

Non-Functional Properties

Prof. Sven Apel

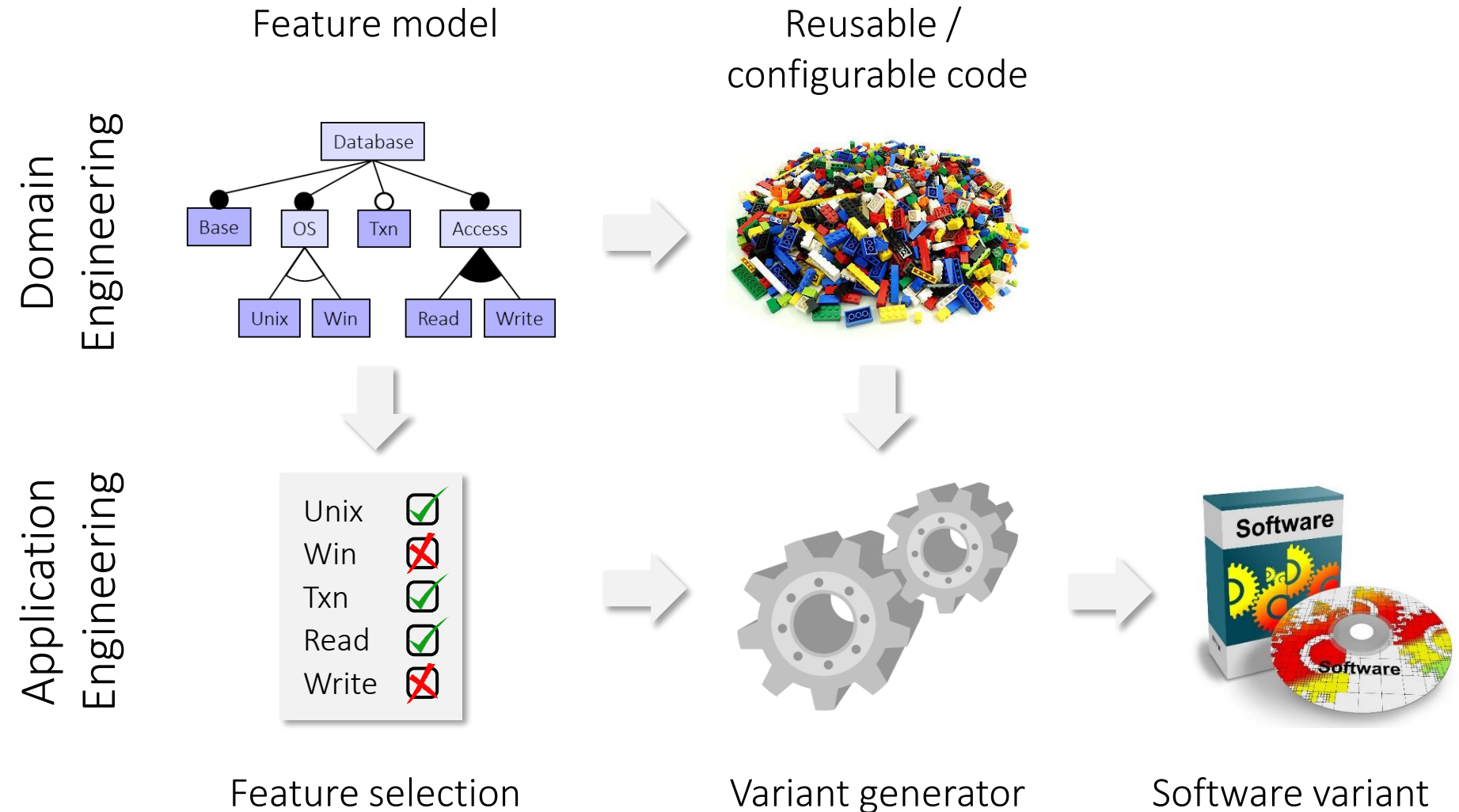
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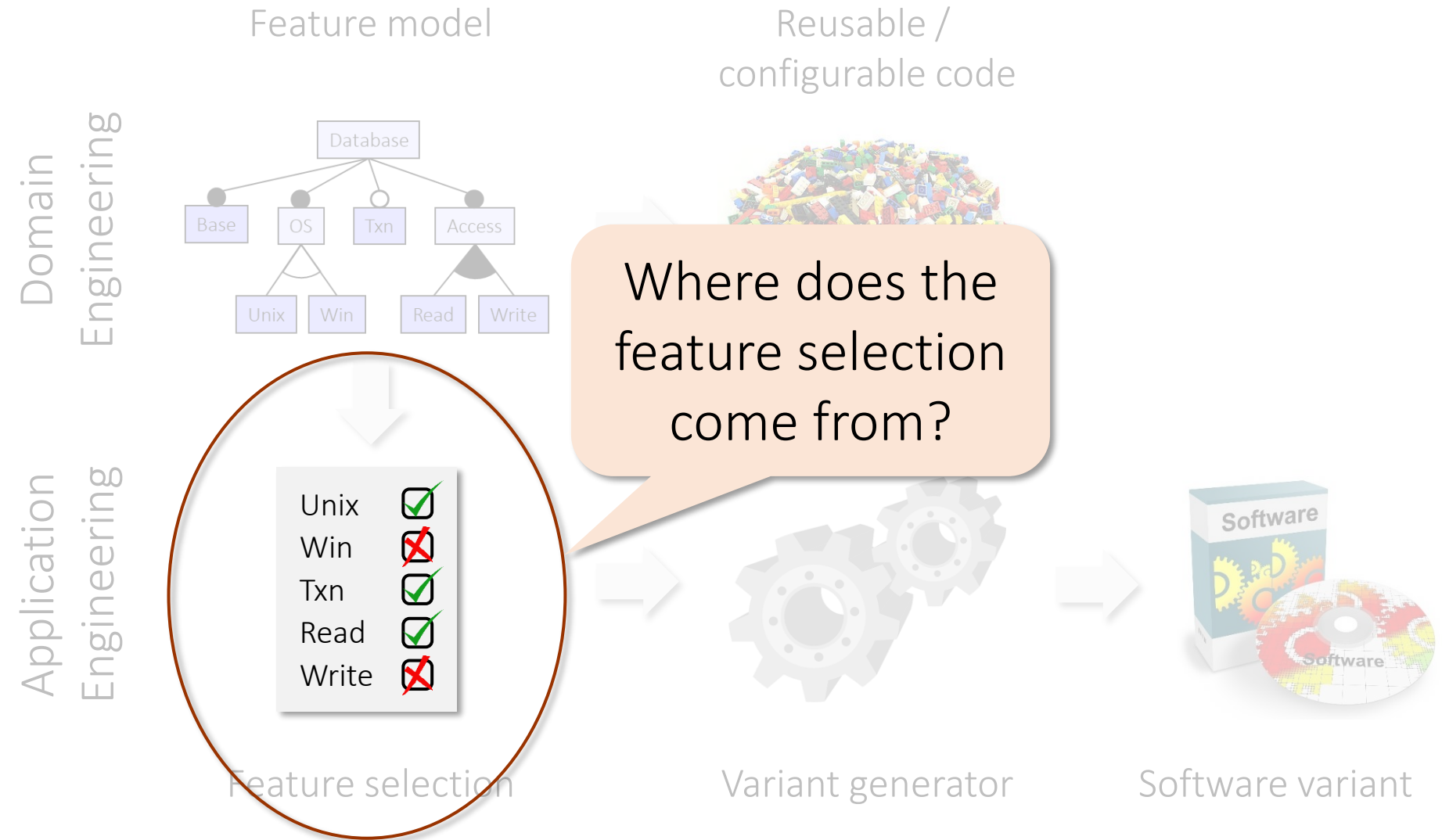
Part I

Motivation and Overview

Our view so far:

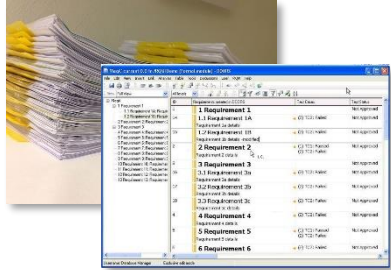


Our view so far:



From Requirements to Configurations

Functional requirements



Features



Encryption



Data analysis



Compression



Reporting



Database

CacheSize

Encryption

Transaction

Compression

Index

Reporting

PageSize

8MB

32MB

128MB

Logging

CommitProtocols

R-Tree

B-Tree

Hash

2KB

4KB

8KB

16KB

Partial feature selection

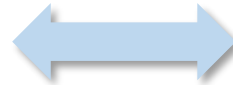
Non-Functional Requirements



Performance



Memory consumption



Footprint



...

Definition(s)

Also known as *quality attributes*

Over 25 definitions

In general:

Any property of a product that is not related with functionality represents a non-functional property.

Often there are *trade-offs* between properties!

Categorization

Quantitative

Response time (performance), throughput, etc.

