

# On Two-Pass Streaming Algorithms for Maximum Bipartite Matching

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Joint work with Dr Christian Konrad

# Overview

## 1 Background

## 2 Our Work

- Lower Bound
- Algorithmic

## 3 Discussion

# Matchings

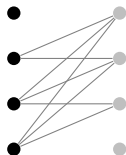
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A **(bipartite) matching** is a subset of edges of a graph where every vertex has degree at most 1.

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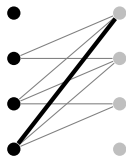
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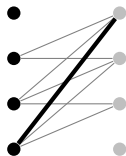


matching

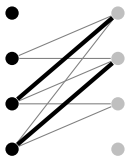
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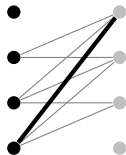


maximal matching

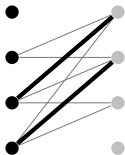
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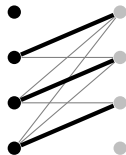
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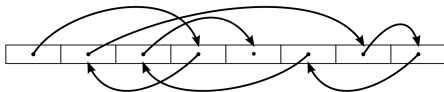
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Finding a maximum matching:

- exact algorithms exists, i.e. Hopcroft-Karp [SWAT71];
- require **random access** to the graph's edges (infeasible requirement for massive graphs).



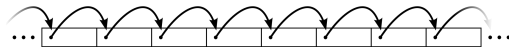


# Semi-Streaming Model

Feigenbaum et al. [ICALP04]

A graph with  $n$  vertices is presented to an algorithm as a stream of edges where the storage space of the algorithm is bounded by  $O(n \text{ polylog } n)$ .

- Only allows **sequential access** to the graph.
- Algorithms with space  $O(n \text{ polylog } n) = O(n (\log n)^{O(1)})$ .
- Ideally with few passes of the stream.



# Maximum Bipartite Matching Literature I

	Algorithmic	Lower Bound
one-pass	$\frac{1}{2}$ [folklore]	$\frac{1}{2} + 0.167$ [SODA12]
		$\frac{1}{2} + 0.132$ [SODA13]
		$\frac{1}{2} + 0.091$ [SODA21]
two-pass		$\frac{1}{2} + 0.019$ [APPROX12]
		$\frac{1}{2} + 0.083$ [ICDMW16]
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		$\frac{1}{2} + 0.085$ [MFCS18]

## Two-Pass Maximum Bipartite Matching

Class of algorithms:

- 1 finds a maximal matching  $M$  (first-pass);
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*Other strategies and techniques are required!*



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<sup>1</sup>where the first pass finds a maximal matching, i.e., at least a  $\frac{1}{2}$ -approximation.

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# Rusza Szemerédi Graphs

## Definition

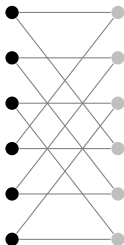
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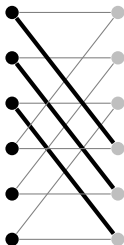
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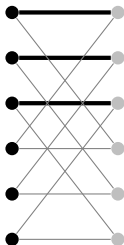
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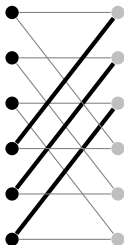
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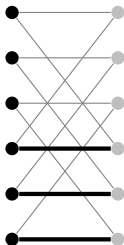
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## Proposition ([SODA12])

There exists a bipartite RS graph with  $N^{\Omega(\frac{1}{\log \log N})}$  induced matchings of size  $\frac{N}{2} - \epsilon N$  where  $N = |A| = |B|$  and  $\epsilon > 0$ .

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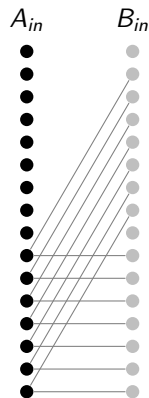
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**Note:** This is a dense RS graph with  $N^{1+\Omega(\frac{1}{\log \log N})} \supset O(N \text{ polylog } N)$  edges.

# One-Pass Lower Bound Proof [SODA12]

## Two-Party Communication Setup

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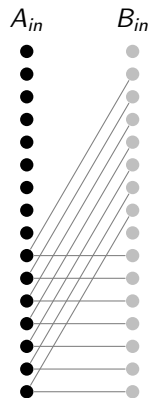




