dog_app

April 30, 2020

1 Convolutional Neural Networks

1.1 Project: Write an Algorithm for a Dog Identification App

In this notebook, some template code has already been provided for you, and you will need to implement additional functionality to successfully complete this project. You will not need to modify the included code beyond what is requested. Sections that begin with '(IMPLEMENTATION)' in the header indicate that the following block of code will require additional functionality which you must provide. Instructions will be provided for each section, and the specifics of the implementation are marked in the code block with a 'TODO' statement. Please be sure to read the instructions carefully!

Note: Once you have completed all of the code implementations, you need to finalize your work by exporting the Jupyter Notebook as an HTML document. Before exporting the notebook to html, all of the code cells need to have been run so that reviewers can see the final implementation and output. You can then export the notebook by using the menu above and navigating to **File -> Download as -> HTML (.html)**. Include the finished document along with this notebook as your submission.

In addition to implementing code, there will be questions that you must answer which relate to the project and your implementation. Each section where you will answer a question is preceded by a 'Question X' header. Carefully read each question and provide thorough answers in the following text boxes that begin with 'Answer:'. Your project submission will be evaluated based on your answers to each of the questions and the implementation you provide.

Note: Code and Markdown cells can be executed using the **Shift + Enter** keyboard shortcut. Markdown cells can be edited by double-clicking the cell to enter edit mode.

The rubric contains *optional* "Stand Out Suggestions" for enhancing the project beyond the minimum requirements. If you decide to pursue the "Stand Out Suggestions", you should include the code in this Jupyter notebook.

Step 0: Import Datasets

Make sure that you've downloaded the required human and dog datasets:

Note: if you are using the Udacity workspace, you *DO NOT* need to re-download these - they can be found in the /data folder as noted in the cell below.

- Download the dog dataset. Unzip the folder and place it in this project's home directory, at the location /dog_images.
- Download the human dataset. Unzip the folder and place it in the home directory, at location /lfw.

Note: If you are using a Windows machine, you are encouraged to use 7zip to extract the folder. In the code cell below, we save the file paths for both the human (LFW) dataset and dog dataset in the numpy arrays human_files and dog_files.

Step 1: Detect Humans

In this section, we use OpenCV's implementation of Haar feature-based cascade classifiers to detect human faces in images.

OpenCV provides many pre-trained face detectors, stored as XML files on github. We have downloaded one of these detectors and stored it in the haarcascades directory. In the next code cell, we demonstrate how to use this detector to find human faces in a sample image.

```
In [2]: import cv2
    import matplotlib.pyplot as plt
    %matplotlib inline

# extract pre-trained face detector
    face_cascade = cv2.CascadeClassifier('haarcascades/haarcascade_frontalface_alt.xml')

# load color (BGR) image
    img = cv2.imread(human_files[50])# convert BGR image to grayscale
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# find faces in image
    faces = face_cascade.detectMultiScale(gray)

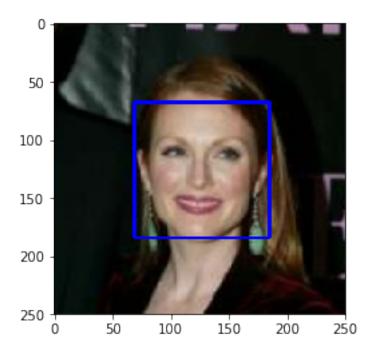
# print number of faces detected in the image
    print('Number of faces detected:', len(faces))
```

```
# get bounding box for each detected face
for (x,y,w,h) in faces:
    # add bounding box to color image
    cv2.rectangle(img,(x,y),(x+w,y+h),(255,0,0),2)

# convert BGR image to RGB for plotting
cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)

# display the image, along with bounding box
plt.imshow(cv_rgb)
plt.show()
```

Number of faces detected: 1



```
In [3]: img.shape
Out[3]: (250, 250, 3)
```

Before using any of the face detectors, it is standard procedure to convert the images to grayscale. The detectMultiScale function executes the classifier stored in face_cascade and takes the grayscale image as a parameter.

In the above code, faces is a numpy array of detected faces, where each row corresponds to a detected face. Each detected face is a 1D array with four entries that specifies the bounding box of the detected face. The first two entries in the array (extracted in the above code as x and y) specify the horizontal and vertical positions of the top left corner of the bounding box. The last two entries in the array (extracted here as w and h) specify the width and height of the box.

1.1.1 Write a Human Face Detector

We can use this procedure to write a function that returns True if a human face is detected in an image and False otherwise. This function, aptly named face_detector, takes a string-valued file path to an image as input and appears in the code block below.

```
In [4]: # returns "True" if face is detected in image stored at img_path
    def face_detector(img_path):
        img = cv2.imread(img_path)
        gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
        faces = face_cascade.detectMultiScale(gray)
        return len(faces) > 0
```

1.1.2 (IMPLEMENTATION) Assess the Human Face Detector

Question 1: Use the code cell below to test the performance of the face_detector function.

- What percentage of the first 100 images in human_files have a detected human face?
- What percentage of the first 100 images in dog_files have a detected human face?

Ideally, we would like 100% of human images with a detected face and 0% of dog images with a detected face. You will see that our algorithm falls short of this goal, but still gives acceptable performance. We extract the file paths for the first 100 images from each of the datasets and store them in the numpy arrays human_files_short and dog_files_short.

