

# Graph Streaming and Maximum Matching (in a Few Passes)

Kheeran K. Naidu

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# Graphs and Bipartite Graphs

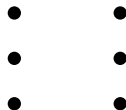
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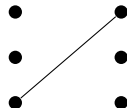
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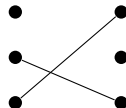
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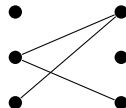
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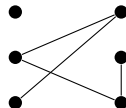
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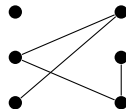
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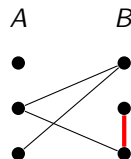
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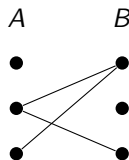
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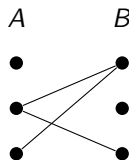
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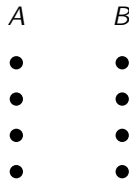
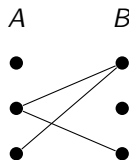
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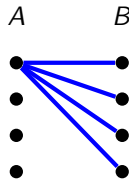
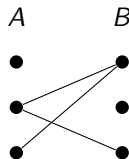
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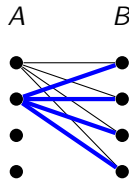
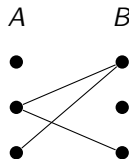
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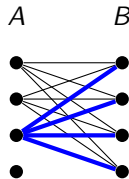
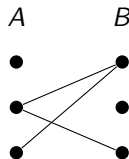
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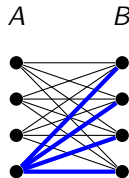
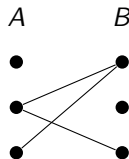
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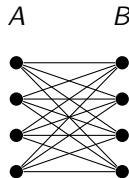
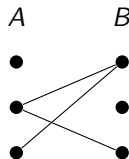
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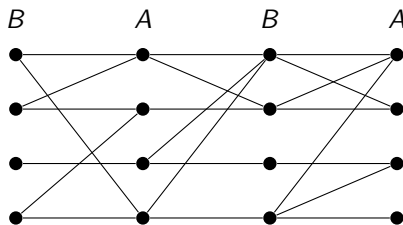
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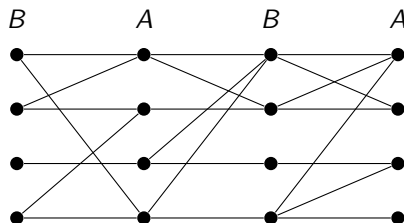
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# Maximum Bipartite Matching (MBM)



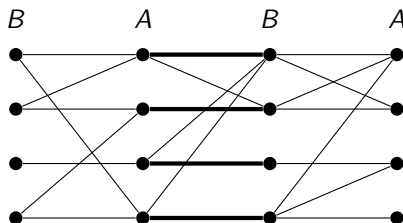
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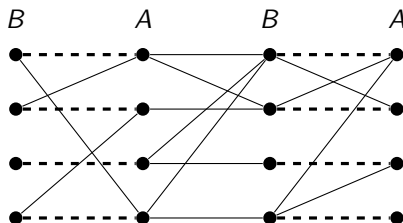


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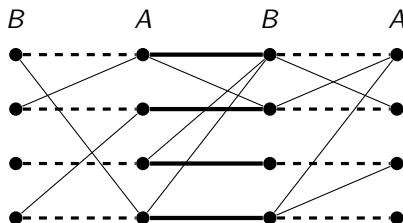


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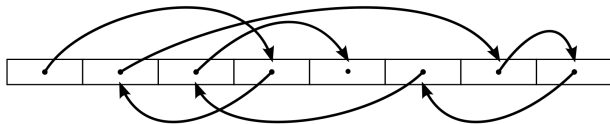
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- Maximal matchings are **0.5-approximations** of maximum matchings.

# Traditional Model of Computation

## Assumption

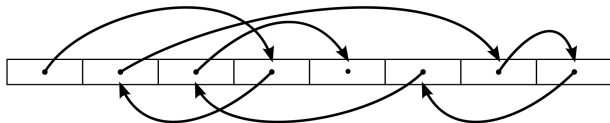
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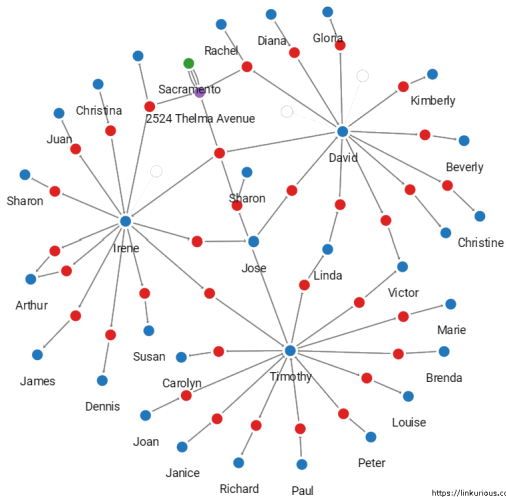
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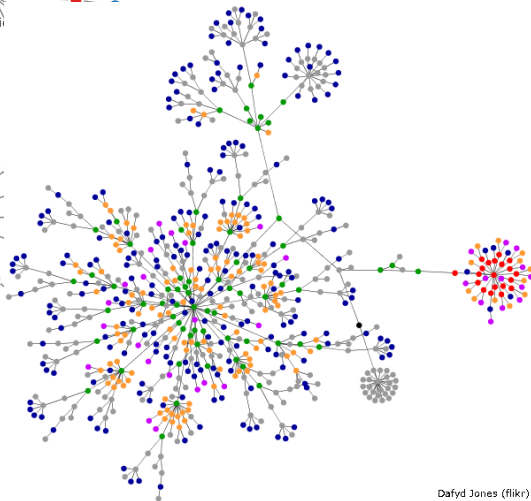
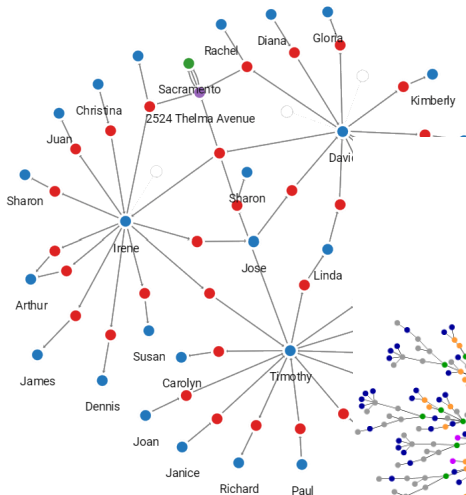


