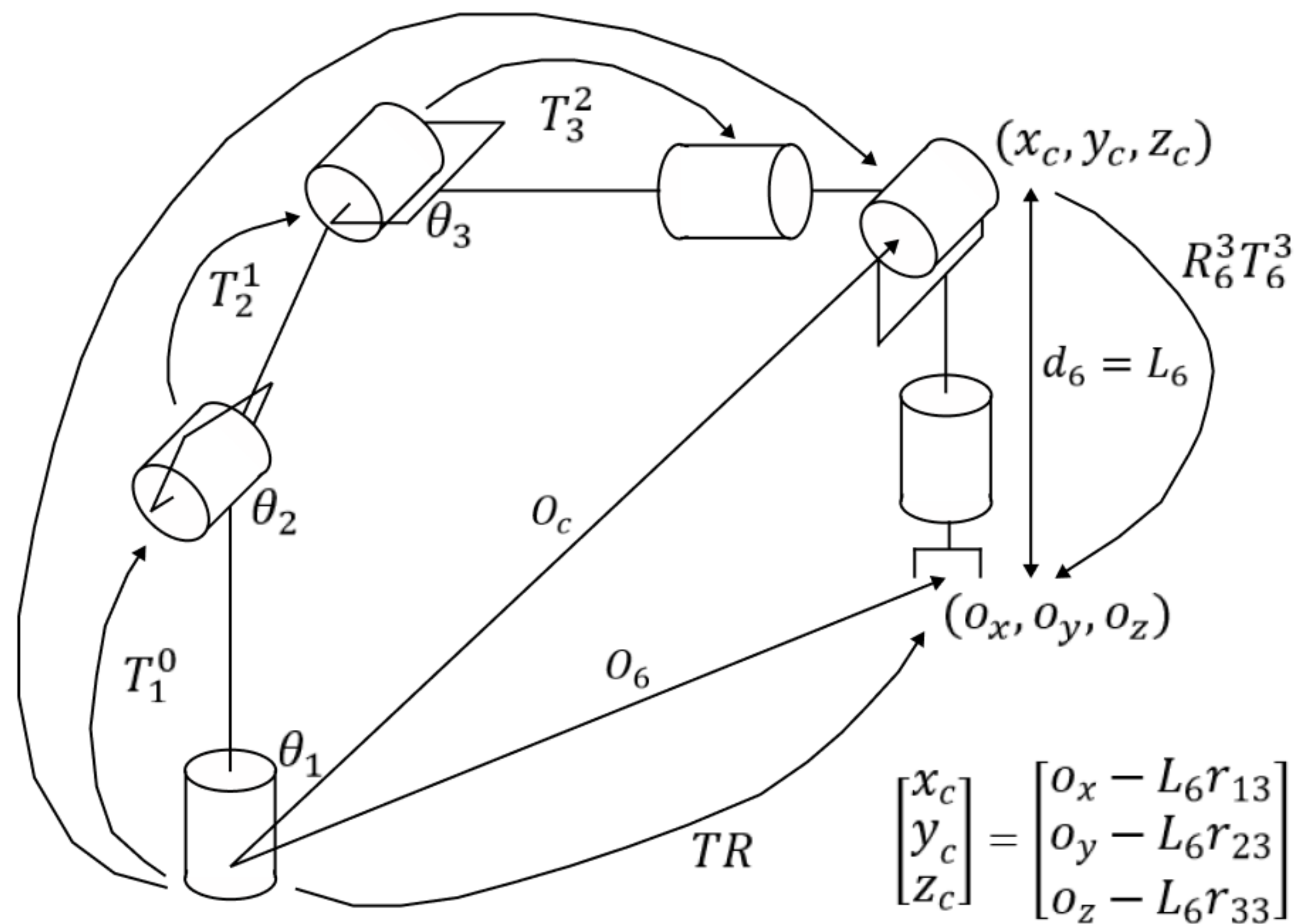