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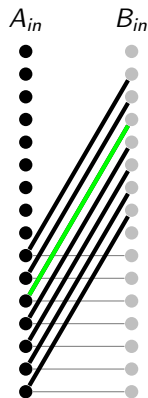
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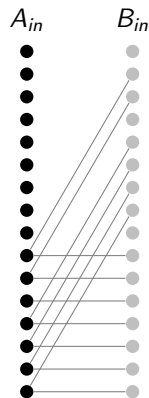
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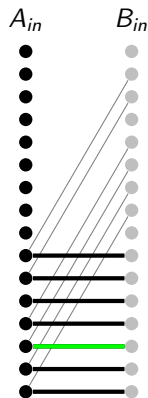
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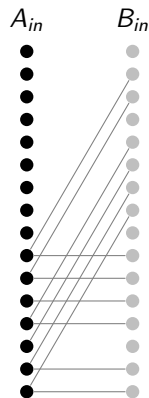
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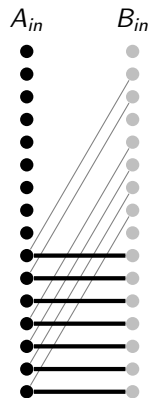
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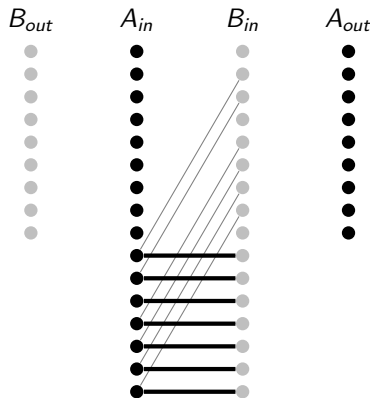
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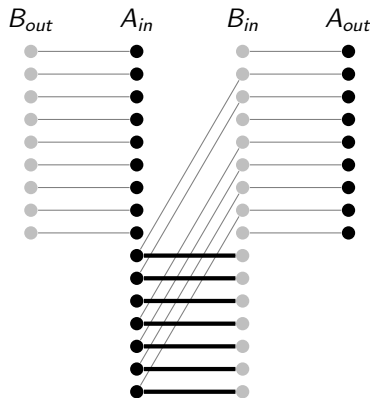
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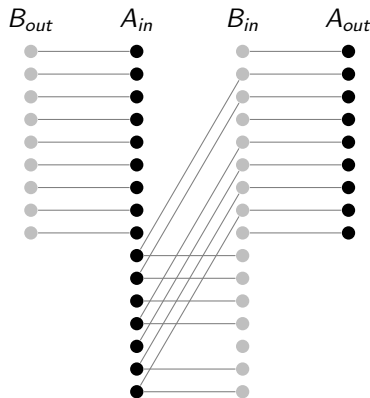
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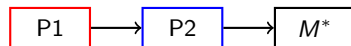
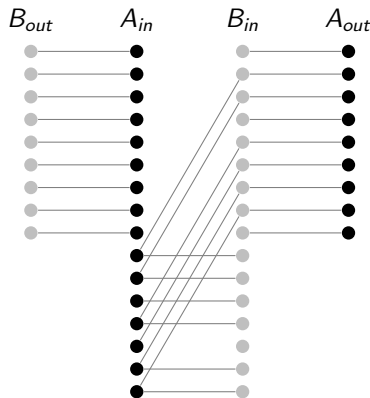
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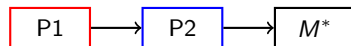
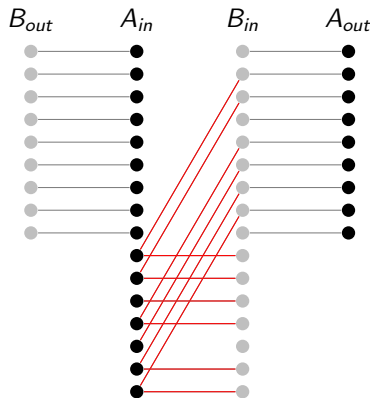
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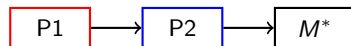
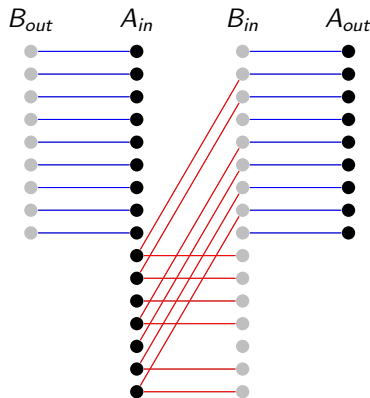
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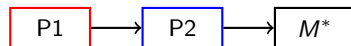
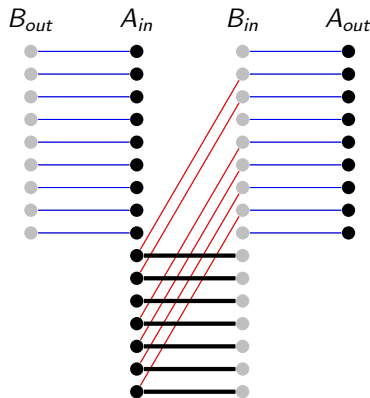
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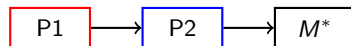
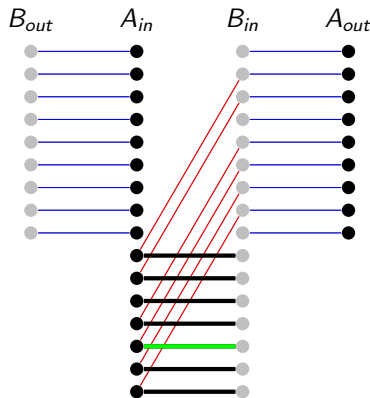
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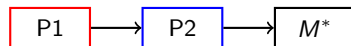
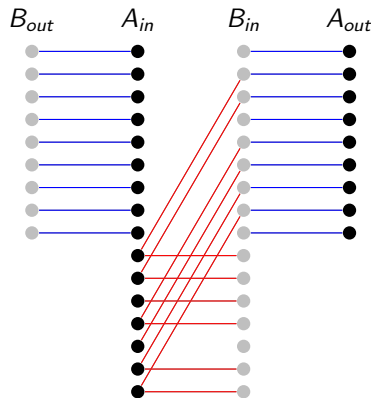
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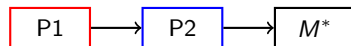
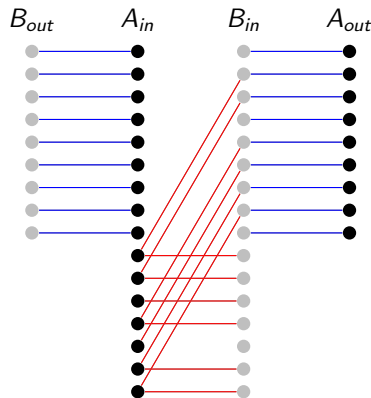
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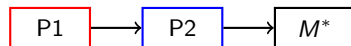
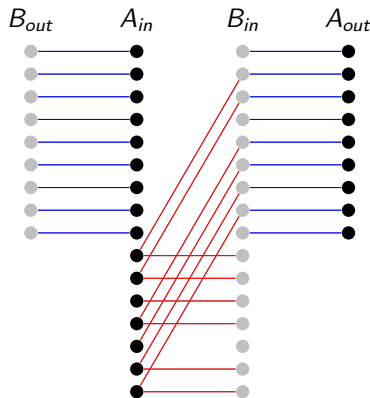




# One-Pass Lower Bound Proof [SODA12]

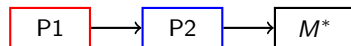
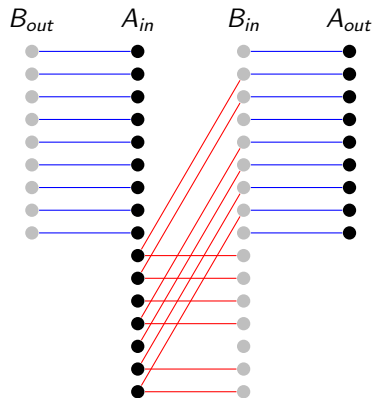
## Two-Party Communication Setup

- 1 Start with the dense RS graph with  $N^{\Omega(\frac{1}{\log \log N})}$  induced matchings of size  $\frac{N}{2} - \epsilon N$ .
- 2 Randomly remove  $\epsilon N$  edges from each induced matching.
- 3 Select a single special matching  $M_j$  at random.
- 4 Introduce two new sets of outer vertices each of size  $\frac{N}{2} + \epsilon N$  and connect to them to the non- $M_j$  inner vertices by a perfect matching.
- 5  $(\frac{2}{3} + \epsilon)$ -approx requires space  $N^{1+\Omega(\frac{1}{\log \log N})} \supset O(N \text{ polylog } N)$ .



# Two-Pass Lower Bound Proof

**Goal:** Give both players knowledge of a maximal matching without affecting the difficulty of the problem.

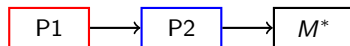
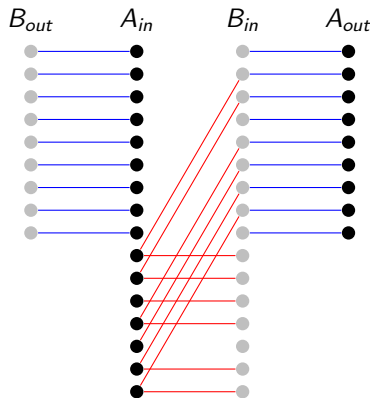


# Two-Pass Lower Bound Proof

**Goal:** Give both players knowledge of a maximal matching without affecting the difficulty of the problem.

**Outline:**

- Do dense RS graphs contain perfect matchings?



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diff

On

$B_{out}$

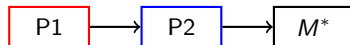
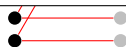
$A_{in}$

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## Proposition

There exists a bipartite RS graph with  $N^{\Omega(\frac{1}{\log \log N})}$  induced matchings of size  $\frac{N}{2} - \epsilon N$  where  $N = |A| = |B|$  and  $\epsilon > 0$  such that there are  $N^{\Omega(\frac{1}{\log \log N})}$  disjoint near-perfect matchings, each of size  $N - 2\epsilon N$ .