Energy- and memory consumption

Measurable properties, metric scale

→ *Easy to evaluate*

Qualitative

Extensibility

Error freeness

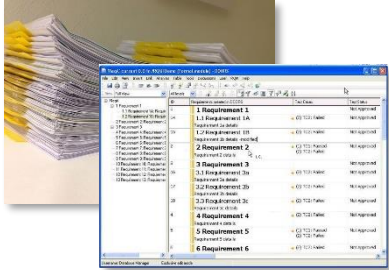
Robustness

Security

→ *No direct measurement (often, no suitable metric)*

Incorporating Non-Functional Properties

Functional requirements



Features



Encryption



Data analysis



Compression



Reporting

Non-functional



Performance



Memory use



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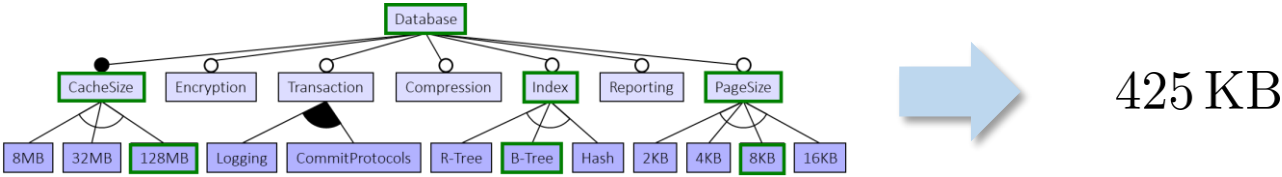
8KB

16KB

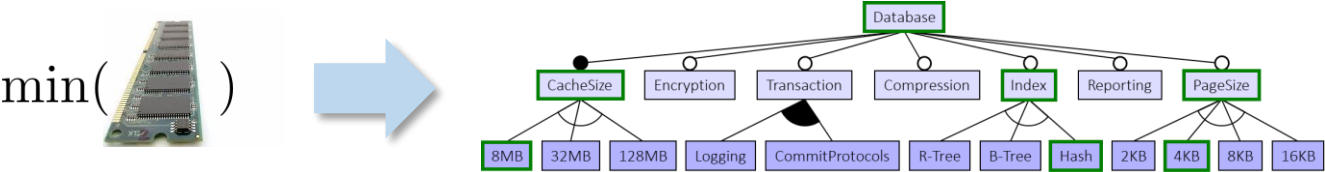


Practical Relevance

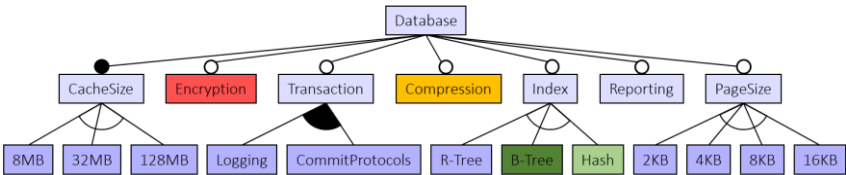
What is the binary footprint of a variant for a given feature selection?



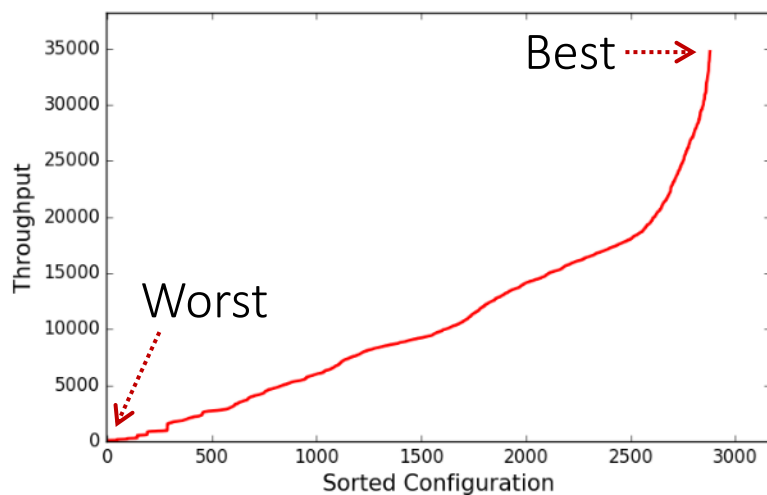
What is the best feature selection to minimize memory consumption?



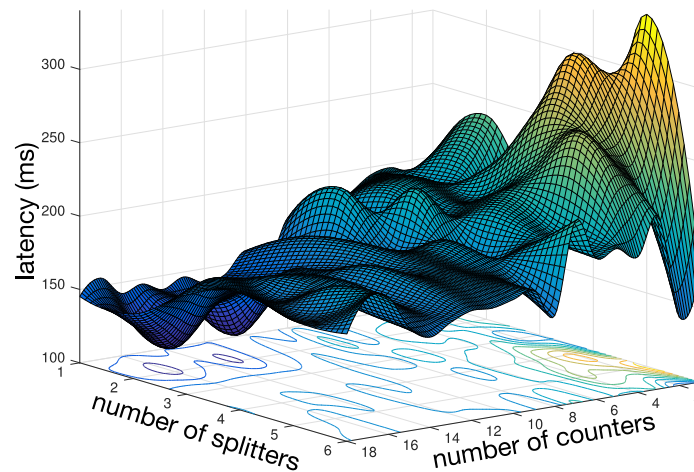
What are the performance critical features?



Practical Relevance



Best configuration is *480 times* better than worst configuration

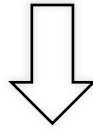
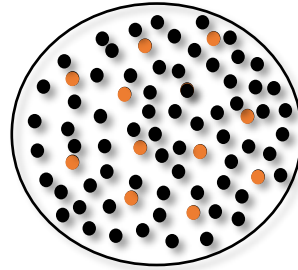


Only by tweaking *2 of 200 options* of Apache Storm led to *100% change in latency*

Overview

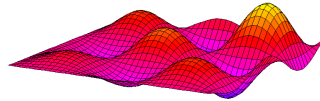
Configuration space

$$|C| = \mathcal{O}(2^{|F|})$$



Performance model

$$\Pi : C \rightarrow \mathbb{R}$$



Goal

1. Measurement

Goal: Measure non-functional properties, e.g., via sampling (select a minimal, representative set of configurations)

Challenges: Size of configuration space, constraints, interactions

Key domains: Combinatorial testing, artificial intelligence, search-based software engineering, design of experiments

2. Learning a model

Goal: Learn a model accurately describing performance of all configurations

Challenges: Dimensionality of the learning problem, interactions

Key domains: machine learning, statistics

3. Optimization

Goal: Finding optimal configurations in a single or multi-objective scenario

Challenges: Size of configuration space, constraints, interactions, lack of ground truth

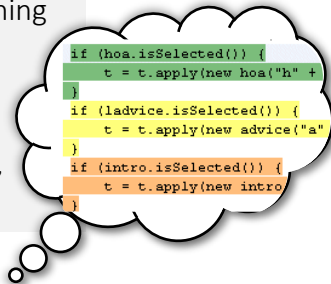
Key domains: search-based software engineering, meta-heuristics, machine learning, artificial intelligence, mathematical optimization

4. Comprehension

Goal: Explainable machine learning with white-box models

Challenges: Trade-off between explainability and accuracy

Key domains: machine learning, software analysis, testing

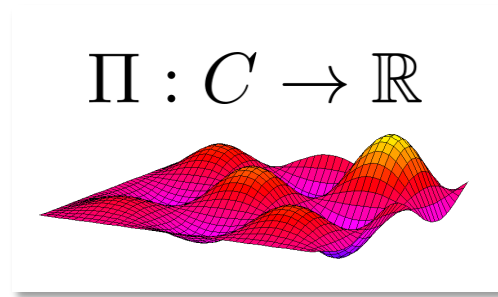


System understanding

$$\begin{array}{lcl} c_i & = & \{ \dots \} \\ \vdots & \vdots & \vdots \\ c_k & = & \{ \dots \} \end{array}$$

Optimal configuration(s)

Predictive Modeling / Machine Learning



Linear regression (Least-square, Lasso, Ridge, ...)

Regression trees (CART, Random Forests, ...)

Support vector machines

Neural networks

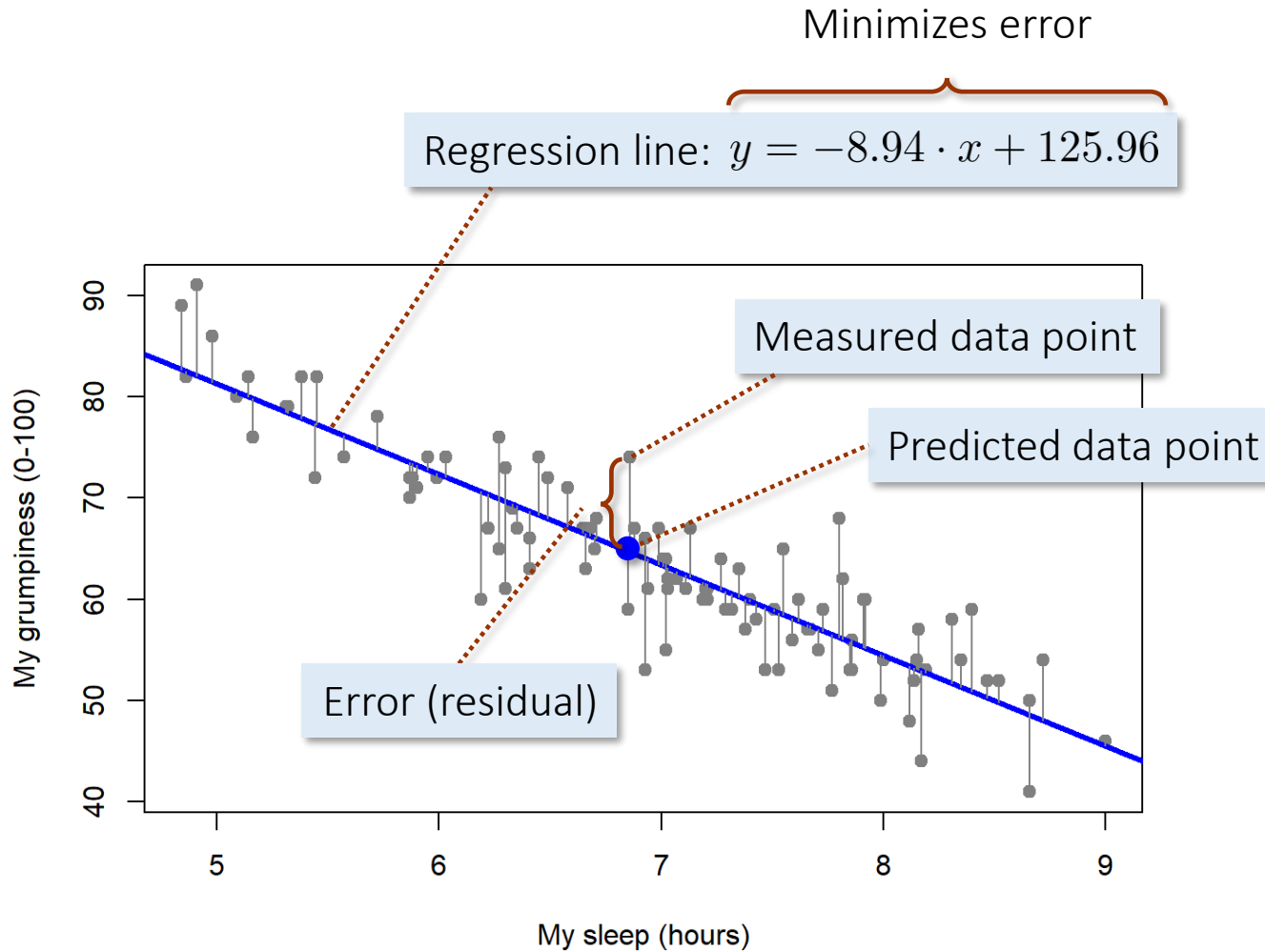
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Part II

