

Greeks Derivations

Kylan Huang

Shared Computations

$$\begin{aligned}N'(d_1) &= \frac{\partial N(d_1)}{\partial d_1} = \frac{1}{\sqrt{2\pi}} e^{-\frac{d_1^2}{2}} \\N'(d_2) &= \frac{\partial N(d_2)}{\partial d_2} = \frac{1}{\sqrt{2\pi}} e^{-\frac{d_2^2}{2}} \\&= \frac{1}{\sqrt{2\pi}} e^{-\frac{(d_1 - \sigma\sqrt{T})^2}{2}} \\&= \frac{1}{\sqrt{2\pi}} e^{-\frac{d_1^2}{2}} \cdot e^{d_1\sigma\sqrt{T} - \frac{\sigma^2 T}{2}} \\&= N'(d_1) \cdot e^{\ln\left(\frac{S_0}{K}\right) + \left(r + \frac{\sigma^2}{2}\right)T - \frac{\sigma^2 T}{2}} \\&= N'(d_1) \cdot \frac{S_0}{K} e^{rT} \\\therefore S_0 N'(d_1) &= K e^{-rT} N'(d_2)\end{aligned}$$

1 Delta

$$\begin{aligned}
\frac{\partial d_1}{\partial S_0} &= \frac{\partial}{\partial S_0} \left(\frac{\ln \left(\frac{S_0}{K} \right) + \left(r + \frac{\sigma^2}{2} \right) T}{\sigma \sqrt{T}} \right) \\
&= \frac{1}{\frac{S_0}{K} \sigma \sqrt{T}} \cdot \frac{1}{K} \\
&= \frac{1}{S_0 \sigma \sqrt{T}} \\
\frac{\partial d_2}{\partial S_0} &= \frac{\partial}{\partial S_0} \left(d_1 - \sigma \sqrt{T} \right) \\
&= \frac{\partial d_1}{\partial S_0} \\
&= \frac{1}{S_0 \sigma \sqrt{T}}
\end{aligned}$$

They cancel out below, so technically this wasn't necessary.

$$\begin{aligned}
\Delta_C &= \frac{\partial C}{\partial S_0} \\
&= \frac{\partial}{\partial S_0} \left(S_0 N(d_1) - K e^{-rT} N(d_2) \right) \\
&= N(d_1) + S_0 \frac{\partial N(d_1)}{\partial S_0} - K e^{-rT} \frac{\partial N(d_2)}{\partial S_0} \\
&= N(d_1) + S_0 \cdot N'(d_1) \cdot \frac{\partial d_1}{\partial S_0} - K e^{-rT} N'(d_2) \cdot \frac{\partial d_2}{\partial S_0} \\
&= N(d_1) + S_0 \cdot N'(d_1) \cdot \frac{1}{S_0 \sigma \sqrt{T}} - S_0 \cdot N'(d_1) \cdot \frac{1}{S_0 \sigma \sqrt{T}} \\
&= \boxed{N(d_1)}
\end{aligned}$$

$$C + K e^{-rT} = P + S_0$$

$$\therefore \frac{\partial}{\partial S_0} (C + K e^{-rT}) = \frac{\partial}{\partial S_0} (P + S_0)$$

$$\therefore \frac{\partial C}{\partial S_0} = \frac{\partial P}{\partial S_0} + 1$$

$$\therefore \Delta_P = \frac{\partial P}{\partial S_0}$$

$$= \frac{\partial C}{\partial S_0} - 1$$

$$= \boxed{N(d_1) - 1}$$

So,

$$\Delta_C = \frac{\partial C}{\partial S_0} = N(d_1)$$

$$\Delta_P = \frac{\partial P}{\partial S_0} = N(d_1) - 1$$

2 Gamma

$$\begin{aligned}
 \Gamma &= \frac{\partial^2 C}{\partial S_0^2} \\
 &= \frac{\partial N(d_1)}{\partial S_0} \\
 &= \frac{\partial N(d_1)}{\partial d_1} \cdot \frac{\partial d_1}{\partial S_0} \\
 &= \boxed{N'(d_1) \cdot \frac{1}{S_0 \sigma \sqrt{T}}}
 \end{aligned}$$

$$\begin{aligned}
 \Gamma &= \frac{\partial^2 P}{\partial S_0^2} \\
 &= \frac{\partial}{\partial S_0} (N(d_1) - 1) \\
 &= \boxed{N'(d_1) \cdot \frac{1}{S_0 \sigma \sqrt{T}}}
 \end{aligned}$$

