

## Homework 6. Solutions.

Here the full solution of exercise 4b) is added, which was absent due to Coursework

### Christoffel symbols and Lagrangians

1 Consider the Lagrangian of "free" particle  $L = \frac{1}{2}g_{ik}\dot{x}^i\dot{x}^k$  for Riemannian manifold with a metric  $G = g_{ik}dx^i dx^k$ .

Write down Euler-Lagrange equations of motion for this Lagrangian and compare them with differential equations for geodesics on this Riemannian manifold.

In fact show that

$$\underbrace{\frac{\partial L}{\partial x^i} = \frac{d}{dt} \frac{\partial L}{\partial \dot{x}^i}}_{\text{Euler-Lagrange equations}} \Leftrightarrow \underbrace{\frac{d^2 x^i}{dt^2} + \Gamma_{km}^i \dot{x}^k \dot{x}^m}_{\text{Equations for geodesics}} = 0, \quad (1)$$

where

$$\Gamma_{km}^i = \frac{1}{2}g^{ij} \left( \frac{\partial g_{jk}}{\partial x^m} + \frac{\partial g_{jm}}{\partial x^k} - \frac{\partial g_{km}}{\partial x^j} \right). \quad (2)$$

Solution: see the lecture notes.

2 a) Write down the Lagrangian of free particle  $L = \frac{1}{2}g_{ik}\dot{x}^i\dot{x}^k$  for Euclidean plane in polar coordinates. Calculate Christoffel symbols for canonical flat connection in polar coordinates using Euler-Lagrange equations for this Lagrangian. Compare with answers which you obtained by the direct use of the formula (2). b) Do the same for cylindrical coordinates in  $\mathbf{E}^3$ .

Solution. Canonical flat connection is Levi-Civita connection of Euclidean metric  $G = dx^2 + dy^2$ . Hence we can calculate Christoffel symbols using Lagrangian method.

Euclidean metric in polar coordinates is  $dr^2 + r^2 d\varphi^2$ . Hence the Lagrangian of the free particle is

$$L = \frac{\dot{r}^2 + r^2 \dot{\varphi}^2}{2}$$

Euler-Lagrange equations:

1) for  $r$ :

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{r}} \right) = \ddot{r} = \frac{\partial L}{\partial r} = r\dot{\varphi}^2$$

i.e.

$$\ddot{r} - r\dot{\varphi}^2 = 0 \Rightarrow \Gamma_{rr}^r = \Gamma_{\varphi r}^r = \Gamma_{r\varphi}^r = 0, \Gamma_{\varphi\varphi}^r = -r.$$

2) for  $\varphi$ :

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\varphi}} \right) = \frac{d}{dt} (r^2 \dot{\varphi}) = r^2 \ddot{\varphi} + 2r\dot{r}\dot{\varphi} = \frac{\partial L}{\partial \varphi} = 0,$$

i.e.

$$\ddot{\varphi} + \frac{2}{r}\dot{r}\dot{\varphi} = 0 \Rightarrow \Gamma_{rr}^\varphi = \Gamma_{\varphi\varphi}^\varphi = 0, \Gamma_{r\varphi}^\varphi = \Gamma_{\varphi r}^\varphi = \frac{1}{r}.$$

b) cylindrical coordinates in  $\mathbf{E}^3$ . Calculations almost the same as for polar coordinates in  $\mathbf{E}^2$ .  $G = dr^2 + r^2 d\varphi^2 + dh^2$ ,

$$L = \frac{\dot{r}^2 + r^2 \dot{\varphi}^2 + \dot{h}^2}{2}$$

for  $r$ :  $\ddot{r} - r\dot{\varphi}^2 = 0 \Rightarrow$

$$\Gamma_{rr}^r = \Gamma_{\varphi r}^r = \Gamma_{r\varphi}^r = \Gamma_{rh}^r = \Gamma_{hr}^r = \Gamma_{h\varphi}^r = \Gamma_{\varphi h}^r = \Gamma_{hh}^r = 0, \Gamma_{\varphi\varphi}^r = -r.$$