**What if the input is extremely large?**

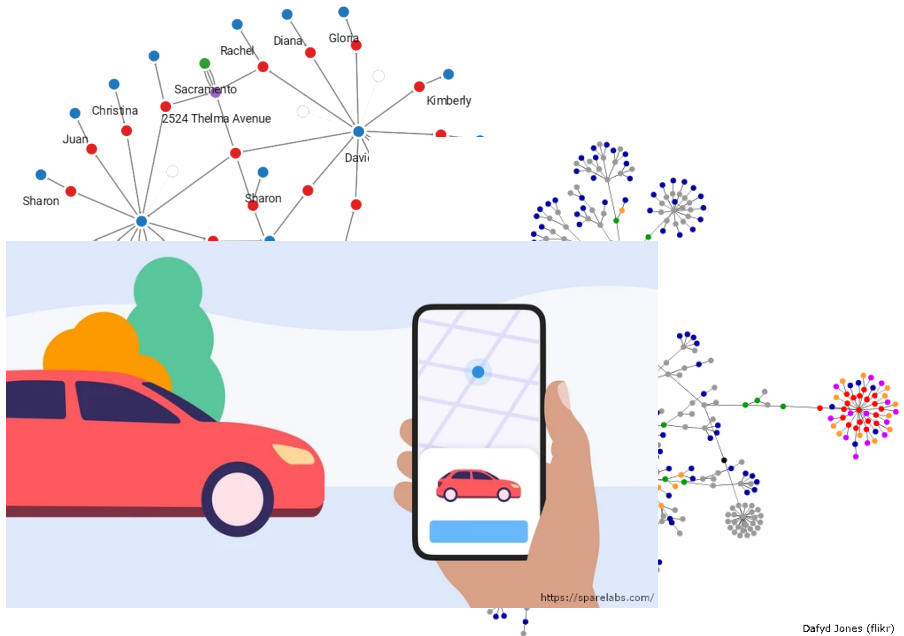




<https://linkurious.com/>



Dafyd Jones (flickr)







# One Trillion Edges: Graph Processing at Facebook-Scale

Sh

Avery Ching  
Facebook  
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Menlo Park, California  
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Sergey Edunov  
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Maja Kabiljo  
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Dionysios Logothetis  
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Sambavi Muthukrishnan  
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## ABSTRACT

Analyzing large graphs provides valuable insights for social networking and web companies in content ranking and recommendations. While numerous graph processing systems have been developed and evaluated on available benchmark graphs of up to 6.6B edges, they often face significant dif-

a project to run Facebook-scale graph applications in the summer of 2012 and is still the case today.

(flickr)

Table 1: Popular benchmark graphs.

Graph	Vertices	Edges

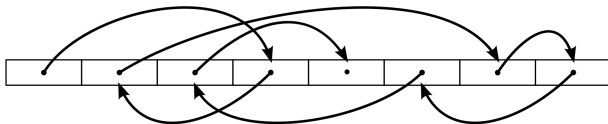
<https://sparelabs.com/>

Dafyd Jones (flickr)

# Massive Graphs

Assumption (**Infeasible**)

Algorithms have **random access** to the **entire graph**.



# Graph Streaming (Model of Computation)

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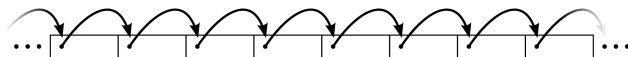
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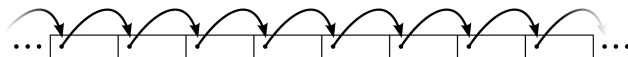
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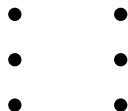
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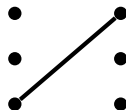
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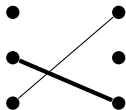
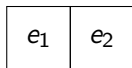
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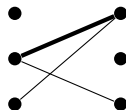
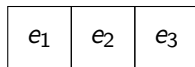
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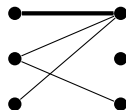
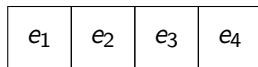
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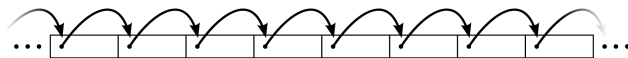
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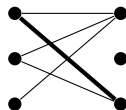
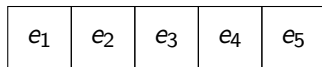
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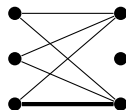
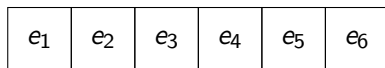
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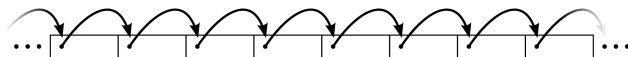
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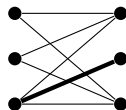
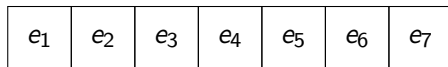
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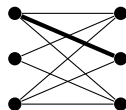
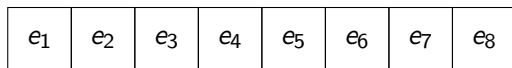
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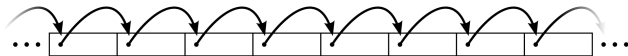
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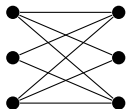
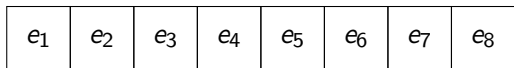
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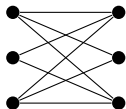
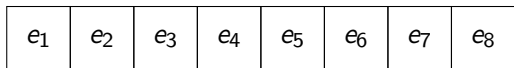
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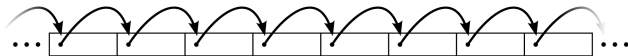
*Trivial Algorithm*

- Stores all edges using  $O(n^2)$  space.