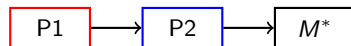
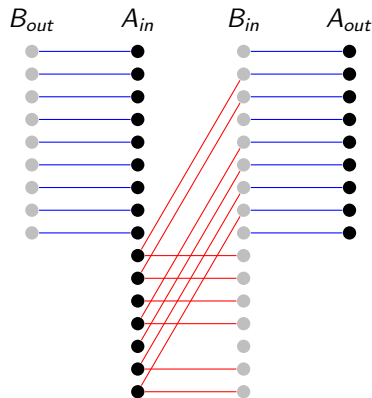


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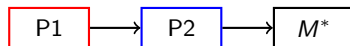
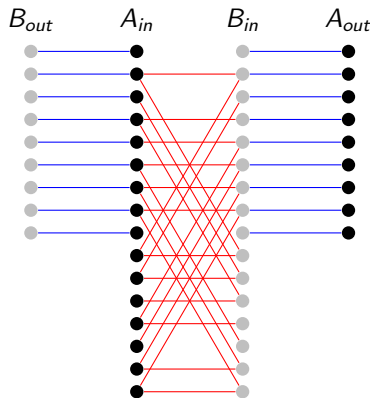


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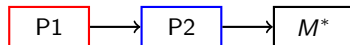
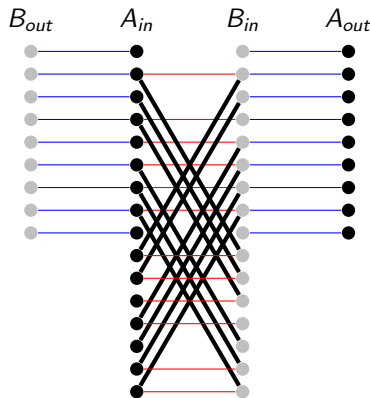


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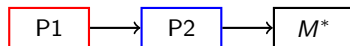
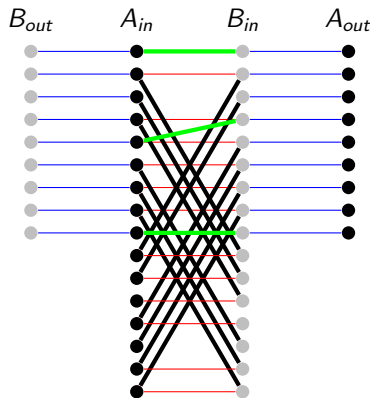


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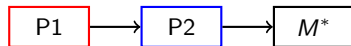
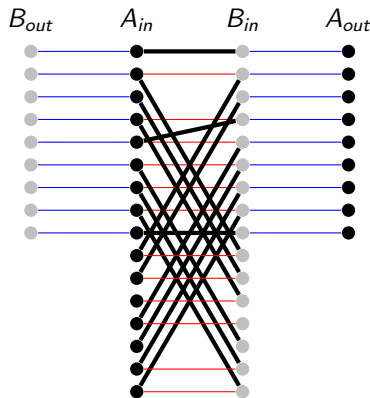


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# Overview

- 1 Background
- 2 Our Work
  - Lower Bound
  - Algorithmic
- 3 Discussion

## Two-Pass Maximum Bipartite Matching

### Algorithmic:

- Even a combination of the two dominant techniques in the area cannot beat the current state-of-the-art  $2 - \sqrt{2} \approx \frac{1}{2} + 0.085$ -approximation.

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- A family of hard-instance graphs shows the analysis is tight.

# Algorithmic Approach

Class of algorithms:

- 1 finds a maximal matching  $M$  (first-pass);
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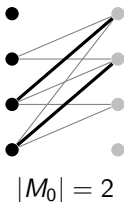
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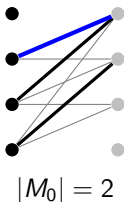
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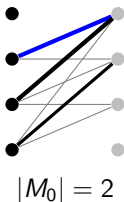
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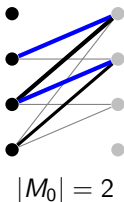
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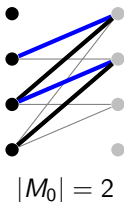
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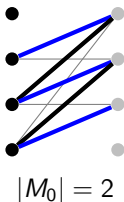
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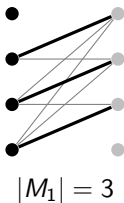
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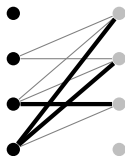
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# Two-Pass Algorithm Summary

Using the two dominant techniques, parameterised by  $p$  and  $d$ :

- 1 subsampling with probability  $p$  [APPROX12] [MFCS18]
- 2 run  $\text{GREEDY}_d$  [ICDMW16] [APPROX17]

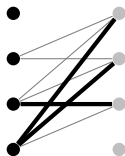


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semi-incomplete matching

Let  $G = (A, B, E)$  be any bipartite graph.

Let  $\pi = e_1, e_2, \dots$  be any stream of its edges.

**First pass:**

- $M \leftarrow \text{GREEDY}(\pi)$

**Second pass:**

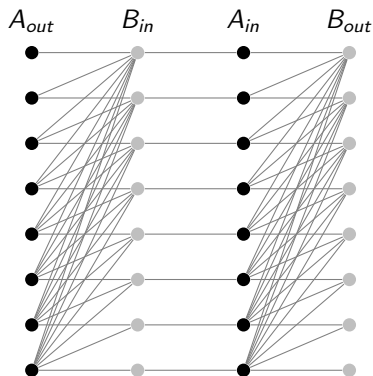
- subsample  $M' \subseteq M$  with prob.  $p$
- $H_L \leftarrow E \cap A_{\text{out}} \times B(M')$
- $H_R \leftarrow E \cap A(M') \times B_{\text{out}}$
- $M'_L \leftarrow \text{GREEDY}_d(\pi_{H_L})$
- $M'_R \leftarrow \text{GREEDY}_d(\pi_{H_R})$



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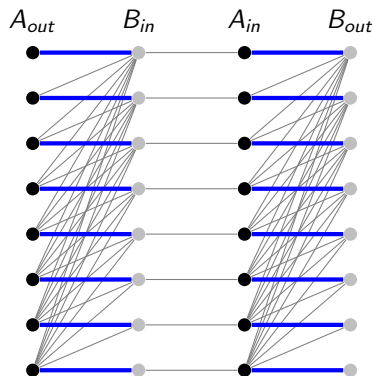


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The goal of the algorithm is to find the maximum matching  $M^*$ .



