits

- Organized as *components* (functional units of TOY: ALU, memory, register, PC, and IR).
- Connected by *busses* (groups of wires that propagate information between components).
- Controlled by *control lines* (single wires that control circuit behavior).

Conventions

- Bus inputs are at the top, input connections are at the left.
- Bus outputs are at the bottom, output connections are at the right.
- Control lines are blue.

These conventions *make circuits easy to understand.*
(Like style conventions in coding.)



Perspective

Q. Why TOY-8?

A. TOY circuit width would be about 5 times TOY-8 circuit width.



Sobering fact. The circuit for your computer is *hundreds to thousands* of times wider.

Reassuring fact. Design of all three is based on the same fundamental ideas.



COMPUTER SCIENCE

SEGEWICK / WAYNE

CS.20.A.CPU.Overview

20. CPU

- Overview
- Bits, registers, and memory
- Program counter
- Connections

Sequential circuits

Q. What is a sequential circuit?

A. A digital circuit (all signals are 0 or 1) *with feedback* (loops).

Q. Why sequential circuits?

A. *Memory* (difference between a DFA and a Turing machine).

Basic abstractions

- On and off.
- Wire: Propagates an on/off value.
- Switch: Controls propagation of on/off values through wires.
- Flip-flop: *Remembers a value* (next).

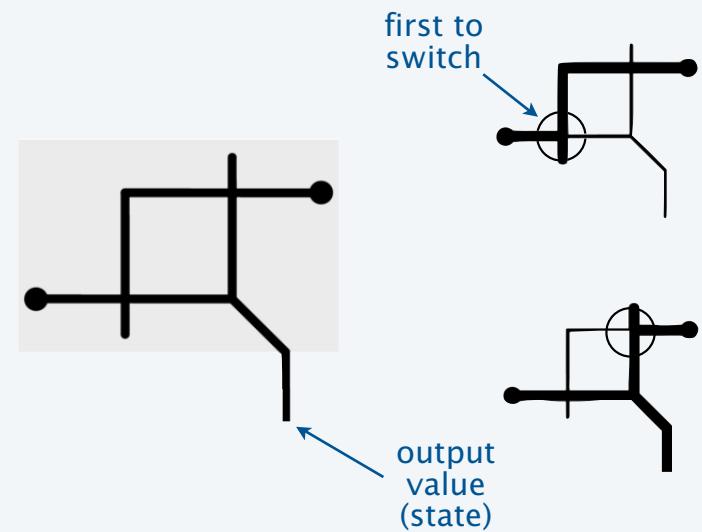
Simple circuits with feedback

Loops in circuits lead to time-varying behavior

- *Sequence* of switch operation matters.
- Need tight control (see next slide).

Example 1. Two switches, each blocked by the other.

- State determined by whichever switches first.
- Stable (once set, state never changes).
- *Basic building block for memory circuits.*



Example 2. Three switches, blocked in a cycle.

- State determined by whichever switches first.
- *Not stable* (cycles through states).

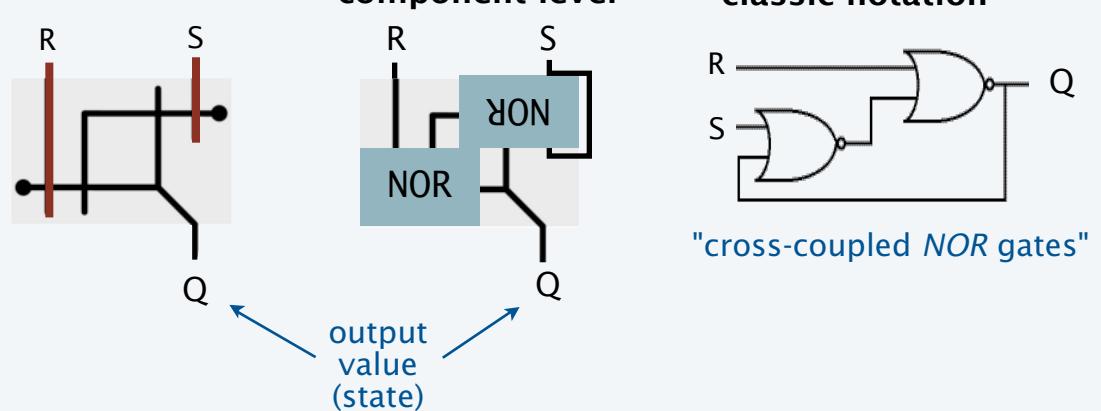


a "buzzer"

A new ingredient: Circuits with memory

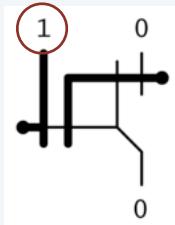
An *SR flip-flop* controls feedback.

- Add control lines to switches in simple feedback loop.
- R (reset) sets state to 0.
- S (set) sets state to 1.
- Q (state) is always available.

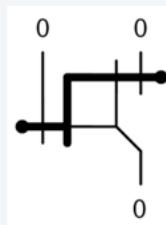


examples

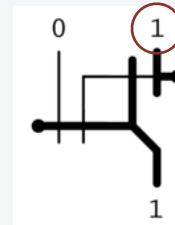
R: set to 0



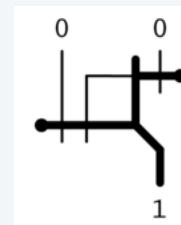
stays 0



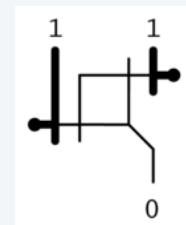
S: set to 1



stays 1



unused

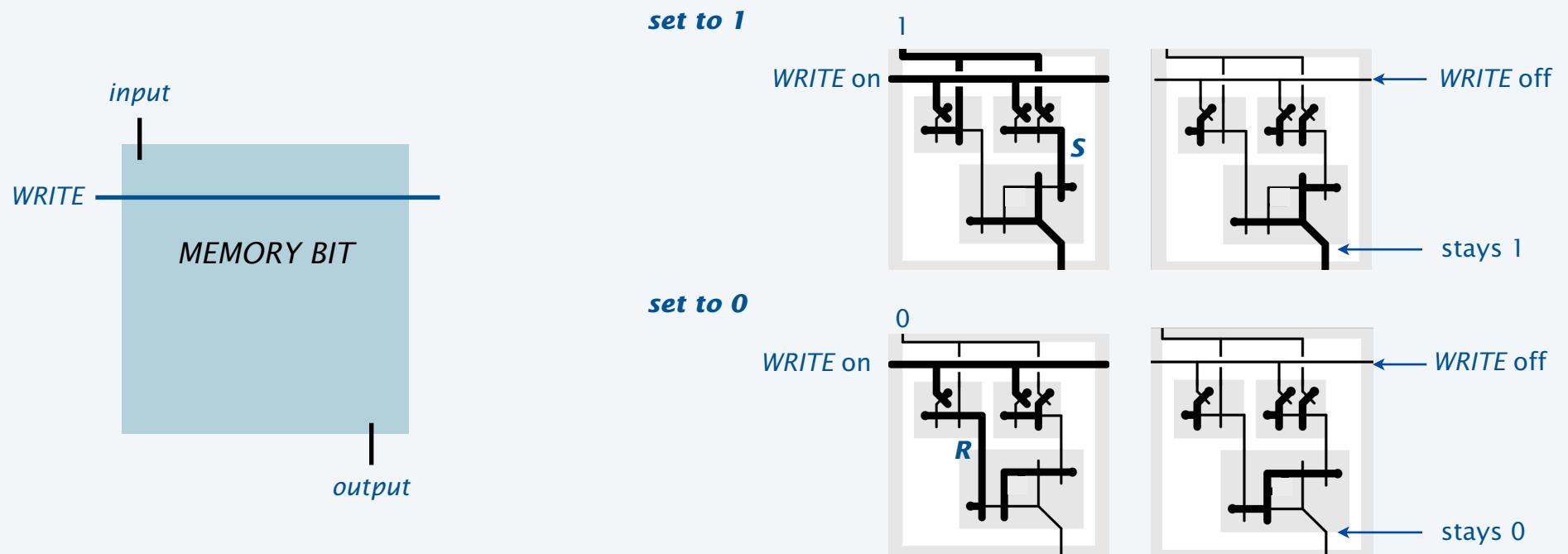


Caveat. Timing of switch vs. propagation delay.

Flip-flop application: Memory bit

Add logic to an SR flip-flop for more precise control

- Provide data value on an *input* wire instead of using S and R controls.
- Use *WRITE* control wire to enable change in flip-flop value.
- Flip-flop value always available as *output*.



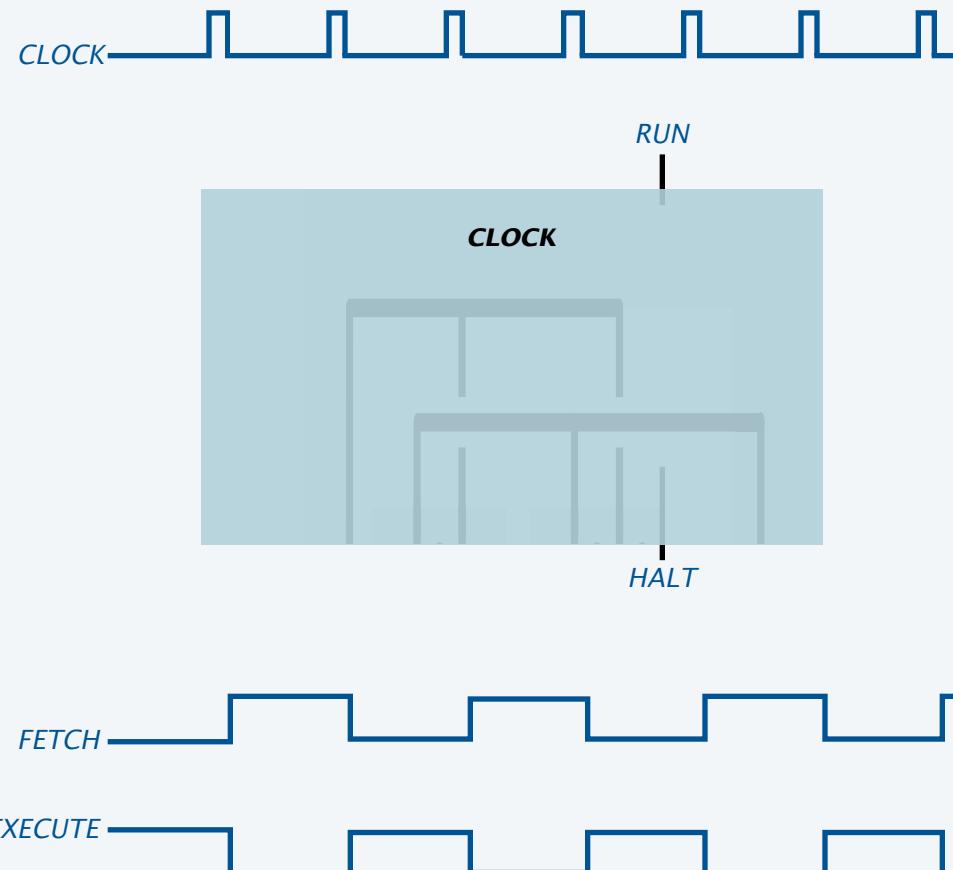
Memory bit application I: fetch/execute clock

Assumptions

- Physical clock provides regular on/off pulses.
- Duration is *just enough* to trigger a flip-flop.
- Space between pulses is long enough to allow the longest chain of flip-flops in the circuit to stabilize.