Learning Influence Models

Linear Regression

Dependent variable (outcome, regressand)



Independent variable (predictor, regressor)

Linear Regression

Model structure:

The diagram illustrates the linear regression model structure. It shows the equation $y_i = \beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip} + \varepsilon_i = \mathbf{x}_i^\top \boldsymbol{\beta} + \varepsilon_i$. The terms are labeled as follows: y_i is labeled "Property (e.g., performance)", β_0 is labeled "Influences", $\beta_1 x_{i1}$ and $\beta_p x_{ip}$ are labeled "Features", and ε_i is labeled "Error". Dotted lines connect the labels to their respective terms in the equation.

$$y_i = \beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip} + \varepsilon_i = \mathbf{x}_i^\top \boldsymbol{\beta} + \varepsilon_i$$

Property
(e.g., performance)

Influences

Features

Error

Single observation: (y, \mathbf{x})
(one sample)

All observations: (\mathbf{y}, X)
(whole sample)

1. Sampling observations:
Influences and errors are unknown!

Linear Regression

Observations:

$$(\mathbf{y}, X)$$

Optimization:

$$\longrightarrow \min \quad \boldsymbol{\varepsilon}^T \boldsymbol{\varepsilon} = (\mathbf{y} - X\boldsymbol{\beta})^T (\mathbf{y} - X\boldsymbol{\beta})$$

Predictor (performance model):

$$\Pi(\mathbf{x}) = \beta_0 + \beta_1 x_1 + \dots + \beta_p x_p$$

Example model:

$$\Pi((x_1, x_2)) = 15 - 8.9 x_1 + 154 x_2$$

2. Learning a predictor:

Minimizing the overall error
when assigning influences

Performance is non-linear!



```
x264
--no-progress

--rc-lookahead 60
--ref 9
-o trailer_480p24.x264
trailer_2k_480p24.y4m
```

661s

```
x264 --quiet
--no-progress

--rc-lookahead 60
--ref 9
-o trailer_480p24.x264
trailer_2k_480p24.y4m
```

487s (-174s)

```
x264
--no-progress
--no-asm
--rc-lookahead 60
--ref 9
-o trailer_480p24.x264
trailer_2k_480p24.y4m
```

551s (-110s)

```
x264 --quiet
--no-progress
--no-asm
--rc-lookahead 60
--ref 9
-o trailer_480p24.x264
trailer_2k_480p24.y4m
```

324s (-337s)

Performance is non-linear!



```
x264
--no-progress

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trailer_2k_480p24.y4m
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661s

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x264 --quiet
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```

487s (-174s)

Influences of individual features
do not add up in combination!

```
x264
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```


551s (-110s)

```
--no-progress
--no-asm
--rc-lookahead 60
--ref 9
-o trailer_480p24.x264
trailer_2k_480p24.y4m
```

324s (-337s)

Feature Selection

We cannot include all possible combinations of features as distinct variables!

$$y_i = \beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip} + \varepsilon_i = \mathbf{x}_i^\top \boldsymbol{\beta} + \varepsilon_i$$


Features & interactions

Features only:

$$I^{(1)} = \mathcal{O}(|F|)$$

All pairs of features:

$$I^{(2)} = \mathcal{O}(|F|^2)$$

...

All feature combinations: $I^* = \mathcal{O}(2^{|F|})$

Which features to
select and how?

Feature Selection: Example

Features



$$X_a = \begin{pmatrix} 1 & 0 & 0 & 20 & 0 \\ 0 & 1 & 1 & 50 & 16 \\ 1 & 0 & 1 & 100 & 32 \\ 1 & 1 & 0 & 50 & 32 \\ 1 & 1 & 1 & 20 & 32 \\ 0 & 0 & 0 & 100 & 0 \\ 1 & 1 & 1 & 100 & 16 \end{pmatrix}$$

$$\mathbf{y} = \begin{pmatrix} 833 \\ 411 \\ 290 \\ 799 \\ 753 \\ 514 \\ 416 \end{pmatrix}$$

$$\beta_a = (102.4 \ 84.3 \ 54.1 \ 5.4 \ 1.3)$$

$$\bar{\varepsilon}_a = 41\%$$

Feature Selection: Example

Features

Interactions



$$X_b = \begin{pmatrix} 1 & 0 & 0 & 20 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 50 & 16 & 0 & 0 & 800 \\ 1 & 0 & 1 & 100 & 32 & 0 & 0 & 0 \\ 1 & 1 & 0 & 50 & 32 & 1 & 0 & 1600 \\ 1 & 1 & 1 & 20 & 32 & 1 & 1 & 640 \\ 0 & 0 & 0 & 100 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 100 & 16 & 1 & 1 & 1600 \end{pmatrix}$$

$$\mathbf{y} = \begin{pmatrix} 833 \\ 411 \\ 290 \\ 799 \\ 753 \\ 514 \\ 416 \end{pmatrix}$$

$$\beta_a = (102.4 \ 84.3 \ 54.1 \ 5.4 \ 1.3)$$

$$\bar{\varepsilon}_a = 41\%$$

$$\beta_b = (132.3 \ 81.3 \ 56.6 \ 3.5 \ 1.9 \ 14.1 \ 5.4 \ 2.4)$$

$$\bar{\varepsilon}_b = 25\%$$

Feature Selection: Example

Features					Interactions			Functions	
1	0	0	20	0	0	0	0	400	—
0	1	1	50	16	0	0	800	2500	1.2
1	0	1	100	32	0	0	0	10^4	0.9
1	1	0	50	32	1	0	1600	2500	1.5
1	1	1	20	32	1	1	640	400	1.5
0	0	0	100	0	0	0	0	10^4	—
1	1	1	100	16	1	1	1600	10^4	1.2

$$X_c = \begin{pmatrix} 1 & 0 & 0 & 20 & 0 & 0 & 0 & 0 & 400 & — \\ 0 & 1 & 1 & 50 & 16 & 0 & 0 & 800 & 2500 & 1.2 \\ 1 & 0 & 1 & 100 & 32 & 0 & 0 & 0 & 10^4 & 0.9 \\ 1 & 1 & 0 & 50 & 32 & 1 & 0 & 1600 & 2500 & 1.5 \\ 1 & 1 & 1 & 20 & 32 & 1 & 1 & 640 & 400 & 1.5 \\ 0 & 0 & 0 & 100 & 0 & 0 & 0 & 0 & 10^4 & — \\ 1 & 1 & 1 & 100 & 16 & 1 & 1 & 1600 & 10^4 & 1.2 \end{pmatrix}$$

$$\mathbf{y} = \begin{pmatrix} 833 \\ 411 \\ 290 \\ 799 \\ 753 \\ 514 \\ 416 \end{pmatrix}$$

$$\beta_a = (102.4 \ 84.3 \ 54.1 \ 5.4 \ 1.3)$$

$$\bar{\varepsilon}_a = 41\%$$










$$\beta_b = (132.3 \ 81.3 \ 56.6 \ 3.5 \ 1.9 \ 14.1 \ 5.4 \ 2.4)$$

$$\bar{\varepsilon}_b = 25\%$$

$$\beta_c = (130.3 \ 83.5 \ 54.2 \ 0.01 \ 0 \ 14.1 \ 5.4 \ 1.4 \ 2.1 \ 8.8)$$

$$\bar{\varepsilon}_c = 7.4\%$$

Feature Selection: Example

	Features					Interactions			Functions		
										$\log(\text{list})$	
$X_c =$	1	0	0	20	0	0	0	0	400	—	$y =$
	0	1	1	50	16	0	0	800	2500	1.2	
	1	0	1	100	32	0	0	0	10^4	0.9	
	1	1	0	50	32	1	0	1600	2500	1.5	
	1	1	1	20	32	1	1	640	400	1.5	
	0	0	0	100	0	0	0	0	10^4	—	
	1	1	1	100	16	1	1	1600	10^4	1.2	
											$\begin{pmatrix} 833 \\ 411 \\ 290 \\ 799 \\ 753 \\ 514 \\ 416 \end{pmatrix}$

$$\beta_a = (102.4 \ 84.3 \ 54.1 \ 5.4 \ 1.3)$$

$$\bar{\varepsilon}_a = 41\%$$

$$\beta_b = (132.3 \ 81.3)$$

$$\bar{\varepsilon}_b = 25\%$$

$$\beta_c = (130.3 \ 83.5)$$

$$\bar{\varepsilon}_c = 7.4\%$$

Search for the best model in *multiple iterations* adding *more and more variables* of *increasing complexity*!

