Monximum likelihood estimates

i) Derivortive with respect to
$$\mu$$
:

 $\frac{2}{2}$ In $p(x|\mu,\sigma^2) = \frac{2}{\sigma^2} \mathcal{E}(x_n-\mu)$

ii) Derivortive with respect to
$$\sigma^2$$
:
$$\frac{2}{3\sigma^2} \ln p(x) \gamma_{mi} \sigma^2) = \frac{1}{2\sigma^4} \mathcal{E}(x_n - \gamma_{mi})^2 - \frac{N}{2\sigma^2}$$

$$\frac{2}{2\sigma_{N}^{4}} = \frac{2}{2\sigma_{N}^{2}} (x_{N} - y_{N})^{2} - \frac{N}{2\sigma_{N}^{2}} = 0 = 0$$

True vorvionnce

$$E[\sigma_{n_{1}}^{2}] = \frac{1}{N} \sum_{n=1}^{N} E[(x_{n} - \mu)^{2}]$$

$$= \frac{1}{N} \sum_{n=1}^{N} E[x_{n}^{2} - 2x_{n}\mu + \mu^{2}]$$

$$= \frac{1}{N} \sum_{n=1}^{N} E[x_{n}^{2}] - \frac{2\mu}{N} \sum_{n=1}^{N} E[x_{n}] + \mu^{2}$$

$$= \frac{1}{N} \sum_{n=1}^{N} (\sigma^{2} + \mu^{2}) - 2\mu^{2} + \mu^{2}$$

$$= \sigma^{2} + \mu^{2} - 2\mu^{2} + \mu^{2}$$

$$= \sigma^{2} + \mu^{2} - 2\mu^{2} + \mu^{2}$$

Jymme try

First of oull, we com write:

$$\begin{aligned} W_{ij} &= W_{ij} + \frac{W_{ji}}{2} - \frac{W_{ji} - W_{ji}}{2} - \frac{W_{ij} + W_{ji}}{2} + \frac{W_{ij} - W_{ji}}{2} \\ W_{ij} &= \frac{W_{ij} + W_{ji}}{2} - \frac{W_{ji} + W_{ij}}{2} - \frac{W_{ji} - W_{ji}}{2} - \frac{W_{ji} - W_{ij}}{2} - \frac{W_{ji} - W_{ji}}{2} - \frac{W_{j$$

1) We horve:

$$\sum_{i=1}^{S} \sum_{j=1}^{S} w_{ij} \times i \times j = \times^{T} W \times X$$

$$= \times^{T} (W^{S} + W^{A}) \times X$$

$$= x^{T}W^{S}x + x^{T}W^{A}x$$

$$= x^{T}W^{S}x + \frac{1}{2}x^{T}W^{A}x + \frac{1}{2}x^{T}(W^{A}x)$$

$$= x^{T}W^{S}x + \frac{1}{2}x^{T}W^{A}x + \frac{1}{2}(w^{A}x)^{T}(x^{T})$$
Symmetry
of the
$$= x^{T}W^{S}x + \frac{1}{2}x^{T}W^{A}x + \frac{1}{2}(w^{A}x)^{T}(x^{T})$$
dot product

$$= x^{T}W^{S}X + \frac{2}{2}x^{T}W^{A}X + \frac{1}{2}x^{T}(W^{A})^{T}X$$

$$= x^{T}W_{X}^{S} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^{T}(W_{X}^{A})^{T} \times W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} - \frac{1}{2}x^{T}W_{X}^{A} \times w_{X}^{A} = x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} - \frac{1}{2}x^{T}W_{X}^{A} \times w_{X}^{A} = x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} = x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} = x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} = x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} = x^{T}W_{X}^{A} + \frac{1}{2}x^{T}W_{X}^{A} + \frac{1}{2}x^$$

$$= x_t M_s x$$

Ii) In a symmetric $D \times D$ montrix, setting the value of Wij gives us Wji = + Wij. Therefore, we can set independently the values or or below) the diagonal and the values of the diagonal itself. The diagonal has D elements and from the remaining D^2 elements, we can set half of the values independently. Therefore, the number of independent parameters is given by: $D + \frac{D^2 - D}{2} = \frac{2D + D^2 - D}{2} = \frac{D^2 + D}{2} = \frac{D(D + D)}{2}$

Misclassification bound

Since a >0, we have a < b => a < ab => a < \ab

Let R1, Re be the two decision regions.