Fetch/execute clock. Attach clock to a memory bit.

- *RUN* control wire starts clock when on.
- *HALT* control wire stops clock when on.
- Memory bit flips on each clock tick (flip value and feed back to input).
- Result: on/off sequence for *FETCH* and *EXECUTE* control wires that control the CPU (stay tuned).



Fetch/execute clock with write pulses

Generates on/off signals for 4 control wires

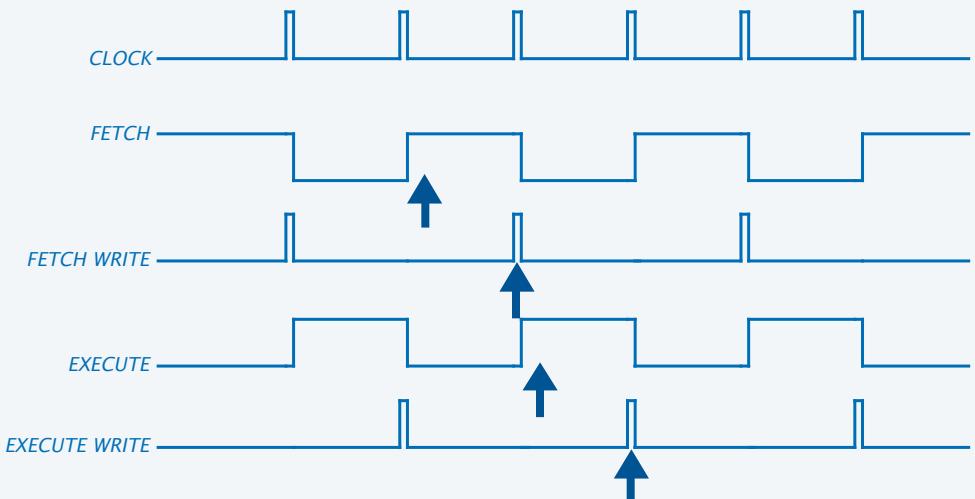
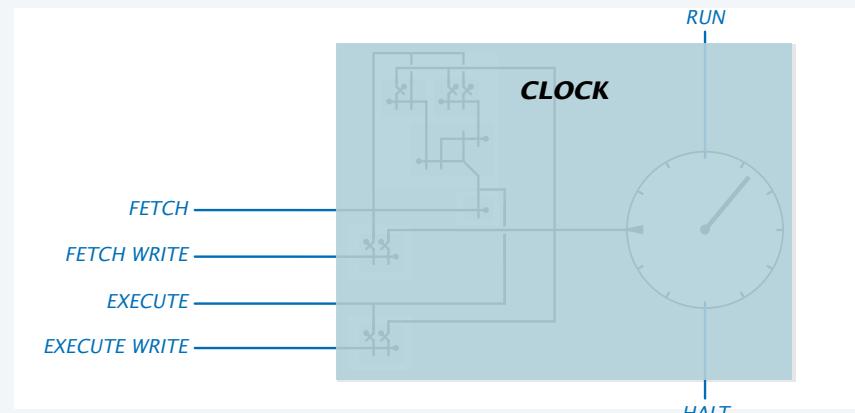
- *FETCH*.
- *FETCH WRITE* pulse.
- *EXECUTE*.
- *EXECUTE WRITE* pulse.

Implementation

- Add AND gates to fetch/execute clock.
- $\text{FETCH WRITE} = \text{FETCH AND CLOCK}$.
- $\text{EXECUTE WRITE} = \text{EXECUTE AND CLOCK}$.

Application

- Implements CPU fetch/execute cycles.
- Signals turn on control wires that change the state of PC, R, IR, and memory.



Interesting events occur at four distinct times in the cycle

Memory bit application II: Register

Register

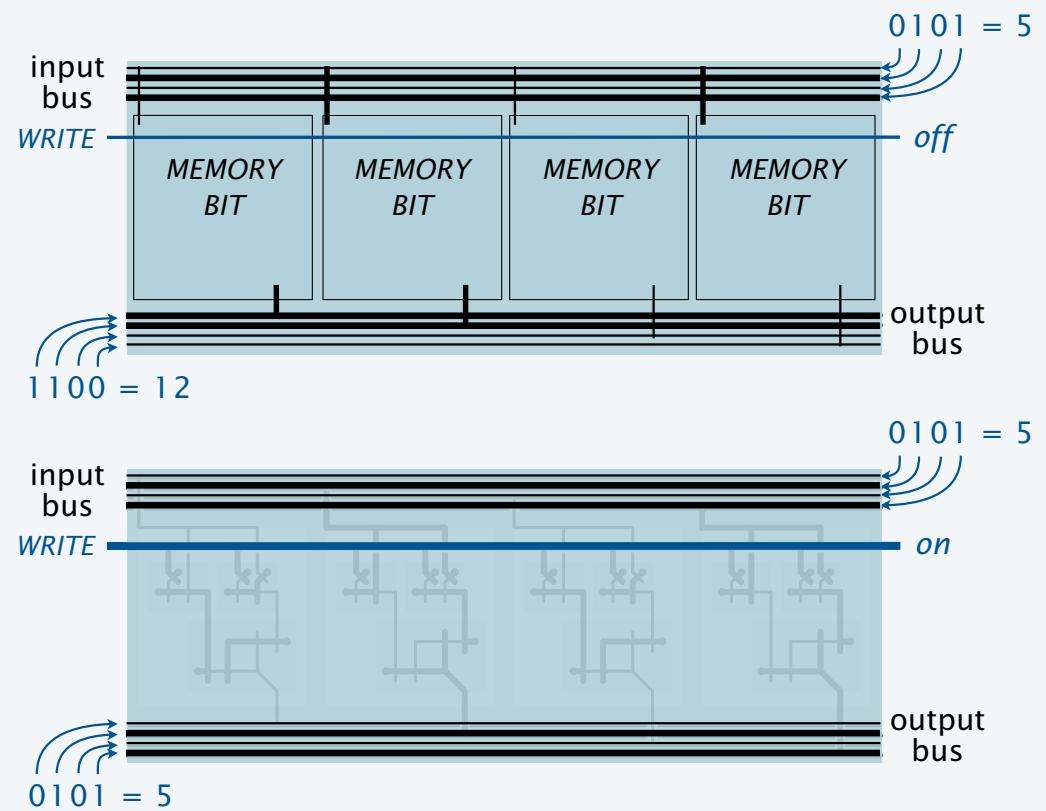
- w memory bits.
- w -bit input bus.
- values available on output bus.
- input loaded on *WRITE* pulse.

Implementation

- Connect memory bits to busses.
- Use *WRITE* pulse for all of them.

Applications for TOY-8

- PC holds 4-bit address.
- IR holds 8-bit instruction.
- R holds 8-bit data value.



Memory bit application III: Memory bank

Memory bank

- 2^n words, each w bits.
- n -bit address input.
- w -bit input bus.
- value *of selected word* available on output bus.
- input loaded *to selected word* on *WRITE* pulse.

Example: 4-words, each 6 bits



Memory bit application III: Memory bank

Memory bank

- 2^n words, each w bits.
- n -bit address input.
- w -bit input bus.
- value *of selected word* available on output bus.
- input loaded *to selected word* on *WRITE* pulse.

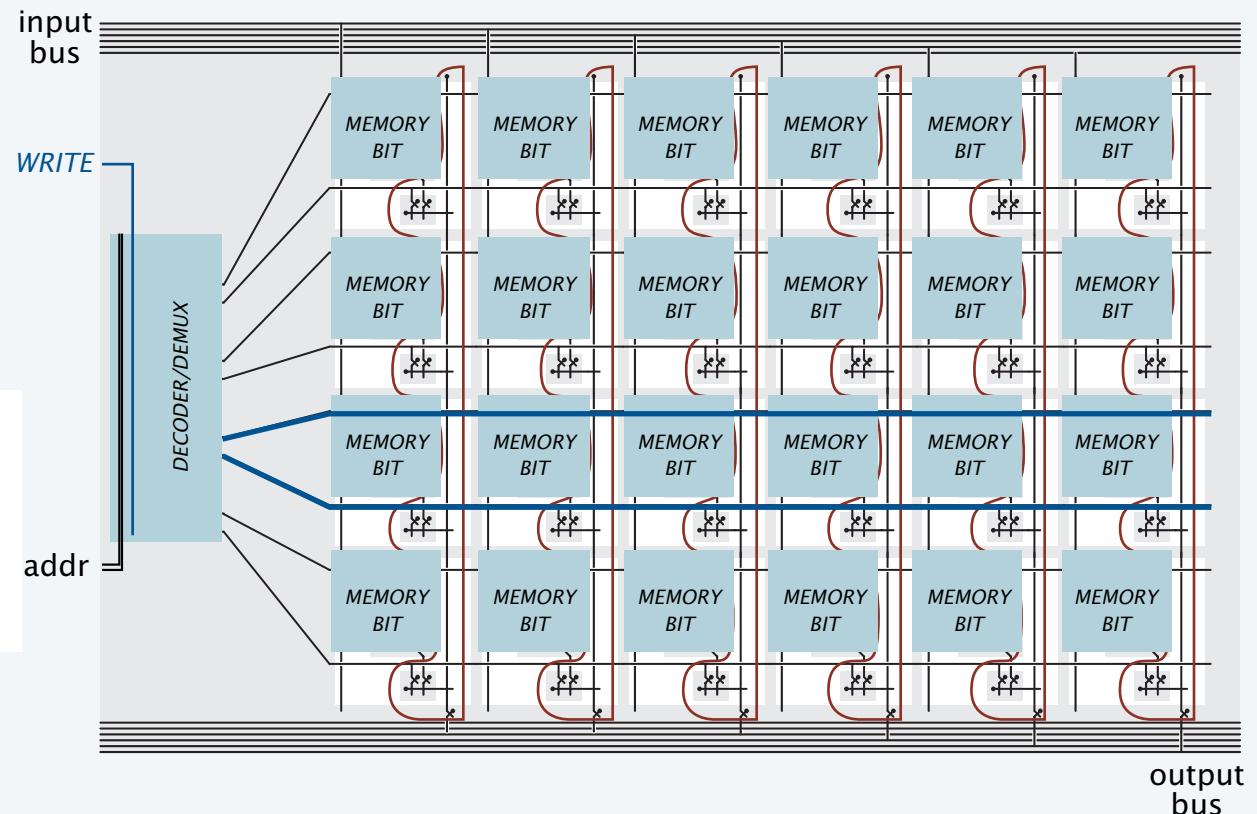
Implementation

- Decoder/demux selects word.
- One-hot muxes take selected word to output bus.

Application for TOY-8

- Main memory.