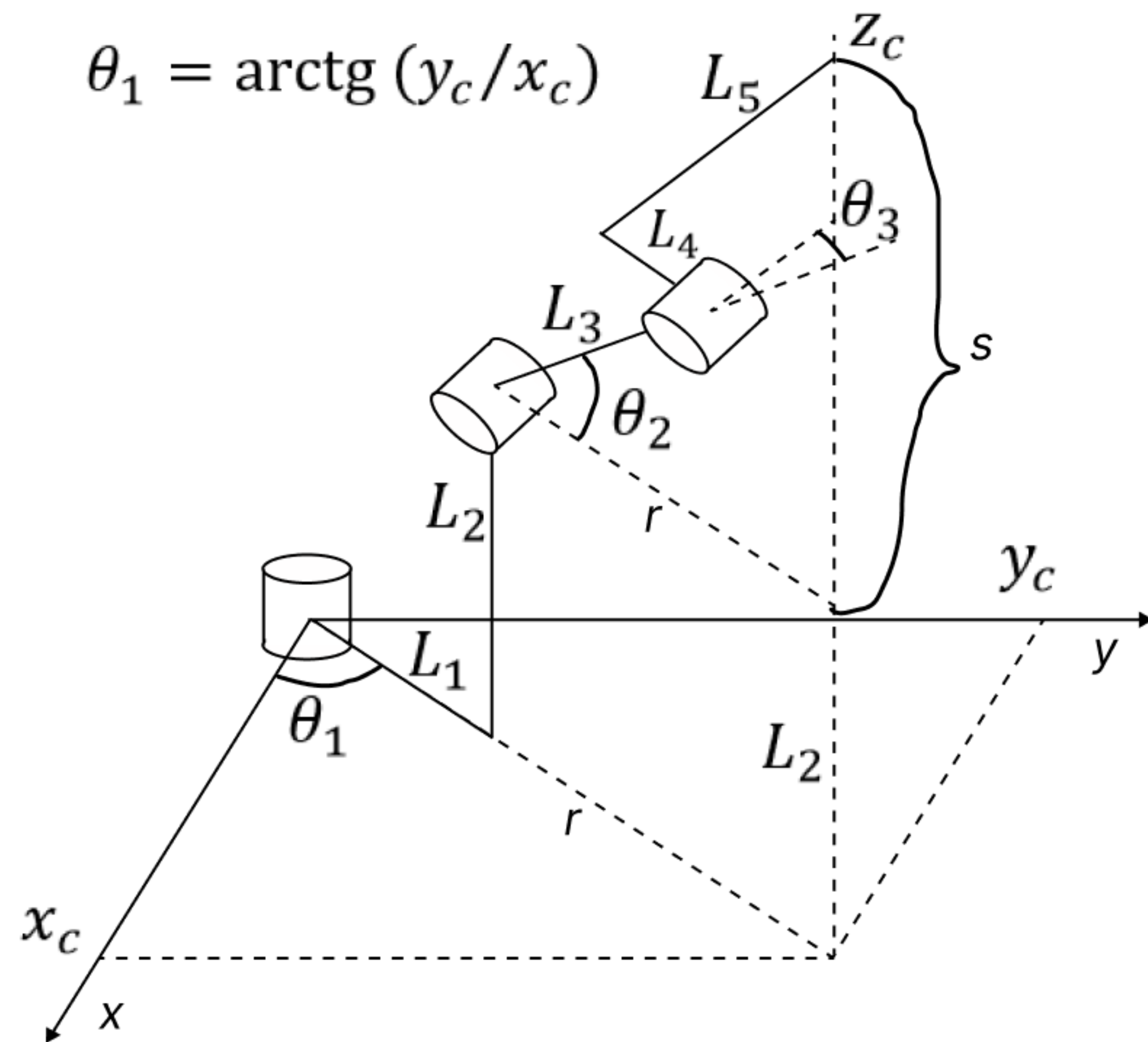