Answer: (You can print out your results and/or write your percentages in this cell)

```
In [4]: from tqdm import tqdm
        human_files_short = human_files[:100]
        dog_files_short = dog_files[:100]
        #-#-# Do NOT modify the code above this line. #-#-#
        ## TODO: Test the performance of the face_detector algorithm
        ## on the images in human_files_short and dog_files_short.
        def check_percent(image_file, detector):
            error = 0
            wrong_index = []
            for i, image in enumerate(image_file):
                if not detector(image):
                    wrong_index.append(i)
                    error += 1
                percent = (len(image_file)-error)/100
            return wrong_index, percent
        wrong_index, percent = check_percent(human_files_short, face_detector)
        print("Correct Percentage of first 100 imges, {:2.2%}".format(percent))
        print("Total wrong images:{}".format(len(wrong_index)))
        wrong_index, percent = check_percent(dog_files_short, face_detector)
        print("Correct Percentage of first 100 imges, {:2.2%}".format(percent))
        print("Total wrong images: {}".format(len(wrong_index)))
```

```
Correct Percentage of first 100 imges, 98.00%
Total wrong image are 2
Correct Percentage of first 100 imges, 17.00%
Total wrong image are 83
```

We suggest the face detector from OpenCV as a potential way to detect human images in your algorithm, but you are free to explore other approaches, especially approaches that make use of deep learning:). Please use the code cell below to design and test your own face detection algorithm. If you decide to pursue this *optional* task, report performance on human_files_short and dog_files_short.

Step 2: Detect Dogs

In this section, we use a pre-trained model to detect dogs in images.

1.1.3 Obtain Pre-trained VGG-16 Model

The code cell below downloads the VGG-16 model, along with weights that have been trained on ImageNet, a very large, very popular dataset used for image classification and other vision tasks. ImageNet contains over 10 million URLs, each linking to an image containing an object from one of 1000 categories.

```
In [5]: import torch
    import torchvision.models as models

# define VGG16 model
    VGG16 = models.vgg16(pretrained=True)

# check if CUDA is available
    use_cuda = torch.cuda.is_available()

# move model to GPU if CUDA is available
    if use_cuda:
        VGG16 = VGG16.cuda()
```

Downloading: "https://download.pytorch.org/models/vgg16-397923af.pth" to /root/.torch/models/vgg100%|| 553433881/553433881 [00:04<00:00, 117711373.88it/s]

Given an image, this pre-trained VGG-16 model returns a prediction (derived from the 1000 possible categories in ImageNet) for the object that is contained in the image.

1.1.4 (IMPLEMENTATION) Making Predictions with a Pre-trained Model

In the next code cell, you will write a function that accepts a path to an image (such as 'dogImages/train/001.Affenpinscher/Affenpinscher_00001.jpg') as input and returns the index corresponding to the ImageNet class that is predicted by the pre-trained VGG-16 model. The output should always be an integer between 0 and 999, inclusive.

Before writing the function, make sure that you take the time to learn how to appropriately pre-process tensors for pre-trained models in the PyTorch documentation.

```
In [6]: from PIL import Image
        import torchvision.transforms as transforms
        data_transform = transforms.Compose([transforms.RandomResizedCrop(224), transforms.ToTen
        def VGG16_predict(img_path):
            Use pre-trained VGG-16 model to obtain index corresponding to
            predicted ImageNet class for image at specified path
            Args:
                img_path: path to an image
            Returns:
                Index corresponding to VGG-16 model's prediction
            ## Load and pre-process an image from the given img_path
            ## Return the *index* of the predicted class for that image
            if img_path is None:
                return None
            pil_img = Image.open(img_path)
            img = data_transform(pil_img).unsqueeze_(0)
            output = VGG16(img)
            _, preds_tensor = torch.max(output,1)
            return preds_tensor.item() # predicted class index
In [7]: print(VGG16_predict(dog_files_short[3]))
243
```

1.1.5 (IMPLEMENTATION) Write a Dog Detector

While looking at the dictionary, you will notice that the categories corresponding to dogs appear in an uninterrupted sequence and correspond to dictionary keys 151-268, inclusive, to include all categories from 'Chihuahua' to 'Mexican hairless'. Thus, in order to check to see if an image is predicted to contain a dog by the pre-trained VGG-16 model, we need only check if the pre-trained model predicts an index between 151 and 268 (inclusive).

Use these ideas to complete the dog_detector function below, which returns True if a dog is detected in an image (and False if not).

```
## TODO: Complete the function.
pred = VGG16_predict(img_path)
if pred in range(151, 268):
    return True
    return False

In [45]: print(dog_detector(dog_files_short[3]))
False
```

1.1.6 (IMPLEMENTATION) Assess the Dog Detector

Question 2: Use the code cell below to test the performance of your dog_detector function.

- What percentage of the images in human_files_short have a detected dog?
- What percentage of the images in dog_files_short have a detected dog?Answer:

We suggest VGG-16 as a potential network to detect dog images in your algorithm, but you are free to explore other pre-trained networks (such as Inception-v3, ResNet-50, etc). Please use the code cell below to test other pre-trained PyTorch models. If you decide to pursue this *optional* task, report performance on human_files_short and dog_files_short.

```
In []: ### (Optional)
     ### TODO: Report the performance of another pre-trained network.
     ### Feel free to use as many code cells as needed.
```

Step 3: Create a CNN to Classify Dog Breeds (from Scratch)

Now that we have functions for detecting humans and dogs in images, we need a way to predict breed from images. In this step, you will create a CNN that classifies dog breeds. You must create your CNN *from scratch* (so, you can't use transfer learning *yet*!), and you must attain

a test accuracy of at least 10%. In Step 4 of this notebook, you will have the opportunity to use transfer learning to create a CNN that attains greatly improved accuracy.

We mention that the task of assigning breed to dogs from images is considered exceptionally challenging. To see why, consider that *even a human* would have trouble distinguishing between a Brittany and a Welsh Springer Spaniel.

```
Brittany Welsh Springer Spaniel
```

It is not difficult to find other dog breed pairs with minimal inter-class variation (for instance, Curly-Coated Retrievers and American Water Spaniels).

```
Curly-Coated Retriever American Water Spaniel
```

Likewise, recall that labradors come in yellow, chocolate, and black. Your vision-based algorithm will have to conquer this high intra-class variation to determine how to classify all of these different shades as the same breed.

```
Yellow Labrador Chocolate Labrador
```

We also mention that random chance presents an exceptionally low bar: setting aside the fact that the classes are slightly imabalanced, a random guess will provide a correct answer roughly 1 in 133 times, which corresponds to an accuracy of less than 1%.