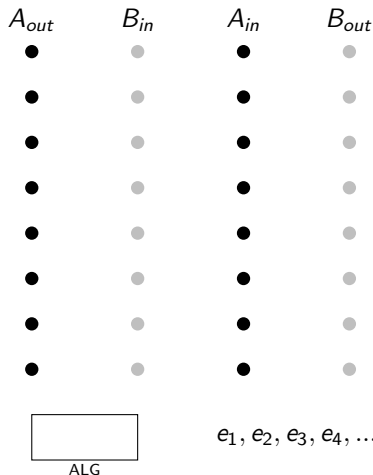
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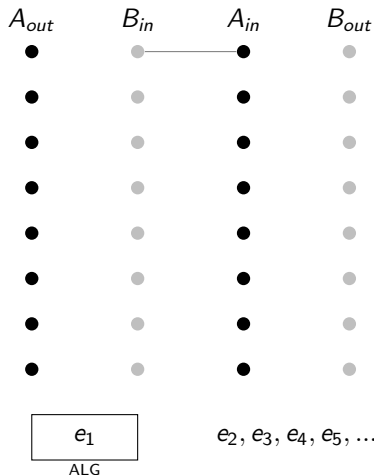
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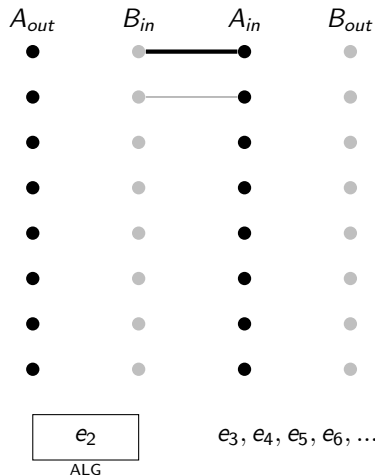
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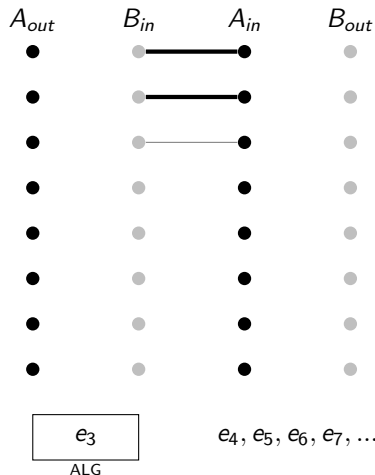
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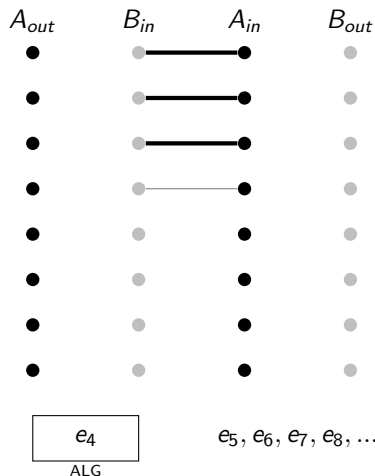
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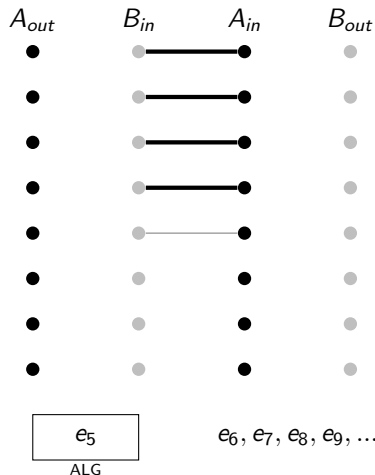
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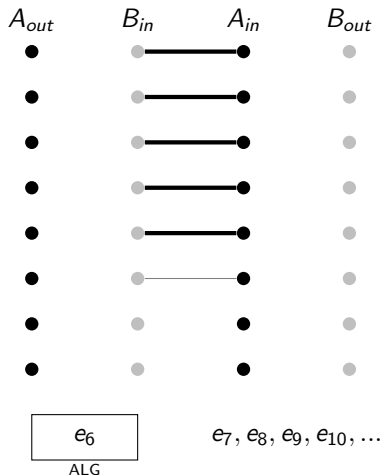
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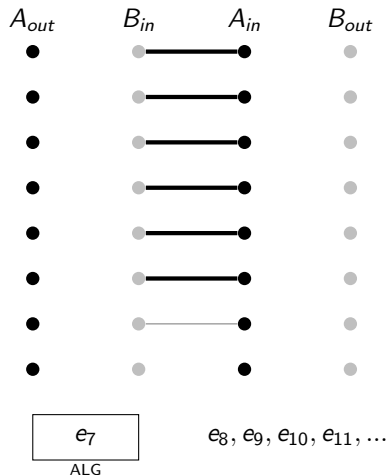
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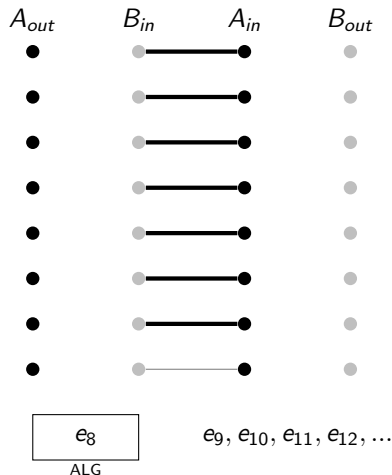
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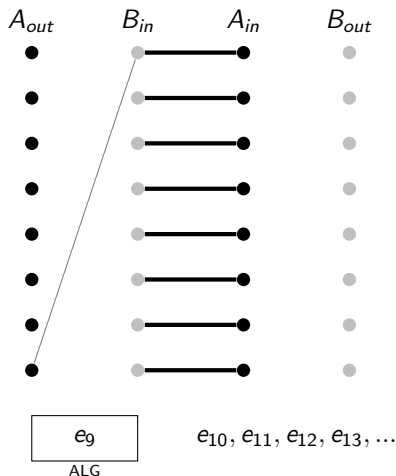
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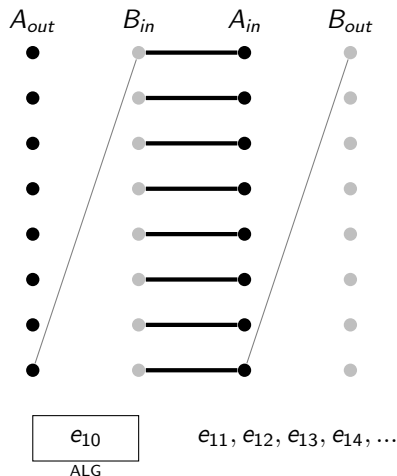
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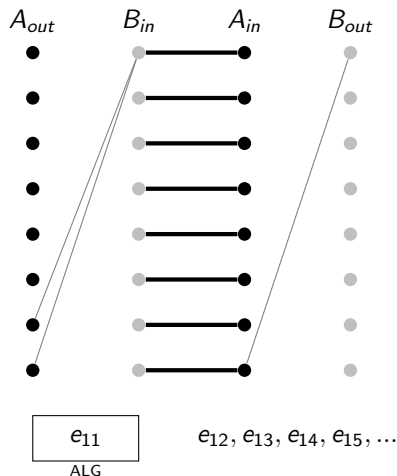
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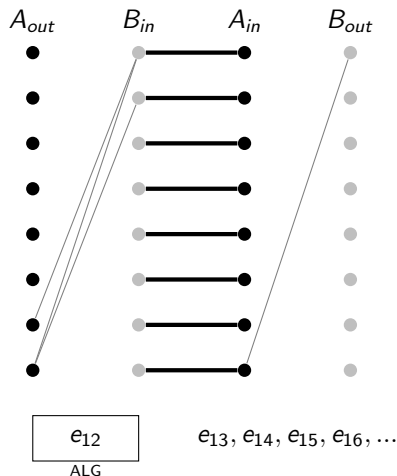
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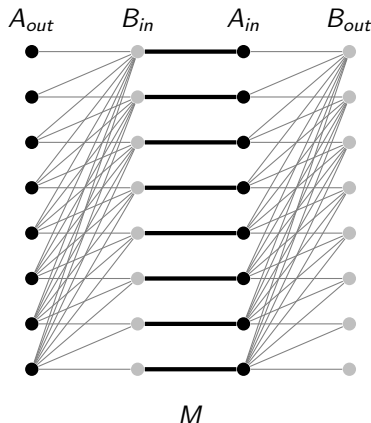
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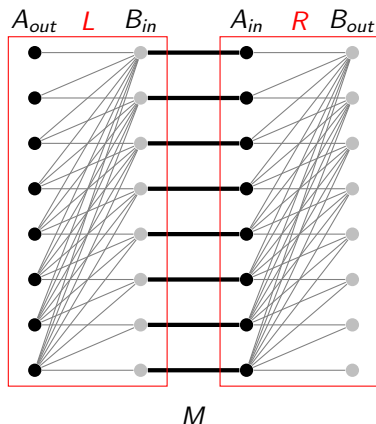
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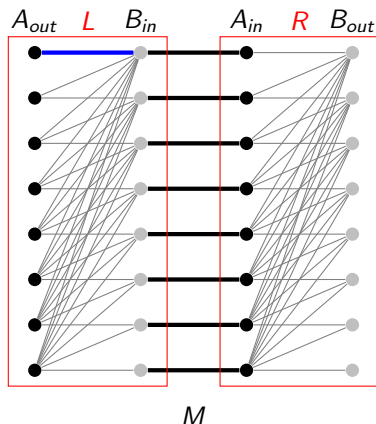
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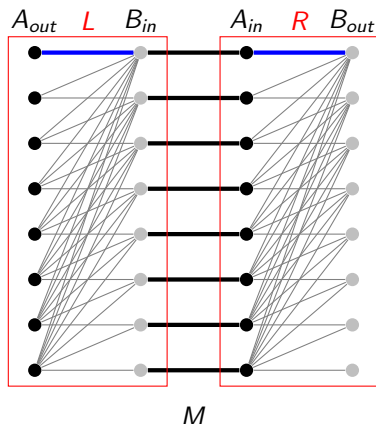
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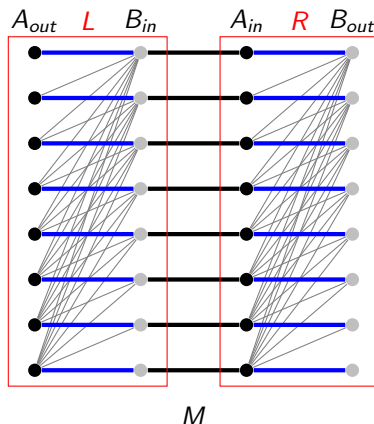
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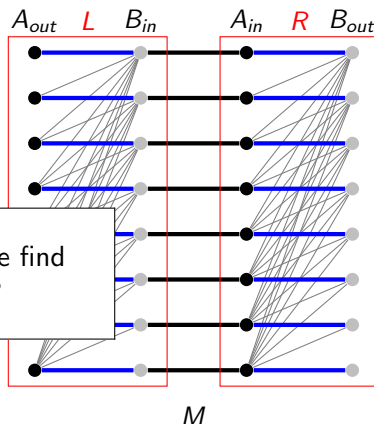
Let  $G = (A, B, E)$  be a hard-instance (worst-case) graph.