Empirical Results

System	Domain	# Binary Opt.	# Numeric Opt.	# Constraints	# Configs
Dune MGS	Multi-Grid Solver	8	3	20	2 304
HIPAC ^{cc}	Image Processing	31	2	416	13 485
HSMGP	Stencil-Grid Solver	11	3	45	3 456
JavaGC	Runtime Env.	12	23	4	10 ³¹
SaC	Compiler	53	7	10	10 ²³
x264	Video Encoder	8	13	0	10 ²⁷

System	Plackett-Burman Design		Random Design	
	Feature-wise	Pair-wise	Feature-wise	Pair-wise
Dune MGS	8.8 %	8.3 %	20.1 %	22.1 %
HIPAC ^{cc}	13.8 %	10.7 %	14.2 %	13.9 %
HSMGP	1.7 %	1.5 %	4.5 %	2.8 %
JavaGC	21.9 %	18.8 %	31.3 %	24.6 %
SaC	16.0 %	25.0 %	21.1 %	30.7 %
x264	21.2 %	15.0 %	14.2 %	13.5 %

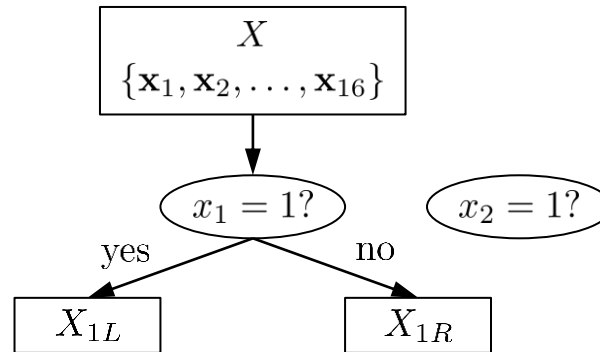
Regression Trees (CART)

Running example:



Configuration	Features																Performance (s)
\mathbf{x}_i	x_1	x_2	x_3	x_4	x_5	x_6	x_7	x_8	x_9	x_{10}	x_{11}	x_{12}	x_{13}	x_{14}	x_{15}	x_{16}	y_i
\mathbf{x}_1	1	1	0	1	1	1	1	0	1	0	0	1	1	0	0	1	651
\mathbf{x}_2	1	1	1	1	1	1	0	1	1	1	0	0	1	0	1	0	536
\mathbf{x}_3	1	1	1	1	0	0	0	0	1	1	0	0	1	0	0	1	581
\mathbf{x}_4	1	0	0	0	0	0	1	0	1	1	0	0	1	0	1	0	381
\mathbf{x}_5	1	1	0	1	0	0	0	1	1	1	0	0	1	0	1	0	424
\mathbf{x}_6	1	1	0	0	1	0	1	1	1	1	0	0	1	0	0	1	615
\mathbf{x}_7	1	0	1	0	1	1	1	0	1	1	0	0	1	0	1	0	477
\mathbf{x}_8	1	0	1	0	0	0	0	1	1	0	0	1	1	1	0	0	263
\mathbf{x}_9	1	0	0	0	0	0	1	1	1	0	0	1	1	1	0	0	272
\mathbf{x}_{10}	1	1	1	1	0	0	0	1	1	0	0	1	1	1	0	0	247
\mathbf{x}_{11}	1	0	0	0	0	0	0	0	1	0	1	0	1	0	0	1	612
\mathbf{x}_{12}	1	0	1	1	1	0	0	0	1	0	0	1	1	0	1	0	510
\mathbf{x}_{13}	1	1	1	1	0	1	1	0	1	0	1	0	1	0	0	1	555
\mathbf{x}_{14}	1	1	0	0	1	0	1	1	1	0	0	1	1	1	0	0	264
\mathbf{x}_{15}	1	0	1	0	0	1	1	1	1	0	0	1	1	0	0	1	576
\mathbf{x}_{16}	1	0	1	0	1	0	1	1	1	0	1	0	1	1	0	0	268

Regression Trees (CART)



Best split!

Sample mean

$$\ell_{X_{iL}} = \frac{1}{|X_{iL}|} \sum_{(\mathbf{x}_j, y_j) \in X_{iL}} y_j$$

$$\ell_{X_{iR}} = \frac{1}{|X_{iR}|} \sum_{(\mathbf{x}_j, y_j) \in X_{iR}} y_j$$

Squared
error loss

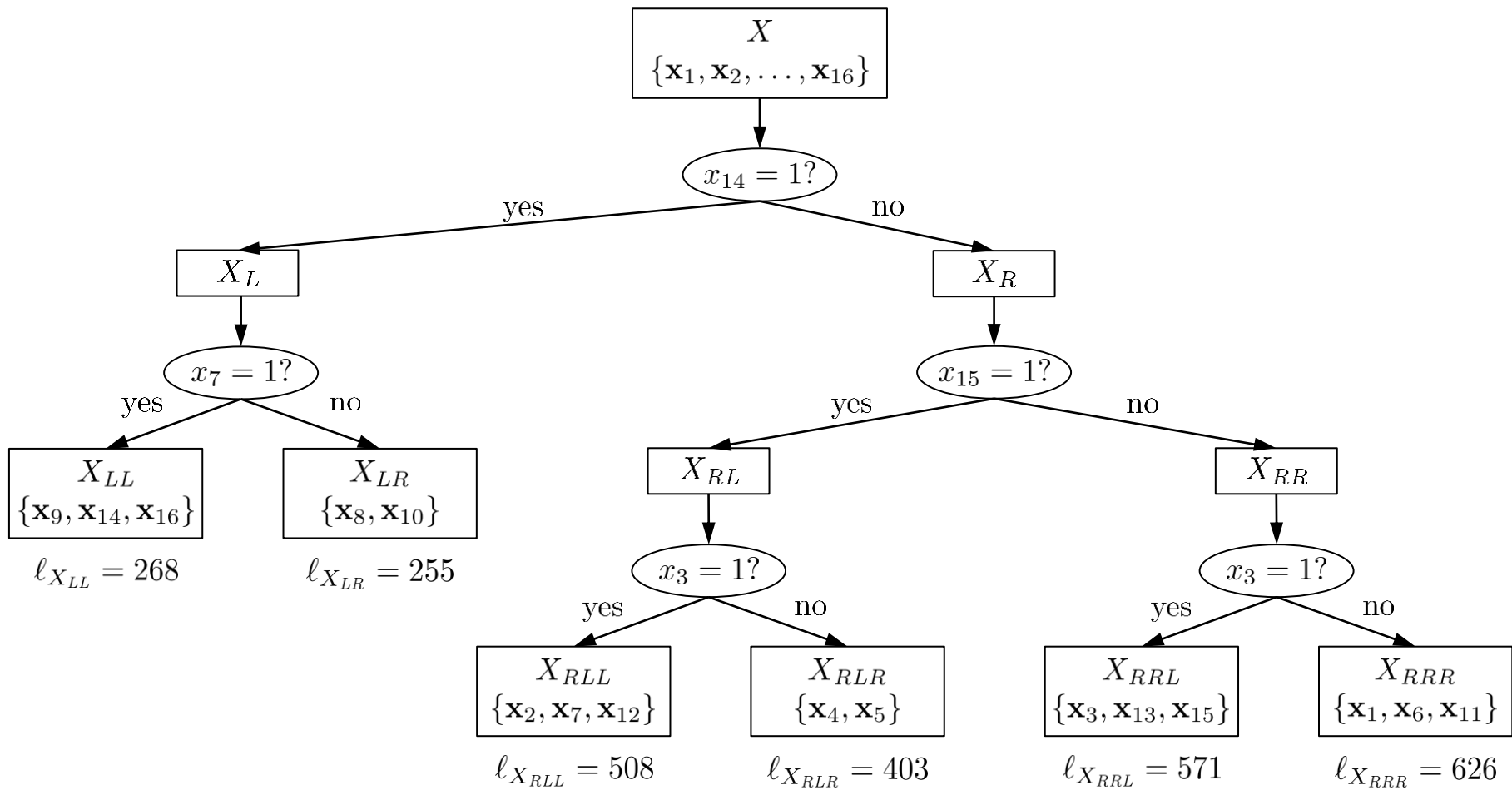
$$\sum_{(\mathbf{x}_j, y_j) \in X_{iL}} (y_j - \ell_{X_{iL}})^2$$