Remember that the practice is far ahead of the theory in deep learning. Experiment with many different architectures, and trust your intuition. And, of course, have fun!

1.1.7 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dog_images/train, dog_images/valid, and dog_images/test, respectively). You may find this documentation on custom datasets to be a useful resource. If you are interested in augmenting your training and/or validation data, check out the wide variety of transforms!

```
In [5]: import os
    import torch
    import torchvision.models as models
    from torchvision import datasets, transforms

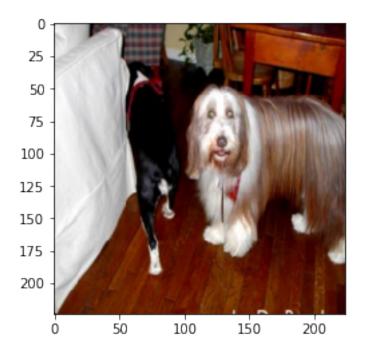
### TODO: Write data loaders for training, validation, and test sets
    ## Specify appropriate transforms, and batch_sizes
    num_workers = 0
    batch_size = 64
    data_dir = '/data/dog_images/'
```

```
valid_dir = os.path.join(data_dir, 'valid/')
        test_dir = os.path.join(data_dir, 'test/')
        rgb_3channel_normalization = transforms.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229]
        train_data_transform = transforms.Compose([
            transforms.Resize(size=(256,256)),
            transforms.RandomResizedCrop(224),
            transforms RandomHorizontalFlip(),
            transforms.RandomRotation(15),
            transforms.ToTensor(),
            rgb_3channel_normalization])
        valid_test_data_transform = transforms.Compose([
            transforms.Resize(size=(256,256)),
            transforms.CenterCrop(224),
            transforms.ToTensor(),
            rgb_3channel_normalization])
        train_data = datasets.ImageFolder(train_dir, transform=train_data_transform)
        valid_data = datasets.ImageFolder(valid_dir, transform=valid_test_data_transform)
        test_data = datasets.ImageFolder(test_dir, transform=valid_test_data_transform)
        print("Number of train_data: {}".format(len(train_data)))
        print("Number of valid_data: {}".format(len(valid_data)))
        print("Number of test_data: {}".format(len(test_data)))
        train_loader = torch.utils.data.DataLoader(train_data, batch_size=batch_size,num_workers
        valid_loader = torch.utils.data.DataLoader(valid_data, batch_size=batch_size,num_workers
        test_loader = torch.utils.data.DataLoader(test_data, batch_size=batch_size,num_workers=m
        print("Number of dog_breed: {}".format(len(train_data.classes)))
        loaders_scratch = {
            'train': train_loader,
            'valid': valid_loader,
            'test': test_loader
        }
Number of train_data: 6680
Number of valid_data: 835
Number of test_data: 836
Number of dog_breed: 133
In [6]: import matplotlib.pyplot as plt
        import numpy as np
        %matplotlib inline
        def un_normalize(tensors, mean, std):
            for tensor in tensors:
```

train_dir = os.path.join(data_dir, 'train/')

```
mean=[0.485, 0.456, 0.406]
std=[0.229, 0.224, 0.225]
dataiter = iter(test_loader)
images, label = dataiter.next()
images, label = dataiter.next()
images = un_normalize(images, mean, std)
images.numpy()
plt.imshow(np.transpose(images, (1,2,0)))
```

Out[6]: <matplotlib.image.AxesImage at 0x7f0985a1def0>



```
In [15]: images, label = dataiter.next()
In [16]: images.shape
Out[16]: torch.Size([64, 3, 224, 224])
```

Question 3: Describe your chosen procedure for preprocessing the data. - How does your code resize the images (by cropping, stretching, etc)? What size did you pick for the input tensor, and why? - Did you decide to augment the dataset? If so, how (through translations, flips, rotations, etc)? If not, why not?

Answer: I use Resize, RandomResizedCrop for resizing for train data and choose 256 for input tensor because I torchvision model prefer 256 or 244 as an input. RandomHorizontalFlip and RandomRotation for augmenting. I use data augmenting only in traindata to prevent the overfitting the data during training.

Same data transform for valid and test and both using only resize and normalize.

1.1.8 (IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. Use the template in the code cell below.

```
In [6]: from PIL import ImageFile
        ImageFile.LOAD_TRUNCATED_IMAGES = True
        classess = len(train data.classes)
        use_cuda = torch.cuda.is_available()
In [7]: import torch.nn as nn
        import torch.nn.functional as F
        import numpy as np
        # define the CNN architecture
        class Net(nn.Module):
            ### TODO: choose an architecture, and complete the class
            def __init__(self):
                super(Net, self).__init__()
                self.conv1 = nn.Conv2d(3, 32, 3,stride=2,padding=1)
                self.conv2 = nn.Conv2d(32, 64, 3,stride=2,padding=1)
                self.conv3 = nn.Conv2d(64, 128, 3,padding=1)
                self.pool = nn.MaxPool2d(2,2)
                self.fc1 = nn.Linear(128 * 7 * 7, 1000)
                self.fc2 = nn.Linear(1000, classess)
                self.dropout = nn.Dropout(0.25)
            def forward(self, x):
                x = self.pool(F.relu(self.conv1(x)))
                x = self.pool(F.relu(self.conv2(x)))
                x = self.pool(F.relu(self.conv3(x)))
                x = x.view(-1, 128 * 7 * 7)
                x = self.dropout(x)
                x = F.relu(self.fc1(x))
                x = self.dropout(x)
                x = self.fc2(x)
                return x
        #-#-# You so NOT have to modify the code below this line. #-#-#
        # instantiate the CNN
        model scratch = Net()
        # move tensors to GPU if CUDA is available
```

Question 4: Outline the steps you took to get to your final CNN architecture and your reasoning at each step.