Let  $\pi = e_1, e_2, \dots$  be a stream of its edges in adversarial (worst-case) order.

**First pass:**

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How can we find these?



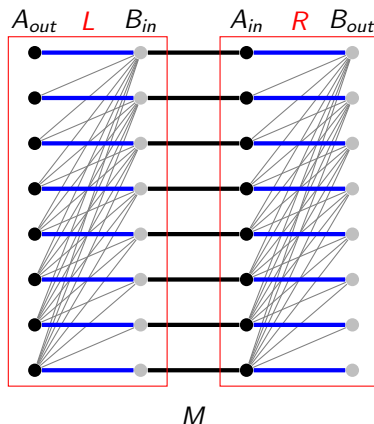
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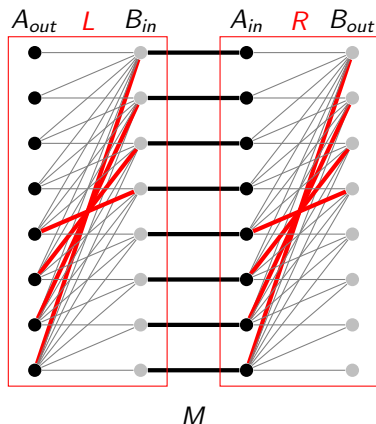
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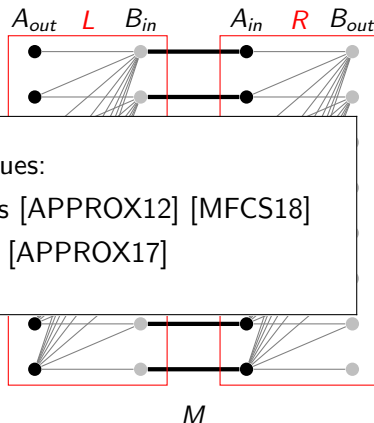
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First

Using the two dominant techniques:

- 1 subsample the inner vertices [APPROX12] [MFCS18]
- 2 run  $\text{GREEDY}_d$  [ICDMW16] [APPROX17]





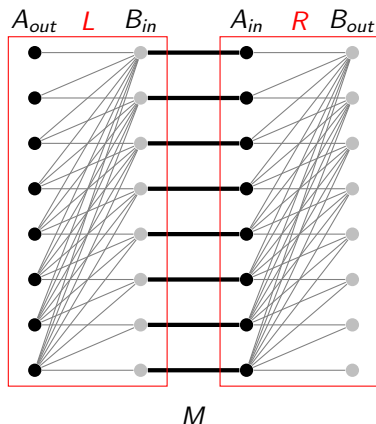
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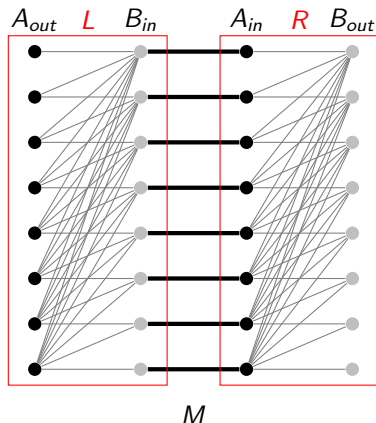
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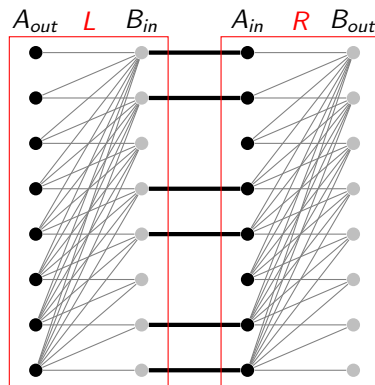
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**Second pass:**

- subsample  $M' \subseteq M$  with prob.  $p$



$M'$

$d = 3, p = 0.67$

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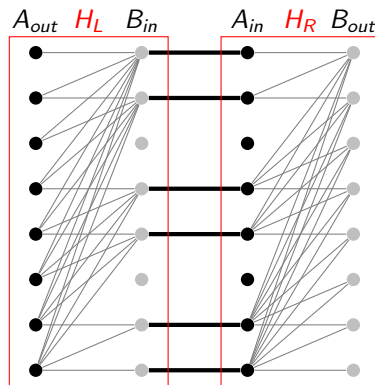
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**Second pass:**

- subsample  $M' \subseteq M$  with prob.  $p$
- $H_L \leftarrow E \cap A_{out} \times B(M')$
- $H_R \leftarrow E \cap A(M') \times B_{out}$



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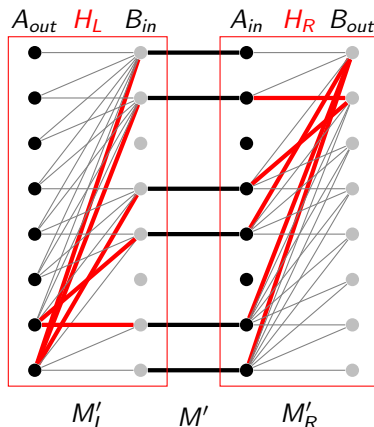
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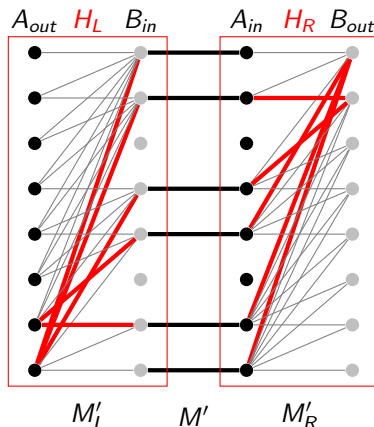
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$$\mathbb{E}_{M'}[|M'_L|] = \frac{dp}{d+p} \cdot |M_L^*|$$

