# An Unconditional Lower Bound for Two-Pass Streaming Algorithms for Maximum Matching Approximation

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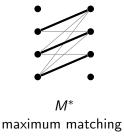




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#### **Approximations**

• M is a  $(\frac{|M|}{|M^*|})$ -approximate matching (e.g.  $\frac{2}{3}$ ).

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A (2n)-vertex graph is presented as a sequence of edges to an algorithm

 $e_1$ 



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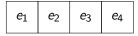


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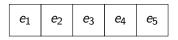


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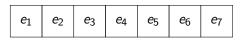


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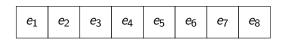


#### **Trivial Algorithm**

• Store all edges with  $O(n^2)$  space.

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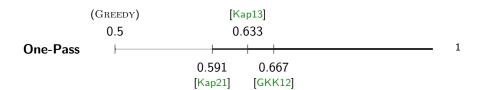
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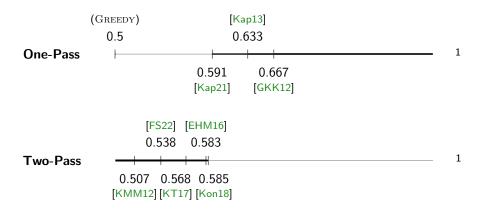
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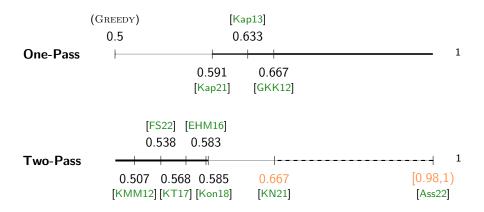
#### **Interesting Algorithms**

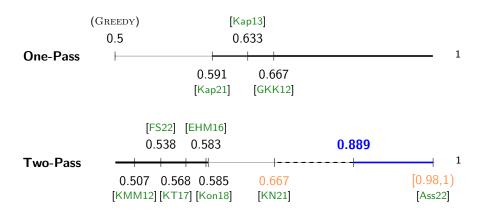
- Use  $O(n \operatorname{polylog} n)$  space (semi-streaming).
  - Many graph problems require  $\Omega(n)$  space in one pass [FKM<sup>+</sup>04].
- Use one or more passes of the stream.

(GREEDY)
0.5
One-Pass









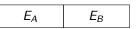
#### Our Result

For  $\varepsilon>0$ , any constant-error two-pass  $\left(\frac{8}{9}+\varepsilon\right)$ -approximation streaming algorithm for MBM requires  $n^{1+\Omega(1/(\log\log n)^2)}$  space.

- Construct a hard graph G.
- Adversarially order its edges.
- Prove hardness via one-way communication complexity.

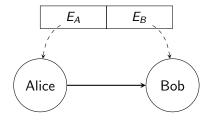


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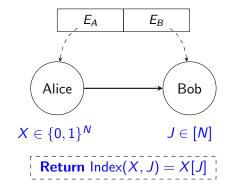


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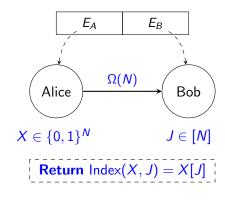
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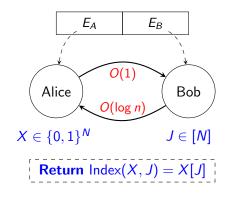
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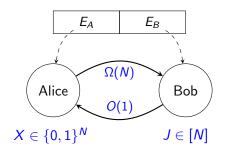


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**Goal:** Construct a stream of edges that is hard for any algorithm.

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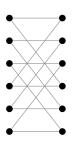


**Return** 
$$Index(X, J) = X[J]$$

#### Info Cost Tradeoff [JRS09]

- If  $ICost_{\mathcal{D}}^{\mathcal{B}}(\pi) = O(1)$ , then

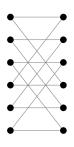
# Ruzsa-Szeméredi (RS) Graphs



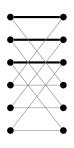
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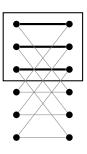
A matching whose vertex induced subgraph contains only its edges.