Answer:

firstly I try with 5 conv layers but after spending 1 around one hours of training the validation loss still over 4.0 and test loss lower than 10% Then I change the dropout value, learning rate, stride etc. but test loss is lower than 10%. After that, I change to 3 conv layer for better speed and testing for training data. After Adjusting fc1 out_feature start from 500 , 800, 1000 and adjusting fc1 in feature by changing stride and padding. only fc1 out_feature=1000's result have got over 10% of test loss. I don't still clearly understand why it like this.

In my current answers, I use 2 fully conneted layer for output 133 classes. As conv layer, I use 3 layers. Actally, I test serveral time with the following code but can't get the validloss less than 4.0.

```
self.conv1 = nn.Conv2d(3, 64, 3,stride=2,padding=1)
self.conv2 = nn.Conv2d(64, 128, 3,stride=2,padding=1)
self.conv3 = nn.Conv2d(128, 256, 3) ```
Then I adjusting server time, by output channel but valid test over 4.0 and testloss lower than
I thought conv1 with 64 may be affect the results, so , I reduce it to 16 but still valid test of
This is the last one that I try with test loss lower than 10%. :(
```

(conv1): Conv2d(3, 32, kernel_size=(3, 3), stride=(2, 2), padding=(1, 1)) with relu activation and pooling (conv2): Conv2d(32, 64, kernel_size=(3, 3), stride=(2, 2), padding=(1, 1)) with relu activation and pooling (conv3): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1)) with relu activation and pooling "'

pooling layer is 2,2 with stride 2 (pool): MaxPool2d(kernel_size=2, stride=2,
padding=0, dilation=1, ceil_mode=False)

conv3 out channel is 128 and muliply by 3 time pooling with stride and padding -> 7 * 7 before going from conv to fully connected layer flatten the input Then drop out with 0.25 fc1 in feature is $6272 \le (128 * 7 * 7)$ and out feature set to 1000.(I add with 800 and 500 too, not

work well in result) (fc1): Linear(in_features=6272, out_features=1000, bias=True) relu activation apply to fc1 and apply drop out again. fc2 in feature with 1000 and out feature set to 133 (total number of training data class) (fc2): Linear(in_features=1000, out_features=133, bias=True) then return the fc2 result

1.1.9 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion_scratch, and the optimizer as optimizer_scratch below.

```
In [9]: import torch.optim as optim
    ### TODO: select loss function
    criterion_scratch = nn.CrossEntropyLoss()

### TODO: select optimizer
    optimizer_scratch = optim.SGD(model_scratch.parameters(), lr=0.1)
```

1.1.10 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model_scratch.pt'.

```
In [10]: def train(n_epochs, loaders, model, optimizer, criterion, use_cuda, save_path):
             """returns trained model"""
             # initialize tracker for minimum validation loss
             valid_loss_min = np.Inf
             for epoch in range(1, n_epochs+1):
                 # initialize variables to monitor training and validation loss
                 train_loss = 0.0
                 valid_loss = 0.0
                 ##################
                 # train the model #
                 ##################
                 model.train()
                 for batch_idx, (data, target) in enumerate(loaders['train']):
                     # move to GPU
                     if use_cuda:
                         data, target = data.cuda(), target.cuda()
                     ## find the loss and update the model parameters accordingly
                     ## record the average training loss, using something like
                     \#\# train_loss = train_loss + ((1 / (batch_idx + 1)) * (loss.data - train_loss)
                     optimizer.zero_grad()
                     output = model(data)
                     loss = criterion(output, target)
                     loss.backward()
```

optimizer.step()

```
#####################
                 # validate the model #
                 ########################
                 model.eval()
                 for batch_idx, (data, target) in enumerate(loaders['valid']):
                     # move to GPU
                     if use cuda:
                         data, target = data.cuda(), target.cuda()
                     ## update the average validation loss
                     output = model(data)
                     loss = criterion(output, target)
                     valid_loss = valid_loss + ((1 / (batch_idx + 1)) * (loss.data - valid_loss)
                 # print training/validation statistics
                 print('Epoch: {} \tTraining Loss: {:.6f} \tValidation Loss: {:.6f}'.format(
                     epoch,
                     train_loss,
                     valid_loss
                     ))
                 ## TODO: save the model if validation loss has decreased
                 if valid_loss < valid_loss_min:</pre>
                     print('Validation loss decreased ({:.6f} --> {:.6f}). Saving Model .....'.
                     torch.save(model.state_dict(), save_path)
                     valid_loss_min = valid_loss
             # return trained model
             return model
         # train the model
         model_scratch = train(20, loaders_scratch, model_scratch, optimizer_scratch,
                               criterion_scratch, use_cuda, 'model_scratch.pt')
         # load the model that got the best validation accuracy
         model_scratch.load_state_dict(torch.load('model_scratch.pt'))
Epoch: 1
                 Training Loss: 4.343825
                                                  Validation Loss: 4.269917
Validation loss decreased (inf --> 4.269917). Saving Model ...
                 Training Loss: 4.300910
                                                  Validation Loss: 4.638744
Epoch: 2
Epoch: 3
                 Training Loss: 4.259300
                                                 Validation Loss: 4.325048
Epoch: 4
                 Training Loss: 4.209668
                                                 Validation Loss: 4.400743
Epoch: 5
                 Training Loss: 4.181178
                                                  Validation Loss: 4.077090
Validation loss decreased (4.269917 --> 4.077090). Saving Model ...
Epoch: 6
                 Training Loss: 4.117984
                                                 Validation Loss: 4.304009
                                                 Validation Loss: 4.154131
Epoch: 7
                 Training Loss: 4.084085
                                                  Validation Loss: 4.072368
Epoch: 8
                 Training Loss: 4.058943
Validation loss decreased (4.077090 --> 4.072368). Saving Model ...
```