for  $\varphi$ ,  $r^2\ddot{\varphi} + 2r\dot{r}\dot{\varphi} = \frac{\partial L}{\partial \varphi} = 0$ , i.e.  $\ddot{\varphi} + \frac{2}{r}\dot{r}\dot{\varphi} = 0 \Rightarrow$

$$\Gamma_{rr}^\varphi = \Gamma_{rh}^\varphi = \Gamma_{hr}^\varphi = \Gamma_{\varphi\varphi}^\varphi = \Gamma_{\varphi h}^\varphi = \Gamma_{h\varphi}^\varphi = \Gamma_{hh}^\varphi = 0, \Gamma_{r\varphi}^\varphi = \Gamma_{\varphi r}^\varphi = \frac{1}{r}$$

3) for  $h$ ,  $\ddot{h} = 0$ ,

$$\Gamma_{rr}^h = \Gamma_{r\varphi}^h = \Gamma_{\varphi r}^h = \Gamma_{rh}^h = \Gamma_{hr}^h = \Gamma_{\varphi\varphi}^h = \Gamma_{\varphi h}^h = \Gamma_{h\varphi}^h = \Gamma_{hh}^h = 0,$$

### 3

Calculate Christoffel symbols of Levi-Civita connection for Riemannian metric  $G = a du^2 + b dv^2$ . Compare with results of the Exercise 1b) in the Homework 5.

Lagrangian of free particle for this metric is

$$L = \frac{a(u,v)\dot{u}^2 + b(u,v)\dot{v}^2}{2}.$$

Euler-lagrange equations

for  $u$ :

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{u}} \right) = \frac{d}{dt}(a\dot{u}) = a_u \dot{u}^2 + a_v \dot{v}\dot{u} + a\ddot{u} = \frac{\partial L}{\partial u} = \frac{a_u \dot{u}^2 + b_u \dot{v}^2}{2}$$

hence

$$\ddot{u} + \frac{1}{2} \frac{a_u}{a} \dot{u}^2 + \frac{a_v}{a} \dot{v}\dot{u} - \frac{1}{2} \frac{b_u}{a} \dot{v}^2$$

Comparing with equation

$$\ddot{u} + \Gamma_{uu}^u \dot{u}\dot{u} + \Gamma_{uv}^u \dot{u}\dot{v} + \Gamma_{vu}^u \dot{v}\dot{u} + \Gamma_{vv}^u \dot{v}\dot{v} + \Gamma_{uu}^u \ddot{u} + 2\Gamma_{uv}^u \dot{u}\dot{v} + \Gamma_{vv}^u \dot{v}\dot{v} = 0$$

we see that

$$\Gamma_{uu}^u = \frac{1}{2} \frac{a_u}{a}, \Gamma_{uv}^u = \Gamma_{vu}^u = \frac{1}{2} \frac{a_v}{a}, \Gamma_{vv}^u = -\frac{1}{2} \frac{b_u}{a},$$

Analogously  $v$ :

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{v}} \right) = \frac{d}{dt}(b\dot{v}) = b_v \dot{v}^2 + b_u \dot{u}\dot{v} + b\ddot{v} = \frac{\partial L}{\partial v} = \frac{a_v \dot{u}^2 + b_v \dot{v}^2}{2}$$

hence

$$\ddot{v} + \frac{1}{2} \frac{b_v}{b} \dot{v}^2 + \frac{b_u}{b} \dot{u}\dot{v} - \frac{1}{2} \frac{a_v}{b} \dot{u}^2 \Rightarrow \Gamma_{vv}^v = \frac{1}{2} \frac{b_v}{b}, \Gamma_{vu}^v = \Gamma_{uv}^v = \frac{1}{2} \frac{b_u}{b}, \Gamma_{uu}^v = -\frac{1}{2} \frac{a_v}{b}.$$

### 4

Write down the Lagrangian of free particle  $L = \frac{1}{2} g_{ik} \dot{x}^i \dot{x}^k$  and using Euler-Lagrange equations for this Lagrangian calculate Christoffel symbols (Christoffel symbols of Levi-Civita connection) for

- cylindrical surface of the radius  $R$
- for the cone  $x^2 + y^2 - k^2 z^2 = 0$
- for the sphere of radius  $R$
- for Lobachevsky plane

Compare with the results that you obtained using straightforwardly the formula (1) or using formulae for induced connection.

