

### Example of two spinors—rotation

orthogonal transformation corresponding to vectors are rotations on angle  $\pi$ . Transformation corresponding to the product of vectors in Clifford algebra looks in  $\mathbf{E}^3$  as a rotation on the angle  $2\varphi$  around the axis which is orthogonal to these vectors. In the case if dimension is higher than 3, still this has a meaning.

In the previous blog we considered the group *pin* generated by product of vectors of  $V$ .

For every vector unit  $\mathbf{v} \in V$

$$\mathbf{v}\mathbf{x}\mathbf{v}^{-1} = L_{\mathbf{v}}(\mathbf{x}) = 2(\mathbf{v}, \mathbf{x})\mathbf{v} - \mathbf{x},$$

where  $Q(\mathbf{x}) = (\mathbf{x}, \mathbf{x})$  is quadratic form, which defines Clifford algebra.

The transformation  $L_{\mathbf{v}}$  has axis directed along vector  $\mathbf{v}$  and all the vectors orthogonal to  $\mathbf{v}$  it rotates on the angle  $\pi$

Consider the action of two rotations of this type: let  $\mathbf{v}_1, \mathbf{v}_2$  be two unit vectors, we calculate

$$\mathbf{v}_1\mathbf{v}_2\mathbf{x}\mathbf{v}_2^{-1}\mathbf{v}_1^{-1} = P(\mathbf{x})$$

Consider how looks operator  $P$  first in  $\mathbf{E}^3$

**Theorem** The rotation  $P_{\mathbf{v}_1\mathbf{v}_2} = L_{\mathbf{v}_1}L_{\mathbf{v}_2}$  in  $\mathbf{E}^3$  this is the element of the group *Spin* (*Spin* contains even elements of the group *pin*)

$P_{\mathbf{v}_1\mathbf{v}_2}$  rotates the space around axis which is orthogonal to the plane  $\mathbf{v}_1, \mathbf{v}_2$  on the angle  $2\varphi$ , where  $\varphi$  is the angle between vectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$ . which is orthogonal to the plane

Choose orthonormal basis  $\{\mathbf{e}, \mathbf{f}, \mathbf{g}\}$  such that  $\mathbf{e}$  is directed along  $\mathbf{v}_1$ , and vector  $\mathbf{g}$  is orthogonal to plane formed by vectors  $\mathbf{v}_1, \mathbf{v}_2$ . Then

$$L_{\mathbf{v}_1}: \begin{cases} L_{\mathbf{v}_1}(\mathbf{e}) = \mathbf{e} \\ L_{\mathbf{v}_1}(\mathbf{f}) = -\mathbf{f} \\ L_{\mathbf{v}_1}(\mathbf{g}) = -\mathbf{g} \end{cases}$$

Now consider the second rotation. It is around the vector  $\mathbf{e}' = \mathbf{v}_2$ , The corresponding basis  $\{\mathbf{e}', \mathbf{f}', \mathbf{g}'\}$ , where

$$\begin{cases} \mathbf{e}' = \cos \varphi \mathbf{e} + \sin \varphi \mathbf{f}, \\ \mathbf{f}' = -\sin \varphi \mathbf{e} + \cos \varphi \mathbf{f}, \\ \mathbf{g}' = \mathbf{g}. \end{cases} \Leftrightarrow \begin{cases} \mathbf{e} = \cos \varphi \mathbf{e}' - \sin \varphi \mathbf{f}', \\ \mathbf{f} = \sin \varphi \mathbf{e}' + \cos \varphi \mathbf{f}', \\ \mathbf{g} = \mathbf{g}'. \end{cases}$$

For the second rotation we have

$$L_{\mathbf{v}_2}: \begin{cases} L_{\mathbf{v}_2}(\mathbf{e}') = \mathbf{e}' \\ L_{\mathbf{v}_2}(\mathbf{f}') = -\mathbf{f}' \\ L_{\mathbf{v}_2}(\mathbf{g}') = -\mathbf{g}' \end{cases}$$

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These elements form subspace in the orthogonal group (see Etude about fantom peines....)