Then, p(mistake) = $p(x \in R1, l_2) + p(x \in R2, l_1)$ = $\int p(x, l_2) dx + \int p(x, l_1) dx$ R1

= $\int p(ce|x) p(x) dx + \int p(c_1|x) p(x) dx$

The regions that minimize the probability of misclassification are such that $p((2|x)) \ge p((2|x))$ for all $x \in R_2$ and $p((2|x)) \ge p((2|x))$ for all $x \in R_2$. Using the first result, we get:

 $\phi \text{ (mistake)} \leq \int_{R_{\mathcal{A}}} \sqrt{p((z|x))} \, \phi((x|x)) \, p(x) dx + \int_{R_{\mathcal{A}}} \sqrt{p((z|x))} \, \phi((z|x)) \, p(x) dx \\
= \int_{R_{\mathcal{A}}} \sqrt{p(x, c_{\mathcal{A}})} \, \phi(x, c_{\mathcal{A}}) \, dx + \int_{R_{\mathcal{A}}} \sqrt{p(x, c_{\mathcal{A}})} \, p(x, c_{\mathcal{A}}) \, dx \\
= \int_{R_{\mathcal{A}}} \sqrt{p(x, c_{\mathcal{A}})} \, \phi(x, c_{\mathcal{A}}) \, dx$

Minimod (oss (i)

1/ We hove that:

$$\begin{aligned} \mathcal{E} L_{kj} p(C_{k}|x) &= \mathcal{E}(1-I_{kj}) p(C_{k}|x) \\ &= \mathcal{E}p(C_{k}|x) - \mathcal{E}I_{kj} p(C_{k}|x) \\ &= 1 - \mathcal{E}I_{kj} p(C_{k}|x) \\ &= 1 - p(C_{j}|x) \end{aligned}$$

Therefore, ve get:

organin
$$\sum_{k} L_{kj} p(C_k|x) = \text{organin} \left[1 - p(C_j|x)\right]$$

$$= \text{organox} p(C_j|x)$$

ii) The loss montrix L hors the dorm:

Let k be the real class. It we predict on class j=k, the loss is equal to 0. Otherwise, for any predicted class j≠k, we get loss equal to 1.

Minimal loss (iii)

The expected loss is:

$$E[L] = \underset{k \neq j}{\mathcal{E}} \underset{k \neq j}{\mathcal{E}} \underset{k \neq j}{\mathsf{Lhj}} p(x, Ch) dx$$

$$= \underset{k \neq j}{\mathcal{E}} \underset{k \neq j}{\mathsf{Lhj}} p(x|Ch) \cdot p((h)dx \quad \text{we set}$$

$$= \underset{k \neq j}{\mathcal{E}} \underset{k \neq j}{\mathsf{Lhj}} \cdot p(x|Ch) dx$$

$$= \underset{k \neq j}{\mathcal{E}} \underset{k \neq j}{\mathsf{Lhj}} \cdot p(x|Ch) dx$$

= \(\) \(\

Let's coull that Lo for brevity. + / Ely. p(x/Gx)dx Rex Re* = Lo+) & Lkp.p(x1Ck)dx
Re Let's consider different decision regions Rz, Rz, ... such that $\hat{R}_i = R_i^* U R_e^*$, $\hat{R}_i^* = R_i^* I R_e^*$ and $\hat{R}_j^* = R_j^*$ for all $j \neq i, l$. Then, it is easy to see that the expected loss is: L= Lo + E { / i } { E { / i } } { E { L kj · p(x | Ck) dx } } = Lo + (& L'ki · p(x/Gk)dx +) R. & L'ki · p(x/Gk)dx + Set Re