Solution.

For cylindrical surface of the radius  $a$ :  $x^2 + y^2 = a^2$   $\mathbf{r}(h, \varphi) = \begin{cases} x = a \cos \varphi \\ y = a \sin \varphi \\ z = h \end{cases}$  we have that induced metric is  $G = dh^2 + a^2 d\varphi^2$  and the Lagrangian of free particle is

$$L = \frac{a^2 \dot{\varphi}^2 + \dot{h}^2}{2}$$

for  $\varphi$ , Euler-Lagrange equations of motion:

$$\frac{\partial L}{\partial \varphi} = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\varphi}} \right) \cdot \quad \frac{\partial L}{\partial \varphi} = 0, \quad \frac{\partial L}{\partial \dot{\varphi}} = a^2 \dot{\varphi}$$

hence

$$\frac{d}{dt} (a^2 \dot{\varphi}) = a^2 \ddot{\varphi} = 0, \quad \ddot{\varphi} = 0.$$

Hence all Christoffel symbols  $\Gamma_{\varphi\varphi}^\varphi, \Gamma_{\varphi h}^\varphi, \Gamma_{h\varphi}^\varphi$  vanish:

$$\Gamma_{\varphi\varphi}^\varphi = 0, \Gamma_{\varphi h}^\varphi = \Gamma_{h\varphi}^\varphi = 0$$

for  $h$ , we have the same. Euler-Lagrange equations of motion::

$$\frac{\partial L}{\partial h} = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{h}} \right) \cdot \quad \frac{\partial L}{\partial h} = 0, \quad \frac{\partial L}{\partial \dot{h}} = \dot{h}$$

hence

$$\frac{d}{dt} (\dot{h}) = \ddot{h} = 0,$$

Hence all Christoffel symbols  $\Gamma_{\varphi\varphi}^h, \Gamma_{\varphi h}^h, \Gamma_{h\varphi}^h$  vanish:

$$\Gamma_{\varphi\varphi}^h = 0, \Gamma_{\varphi h}^h = \Gamma_{h\varphi}^h = 0$$

We see that on cylindrical surface in coordinates  $h, \varphi$  all Christoffel symbols vanish: this is not surprising, since Riemannian metric  $dh^2 + a^2 d\varphi^2$  has constant coefficients.

For cone:  $x^2 + y^2 = k^2 z^2$  we have  $\mathbf{r}(h, \varphi) = \begin{cases} x = kh \cos \varphi \\ y = kh \sin \varphi \\ z = h \end{cases}$  and induced metric is  $G = (k^2 + 1)dh^2 + k^2 h^2 d\varphi^2$  (see previous Homeworks) and the Lagrangian of free particle is

$$L = \frac{k^2 h^2 \dot{\varphi}^2 + (k^2 + 1) \dot{h}^2}{2}$$

for  $\varphi$ , Euler-Lagrange equations of motion:

The full solution will appear after coursework.

Here it is

For cone:  $x^2 + y^2 = k^2 z^2$  we have  $\mathbf{r}(h, \varphi) = \begin{cases} x = kh \cos \varphi \\ y = kh \sin \varphi \\ z = h \end{cases}$

$$\frac{\partial}{\partial h} = \mathbf{r}_h = \begin{pmatrix} k \cos \varphi \\ k \sin \varphi \\ 1 \end{pmatrix}, \quad \frac{\partial}{\partial \varphi} = \mathbf{r}_\varphi = \begin{pmatrix} -kh \sin \varphi \\ kh \cos \varphi \\ 0 \end{pmatrix}, \quad \mathbf{n} = \frac{1}{\sqrt{1+k^2}} \begin{pmatrix} \cos \varphi \\ \sin \varphi \\ -k \end{pmatrix}$$

We have  $\mathbf{r}_{hh} = 0$ , hence  $\nabla_{\partial_h} \partial_h = 0$ . i.e.  $\Gamma_{hh}^h = \Gamma_{hh}^\varphi = 0$ .

