Graph Neural Networks

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Recap



- ► Complex graphs can be successfully generated via sequential generation using deep learning.
- Two of the ways that we can do this by leveraging RNNs or Reinforcement Learning.
- In GraphRNN, we sequentially predict nodes and then edge connections for these nodes.
- ► In GCPN (RL based method), the model predicts potential links using node embeddings.

Deep Learning Performance



- ► Recent years have seen impressive performance of deep learning models in a variety of applications.
- ► For example, In computer vision, deep convolutional networks have achieved human-level performance on ImageNet (image category classification).
- ▶ But are these models ready to be deployed in real world?

Adversarial Examples



- Deep convolutional neural networks are vulnerable to adversarial attacks.
- ► For example, Imperceptible noise changes the prediction.



Adversarial examples are also reported in natural language processing [Jia Liang et al. EMNLP 2017] and audio processing [Carlini et al. 2018] domains.

Implications



- ► The existence of adversarial examples prevents the reliable deployment of deep learning models to the real world.
 - Adversaries may try to actively hack the deep learning models.
 - The model performance can become much worse than we expect.
- ▶ Deep learning models are often not robust.
 - In fact, it is an active area of research to make these models robust against adversarial examples.

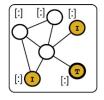
Graph Adversarial Learning



- ► Common applications of GNNs involve public platforms and monetary interests.
 - Recommender systems
 - Social networks
 - Search engines
- Adversaries have the incentive to manipulate input graphs and hack GNNs' predictions.

Graph Adversarial Learning (cont.)



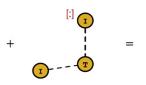


Prediction



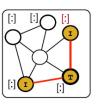
"Class 2"

80.4% confidence



Perturbations

- Target
- Influencer
- Class1
- Class2
- Class3
- [:] Node features



Prediction



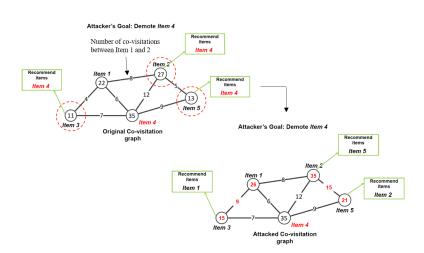
"Class 3"

92.1% confidence

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Graph Adversarial Learning (cont.)

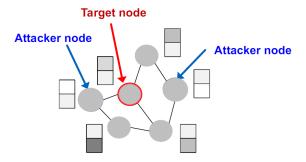




Attack Possibilities



- ▶ What are the attack possibilities in real world?
 - Target node $t \in V$: node whose label prediction we want to change.
 - Attacker nodes $S \subset V$: nodes the attacker can modify.



Direct Attack



- ▶ Direct Attack: Attacker node is the target node: S = {t}
- ► Modify target node feature.
 - For example, change website content.
- Add connections to target.
 - For example, buy likes/followers.
- ▶ Remove connections from target.
 - For example, unfollow users.



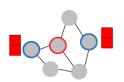




Indirect Attack



- ▶ **Indirect Attack:** The target node is not in the attacker nodes: $t \notin S$
- ► Modify attacker node features.
 - For example, hijack friends of targets.
- Add connections to attackers.
 - For example, create a link, link farm.
- ▶ Remove connections from attackers.
 - For example, delete undesirable link.



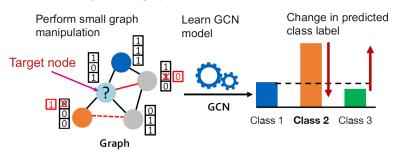




Formalizing Adversarial Attacks



- ▶ **Objective for the attacker:** Maximize (change of target node label prediction) Subject to (graph manipulation is small).
- ► If graph manipulation is too large, it will easily be detected. Successful attacks should change the target prediction with "unnoticeably-small" graph manipulation.



Mathematical Formulation



- ► Original graph:
 - A: adjacency matrix, X: feature matrix
- Manipulated graph (aXer adding noise):
 - A': adjacency matrix, X': feature matrix
- ▶ Assumption: $(A, X) \approx (A', X')$
 - Graph manipulation is unnoticeably small i.e., preserves basic graph statistics (e.g,. degree distribution) and feature statistics.
 - Graph manipulation is either direct (changing the feature/connection of target nodes) or indirect.



