# Summary Optimal Bayesian Classifier I

# **Ingredients:**

- 1. Stochastic variables (X,Y) with distribution  $P(\cdot,\cdot)$
- 2. Loss function  $L(\cdot,\cdot)$
- 3. Construct  $\hat{Y}(\cdot)$  by minimizing  $EL(Y, \hat{Y}(X))$

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#### **Solution:**

 $\forall x$ , solve  $\min_{\hat{Y}(x)} E_{Y|X=x} L(Y, \hat{Y}(x))$ .

In the binary case:

$$\hat{Y}(x) = I(\frac{P(Y=1|X=x)L(0,1)}{P(Y=0|X=x)L(1,0)} > 1)$$
(1)

This is of the form:

$$\hat{Y}(x) = I(\frac{P(Y=1|X=x)}{P(Y=0|X=x)} > c), \qquad c = \frac{L(1,0)}{L(0,1)}$$
(2)

We derived it last time when X is a discrete s.v; the results are true in general.

# Observe that by Bayes rule:

$$P(Y = y|X = x) = P(X = x|Y = y)P(Y = y)\frac{1}{P(X = x)}$$

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(4)

can be rewritten as:

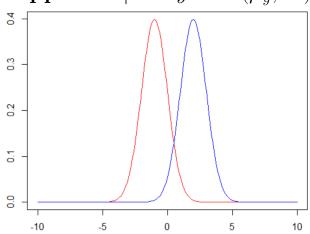
$$\hat{Y}(x) = I(\frac{P(X=x|Y=1)P(Y=1)}{P(X=x|Y=0)P(Y=0)} > c), \qquad c = \frac{L(1,0)}{L(0,1)}$$
(5)

$$\hat{Y}(x) = I(\frac{P(X=x|Y=1)}{P(X=x|Y=0)} > c_1), \qquad c_1 = \frac{L(1,0)P(Y=0)}{L(0,1)P(Y=1)}$$
(6)

Remember:

$$\hat{Y}(x) = I(\frac{P(X=x|Y=1)}{P(X=x|Y=0)} > c_1), \qquad c_1 = \frac{L(1,0)P(Y=0)}{L(0,1)P(Y=1)}$$
(7)

Suppose  $X|Y = y \sim \mathcal{N}(\mu_y, \sigma^2)$ 



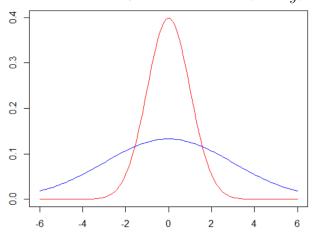
$$P(X|Y=0), P(X|Y=1),$$

How does  $\hat{Y}(x)$  look like?

### Remember:

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(8)

# Suppose $X|Y = y \sim \mathcal{N}(\mu, \sigma_y^2)$



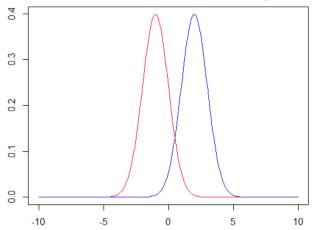
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(9)

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$$P(X|Y=0), P(X|Y=1),$$

How does  $\hat{Y}(x)$  look like?

#### Observe:

Strictly speaking not necesarry to know the (conditional) distributions, only their ratio.

We solve a harder problem than the original one.

### Naive Bayesian Classifier

#### Remember:

$$\hat{Y}(x) = I(\frac{P(X=x|Y=1)}{P(X=x|Y=0)} > c_1), \qquad c_1 = \frac{L(1,0)P(Y=0)}{L(0,1)P(Y=1)}$$
(10)

How to define (estimate) P(X = x | Y = y) in general? This is not obvious if X is a (high dimensional) vector.

### Naive Bayesian Classifier

#### Remember:

$$\hat{Y}(x) = I(\frac{P(X=x|Y=1)}{P(X=x|Y=0)} > c_1), \qquad c_1 = \frac{L(1,0)P(Y=0)}{L(0,1)P(Y=1)}$$
(11)

How to define (estimate) P(X = x | Y = y) in general? This is not obvious if X is a (high dimensional) vector.