We have that  $\mathbf{r}_{h\varphi} = \mathbf{r}_{\varphi h} = \begin{pmatrix} -k \sin \varphi \\ k \cos \varphi \\ 0 \end{pmatrix} = \frac{\mathbf{r}_\varphi}{h}$ , i.e.  $\nabla_{\partial_h} \partial_\varphi = \nabla_{\partial_\varphi} \partial_h = \frac{\mathbf{r}_\varphi}{h}$ :

$$\Gamma_{h\varphi}^\varphi = \Gamma_{\varphi h}^\varphi = \frac{1}{h}, \quad \Gamma_{h\varphi}^h = \Gamma_{\varphi h}^h.$$

Now calculate  $\mathbf{r}_{\varphi\varphi}$ :  $\mathbf{r}_{\varphi\varphi} = \begin{pmatrix} -kh \cos \varphi \\ -kh \sin \varphi \\ 0 \end{pmatrix}$ . This vector is neither tangent to the cone nor orthogonal to the cone:  $0 \neq \langle \mathbf{r}_{\varphi\varphi}, \mathbf{n} \rangle = -\frac{kh}{\sqrt{1+k^2}}$ . Hence we have to consider its decomposition:

$$\mathbf{r}_{\varphi\varphi} = \underbrace{\mathbf{r}_{\varphi\varphi} - \langle \mathbf{r}_{\varphi\varphi}, \mathbf{n} \rangle \mathbf{n}}_{\text{tangent component}} + \underbrace{\langle \mathbf{r}_{\varphi\varphi}, \mathbf{n} \rangle \mathbf{n}}_{\text{orthogonal component}}$$

Hence we have

$$\begin{aligned} \nabla_\varphi \partial_\varphi &= (\mathbf{r}_{\varphi\varphi})_{\text{tangent}} = \mathbf{r}_{\varphi\varphi} - \langle \mathbf{r}_{\varphi\varphi}, \mathbf{n} \rangle \mathbf{n} = \mathbf{r}_{\varphi\varphi} + \frac{kh}{\sqrt{1+k^2}} \mathbf{n} = \\ &= \begin{pmatrix} -kh \cos \varphi \\ -kh \sin \varphi \\ 0 \end{pmatrix} + \frac{kh}{1+k^2} \begin{pmatrix} \cos \varphi \\ \sin \varphi \\ -k \end{pmatrix} = -\frac{hk^2}{1+k^2} \begin{pmatrix} k \cos \varphi \\ k \sin \varphi \\ 1 \end{pmatrix} = -\frac{hk^2}{1+k^2} \mathbf{r}_h, \end{aligned}$$

i.e.

$$\Gamma_{\varphi\varphi}^h = -\frac{hk^2}{1+k^2}, \quad \Gamma_{\varphi\varphi}^\varphi = 0.$$

Calculations for Levi-Civita connection using metric see in Lecture Notes.

Calculate Christoffel symbols using equations of motion of Lagrangian of free particle:

For cone:  $x^2 + y^2 = k^2 z^2$  we have  $\mathbf{r}(h, \varphi) = \begin{cases} x = kh \cos \varphi \\ y = kh \sin \varphi \\ z = h \end{cases}$  and induced metric is  $G = (k^2 + 1)dh^2 + k^2 h^2 d\varphi^2$  (see previous Homeworks) and the Lagrangian of free particle is

$$L = \frac{k^2 h^2 \dot{\varphi}^2 + (k^2 + 1)^2 \dot{h}^2}{2}$$

for  $\varphi$ , Euler-Lagrange equations of motion:

$$\frac{\partial L}{\partial \varphi} = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\varphi}} \right), \quad \frac{\partial L}{\partial \varphi} = 0, \quad \frac{\partial L}{\partial \dot{\varphi}} = k^2 h^2 \dot{\varphi}$$

hence

$$\frac{d}{dt} (k^2 h^2 \dot{\varphi}) = k^2 h^2 \ddot{\varphi} + 2k^2 h \dot{h} \dot{\varphi} = 0,$$

i.e.

$$\ddot{\varphi} + \frac{2}{h} \dot{h} \dot{\varphi} = 0,$$

i.e. for Christoffel symbols  $\Gamma_{\dots}^\varphi$  we have:

$$\Gamma_{\varphi h}^\varphi = \Gamma_{h\varphi}^\varphi = \frac{1}{h}$$

and  $\Gamma_{\varphi\varphi}^\varphi, \Gamma_{hh}^\varphi$  vanish.

