Graph Streaming and Maximum Matching (in a Few Passes)

Kheeran K. Naidu

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Definition (Graph)

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A graph is made up of entities called vertices and relations between them called edges.

Definition (Bipartite Graph)

A bipartite graph G = (A, B, E) is such that, for all $(a, b) \in E$, $a \in A$ and $b \in B$.



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Observation

For any
$$G = (A, B, E)$$
 such that $|A| = |B| = n/2$,

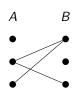
$$0 \le |E| \le n^2/4,$$

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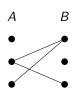
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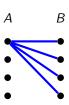
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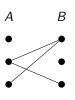


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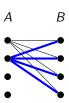
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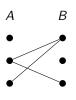


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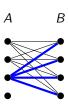
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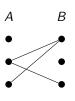


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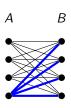
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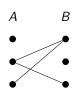


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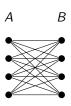
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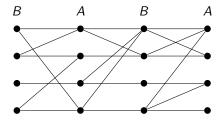
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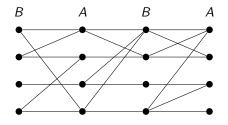


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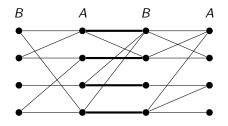






Matchings

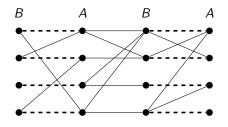
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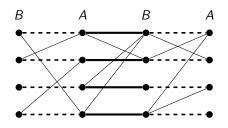
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- Maximum: Largest size, $\mu(G)$.



Matchings

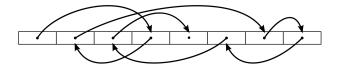
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- **Maximal**: Every edge $e \in E \setminus M$ is incident to M.
- Maximum: Largest size, $\mu(G)$.
- Maximal matchings are 0.5-approximations of maximum matchings.

Traditional Model of Computation

Assumption

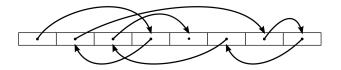
Algorithms have random access to the entire graph.



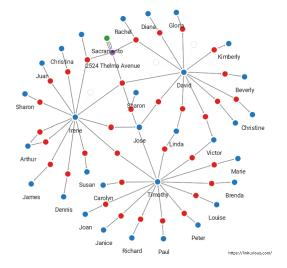
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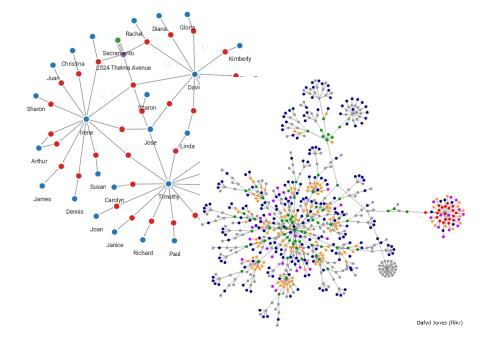
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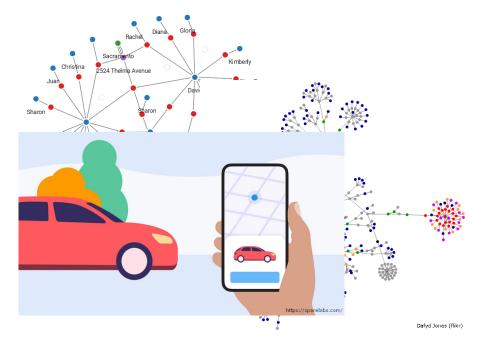
Algorithms have random access to the entire graph.



What if the input is extremely large?











One Trillion Edges: Graph Processing at Facebook-Scale

Avery Ching Facebook 1 Hacker Lane Menlo Park, California aching@fb.com

Sergey Edunov Facebook 1 Hacker Lane Menlo Park, California edunov@fb.com

Maia Kabilio Facebook 1 Hacker Lane Menlo Park, California majakabiljo@fb.com

Dionysios Logothetis Facebook 1 Hacker Lane Menlo Park, California dionysios@fb.com

Sambavi Muthukrishnan Facebook 1 Hacker Lane Menlo Park, California sambavim@fb.com

ABSTRACT

Sh

Analyzing large graphs provides valuable insights for social networking and web companies in content ranking and recommendations. While numerous graph processing systems have been developed and evaluated on available benchmark graphs of up to 6.6B edges, they often face significant difa project to run Facebook-scale graph applications in the summer of 2012 and is still the case today.

