MILESTONE 3 - Linked Lists and MCU I/O

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MECH 458 - B01 Group 1

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Documented Codes

/* Solution Set for the LinkedQueue.c */
/*

Course : UVic Mechatronics 458

Milestone : 3

Title : Data structures for MCUs and the Linked Queue Library

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Description: Use mTimer, Linked Lists, User Input, and button to display items in list shifted two bits each time.

```
/* include libraries */
#include <stdlib.h>
#include <avr/io.h>
#include "LinkedQueue.h" /* This is the attached header file, which cleans things up */
void mTimer(int count);
int main(int arge, char *argv[]){
```

```
CLKPR = 0x80;
CLKPR = 0x01;
TCCR1B = BV(CS11);
char readInput;
                              /* The ptr to the head of the queue */
link *head;
                              /* The ptr to the tail of the queue */
link *tail;
link *newLink;
                       /* A ptr to a link aggregate data type (struct) */
                       /* same as the above */
link *rtnLink;
element eTest;
                       /* A variable to hold the aggregate data type known as element */
DDRC = 0xFF;
                       /* Used for debugging purposes only LEDs on PORTC */
//DDRD = 0xFF;
DDRA = 0x00; // sets port A to input
DDRC = 0xFF; //sets port C to output bits for red LEDs
while(1){
       rtnLink = NULL;
       newLink = NULL;
       setup(&head, &tail);
       for(int i = 0; i < 3; i++){
               //check button
               while((PINA&0x04)==0x04); //checking if button is HIGH ie pushed
               mTimer(20); //debounce
               initLink(&newLink);
               newLink->e.itemCode = (PINA&0x03);
               enqueue(&head, &tail, &newLink);
               //check button
               while((PINA&0x04)==0x00); //checking if button is LOW ie not pushed
```

```
mTimer(20); //debounce
           }
           int i = 0;
           while(isEmpty(&head)!=1){
                 dequeue(&head, &rtnLink); //remove the item at the head of the list
                 PORTC = rtnLink->e.itemCode<<i;
                 mTimer(2000);
                 i=i+2;
           }
           while((PINA\&0x04)==0x04);
           mTimer(20); //debounce
           PORTC = 0;
           while((PINA&0x04)==0x00); //checking if button is LOW ie not pushed
           mTimer(20); //debounce
     }
     return(0);
}/* main */
/***********************
/****** SUBROUTINES
**/
/**********************
* DESC: initializes the linked queue to 'NULL' status
* INPUT: the head and tail pointers by reference
*/
```

```
void setup(link **h,link **t){
                               /* Point the head to NOTHING (NULL) */
        *h = NULL;
       *t = NULL;
                              /* Point the tail to NOTHING (NULL) */
        return;
}/*setup*/
**
* DESC: This initializes a link and returns the pointer to the new link or NULL if error
* INPUT: the head and tail pointers by reference
void initLink(link **newLink){
       //link *1;
        *newLink = malloc(sizeof(link));
       (*newLink)->next = NULL;
       return;
}/*initLink*/
* DESC: Accepts as input a new link by reference, and assigns the head and tail
* of the queue accordingly
* INPUT: the head and tail pointers, and a pointer to the new link that was created
*/
/* will put an item at the tail of the queue */
```

```
void enqueue(link **h, link **t, link **nL){
       if (*t != NULL){
               /* Not an empty queue */
               (*t)->next = *nL;
               *t = *nL; //(*t)->next;
       }/*if*/
       else{
               /* It's an empty Queue */
               //(*h)->next = *nL;
               //should be this
               *h = *nL:
               *t = *nL;
       }/* else */
       return;
}/*enqueue*/
* DESC: Removes the link from the head of the list and assigns it to deQueuedLink
* INPUT: The head and tail pointers, and a ptr 'deQueuedLink'
                which the removed link will be assigned to
*/
/* This will remove the link and element within the link from the head of the queue */
void dequeue(link **h, link **deQueuedLink){
       /* ENTER YOUR CODE HERE */
        *deQueuedLink = *h; // Will set to NULL if Head points to NULL
       /* Ensure it is not an empty queue */
       if (*h != NULL){
```

```
h = (h) - \text{next};
        }/*if*/
        return;
}/*dequeue*/
* DESC: Peeks at the first element in the list
* INPUT: The head pointer
* RETURNS: The element contained within the queue
/* This simply allows you to peek at the head element of the queue and returns a NULL pointer if empty
element firstValue(link **h){
        return((*h)->e);
}/*firstValue*/
**
* DESC: deallocates (frees) all the memory consumed by the Queue
* INPUT: the pointers to the head and the tail
*/
/* This clears the queue */
void clearQueue(link **h, link **t){
```

```
link *temp;
      while (*h != NULL){
            temp = *h;
            *h=(*h)->next;
            free(temp);
      }/*while*/
      /* Last but not least set the tail to NULL */
      *t = NULL;
      return;
}/*clearQueue*/
* DESC: Checks to see whether the queue is empty or not
* INPUT: The head pointer
* RETURNS: 1:if the queue is empty, and 0:if the queue is NOT empty
*/
/* Check to see if the queue is empty */
char isEmpty(link **h){
      /* ENTER YOUR CODE HERE */
      return(*h == NULL);
}/*isEmpty*/
```

```
* DESC: Obtains the number of links in the queue
* INPUT: The head and tail pointer
* RETURNS: An integer with the number of links in the queue
*/
/* returns the size of the queue*/
int size(link **h, link **t){
       link
                *temp;
                                       /* will store the link while traversing the queue */
               numElements;
        int
        numElements = 0;
                                       /* point to the first item in the list */
        temp = *h;
        while(temp != NULL){
               numElements++;
               temp = temp->next;
        }/*while*/
        return(numElements);
}/*size*/
* DESC: Acts as a clock.
* INPUT: Amount of time that has to be counted.
* RETURNS: Nothing
```

```
*/
void mTimer (int count){
   Setup Timer1 as a ms timer
        Using polling method not Interrupt Driven
 ***/
 int i;
 i = 0;
 //TCCR1B |= BV (CS11); // Set prescaler (/8) clock 16MHz/8 -> 2MHz
 /* Set the Waveform gen. mode bit description to clear
  on compare mode only */
 TCCR1B = BV(WGM12);
 /* Set output compare register for 1000 cycles, 1ms */
 OCR1A = 0x03E8;
 /* Initialize Timer1 to zero */
 TCNT1 = 0x0000;
 /* Enable the output compare interrupt */
 TIMSK1 = TIMSK1 | 0b00000010;
 /* Clear the Timer1 interrupt flag and begin timing */
 TIFR1 = BV(OCF1A);
 /* Poll the timer to determine when the timer has reached 1ms */
 while (i < count)
   if((TIFR1 \& 0x02) == 0x02){
```

```
/* Clear the interrupt flag by WRITING a ONE to the bit */
    TIFR1 |= _BV(OCF1A);
    i++;
    }
} return;
} /* mTimer */
```

Lab Assignment Solutions

No lab assignments.

Supplementary Information

No supplementary information.