# Numerical Analysis: Final exam

(**50 marks**, only the 5 best questions count)

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**Question 1** (Floating point arithmetic, **10 marks**). True or false? +1/-1

1. Let $(\bullet)_3$ denote base 3 representation. It holds that
$$(120)_3 + (111)_3 = (1001)_3.$$

2. Let $(\bullet)_2$ denote binary representation. It holds that
$$(1000)_2 \times (0.1\overline{01})_2 = (101.\overline{01})_2.$$

3. In Julia, `Float64(.25) == Float32(.25)` evaluates to `true`.

4. The spacing (in absolute value) between successive double-precision (`Float64`) floating point numbers is constant.

5. The machine epsilon is the smallest strictly positive number that can be represented in a floating point format.

6. Let $\mathbf{F}_{64} \subset \mathbf{R}$ denote the set of double-precision floating point numbers. If $x \in \mathbf{F}_{64}$, then $x$ admits a finite decimal representation.

7. Let $x$ be a real number. If $x \in \mathbf{F}_{64}$, then $2x \in \mathbf{F}_{64}$.

8. The following equality holds
$$(0.\overline{101})_2 = \frac{7}{3}.$$

9. In Julia, `256.0 + 2.0*eps(Float64) == 256.0` evaluates to `true`.

10. The set $\mathbf{F}_{64}$ of double-precision floating point numbers contains twice as many real numbers as the set $\mathbf{F}_{32}$ of single-precision floating point numbers.

11. Let $x$ and $y$ be two numbers in $\mathbf{F}_{64}$. The result of the machine addition $x \mathbin{\widehat{+}} y$ is sometimes exact and sometimes not, depending on the values of $x$ and $y$.

**Question 2** (Iterative method for linear systems, **10 marks**). Assume that $\mathsf{A} \in \mathbf{R}^{n\times n}$ is a nonsingular matrix and that $\boldsymbol{b} \in \mathbf{R}^n$. We wish to solve the linear system

$$\mathsf{A}\boldsymbol{x} = \boldsymbol{b} \tag{1}$$

using an iterative method where each iteration is of the form

$$\mathsf{M}\boldsymbol{x}_{k+1} = \mathsf{N}\boldsymbol{x}_k + \boldsymbol{b}.$$

Here $\mathsf{A} = \mathsf{M} - \mathsf{N}$ is a splitting of $\mathsf{A}$ such that $\mathsf{M}$ is nonsingular, and $\boldsymbol{x}_k \in \mathbf{R}^n$ denotes the $k$-th iterate of the numerical scheme.

1. (**3 marks**) Let $\boldsymbol{e}_k := \boldsymbol{x}_k - \boldsymbol{x}_*$, where $\boldsymbol{x}_*$ is the exact solution to (1). Prove that

$$\boldsymbol{e}_{k+1} = \mathsf{M}^{-1}\mathsf{N}\boldsymbol{e}_k.$$

2. (**3 marks**) Let $L = \|\mathsf{M}^{-1}\mathsf{N}\|_\infty$. Prove that

$$\forall k \in \mathbf{N}, \qquad \|\boldsymbol{e}_k\|_\infty \leq L^k \|\boldsymbol{e}_0\|_\infty.$$

3. (**1 mark**) Is the condition $\|\mathsf{M}^{-1}\mathsf{N}\|_\infty < 1$ necessary for convergence when $\boldsymbol{x}_0 \neq \boldsymbol{x}_*$?

4. (**3 marks**) Assume that $\mathsf{A}$ is strictly row diagonally dominant, in the sense that

$$\forall i \in \{1, \dots, n\}, \qquad |a_{ii}| > \sum_{j=1, j\neq i}^{n} |a_{ij}|.$$

Show that, in this case, the inequality $\|\mathsf{M}^{-1}\mathsf{N}\|_\infty < 1$ holds for the Jacobi method, i.e. when $\mathsf{M}$ contains just the diagonal of $\mathsf{A}$. You may take for granted the following expression for the $\infty$-norm of a matrix $\mathsf{X} \in \mathbf{R}^{n\times n}$:

$$\|\mathsf{X}\|_\infty = \max_{1\leq i\leq n} \sum_{j=1}^{n} |x_{ij}|.$$

5. (**Bonus +1**) Write down a few iterations of the Jacobi method when

$$\mathsf{A} = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}, \qquad \boldsymbol{b} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \qquad \boldsymbol{x}_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

Is the method convergent?

