

# SOLUTIONS/ MARKING SCHEME

## CONFIDENTIAL – Do Not Release to Students

SINGAPORE POLYTECHNIC

\_2019 / 20\_ Semester \_1\_ Mid Semester Test

Module Name: MAPP / EDBPII

Module Code: ET1010 / ET1216

Course: DASE/DESM/DCPE/DEEE/DMRO/DEB

Year: 2FT

Set by: M.Fikret Ercan

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No.	SOLUTION	MARKS	TOTAL MARKS
	<b>Section A</b>		
<b>A1</b>	d	3	
<b>A2</b>	a	3	
<b>A3</b>	b	3	
<b>A4</b>	b	3	
<b>A5</b>	c	3	
<b>A6</b>	a	3	
<b>A7</b>	d	3	
<b>A8</b>	b	3	
<b>A9</b>	c	3	
<b>A10</b>	b	3	
			<b>30</b>

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No.	SOLUTION	MARKS	TOTAL MARKS
	<b>Section B</b>		
<b>B1</b>	a) TRISD = 0b 0000 0000; // last bit must be 0	4	
	b) PORTDbits.RD0 = 1; // Set pulse HIGH	1	
	delay_ms(2); // delay for 2 ms	2	
	PORTDbits.RD0 = 0; // Set LOW	1	
	delay_ms(18); // delay for 20 ms	2	
	c)		
	<pre> int i; // configure the pins <b>TRISDbits.TRISD0 = 0;</b> while (1) {     for (i=0;i&lt;100;i++) {         <u>PORTDbits.RD0 = 1;</u> // set HIGH         <u>delay_ms(2);</u> // delay for 2 ms         <u>PORTDbits.RD0 = 0;</u> // set LOW          <u>delay_ms(18);</u> // delay 18 ms     } // for     for (i=0;i&lt;150;i++) {         <u>PORTDbits.RD0 = 1;</u> // set HIGH         <u>delay_ms(1);</u> // delay for 1ms         <u>PORTDbits.RD0 = 0;</u> // set LOW          <u>delay_ms(19);</u> // delay 19 ms     } // for } // while                     </pre>	<div>2</div> <div>2</div> <div>2</div> <div>2</div>	
			<b>18</b>

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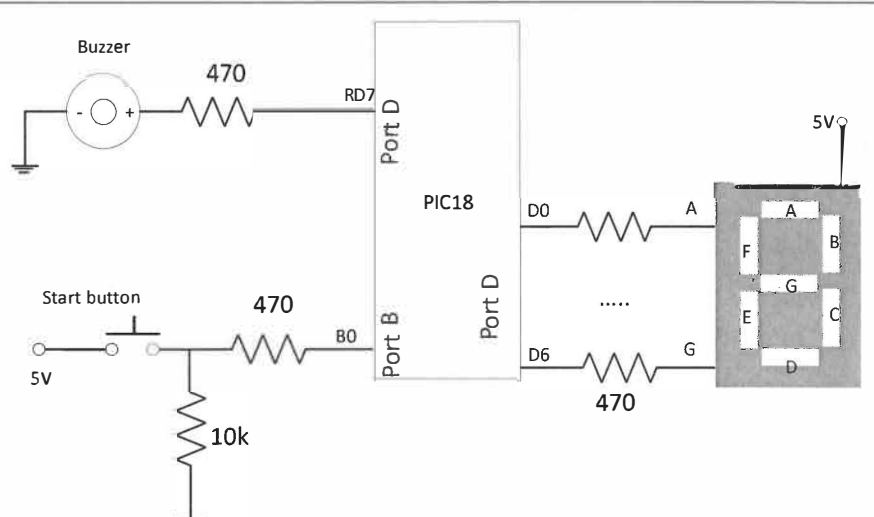
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No.	SOLUTION	MARKS	TOTAL MARKS
	<b>Section B</b>		
<b>B2</b>	(a)		
	 <p>Correct seven segment display circuit 2 marks, Correct button circuit 2 marks, Correct buzzer circuit 2 marks</p>	6	
	(b) TRISD = 0b 0000 0000; TRISB = 0b 1111 1111;	2	

