## **Assignment A2: Spatial Filtering**

## CS 4640 Spring 2018

**Assigned:** 23 January 2018

**Due:** 8 February 2018

For this problem, handin Matlab .m files for the functions described by the headers below. Note that one of these is a driver which creates inputs for each function and runs the function on those inputs to obtain the output.

None of the functions should write to the interpreter, draw, etc.

```
function [mag, ori] = CS4640_edge(im)
% CS4640_edge - compute edge magnitudes and orientations
% On input:
      im (MxN array): input image
% On output:
      mag (MxN array): edge magnitudes
      ori (Mxn array): edge orientations (gradient direction)
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% Call:
      [mag, ori] = CS4640\_edge(im);
% Author:
      <Your name>
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function H_im = CS4630_Hessian(im)
% CS4640_Hessian - compute the eigenvalues of the Hessian at each
                   pixel
% On input:
      im (MxN array): graylevel image
```

```
% On output:
      H_im (MxNx2 array): 2-channels with eigenvalues of Hessian
% Call:
      H = CS4640 _ Hessian(im);
% Author:
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function imo = CS4640 \text{ median(im,s)}
% CS4640_median - compute median value at each pixel
% On input:
      im (MxN array): input image
      s (int): median window side length (must be odd)
% On output:
      imo (MxN array): median filtered image
% Call:
      imo = CS4640_median(im);
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function im =
CS4640_create_im_gen(f_name,M,N,Q,x_min,x_max,y_min,y_max,...
    args)
% CS4640_create_im_gen - create an image from a function with
% arguments
% On input:
      f_name (string): name of function
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      M (int): number of rows in image
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      N (int): number of cols in image
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      Q (int): number of quantization levels in image
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      x_min (float): min x value for planar patch
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      x_max (float): max x value for planar patch
      y_min (float): min y value for planar patch
      y_max (float): max y value for planar patch
```

```
args (1xq vector): arguments for function (in addition to x,y)
% On output:
      im (MxN array): image
% Call:
      im = CS4640\_creat\_im\_gen('CS4640\_LoG', 100, 100, 64, -4, 4, -4, 4, 2);
% Author:
      <Your name>
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      UU
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function imo = CS4640_zc(im)
% CS4640_zc - zero crossings
% On input:
      im (MxN array): input image
% On output:
      imo (MxN array): zero crossings in image
% Call:
      imo = CS4640_zc(im);
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function h = CS4640\_LoG(x,y,sigma2)
% CS4640_LoG - Laplacian of Gaussian function
% On input:
      x (double): x value
      y (double): y value
      sigma2 (double): variance of Gaussian
% On output:
      h (double): LoG value
% Call:
      h = CS4640\_create\_im\_gen(3,2,2);
% Author:
응
      <Your name>
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      UU
      Spring 2018
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```

```
function [imo,imzc] = CS4640_LapG(im,s,sigma2)
% CS4640_LapG - Laplacian of Gaussian
% On input:
      im (MxN array): input image
      s (int): side length of LoG filter
      sigma2 (double): variance of Gaussian filter
% On output:
      imo (MxN array): LoG image
      imzc (MxN arry): zero-crossings
% Call:
      [imo, imzc] = CS4640\_LaG(T1gs, 7, 3);
% Author:
      <Your name>
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function CS4640_A2_driver
% CS4640_A2_driver - driver for A2 functions
% On input:
      N/A
% On output:
응
      N/A
% Call:
      CS4640_A2_driver
% Author:
      <Your name>
      UU
      Spring 2018
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```