### Introduction - IMAGE TO SKETCH CONVERSION

Autoencoder is special type of deep learning architecture consisting of two networks a) encoder b)decoder. Encoder can be fully connected dense neural network or Convolution neural network. Encoder is used to downsample our original sample image into latent vector by passing image through Convolution layers and maxpool layer. Similary, decoder also can be fully connected neural network or Convolution neural network, decoder is used to upsample the latent vector downsampled by encoder. This upsampled latent vector is compared with the original input and reconstruction loss is calculated. Backpropagation is used to minimized this reconstruction loss. Simple autoencoder can be used for Domain transformation, denoising images, image colorization, anamoly detection etc. Here we are going to train my autoencoder model to generate sketch of the input image.

## **Objective:**

To convert image to sketch using autoencoder

### **Import Necessary Libraries**

```
import numpy as np
import tensorflow as tf
import keras
from keras.layers import Dense, Conv2D, MaxPool2D, UpSampling2D,
Dropout, Input
from tensorflow.keras.utils import img_to_array
import matplotlib.pyplot as plt
import cv2
from tqdm import tqdm
import os
import re
```

#### Load data

This dataset consist of 188 image and their corresponding sketches. As these images aren't enough for training our autoencoder model, we have augmented them using open cv library. After Augmentation we have got around 1500 images, these 1500 images. These images are converted into array and are stored in the list.

```
# to get the files in proper order
def sorted_alphanumeric(data):
    convert = lambda text: int(text) if text.isdigit() else
text.lower()
    alphanum_key = lambda key: [convert(c) for c in re.split('([0-9]+)',key)]
    return sorted(data,key = alphanum_key)

# defining the size of image
```

```
SIZE = 256
image_path = '/kaggle/input/cuhk-face-sketch-database-cufs/cuhk-face-
sketch-database-cufs/photos'
img array = []
sketch path = '/kaggle/input/cuhk-face-sketch-database-cufs/cuhk-face-
sketch-database-cufs/sketches'
sketch array = []
image file = sorted alphanumeric(os.listdir(image path))
sketch file = sorted alphanumeric(os.listdir(sketch path))
for i in tqdm(image file):
    image = cv2.imread(image path + '/' + i,1)
    # as opency load image in bgr format converting it to rgb
    image = cv2.cvtColor(image, cv2.COLOR BGR2RGB)
    # resizing images
    image = cv2.resize(image, (SIZE, SIZE))
    # normalizing image
    image = image.astype('float32') / 255.0
    #appending normal normal image
    img array.append(img to array(image))
    # Image Augmentation
    # horizontal flip
    img1 = cv2.flip(image, 1)
    img array.append(img to array(img1))
    #vertical flip
    img2 = cv2.flip(image, -1)
    img_array.append(img_to_array(img2))
    #vertical flip
    img3 = cv2.flip(image, -1)
    # horizontal flip
    img3 = cv2.flip(img3,1)
    img_array.append(img_to_array(img3))
    # rotate clockwise
    img4 = cv2.rotate(image, cv2.ROTATE 90 CLOCKWISE)
    img array.append(img to array(img4))
    # flip rotated image
    img5 = cv2.flip(img4,1)
    img_array.append(img_to array(img5))
     # rotate anti clockwise
    img6 = cv2.rotate(image, cv2.ROTATE 90 COUNTERCLOCKWISE)
    img array.append(img to array(img6))
```

```
# flip rotated image
    img7 = cv2.flip(img6,1)
    img_array.append(img_to_array(img7))
for i in tqdm(sketch file):
    image = cv2.imread(sketch path + '/' + i,1)
    # as opencv load image in bgr format converting it to rgb
    image = cv2.cvtColor(image, cv2.COLOR BGR2RGB)
    # resizing images
    image = cv2.resize(image, (SIZE, SIZE))
    # normalizing image
    image = image.astype('float32') / 255.0
    # appending normal sketch image
    sketch_array.append(img_to_array(image))
    #Image Augmentation
    # horizontal flip
    img1 = cv2.flip(image, 1)
    sketch array.append(img to array(img1))
    #vertical flip
    img2 = cv2.flip(image, -1)
    sketch array.append(img to array(img2))
    #vertical flip
    img3 = cv2.flip(image, -1)
    # horizontal flip
    img3 = cv2.flip(img3,1)
    sketch array.append(img to array(img3))
    # rotate clockwise
    img4 = cv2.rotate(image, cv2.ROTATE 90 CLOCKWISE)
    sketch array.append(img to array(img4))
    # flip rotated image
    img5 = cv2.flip(img4,1)
    sketch array.append(img to array(img5))
    # rotate anti clockwise
    img6 = cv2.rotate(image, cv2.ROTATE 90 COUNTERCLOCKWISE)
    sketch array.append(img to array(img6))
    # flip rotated image
    img7 = cv2.flip(img6,1)
    sketch array.append(img to array(img7))
```

```
| 188/188 [00:05<00:00, 36.05it/s]
| 100% | 188/188 [00:02<00:00, 82.54it/s]
| print("Total number of sketch images:",len(sketch_array))
| print("Total number of images:",len(img_array))
| Total number of sketch images: 1504
| Total number of images: 1504
```