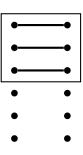
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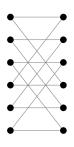
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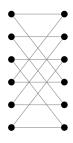
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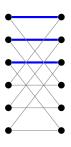
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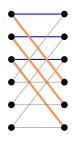
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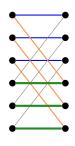
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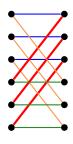
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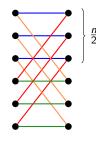
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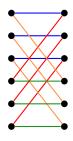


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A graph whose edges set is the union of t many edge-disjoint induced matchings of size r.



# Proposition ([GKK12] (see also [FLN+02]))

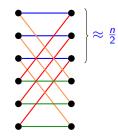
For constant  $\delta > 0$ , there exists a (bipartite) (r,t)-RS graph on 2n vertices where  $r = (\frac{1}{2} - \delta) \cdot n$  and  $t = n^{\Omega(1/\log\log n)}$ .

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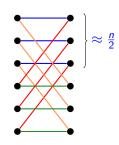
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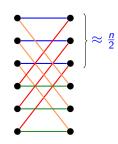
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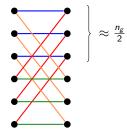
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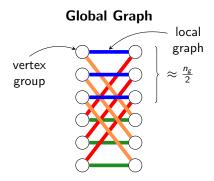


- $n^{\Omega(1/\log\log n)}$  many induced matchings.
- $\gg n \operatorname{polylog} n$  edges in the graph.

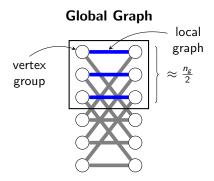
### **Global Graph**



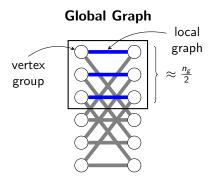
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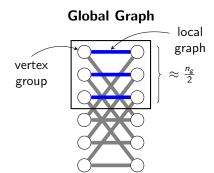
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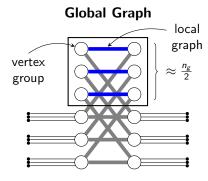


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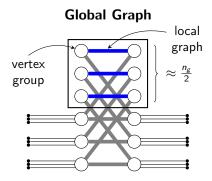
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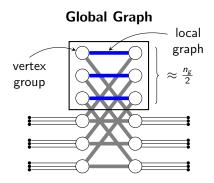


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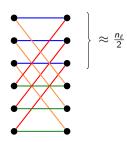


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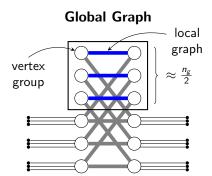


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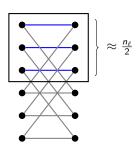


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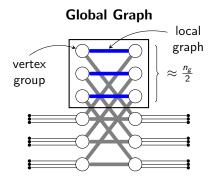


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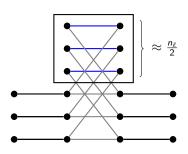
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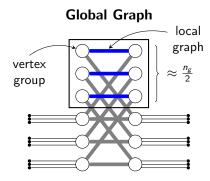
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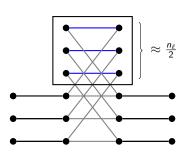
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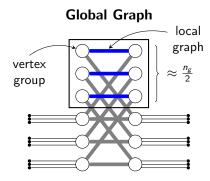
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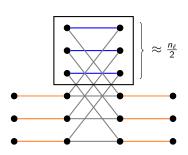
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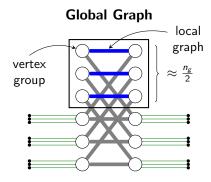
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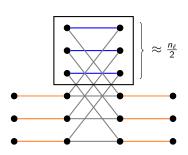
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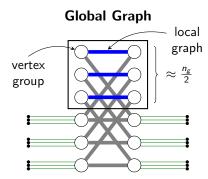
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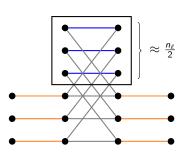


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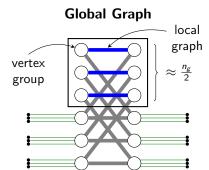
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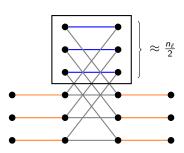


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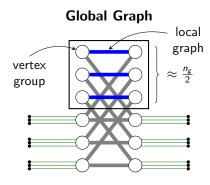