Table 1: Popular benchmark graphs. Graph Vertices Edges https://sparelabs.com/

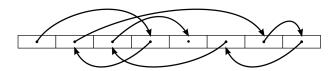
Dafyd Jones (flikr)

(fliker)

Massive Graphs

Assumption (Infeasible)

Algorithms have random access to the entire graph.



Definition

An *n*-vertex graph is presented as a sequence of edges to an algorithm.



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Insertion-only [FKM⁺04]

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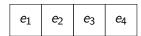




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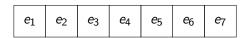




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Insertion-only [FKM⁺04] (finite stream)



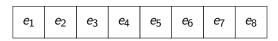


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Trivial Algorithm

• Stores all edges using $O(n^2)$ space.

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Trivial Algorithm

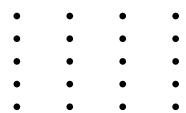
• Stores all edges using $O(n^2)$ space.

Interesting Algorithm

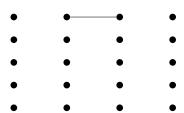
- Uses $O(n \operatorname{polylog} n)$ space.
- Uses one or more passes.

GREEDY Matching:

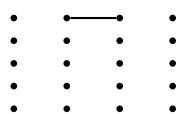
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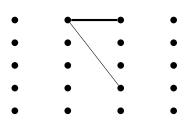
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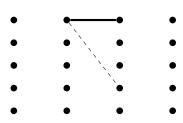
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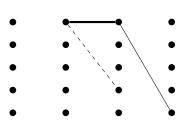
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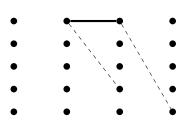
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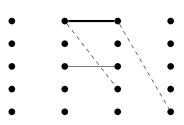
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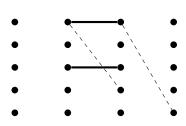
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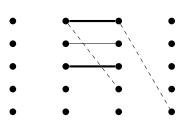
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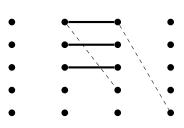
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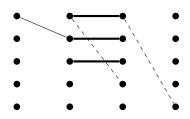
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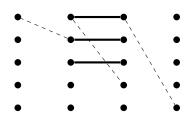
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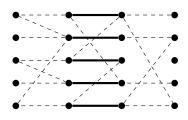
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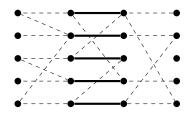


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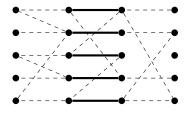
GREEDY Matching:

- Add edge if neither endpoint is matched
 - Maximal



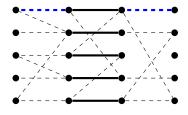
GREEDY Matching:

- Add edge if neither endpoint is matched
 - Maximal
- 0.5-approximation



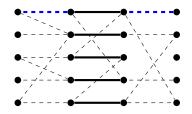
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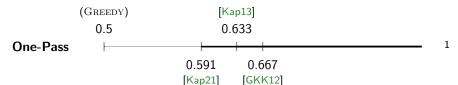


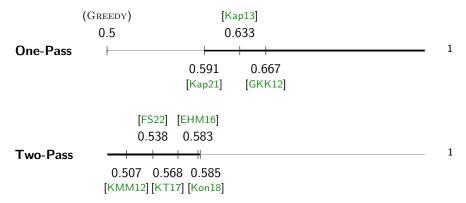
Space Used

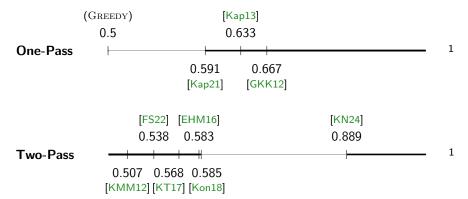
Only the matching M is stored by the algorithm $\implies O(n \log n)$ space since each edge requires $\Theta(\log n)$ space to store.