The naive Bayesian classifier is based on the simplification (assumption) that X|Y=y are independent s.v. :  $P(X=x|Y=y)=\prod_i P(X_i=x_i|Y=y)$ .

Instead of 1 d-dimensional problem, we have d 1-dimensional problems.

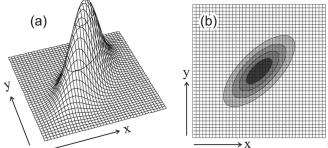
We say 
$$X = (X_1, \dots, X_d) \sim \mathcal{N}(\mu, \Sigma)$$
 if 
$$f_X(x) = \frac{1}{(2\pi)^{d/2} \sqrt{|\Sigma|}} \exp(-\frac{(x-\mu)^t \Sigma^{-1} (x-\mu)}{2})$$

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### Example:

**Take** d = 2.



(from: Keith Sircombe, axes shoud be  $x_1$  and  $x_2$ )

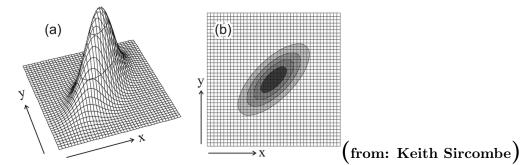
Contours are ellipses (ellipsoides)

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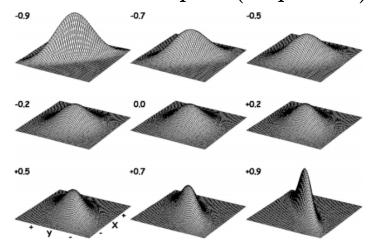
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### Example:

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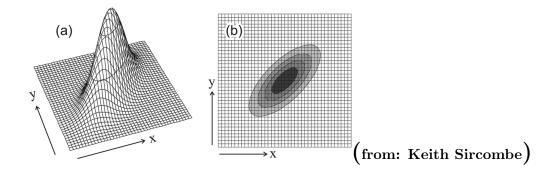


We say  $X \sim \mathcal{N}(\mu, \Sigma)$  if

$$f_X(x) = \frac{1}{(2\pi)^{d/2}\sqrt{|\Sigma|}} \exp(-\frac{-(x-\mu)^t \Sigma^{-1}(x-\mu)}{2})$$

### Example:

Take d=2.



#### Contours are ellipses (ellipsoides)

#### **Properties:**

- $EX = \mu$
- $Cov(X) := [Cov(X_i, X_j)]_{i,j} = \Sigma$

#### **Properties:**

- $l^t X$  is also normal distributed. In general  $Y = \mathbb{A} X \sim \mathcal{N}(\mathbb{A} \mu, \mathbb{A} \Sigma \mathbb{A}^t)$
- Marginal and conditional distributions are also normal.
- X has independent components if and only if  $\Sigma$  is diagonal matrix.

# Optimal Bayesian Classifier II

Remember:

$$\hat{Y}(x) = I(\frac{P(X=x|Y=1)}{P(X=x|Y=0)} > c_1), \qquad c_1 = \frac{L(1,0)P(Y=0)}{L(0,1)P(Y=1)}$$
(12)

Case 1:  $X|Y = y \sim \mathcal{N}(\mu_y, \Sigma)$ 

How does  $\hat{Y}(x)$  look like?

### Optimal Bayesian Classifier II

Remember:

$$\hat{Y}(x) = I(\frac{P(X=x|Y=1)}{P(X=x|Y=0)} > c_1), \qquad c_1 = \frac{L(1,0)P(Y=0)}{L(0,1)P(Y=1)}$$
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Case 1:  $X|Y = y \sim \mathcal{N}(\mu_y, \Sigma)$ 

How does  $\hat{Y}(x)$  look like?