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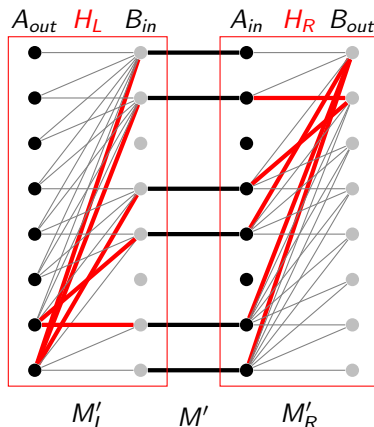
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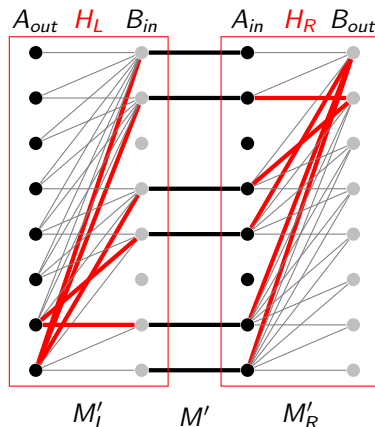
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# Two-Pass Algorithm

## Analysis



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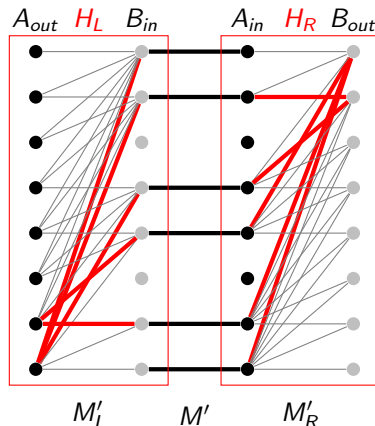
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# Two-Pass Algorithm

## Analysis

$$|\mathcal{Q}| = \left( \frac{p}{d+p} - \frac{p}{2d} \right) \cdot |M^*|.$$



$$d = 3, p = 0.67$$

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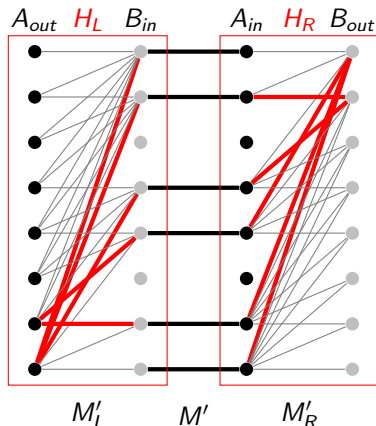
# Two-Pass Algorithm

## Analysis

$$|Q| = \left( \frac{p}{d+p} - \frac{p}{2d} \right) \cdot |M^*|.$$

Therefore, the final matching is of size

$$\left( \frac{1}{2} + \frac{p}{d+p} - \frac{p}{2d} \right) \cdot |M^*|.$$



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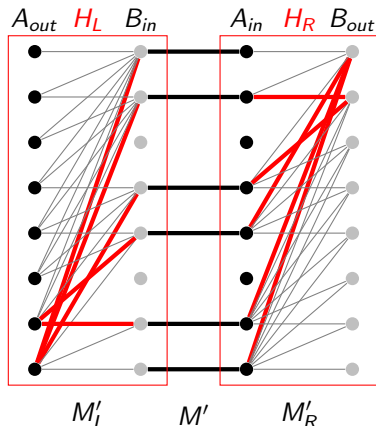
# Two-Pass Algorithm

## Analysis

$$|Q| \geq \left( \frac{p}{d+p} - \frac{p}{2d} \right) \cdot |M^*|.$$

Therefore, the final matching is of size *at least*

$$\left( \frac{1}{2} + \frac{p}{d+p} - \frac{p}{2d} \right) \cdot |M^*|.$$

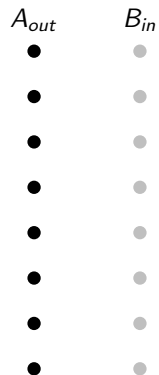


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$$\mathbb{E}_{M'}[|M'_L|] \geq \frac{dp}{d+p} \cdot |M_L^*|$$

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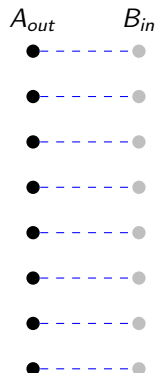
# Main Proof Outline



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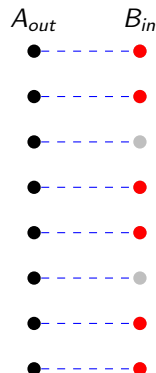
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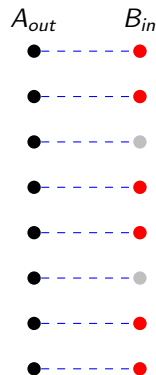