$$\sum_{(\mathbf{x}_j, y_j) \in X_{iR}} (y_j - \ell_{X_{iR}})^2$$

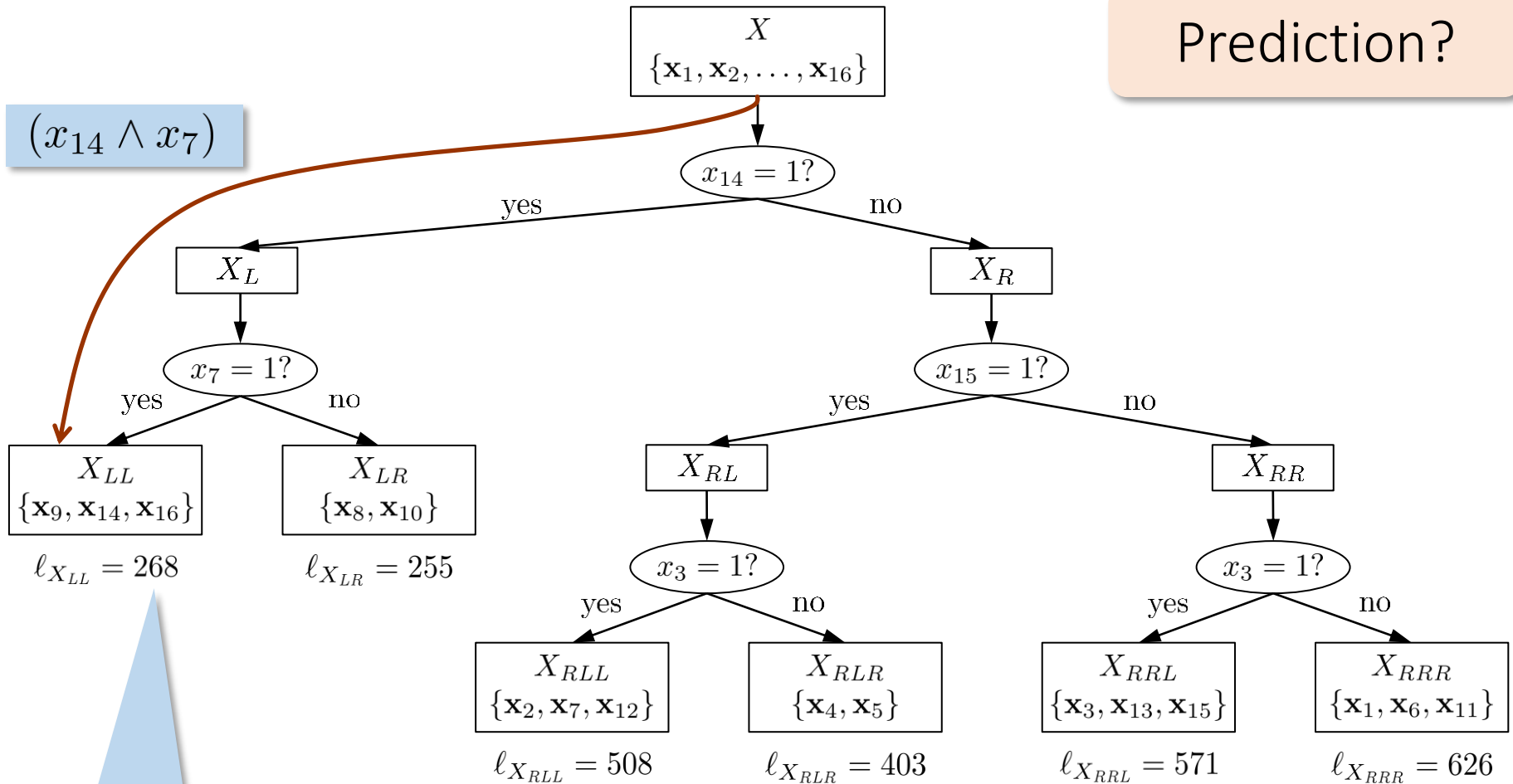
Sum of squared
error loss

$$\sum_{(\mathbf{x}_j, y_j) \in X_{iL}} (y_j - \ell_{X_{iL}})^2 + \sum_{(\mathbf{x}_j, y_j) \in X_{iR}} (y_j - \ell_{X_{iR}})^2$$

is minimal!



Prediction?

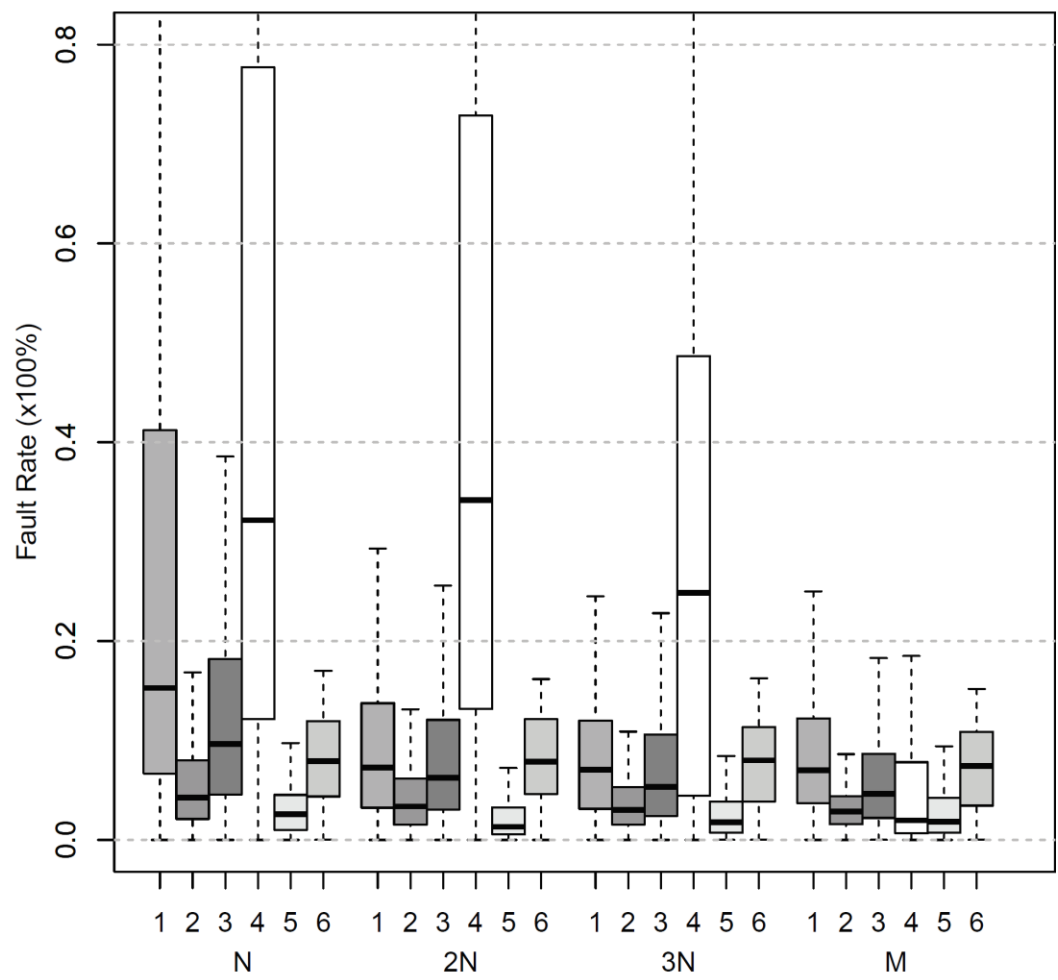


Predicted value
for any configuration
selecting feature x_{14}
and feature x_7

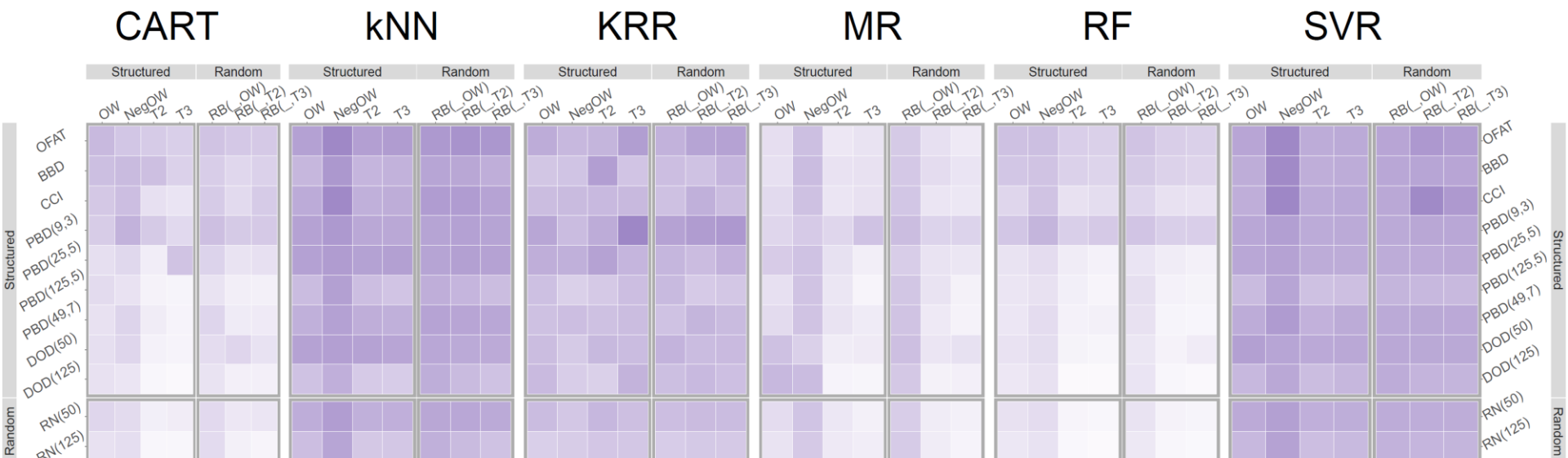
Empirical Results

	System	Domain	Lang.	LOC	$ P $	N	M
1	APACHE	Web Server	C	230,277	192	9	29
2	LLVM	Compiler	C++	47,549	1,024	11	62
3	x264	Encoder	C	45,743	1,152	16	81
4	BERKELEY DB	Database	C	219,811	2,560	18	139
5	BERKELEY DB	Database	JAVA	42,596	400	26	48
6	SQLITE	Database	C	312,625	3,932,160	39	566