(x)Cx)dx Therefore, we have $\tilde{L}-L^{*}=\int_{\mathbb{R}^{2}}\left[\underset{k}{\mathcal{E}}_{\text{lii}}\cdot p(x|C_{k})-\underset{k}{\mathcal{E}}_{\text{lii}}\cdot p(x|C_{k})\right]dx<0,$ which is a contradiction. $\ell\neq i=$ arginin $\underset{k}{\mathcal{E}}_{\text{lii}}\cdot p(x|C_{k})$

Theory (calculus of voirion tions)

Assume we have a quantity $Q(x, y(x)) = \int G(x, y(x), \dot{y}(x)) dx$ and we want to find the function y(x) that maximizes the given quantity. To all that, we obtain an functional $J[y] = \int G(x, y(x), \dot{y}(x)) dx$ and we set its functional derivative $\int J$ to zero.

• x, y real: $\frac{\partial J}{\partial y} = 0 \iff \frac{\partial G}{\partial y} = 0$ where $\frac{\partial G}{\partial y} = 0$ wher

• y real: $Q(x, y(x)) = \int G(x, y(x), \nabla y(x)) dx$, x = 3-dimensional $\frac{\partial J}{\partial y} = 0 \Leftrightarrow \frac{\partial G}{\partial y} - \nabla \cdot \frac{\partial G}{\partial y} = 0$ Example: $G = g^2(x) + \nabla g(x) \cdot \nabla g(x) = g^2(x) + \frac{\partial g}{\partial x} + \frac{\partial g}{\partial$

Example: $G = y^{2}(x) + \nabla y(x) \cdot \nabla y(x) = y^{2}(x) + \left(\frac{\partial y}{\partial x_{x}}\right)^{2} + \left(\frac{\partial y}{\partial x_{y}}\right)^{2} + \left(\frac{\partial y}{\partial x_{y$

• x vector:
$$J[y] = J[y_2, y_2, ..., y_m]$$

=Q(x, y_2(x), y_2(x), ..., y_m(x))

=\(\begin{align*} \(\times_1, \times_2, ..., \times_n, \times_1, \times_n, \times_n,

$$\frac{\int J}{\int y} = 0 \iff \frac{\partial}{\partial y} = 0 \iff \frac{\partial}{\partial y} = 0 \iff i = 1, 2, ..., m$$

$$\frac{\partial G}{\partial y_i} = \frac{\partial}{\partial x_i} \frac{\partial}{\partial y_{i,j}} = 0 \iff \text{Lor } i = 1, 2, ..., m$$

$$\text{Example in the exercise (Tangeti)},$$

Torrgets

Consider the functional

$$J[y] = \int \int ||y(x) - t||^2 p(x,t) dt dx = E[L(t,y(x))]$$

ound let $G(x,y(x)) = \int ||y(x)-t||^2 p(x,t) dt$.

To find the function $y(x) = [y_2(x), ..., y_m(x)]$ we use:

$$\frac{\partial G}{\partial y_i} - \frac{\mathcal{E}}{\mathcal{E}} \frac{\partial}{\partial x_j} \left(\frac{\partial G}{\partial y_{i,j}} \right) = 0 \text{ for } i = 1, ..., m \Longrightarrow$$

$$\frac{\partial G}{\partial y_i} = 0$$
 for $i=2,..., m (=)$

$$\int \frac{\partial}{\partial y_{i}} \left[\|y(x) - t\|^{2} \right] p(x,t) dt = 0 \quad \text{for } i=1,...,m \in \mathbb{Z}$$

$$2(y_i(x)-t_i)p(x,t)dt = 0$$
 for $i=1,...,m = 0$

$$y_i(x).$$
 $\int p(x,t)dt = \int t_i \cdot p(x,t)dt$ for $i=1,...,m \in S$

$$y_{i}(x) \cdot \int p(x,t) dt = \int f_{i} \cdot p(x,t) dt \quad \text{for } i = 1, \dots, m \in S$$

$$y(x) = \int \frac{f_{i} \cdot p(x,t) dt}{p(x)} = \int f_{i} \cdot p(f_{i}(x)) df = E_{f_{i}}[f_{i}(x)]$$

Regression

1) Consider the functional

$$J[y] = \int \int [y(x) - t]^2 p(x,t) dt dx = E[L(t,y(x))]$$

ound let $G(x,y(x)) = \int |y(x)-t|^{\nu} p(x,t) dt$.