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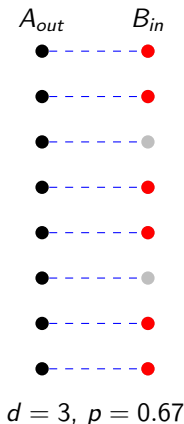
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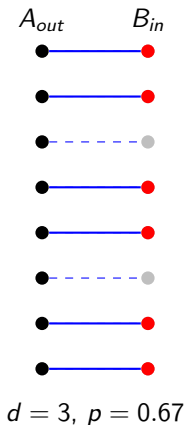
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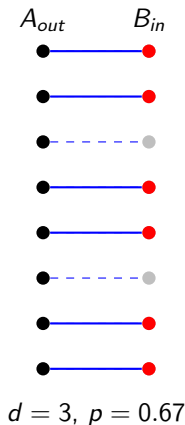
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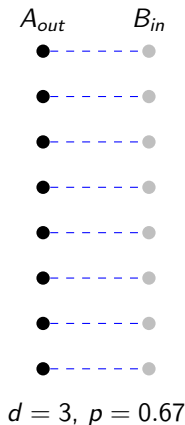
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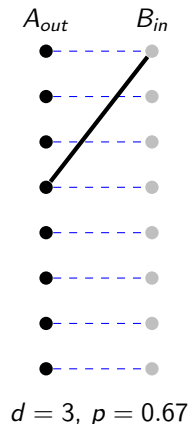
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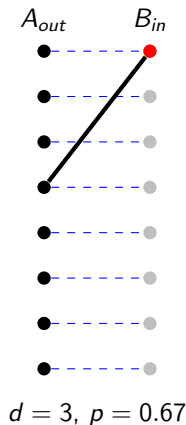
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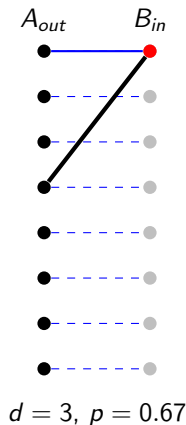
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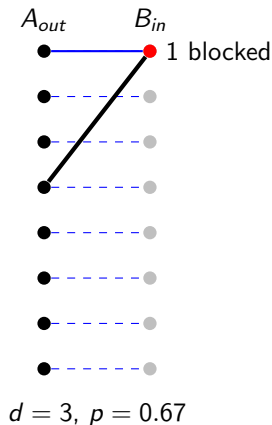
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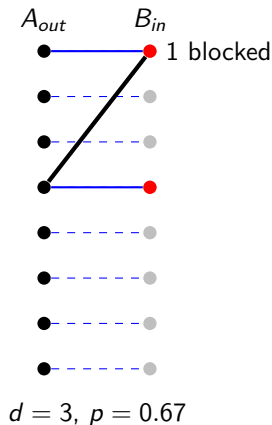
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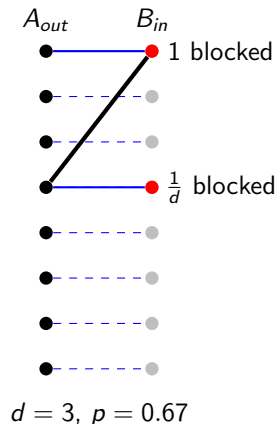
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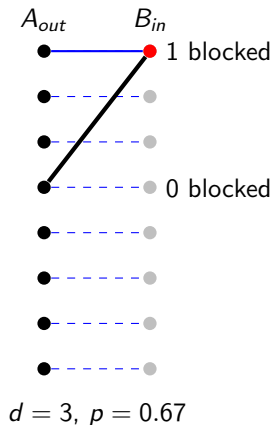
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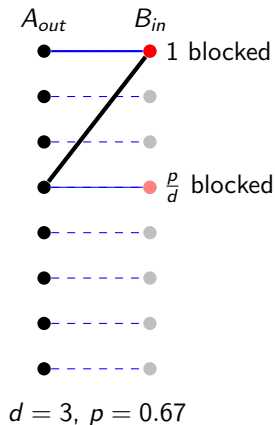
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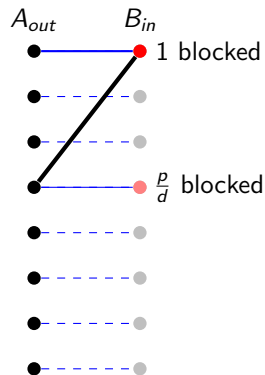
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$$\mathbb{E}[|M_{B'}^*|] \leq (1 + \frac{p}{d})\mathbb{E}[|M|]$$

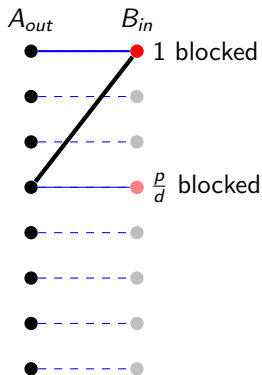
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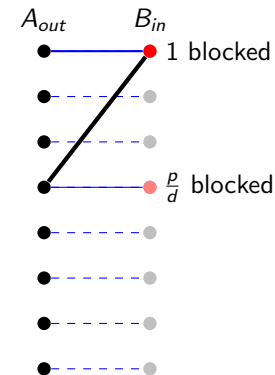
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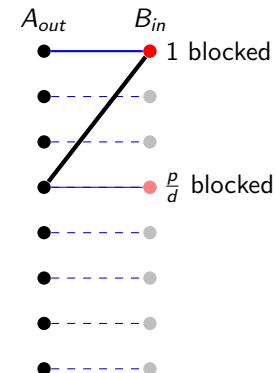
# Main Proof Outline

## Setup:

- any bipartite graph  $G = (A, B, E)$  with a maximum matching  $M^*$  and any stream of edges  $\pi$ ;
- subsample  $B' \subseteq B$  with prob.  $p$  to get  $H = G[A \cup B']$ ;
- $M \leftarrow \text{GREEDY}_d(\pi_H)$ .

## Proof:

- $M_{B'}^* \leftarrow \{ab \in M^* : b \in B'\}$ ;
- For every edge that is added by  $\text{GREEDY}_d$ , how many edges in  $M_{B'}^*$  are blocked?
- Formalised using Wald's Equation.



$$d = 3, p = 0.67$$

$$\mathbb{E}[|M|] \geq \frac{dp}{d+p} \cdot |M^*|$$

# Optimal Algorithms

The final matching returned is always at least of size

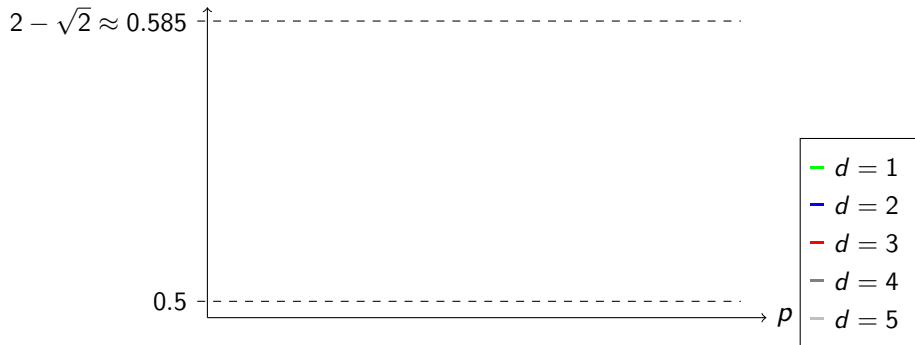
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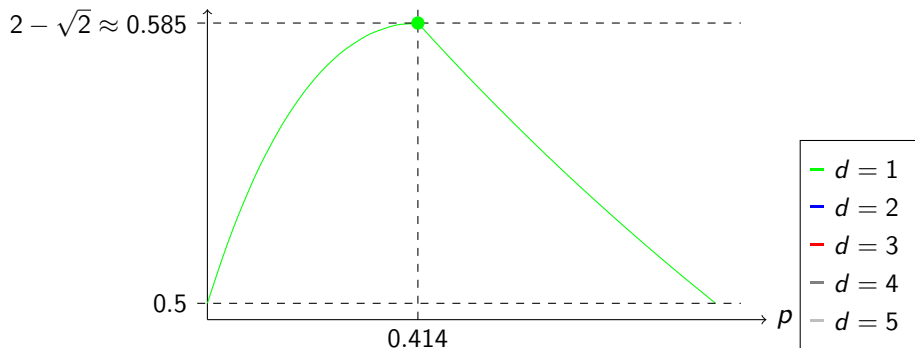
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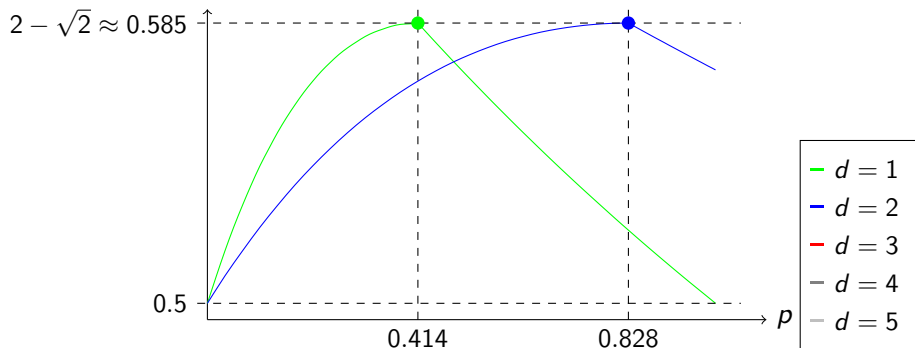
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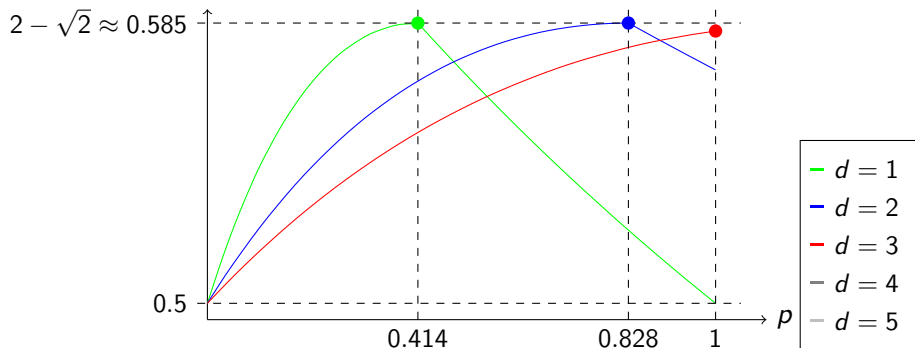
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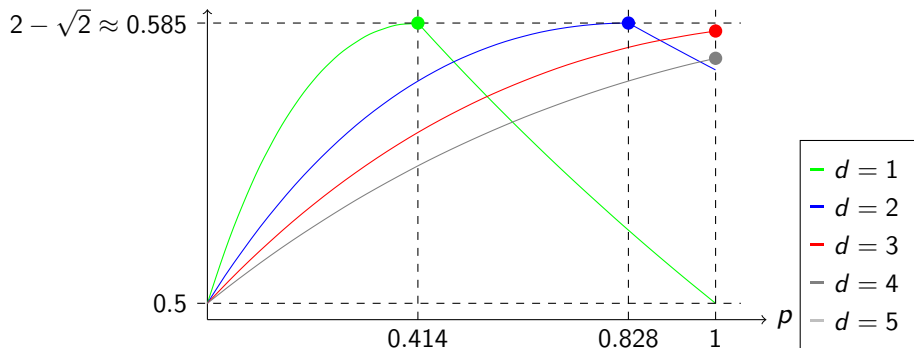
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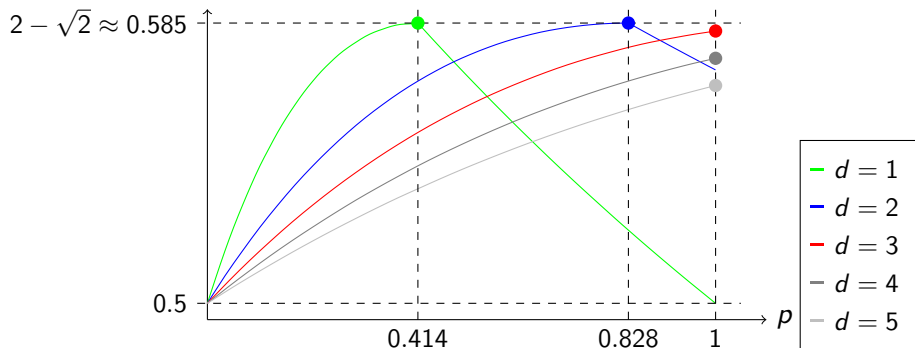
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# Overview