**Question 3** (Nonlinear equations, **10 marks**). Assume that $\boldsymbol{x}_* \in \mathbf{R}^n$ is a solution to the equation

$$\boldsymbol{F}(\boldsymbol{x}) = \boldsymbol{x},$$

where $\boldsymbol{F}\colon \mathbf{R}^n \to \mathbf{R}^n$ is a smooth nonlinear function. We consider the following fixed-point iterative method for approximating $\boldsymbol{x}_*$:

$$\boldsymbol{x}_{k+1} = \boldsymbol{F}(\boldsymbol{x}_k). \tag{2}$$

1. (**8 marks**) Assume in this part that $\boldsymbol{F}$ satisfies the local Lipschitz condition

$$\forall \boldsymbol{x} \in B_\delta(\boldsymbol{x}_*), \qquad \|\boldsymbol{F}(\boldsymbol{x}) - \boldsymbol{F}(\boldsymbol{x}_*)\| \leq L\|\boldsymbol{x} - \boldsymbol{x}_*\|, \tag{3}$$

with $0 \leq L < 1$ and $\delta > 0$. Here $B_\delta(\boldsymbol{x}_*)$ denotes the open ball of radius $\delta$ centered at $\boldsymbol{x}_*$. Show that the following statements hold:

- (**2 marks**) There is no fixed point of $\boldsymbol{F}$ in $B_\delta(\boldsymbol{x}_*)$ other than $\boldsymbol{x}_*$.
- (**2 marks**) If $\boldsymbol{x}_0 \in B_\delta(\boldsymbol{x}_*)$, then all the iterates $(\boldsymbol{x}_k)_{k\in\mathbf{N}}$ belong to $B_\delta(\boldsymbol{x}_*)$.
- (**3 marks**) If $\boldsymbol{x}_0 \in B_\delta(\boldsymbol{x}_*)$, then the sequence $(\boldsymbol{x}_k)_{k\in\mathbf{N}}$ converges to $\boldsymbol{x}_*$ and

$$\forall k \in \mathbf{N}, \qquad \|\boldsymbol{x}_k - \boldsymbol{x}_*\| \leq L^k\|\boldsymbol{x}_0 - \boldsymbol{x}_*\|.$$

2. (**3 marks**) Explain with an example how the iterative scheme (2) can be employed for solving a nonlinear equation of the form

$$\boldsymbol{f}(\boldsymbol{x}) = \boldsymbol{0}.$$

3. (**Bonus +1**) Let $\mathsf{J}_F\colon \mathbf{R}^n \to \mathbf{R}^{n\times n}$ denote the Jacobian matrix of $\boldsymbol{F}$. Show that if

$$\forall \boldsymbol{x} \in B_\delta(\boldsymbol{x}_*), \qquad \|\mathsf{J}_F(\boldsymbol{x})\| \leq L,$$

then the local Lipschitz condition (3) is satisfied.

**Question 4** (Error estimate for eigenvalue problem, **10 marks**). Let $\|\bullet\|$ denote the Euclidean norm, and assume that $\mathsf{A} \in \mathbf{R}^{n\times n}$ is symmetric and nonsingular.

1. (**5 marks**) Describe with words and pseudocode a simple numerical method for calculating the eigenvalue of $\mathsf{A}$ of smallest modulus, as well as the corresponding eigenvector.

2. (**Bonus +1**) Let $\mathsf{M} \in \mathbf{R}^{n\times n}$ denote a nonsingular symmetric matrix. Prove that

$$\forall \boldsymbol{x} \in \mathbf{R}^n, \qquad \|\mathsf{M}\boldsymbol{x}\| \geq \|\mathsf{M}^{-1}\|^{-1}\|\boldsymbol{x}\|. \tag{4}$$

Let $\lambda_{\min}(\mathsf{M})$ denote the eigenvalue of $\mathsf{M}$ of smallest modulus. Deduce from (4) that

$$\forall \boldsymbol{x} \in \mathbf{R}^n, \qquad \|\mathsf{M}\boldsymbol{x}\| \geq |\lambda_{\min}(\mathsf{M})|\|\boldsymbol{x}\|. \tag{5}$$

