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The following lemma is useful.

Let  $M$  be  $n$ -dimensional Riemannian manifold. Consider the spray of the geodesics  $x^i = x^i(t, \mathbf{n})$ , (differential equation:

$$x^i(t, \tau): \begin{cases} x^i tt + \Gamma_{km}^i x_t^k x_t^m = 0 \\ x^i(t)|_{t=0} = 0 \\ x^i(t, \mathbf{n})|_{t=0} = \mathbf{n}. \end{cases} \quad \mathbf{n} \text{ is unit vector}$$

Thus we have the exponential map which assigns to every unit vector  $\mathbf{n} \in T_{\mathbf{pt}}M$ , the geodesics.

The natural question can be asked. Consider the disc of the radius  $R$ , i.e. the set of the points  $x^i(t, \mathbf{n}): t \in [0, R]$ . Does the boundary of the disc is perpendicular to the geodesics, i.e. is it true that

$$\langle x_t(t, \mathbf{n}), \delta x \rangle = 0$$

Let  $\tau_\alpha$  ( $\alpha = 1, \dots, n-1$ ) be coordinates on unit sphere  $\mathbf{n} = \mathbf{n}(\tau_\alpha)$ .

Denote

$$L = \langle \mathbf{x}_t, \mathbf{x}_\tau \rangle = g_{ij} x_t^i x_\tau^j.$$

It is evident that  $L(t, \tau)|_{t=0} = 0$  since this is scalar product of unit vector on the tangent vector to the unit sphere. Prove that it vanishes for all  $t$ .

Let  $E = \frac{1}{2}|x_t^i|^2$ . This is equal to constant. Hence

$$\begin{aligned} 0 &= \left( \frac{1}{2} g_{mn} x_t^m x_t^n \right)_\tau = \frac{1}{2} x_\tau^p \partial_p g_{mn} x_t^m x_t^n + g_{mn} x_{t\tau}^m x_t^n = \frac{1}{2} x_\tau^p \partial_p g_{mn} x_t^m x_t^n + (g_{mn} x_\tau^m x_t^n)_t = \\ &= \frac{1}{2} x_\tau^p \partial_p g_{mn} x_t^m x_t^n + L_t - x_t^r \partial_r g_{mn} x_\tau^m x_t^n - g_{mn} x_\tau^m x_{tt}^n = \end{aligned}$$

$$L_t - \frac{1}{2} (\partial_m g_{np} + \partial_n g_{mp} - \partial_p g_{mn}) x_\tau^p x_t^m x_t^n - g_{mn} x_\tau^m x_{tt}^n = L_t - g_{mn} x_\tau^m (x_{tt}^n + \Gamma_{mn}^i x_t^m x_t^n) = L_t = 0. \quad \blacksquare$$

Invariant proof.

Consider two vector fields  $\mathbf{v}, \mathbf{Y}$  which commute Then We have

$$0 = \partial_{\mathbf{Y}} \left( \frac{1}{2} \langle \mathbf{v}, \mathbf{v} \rangle \right) = \langle \nabla \mathbf{Y} \mathbf{v}, \mathbf{v} \rangle = \langle \nabla_{\mathbf{v}} \mathbf{Y}, \mathbf{v} \rangle = \partial_{\mathbf{v}} \langle \mathbf{Y}, \mathbf{v} \rangle - \langle \mathbf{Y}, \nabla_{\mathbf{v}} \mathbf{v} \rangle.$$