For  $h$ , we have Euler-Lagrange equations of motion::

$$\frac{\partial L}{\partial h} = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{h}} \right), \quad \frac{\partial L}{\partial h} = k^2 h \dot{\varphi}^2, \quad \frac{\partial L}{\partial \dot{h}} = (k^2 + 1) \dot{h},$$

hence

$$\frac{d}{dt} \left( (k^2 + 1) \dot{h} \right) = (k^2 + 1) \ddot{h} = k^2 h \dot{\varphi}^2, \text{ i.e. } \ddot{h} = \frac{k^2 h}{k^2 + 1} \dot{\varphi}^2$$

Hence we have that  $\Gamma_{\varphi\varphi}^h = -\frac{k^2 h}{k^2 + 1}$  and  $\Gamma_{\varphi h}^h = \Gamma_{h\varphi}^h = \Gamma_{hh}^h = 0$ .

c) *For the sphere:*

Riemannian metric on sphere in spherical coordinates is  $G = R^2 d\theta^2 + R^2 \sin^2 \theta d\varphi^2$ . Hence the Lagrangian of the free particle is

$$L = \frac{R^2 \dot{\theta}^2 + R^2 \sin^2 \theta \dot{\varphi}^2}{2}$$

Euler-Lagrange equations for  $\theta$ :

$$\frac{\partial L}{\partial \theta} = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\theta}} \right), \quad \frac{\partial L}{\partial \theta} = R^2 \sin \theta \cos \theta \dot{\varphi}^2, \quad \frac{\partial L}{\partial \dot{\theta}} = R^2 \dot{\theta}$$

Hence

$$\frac{d}{dt} (R^2 \dot{\theta}) = R^2 \sin \theta \cos \theta \dot{\varphi}^2, \quad R^2 \ddot{\theta} = R^2 \sin \theta \cos \theta \dot{\varphi}^2,$$

hence

$$\ddot{\theta} - \sin \theta \cos \theta \dot{\varphi}^2 = 0.$$

Comparing with equation for geodesic

$$\ddot{\theta} + \Gamma_{\theta\theta}^{\theta} \dot{\theta} \dot{\theta} + \Gamma_{\theta\varphi}^{\theta} \dot{\theta} \dot{\varphi} + \Gamma_{\varphi\theta}^{\theta} \dot{\varphi} \dot{\theta} + \Gamma_{\varphi\varphi}^{\theta} \dot{\varphi} \dot{\varphi} = \ddot{\theta} + \Gamma_{\theta\theta}^{\theta} \dot{\theta} \dot{\theta} + 2\Gamma_{\theta\varphi}^{\theta} \dot{\theta} \dot{\varphi} + \Gamma_{\varphi\varphi}^{\theta} \dot{\varphi} \dot{\varphi} = 0$$

we see that

$$\Gamma_{\theta\theta}^{\theta} = \Gamma_{\theta\varphi}^{\theta} = \Gamma_{\varphi\theta}^{\theta} = 0, \quad \Gamma_{\varphi\varphi}^{\theta} = -\sin \theta \cos \theta$$

Analogously Euler-Lagrange equations for  $\varphi$ :

$$\frac{\partial L}{\partial \varphi} = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\varphi}} \right), \quad \frac{\partial L}{\partial \varphi} = 0, \quad \frac{\partial L}{\partial \dot{\varphi}} = R^2 \sin^2 \theta \dot{\varphi}.$$