Example: 4-words, each 6 bits



TOY-8 main memory bank

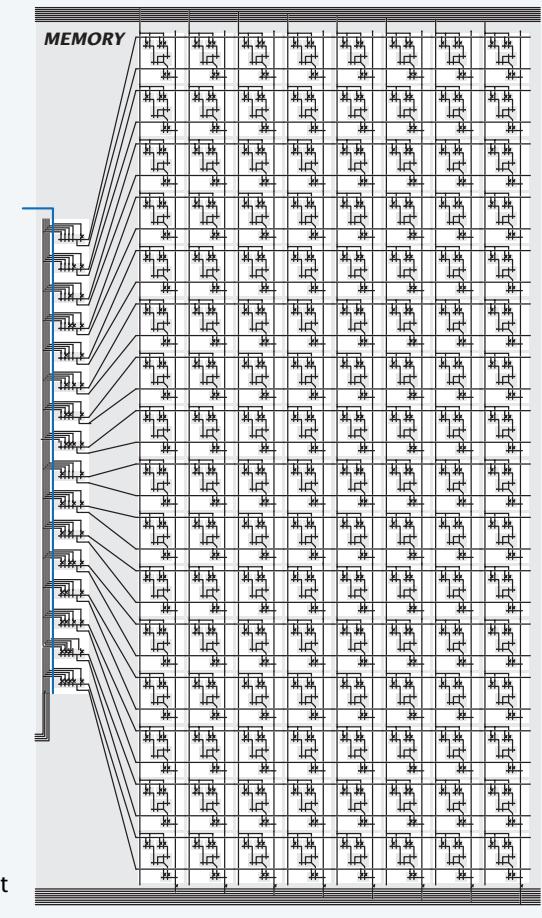
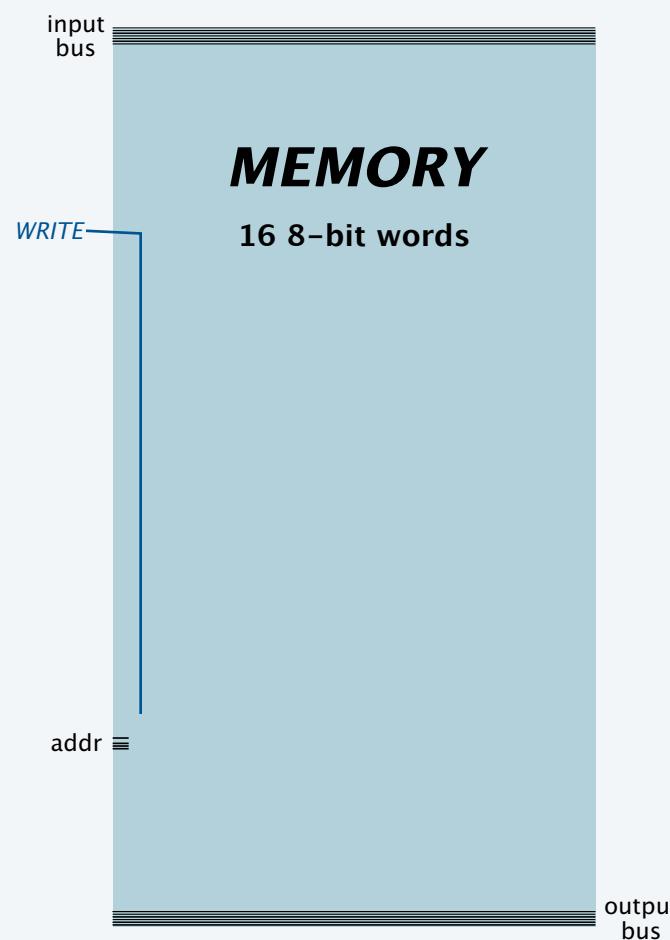
Interface

- Input bus (for *store*)
- Output bus (for *load*)
- Address to select a word
- *Write* control signal

Connections

- Input bus from registers
- Output bus to IR and R
- Address bits from PC and IR

	words	bits/word	addr bits
TOY-8	16	8	4
TOY	256	16	8
your computer	1 billion	64	32





COMPUTER SCIENCE
SEGEWICK / WAYNE

CS.20.B.CPU.Memory

20. CPU

- Overview
- Bits, registers, and memory
- Program counter
- Components and connections

Designing a digital circuit: overview

Steps to design a digital (sequential) circuit

- Design **interface**: input busses, output busses, control signals.
- Determine **components**.
- Determine **connections**.
- Establish **control sequence**.



Warmup. Design TOY-8 program counter (PC).

First challenge. Need an *incrementer* circuit.

Second challenge. Multiple bus connections.

Pop quiz on combinational circuit design

Q. Design a circuit to compute $x + 1$.

Pop quiz on combinational circuit design

Q. Design a circuit to compute $x + 1$.

A. Start with a bitwise adder

- Delete y inputs, set carry in to 1.
- Compute carry with AND and sum with XOR.

C_4	C_3	C_2	C_1	I
+	X_3	X_2	X_1	X_0
	Z_3	Z_2	Z_1	Z_0

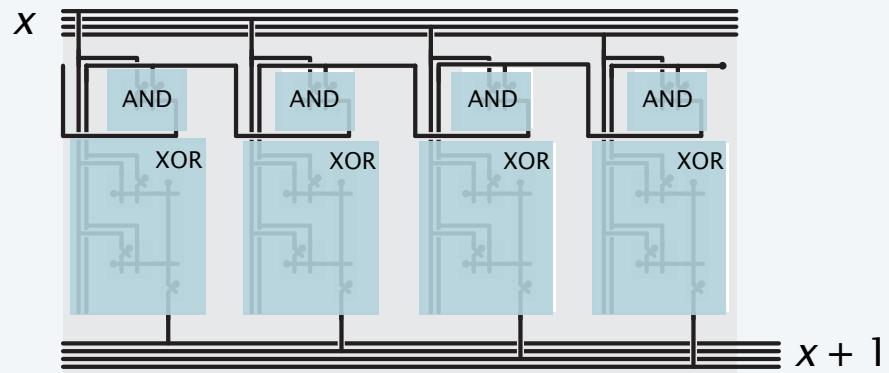
carry bit

X_i	C_i	C_{i+1}	AND
0	0	0	0
0	1	0	0
1	0	0	0
1	1	1	1

sum bit

X_i	C_i	Z_i	XOR
0	0	0	0
0	1	1	1
1	0	1	1
1	1	0	0

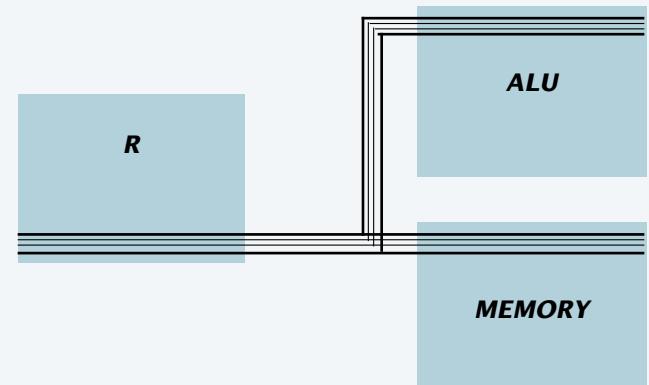
4-bit incrementer



Multiple bus connections

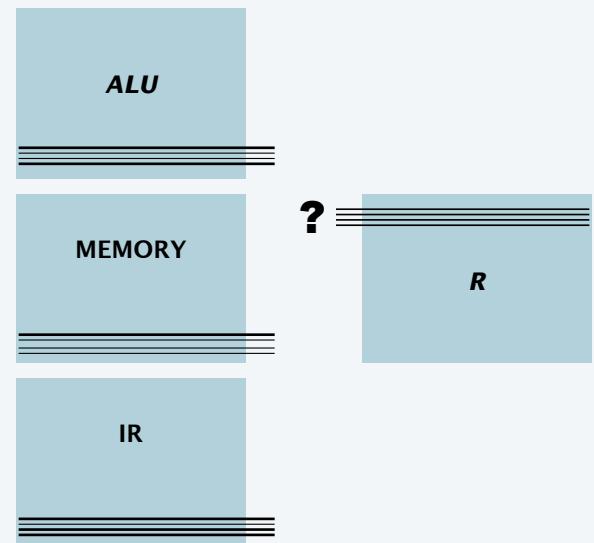
If component *outputs* go to multiple other components

- No problem, just use T connections.
- Values on both busses are the same.
- Example: Register connects to ALU and memory.



If component *inputs* come from multiple other components

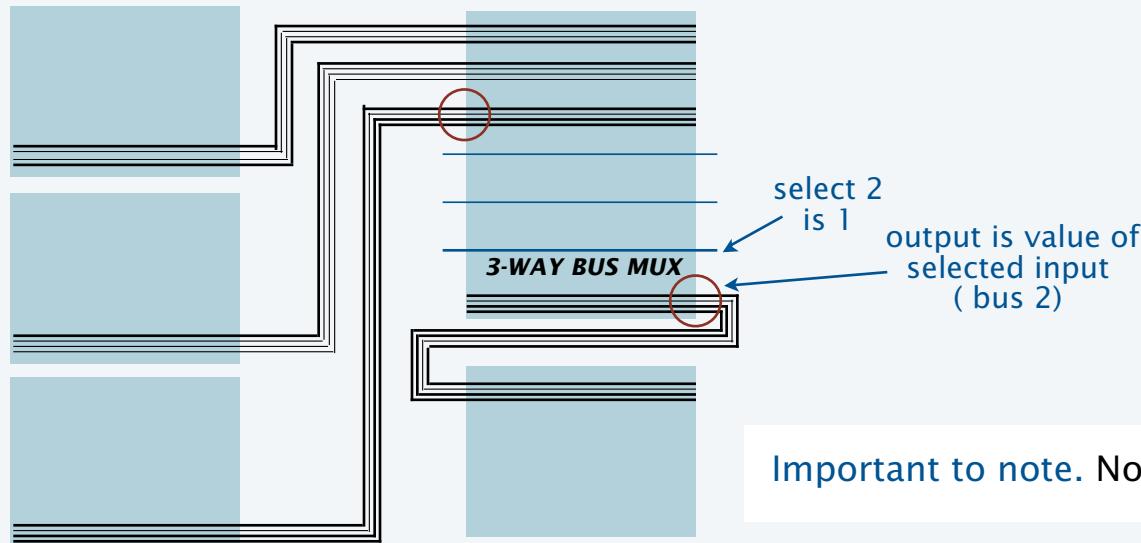
- Problem.
- Values on the busses are *different*.
- Example: ALU, memory, and IR connect to register.
- Solution: Need a *selector switch* (bus mux).