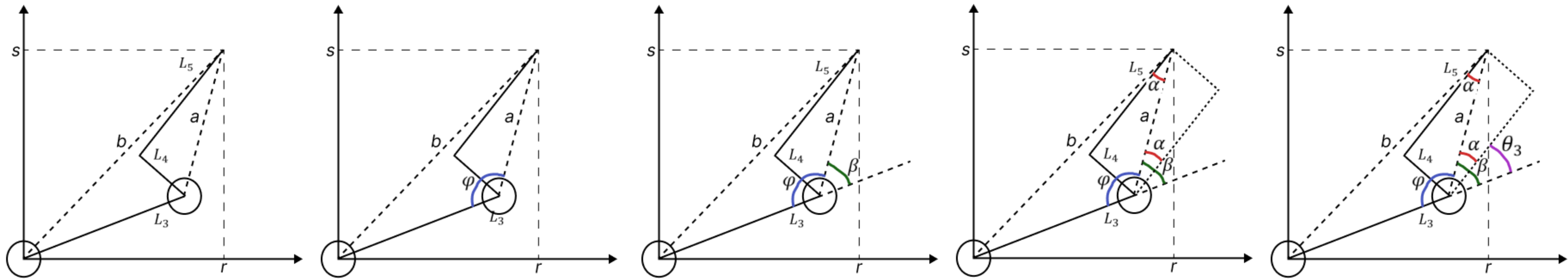
$$R_3^0 T_3^0 = T_1^0 \cdot T_2^1 \cdot T_3^2$$