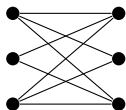
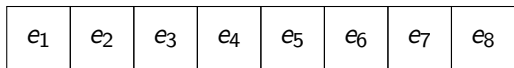
# Graph Streaming (Model of Computation)

## Definition

An  $n$ -vertex graph is presented as a sequence of edges to an algorithm.



## Insertion-only [FKM<sup>+</sup>04] (finite stream)



### *Trivial Algorithm*

- Stores all edges using  $O(n^2)$  space.

### *Interesting Algorithm*

- Uses  $O(n \text{ polylog } n)$  space.
- Uses one or more passes.

# GREEDY: Simple and Powerful

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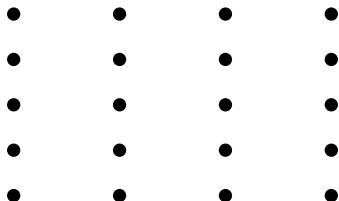
## GREEDY Matching:

- 1 Add edge if neither endpoint is matched

# GREEDY: Simple and Powerful

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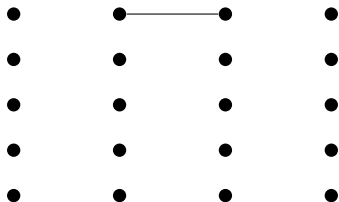
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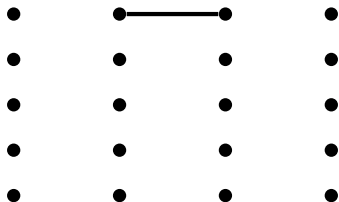




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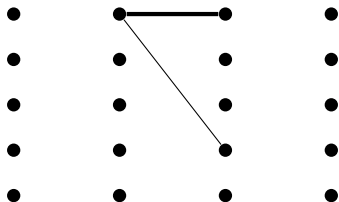
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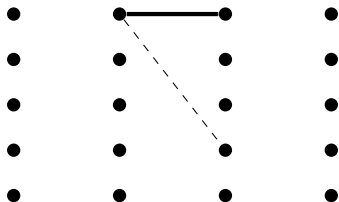
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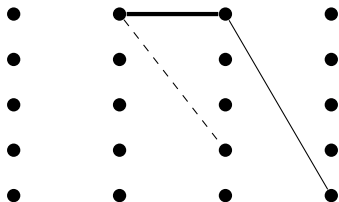
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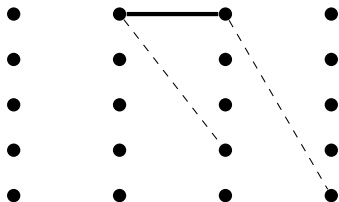
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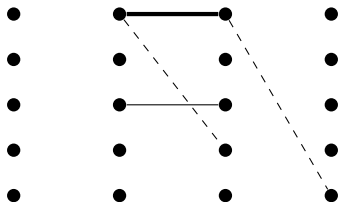
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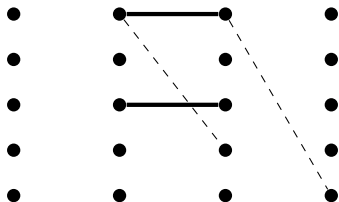
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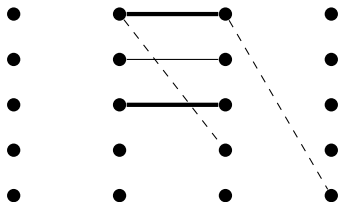
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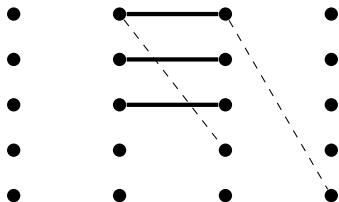




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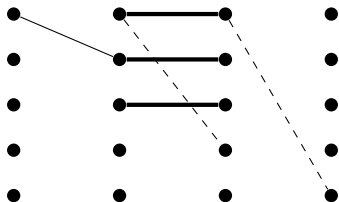
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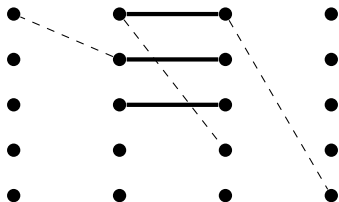
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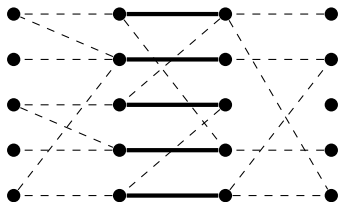
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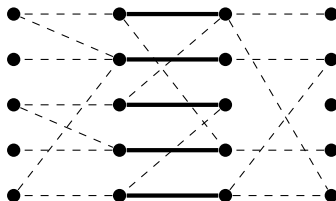
- 1 Add edge if neither endpoint is matched



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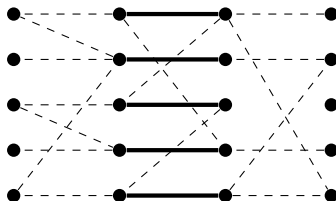
- 1 Add edge if neither endpoint is matched
- Maximal



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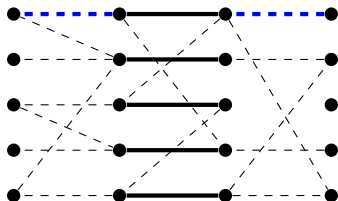
- ➊ Add edge if neither endpoint is matched
- Maximal
- 0.5-approximation



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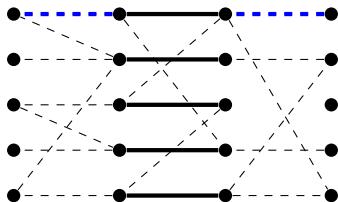
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# GREEDY: Simple and Powerful

## GREEDY Matching:

- ➊ Add edge if neither endpoint is matched
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- 0.5-approximation



## Space Used

Only the matching  $M$  is stored by the algorithm  $\implies O(n \log n)$  space since each edge requires  $\Theta(\log n)$  space to store.