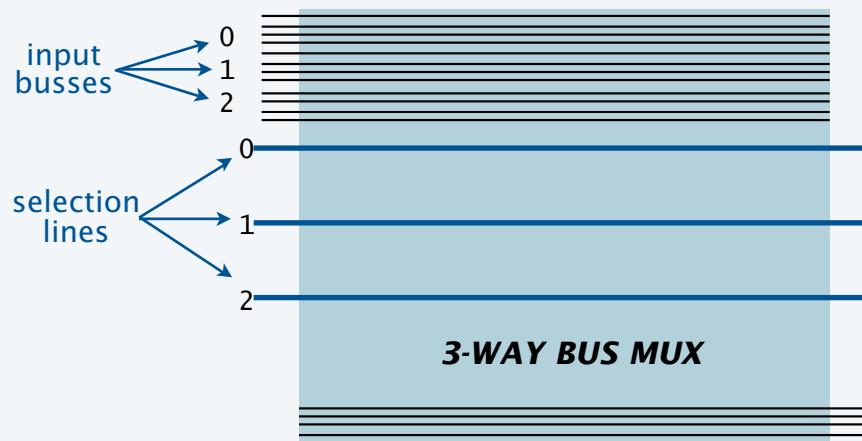
A (virtual) bus selector switch

One-hot m -way bus mux

- m input busses.
- m control lines (selection).
- One output bus.
- At most one selection line is 1.
- Output bus lines have same value as selected input bus lines.



Example: 4-bit 3-way bus mux



Important to note. No direct connection from input to output.

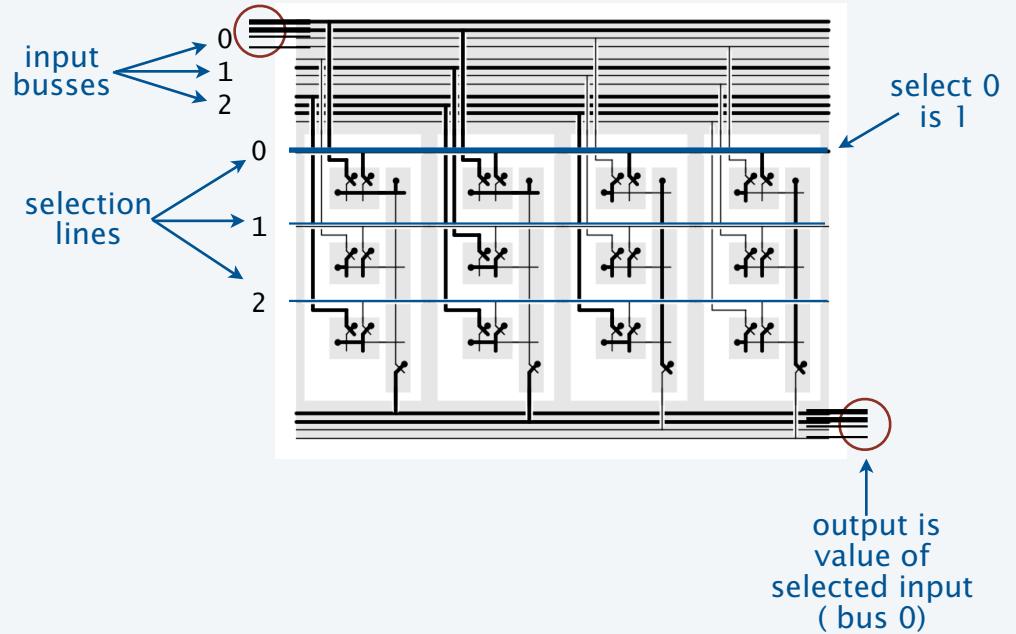
One-hot bus mux

One-hot m -way bus mux

- m input busses.
- m control lines (selection).
- One output bus.
- At most one selection line is 1.
- Output bus lines have same value as selected input bus lines.

Implementation

- Bitwise one-hot muxes for output.



Application (next): Select among inputs to a component.

Program counter (PC)

The *PC* holds an address and supports 3 control wires:

- *INCREMENT*. Add 1 to value when *WRITE* becomes 1.
- *LOAD*. Set value from input bus when *WRITE* becomes 1.
- *WRITE*. Enable PC address to change as specified.

The current address is always available on the output bus.

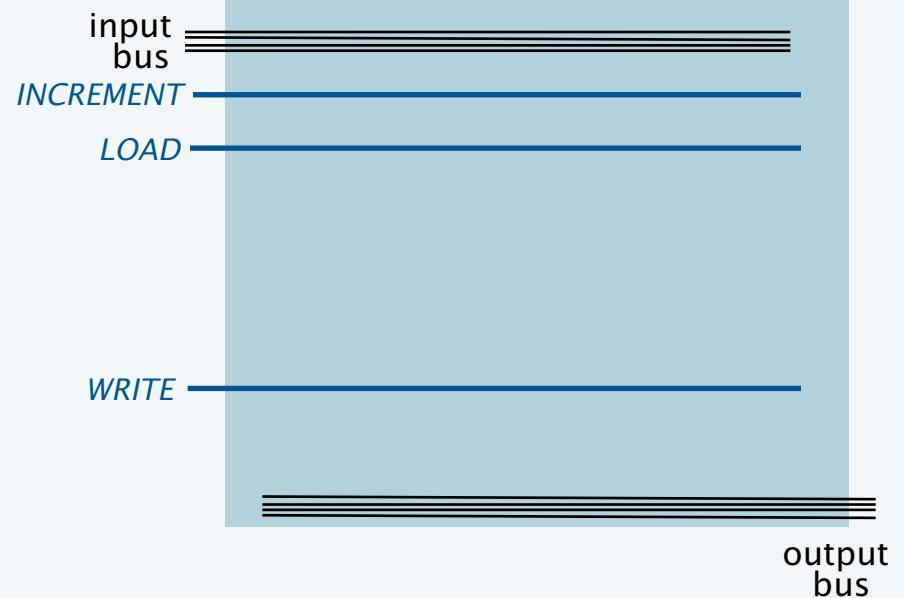
Components

- PC register (4-bit).
- Incrementer (add 1).

Connections

- Input bus to **PC register.** *need 2-way bus mux*
- Incrementer to **PC register.**
- PC register to incrementer.
- PC register to output bus.

PC



Program counter (PC)

The *PC* holds an address and supports 3 control wires:

- *INCREMENT*. Add 1 to value when *WRITE* becomes 1.
- *LOAD*. Set value from input bus when *WRITE* becomes 1.
- *WRITE*. Enable PC address to change as specified.

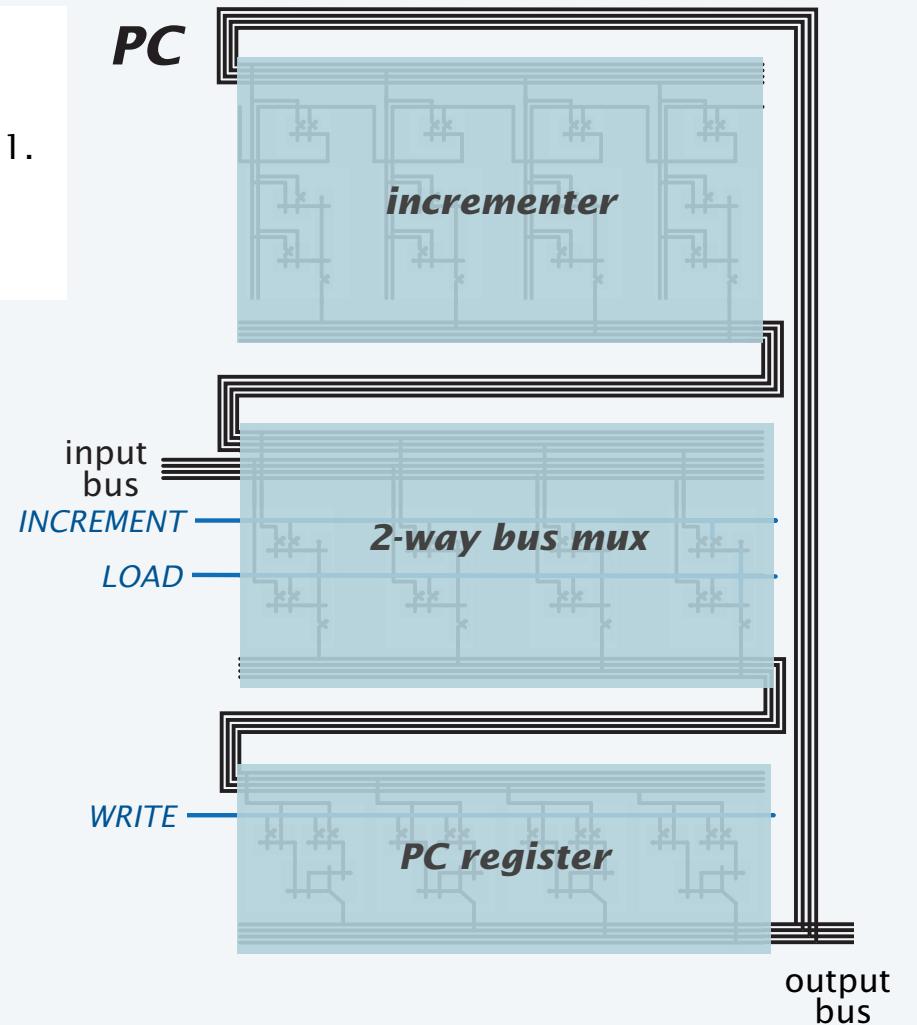
The current address is always available on the output bus.

Components

- PC register (4-bit).
- Incrementer (add 1).
- 2-way bus mux.

Connections

- Input bus to bus mux.
- Incrementer to bus mux.
- Bus mux to PC register.
- PC register to incrementer.
- PC register to output bus.

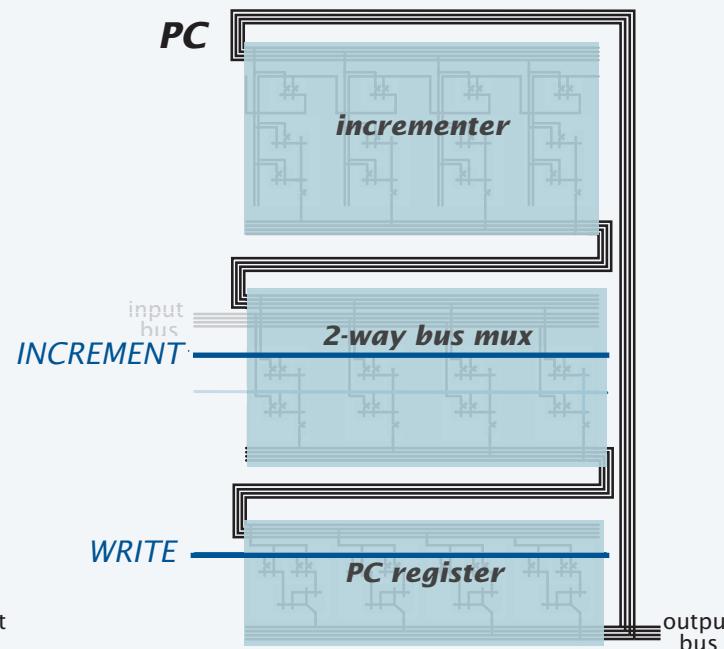
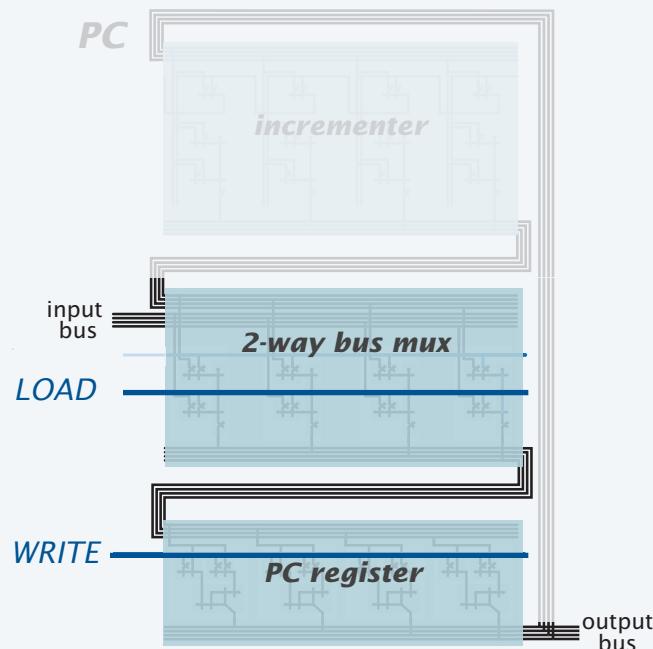


Summary of TOY-8 PC circuit

The *PC* supports two control-signal sequences:

- *Load, then write.* Set address from input bus (example: branch instruction).
- *Increment, then write.* Add one to value.

