

Robot Navigation Project - Sequence Classification

This dataset was obtained from the UCI Machine Learning Repository.

You can find more information on this dataset here:

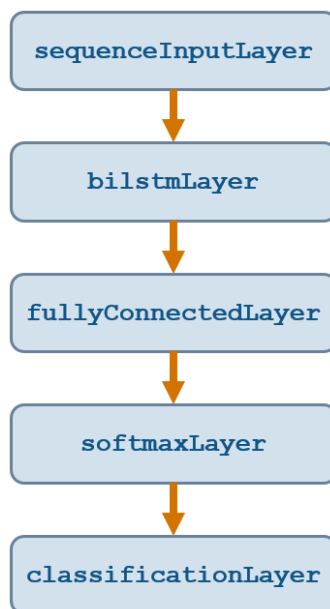
<https://archive.ics.uci.edu/ml/datasets/Wall-Following+Robot+Navigation+Data>

Load the processed sensor data. This mat file contains 4 variables for the sensor data and the robot's action.

- XTrain: A matrix with 2 columns, one for each sensor reading. The first row is the sensor reading from the front of the robot, and the second row is the sensor reading from the left of the robot.
- XTest: The last 1000 time steps are reserved for testing.
- YTrain and YTest: The action the robot should take at a time step. At any point, the robot can either move forward, turn slightly to the left, turn slightly to the right, or turn sharply to the right.

```
load robotDataProcessed.mat
```

Network architecture



```
layers = [  
    sequenceInputLayer(2)  
    bilstmLayer(100,"OutputMode","sequence")  
    fullyConnectedLayer(4)  
    softmaxLayer()  
    classificationLayer()]
```

```
layers =  
5x1 Layer array with layers:
```

```
1    ''    Sequence Input          Sequence input with 2 dimensions
```

```

2  ''  BiLSTM                      BiLSTM with 100 hidden units
3  ''  Fully Connected             4 fully connected layer
4  ''  Softmax                     softmax
5  ''  Classification Output       crossentropyex

```

Train the network

```
options=trainingOptions("adam","MaxEpochs",100,"InitialLearnRate",0.05,"Plots","training-progress")
```

```

X = 2x4456
    1.6870    1.6870    1.6870    1.6870    1.6870    1.6860    1.6840    1.6800 ...
    0.4450    0.4490    0.4490    0.4490    0.4490    0.4460    0.4510    0.4530

```

```
Y = 1x4456 categorical
```

```
Slight-Right-Turn    Slight-Right-Turn    Slight-Right-Turn    Slight-Right-Turn ...
```

```
options =
```

```
TrainingOptionsADAM with properties:
```

```

    GradientDecayFactor: 0.9000
    SquaredGradientDecayFactor: 0.9990
        Epsilon: 1.0000e-08
        InitialLearnRate: 0.0500
        LearnRateSchedule: 'none'
        LearnRateDropFactor: 0.1000
        LearnRateDropPeriod: 10
        L2Regularization: 1.0000e-04
    GradientThresholdMethod: 'l2norm'
        GradientThreshold: Inf
        MaxEpochs: 100
        MiniBatchSize: 128
        Verbose: 1
        VerboseFrequency: 50
        ValidationData: []
        ValidationFrequency: 50
        ValidationPatience: Inf
        Shuffle: 'once'
        CheckpointPath: ''
    ExecutionEnvironment: 'auto'
        WorkerLoad: []
        OutputFcn: []
        Plots: 'training-progress'
        SequenceLength: 'longest'
        SequencePaddingValue: 0
        SequencePaddingDirection: 'right'
        DispatchInBackground: 0
        ResetInputNormalization: 1

```

Train the LSTM network.

```
net = trainNetwork(X,Y,layers,options)
```

Training on single CPU.