Remember

$$f_X(x) = \frac{1}{(2\pi)^{d/2}\sqrt{|\Sigma|}} \exp(-\frac{(x-\mu)^t \Sigma^{-1}(x-\mu)}{2})$$

$$log\frac{P(X=x|Y=1)}{P(X=x|Y=0)} = \frac{-(x-\mu_1)^t \Sigma^{-1}(x-\mu_1)}{2} + \frac{(x-\mu_0)^t \Sigma^{-1}(x-\mu_0)}{2} + c^*$$

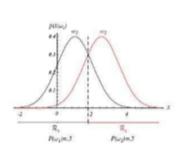
RHS is of the form

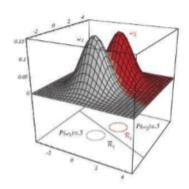
$$\Sigma^{-1}(\mu_1 - \mu_0)x + c^{**}$$

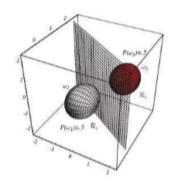
Hence classifier is of the form:

$$\hat{Y}(x) = I(l^t x > c^{***}), \qquad l = \Sigma^{-1}(\mu_1 - \mu_0)$$
 (14)

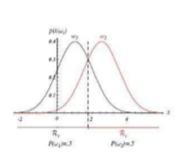
This is called the Linear Discriminant Analysis Classifier (LDA)

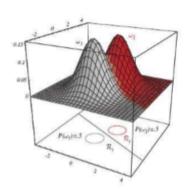


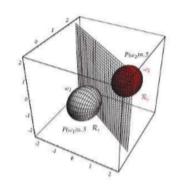




(from: Duda and Hart book)



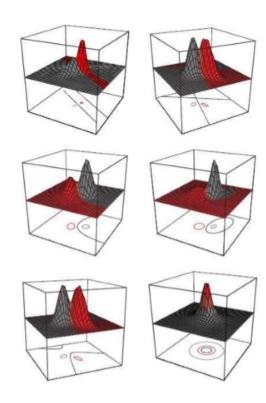




(from: Duda and Hart book)

Case 2:  $X|Y = y \sim \mathcal{N}(\mu_y, \Sigma_y)$ 

How does  $\hat{Y}(x)$  look like?



(from: Duda and Hart book)

This is called the Quadratic Discriminant Analysis Classifier (QDA)

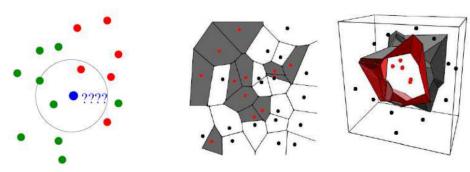
#### k- Nearest Neighbor classifier

#### Idea:

Given x. To decide  $\hat{y}(x)$ , look for  $N_k(x)$  the set of the k nearest observations to x.

For clasification: decide by voting: assign most frequent category in  $\{y_i, i \in N_k(x)\}$ For regression: decide by averaging: calculate mean of  $\{y_i, i \in N_k(x)\}$ 

### Example for classification:



(LHS from: Duda and Hart book)

For k = 1: relation with Voronoi diagram

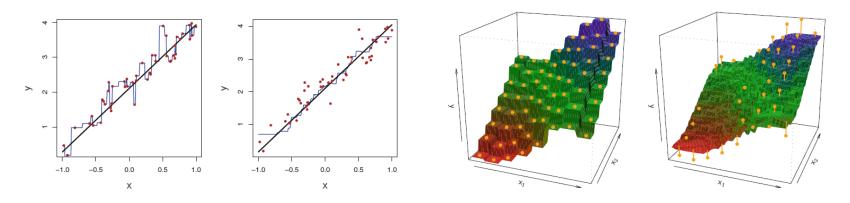
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### Example for regression:



(from: ISL book)

k=1 versus k=7

Quiz: What properties do you observe?

Denote by  $L^*$  the (mean) error of the optimal Bayes classifier,  $f_n$  a classifier based on  $\{(X_i,Y_i)\}_1^n$ , and  $L(f_n)=E(L(Y,f_n(X))$ , one can prove:

**Property 1** If  $n \to \infty$  and  $f_n$  is 1-NN classifier:

$$L^* \le EL(f_n) \le 2 * L^*$$

Property 2 If  $n \to \infty$  and  $k \to \infty$  such that  $k/n \to 0$ , if  $f_n$  is k-NN classifier: for any P():

$$EL(f_n) \to L^*$$

On the other hand:

Theorem no free lunch: for finite n, within any assumption about P, no classifier is superior.