Address is written to the PC register in both cases and always available on the output bus.



Important note: *write* pulse must be very short because of the cycle in this circuit.



COMPUTER SCIENCE
SEGEWICK / WAYNE

CS.20.C.CPU.PC

20. CPU

- Overview
- Bits, registers, and memory
- Program counter
- Components, connections, and control

TOY-8: Interface

CPU is a circuit inside the machine



RUN

Interface to outside world

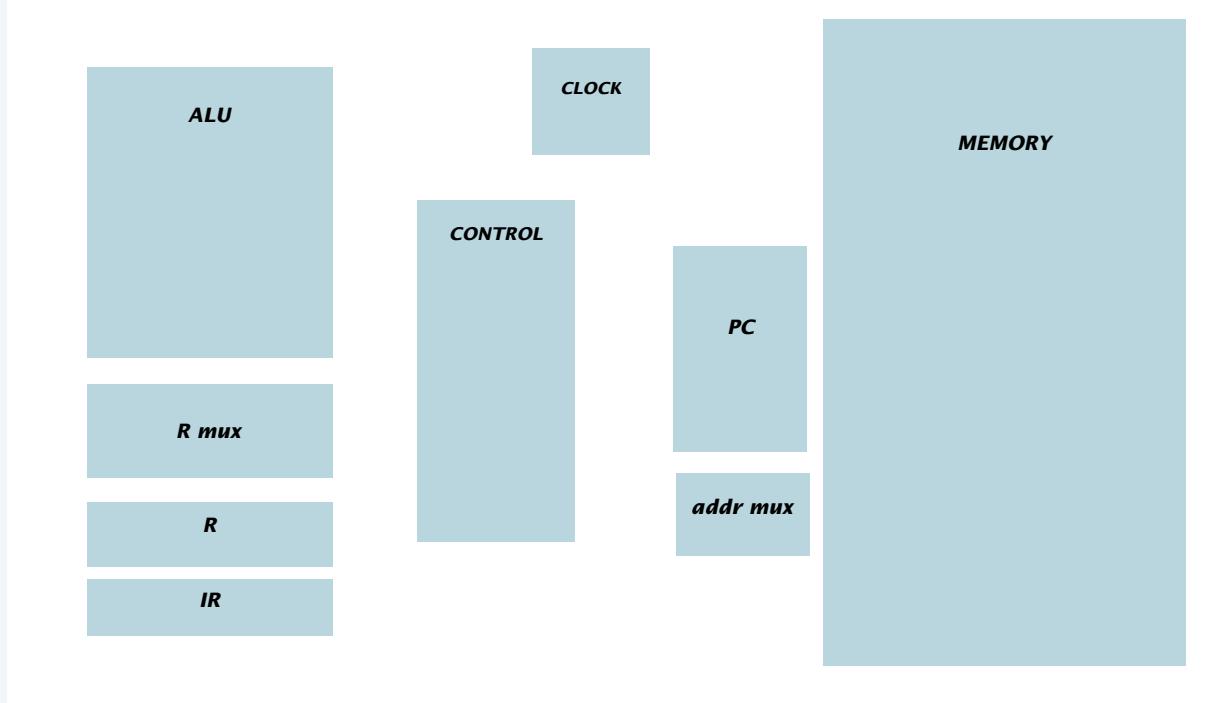
- Switches and lights
- ON/OFF
- RUN

Connections to outside (omitted)

- ADDR to PC
- DATA to memory bank input bus
- Buttons to control lines that activate memory load/store

TOY-8
A computing machine

Review: CPU circuit components for TOY-8



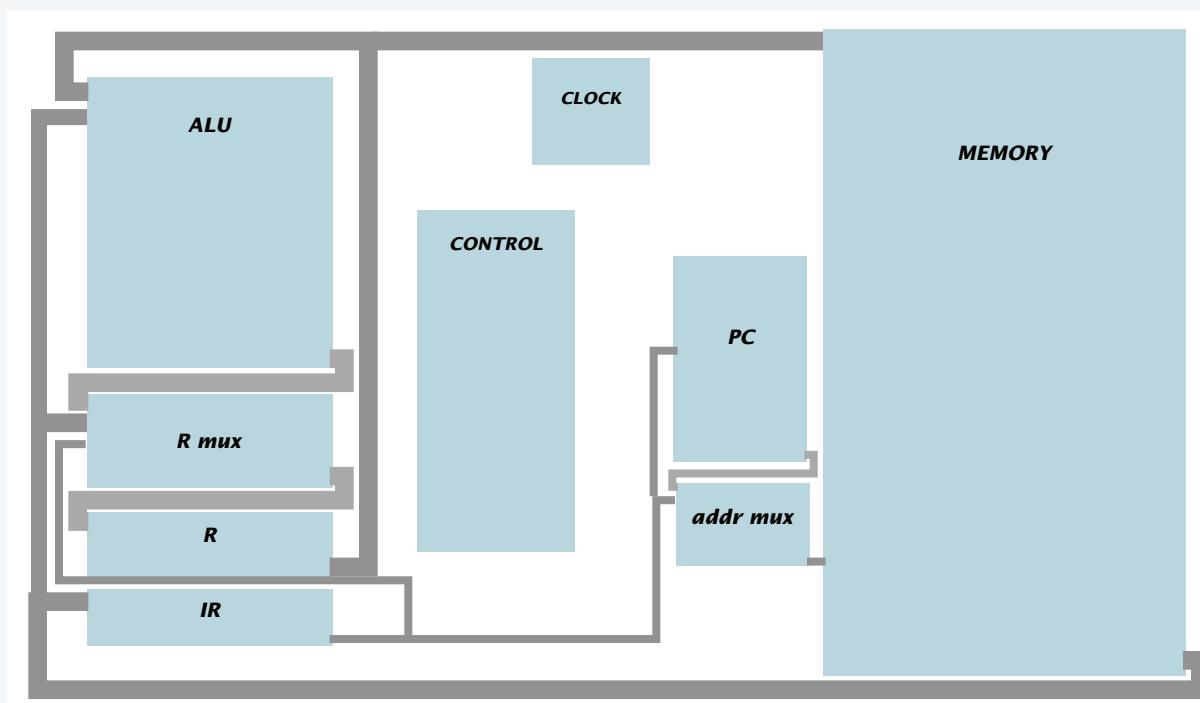
TOY-8 CPU

- ALU (adder, AND, XOR)
- Memory
- Register (R)
- PC
- IR
- Control
- Clock



Also needed (see next slide): Bus muxes for R and memory addr.

Connections for TOY-8 CPU

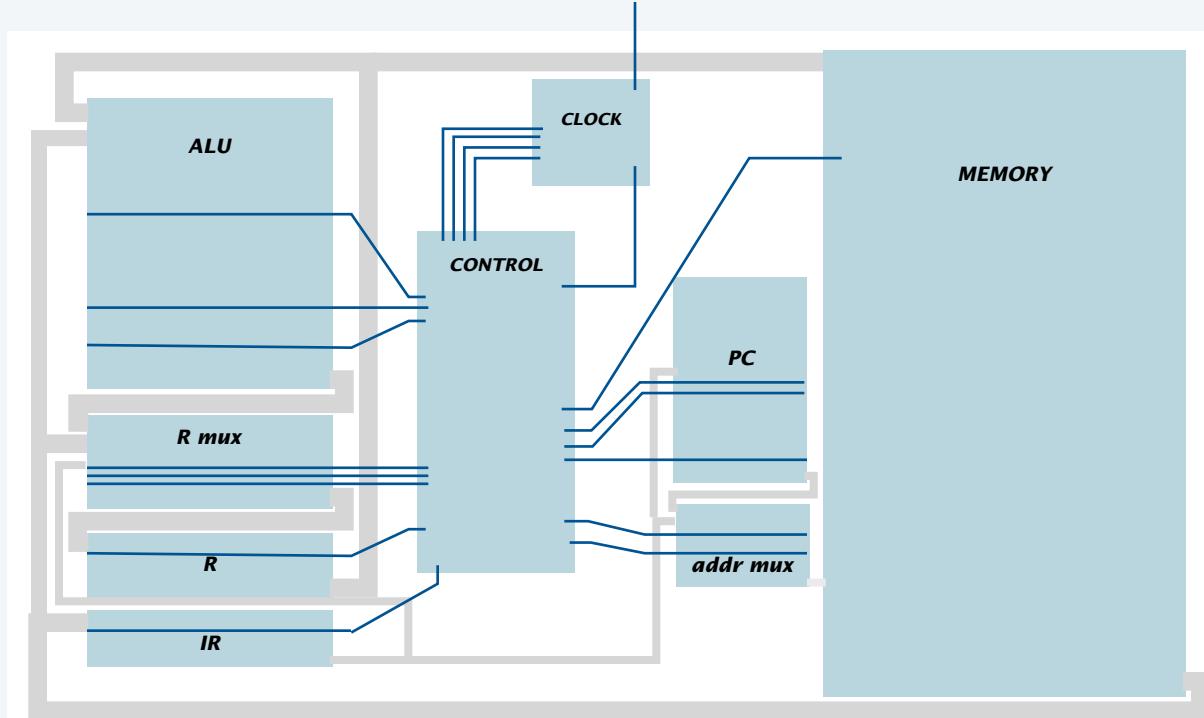


instructions	bus connections
fetch (all)	<i>PC to memory addr</i> <i>memory to IR</i>
halt	<i>none</i>
add, and, xor	<i>IR addr to memory addr</i> <i>memory to ALU 1</i> <i>R to ALU 0</i>
load address	<i>ALU to R</i> <i>IR addr to R</i>
load	<i>IR addr to memory addr</i> <i>memory to R</i>
store	<i>IR addr to memory addr</i> <i>R to memory</i>
branch if zero	<i>IR addr to PC</i>

Annotations in red circles highlight specific bus connections:

- PC to memory addr**: Need 2-way bus mux.
- ALU to R**: Need 3-way bus mux.
- IR addr to R**: Need 3-way bus mux.
- memory to R**: Need 3-way bus mux.