$N = |F|$ M = Number of configurations required by pair-wise sampling



More Sampling & Learning Strategies



Learning strategies

CART	Classification and Regression Tree
kNN	k-Nearest-Neighbors Regression
KRR	Kernel Ridge Regression
MR	Multiple Linear Regression
RF	Random Forest
SVR	Support Vector Regression

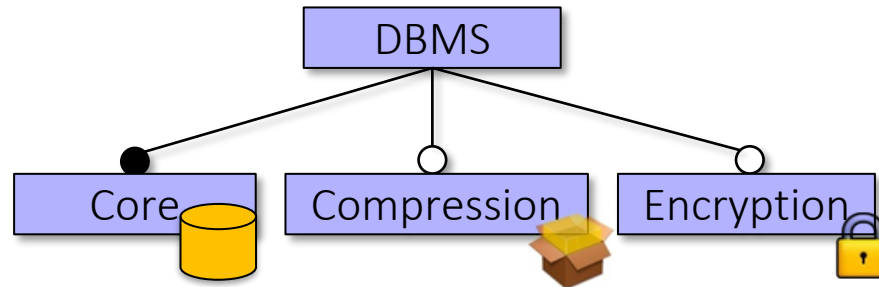
Sampling strategies

OW	Option-wise
T*	T-wise
NewOW	Negative Option-wise
RB	Random (Binary)
OFAT	One Factor At A Time
BBD	Box-Behnken Design
CCI	Central Composite Inscribed Design
PBD	Plackett-Burman Design
DOD	D-Optimal Design
RN	Random (Numeric)

Part III

Non-Functional Feature Interactions

Example



$$\text{clock}(\text{cylinder}) = 100\text{s}$$

$$\text{clock}(\text{cylinder}, \text{box}) = 120\text{s}$$

$$\Delta(\text{box}) = 20\text{s}$$

$$\text{clock}(\text{cylinder}) = 100\text{s}$$

$$\text{clock}(\text{cylinder}, \text{lock}) = 130\text{s}$$

$$\Delta(\text{lock}) = 30\text{s}$$

$$\begin{aligned} \Pi(\text{cylinder}, \text{box}, \text{lock}) &= \text{clock}(\text{cylinder}) + \Delta(\text{box}) + \Delta(\text{lock}) \\ &= 150\text{s} \end{aligned}$$

Example

Π

Predicted
performance



Measured
performance

$$\begin{aligned}\Pi(\text{cylinder}, \text{box}, \text{lock}) &= \text{stopwatch}(\text{cylinder}) + \Delta(\text{box}) + \Delta(\text{lock}) \\ &= 100s + 20s + 30s \\ &= 150s\end{aligned}$$



$$\text{stopwatch}(\text{cylinder}, \text{box}, \text{lock}) = 140s$$

Feature interaction:



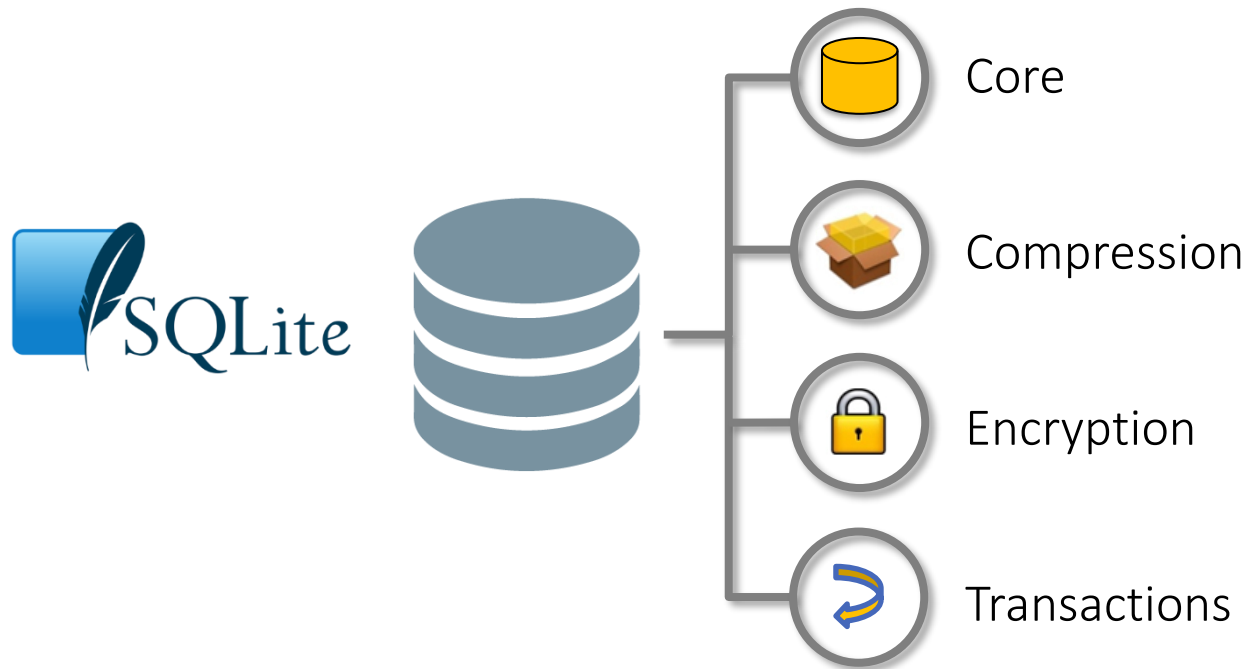
due to encrypting compressed data

Definition

$$\begin{array}{c}
 f \notin c_{\min} \quad f' \notin c_{\min} \\
 \text{selectable}(\Psi, f) \quad \text{selectable}(\Psi, f') \quad \text{selectable}(\Psi, f \wedge f') \\
 \left| \left(\text{cost}(c_{\min} \cup \{f\}) + \text{cost}(c_{\min} \cup \{f'\}) \right) - \text{cost}(c_{\min} \cup \{f, f'\}) \right| > \varepsilon \\
 \hline
 \text{interact}(f, f', \Psi)
 \end{array}$$

c_{\min} : Minimal configuration (minimal set of features)

Influence Models

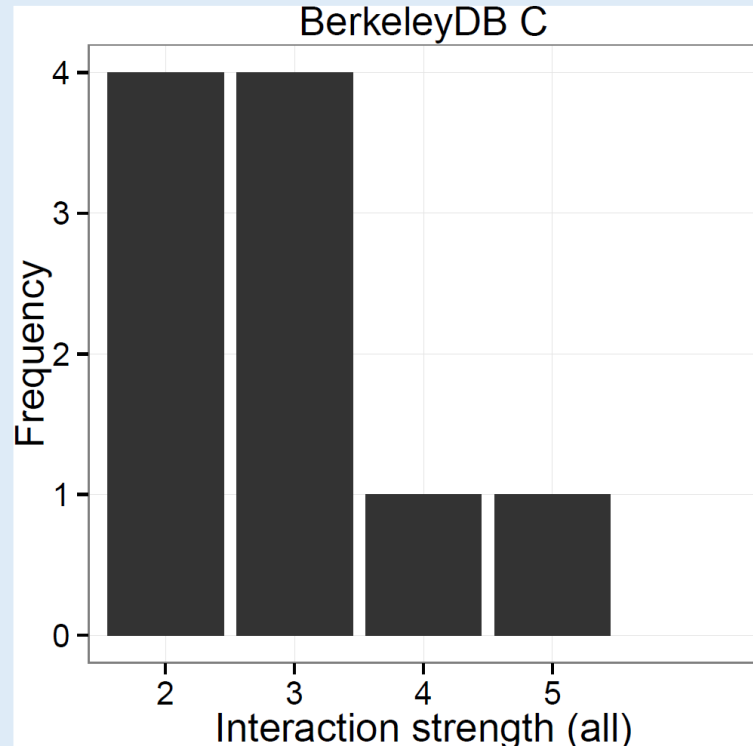
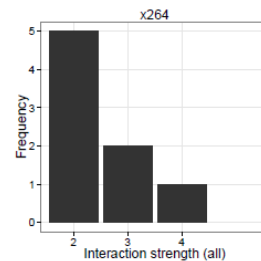
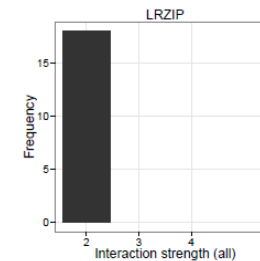
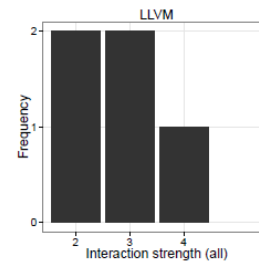
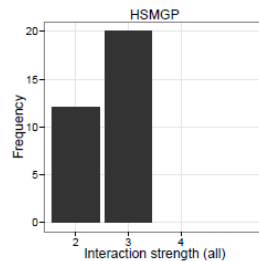
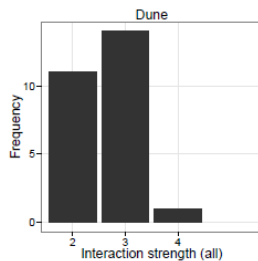
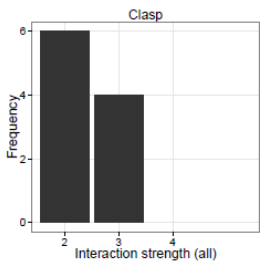
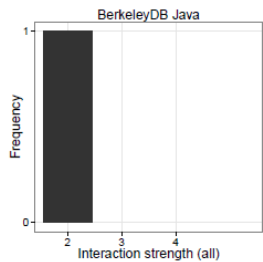
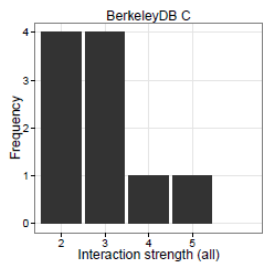
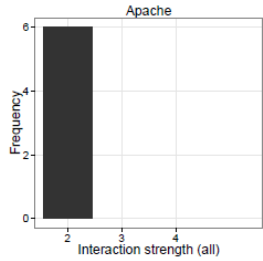