Hence

$$\frac{d}{dt} (R^2 \sin^2 \theta \dot{\varphi}) = 0, \quad R^2 \sin^2 \theta \ddot{\varphi} + 2R^2 \sin \theta \cos \theta \dot{\theta} \dot{\varphi} = 0,$$

hence

$$\ddot{\theta} + \cotan \theta \dot{\theta} \dot{\varphi} = 0,$$

Comparing with equation for geodesic

$$\ddot{\varphi} + \Gamma_{\theta\theta}^{\varphi} \dot{\theta} \dot{\theta} + \Gamma_{\theta\varphi}^{\varphi} \dot{\theta} \dot{\varphi} + \Gamma_{\varphi\theta}^{\varphi} \dot{\varphi} \dot{\theta} + \Gamma_{\varphi\varphi}^{\varphi} \dot{\varphi} \dot{\varphi} = \ddot{\varphi} + \Gamma_{\theta\theta}^{\varphi} \dot{\theta} \dot{\theta} + 2\Gamma_{\theta\varphi}^{\varphi} \dot{\theta} \dot{\varphi} + \Gamma_{\varphi\varphi}^{\varphi} \dot{\varphi} \dot{\varphi} = 0$$

we see that

$$\Gamma_{\theta\theta}^{\varphi} = \Gamma_{\varphi\varphi}^{\varphi} = 0, \quad \Gamma_{\varphi\theta}^{\varphi} = \Gamma_{\theta\varphi}^{\varphi} = \cotan \theta.$$

d) *For Lobachevsky plane:*

Lagrangian of "free" particle on the Lobachevsky plane with metric  $G = \frac{dx^2 + dy^2}{y^2}$  is

$$L = \frac{1}{2} \frac{\dot{x}^2 + \dot{y}^2}{y^2}.$$

Euler-Lagrange equations are

$$\frac{\partial L}{\partial x} = 0 = \frac{d}{dt} \frac{\partial L}{\partial \dot{x}} = \frac{d}{dt} \left( \frac{\dot{x}}{y^2} \right) = \frac{\ddot{x}}{y^2} - \frac{2\dot{x}\dot{y}}{y^3}, \text{ i.e. } \ddot{x} - \frac{2\dot{x}\dot{y}}{y} = 0,$$

$$\frac{\partial L}{\partial y} = -\frac{\dot{x}^2 + \dot{y}^2}{y^3} = \frac{d}{dt} \frac{\partial L}{\partial \dot{y}} = \frac{d}{dt} \left( \frac{\dot{y}}{y^2} \right) = \frac{\ddot{y}}{y^2} - \frac{2\dot{y}^2}{y^3}, \text{ i.e. } \ddot{y} + \frac{\dot{x}^2}{y} - \frac{\dot{y}^2}{y} = 0.$$

Comparing these equations with equations for geodesics:  $\ddot{x}^i - \dot{x}^k \Gamma_{km}^i \dot{x}^m = 0$  ( $i = 1, 2$ ,  $x = x^1, y = x^2$ ) we come to

$$\Gamma_{xx}^x = 0, \Gamma_{xy}^x = \Gamma_{yx}^x = -\frac{1}{y}, \Gamma_{yy}^x = 0, \Gamma_{xx}^y = \frac{1}{y}, \Gamma_{xy}^y = \Gamma_{yx}^y = 0, \Gamma_{yy}^y = -\frac{1}{y}. \blacksquare$$

The answers are the same as calculated with other methods. We see that Lagrangians give us the nice and quick way to calculate Christoffel symbols.

5 Consider the following magnitudes:

$$\text{a) } I_{\text{cylindr}}(t) = \dot{h}(t), \quad I'_{\text{cylindr}}(t) = \dot{\varphi}(t), \quad \text{for cylindre } \begin{cases} x = a \cos \varphi \\ y = a \sin \varphi \\ z = h \end{cases},$$

$$\text{b) } I_{\text{cone}}(t) = h^2(t) \dot{\varphi}(t), \quad \text{for cone } \begin{cases} x = kh \cos \varphi \\ y = kh \sin \varphi \\ z = h \end{cases},$$

$$\text{c) } I_{\text{sphere}}(t) = \sin^2 \theta(t) \dot{\varphi}(t), \quad \text{for sphere } \begin{cases} x = R \sin \theta \cos \varphi \\ y = R \sin \theta \sin \varphi \\ z = R \cos \theta \end{cases},$$

$$\text{d) } I_{\text{Lob.}}(t) = \frac{\dot{x}(t)}{y^2(t)}, \text{ for the Lobachevsky plane (metric } G = \frac{dx^2 + dy^2}{y^2} \text{)}.$$