Control wires for TOY-8 CPU



component	control wires
CLOCK	<i>RUN</i> <i>HALT</i>
CONTROL	<i>FETCH</i> <i>FETCH WRITE</i> <i>EXECUTE</i> <i>EXECUTE WRITE</i>
ALU	<i>ADD</i> <i>XOR</i> <i>AND</i>
R mux	<i>R MUX ALU</i> <i>R MUX MEM</i> <i>R MUX IR</i>
R	<i>R WRITE</i>
IR	<i>IR WRITE</i>
memory	<i>MEMORY WRITE</i>
PC	<i>PC INCREMENT</i> <i>PC LOAD</i> <i>PC WRITE</i>
addr mux	<i>ADDR MUX PC</i> <i>ADDR MUX IR</i>

One final combinational circuit: Control

Control. Circuit for *control wire sequencing*.

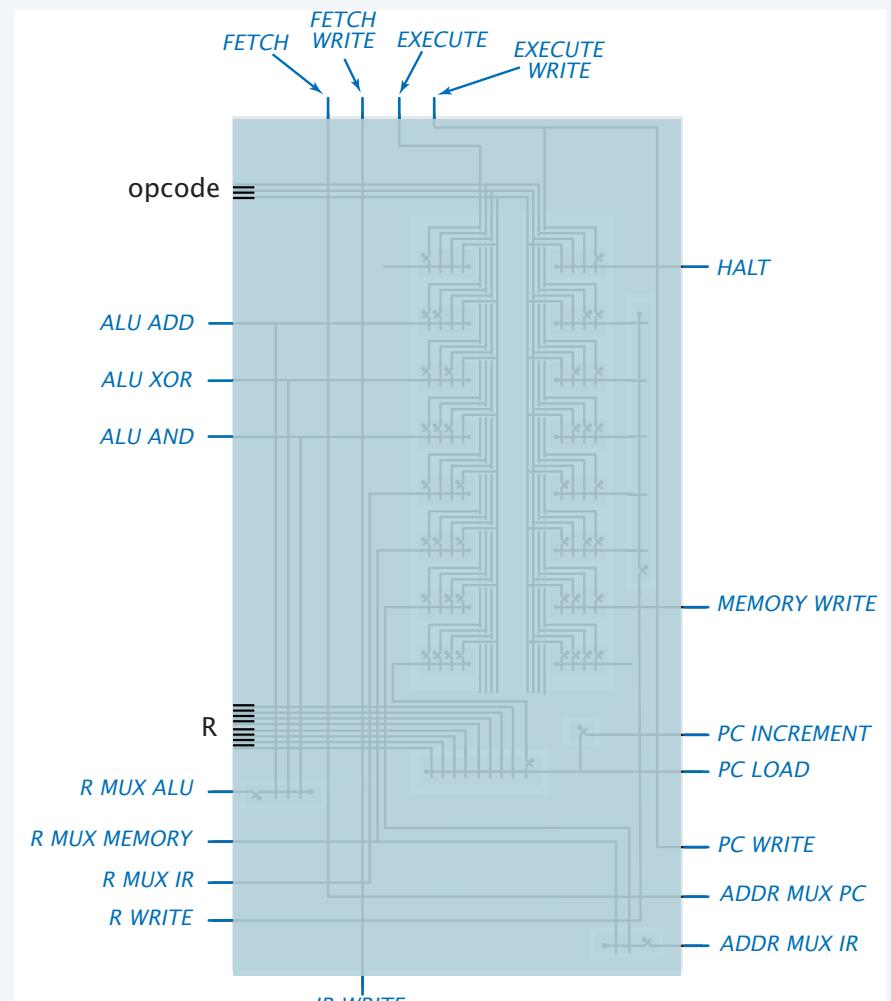
Inputs

- Four control wires from clock.
- opcode from IR.
- contents of R.

Outputs

- 15 control wires for CPU components.

Key feature. A simple combinational circuit.

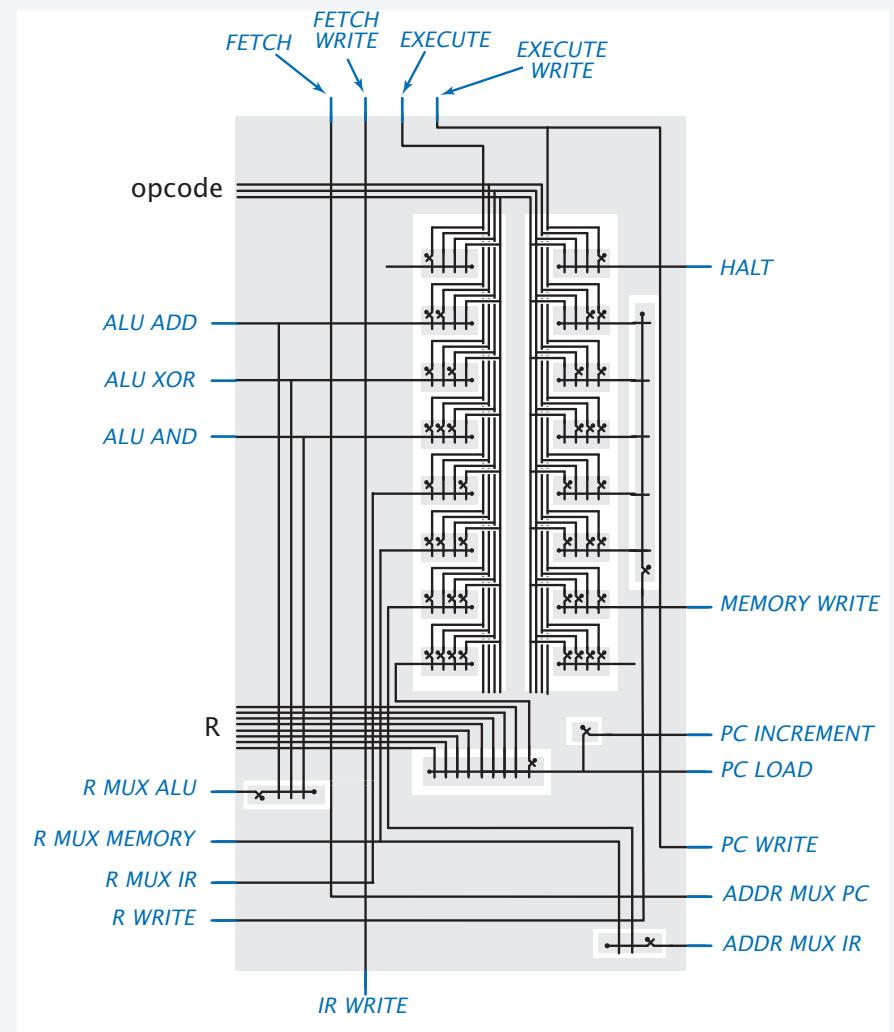


Control wire sequences

	FETCH	FETCH WRITE	EXECUTE WRITE
all instructions	ADDR MUX PC	IR WRITE	PC WRITE
	PC INCREMENT*		

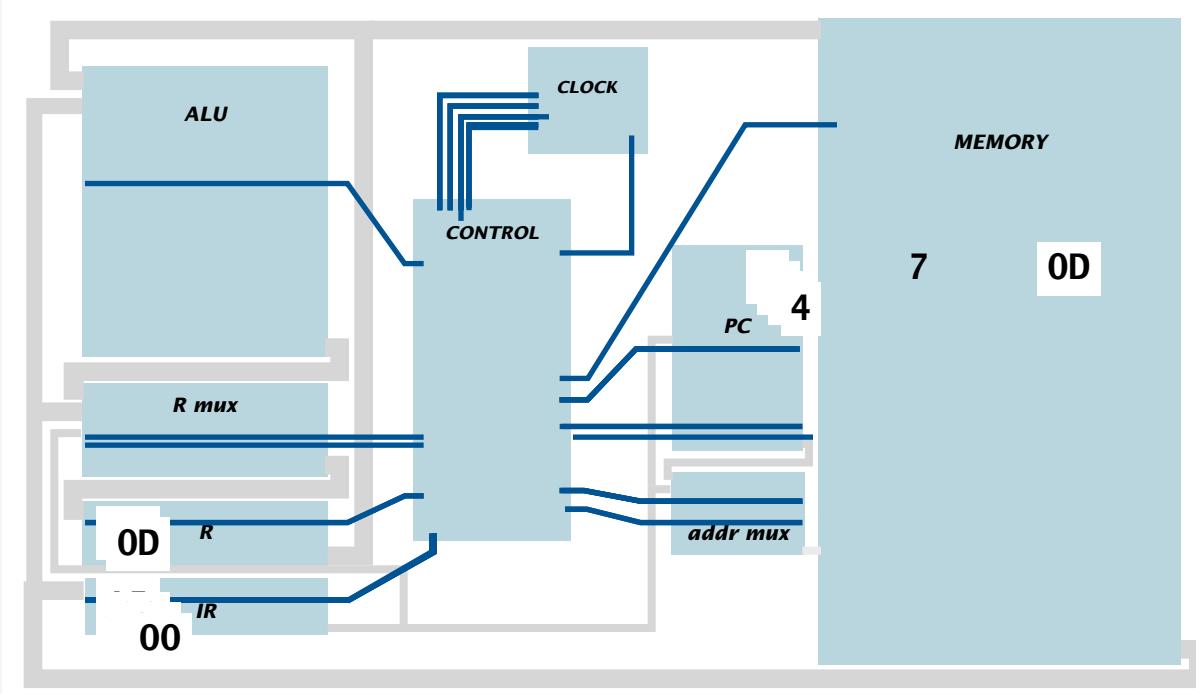
* PC LOAD for branch if 0 if R is 0.

instruction	EXECUTE	EXECUTE WRITE
halt	HALT	
add	ALU ADD	R WRITE
	R MUX ALU	
xor	ALU ADD	R WRITE
	R MUX ALU	
and	ALU ADD	R WRITE
	R MUX ALU	
load address	R MUX IR	R WRITE
load	R MUX MEMORY	R WRITE
	ADDR MUX IR	
store	ADDR MUX IR	MEMORY WRITE