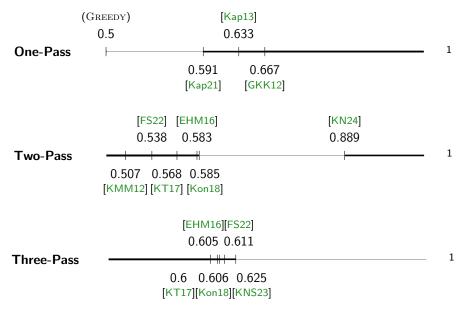
(Greedy) 0.5

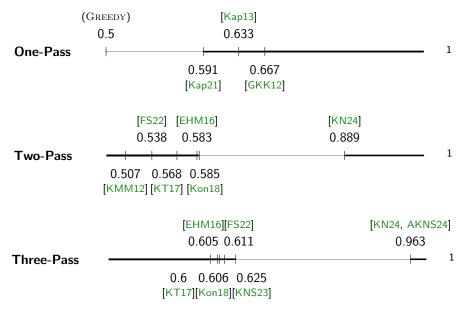
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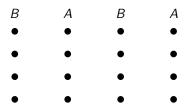
Three-Pass Algorithmic Idea

First Pass

Find a maximal matching M in G using GREEDY.

Subsequent Passes

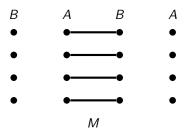
Find vertex-disjoint augmenting paths (also using GREEDY).



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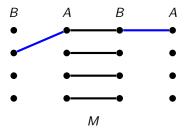
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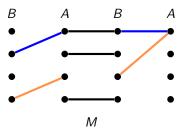
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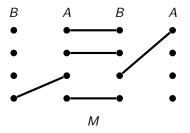
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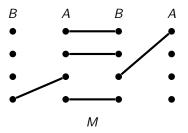


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Find a maximal matching M in G using GREEDY.

Subsequent Passes

Find vertex-disjoint augmenting paths (also using GREEDY). (How?)

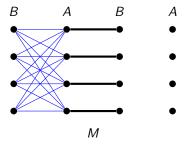


- Find left wings
- Extend with right wings

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$$|M| = 0.5 \cdot \mu(G)$$

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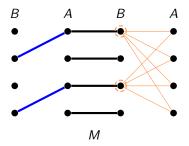
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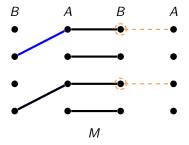
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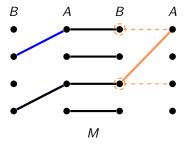
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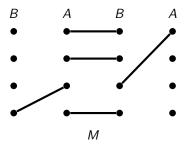
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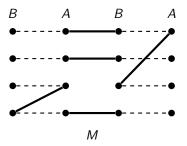
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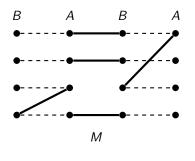
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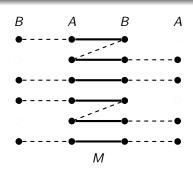
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- $|M| = 0.5 \cdot \mu(G)$
- 0.625-approximation
- Not hard!

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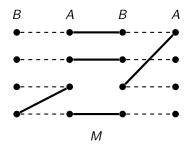


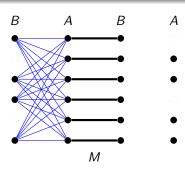


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Simple Strategy

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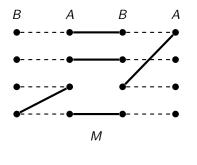


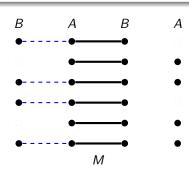


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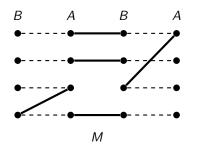
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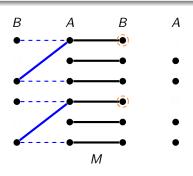




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- Find left wings
- Extend with right wings

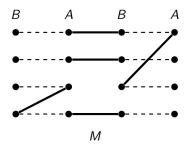


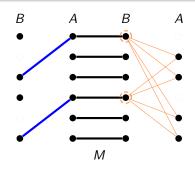


- $|M| = 0.5 \cdot \mu(G)$
- 0.625-approximation
- Not hard!