Overview of the attack framework

- ▶ Original adjacency matrix A, node features X, node labels Y.
- \bullet θ^* : Model parameter learned over A, X, Y.
 - c_v^* : class label of node v predicted by GCN with θ^* .
- \blacktriangleright An attacker has access to A, X, Y and the learning algorithm.
- ▶ The attacker modifies (A, X) into (A', X').
- \bullet $\theta^{*'}$: Model parameter learned over A', X', Y'.
 - $c_v^{*'}$: class label of node v predicted by GCN with $\theta^{*'}$.
- ▶ The goal of the attacker is to make $c_{v}^{*} \neq c_{v}^{*'}$.



- ▶ Target Node: $v \in V$.
- ► GCN learned over the original graph

$$\theta^* = \underset{\theta}{\operatorname{arg \; min}} \; \mathcal{L}_{\mathit{train}}(\theta; A, X)$$

► GCN's original prediction on the target node:

$$c_{\nu}^* = \underset{c}{\operatorname{arg}} \max_{c} f_{\theta^*}(A, X)_{\nu, c}$$



► GCN learned over the manipulated graph

$$\theta^{*'} = \underset{\theta}{\operatorname{arg min}} \ \mathcal{L}_{\textit{train}}(\theta; A', X')$$

► GCN's prediction on the target node:

$$c_{v}^{*'} = \underset{c}{\operatorname{arg max}} f_{\theta^{*'}}(A', X')_{v,c}$$

▶ We want the prediction to change after the graph is manipulated:

$$c_{v}^{*} \neq c_{v}^{*'}$$



Change of prediction on target node v:

$$\Delta(v; A', X') = \log f_{\theta^{*'}}(A', X')_{v,c_v^{*'}} - \log f_{\theta^{*'}}(A', X')_{v,c_v^{*}}$$

Predicted (log) probability of the newly-predicted class $c_{v}^{*\prime}$

Want to increase

Predicted (log) probability of the originally-predicted class c_v^*



Experiment



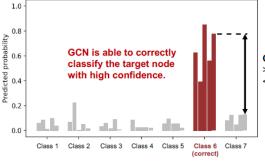
- ▶ **Setting:** Semi-supervised node classification with GCN.
- ► **Graph:** Paper citation network (2,800 nodes, 8,000 edges).
- ► Attack type: Edge modification (addition or deletion of edges).
- ▶ Attack budget on node v: $d_v + 2$ modifications (d_v : degree of node v).
 - Intuition: It is harder to attack a node with a larger degree.
- ▶ Model is trained and attacked 5 times using different random seeds.

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Experiment (cont.)



Predicted probabilities of a target node v over 5 retrainings (each bar represents a single trial) (without graph manipulation, i.e., clean graph)



Classification margin

- > 0: Correct classification
- < 0: Incorrect classification

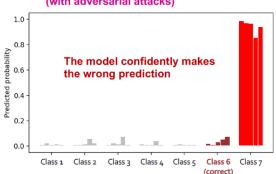
7-class classification

Experiment (cont.)



GCN's prediction after modifying 5 edges attached to the target node (direct adversarial attack).



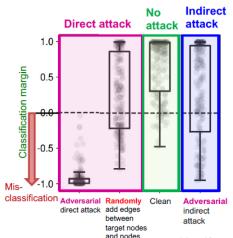


Experiment (cont.)



- ► Adversarial direct attack is the strongest attack, significantly worsening GCN's performance (compared to no attack).
- Random attack is much weaker than adversarial attack.
- Indirect attack is more challenging than direct attack.

Each dot indicates one attack trial.



with different

labels.

4 D > 4 B > 4 E > 4 E > 9 Q Q

Adopted from

Zügner et al.

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KDD 2018

Adversarial Defense on Graph



The defense methods can be categorized into three main categories.

- ▶ Adversarial Training: The model is made more resilient to adversarial attacks by training it on perturbed graphs as well as clean graphs during training.
- ▶ Adversarial Detection: These methods assume that the data has already been polluted and employ preprocessing methods to detect and remove/reduce the effect of attacks.
- ▶ **Robust Optimization:** These methods emply more robust loss functions to improve the robustness of models.

Summary



- Machine Learning models can be very senstive to very perturbations and can be tricked.
- GCN's prediction performance can be significantly harmed by adversarial attacks.
- ► GCN is not robust to adversarial attacks but it is somewhat robust to indirect attacks and random noise.
- Several defense methods exist which are used to improve the robustness of models.

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References



These slides have been adapted from

- ▶ Jure Leskovec, Stanford CS224W: Machine Learning with Graphs
- Stephan Gunnemann, Graph Neural Networks: Adversarial Robustness
- ▶ Jintang Li,Spectra: Adversarial Learning on Graph Introduction