Sample program

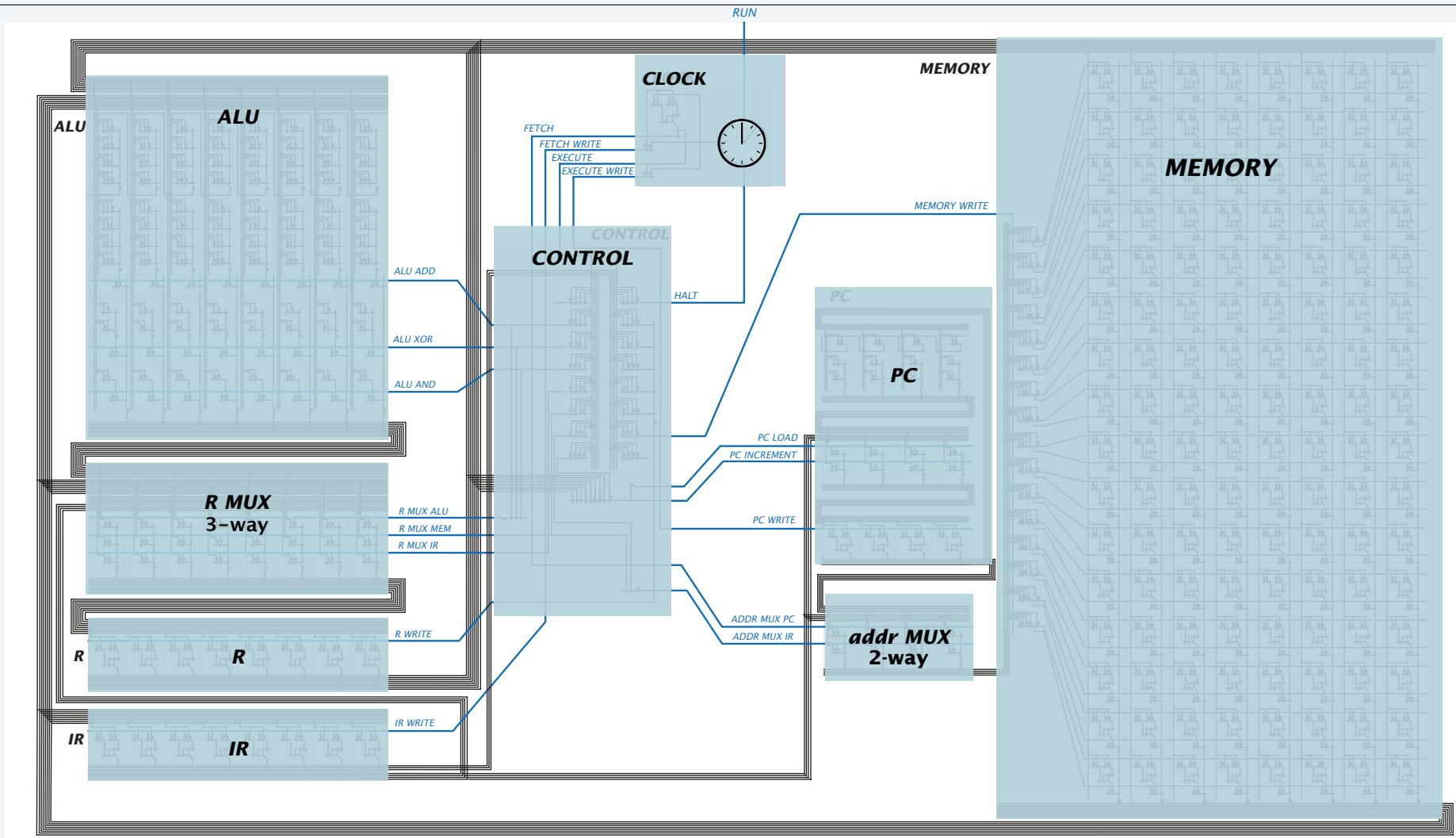
1 A5
2 26
3 C7
4 00
5 05
6 08



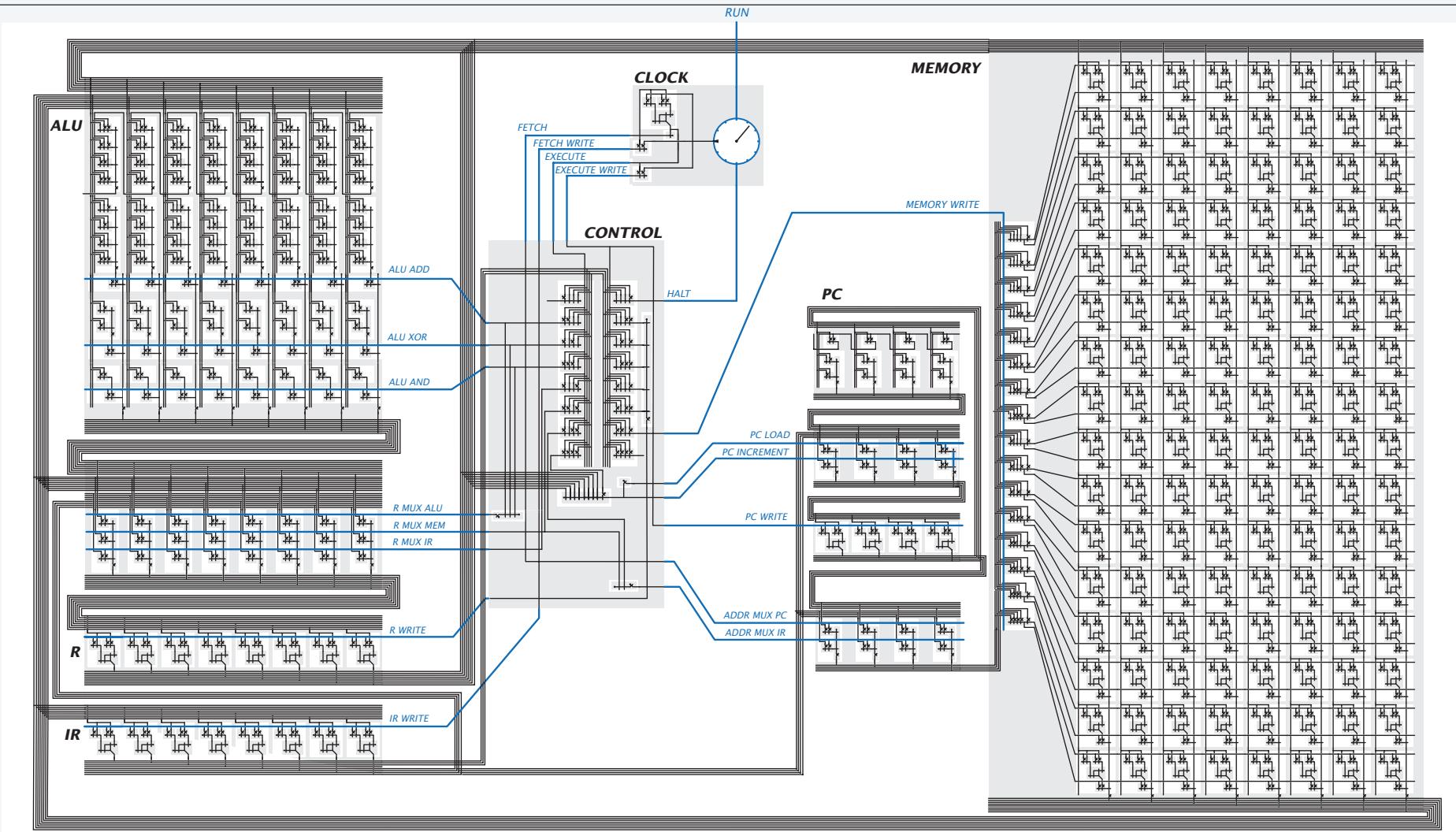
	<i>control signal</i>	<i>result</i>
FETCH	ADDR MUX PC	
FETCH WRITE	IR WRITE	IR = A5
EXECUTE	PC INCREMENT	
	ADDR MUX IR	
	R MUX MEMORY	
EXECUTE WRITE	R WRITE	R = 05
	PC WRITE	PC = 2
FETCH	ADDR MUX PC	
FETCH WRITE	IR WRITE	IR = 26
EXECUTE	PC INCREMENT	
	ALU ADD	
	R MUX ALU	
EXECUTE WRITE	R WRITE	R = 0D
	PC WRITE	PC = 3
FETCH	ADDR MUX PC	
FETCH WRITE	IR WRITE	IR = C7
EXECUTE	PC INCREMENT	
	ADDR MUX IR	
EXECUTE WRITE	MEMORY WRITE	M[7] = 0D
	PC WRITE	PC = 4
FETCH	ADDR MUX PC	
FETCH WRITE	IR WRITE	IR = 00
EXECUTE	PC INCREMENT	
	HALT	

And THAT . . . is how your computer works!

