

Homework 2  
CESG506  
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2-1

1. Using Henky strain, a linear relation  $\sigma = E\epsilon$ ,  $A = \text{const.}$  and equilibrium on the deformed system, derive the relationship between displacements and forces on the free node. Adjust it for path following as

$$R(\gamma, \underline{u}) = \gamma \bar{\underline{P}} - F(\underline{u}(s)) = 0$$

with reference load  $\bar{\underline{P}} = -(0.99 \text{ kN}) \underline{j}$  load intensity factor  $\gamma$  and displacement  $\underline{u}$

Find the tangents  $\partial R / \partial \gamma$  and  $\partial R / \partial \underline{u}$

$$\epsilon = \frac{1}{2} \ln(\lambda^2) \quad \lambda^2 = \frac{l^2}{L^2} = \frac{|\underline{l}|^2}{L^2} = \frac{|\underline{L} + \underline{u}|^2}{L^2}$$

$$\frac{\partial R}{\partial \underline{u}} = [\underline{K}_T] = \begin{bmatrix} \underline{k}^e & -\underline{k}^e \\ -\underline{k}^e & \underline{k}^e \end{bmatrix} \quad \text{w/} \quad \underline{k}^e = \frac{EA}{l^e} \underline{n}^e \otimes \underline{n}^e + \frac{f^e}{l^e} \left( \underline{1} - \frac{\gamma}{l^e} \underline{n}^e \otimes \underline{n}^e \right)$$

As we showed last week  $\frac{\partial}{\partial \underline{u}} \gamma \bar{\underline{P}} = 0$

$$\frac{\partial R}{\partial \gamma} = \bar{\underline{P}} - 0 = -(0.99 \text{ kN}) \underline{j}$$

2-1  
2.

$$\begin{Bmatrix} \underline{R}(\gamma, \underline{u}) \\ g(\underline{u}) \end{Bmatrix} + \begin{Bmatrix} \underline{\bar{P}} \\ 0 \end{Bmatrix} \cdot \Delta\gamma + \begin{Bmatrix} \underline{K}_T \\ \underline{e}_k \end{Bmatrix} \cdot \Delta\underline{u} = 0$$

$$\begin{bmatrix} \underline{K}_T & -\underline{\bar{P}} \\ \underline{e}_k & 0 \end{bmatrix} \begin{Bmatrix} \Delta\underline{u} \\ \Delta\gamma \end{Bmatrix} = \begin{Bmatrix} \underline{R} \\ g \end{Bmatrix}$$

with  $\underline{R} = \gamma \underline{\bar{P}} - F(\underline{u}(\gamma))$  &  $g(\underline{u}) = \underline{e}_k \cdot \underline{u} - \bar{u}_k = 0$

1. Calculate disp. ( $\underline{u}_0$ ) based on current residue forces ( $\underline{R}$ )

$$\underline{u}_0 = \underline{K}^{-1} \cdot \underline{R}$$

and disp. ( $\underline{u}_1$ ) based on reference force ( $\underline{\bar{P}}$ )