$$100 \cdot \text{Core} + 20 \cdot \text{Compression} + 30 \cdot \text{Encryption} + 10 \cdot \text{Transactions} + 10 \cdot \text{Compression} \cdot \text{Encryption}$$

A brown curly brace is positioned under the last term, $10 \cdot \text{Compression} \cdot \text{Encryption}$, indicating a feature interaction.

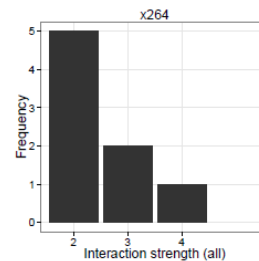
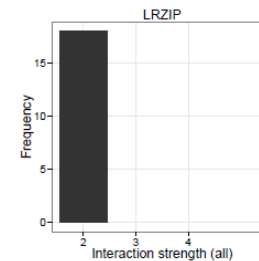
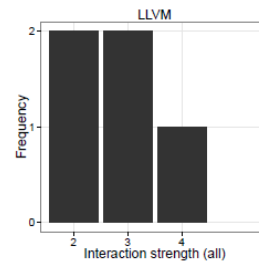
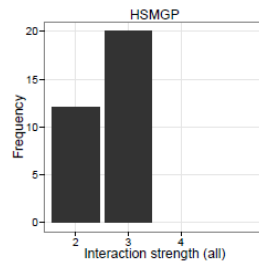
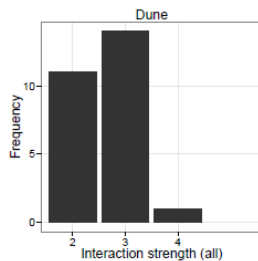
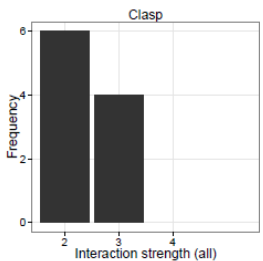
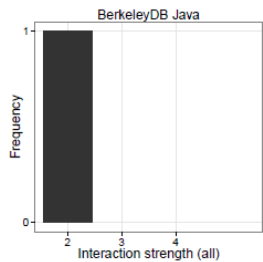
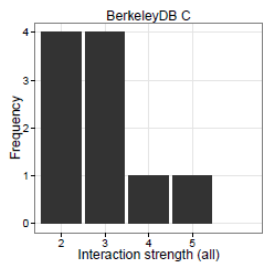
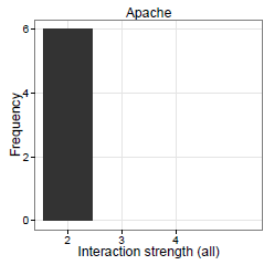
Feature Interaction!

Performance Interactions

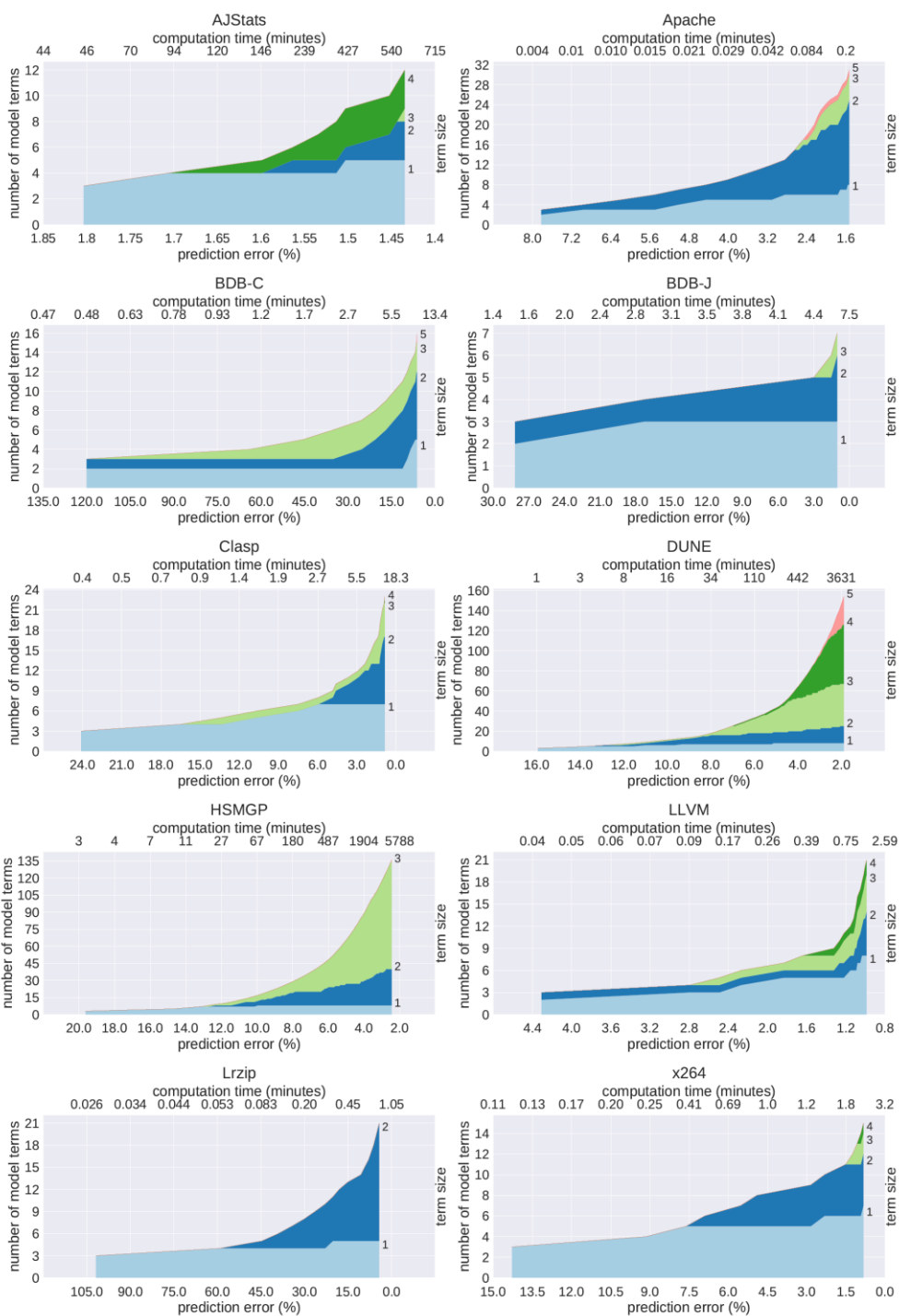


Performance Interactions

Two confirmed performance bugs in the LLVM extension Polly



Feature Interactions vs. Prediction Error



Comprehension



JUQUEEN – Jülich Blue Gene/Q
(458.752 Cores, 5.9 Petaflops)

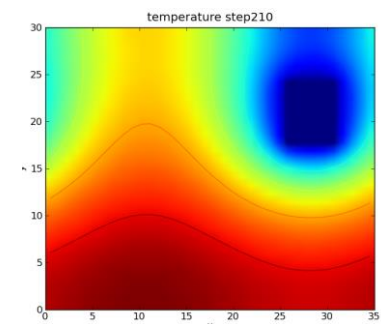
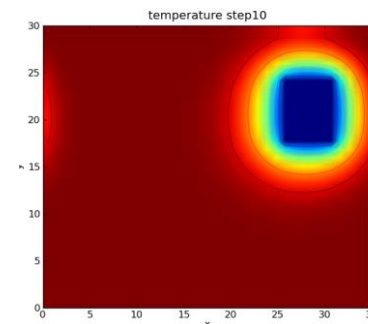


Matthias Boltén



Christian Engwer

$$\frac{\partial u}{\partial t} - \alpha \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) = 0$$