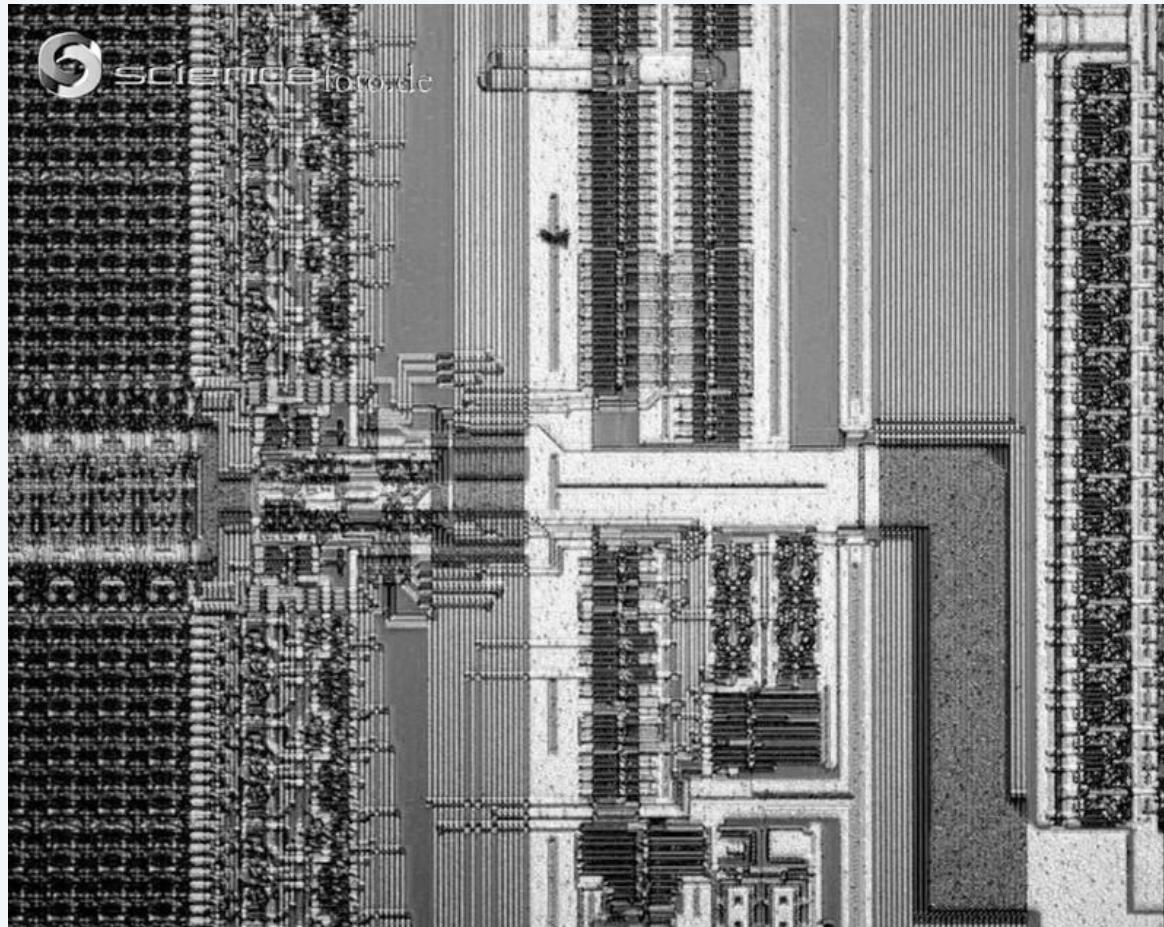
TOY-8 CPU



TOY-8 CPU



Scanning electron microscope image of a real microprocessor



Memory bits per square cm

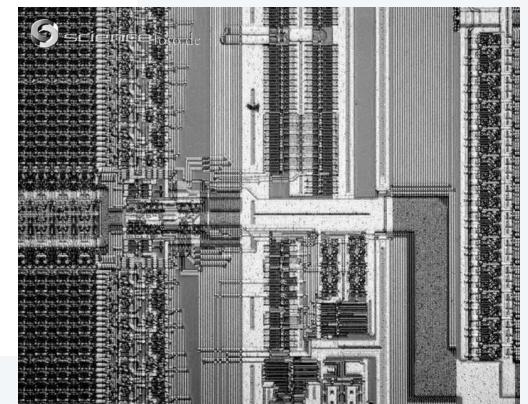
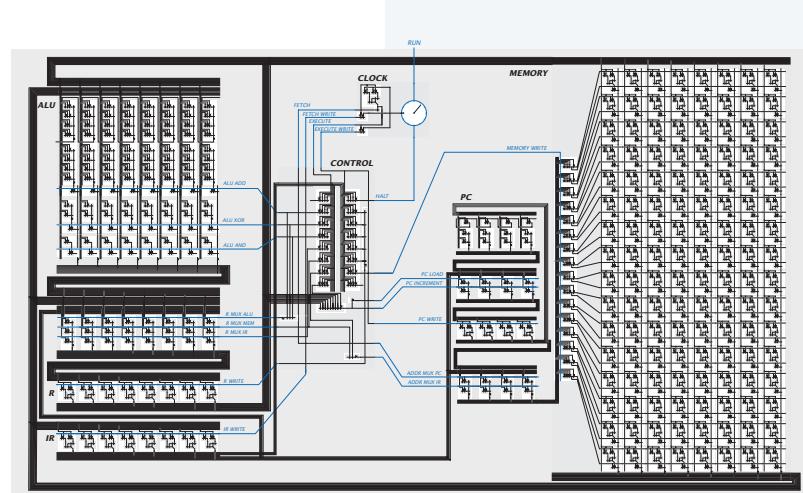
modern microprocessor	25 billion
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TOY-8	1
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How does your computer work?

A not-so-short answer, in case someone asks...

- A circuit known as the *CPU* is built from *switches* connected by *wires*.
 - The CPU performs operations on information encoded in binary, *including its own instructions*.
 - Circuits with feedback implement *memories*.
 - Instructions move information among memories, specify the next operation, or implement mathematical functions based on *Boolean logic*.
 - Clock pulses activate sequences of *control signals*, which cause state changes that implement machine instructions.
 - Virtually everything else is implemented as *layers of software*, each layer adding additional power and scope.



What is this course about?

A broad introduction to **computer science**.

Goals

- Empower you to exploit available technology. ✓
- Build awareness of intellectual underpinnings. ✓
- Demystify computer systems. ✓

BST insertion: random order visuc

LRS: An efficient solution

0 1 2 3 4 5 6 7 8 9 10 11
a a c a a g t t a c a

1. Form suffix strings

0 a a c a a g t
1 a c a a g t t
2 c a a g t t t
3 a a g t t t a
4 a g t t t a c
5 g t t t a c a
6 t t t a c a a
7 t t a c a a g
8 t a c a a g c
9 a c a a g c
10 c a a g c
11 a a g c
12 a g c
13 g c
14 c

Universality

UTM: A simple and universal

Definition. A task is computable if there exists a

Theorem (Turing, 1936) machine which can be used to solve it.

Profound implications

- Any machine that can simulate UTM can compute anything
- Any machine that can simulate UTM can be simulated by another machine
- Don't need separate device for each task

3-COLOR

EXACT COVER

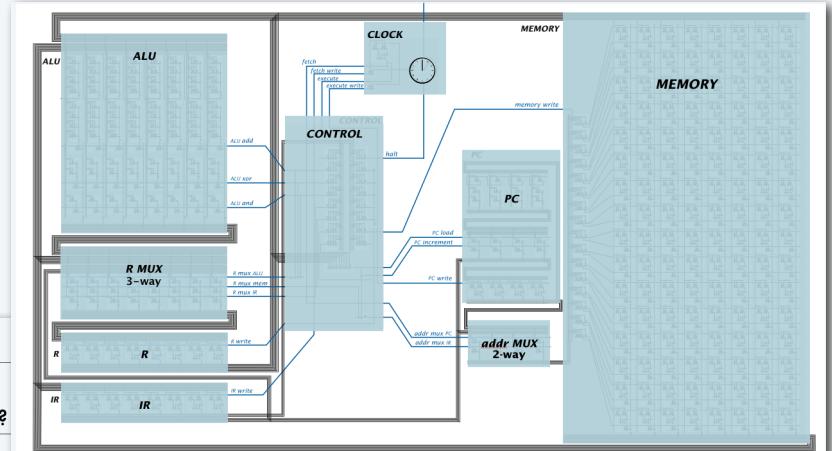
SUBSET SUM

PARTITION

KNAPSACK

BIN

3. Find longest LCP among adjacent elements



Is TOY real?

Q. How did we debug all our TOY programs?

A. We wrote a Java program to simulate TOY.

Comments

- YOU could write a TOY simulator (stay tuned).
- We designed TOY by refining this code.
- All computers are designed in this way.

Estimated number of TOY devices: 0



Estimated number of Android devices: 1 billion+



Estimated number of TOY devices: 1 billion+

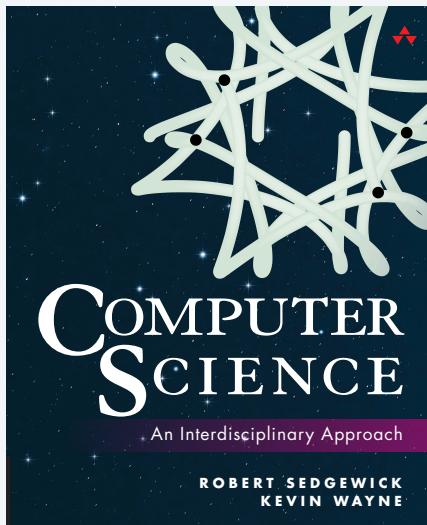
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[Next: Algorithms.](#)





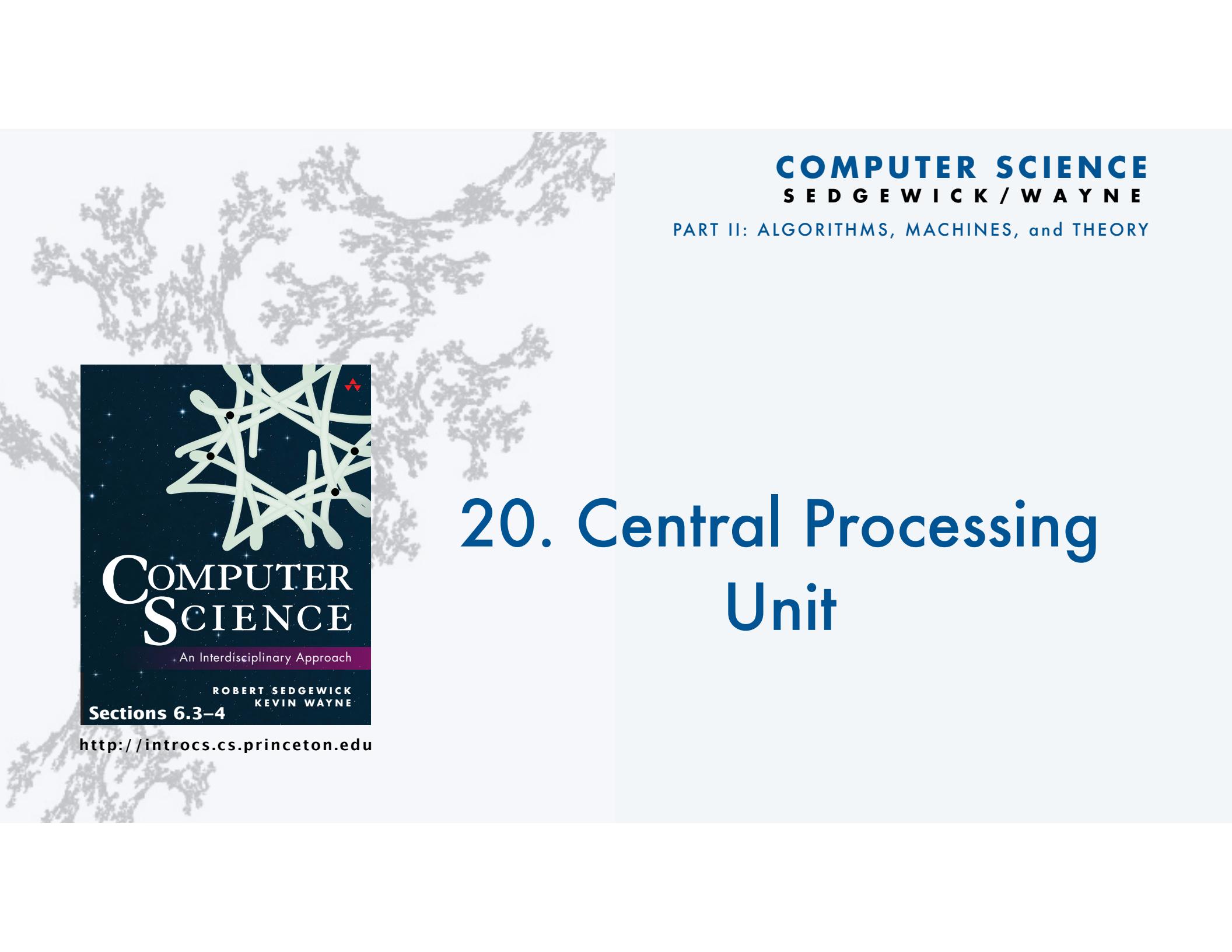
COMPUTER SCIENCE

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Image sources

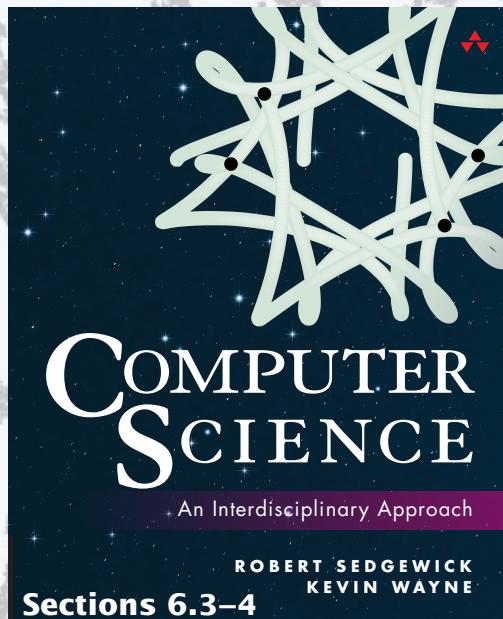
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PART II: ALGORITHMS, MACHINES, and THEORY



<http://introcs.cs.princeton.edu>

20. Central Processing Unit