train_loss = train_loss + ((1 / (batch_idx + 1)) * (loss.data - train_loss)

```
Validation Loss: 4.033435
Epoch: 9
                 Training Loss: 4.022753
Validation loss decreased (4.072368 --> 4.033435). Saving Model ...
                  Training Loss: 3.978204
                                                  Validation Loss: 4.081304
Epoch: 10
                  Training Loss: 3.894932
                                                  Validation Loss: 3.998673
Epoch: 11
Validation loss decreased (4.033435 --> 3.998673). Saving Model ...
                  Training Loss: 3.903075
                                                  Validation Loss: 3.975646
Epoch: 12
Validation loss decreased (3.998673 --> 3.975646). Saving Model ...
Epoch: 13
                  Training Loss: 3.857222
                                                  Validation Loss: 3.928222
Validation loss decreased (3.975646 --> 3.928222). Saving Model ...
Epoch: 14
                  Training Loss: 3.825777
                                                  Validation Loss: 3.811271
Validation loss decreased (3.928222 --> 3.811271). Saving Model ...
Epoch: 15
                  Training Loss: 3.761439
                                                  Validation Loss: 3.978296
                                                  Validation Loss: 3.988136
                  Training Loss: 3.738445
Epoch: 16
Epoch: 17
                  Training Loss: 3.678489
                                                  Validation Loss: 4.048996
Epoch: 18
                  Training Loss: 3.684090
                                                  Validation Loss: 4.761930
                  Training Loss: 3.629445
                                                  Validation Loss: 3.904406
Epoch: 19
Epoch: 20
                  Training Loss: 3.600253
                                                  Validation Loss: 3.852485
In [1]: !ls
dog_app-cn.ipynb haarcascades
                                      model_scratch.pt
dog_app.ipynb
                       images
                                     README.md
In [10]: model_scratch.load_state_dict(torch.load('model_scratch.pt'))
```

1.1.11 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 10%.

```
In [11]: def test(loaders, model, criterion, use_cuda):
    # monitor test loss and accuracy
    test_loss = 0.
    correct = 0.
    total = 0.

model.eval()
    for batch_idx, (data, target) in enumerate(loaders['test']):
        # move to GPU
        if use_cuda:
            data, target = data.cuda(), target.cuda()
            # forward pass: compute predicted outputs by passing inputs to the model output = model(data)
            # calculate the loss
            loss = criterion(output, target)
            # update average test loss
```

```
test_loss = test_loss + ((1 / (batch_idx + 1)) * (loss.data - test_loss))
    # convert output probabilities to predicted class
    pred = output.data.max(1, keepdim=True)[1]
    # compare predictions to true label
    correct += np.sum(np.squeeze(pred.eq(target.data.view_as(pred))).cpu().numpy())
    total += data.size(0)

print('Test Loss: {:.6f}\n'.format(test_loss))

print('\nTest Accuracy: %2d% (%2d/%2d)' % (
    100. * correct / total, correct, total))

# call test function
    test(loaders_scratch, model_scratch, criterion_scratch, use_cuda)

Test Loss: 3.756151

Test Accuracy: 13% (113/836)
```

Step 4: Create a CNN to Classify Dog Breeds (using Transfer Learning)
You will now use transfer learning to create a CNN that can identify dog breed from

You will now use transfer learning to create a CNN that can identify dog breed from images. Your CNN must attain at least 60% accuracy on the test set.

1.1.12 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dogImages/train, dogImages/valid, and dogImages/test, respectively).

If you like, **you are welcome to use the same data loaders from the previous step**, when you created a CNN from scratch.

```
In [3]: ## TODO: Specify data loaders
    import os
    import torch
    import torchvision.models as models
    from torchvision import datasets, transforms

num_workers = 0
batch_size = 64
data_dir = '/data/dog_images/'
train_dir = os.path.join(data_dir, 'train/')
valid_dir = os.path.join(data_dir, 'valid/')
test_dir = os.path.join(data_dir, 'test/')
rgb_3channel_normalization = transforms.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229]
```

```
train_data_transform = transforms.Compose([
            transforms.Resize(size=(224,224)),
            transforms.RandomResizedCrop(224),
            transforms.RandomHorizontalFlip(),
            transforms.RandomRotation(15),
            transforms.ToTensor(),
            rgb_3channel_normalization])
        valid_test_data_transform = transforms.Compose([
            transforms.Resize(size=(224,224)),
            transforms.CenterCrop(224),
            transforms.ToTensor(),
            rgb_3channel_normalization])
        train_data = datasets.ImageFolder(train_dir, transform=train_data_transform)
        valid_data = datasets.ImageFolder(valid_dir, transform=valid_test_data_transform)
        test_data = datasets.ImageFolder(test_dir, transform=valid_test_data_transform)
        print("Number of train_data: {}".format(len(train_data)))
        print("Number of valid_data: {}".format(len(valid_data)))
        print("Number of test_data: {}".format(len(test_data)))
        train_loader = torch.utils.data.DataLoader(train_data, batch_size=batch_size,num_workers
        valid_loader = torch.utils.data.DataLoader(valid_data, batch_size=batch_size,num_workers
        test_loader = torch.utils.data.DataLoader(test_data, batch_size=batch_size,num_workers=n
        print("Number of dog_breed: {}".format(len(train_data.classes)))
        loaders_transfer = {
            'train': train_loader,
            'valid': valid_loader,
            'test': test_loader
        }
Number of train_data: 6680
Number of valid data: 835
Number of test_data: 836
Number of dog_breed: 133
In [4]: dataiter = iter(test_loader)
        images, label = dataiter.next()
        images.shape
Out[4]: torch.Size([64, 3, 224, 224])
```