To find the function y(x) that minimizes the loss, we use:

$$\frac{\partial G}{\partial y} - \frac{d}{dx} \frac{\partial G}{\partial \dot{y}} = 0 \iff$$

$$\int_{-\infty}^{4(x)} [y(x)-t]^{q-2} \cdot p(t|x)dt = \int_{y(x)}^{\infty} [y(x)-t]^{q-2} \cdot p(t|x)dt$$

(i) When
$$q=1$$
, we get:

 $y(x)$
 $y(x)$

iii) We have E[lq]= \(\left\) |y(x)-11 p(x,1) dx dt \\ = \left\] \(\left\) |y(x)-11 p(t1x) dt \\ p(x) dx.

Therefore, the expected loss is minimized if, for each x independently, we choose the value y(x) that minimizes (1,1) 1120/11/11

minimizes (1y(x)-+12p(+1x)olt.

We can see that, when $q \rightarrow 0$, the quantity $ly(x)-\ell l^2$ equals 1 when $t \neq y(x)$ and gets value 0 in an infinitesimally small region around t = y(x). Therefore, the previous integral is minimized when we set y(x)=t and the point t that maximizes the quantity p(t|x), i.e., the conditional mode.

Decision boundary

i) It is
$$P(error) = P(error|C_4) \cdot P(C_4) + P(error|C_6) \cdot P(C_6)$$

$$= P(x \le f) |C_4) \cdot P(C_4) + P(x > f) |C_6) \cdot P(C_6)$$

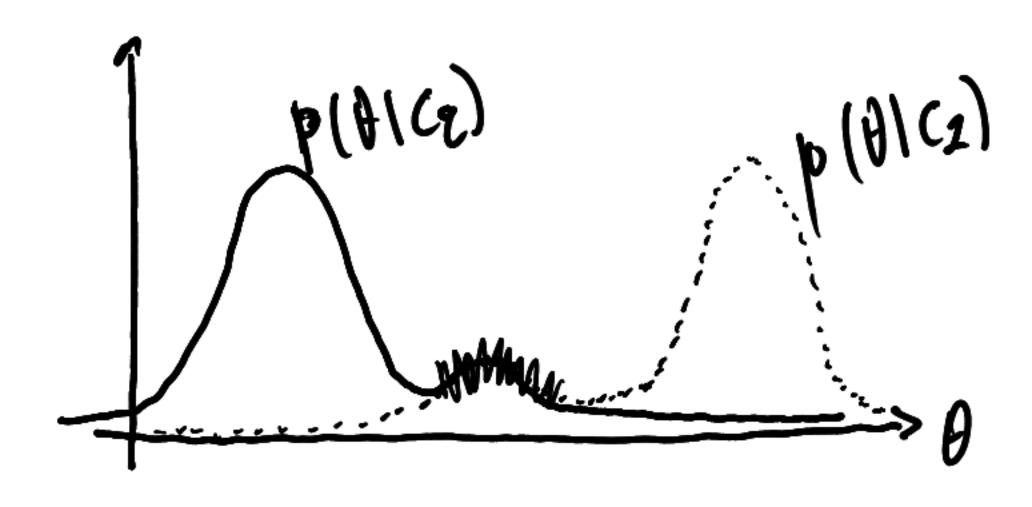
$$= P(C_4) \int_{-\infty}^{6} p(x) |C_4| dx + P(C_6) \int_{0}^{\infty} p(x) |C_6| dx$$

ii) The second term con be rewritten as:
$$P((e) \cdot \left[\int_{-\infty}^{\infty} (x | C_e) dx - \int_{\infty}^{0} (x | C_e) dx \right] = P((e) - P((e)) \cdot \int_{\infty}^{\infty} (x | C_e) dx$$