$$\underline{u}_1 = \underline{K}^{-1} \cdot \underline{\bar{P}}$$

2. Calculate required change in reference force to match disp. in controlled DoF

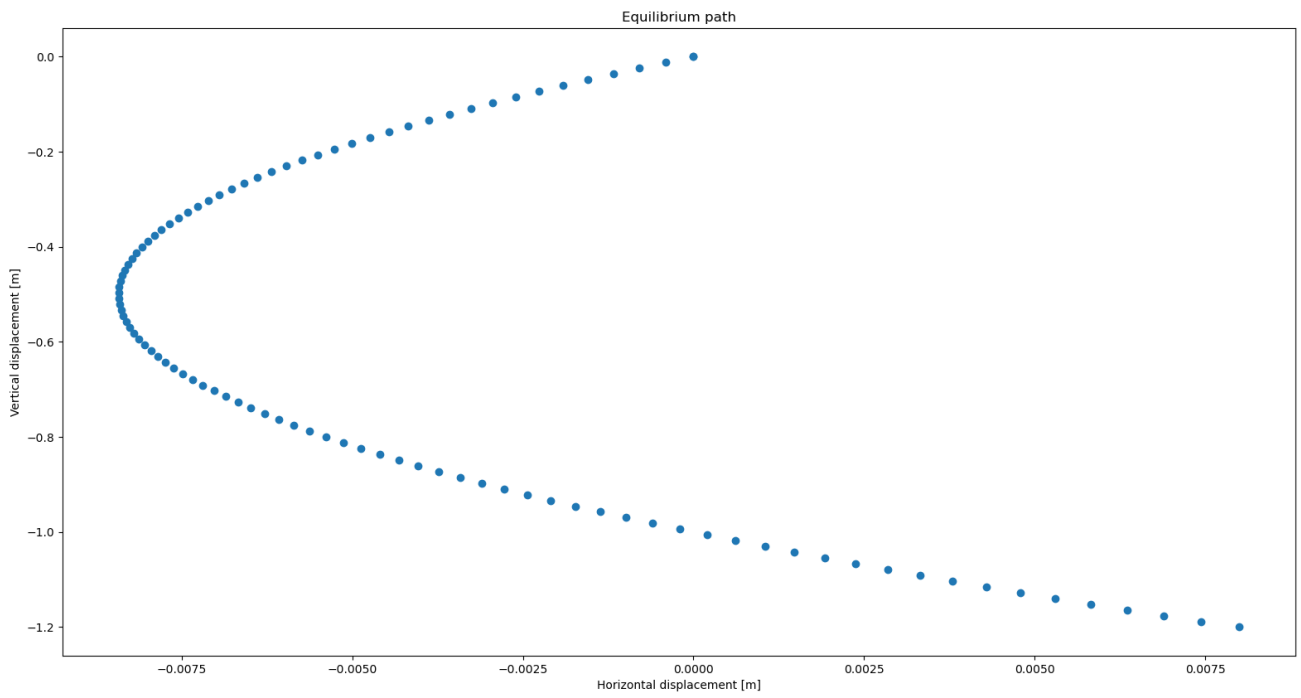
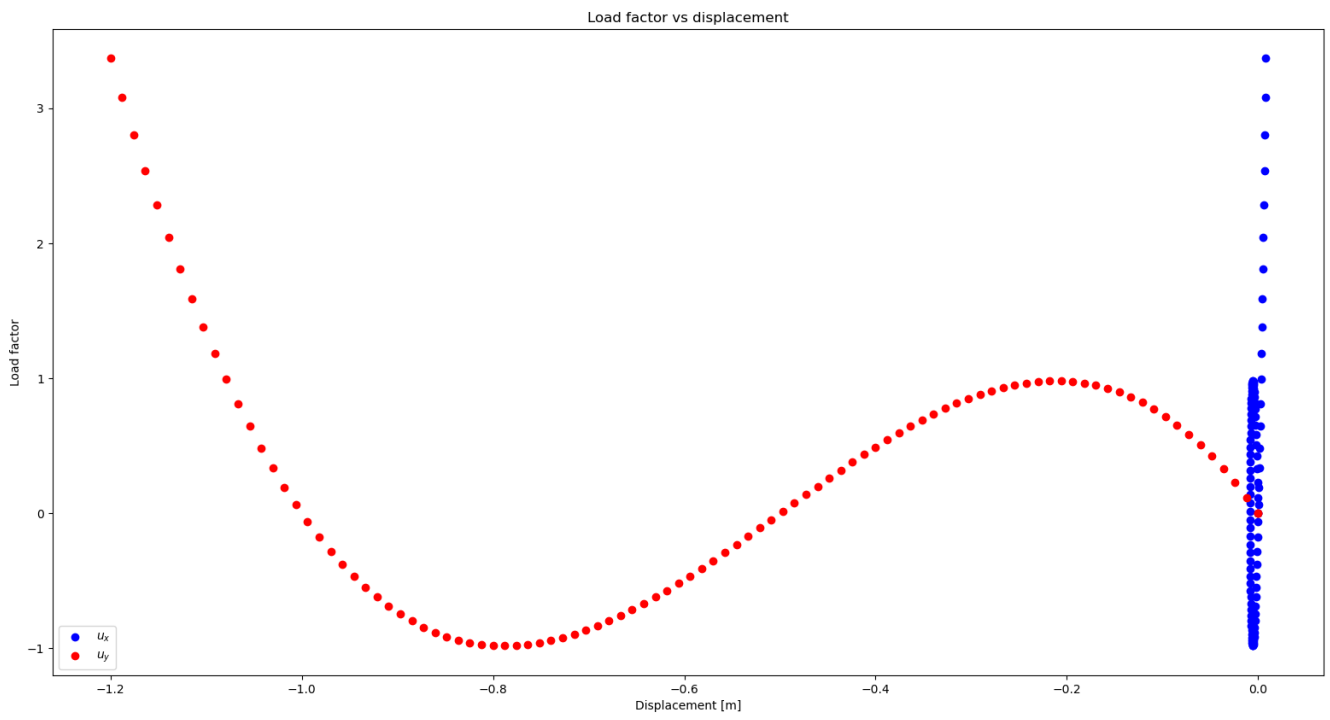
$$\Delta\gamma = - \frac{g + \underline{e}_k \cdot \underline{u}_0}{\underline{e}_k \cdot \underline{u}_1}$$

