LAB 2

In the following documentation we will explain the changes we have made in XV6 in chronological order.

- 1) In proc.h we created an "int priority" struct proc.
- In the following files we created the syscall "setpriority"
 - i) Syscall.c
 - ii) Syscall.h
 - iii) User.h
 - iv) Proc.c
 - v) Defs.h
 - vi) sysproc.c
 - 3) In sysproc.c under the function sys setpriority we implemented the following:

```
118
           argint(0, &pid);
                                                        //passing firs
           argptr(1,(void*)&status,sizeof(status));
119
120
           argint(2, &options);
121
           return waitpid(pid, status, options);
122
      L3
123
124
125
       int
       sys_setpriority(void)
                                                            //change p
126
     ₽{
127
128
           int priority;
129
           //cprintf("priority from sysproc: "); //print priority
130
           if(argint(0, &priority) < 0)
131
132
               return -1;
133
           return setpriority(priority);
      }
134
135
```

4) in the proc.c we implemented in the function "scheduler" the following which loops through the pTable to find the highest priority and run the highest priority process.

```
sti();
492
         int max = 31;//lab2
          // Loop over process table looking for process to run.
494
         acquire(&ptable.lock);
496
          //lab2
          //find the maximum priority
          for ( p = ptable.proc; p < &ptable.proc[NPROC]; p++) //scan through table</pre>
499 ~
                //cprintf("find \n");
502 🕶
                if ( p->priority < max && p->state == RUNNABLE) //make sure the maximum is always runnable
                         max = p->priority; //set max to the the highest priortiy
                //cprintf("find \n");
509
              //cprintf("find %d \n", max); ///why run forever
              //lab2
              //check highest priority
         for(p = ptable.proc; p < &ptable.proc[NPROC]; p++){
   if(/*p->priority != max ||*/ p->state != RUNNABLE ) //if it is not the max or not runnable
514 🗸
515 ~
                                                                                                                  ://p-
              continue;
     //cprintf("the max is %d \n", max);
            // Switch to chosen process. It is the process's job
```

- i) We initiate int max = 31 on line 492
- ii) on line 502 we make a condition is p->priority is less than max we make it the new max

iii) on line 527 if p->priority is == max then we run the process

```
// to release ptable.lock and then reacquire it
// before jumping back to us.

if (p->priority == max)
{
    //p->priority++; //lower priority
    c->proc = p;
    //cprintf("we are now runnning process with priority : %d \n", p->priority);
    switchuvm(p);
    p->state = RUNNING;

switchkvm();
    c->proc = 0;
    // Process is done running for now.

// It should have changed its p->state before coming back.

}

else
{
    p->priority_counter--; //count down
    if (p->priority_counter == 0)
    {
        p->priority_counter == 0);
    }

release(&ptable.lock);

release(&ptable.lock);
```

For the extra bonus we created a int priority_counter struct in proc.h.

This is to keep track of the counter for each time a process is waiting and each 10 time it waits the process's priority increases while the process that's running its priority decreases. The implementation can be seen in the above figure in line 544.