

# Sobel Filter

GNR-607 Course Project

# THEORY

— — —

- ❖ Apply sobel mask for x-direction
- ❖ Apply sobel mask for y-direction
- ❖ Let **A** be the source image
- ❖ Consider **G<sub>x</sub>** and **G<sub>y</sub>** are two images, each point contain the horizontal & vertical derivative approximations respectively

# Computation

— — —

$$\mathbf{G}_x = \begin{bmatrix} -1 & 0 & +1 \\ -2 & 0 & +2 \\ -1 & 0 & +1 \end{bmatrix} * \mathbf{A} \quad \text{and} \quad \mathbf{G}_y = \begin{bmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ +1 & +2 & +1 \end{bmatrix} * \mathbf{A}$$

where \*denotes the 2-dimensional signal processing convolution operation

The matrix used in  $\mathbf{G}_x$  is sobel operator for x-axis

The matrix used in  $\mathbf{G}_y$  is sobel operator for y-axis

# Computation

— — —

At each point in the image, the resulting gradient approximations can be combined to give the gradient magnitude, using:

$$\mathbf{G}^2 = \mathbf{G}_x^2 + \mathbf{G}_y^2$$

Finally we display the magnitude **G** as the final output.

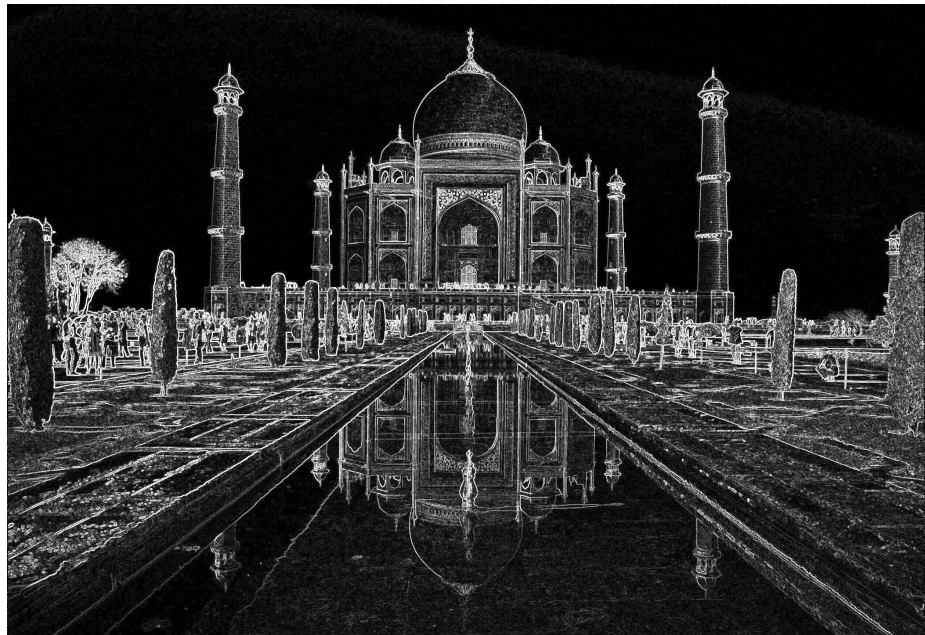
We can also apply a threshold while displaying the image

# Sample Output

— — —



# Sample Output





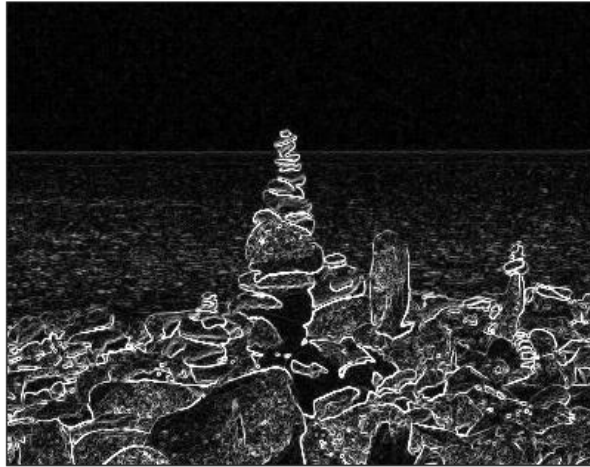
# GUI Interface

Threshold

**Input Image**



**Intensity Gradient**



**Edge Detected Image**