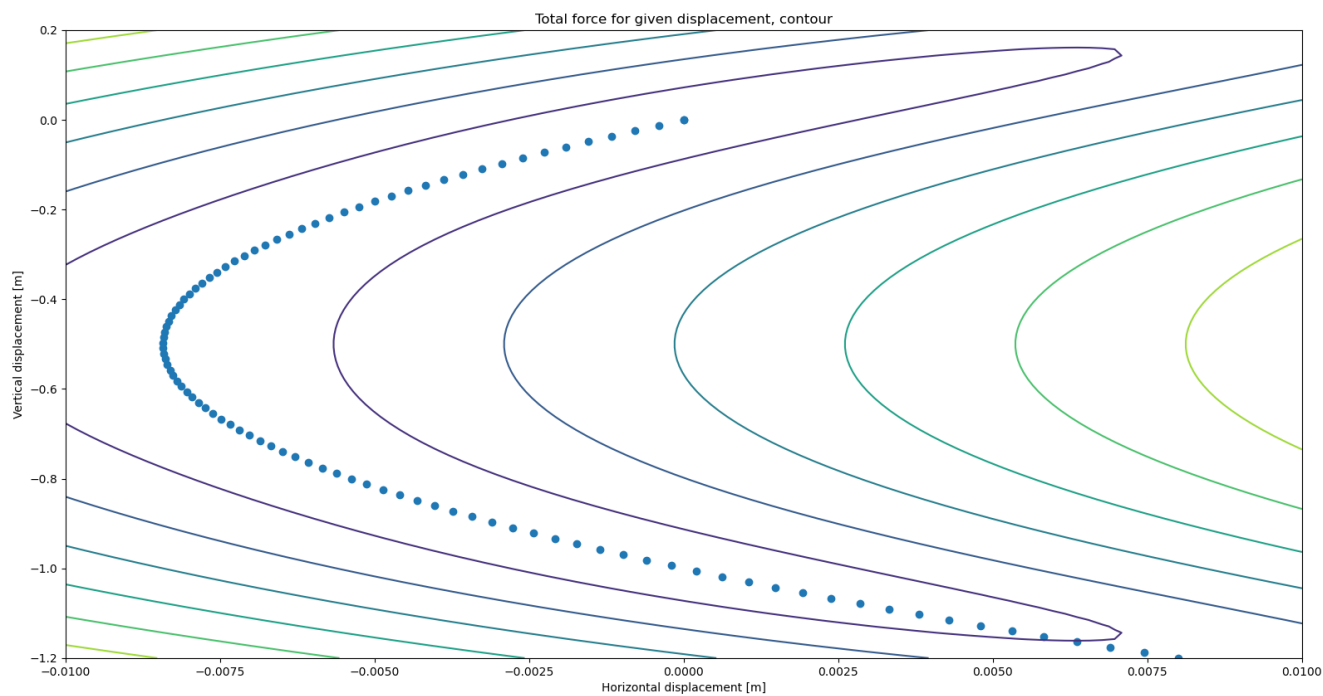
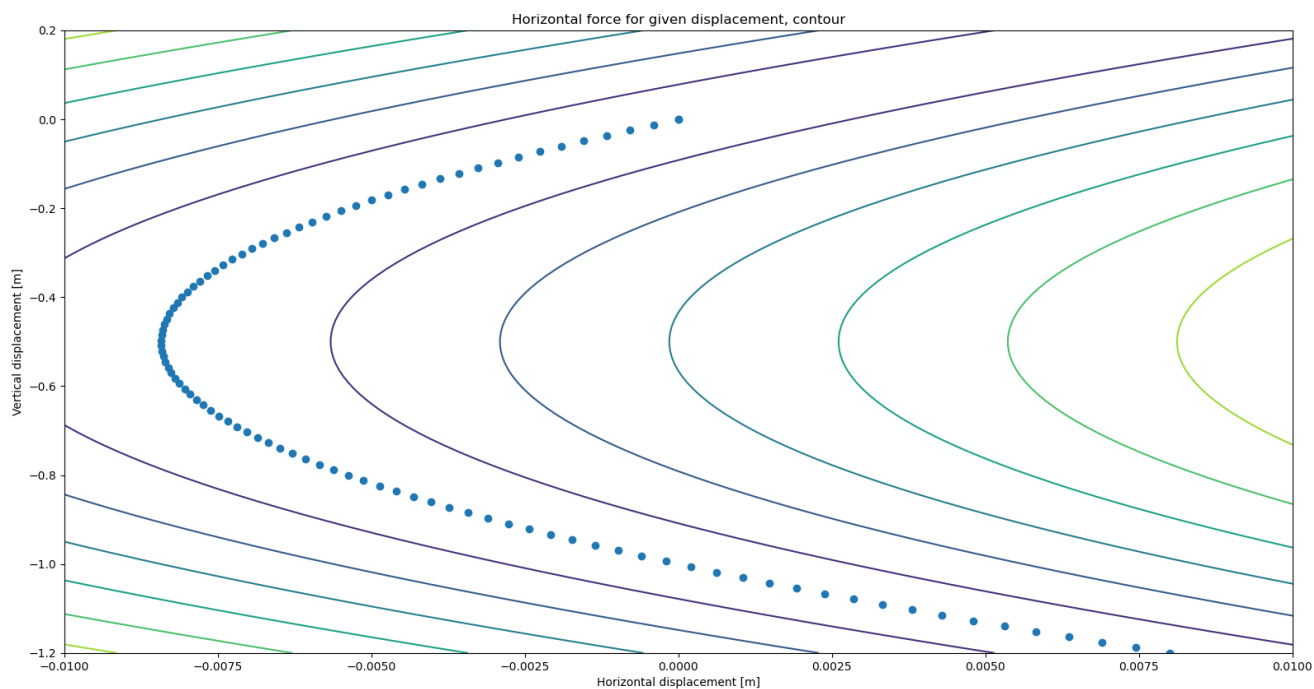