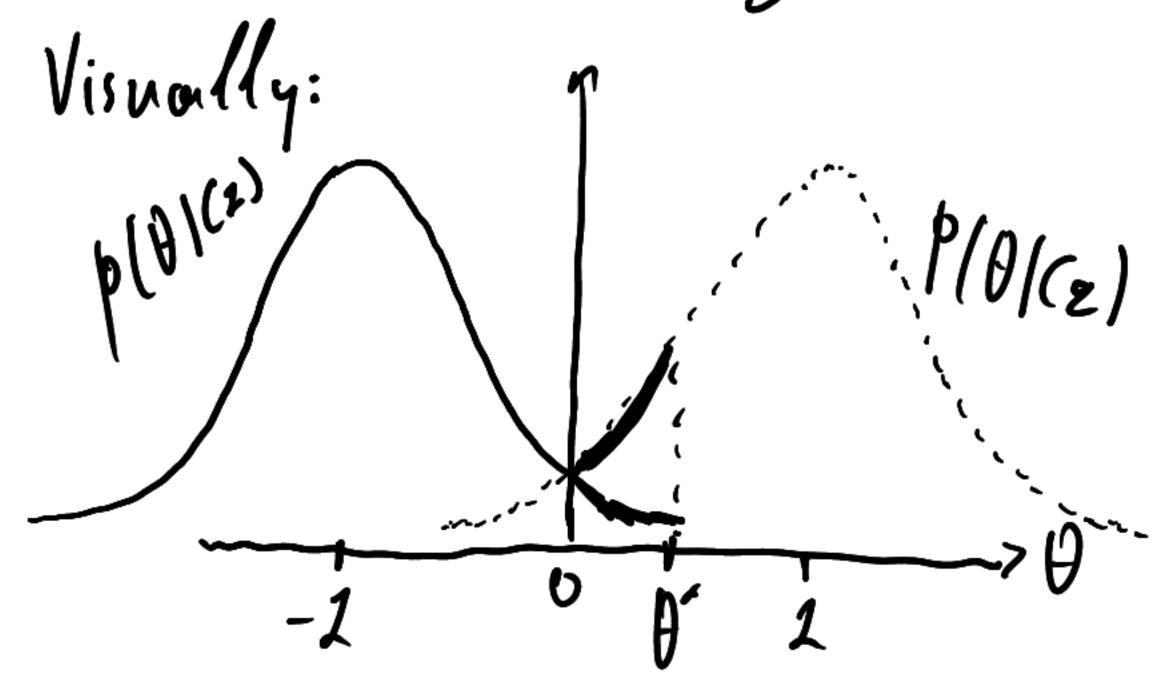
Therefore,
$$\frac{dP(error)}{d\theta} = 0 \Leftrightarrow P(G) \cdot p(\theta|G) - P((e) \cdot p(\theta|G) = 0 \Leftrightarrow P(G) \cdot p(\theta|G) = P(G) \cdot p(\theta|G)$$

$$P(G) \cdot p(\theta|G) = P(G) \cdot p(\theta|G)$$

iii) It does not uniquely identify D. It could be P(G)=P(G). Then, it suffices to find or rounge of D where the conditionals match.



iv) Assume P((2)=P((2)=\frac{2}{9}, and \text{\text{\$1/2\$}} \sim N(-2,2), \text{\text{\$1/2\$}} \text{\text{\$1/2\$}}.