1.1.13 (IMPLEMENTATION) Model Architecture

Use transfer learning to create a CNN to classify dog breed. Use the code cell below, and save your initialized model as the variable model_transfer.

```
In [5]: import torchvision.models as models
        import torch.nn as nn
        last_output= len(train_data.classes)
        model_transfer = models.vgg19(pretrained=True)
        for param in model_transfer.features.parameters():
            param.requires_grad = False
        n_input = model_transfer.classifier[6].in_features
        last_layer = nn.Linear(n_input,last_output)
        model_transfer.classifier[6] = last_layer
        use_cuda = torch.cuda.is_available()
        if use cuda:
            model_transfer = model_transfer.cuda()
        model_transfer
Downloading: "https://download.pytorch.org/models/vgg19-dcbb9e9d.pth" to /root/.torch/models/vgg
100%|| 574673361/574673361 [00:06<00:00, 95107944.32it/s]
Out[5]: VGG(
          (features): Sequential(
            (0): Conv2d(3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (1): ReLU(inplace)
            (2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (3): ReLU(inplace)
            (4): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
            (5): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (6): ReLU(inplace)
            (7): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (8): ReLU(inplace)
            (9): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
            (10): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (11): ReLU(inplace)
            (12): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (13): ReLU(inplace)
            (14): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (15): ReLU(inplace)
            (16): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (17): ReLU(inplace)
            (18): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
            (19): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (20): ReLU(inplace)
            (21): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (22): ReLU(inplace)
            (23): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (24): ReLU(inplace)
            (25): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
```

```
(26): ReLU(inplace)
    (27): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (28): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (29): ReLU(inplace)
    (30): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (31): ReLU(inplace)
    (32): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (33): ReLU(inplace)
    (34): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (35): ReLU(inplace)
    (36): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (classifier): Sequential(
    (0): Linear(in_features=25088, out_features=4096, bias=True)
    (1): ReLU(inplace)
    (2): Dropout(p=0.5)
    (3): Linear(in_features=4096, out_features=4096, bias=True)
    (4): ReLU(inplace)
    (5): Dropout(p=0.5)
    (6): Linear(in_features=4096, out_features=133, bias=True)
 )
)
```

Question 5: Outline the steps you took to get to your final CNN architecture and your reasoning at each step. Describe why you think the architecture is suitable for the current problem.

Answer: Actually, I choose inception_v3 because its top 5 error is 6.44 and quite interesting. I developed by reference and setting the image size to 299. Because it requires N 3 299 * 299. (https://pytorch.org/tutorials/beginner/finetuning_torchvision_models_tutorial.html).

Unfortunately, got cuda run time error out of memory. :(I don't know how to solve it so I change the model to VGG19 with input image size 224. just fixing the final layer of output to 133(dog breed class) and train the data. Got 76% test accuracy.

1.1.14 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion_transfer, and the optimizer as optimizer_transfer below.

1.1.15 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model_transfer.pt'.

```
def train(n_epochs, loaders, model, optimizer, criterion, use_cuda, save_path):
    """returns trained model"""
    valid_loss_min = np.Inf
    for epoch in range(1, n_epochs+1):
        train_loss = 0.0
        valid_loss = 0.0
        ###################
        # train the model #
        ###################
        model.train()
        for batch_idx, (data, target) in enumerate(loaders['train']):
            # move to GPU
            if use cuda:
                data, target = data.cuda(), target.cuda()
            optimizer.zero_grad()
            outputs = model(data)
            loss = criterion(outputs, target)
            loss.backward()
            optimizer.step()
            train_loss = train_loss + ((1 / (batch_idx + 1)) * (loss.data - train_loss))
        ######################
        # validate the model #
        ######################
        model.eval()
        for batch_idx, (data, target) in enumerate(loaders['valid']):
            # move to GPU
            if use_cuda:
                data, target = data.cuda(), target.cuda()
            output = model(data)
            loss = criterion(output, target)
            valid_loss = valid_loss + ((1 / (batch_idx + 1)) * (loss.data - valid_loss))
        print('Epoch: {} \tTraining Loss: {:.6f} \tValidation Loss: {:.6f}'.format(
            epoch,
            train_loss,
            valid_loss
            ))
        ## TODO: save the model if validation loss has decreased
        if valid_loss < valid_loss_min:</pre>
            print('Validation loss decreased ({:.6f} --> {:.6f}). Saving Model ......'.f
            torch.save(model.state_dict(), save_path)
            valid_loss_min = valid_loss
    # return trained model
    return model
```

n_epochs=5

```
# train the model
        model_transfer = train(n_epochs, loaders_transfer, model_transfer, optimizer_transfer, or
        # load the model that got the best validation accuracy (uncomment the line below)
        model_transfer.load_state_dict(torch.load('model_transfer.pt'))
Epoch: 1
                 Training Loss: 2.776448
                                                 Validation Loss: 0.892477
Validation loss decreased (inf --> 0.892477). Saving Model ...
                Training Loss: 1.635522
Epoch: 2
                                                 Validation Loss: 0.821674
Validation loss decreased (0.892477 --> 0.821674). Saving Model ...
                 Training Loss: 1.434810
                                                 Validation Loss: 0.665447
Epoch: 3
Validation loss decreased (0.821674 --> 0.665447). Saving Model ...
                 Training Loss: 1.342706
                                                 Validation Loss: 0.596398
Epoch: 4
Validation loss decreased (0.665447 --> 0.596398). Saving Model ...
                                                 Validation Loss: 0.547008
Epoch: 5
                Training Loss: 1.296078
Validation loss decreased (0.596398 --> 0.547008). Saving Model ...
```