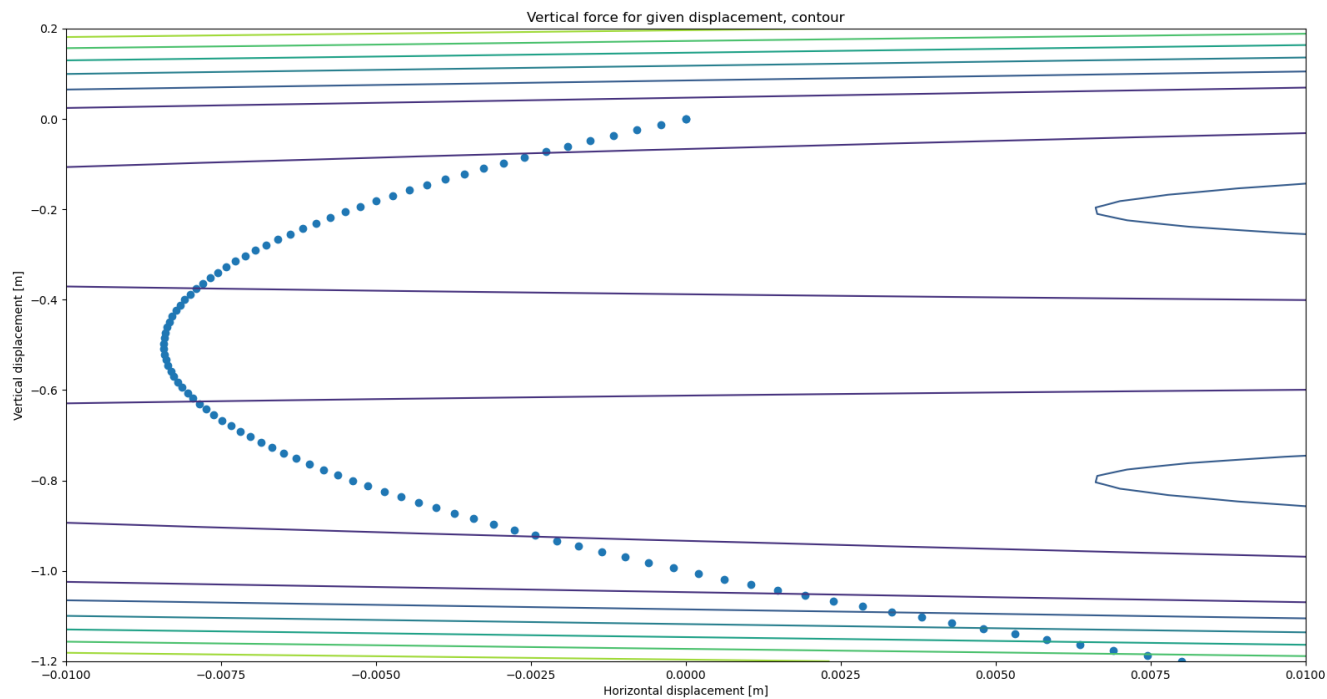
3. Calculate new displacement increment