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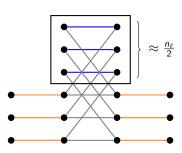


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local RS-graphs	local selectors	global selector
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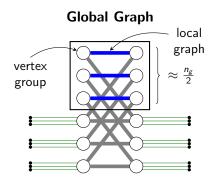


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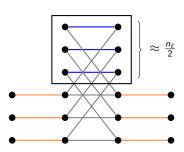
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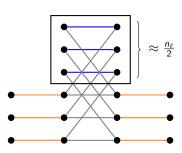
local RS-graphs local selectors global selector o(1) per local graph (Index instance)  $\mathcal{A}$  O(n)

# Global Graph local graph vertex $\approx \frac{n_g}{2}$ group

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An Unconditional LB for Two-Pass Streaming Matching

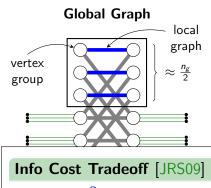
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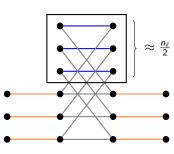
global local RS-graphs local selectors

O(n)



- If  $\mathsf{ICost}^{\mathcal{B}}_{\mathcal{D}}(\pi) = O(1)$ , then

### Local Graphs



- $(2n_{\ell})$ -vertex  $(r_{\ell}, t_{\ell})$ -RS graph.
- $\bullet$  1/3<sup>rd</sup> of the vertices are special.
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local RS-graphs

local selectors

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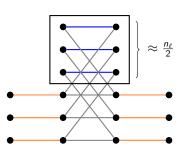
o(1) per local graph (Index instance)

J

# $\begin{array}{c|c} \textbf{Global Graph} \\ \textbf{vertex} \\ \textbf{group} \end{array} \approx \frac{n_g}{2}$

- $(2n_g)$ -vertex  $(r_g, t_g)$ -RS graph.
- $\bullet$   $\Theta(n_g)$  small hard instances
- $1/3^{rd}$  of the vertices are special.

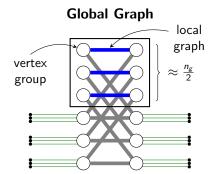
### **Local Graphs**



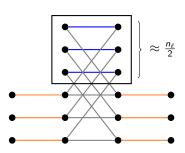
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local RS-graphs local selectors global elector

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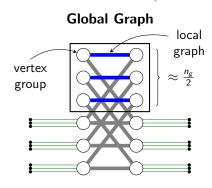
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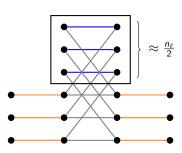
	local RS-graphs	local selectors	global
$\overline{\mathcal{A}}$	$\gg n \operatorname{polylog} n$	O(n)	•

# Two-Pass Hard Graph and Adversarial Stream



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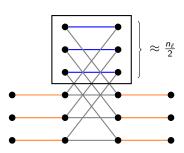
local RS-graphs local selectors global elector o(1) fraction of edges  $\mathcal{A}$  O(n)

# Two-Pass Hard Graph and Adversarial Stream

# $\begin{array}{c|c} \textbf{Global Graph} \\ \text{vertex} \\ \text{group} \end{array} \geqslant \frac{n_g}{2}$

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## **Local Graphs**



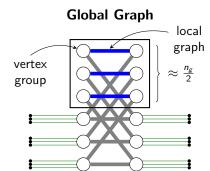
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local RS-graphs | local fectors | global elector

o(1) fraction of edges

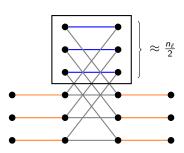
 $\mathcal{A}$ 

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8/9-approximation

#### Our Result

For  $\varepsilon > 0$ , any constant-error two-pass  $(\frac{8}{9} + \varepsilon)$ -approximation streaming algorithm for MBM requires  $n^{1+\Omega(1/(\log\log n)^2)}$  space.

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#### **Multiple Passes**

- [AS23] recently showed that  $(1 \varepsilon)$ -approximations require  $\Omega(\log 1/\varepsilon)$  passes (conditional)
- Algorithms require either  $O(1/\varepsilon^2)$  or  $O((1/\varepsilon) \cdot \log n)$  passes.

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#### **Open Questions**

- Narrow the gap for either the 1-pass, 2-pass or multi-pass settings.
- Well do these ideas work for other graph problems?

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# Thank you!

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