# Approximate MBM using $O(n \text{ polylog } n)$ Space

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(GREEDY)

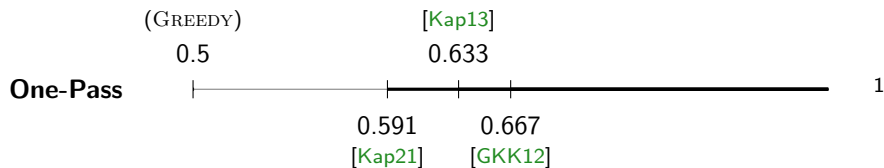
0.5

One-Pass

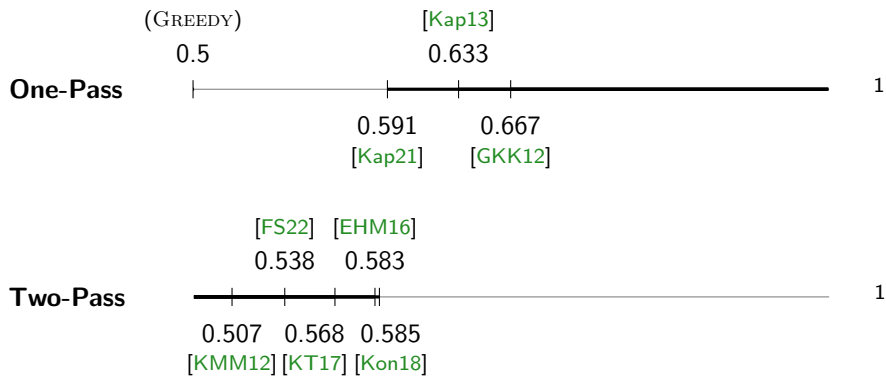
|

1

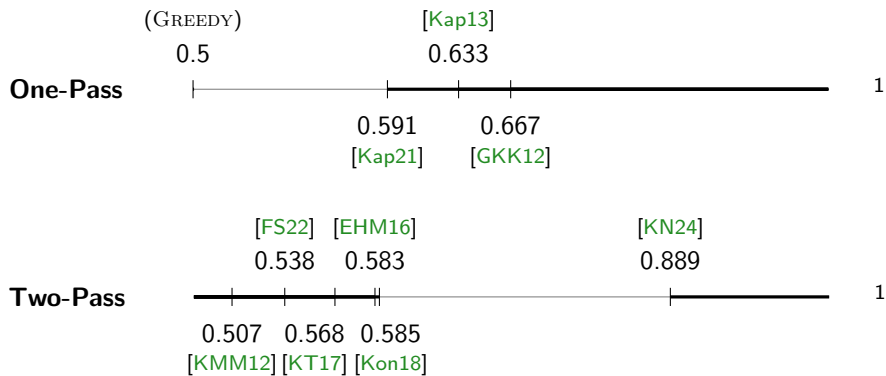
# Approximate MBM using $O(n \text{ polylog } n)$ Space



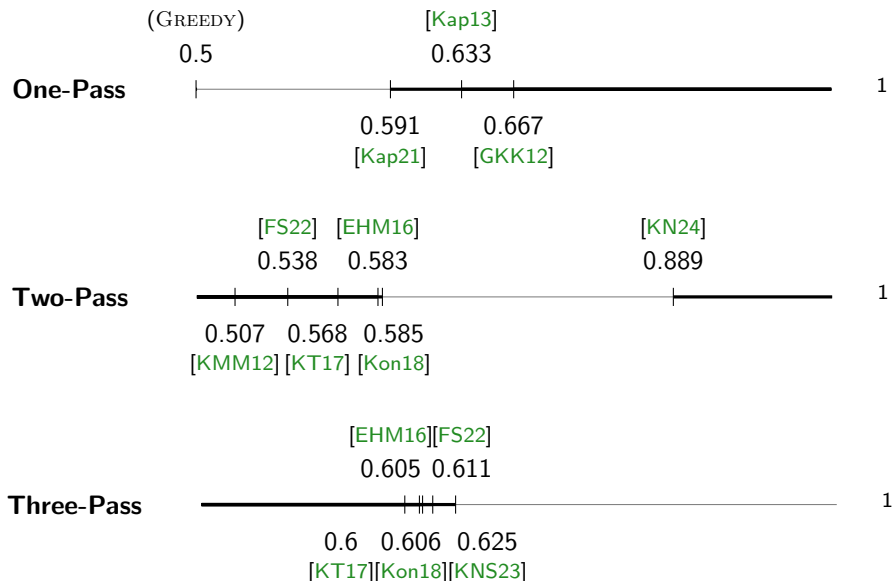
# Approximate MBM using $O(n \text{ polylog } n)$ Space



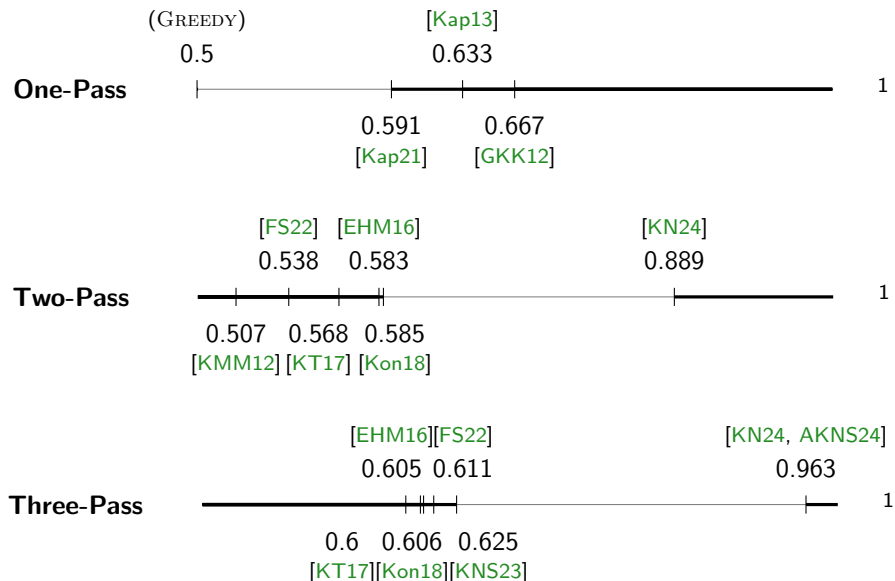
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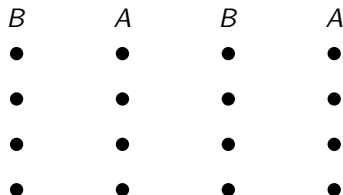
# Three-Pass Algorithmic Idea

## First Pass

Find a maximal matching  $M$  in  $G$  using GREEDY.