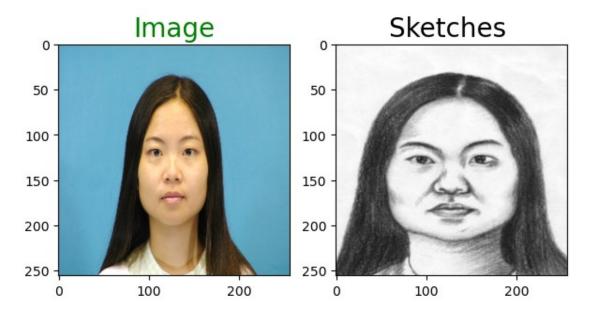
# Visualizing images

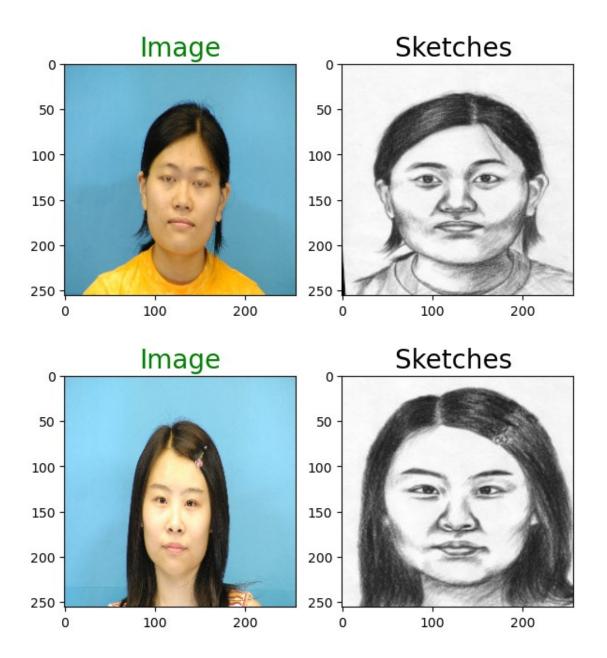
Here we have plotted all augmented images and its augmented sketches