1.1.16 (IMPLEMENTATION) Test the Model

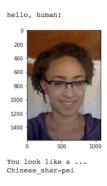
Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 60%.

```
In [6]: def test(loaders, model, criterion, use_cuda):
            # monitor test loss and accuracy
            test_loss = 0.
            correct = 0.
            total = 0.
            model.eval()
            for batch_idx, (data, target) in enumerate(loaders['test']):
                # move to GPU
                if use_cuda:
                    data, target = data.cuda(), target.cuda()
                # forward pass: compute predicted outputs by passing inputs to the model
                output = model(data)
                # calculate the loss
                loss = criterion(output, target)
                # update average test loss
                test_loss = test_loss + ((1 / (batch_idx + 1)) * (loss.data - test_loss))
                # convert output probabilities to predicted class
                pred = output.data.max(1, keepdim=True)[1]
                # compare predictions to true label
                correct += np.sum(np.squeeze(pred.eq(target.data.view_as(pred))).cpu().numpy())
                total += data.size(0)
```

1.1.17 (IMPLEMENTATION) Predict Dog Breed with the Model

Write a function that takes an image path as input and returns the dog breed (Affenpinscher, Afghan hound, etc) that is predicted by your model.

```
In [7]: model_transfer.load_state_dict(torch.load('model_transfer.pt'))
In [8]: # list of class names by index, i.e. a name can be accessed like class_names[0]
        from PIL import Image
        import torchvision.transforms as transforms
        data_transform = transforms.Compose([transforms.RandomResizedCrop(224), transforms.ToTen
        data_transfer = {
            'train': train_data,
            'valid': valid_data,
            'test': test_data
        }
        class_names = [item[4:].replace("_", " ") for item in data_transfer['train'].classes]
        def model_predict(img_path):
            if img_path is None:
                return None
            pil_img = Image.open(img_path)
            img = data_transform(pil_img).unsqueeze_(0)
            output = model_transfer(img.cuda())
            _, preds_tensor = torch.max(output,1)
            return preds_tensor.item()
        def predict_breed_transfer(img_path):
            # load the image and return the predicted breed
                return class_names[model_predict(img_path)]
            except IndexError as error:
                return ""
        print(predict_breed_transfer(dog_files[2]))
```



Sample Human Output

Bulldog

Step 5: Write your Algorithm

Write an algorithm that accepts a file path to an image and first determines whether the image contains a human, dog, or neither. Then, - if a **dog** is detected in the image, return the predicted breed. - if a **human** is detected in the image, return the resembling dog breed. - if **neither** is detected in the image, provide output that indicates an error.

You are welcome to write your own functions for detecting humans and dogs in images, but feel free to use the face_detector and human_detector functions developed above. You are required to use your CNN from Step 4 to predict dog breed.

Some sample output for our algorithm is provided below, but feel free to design your own user experience!

1.1.18 (IMPLEMENTATION) Write your Algorithm

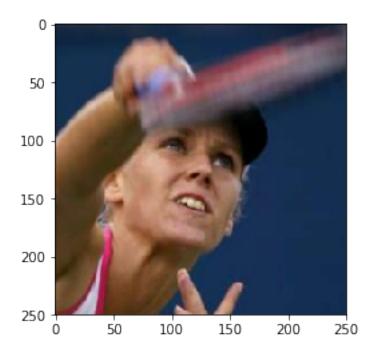
```
In [9]: import matplotlib.pyplot as plt
    import cv2
    import numpy as np
    %matplotlib inline
    import torch
    import torchvision.models as models

# define VGG16 model
    VGG19 = models.vgg19(pretrained=True)

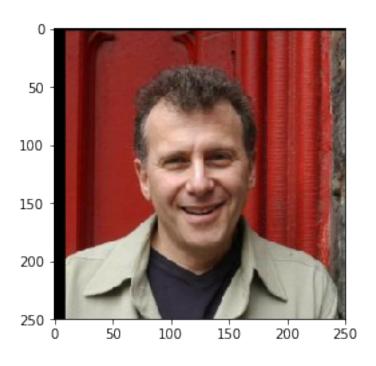
# check if CUDA is available
    use_cuda = torch.cuda.is_available()

# move model to GPU if CUDA is available
    if use_cuda:
        VGG19 = VGG19.cuda()
```

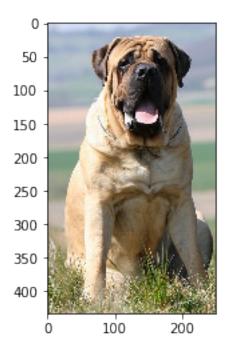
```
for tensor in tensors:
        for t,m,s in zip(tensor,mean,std):
            t.mul_(s).add_(m)
    return tensor
def face_detector(img_path):
    img = cv2.imread(img_path)
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
    faces = face_cascade.detectMultiScale(gray)
    return len(faces) > 0
def VGG19_predict(img_path):
    if img_path is None:
        return None
    pil_img = Image.open(img_path)
    img = data_transform(pil_img).unsqueeze_(0)
    output = VGG19(img.cuda())
    _, preds_tensor = torch.max(output,1)
    return preds_tensor.item()
def dog_detector(img_path):
    pred = VGG19_predict(img_path)
    if pred in range(151, 268):
        return True
    return False
def img_show(img_path):
    img = cv2.imread(img_path)
    cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
    imgplot = plt.imshow(cv_rgb)
    return imgplot
def run_app(img_path):
    dog_type = predict_breed_transfer(img_path)
    if face_detector(img_path):
        print ("You are human!!! But you look like {} !!!!".format(dog_type))
        img_show(img_path)
    elif dog_detector(img_path):
        print ("Oh my lovely puppy. I think you are {} !!!!".format(dog_type))
        img_show(img_path)
    else:
        print ("We can't detect you. Sorry")
        img_show(img_path)
run_app(human_files[200])
```



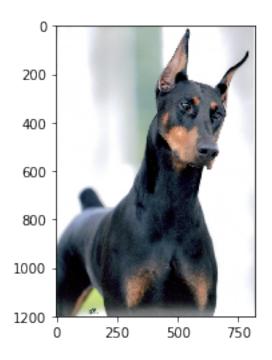
In [21]: run_app(human_files[30])
You are human!!! But you look like Irish water spaniel !!!!



```
In [22]: run_app(dog_files[2])
Oh my lovely puppy. I think you areMastiff !!!!
```



In [23]: run_app(dog_files[100])
Oh my lovely puppy. I think you areGerman pinscher !!!!