## Subsequent Passes

Find vertex-disjoint augmenting paths (also using GREEDY).





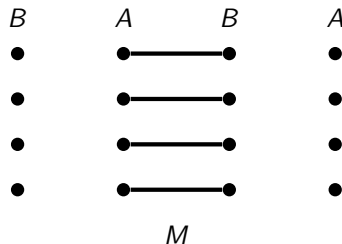
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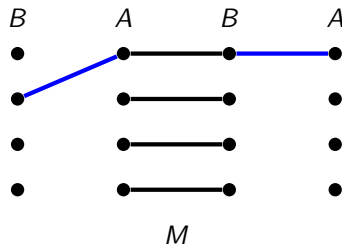
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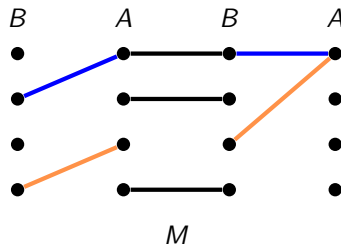
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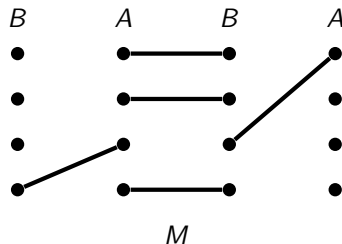
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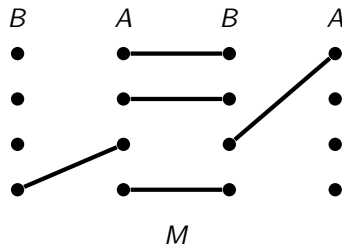
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# Finding length-3 augmenting paths [KT17]

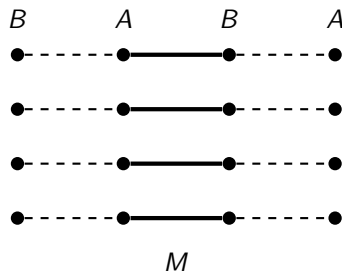
## Simple Strategy

- 1 Find left wings
- 2 Extend with right wings

# Finding length-3 augmenting paths [KT17]

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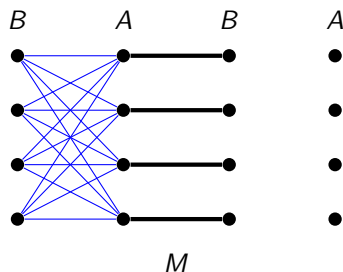


- $|M| = 0.5 \cdot \mu(G)$

# Finding length-3 augmenting paths [KT17]

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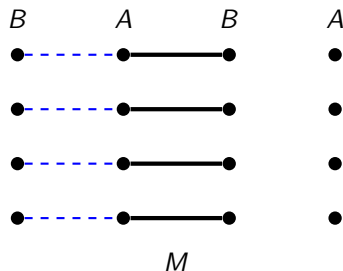
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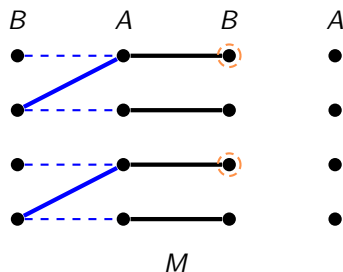


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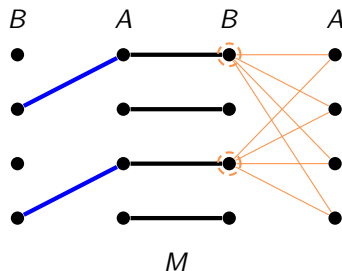


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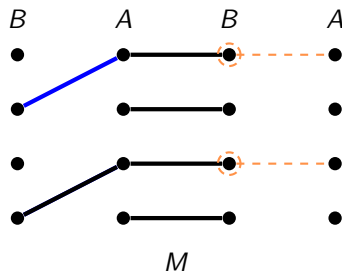


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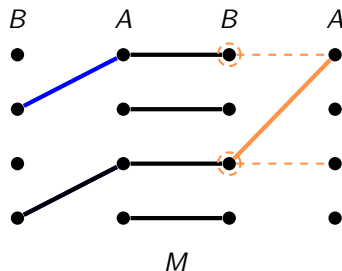


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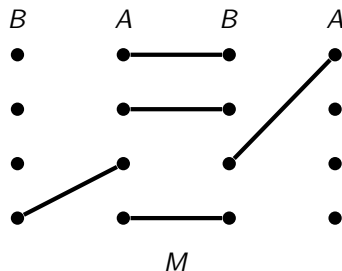


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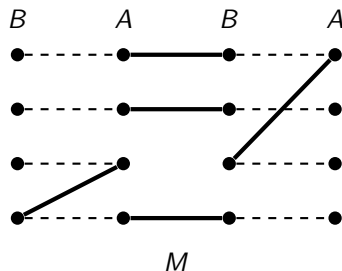


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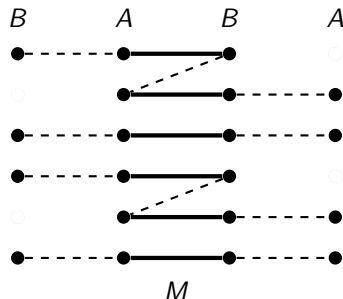
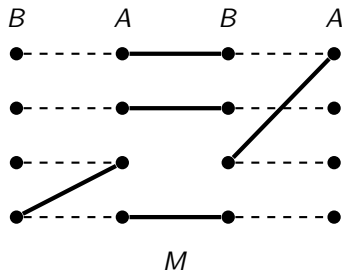