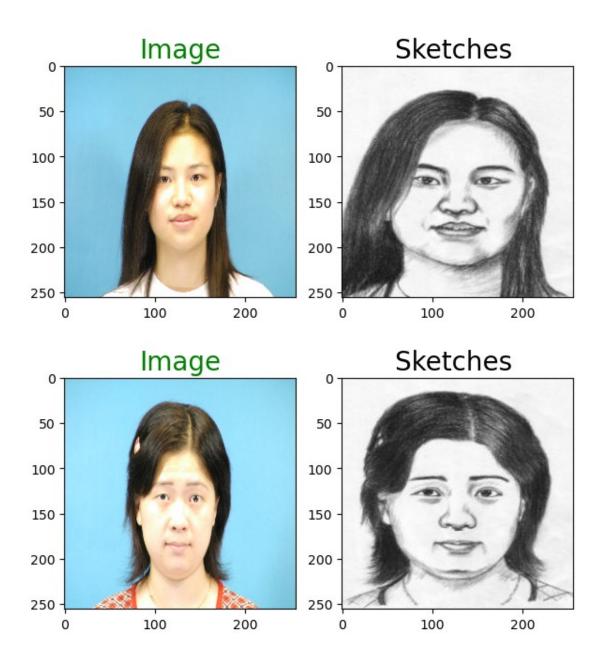
```
# defining function to plot images pair
def plot_images(image, sketches):
    plt.figure(figsize=(7,7))
    plt.subplot(1,2,1)
    plt.title('Image', color = 'green', fontsize = 20)
    plt.imshow(image)
    plt.subplot(1,2,2)
    plt.title('Sketches ', color = 'black', fontsize = 20)
    plt.imshow(sketches)

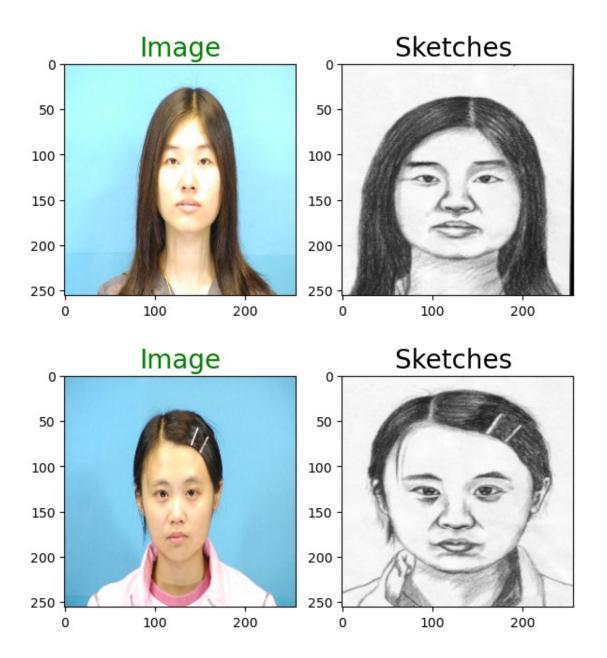
    plt.show()

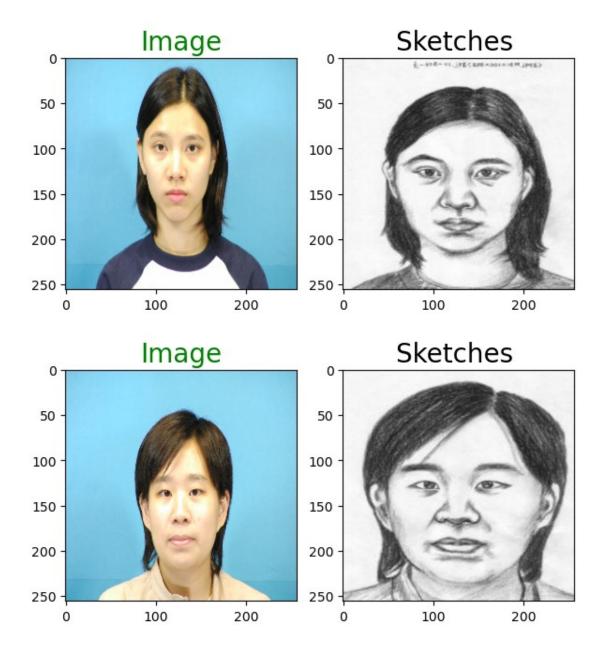
ls = [i for i in range(0,65,8)]
for i in ls:
    plot_images(img_array[i],sketch_array[i])
```











# Slicing and reshaping

Out of 1504 images We have sliced them to two part. train images consist 1400 images while test images contains 104 images. After slicing image array, we reshaped them so that images can be fed directly into our encoder network

```
train_sketch_image = sketch_array[:1400]
train_image = img_array[:1400]
test_sketch_image = sketch_array[1400:]
test_image = img_array[1400:]
# reshaping
train_sketch_image = np.reshape(train_sketch_image,
(len(train_sketch_image),SIZE,SIZE,3))
```

```
train image = np.reshape(train image, (len(train image),SIZE,SIZE,3))
print('Train color image shape:',train image.shape)
test sketch image = np.reshape(test sketch image,
(len(test sketch image), SIZE, SIZE, 3))
test_image = np.reshape(test_image, (len(test_image),SIZE,SIZE,3))
print('Test color image shape',test image.shape)
Train color image shape: (1400, 256, 256, 3)
Test color image shape (104, 256, 256, 3)
Downsample layer
def downsample(filters, size, apply batch normalization = True):
    downsample = tf.keras.models.Sequential()
    downsample.add(keras.layers.Conv2D(filters = filters, kernel size
= size, strides = 2, use bias = False, kernel initializer =
'he normal'))
    if applv batch normalization:
        downsample.add(keras.layers.BatchNormalization())
    downsample.add(keras.layers.LeakyReLU())
    return downsample
Upsample Layer
def upsample(filters, size, apply dropout = False):
    upsample = tf.keras.models.Sequential()
    upsample.add(keras.layers.Conv2DTranspose(filters = filters,
kernel size = size, strides = 2, use bias = False, kernel initializer
= 'he normal'))
    if apply dropout:
        upsample.add(tf.keras.layers.Dropout(0.1))
    upsample.add(tf.keras.layers.LeakyReLU())
    return upsample
Model
Here we have use sequence of downsample layer for encoder and upsample layer for
decoder
def model():
    encoder input = keras.Input(shape = (SIZE, SIZE, 3))
    x = downsample(16, 4, False)(encoder_input)
    x = downsample(32,4)(x)
    x = downsample(64, 4, False)(x)
    x = downsample(128,4)(x)
    x = downsample(256,4)(x)
    encoder output = downsample(512,4)(x)
```