The condition gives $\theta = 0$. Then,: $e^* = P(error) = \frac{1}{2} \int p(x|C_2) dx + \frac{1}{2} \int p(x|C_2) dx$

For every $\theta > 0$, we have: $e=P(error)=\frac{1}{2}\int_{-\infty}^{\infty}(x(x))dx+\frac{1}{2}\int_{0}^{\infty}p(x(x))dx+\frac{1}{2}\int_{0}^{\infty}(p(x(x)))dx$

$$= e^{x} + \frac{1}{2} \int_{0}^{\infty} \left[p(x|C_{2}) - p(x|C_{2}) \right] dx$$

$$< e^{x}$$

Similarly, for
$$\theta' < \theta$$
:
$$e = e^{*} + \frac{1}{2} \int_{0}^{\infty} [p(x)(x) - p(x)(x)] dx < e^{*}.$$

Optional: What is the optimal D in the previous example?

We have that: $P(error) = P(X \le \theta \mid C_{+}) \cdot \frac{1}{2} + P(X > \theta \mid C_{+}) \cdot \frac{1}{2}$ $= P(Z \le \frac{\theta - (-1)}{1}) \cdot \frac{1}{2} + P(Z > \frac{\theta - 1}{1}) \cdot \frac{1}{2} \quad \text{where}$ $= P(Z \le \theta + 1) \cdot \frac{1}{2} + [1 - P(Z \le \theta + 1)] \cdot \frac{1}{2}$ $= \frac{1}{2} + \frac{1}{2} [P(Z \le \theta + 1) - P(Z \le \theta - 1)]$ $= \frac{1}{2} + \frac{1}{2} P(\theta - 1 \le Z \le \theta + 1)$

For every $\theta \in \mathbb{R}$, it is easy to see that $P(error) \ge \frac{1}{2}$. Instead, we get $\lim_{\theta \to -\infty} P(error) = \lim_{\theta \to \infty} P(error) = \frac{1}{2}$. In the limit, we either classify only samples as (1) (and mis-classify only samples of (2) or the opposite. Because $P(\zeta_1) = P(\zeta_2) = \frac{1}{2}$, we get $P(error) = \frac{1}{2}$.

A1 the limit

1) The minimum-error-rate decision rule returns (2 if P(C1/x) > P(C2/x) and C2 otherwise.

We hore:

$$\frac{P(x|(x)\cdot P((x)))}{P(x)} > \frac{P(x|(x)\cdot P((x)))}{P(x)} \qquad P((x)) = P((x)) = \frac{2}{2}$$

$$P(x|C_{x}) > P(x|C_{x}) = 0$$

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$$P(x|C_{x}) > P(x|C_{x}) = 0$$

$$= \frac{1}{2} \times \frac{1}{2} \log p + \frac{1}{2} (1-x;) \log (1-p) > \frac{1}{2} \times \frac{1}{2} \log (1-p) + \frac{1}{2} (1-x;) \log p = 0$$

$$logp : \stackrel{d}{\underset{i=1}{\xi}} x_i + d \cdot log(1-p) - log(1-p) \cdot \stackrel{d}{\underset{i=1}{\xi}} x_i > log(1-p) \cdot \stackrel{e}{\underset{i=1}{\xi}} x_i > log(1-p) \cdot \stackrel{e}{\underset{i=1}{\xi}} x_i = log(1-p) \cdot \stackrel{e}{\underset{i=$$