So,

$$\Gamma = \frac{\partial^2 C}{\partial S_0^2} = \frac{\partial^2 P}{\partial S_0^2} = N'(d_1) \cdot \frac{1}{S_0 \sigma \sqrt{T}}$$

3 Vega

$$\begin{aligned}
x &= \ln\left(\frac{S_0}{K}\right) + \left(r + \frac{\sigma^2}{2}\right)T \\
\frac{\partial d_1}{\partial \sigma} &= \frac{\partial}{\partial \sigma} \left(\frac{\ln\left(\frac{S_0}{K}\right) + \left(r + \frac{\sigma^2}{2}\right)T}{\sigma\sqrt{T}} \right) \\
&= \frac{\sigma T \cdot \sigma\sqrt{T} - x\sqrt{T}}{\sigma^2 T} \\
&= \sqrt{T} - \frac{1}{\sigma} \cdot \frac{x}{\sigma\sqrt{T}} \\
&= \sqrt{T} - \frac{d_1}{\sigma} \\
\frac{\partial d_2}{\partial \sigma} &= \frac{\partial}{\partial \sigma} (d_1 - \sigma\sqrt{T}) \\
&= \sqrt{T} - \frac{d_1}{\sigma} - \sqrt{T} \\
&= -\frac{d_1}{\sigma} \\
\frac{\partial C}{\partial \sigma} &= \frac{\partial}{\partial \sigma} (S_0 N(d_1) - K e^{-rT} N(d_2)) \\
&= S_0 \cdot \frac{\partial N(d_1)}{\partial d_1} \cdot \frac{\partial d_1}{\partial \sigma} - K e^{-rT} \frac{\partial N(d_2)}{\partial d_2} \cdot \frac{\partial d_2}{\partial \sigma} \\
&= S_0 \cdot N'(d_1) \cdot \left(-\frac{d_1}{\sigma} + \sqrt{T}\right) - K e^{-rT} N'(d_2) \cdot \left(-\frac{d_1}{\sigma}\right) \\
&= S_0 \cdot N'(d_1) \cdot \left(-\frac{d_1}{\sigma} + \sqrt{T}\right) - S_0 \cdot N'(d_1) \cdot \left(-\frac{d_1}{\sigma}\right) \\
&= \boxed{S_0 \cdot N'(d_1) \cdot \sqrt{T}} \\
C + K e^{-rT} &= P + S_0 \\
\therefore \frac{\partial}{\partial \sigma} (C + K e^{-rT}) &= \frac{\partial}{\partial \sigma} (P + S_0) \\
\therefore \frac{\partial C}{\partial \sigma} &= \frac{\partial P}{\partial \sigma} = \boxed{S_0 \cdot N'(d_1) \cdot \sqrt{T}}
\end{aligned}$$

So,

$$\nu = 1\% \cdot \frac{\partial C}{\partial \sigma} = 1\% \cdot \frac{\partial P}{\partial \sigma} = 1\% \cdot S_0 \cdot N'(d_1) \cdot \sqrt{T}$$