$$\theta_1 = \text{arctg}(y_c/x_c)$$



I



$$a = \sqrt{L_4^2 + L_5^2}$$

$$r = \sqrt{x_c^2 + y_c^2} - L_1$$

$$s = z_c - L_2$$

$$b = \sqrt{r^2 + s^2}$$

$$\cos \varphi = \frac{L_3^2 + a^2 - b^2}{2 \cdot L_3 \cdot a} = D$$

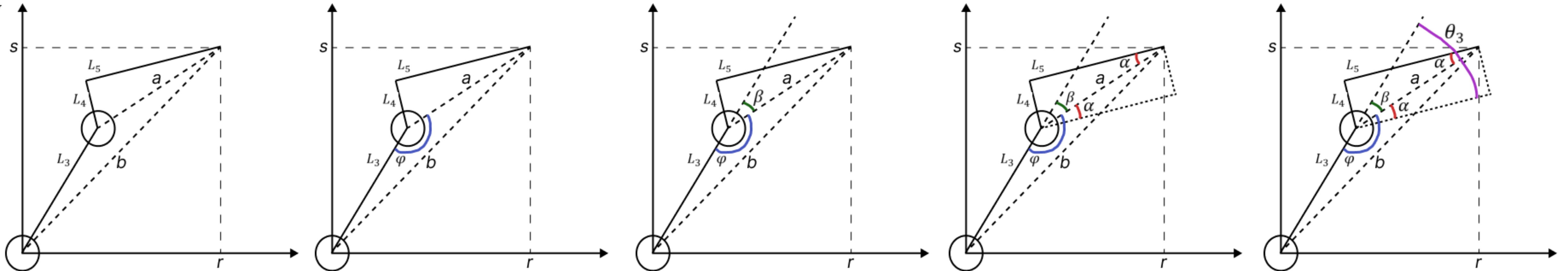
$$\varphi = \arccos(D)$$

$$\beta = 180^\circ - \varphi$$

$$\alpha = \arctg(L_4/L_5)$$

$$\theta_3 = \beta - \alpha + 90^\circ$$

II



$$a = \sqrt{L_4^2 + L_5^2}$$

$$r = \sqrt{x_c^2 + y_c^2} - L_1$$

$$s = z_c - L_2$$

$$b = \sqrt{r^2 + s^2}$$

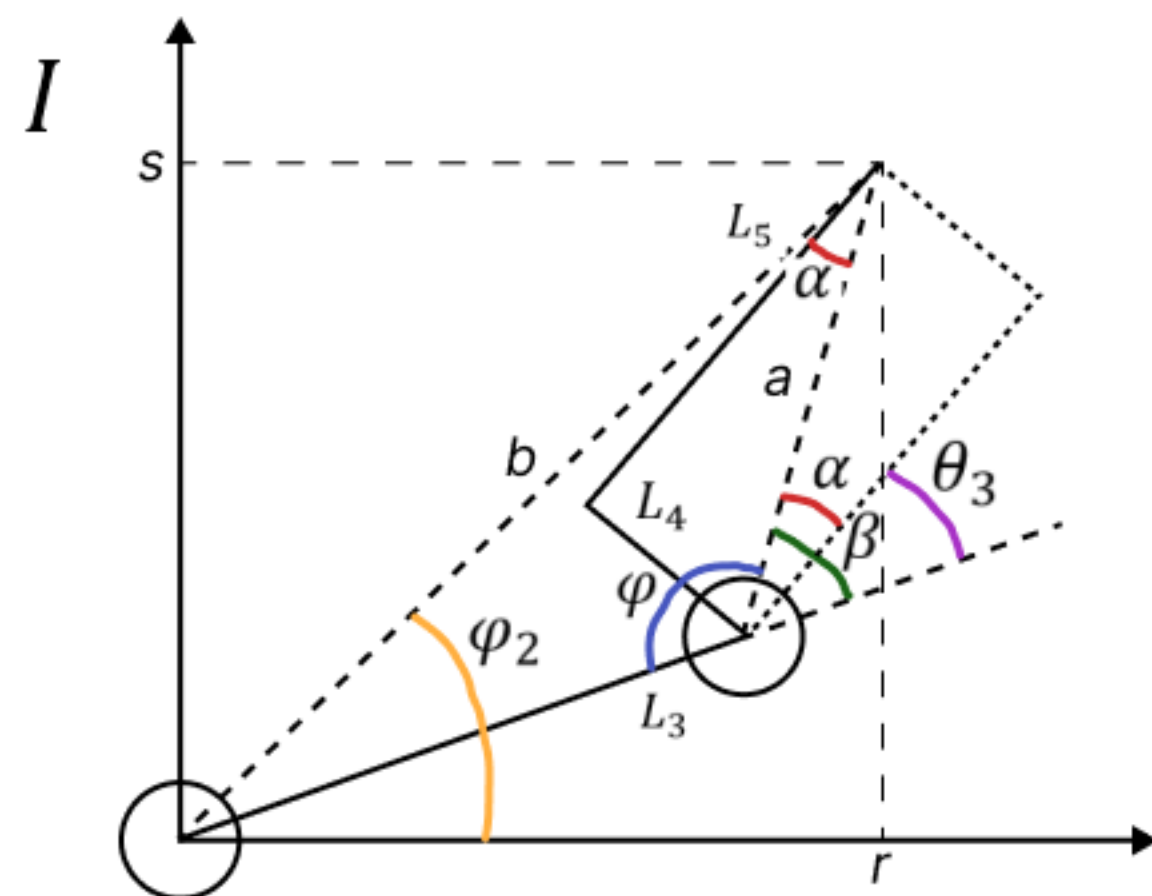
$$\cos \varphi = \frac{L_3^2 + a^2 - b^2}{2 \cdot L_3 \cdot a} = D$$

