

Homework 9. Solutions

Almost all exercises of this homework are considered in detail in the subsection 4.2, 4.3 of the lecture notes (see the subsections: "Derivation formulae", Gauss condition (structure equations), "Geometrical meaning and Weingarten operator in terms of derivation formulae", "Gaussian and mean curvature in terms of derivation formulae".

1) Let M be a surface embedded in Euclidean space \mathbf{E}^3 . We say that the triple of vector fields $\{\mathbf{e}, \mathbf{f}, \mathbf{n}\}$ is adjusted to the surface M if $\mathbf{e}, \mathbf{f}, \mathbf{n}$ be three vector fields defined on the points of this surface such that they form an orthonormal basis at any point, so that the vectors \mathbf{e}, \mathbf{f} are tangent to the surface and the vector \mathbf{n} is orthogonal to the surface.

Consider the derivation formulae for adjusted vector fields $\{\mathbf{e}, \mathbf{f}, \mathbf{n}\}$:

$$d \begin{pmatrix} \mathbf{e} \\ \mathbf{f} \\ \mathbf{n} \end{pmatrix} = \begin{pmatrix} 0 & a & b \\ -a & 0 & c \\ -b & -c & 0 \end{pmatrix} \begin{pmatrix} \mathbf{e} \\ \mathbf{f} \\ \mathbf{n} \end{pmatrix}, \quad (1)$$

where a, b, c are 1-forms on the surface M .

Write down the explicit expression for connection, Weingarten operator, the mean curvature and the Gaussian curvature of M in terms of 1-forms a, b, c and vector fields $\{\mathbf{e}, \mathbf{f}, \mathbf{n}\}$.

Solution (see also lecture notes):

Induced connection

Let ∇ be the connection induced by the canonical flat connection on the surface M . Then according to derivation formulae for every tangent vector \mathbf{X}

$$\nabla_{\mathbf{X}} \mathbf{e} = (\partial_{\mathbf{X}} \mathbf{e})_{\text{tangent}} = (d\mathbf{e}(\mathbf{X}))_{\text{tangent}} = (a(\mathbf{X})\mathbf{f} + b(\mathbf{X})\mathbf{n})_{\text{tangent}} = a(\mathbf{X})\mathbf{f}.$$

and

$$\nabla_{\mathbf{X}} \mathbf{f} = (\partial_{\mathbf{X}} \mathbf{f})_{\text{tangent}} = (d\mathbf{f}(\mathbf{X}))_{\text{tangent}} = (-a(\mathbf{X})\mathbf{e} + c(\mathbf{X})\mathbf{n})_{\text{tangent}} = -a(\mathbf{X})\mathbf{e}.$$

In particular

$$\begin{aligned} \nabla_{\mathbf{e}} \mathbf{e} &= a(\mathbf{e})\mathbf{f} & \nabla_{\mathbf{f}} \mathbf{e} &= a(\mathbf{f})\mathbf{f} \\ \nabla_{\mathbf{e}} \mathbf{f} &= -a(\mathbf{e})\mathbf{e} & \nabla_{\mathbf{f}} \mathbf{f} &= -a(\mathbf{f})\mathbf{e} \end{aligned}$$

Weingarten operator

Let S be Weingarten operator: $S\mathbf{X} = -\partial_{\mathbf{X}} \mathbf{n}$. Then

$$S\mathbf{X} = -\partial_{\mathbf{X}} \mathbf{n} = -d\mathbf{n}(\mathbf{X}) = -(-b(\mathbf{X})\mathbf{e} - c(\mathbf{X})\mathbf{f}) = b(\mathbf{X})\mathbf{e} + c(\mathbf{X})\mathbf{f}$$

since $d\mathbf{n} = -b\mathbf{e} - c\mathbf{f}$ due to derivation formulae. In particular

$$S(\mathbf{e}) = b(\mathbf{e})\mathbf{e} + c(\mathbf{e})\mathbf{f}, S(\mathbf{f}) = b(\mathbf{f})\mathbf{e} + c(\mathbf{f})\mathbf{f}$$

and the matrix of the Weingarten operator in the basis $\{\mathbf{e}, \mathbf{f}\}$ is

$$S = \begin{pmatrix} b(\mathbf{e}) & c(\mathbf{e}) \\ b(\mathbf{f}) & c(\mathbf{f}) \end{pmatrix}$$