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	<b>Section B</b>																						
<b>B2</b>	<p>(c)</p> <pre> graph TD     Start([Start]) --&gt; SetIO[Set i/o pins]     SetIO --&gt; Counter[Counter=0]     Counter --&gt; Button{Is button pressed?}     Button -- NO --&gt; Button     Button -- YES --&gt; StartBuzzer[Start buzzer]     StartBuzzer --&gt; Display[Display count]     Display --&gt; Delay[Delay 1 sec]     Delay --&gt; Increment[Increment count]     Increment --&gt; Count8{Is count 8?}     Count8 -- YES --&gt; StopBuzzer[Stop buzzer]     Count8 -- NO --&gt; Display     </pre> <table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td>Display count</td><td>F</td><td>Start buzzer</td><td>E</td></tr> <tr> <td>Stop buzzer</td><td>K</td><td>Start</td><td>A</td></tr> <tr> <td>Set i/o pins</td><td>B</td><td>Increment counter</td><td>H</td></tr> <tr> <td>counter=0</td><td>C</td><td>Is button pressed?</td><td>D</td></tr> <tr> <td>Is count ==8?</td><td>J</td><td>Delay 1 sec</td><td>G</td></tr> </table> <p>(1 marks for each correct answer. Order for "Set i/o pins" , "counter=0" can be reversed award full mark as long as flow chart works )</p>	Display count	F	Start buzzer	E	Stop buzzer	K	Start	A	Set i/o pins	B	Increment counter	H	counter=0	C	Is button pressed?	D	Is count ==8?	J	Delay 1 sec	G	10	
Display count	F	Start buzzer	E																				
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	<b>Section B</b>		
<b>B3</b>	a) $\frac{5x-0}{10-5} = \frac{2.78-0}{7-5}$ Ph=7.78	4	
	b) 0 and 1023 (or, 0000000000 and 1111111111)	2	
	c) Ph =9 -> 818 -> 1100110010 Ph=8 -> 614 -> 1001100110 ( 3 marks each)	6	
	d) Waiting for AD conversion to complete and data captured	2	
	e) left justified	2	
			<b>16</b>

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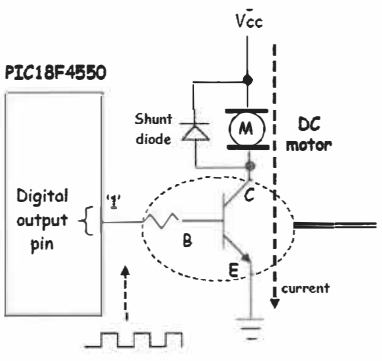
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	<b>Section B</b>		
<b>B4</b>	<p>(a) correct use of shunt diode (2 marks), correct connection of motor (2 marks), correct transistor connection (4 marks)</p> 	8	
	<p>(b) Example solution (Student may provide different solution. Award grade based on your professional judgement). Port configuration 2 marks, correct use of while loop (2 marks), correct if-else constructs (6 marks)</p> <pre> // configure the pins int i=0; TRISAbits.TRISA0 = 1; TRISDbits.TRISD1 = 0; while (1) {     if (PORTAbits.RA0==1 &amp;&amp; i==0) {         delay_ms (2000);           // 2 sec delay         if (PORTAbits.RA0==1) i=1; else i=0; // check if SW1 still pressed     }     if ((PORTAbits.RA0==1) &amp;&amp; ( i==1)) { // i=1 indicates 2 second delay         PORTDbits.RD1 = 1; // turn on the motor         delay_ms(20); // give a short delay     }     else { PORTDbits.RD1 = 0; // turn off the motor      i=0;     } } // while                     </pre>	10	
			<b>18</b>

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