$$\varphi = \arccos(D)$$

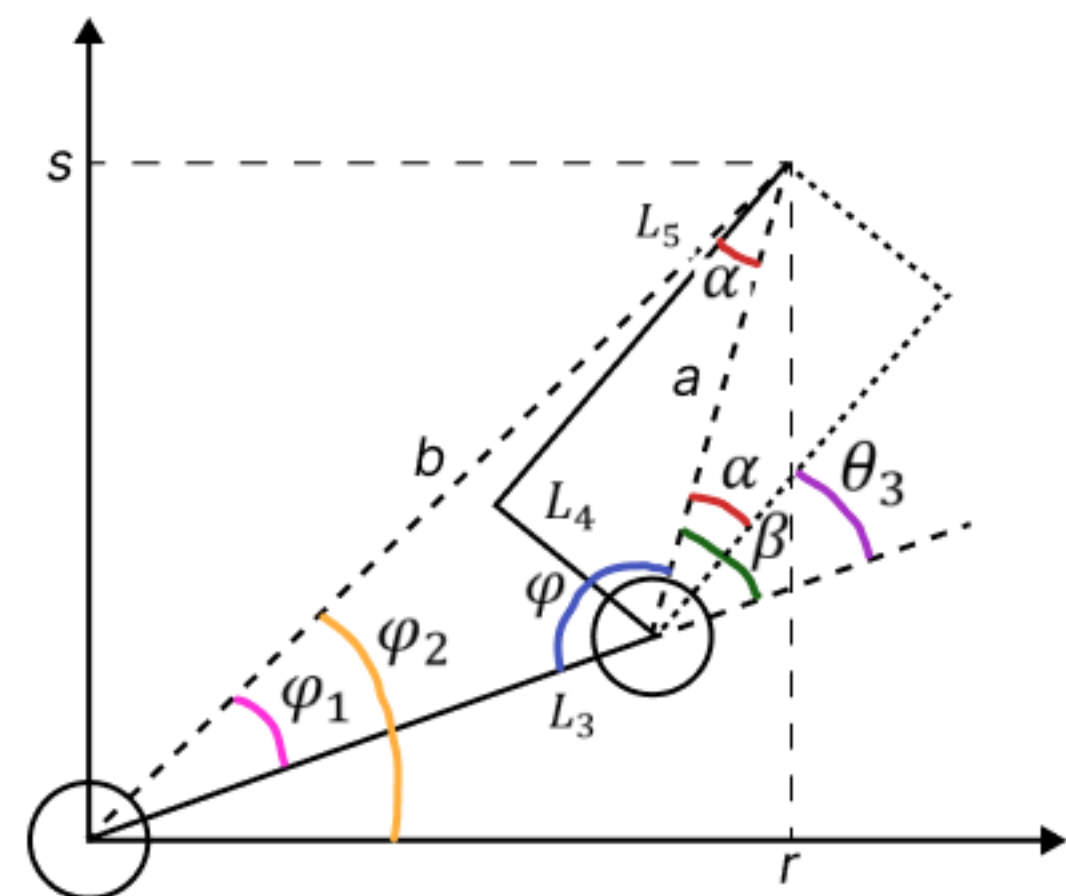
$$\beta = 180^\circ - \varphi$$

$$\alpha = \arctg(L_4/L_5)$$

$$\theta_3 = -(\beta + \alpha) + 90^\circ$$

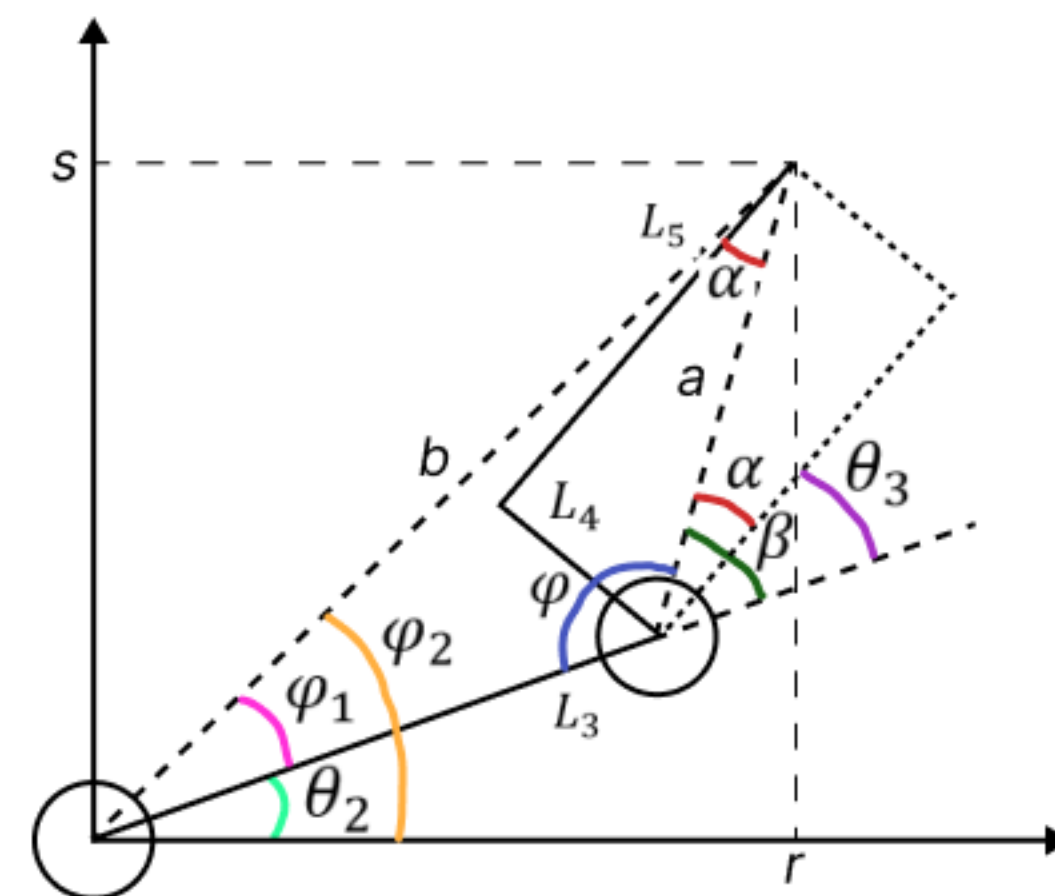


$$\varphi_2 = \arctg (s/r)$$

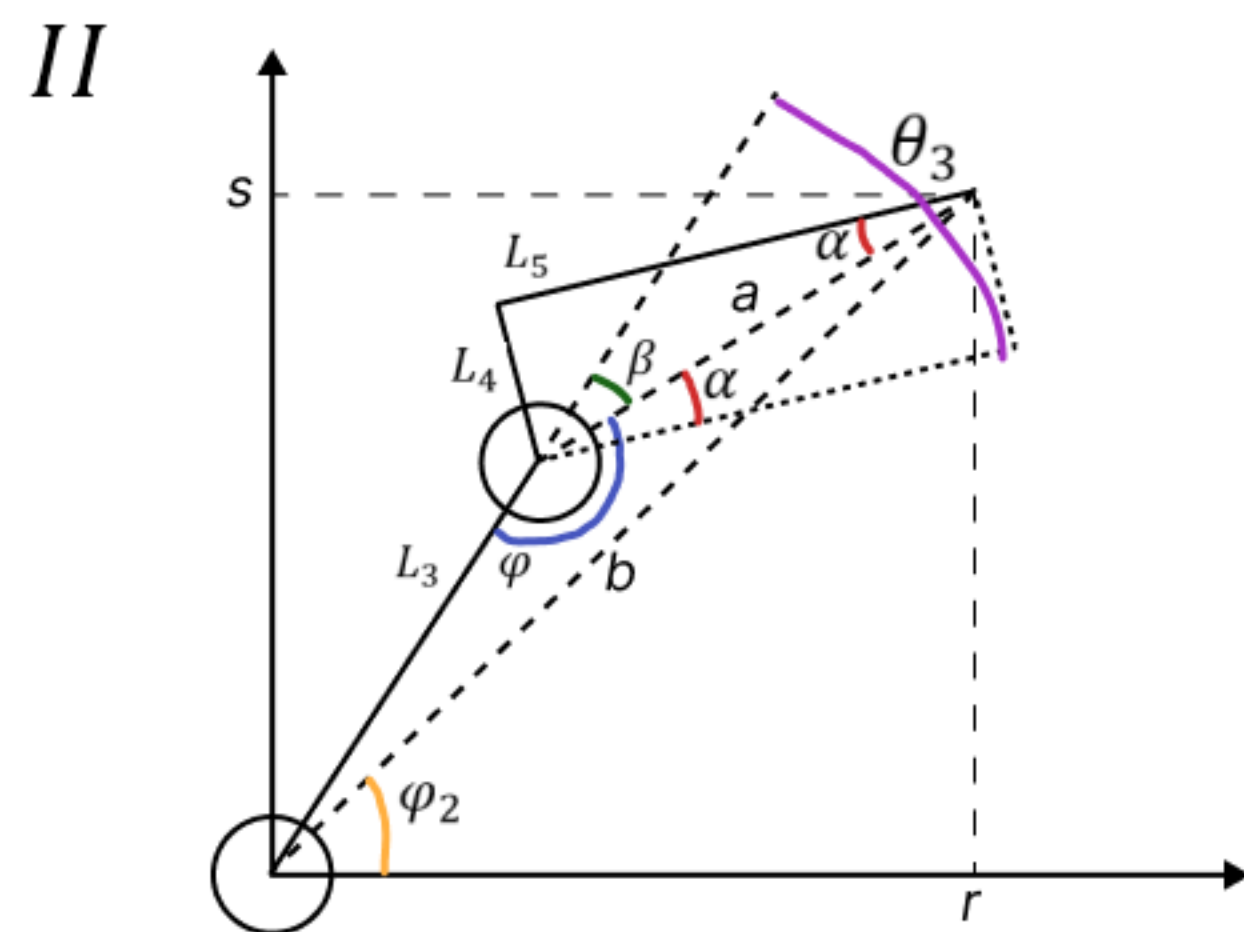


$$\cos \varphi_1 = \frac{L_3^2 + b^2 - a^2}{2 \cdot L_3 \cdot a} = D_1$$