$$\Delta\underline{u} = \underline{u}_0 + \Delta\gamma \cdot \underline{u}_1$$

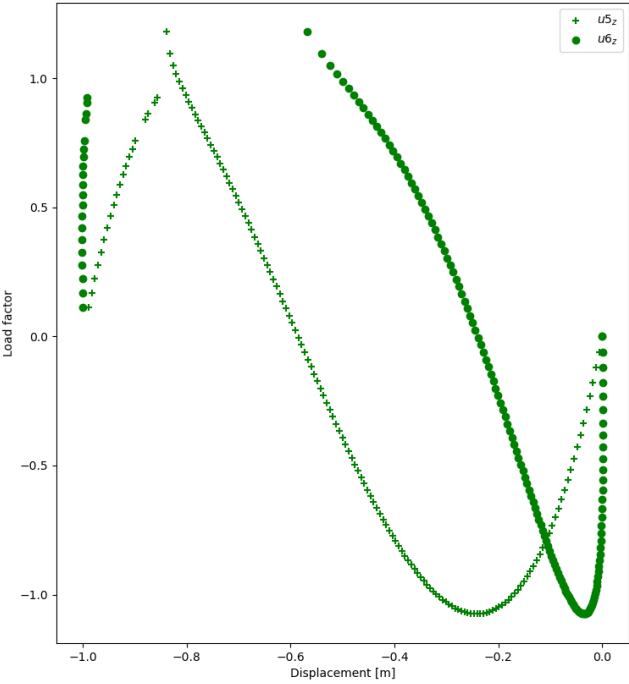
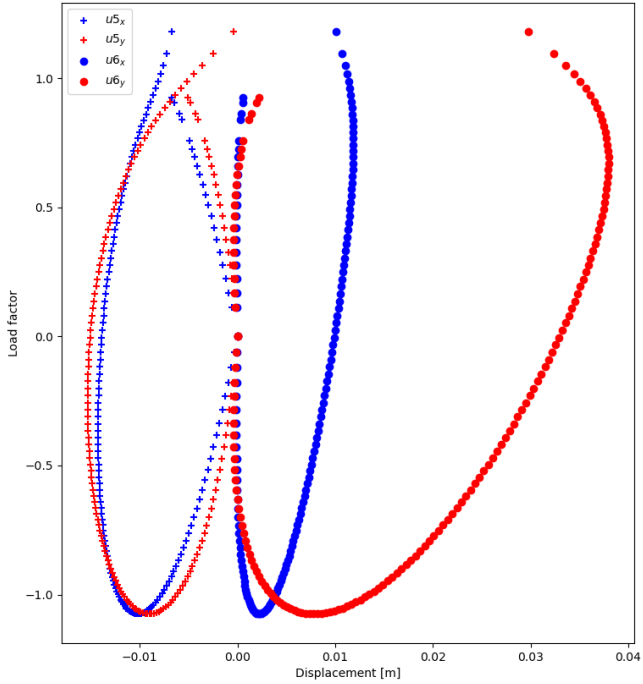
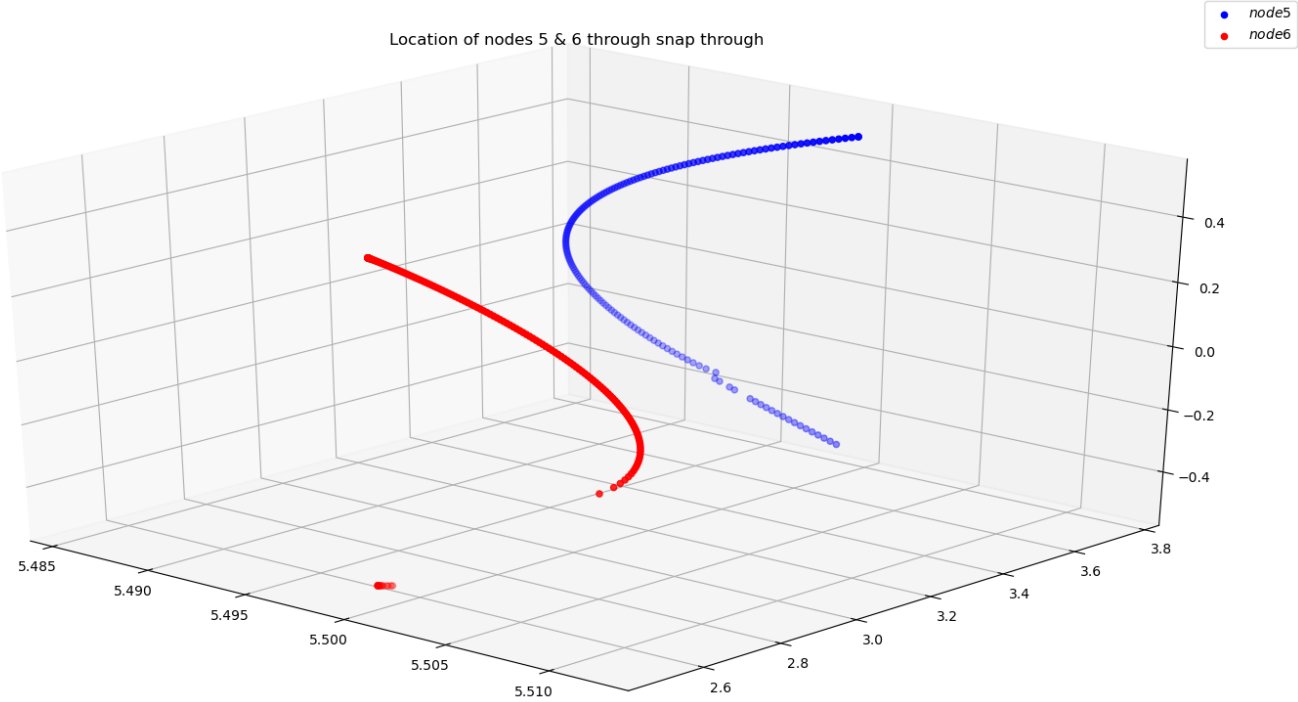
4. Update Residue force ( $\underline{R}(\gamma, \underline{u})$ ) based on new total  $\underline{u}$  and  $\gamma$

Repeat 1-4 until tolerance norm( $\underline{R}$ ) is within desired limits.





Problem 2-2



All code for problem 2-1 and 2-2 can be found in github file structure. Running main.py will run through all calculations and produce all figures shown here.