- $|M| = 0.5 \cdot \mu(G)$
- 0.625-approximation
- **Not hard!**

# Finding length-3 augmenting paths [KT17]

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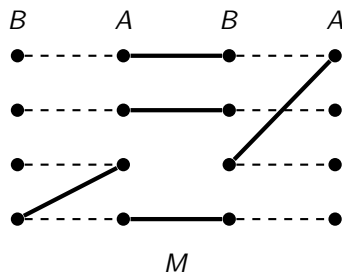
- $|M| = 0.6 \cdot \mu(G)$



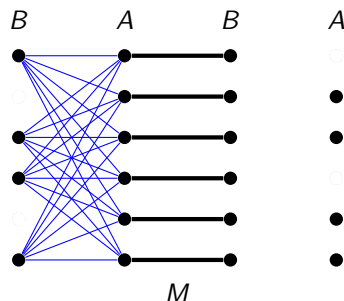
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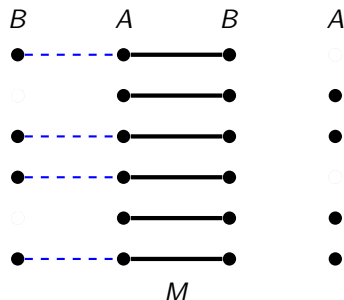
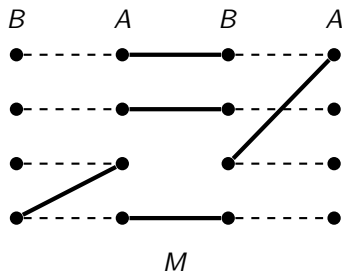


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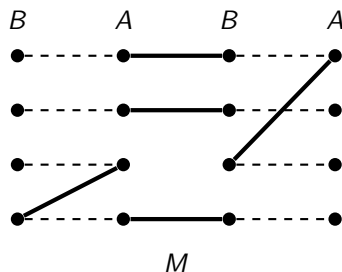
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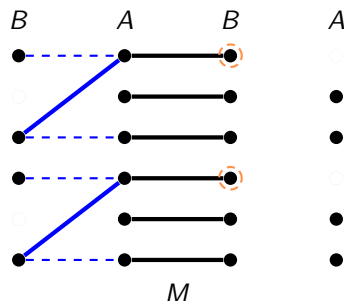
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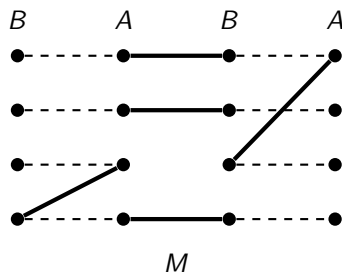


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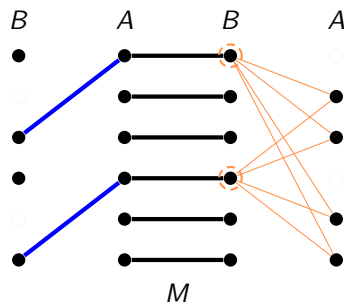
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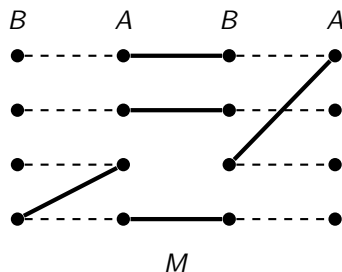


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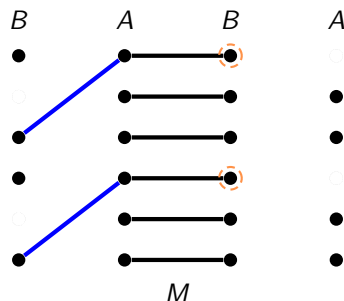
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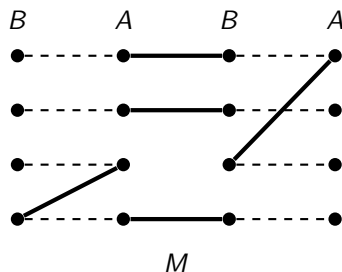


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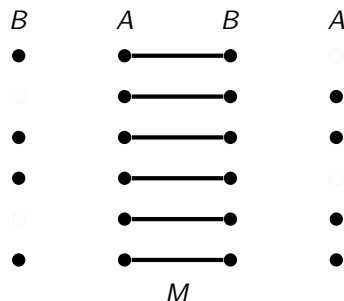
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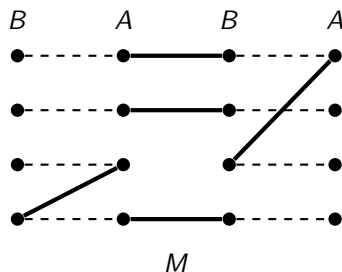


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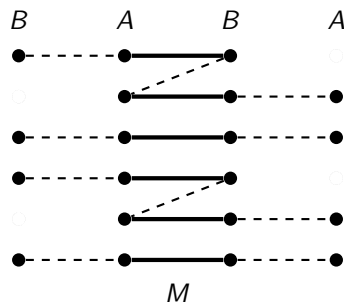
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## Simple Strategy

- 1 Find left wings
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- 0.625-approximation
- **Not hard!**



- $|M| = 0.6 \cdot \mu(G)$
- 0.6-approximation
- **Hard instance!**

# Finding length-3 & length-5 augmenting paths [KNS23]

## Our Strategy

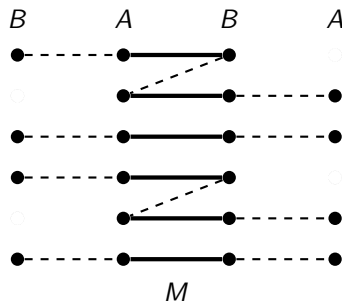
- ① Find left and right wings
- ② Extend paths to either length-3 or length-5 augmenting paths



# Finding length-3 & length-5 augmenting paths [KNS23]

## Our Strategy

- 1 Find left and right wings
- 2 Extend paths to either length-3 or length-5 augmenting paths