Curvatures We have that Gaussian curvature

$$K = \det S = \det \begin{pmatrix} b(\mathbf{e}) & c(\mathbf{e}) \\ b(\mathbf{f}) & c(\mathbf{f}) \end{pmatrix} = b(\mathbf{e})c(\mathbf{f}) - b(\mathbf{f})c(\mathbf{e}),$$

and Mean curvature

$$H = \text{Tr } S = \text{Tr} \begin{pmatrix} b(\mathbf{e}) & c(\mathbf{e}) \\ b(\mathbf{f}) & c(\mathbf{f}) \end{pmatrix} = b(\mathbf{e}) + c(\mathbf{f}),$$

Remark* Note that Gaussian curvature $K = b(\mathbf{e})c(\mathbf{f}) - b(\mathbf{f})c(\mathbf{e}) = b \wedge c(\mathbf{e}, \mathbf{f}) = da(\mathbf{e}, \mathbf{f})$ due to Gauss condition. This is very important to deduce the formula of rotation of the vector during parallel transport along the closed curve.

2*) Show that in derivation formulae $da + b \wedge c = 0$.

Solution

Recall that a, b, c are 1-forms, $\mathbf{e}, \mathbf{f}, \mathbf{n}$ are vector valued functions (0-forms) and $d\mathbf{e}, d\mathbf{f}, d\mathbf{n}$ are vector valued 1-forms. (We use the simple identity that $d\mathbf{d}\mathbf{f} = 0$ and the fact that for 1-form $\omega \wedge \omega = 0$.) We have from derivation formulae that

$$d^2\mathbf{e} = 0 = d(a\mathbf{f} + b\mathbf{n}) = da\mathbf{f} - a \wedge d\mathbf{f} + db\mathbf{n} - b \wedge d\mathbf{n} =$$

$$da\mathbf{f} - a \wedge (-a\mathbf{e} + c\mathbf{n}) + db\mathbf{n} - b \wedge (-b\mathbf{e} - c\mathbf{f}) =$$

$$(da + b \wedge c)\mathbf{f} + (a \wedge a + b \wedge b)\mathbf{e} + (db - a \wedge c)\mathbf{n} = (da + b \wedge c)\mathbf{f} + (db + c \wedge a)\mathbf{n} = 0.$$

We see that $(da + b \wedge c)\mathbf{f} + (db + c \wedge a)\mathbf{n} = 0$. Hence components of the left hand side equal to zero: $(da + b \wedge c) = 0$, $(db + c \wedge a) = 0$. In particular $da + b \wedge c = 0$ ■.

3) Find explicitly a triple of vector fields $\{\mathbf{e}, \mathbf{f}, \mathbf{n}\}$ adjusted to the surface M if M is a) cylinder, b) cone, c) sphere

Solution.

See the detailed solution of this and of the next exercise in the Lecture Notes (section 4.3).

One can consider different adjusted triples. In the Lecture Notes we just consider an example of the adjusted triple

4) Using results of the previous exercise find explicit expression for derivation formulae (1) in the case if the surface M is a) cylinder, b) cone, c) sphere

Deduce from these results the formulae for Gaussian and mean curvature for cylinder, cone and sphere

See the detailed solution of this and of the previous exercise in the lecture notes (section 4.3).

5) a) Find explicitly a triple of vector fields $\{\mathbf{e}, \mathbf{f}, \mathbf{n}\}$ adjusted to the surface M if a Riemannian metric on a surface M is given by formula $G = \sigma(u, v)(du^2 + dv^2)$.

b)†) Using derivation formulae calculate Gaussian curvature for surface given in conformal coordinates. Show that it is expressed by the formula:

$$K = -\frac{1}{2\sigma} \left(\frac{\partial^2 \sigma(u, v)}{\partial u^2} + \frac{\partial^2 \sigma(u, v)}{\partial v^2} \right).$$

Solution.

a) E.g. one may take

$$\mathbf{e} = \frac{1}{\sqrt{\sigma}} \frac{\partial}{\partial u}, \quad \mathbf{f} = \frac{1}{\sqrt{\sigma}} \frac{\partial}{\partial v}$$

and \mathbf{n} its vector product. It is evident that these vectors form orthonormal basis. Of course one may consider another examples.

See detailed calculations in Lecture Notes (section 4).