4 Theta

$$\begin{aligned}
x &= \ln\left(\frac{S_0}{K}\right) + \left(r + \frac{\sigma^2}{2}\right)T \\
\frac{\partial d_1}{\partial T} &= \frac{\partial}{\partial T} \left(\frac{\ln\left(\frac{S_0}{K}\right) + \left(r + \frac{\sigma^2}{2}\right)T}{\sigma\sqrt{T}} \right) \\
&= \frac{\left(r + \frac{\sigma^2}{2}\right) \cdot \sigma\sqrt{T} - \frac{\sigma}{2\sqrt{T}}x}{\sigma^2 T} \\
&= \frac{r + \frac{\sigma^2}{2}}{\sigma\sqrt{T}} - \frac{d_1}{2T} \\
\frac{\partial d_2}{\partial T} &= \frac{\partial}{\partial T} (d_1 - \sigma\sqrt{T}) \\
&= \frac{r + \frac{\sigma^2}{2}}{\sigma\sqrt{T}} - \frac{d_1}{2T} - \frac{\sigma}{2\sqrt{T}} \\
&= \frac{r}{\sigma\sqrt{T}} - \frac{d_1}{2T} \\
\frac{\partial C}{\partial T} &= \frac{\partial}{\partial T} (S_0 N(d_1) - K e^{-rT} N(d_2)) \\
&= S_0 \cdot \frac{dN(d_1)}{dd_1} \cdot \frac{dd_1}{dT} - K e^{-rT} \cdot \frac{dN(d_2)}{dd_2} \cdot \frac{dd_2}{dT} + r K e^{-rT} N(d_2) \\
&= S_0 \cdot N'(d_1) \cdot \left(\frac{r + \frac{\sigma^2}{2}}{\sigma\sqrt{T}} - \frac{d_1}{2T} \right) - K e^{-rT} \cdot N'(d_2) \cdot \left(\frac{r}{\sigma\sqrt{T}} - \frac{d_1}{2T} \right) + r K e^{-rT} N(d_2) \\
&= S_0 \cdot N'(d_1) \cdot \left(\frac{r + \frac{\sigma^2}{2}}{\sigma\sqrt{T}} - \frac{d_1}{2T} \right) - S_0 \cdot N'(d_1) \cdot \left(\frac{r}{\sigma\sqrt{T}} - \frac{d_1}{2T} \right) + r K e^{-rT} N(d_2) \\
&= \boxed{S_0 \cdot N'(d_1) \cdot \frac{\sigma}{2\sqrt{T}} + r K e^{-rT} N(d_2)} \\
C + K e^{-rT} &= P + S_0 \\
\therefore \frac{\partial}{\partial \theta} (C + K e^{-rT}) &= \frac{\partial}{\partial \theta} (P + S_0) \\
\therefore \frac{\partial C}{\partial \theta} + K e^{-rT} \cdot (-r) &= \frac{\partial P}{\partial \theta} \\
\therefore \frac{\partial P}{\partial \theta} &= S_0 \cdot N'(d_1) \cdot \frac{\sigma}{2\sqrt{T}} - r K e^{-rT} (1 - N(d_2)) \\
&= \boxed{S_0 \cdot N'(d_1) \cdot \frac{\sigma}{2\sqrt{T}} - r K e^{-rT} \cdot N(-d_2)}
\end{aligned}$$

So,

$$\theta_C = -\frac{1}{360} \cdot \frac{\partial C}{\partial T} = \frac{1}{360} \cdot \left(-S_0 \cdot N'(d_1) \cdot \frac{\sigma}{2\sqrt{T}} - rKe^{-rT}N(d_2) \right)$$

$$\theta_P = -\frac{1}{360} \cdot \frac{\partial P}{\partial T} = \frac{1}{360} \cdot \left(-S_0 \cdot N'(d_1) \cdot \frac{\sigma}{2\sqrt{T}} + rKe^{-rT} \cdot N(-d_2) \right)$$

Negative sign by convention, since YTE decreases as time passes.

5 Rho

$$\begin{aligned}
\frac{\partial d_2}{\partial r} &= \frac{\partial}{\partial r} (d_1 - \sigma\sqrt{T}) \\
&= \frac{\partial d_1}{\partial r} \\
\frac{\partial C}{\partial r} &= \frac{\partial}{\partial r} (S_0 N(d_1) - K e^{-rT} N(d_2)) \\
&= S_0 \cdot \frac{\partial N(d_1)}{\partial d_1} \cdot \frac{\partial d_1}{\partial r} + T K e^{-rT} \cdot N(d_2) - K e^{rT} \cdot \frac{\partial N(d_2)}{\partial d_2} \cdot \frac{\partial d_2}{\partial r} \\
&= S_0 \cdot N'(d_1) \cdot \frac{\partial d_1}{\partial r} + T K e^{-rT} \cdot N(d_2) - K e^{rT} \cdot N'(d_2) \cdot \frac{\partial d_2}{\partial r} \\
&= S_0 \cdot N'(d_1) \cdot \frac{\partial d_1}{\partial r} + T K e^{-rT} \cdot N(d_2) - S_0 \cdot N'(d_1) \cdot \frac{\partial d_1}{\partial r} \\
&= \boxed{T K e^{-rT} \cdot N(d_2)} \\
C + K e^{-rT} &= P + S_0 \\
\therefore \frac{\partial}{\partial r} (C + K e^{-rT}) &= \frac{\partial}{\partial r} (P + S_0) \\
\therefore \frac{\partial C}{\partial r} + K e^{-rT} \cdot (-T) &= \frac{\partial P}{\partial r} \\
\therefore \frac{\partial P}{\partial r} &= T K e^{-rT} (N(d_2) - 1) \\
&= \boxed{-T K e^{-rT} \cdot N(-d_2)}
\end{aligned}$$

So,

$$\begin{aligned}
\rho_C &= 1\% \cdot \frac{\partial C}{\partial r} = 1\% \cdot T K e^{-rT} \cdot N(d_2) \\
\rho_P &= 1\% \cdot \frac{\partial P}{\partial r} = 1\% \cdot (-T K e^{-rT} \cdot N(-d_2))
\end{aligned}$$