Comprehension

```
2667.4 - 343.8 * log2( numNodes ) * numPre - 926.5 * log2( numNodes ) * numPost -
33.3 * log2( numNodes ) - 317.5 * log2( numNodes ) - 76.9 * mpi_CustomDatatypes +
1545.2 * numPre - 6.4E7 * numPost - 0.1 * log2( numNodes ) * ( 64 - numNodes ) - 0.3 *
log2( numNodes ) * ( 64 - numNodes ) * log2( ranksPerNode ) + 2.3 * log2( numNodes ) *
numPre * ( 64.0 - numNodes ) - 0.4 * log2( numNodes ) * numPre * ( 64.0 - numNodes ) *
log2( tileSize_x ) - 0.5 * log2( numNodes ) * numPre * ( 64.0 - numNodes ) * log2(
ranksPerNode ) - 0.1 * log2( numNodes ) * numPre * ( 64.0 - numNodes ) * log2(
ranksPerNode ) * vectorize + 0.06 * numPost * ( 1.0E9 - tileSize_x ) + 101.0 * log2(
numNodes ) * numPost * log2( numNodes ) - 0.4 * log2( ranksPerNode ) * ( 64.0 -
ranksPerNode ) + 1.0 * log2( ranksPerNode ) * numNodes - 111.1 * log2( ranksPerNode )
- 174.3 * log2( numNodes ) + 0.006 * log2( ranksPerNode ) * numNodes * ( 64 -
numNodes ) - 0.7 * log2( numNodes ) * log2( ranksPerNode ) - 0.03 * log2( numNodes )
* ( 64.0 - ranksPerNode ) - 0.03 * log2( numNodes ) * ( 64 - numNodes ) - 4.5 * log2(
numNodes ) - 2.7 * mpi_CustomDatatypes * ranksPerNode - 16.3 *
mpi_CustomDatatypes * ( 4.0 - minLevel ) - 86.7 * omp_parallelizeLoopOverDimensions
+ 2.2 * mpi_CustomDatatypes * ranksPerNode * log2( numNodes )
```

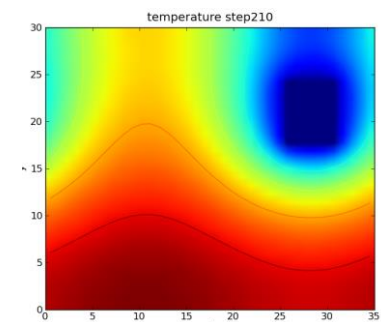
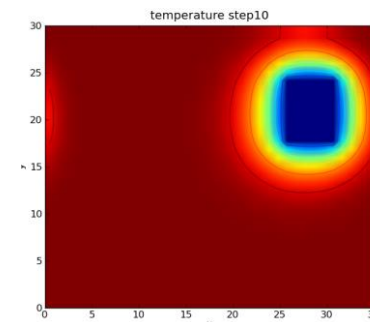


Matthias Boltén



Christian Engwer

$$\frac{\partial u}{\partial t} - \alpha \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) = 0$$



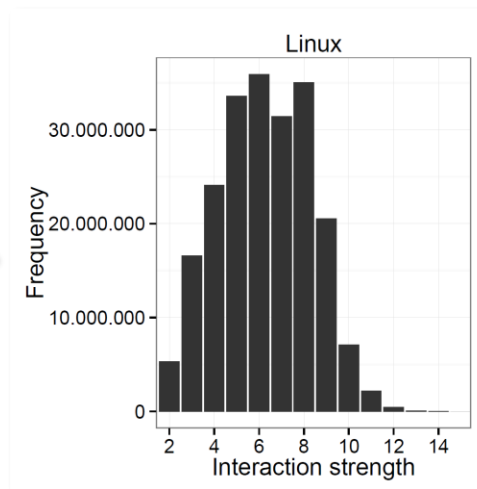
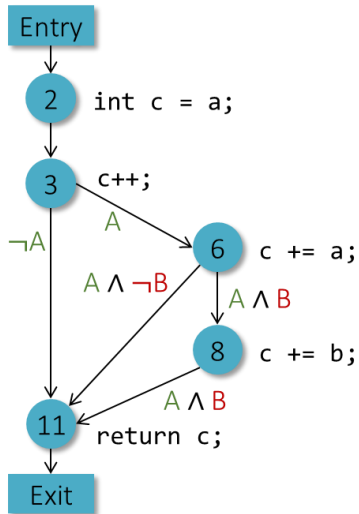


the road not taken

**Two Roads Diverged In A Yellow Wood,
And Sorry I Could Not Travel Both.**

Perspectives

Properties &
Distribution?



Correlation?



Prediction?

$$\Pi(\text{📦}, \text{🔒}) = 60s$$

Literature

T. Xu, et al.: *Hey, you have given me too many knobs!: understanding and dealing with over-designed configuration in system software*. Proceedings ESEC/FSE. 307-319, ACM, 2015

N. Siegmund, et al.: *Performance-influence models for highly configurable systems*. Proceedings ESEC/FSE, 284-294, ACM, 2015

J. Guo, et al.: *Data-efficient performance learning for configurable systems*. EMSE 23(3): 1826-1867, 2018

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S. Kolesnikov, et al.: *Tradeoffs in modeling performance of highly configurable software systems*. SoSyM 18(3): 2265-2283, 2019

S. Apel, et al.: *Exploring feature interactions in the wild: The new feature-interaction challenge*. Proceedings FOSD, 1-8, ACM, 2013

Quiz

Model A:

$$1000 - 250 \cdot \text{AccessLog} - 150 \cdot \text{HostnameLookups}$$

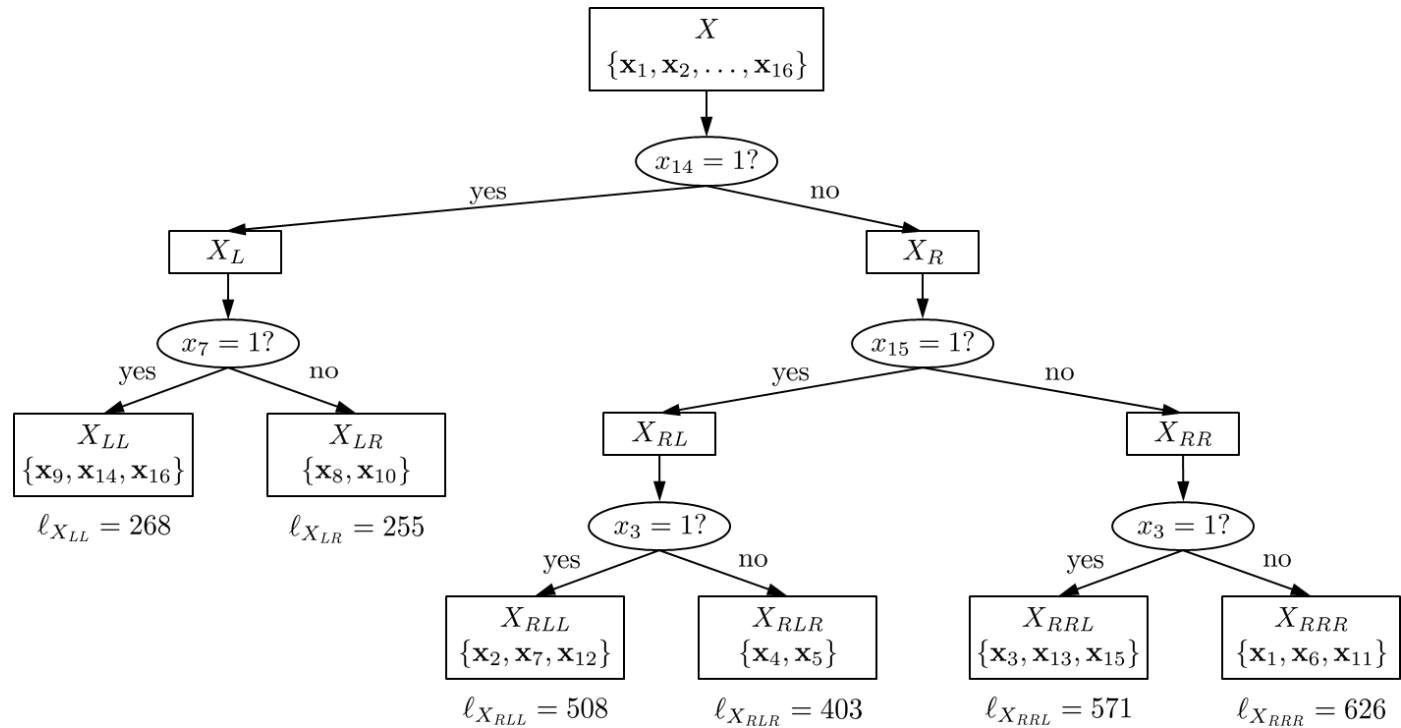
Model B:

$$\begin{aligned} &1000 - 250 \cdot \text{AccessLog} - 150 \cdot \text{HostnameLookups} \\ &+ 100 \cdot \text{AccessLog} \cdot \text{HostnameLookups} \\ &+ 2 \cdot \text{AccessLog} \cdot \text{EnableSendfile} \cdot \text{KeepAlive} \\ &+ 1 \cdot \text{EnableSendfile} \cdot \text{FollowSymLinks} \cdot \text{Handle} \end{aligned}$$

Calculate the predicted performance:

Configuration	Measured	Prediction (Model A)	Prediction (Model B)
AccessLog	750		
HostnameLookups	850		
AccessLog, HostnameLookups	600		
AccessLog, EnableSendfile, KeepAlive	750		
AccessLog, EnableSendfile, Handle	750		
AccessLog, EnableSendfile, FollowSymLinks, Handle	750		

Quiz



Calculate the predicted performance:

Configuration	Prediction
$\neg x_3 \wedge \neg x_{14} \wedge x_{15}$	
$x_3 \wedge \neg x_7 \wedge \neg x_{14} \wedge \neg x_{15}$	
$x_7 \wedge x_{14} \wedge \neg x_{16}$	
\mathbf{x}_4	
\mathbf{x}_8	
\mathbf{x}_{10}	