Thus we have

$$P = P_{\mathbf{v}_1 \mathbf{v}_2} = L_{\mathbf{v}_1} L_{\mathbf{v}_2}:$$

$$\begin{cases} P(\mathbf{e}) = L_{\mathbf{v}_1} L_{\mathbf{v}_2}(\mathbf{e}) = L_{\mathbf{v}_1} L_{\mathbf{v}_2}(\cos \varphi \mathbf{e}' - \sin \varphi \mathbf{f}') = L_{\mathbf{v}_1}(\cos \varphi \mathbf{e}' + \sin \varphi \mathbf{f}') = \\ L_{\mathbf{v}_1}(\cos 2\varphi \mathbf{e} + \sin 2\varphi \mathbf{f}') = \cos 2\varphi \mathbf{e} - \sin 2\varphi \mathbf{f} \\ P(\mathbf{f}) = L_{\mathbf{v}_1} L_{\mathbf{v}_2}(\mathbf{f}) = L_{\mathbf{v}_1} L_{\mathbf{v}_2}(\sin \varphi \mathbf{e}' + \cos \varphi \mathbf{f}') = L_{\mathbf{v}_1}(\sin \varphi \mathbf{e}' - \sin \varphi \mathbf{f}') = \\ L_{\mathbf{v}_1}(\sin 2\varphi \mathbf{e} - \cos 2\varphi \mathbf{f}) = \sin 2\varphi \mathbf{e} + \cos 2\varphi \mathbf{f} \\ P(\mathbf{g}) = L_{\mathbf{v}_1} L_{\mathbf{v}_2}(\mathbf{g}) = L_{\mathbf{v}_1}(-\mathbf{g}) = \mathbf{g} \end{cases}$$

Thus matrix of the operator  $P$  in the basis  $\{\mathbf{e}, \mathbf{f}, \mathbf{g}\}$  is

$$\begin{pmatrix} \cos 2\varphi & -\sin 2\varphi & 0 \\ \sin 2\varphi & \cos 2\varphi & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

so f is finished.

In the case of arbitrary  $\mathbf{E}^n$  the transformation look :

$$\begin{cases} P(\mathbf{e}) = L_{\mathbf{v}_1} L_{\mathbf{v}_2}(\mathbf{e}) = L_{\mathbf{v}_1} L_{\mathbf{v}_2}(\cos \varphi \mathbf{e}' - \sin \varphi \mathbf{f}') = L_{\mathbf{v}_1}(\cos \varphi \mathbf{e}' + \sin \varphi \mathbf{f}') = \\ L_{\mathbf{v}_1}(\cos 2\varphi \mathbf{e} + \sin 2\varphi \mathbf{f}') = \cos 2\varphi \mathbf{e} - \sin 2\varphi \mathbf{f} \\ P(\mathbf{f}) = L_{\mathbf{v}_1} L_{\mathbf{v}_2}(\mathbf{f}) = L_{\mathbf{v}_1} L_{\mathbf{v}_2}(\sin \varphi \mathbf{e}' + \cos \varphi \mathbf{f}') = L_{\mathbf{v}_1}(\sin \varphi \mathbf{e}' - \sin \varphi \mathbf{f}') = \\ L_{\mathbf{v}_1}(\sin 2\varphi \mathbf{e} - \cos 2\varphi \mathbf{f}) = \sin 2\varphi \mathbf{e} + \cos 2\varphi \mathbf{f} \\ P(\mathbf{g}_i) = L_{\mathbf{v}_1} L_{\mathbf{v}_2}(\mathbf{g}) = L_{\mathbf{v}_1}(-\mathbf{g}) = \mathbf{g}_i \end{cases}$$

Here  $\{\mathbf{e}, \mathbf{f}, \mathbf{g}_i\}$  orthonormal basis. Matrix of the operator  $P$  in the basis  $\{\mathbf{e}, \mathbf{f}, \mathbf{g}_1, \mathbf{g}_2, \dots, \mathbf{g}_{n-2}\}$  is

$$\begin{pmatrix} \cos 2\varphi & -\sin 2\varphi & 0 & 0 & \dots & 0 \\ \sin 2\varphi & \cos 2\varphi & 0 & 0 & \dots & 0 \\ 0 & 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 0 & 1 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots & 0 \\ 0 & 0 & 0 & 0 & \dots & 1 \end{pmatrix}$$