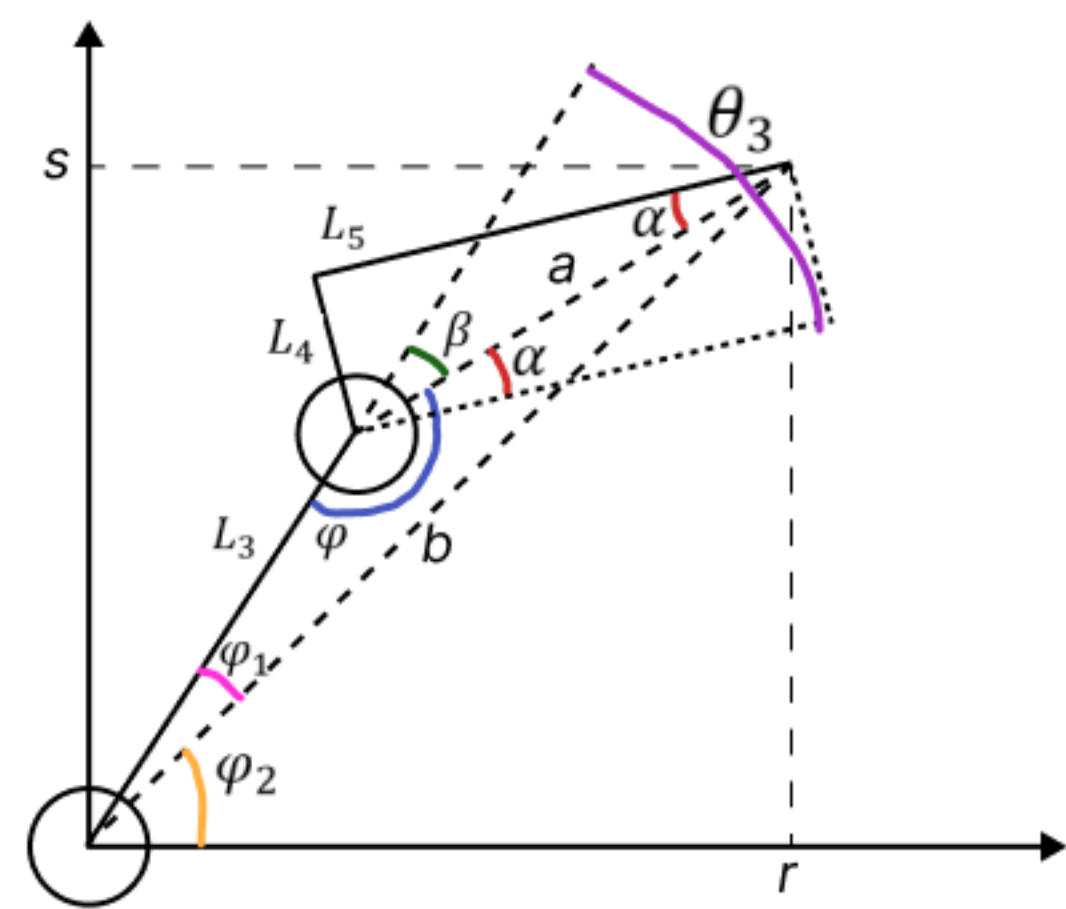
$$\varphi_1 = \arccos (D_1)$$



$$\theta_2 = \varphi_2 - \varphi_1$$

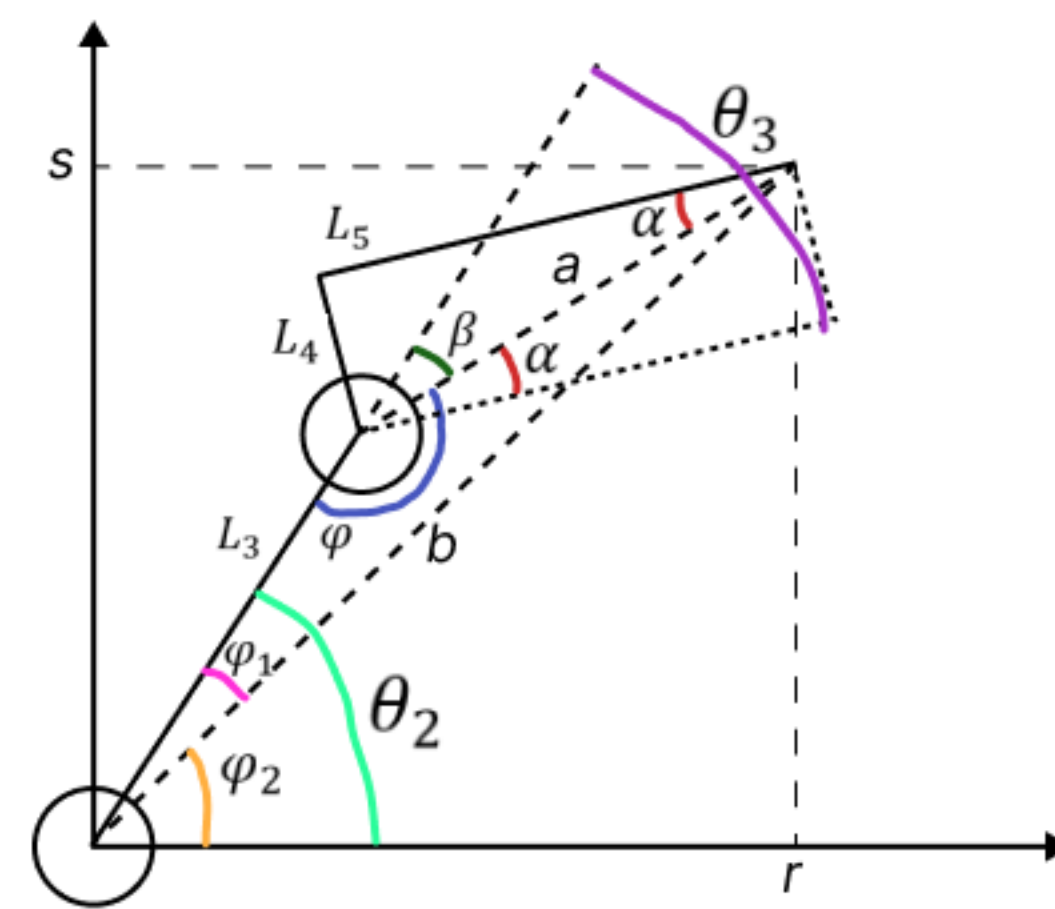


$$\varphi_2 = \arctg (s/r)$$

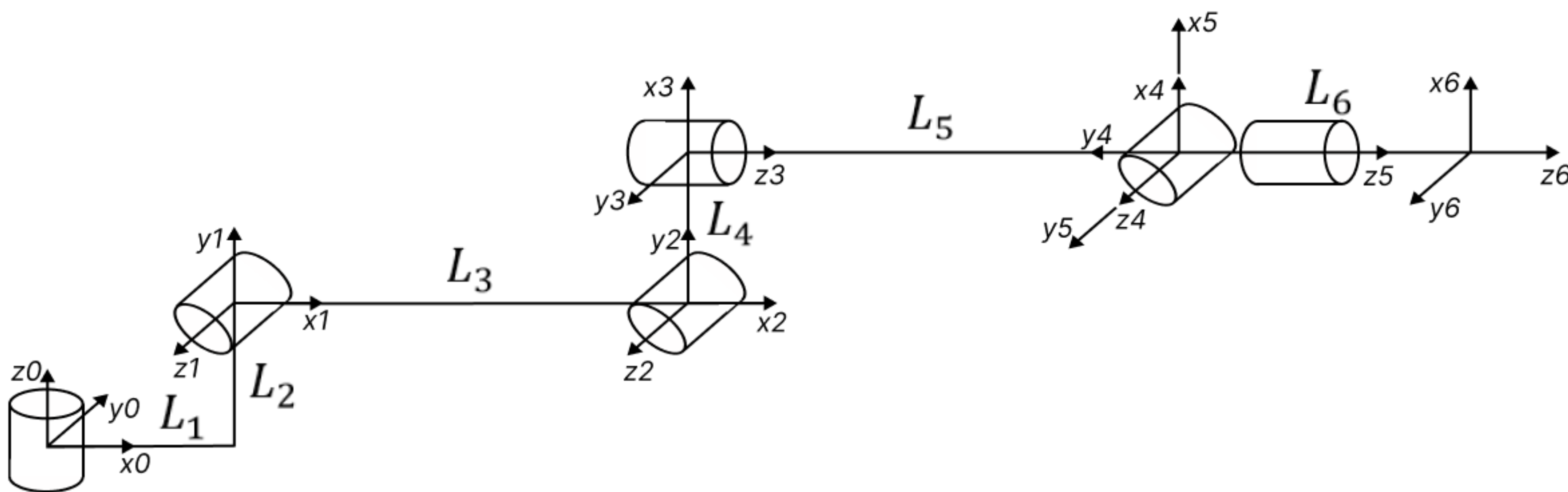


$$\cos \varphi_1 = \frac{L_3^2 + b^2 - a^2}{2 \cdot L_3 \cdot a} = D_1$$

$$\varphi_1 = \arccos (D_1)$$



$$\theta_2 = \varphi_2 + \varphi_1$$



n	θ	α	r	d