Epoch	Iteration	Time Elapsed (hh:mm:ss)	Mini-batch Accuracy	Mini-batch Loss	Base Learning Rate
1	1	00:00:02	37.46%	1.3853	0.0500

```
options2=trainingOptions("adam","MaxEpochs",200,"InitialLearnRate",0.05,"Plots","training-progress")
```

```
net2 = trainNetwork(X,Y,layers,options2)
```

```
options3=trainingOptions("adam","MaxEpochs",300,"InitialLearnRate",0.05,"Plots","training-progress")
```

```
pred = 1×1000 categorical
```

```
Move-Forward      Sharp-Right-Turn      Move-Forward      Move-Forward      Move-Forward ...
```

```
options3 =
```

```
TrainingOptionsADAM with properties:
```

```

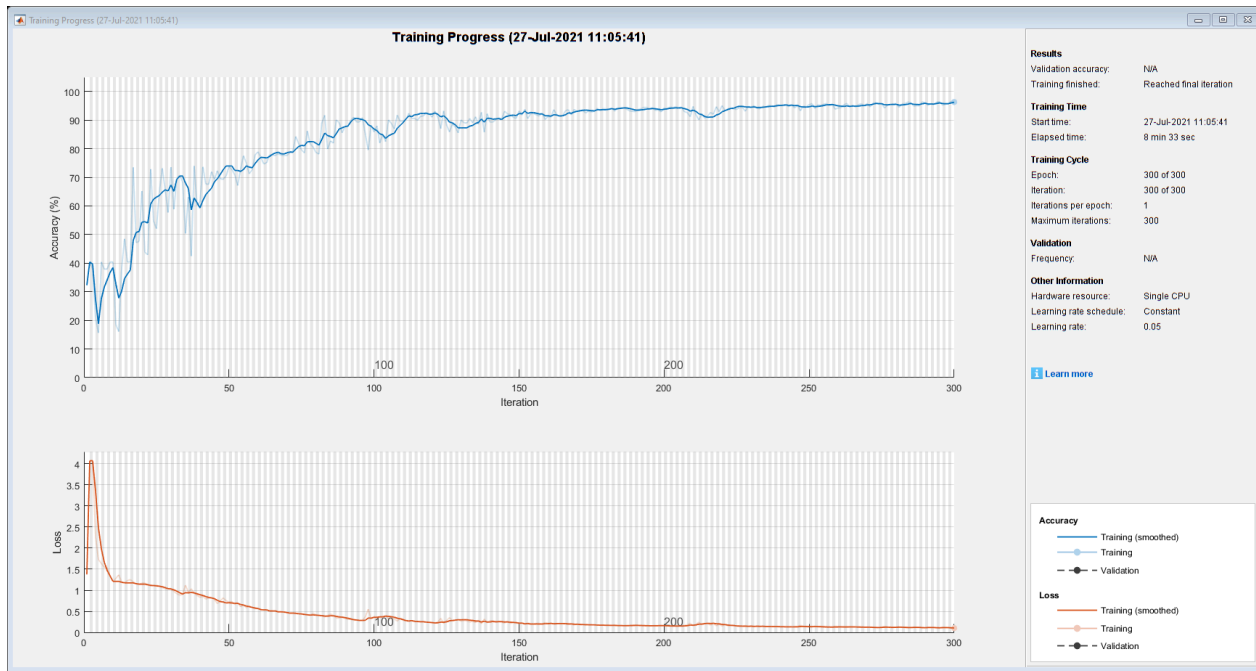
    GradientDecayFactor: 0.9000
    SquaredGradientDecayFactor: 0.9990
        Epsilon: 1.0000e-08
    InitialLearnRate: 0.0500
    LearnRateSchedule: 'none'
    LearnRateDropFactor: 0.1000
    LearnRateDropPeriod: 10
    L2Regularization: 1.0000e-04
    GradientThresholdMethod: 'l2norm'
    GradientThreshold: Inf
    MaxEpochs: 300
    MiniBatchSize: 128
    Verbose: 1
    VerboseFrequency: 50
    ValidationData: []
    ValidationFrequency: 50
    ValidationPatience: Inf
    Shuffle: 'once'
    CheckpointPath: ''
    ExecutionEnvironment: 'auto'
    WorkerLoad: []
    OutputFcn: []
    Plots: 'training-progress'
    SequenceLength: 'longest'
    SequencePaddingValue: 0
    SequencePaddingDirection: 'right'
    DispatchInBackground: 0
    ResetInputNormalization: 1

```

```
net3= trainNetwork(X,Y,layers,options3)
```

Training on single CPU.

Epoch	Iteration	Time Elapsed (hh:mm:ss)	Mini-batch Accuracy	Mini-batch Loss	Base Learning Rate
1	1	00:00:02	32.29%	1.3758	0.0500
50	50	00:01:31	73.68%	0.7236	0.0500
100	100	00:03:02	85.86%	0.3807	0.0500
150	150	00:04:24	93.18%	0.2103	0.0500
200	200	00:05:48	94.19%	0.1587	0.0500
250	250	00:07:10	95.42%	0.1275	0.0500
300	300	00:08:33	96.30%	0.1036	0.0500



```
net3 =
  SeriesNetwork with properties:

    Layers: [5x1 nnet.cnn.layer.Layer]
    InputNames: {'sequenceinput'}
    OutputNames: {'classoutput'}
```

Plot confusion matrix

```
pred3=classify(net3,XTest)
```

```
pred3 = 1x1000 categorical
Slight-Left-Turn    Slight-Left-Turn    Slight-Left-Turn    Slight-Left-Turn    ...
```

```
confusionchart(YTest,pred3)
```

True Class	Move-Forward	350	23	1	30
	Sharp-Right-Turn	1	405	2	
	Slight-Left-Turn			79	
	Slight-Right-Turn	3			106
		Move-Forward	Sharp-Right-Turn	Slight-Left-Turn	Slight-Right-Turn
		Predicted Class			