Show that these magnitudes are preserved along the corresponding geodesics. (You may use the Lagrangians from the previous exercise.)

a) Let  $C: h(t), \varphi(t)$  be an arbitrary geodesic on cylindre.

The Lagrangian of a free particle on cylindre is  $L = \frac{a^2 \dot{\varphi}^2 + \dot{h}^2}{2}$ .

The Lagrangian  $L$  does not depend explicitly on  $h$  hence the magnitude  $\dot{h} = \frac{\partial L}{\partial h}$  is preserved on geodesic.

In detail:

$$\frac{dI}{dt} = \frac{d}{dt} (\dot{h}) \Big|_{\text{on equat. of motion}} = 0$$

since on equation of motion

$$\frac{d}{dt} (\dot{h}) = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{h}} \right) = \frac{\partial L}{\partial h} = 0.$$

We see that  $\dot{h}$  is preserved on the geodesic.

The Lagrangian  $L$  does not depend explicitly on  $\varphi$  also, and the magnitude  $a\dot{\varphi} = \frac{\partial L}{\partial \varphi}$  is preserved along geodesic. In detail:

$$\frac{dI}{dt} = \frac{d}{dt} (a\dot{\varphi}) \Big|_{\text{on equat. of motion}} = 0$$

since on equation of motion

$$\frac{d}{dt} (a\dot{\varphi}) = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\varphi}} \right) = \frac{\partial L}{\partial \varphi} = 0.$$

We see that  $a\dot{\varphi}$  is preserved on the geodesic, hence  $\dot{\varphi}$  is preserved also.

b) Let  $C: h(t), \varphi(t)$  be an arbitrary geodesic on the cone  $x = kh \cos \varphi, y = kh \sin \varphi, z = h$ .

The Lagrangian of a free particle on the cone is  $L = \frac{(k^2+1)h^2+k^2\dot{\varphi}^2}{2}$ .

The Lagrangian  $L$  does not depend explicitly on  $h$  and the magnitude  $k^2h^2\dot{\varphi} = \frac{\partial L}{\partial \dot{\varphi}}$  is an integral of motion and it is preserving along geodesics. In detail:

$$\frac{dI}{dt} = \frac{d}{dt} (k^2h^2\dot{\varphi}) \big|_{\text{on equat. of motion}} = 0$$

since on equation of motion

$$\frac{d}{dt} (k^2h^2\dot{\varphi}) = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\varphi}} \right) = \frac{\partial L}{\partial \varphi} = 0.$$

We see that the magnitude  $k^2h^2\dot{\varphi}$  is preserved on the geodesic hence  $I(t) = h^2(t)\dot{\varphi}(t)$  is preserved also.

c) Let  $C: x(t), y(t)$  be an arbitrary geodesic on the Lobachevsky plane.

The Lagrangian of a free particle on the Lobachevsky plane is  $L = \frac{\dot{x}^2 + \dot{y}^2}{2y^2}$ .

The Lagrangian  $L$  does not depend explicitly on  $x$  and the magnitude  $I = \frac{\dot{x}}{y^2} = \frac{\partial L}{\partial \dot{x}}$  is an integral of motion and it is preserving along geodesics. In detail:

$$\frac{dI}{dt} = \frac{d}{dt} \left( \frac{\dot{x}}{y^2} \right) \big|_{\text{on equat. of motion}} = 0$$

since on equation of motion

$$\frac{d}{dt} \left( \frac{\dot{x}}{y^2} \right) = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{x}} \right) = \frac{\partial L}{\partial x} = 0.$$

We see that the magnitude  $I = \frac{\dot{x}}{y^2}$  is preserved along the geodesic on Lobachevsky plane.