In [24]: run_app(dog_files[130])
Oh my lovely puppy. I think you areIrish water spaniel !!!!



Step 6: Test Your Algorithm

In this section, you will take your new algorithm for a spin! What kind of dog does the algorithm think that *you* look like? If you have a dog, does it predict your dog's breed accurately? If you have a cat, does it mistakenly think that your cat is a dog?

1.1.19 (IMPLEMENTATION) Test Your Algorithm on Sample Images!

Test your algorithm at least six images on your computer. Feel free to use any images you like. Use at least two human and two dog images.

Question 6: Is the output better than you expected:)? Or worse:(? Provide at least three possible points of improvement for your algorithm.

Answer: (Three possible points for improvement)

- 1. Can't test with .png file (because of 4 channel) adding for 4 channel and train again we get a better real project.
- 2. My current dog detector is using vgg19 pretrain model. I feel it doesn't work well. If I improve and testing again with dog detector with other pretrain model like Densenet and Inception v3, I will get more accurate result.
- 3. My model_transfer training with only 5 epoches and stop but validation loss contining still drop. If I increase the number of epoch, I will get more accurate result I think.
- 4. I use the original Face Detecor and sample dog detector. It work well but a photo with dog and human, we should mentioned both human and dog. My current algorithm detect the face and return as human. I should check both dog and human result and generate the total count.

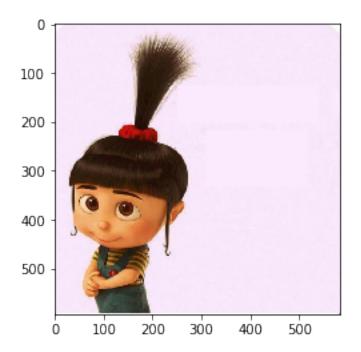
In [21]: run_app('/home/workspace/dog_project/img3.JPG')
We can't detect you. Sorry



In [29]: run_app('/home/workspace/dog_project/img1.JPG')
You are human!!! But you look like Dogue de bordeaux !!!!



In [24]: run_app('/home/workspace/dog_project/img4.JPG')
We can't detect you. Sorry



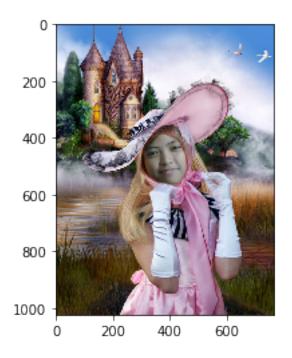
In [25]: run_app('/home/workspace/dog_project/img5.JPG')
You are human!!! But you look like Italian greyhound !!!!



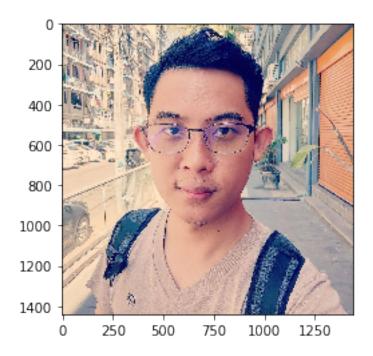
In [27]: run_app('/home/workspace/dog_project/img6.JPG')



In [28]: run_app('/home/workspace/dog_project/.JPG')
You are human!!! But you look like Havanese !!!!



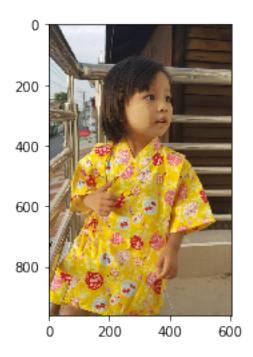
```
In [31]: run_app('/home/workspace/dog_project/chan.jpg')
You are human!!! But you look like Havanese !!!!
```



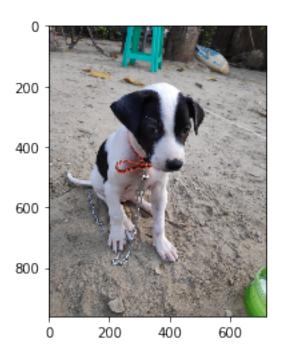
In [10]: run_app('/home/workspace/dog_project/babyyu.jpg')
You are human!!! But you look like Dogue de bordeaux !!!!



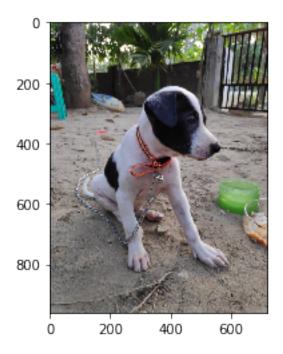
In [11]: run_app('/home/workspace/dog_project/chueshint.jpg')
You are human!!! But you look like Maltese !!!!



In [12]: run_app('/home/workspace/dog_project/dog1.jpg')
Oh my lovely puppy. I think you are Bull terrier !!!!



In [13]: run_app('/home/workspace/dog_project/dog2.jpg')
Oh my lovely puppy. I think you are Bull terrier !!!!



```
In [14]: run_app('/home/workspace/dog_project/dogandhuman.jpg')
You are human!!! But you look like Great pyrenees !!!!
```