Simple Strategy

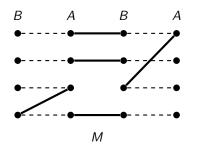
- Find left wings
- Extend with right wings

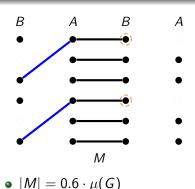




- $|M| = 0.5 \cdot \mu(G)$
- 0.625-approximation
- Not hard!

- Find left wings
- Extend with right wings

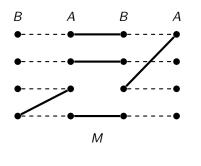


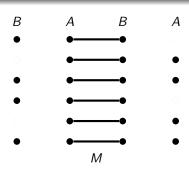


- $|M| = 0.5 \cdot \mu(G)$
- 0.625-approximation
- Not hard!

Simple Strategy

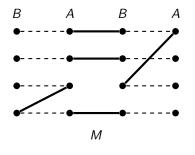
- Find left wings
- Extend with right wings



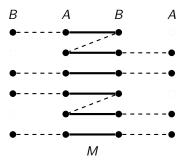


- $|M| = 0.5 \cdot \mu(G)$
- 0.625-approximation
- Not hard!

- Find left wings
- Extend with right wings



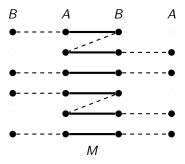
- $|M| = 0.5 \cdot \mu(G)$
- 0.625-approximation
- Not hard!



- $|M| = 0.6 \cdot \mu(G)$
- 0.6-approximation
- Hard instance!

- Find left and right wings
- 2 Extend paths to either length-3 or length-5 augmenting paths

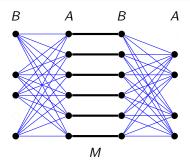
- Find left and right wings
- 2 Extend paths to either length-3 or length-5 augmenting paths



•
$$|M| = 0.6 \cdot \mu(G)$$

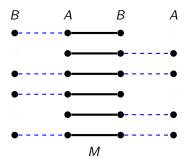
Our Strategy

- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths

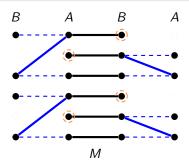


Our Strategy

- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths



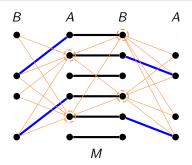
- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths



•
$$|M| = 0.6 \cdot \mu(G)$$

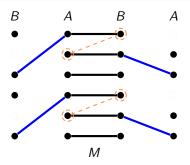
Our Strategy

- Find left and right wings
- 2 Extend paths to either length-3 or length-5 augmenting paths



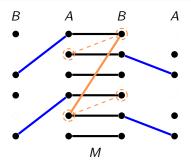
Our Strategy

- Find left and right wings
- 2 Extend paths to either length-3 or length-5 augmenting paths

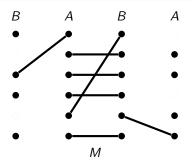


Our Strategy

- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths

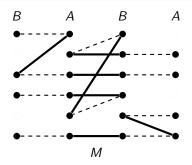


- Find left and right wings
- 2 Extend paths to either length-3 or length-5 augmenting paths



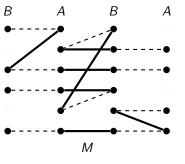
•
$$|M| = 0.6 \cdot \mu(G)$$

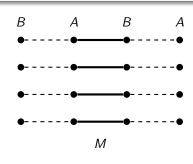
- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths



- $|M| = 0.6 \cdot \mu(G)$
- 0.7-approximation
- Not hard anymore!

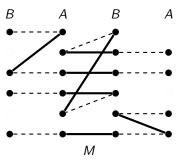
- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths

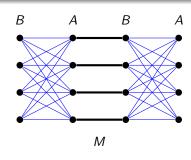




- $|M| = 0.6 \cdot \mu(G)$
- $|M| = 0.5 \cdot \mu(G)$ 0.7-approximation
- Not hard anymore!

- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths

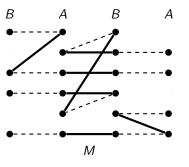


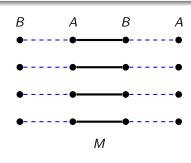


- $|M| = 0.6 \cdot \mu(G)$
- 0.7-approximation
- Not hard anymore!

$$\bullet |M| = 0.5 \cdot \mu(G)$$

- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths



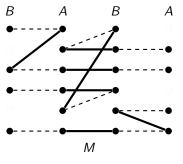


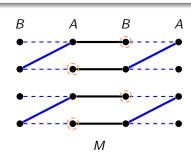
- $|M| = 0.6 \cdot \mu(G)$
- 0.7-approximation
- Not hard anymore!

$$\bullet |M| = 0.5 \cdot \mu(G)$$

Our Strategy

- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths

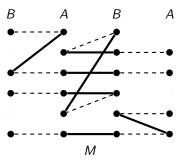


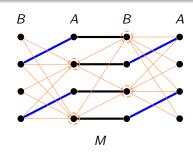


- $|M| = 0.6 \cdot \mu(G)$
- 0.7-approximation
- Not hard anymore!

 $\bullet |M| = 0.5 \cdot \mu(G)$

- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths

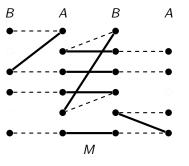


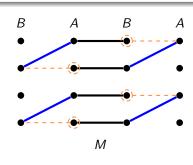


- $|M| = 0.6 \cdot \mu(G)$
- 0.7-approximation
- Not hard anymore!

$$\bullet |M| = 0.5 \cdot \mu(G)$$

- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths

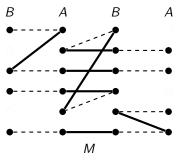


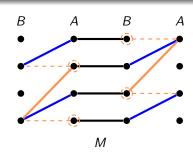


- $|M| = 0.6 \cdot \mu(G)$
- 0.7-approximation
- Not hard anymore!

$$\bullet |M| = 0.5 \cdot \mu(G)$$

- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths



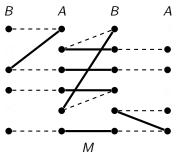


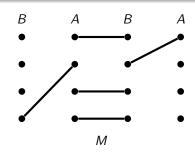
- $|M| = 0.6 \cdot \mu(G)$
- 0.7-approximation
- Not hard anymore!

$$\bullet |M| = 0.5 \cdot \mu(G)$$

Our Strategy

- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths

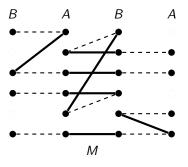


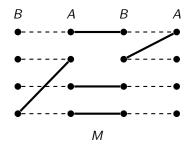


- $|M| = 0.6 \cdot \mu(G)$
- 0.7-approximation
- Not hard anymore!

 $\bullet |M| = 0.5 \cdot \mu(G)$

- Find left and right wings
- Extend paths to either length-3 or length-5 augmenting paths





- $|M| = 0.6 \cdot \mu(G)$
- 0.7-approximation
- Not hard anymore!

- $|M| = 0.5 \cdot \mu(G)$
- 0.625-approximation
- Hard instance!

Our Analysis [KNS23]

Main Lemma

Let $|M| = (0.5 + \epsilon) \cdot \mu(G)$ for $\epsilon \ge 0$, then our strategy finds

$$(0.125 - \frac{3}{4}\epsilon) \cdot \mu(G)$$

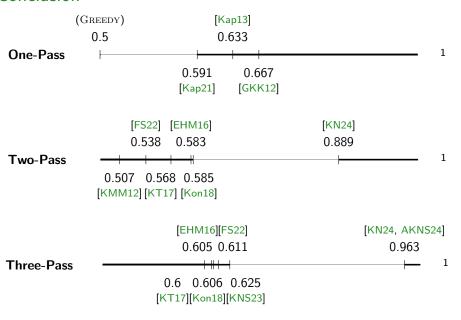
vertex-disjoint augmenting paths and the large matching found is of size

$$(0.625 + \frac{\epsilon}{4}) \cdot \mu(G).$$

Space Used

GREEDY only stores O(n) edges in each pass $\implies O(n \log n)$ space.

Conclusion



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