decoder input = upsample(512,4,True)(encoder output)

x = upsample(256, 4, False)(decoder input)

```
x = upsample(128,4, True)(x)
x = upsample(64,4)(x)
x = upsample(32,4)(x)
x = upsample(16,4)(x)
x = tf.keras.layers.Conv2DTranspose(8,(2,2),strides = (1,1),
padding = 'valid')(x)
decoder_output = tf.keras.layers.Conv2DTranspose(3,(2,2),strides = (1,1), padding = 'valid')(x)
```

return tf.keras.Model(encoder\_input, decoder\_output)

```
# to get summary of model
model = model()
model.summary()
```

Model: "model"

Layer (type)	Output Shape	Param #
input_1 (InputLayer)	[(None, 256, 256, 3)]	0
sequential (Sequential)	(None, 127, 127, 16)	768
<pre>sequential_1 (Sequential)</pre>	(None, 62, 62, 32)	8320
<pre>sequential_2 (Sequential)</pre>	(None, 30, 30, 64)	32768
<pre>sequential_3 (Sequential)</pre>	(None, 14, 14, 128)	131584
<pre>sequential_4 (Sequential)</pre>	(None, 6, 6, 256)	525312
<pre>sequential_5 (Sequential)</pre>	(None, 2, 2, 512)	2099200
<pre>sequential_6 (Sequential)</pre>	(None, 6, 6, 512)	4194304
<pre>sequential_7 (Sequential)</pre>	(None, 14, 14, 256)	2097152
<pre>sequential_8 (Sequential)</pre>	(None, 30, 30, 128)	524288
<pre>sequential_9 (Sequential)</pre>	(None, 62, 62, 64)	131072
sequential_10 (Sequential)	(None, 126, 126, 32)	32768
<pre>sequential_11 (Sequential)</pre>	(None, 254, 254, 16)	8192

```
conv2d transpose 6 (Conv2DT (None, 255, 255, 8)
                                                      520
ranspose)
conv2d transpose 7 (Conv2DT (None, 256, 256, 3)
                                                      99
ranspose)
```