$$\frac{2}{2}xi > \frac{d}{2}$$

(i) The probability of error is: $P_{e}(d,p) = P(error | C_{1}) \cdot P(C_{1}) + P(error | C_{2}) \cdot P(C_{2})$ $= P(\underbrace{\xi}_{x_{i}} \leq \frac{d}{2} | C_{2}) \cdot \frac{1}{2} + P(\underbrace{\xi}_{x_{i}} > \frac{d}{2} | C_{2}) \cdot \frac{1}{2}$ $= P(\underbrace{\xi}_{x_{i}} \leq \frac{d-1}{2} | C_{1}) \cdot \frac{1}{2} + P(\underbrace{\xi}_{x_{i}} > \frac{d+1}{2} | C_{2}) \cdot \frac{1}{2}$ $= P(\underbrace{\xi}_{i=1} \times i \leq \frac{d-1}{2} | C_{1}) \cdot \frac{1}{2} + P(\underbrace{\xi}_{x_{i}} > \frac{d+1}{2} | C_{2}) \cdot \frac{1}{2}$ $= P(\underbrace{\xi}_{i=1} \times i \leq \frac{d-1}{2} | C_{1}) \cdot \frac{1}{2} + P(\underbrace{\xi}_{x_{i}} > \frac{d+1}{2} | C_{2}) \cdot \frac{1}{2}$ $= \frac{1}{2} \underbrace{\xi}_{k=0}^{(d-1)/2} | p^{k} (1-p) \cdot p^{(d-k)} + \underbrace{\xi}_{k=(d+1)/2}^{(d-k)} | p^{k} (1-p) \cdot p^{(d-k)}$

In the second term, we set j = d - k and we get: $Pe(d,p) = \frac{1}{\epsilon} \mathop{\mathbb{E}}_{k=0}^{(d-1)/2} \binom{d}{k} p^{k} (1-p)^{d-k} + \frac{1}{\epsilon} \mathop{\mathbb{E}}_{j=0}^{(d-1)/2} \binom{d}{d-j} p^{j} (1-p)^{d-j} \underset{(d-j)=(j)}{\text{Recoll that}}$ $= \mathop{\mathbb{E}}_{(u,j)}^{(d-1)/2} \binom{d}{k} p^{k} (1-p)^{d-k}$

 $||f|| = \frac{|f|}{|f|} ||f|| = \frac{|f|}{|f|} ||f|$

We have that:
$$\frac{Z}{k} \begin{pmatrix} d \\ k \end{pmatrix} = g^{d} = 3$$

$$\frac{Z}{k-2} \begin{pmatrix} d \\ k \end{pmatrix} = g^{d} = 3$$

$$\frac{Z}{k-2} \begin{pmatrix} d \\ k \end{pmatrix} + \frac{Z}{k-2} \begin{pmatrix} d \\ k \end{pmatrix} = g^{d}$$
We set $j = d-k$ and similarly as before, we get:
$$\frac{(d-1)/2}{2 \cdot E} \begin{pmatrix} d \\ k \end{pmatrix} = g^{d-k}$$
Therefore, $\lim_{k \to 0} Pe(d, p) = \left(\frac{1}{2}\right)^{k} \cdot 2^{d-k} = \frac{1}{2}$.

$$\frac{Z}{k-2} \begin{pmatrix} d \\ k \end{pmatrix} = g^{d-k}$$
Therefore, $\lim_{k \to 0} Pe(d, p) = \left(\frac{1}{2}\right)^{k} \cdot 2^{d-k} = \frac{1}{2}$.

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Therefore, $\lim_{k \to 0} Pe(d, p) = \lim_{k \to 0} P(0 \le x \le (d-1)/2)$
Therefore:
$$\lim_{k \to 0} Pe(d, p) = \lim_{k \to 0} P(0 \le x \le (d-1)/2)$$

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Therefore:
$$\lim_{k \to 0} P(d, p) = \lim_{k \to 0} P(0 \le x \le (d-1)/2)$$

$$\lim_{k \to 0} P(d-k) = 2^{d}$$
Therefore is a constant of the property of the p

 $= \lim_{\Delta \to \infty} P\left(-\sqrt{\Delta} \frac{\sqrt{p}}{\sqrt{1-p}} \leq Z \leq \frac{\sqrt{d}(2/2-p)-2\sqrt{d}}{\sqrt{p}(2-p)}\right)$ where $Z \sim \mathcal{N}(0,1)$.

It is easy to see that the left hand side converges to $-\infty$ and, since $p > \frac{1}{2} = > \sqrt{d(1/2 - p)} < 0$, the right hand side also converges to $-\infty$.

Therefore $\lim_{d \to \infty} P_e(d, p) = P(-\infty \le Z \le -\infty) = 0$.