## 1 Background

## 2 Our Work

- Lower Bound
- Algorithmic

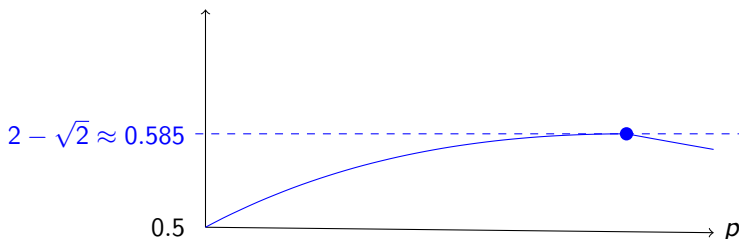
## 3 Discussion

# Conclusion



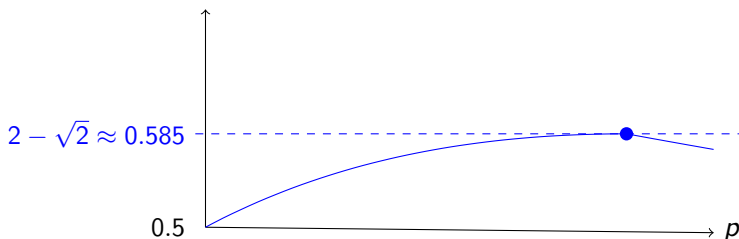
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- Our two-pass algorithm unifies the dominant techniques used, achieving the current state-of-the-art.



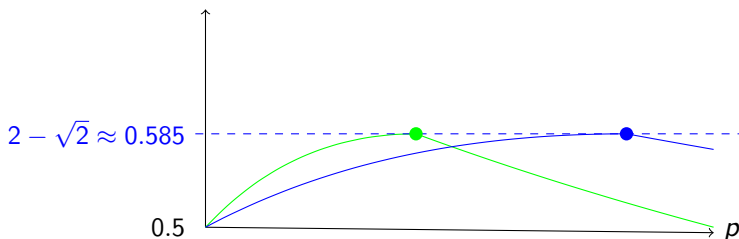
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- For appropriate settings of  $d$  and  $p$ , we can find Konrad's [MFCS18] and Esfandiari et al.'s [ICDMW16] algorithms.



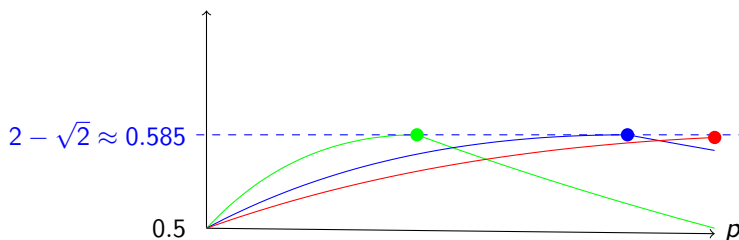
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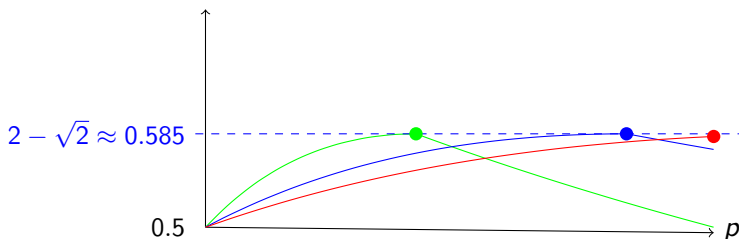
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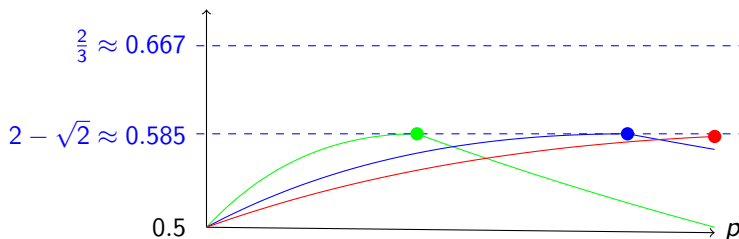
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- Our hard-instance family of graphs proves that the analysis is tight.
- We reduced the gap of possibility with this class of algorithms to  $[0.585, 0.667]$ .



# Open Questions

- Can we extend other one-pass lower bounds to improve the two-pass result? I.e. Kapralov's [SODA21].
- Is there a way to do better by finding more than just a maximal matching in the first-pass?
- Can we beat a  $\frac{1}{2}$ -approximation in just one-pass?

# Thank You