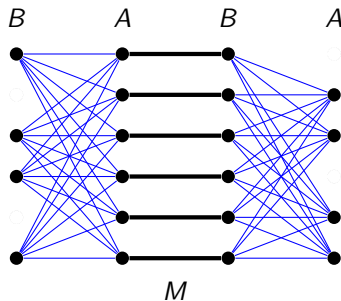


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# Finding length-3 & length-5 augmenting paths [KNS23]

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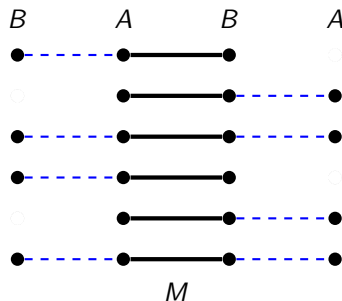


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# Finding length-3 & length-5 augmenting paths [KNS23]

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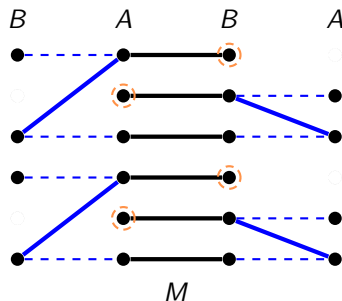


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# Finding length-3 & length-5 augmenting paths [KNS23]

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- 1 Find left and right wings
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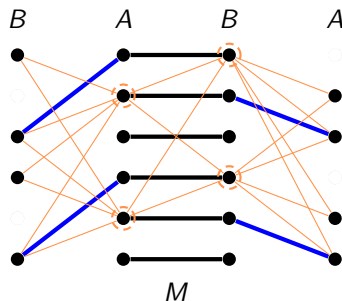


- $|M| = 0.6 \cdot \mu(G)$

# Finding length-3 & length-5 augmenting paths [KNS23]

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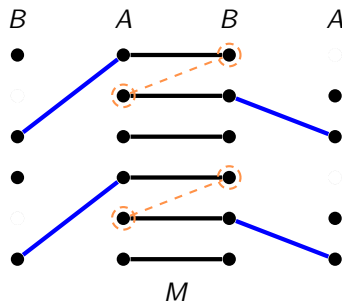


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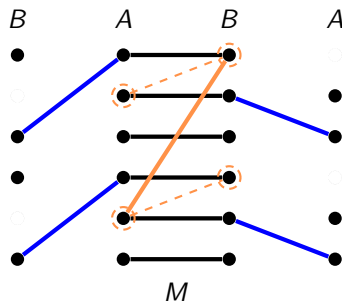


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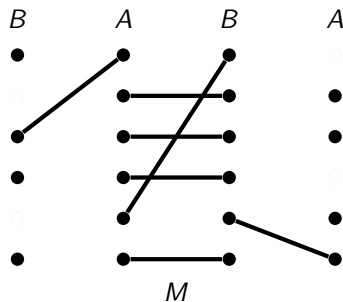


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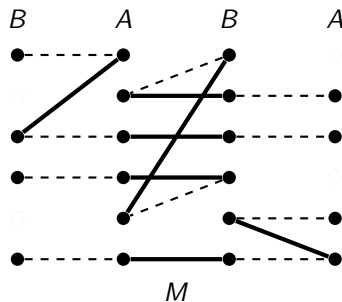
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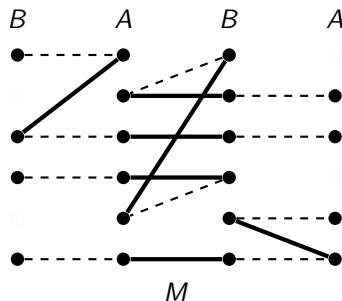


- $|M| = 0.6 \cdot \mu(G)$
- 0.7-approximation
- **Not hard anymore!**

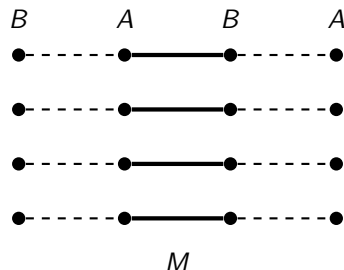
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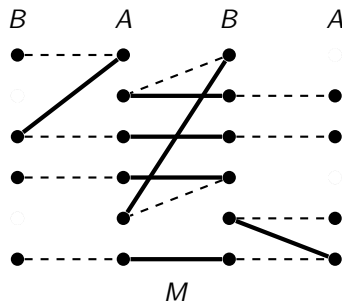


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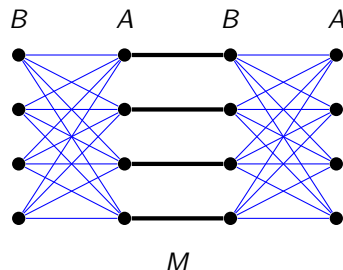
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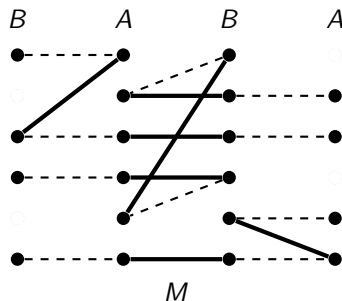


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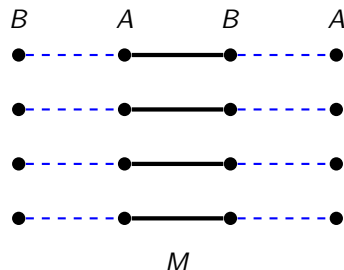
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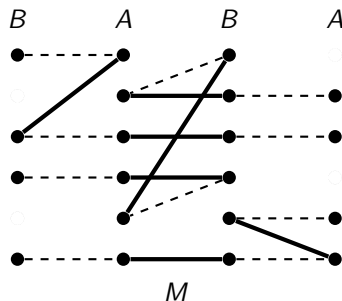