1	θ	90°	L_1	L_2
2	θ	0°	L_3	0
3	$\theta + 90^\circ$	90°	L_4	0
4	θ	270°	0	L_5
5	θ	90°	0	0
6	θ	0°	0	L_6

$$R_6^3 = \begin{bmatrix} \cos\theta_4 \cos\theta_5 \cos\theta_6 - \sin\theta_4 \sin\theta_6 & -\cos\theta_4 \cos\theta_5 \sin\theta_6 - \sin\theta_4 \cos\theta_6 & \cos\theta_4 \sin\theta_5 \\ \sin\theta_4 \cos\theta_5 \cos\theta_6 + \cos\theta_4 \sin\theta_6 & -\sin\theta_4 \cos\theta_5 \sin\theta_6 + \cos\theta_4 \cos\theta_6 & \sin\theta_4 \sin\theta_5 \\ -\sin\theta_5 \cos\theta_6 & \sin\theta_5 \sin\theta_6 & \cos\theta_5 \end{bmatrix}$$

$$\theta_4 = \arctg (R_6^3(2.3)/R_6^3(1.3))$$

$$\theta_5 = \arccos (R_6^3(3.3))$$

$$\theta_6 = \arctg (-R_6^3(3.2)/R_6^3(3.1))$$

$$R = R_3^0 \cdot R_6^3 \rightarrow R_6^3 = R \cdot (R_3^0)^T$$