Total params: 9,786,347 Trainable params: 9,784,491 Non-trainable params: 1,856

```
# ## Model
# Here we have defined two blocks of networks. Encoder network takes
256 by 256 image and downsample it to 16 by 16 latent vector
# by passing our image via series of Convolution and Maxpooling layer.
This downsampled 16 by 16 latent vector is upsampled by passing
# through series of Convolution and UpSampling layer. The final
decoder output is same as our encoder input. This upsamples output of
decoder
# is compared with our sketches and reconstruction loss is calculated.
This loss is minimized by updating weight and bias of network through
# backpropagation.
# encoder_input = keras.Input(shape=(SIZE, SIZE, 3), name="img")
\# x = Conv2D(filters = 16, kernel size = (3,3), activation = 'relu',
padding = 'same')(encoder_input)
\# x = MaxPool2D(pool size = (2,2))(x)
\# x = Conv2D(filters = 32, kernel size = (3,3), strides = (2,2),
activation = 'relu', padding = 'valid')(x)
\# x = Conv2D(filters = 64, kernel size = (3,3), strides = (2,2),
activation = 'relu', padding = 'same')(x)
\# x = MaxPool2D(pool size = (2,2))(x)
\# x = Conv2D(filters = 128, kernel size = (3,3), activation = 'relu',
padding = 'same')(x)
\# x = Conv2D(filters = 256 , kernel\_size = (3,3), activation = 'relu',
padding = 'same')(x)
# encoder output = Conv2D(filters = 512 , kernel size = (3,3),
activation = 'relu', padding = 'same')(x)
# encoder = tf.keras.Model(encoder input, encoder output)
# decoder input = Conv2D(filters = 512 ,kernel_size = (3,3),
activation = 'relu', padding = 'same')(encoder output)
\# x = UpSampling2D(size = (2,2))(decoder input)
\# x = Conv2D(filters = 256, kernel size = (3,3), activation = 'relu',
padding = 'same')(x)
\# x = Conv2D(filters = 128, kernel size = (3,3), activation = 'relu',
padding = 'same')(x)
\# x = UpSampling2D(size = (2,2))(x)
```

```
\# x = Conv2D(filters = 64, kernel size = (3,3), activation = 'relu',
padding = 'same')(x)
\# x = UpSampling2D(size = (2,2))(x)
\# x = Conv2D(filters = 32, kernel size = (3,3), activation = 'relu',
padding = 'same')(x)
\# x = UpSampling2D(size = (2,2))(x)
\# x = Conv2D(filters = 16), kernel size = (3,3), activation = 'relu',
padding = 'same')(x)
# decoder output = Conv2D(filters = 3, kernel size = (3,3), activation
= 'relu', padding = 'same')(x)
# # final model
# model = keras.Model(encoder input, decoder output)
# model.summary()
Compiling and Fitting our model
Here we have used Adam optimizer and mean_squared_error as loss and have trained
model for 100 epochs
model.compile(optimizer = tf.keras.optimizers.Adam(learning rate =
0.0001), loss = 'mean absolute error',
              metrics = ['acc'])
model.fit(train image, train sketch image, epochs = 200, verbose = 0)
<keras.callbacks.History at 0x7fb13cb86bd0>
model.save('/kaggle/working/final model.h5')
model.save('/kaggle/working/model 3.h5')
model.save('./model 4.h5')
import pickle
pickle.dump(model,open("model.h5","wb"))
Keras weights file (<HDF5 file "variables.h5" (mode r+)>) saving:
...layers
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...vars
Keras model archive saving:
File Name
                                                                               Modified
Size
                                                                     2023-03-29 12:43:43
config.json
17886
                                                                     2023-03-29 12:43:44
variables.h5
117557856
                                                                     2023-03-29 12:43:43
metadata.json
64
Evaluating our model
prediction_on_test_data = model.evaluate(test_image,
test_sketch_image)
print("Loss: ", prediction on test data[0])
print("Accuracy: ", np.round(prediction_on_test_data[1] * 100,1))
```

```
acc: 0.4082
Loss: 0.11403301358222961
Accuracy: 40.8
Plotting our predicted sketch along with real sketch
def show images(real, sketch, predicted):
   plt.figure(figsize = (12,12))
   plt.subplot(1,3,1)
   plt.title("Image", fontsize = 15, color = 'Lime')
   plt.imshow(real)
   plt.subplot(1,3,2)
   plt.title("sketch",fontsize = 15, color = 'Blue')
   plt.imshow(sketch)
   plt.subplot(1,3,3)
   plt.title("Predicted",fontsize = 15, color = 'gold')
   plt.imshow(predicted)
ls = [i for i in range(0,95,8)]
for i in ls:
   predicted
=np.clip(model.predict(test image[i].reshape(1,SIZE,SIZE,3)),0.0,1.0).
reshape(SIZE, SIZE, 3)
   show images(test image[i],test sketch image[i],predicted)
1/1 [======= ] - 0s 336ms/step
1/1 [=======] - 0s 89ms/step
1/1 [======= ] - 0s 85ms/step
1/1 [======] - 0s 101ms/step
1/1 [=======] - 0s 93ms/step
1/1 [======= ] - 0s 95ms/step
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         1/1 [=====
          ====== 1 - 0s 90ms/step
1/1 [===
                           ==| - 0s 102ms/step
1/1 [==:
             ======== 1 - 0s 117ms/step
        Image
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                  200
                                   200
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                  250
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```