3. (**5 marks**) Assume that $\widehat{\lambda} \in \mathbf{R}$ and $\widehat{\boldsymbol{v}} \in \mathbf{R}^n$ are such that

$$\|\mathsf{A}\widehat{\boldsymbol{v}} - \widehat{\lambda}\widehat{\boldsymbol{v}}\| = \varepsilon > 0, \qquad \|\widehat{\boldsymbol{v}}\| = 1. \tag{6}$$

Using (5), prove that there exists an eigenvalue $\lambda$ of $\mathsf{A}$ such that

$$|\lambda - \widehat{\lambda}| \leq \varepsilon.$$

4. (**Bonus +1**) Show that, in the more general case where $\mathsf{A} = \mathsf{V}\mathsf{D}\mathsf{V}^{-1}$ is diagonalizable but not necessarily Hermitian, equation (6) implies the existence of an eigenvalue $\lambda$ of $\mathsf{A}$ with

$$|\widehat{\lambda} - \lambda| \leq \|\mathsf{V}\|\|\mathsf{V}^{-1}\|\varepsilon.$$

**Hint**: Introduce $\boldsymbol{r} = \mathsf{A}\widehat{\boldsymbol{v}} - \widehat{\lambda}\widehat{\boldsymbol{v}}$ and rewrite

$$\|\widehat{\boldsymbol{v}}\| = \|(\mathsf{A} - \widehat{\lambda}\mathsf{I})^{-1}\boldsymbol{r}\| = \|\mathsf{V}(\mathsf{D} - \widehat{\lambda}\mathsf{I})^{-1}\mathsf{V}^{-1}\boldsymbol{r}\|.$$

**Question 5** (Interpolation error, **10 marks**). Let $u$ denote the function

$$u\colon [0,2\pi] \to \mathbf{R};$$
$$x \mapsto \cos(x).$$

Let $p_n\colon [0,2\pi] \to \mathbf{R}$ denote the interpolating polynomial of $u$ through at the nodes

$$x_i = \frac{2\pi i}{n}, \qquad i = 0,\dots,n.$$

1. (**3 marks**) Using a method of your choice, calculate $p_n$ for $n = 2$.

2. (**6 marks**) Let $n \in \mathbf{N}_{>0}$ and $e_n(x) := u(x) - p_n(x)$. Prove that

$$\forall x \in [0,2\pi], \qquad |e_n(x)| \leq \frac{|\omega(x)|}{(n+1)!},$$

   where we introduced

$$\omega_n(x) := \prod_{i=0}^{n} (x - x_i).$$

   **Hint:** You may find it useful to introduce the function

$$g(t) = e_n(t)\omega_n(x) - e_n(x)\omega_n(t).$$

3. (**1 mark**) Does the maximum absolute error

$$E_n := \sup_{x\in[0,2\pi]} |e_n(x)|$$

   tend to zero in the limit as $n \to \infty$?

(**Bonus +1**) Using the Gregory–Newton formula, find a closed expression for the sum

$$S(n) = \sum_{k=1}^{n} k^2.$$

**Question 6** (Numerical integration, **10 marks**). The third exercise below is independent of the first two.

1. (**5 marks**) Construct an integration rule of the form
$$\int_{-1}^{1} u(x)\,\mathrm{d}x \approx w_1 u\left(-\frac{1}{2}\right) + w_2 u(0) + w_3 u\left(\frac{1}{2}\right)$$
with a degree of precision equal to at least 2.

2. (**1 mark**) What is the degree of precision of the rule constructed?

3. (**4 marks**) The Gauss–Laguerre quadrature rule with $n$ nodes is an approximation of the form
$$\int_{0}^{\infty} u(x)\,\mathrm{e}^{-x}\,\mathrm{d}x \approx \sum_{i=1}^{n} w_i u(x_i),$$
such that the rule is exact when $u$ is a polynomial of degree less than or equal to $2n-1$. Find the Gauss–Laguerre rule with one node ($n = 1$).

4. (**Bonus +1**) Find the Gauss–Laguerre quadrature rule with two nodes ($n = 2$). You may find it useful to first calculate the Laguerre polynomial of degree 2.