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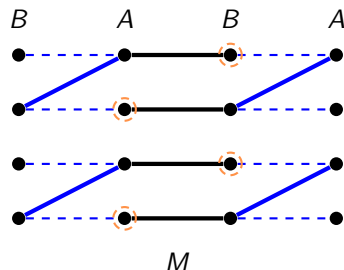
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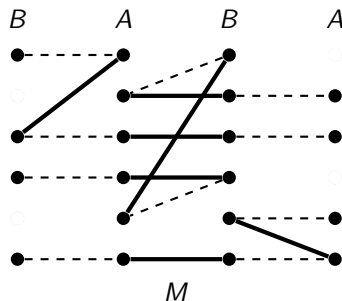


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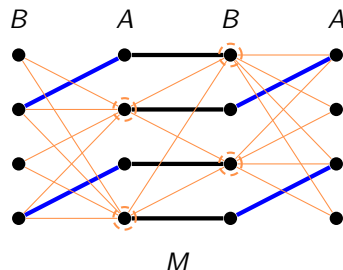
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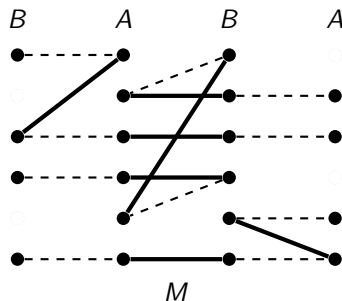


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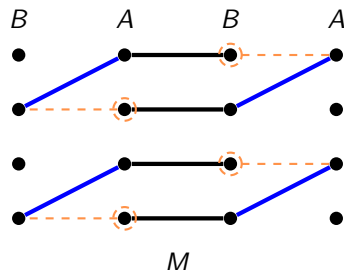
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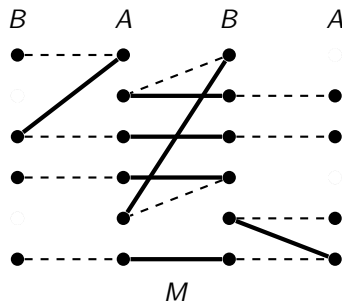


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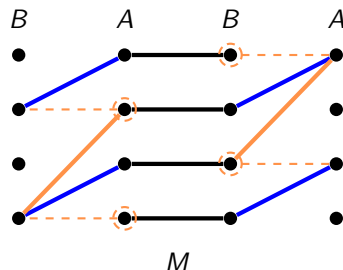
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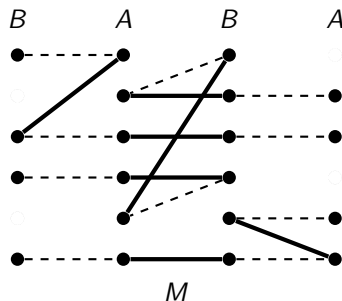
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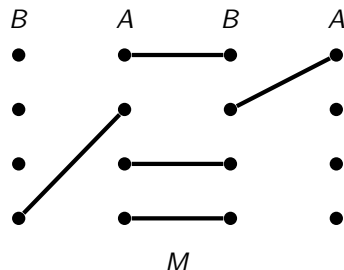
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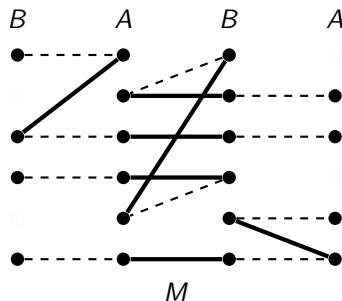


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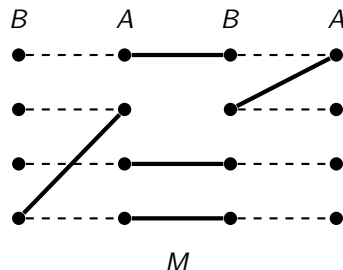
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## Our Strategy

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- 2 Extend paths to either length-3 or length-5 augmenting paths



- $|M| = 0.6 \cdot \mu(G)$
- 0.7-approximation
- **Not hard anymore!**



- $|M| = 0.5 \cdot \mu(G)$
- 0.625-approximation
- **Hard instance!**

# Our Analysis [KNS23]

## Main Lemma

Let  $|M| = (0.5 + \epsilon) \cdot \mu(G)$  for  $\epsilon \geq 0$ , then our strategy finds

$$(0.125 - \frac{3}{4}\epsilon) \cdot \mu(G)$$

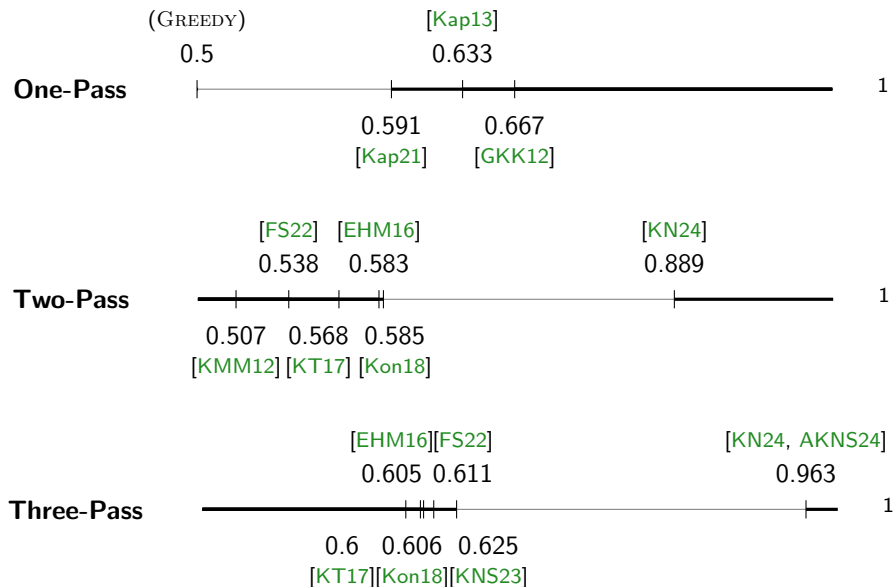
vertex-disjoint augmenting paths and the large matching found is of size

$$(0.625 + \frac{\epsilon}{4}) \cdot \mu(G).$$

## Space Used

GREEDY only stores  $O(n)$  edges in each pass  $\implies O(n \log n)$  space.

# Conclusion



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