

## Muhammad Izzat bin Fadzlon

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### EDUCATION

<b>SkillsFuture Career Transition Programme (SCTP)</b>	<b>Nov 2023 – Current</b>
<ul style="list-style-type: none"><li>Relevant skills: HTML, CSS, Javascript, Java, React, Springboot, DevOps, Containerization, React Native</li></ul>	
<b>Nanyang Technological University</b>	<b>Aug 2018 – Aug 2022</b>
Mechanical Engineering (Robotics and Mechatronics Stream)	
<ul style="list-style-type: none"><li>CGPA 4.27/5.00</li><li>Relevant modules: Intro to Computational Thinking, Robotics, Mechatronics System Interfacing, Realtime Software for Mechatronic Systems, Mechatronics Engineering Design</li></ul>	

### SKILLS

- Software: HTML, CSS, MATLAB, React, Redux, GIT, JavaScript, C, C++, OOP, JIRA, Confluence, Agile, ROS, Python, VS Code, Blender, Arduino, Vector CANoe, IBM DOORS
- Languages: English(fluent), Malay (fluent)

### PROJECTS

#### Personal Projects

<b>SteamBot that automatically add/chat/trades with Steam users</b>	<b>Jan 2023 – Mar 2023</b>
<ul style="list-style-type: none"><li>Design a fully automated steam Bot that automatically adds and trades users on Steam.</li><li>Ability to auto-add and auto-trade conditionally with players based on a modifiable pricelist object.</li><li>Automatically tracks and manages in-game currency from Team Fortress 2 within the bot's backpack to always display up-to-date currency information and ensure enough currency is available at all times.</li><li>Included a chat function whereby steam users can ask the bot for help using certain prompts to allow for autonomous assistance.</li><li>Achieved a 75% profit in 1 month of running the bot from trading with public Steam users.</li></ul>	

#### University Academic Projects

<b>Dyson x NTU Product Development Challenge</b>	<b>Aug 2020 – Nov 2020</b>
<ul style="list-style-type: none"><li>Conceptualized an original product under the mentorship of a Dyson engineer.</li><li>Designed and built kitchen prototypes for a bicycle helmet that allows for easy signalling using signal lights, with the inclusion of HUD technology.</li></ul>	
<b>Mechatronics system competition to design an Arcade Game (3<sup>rd</sup> place)</b>	<b>Sept 2019 – Nov 2019</b>
<ul style="list-style-type: none"><li>Collaborated with a group of 3 to build a game using Arduino microcontrollers and C coding.</li><li>Built a 2 levelled scaled down escape room to be maneuvered by a joystick-controlled car we designed.</li></ul>	

### WORK EXPERIENCE

<b>Software Engineer, Continental Automotive</b>	<b>July 2022 – Current</b>
<ul style="list-style-type: none"><li>Ensuring API calls triggered by driver input are accurately received between different control units in the cars, such as digital clusters and head units.</li><li>Debugging of test tickets received from customer by analyzing CAN traces, and assigning it to relevant teams.</li><li>Usage of JIRA for ticket creation and allocation in the context of Scrum methodology.</li><li>Development of new features through object-oriented programming while conducting unit test validation through GoogleTest using C/C++.</li></ul>	
<b>Lead Product Design, Amplefresh</b>	<b>Aug 2021 – July 2022</b>
<ul style="list-style-type: none"><li>Spearheaded the design and development of water-channelling conduits used in our first testbed situated at Bulim Square in collaboration with JTC.</li><li>Developed technical animations using Blender, explaining key features of our testbed to clearly present to sub-contractors our structural design requirements.</li></ul>	
<b>Mechanical Engineer Intern, Continental Automotive</b>	<b>Jan 2021 – May 2021</b>
<ul style="list-style-type: none"><li>Assisted in characterization of smart materials used in generating haptic feedback and morphing surfaces with oscilloscopes and signal generators.</li><li>Given full responsibility in self-learning Blender software for product animation of relevant prototypes, eventually being showcased during the Continental-NTU Corporate Lab inauguration.</li></ul>	
<b>Robotics Software Engineering Intern, Transforma Robotics</b>	<b>May 2021-Sep 2021</b>
<ul style="list-style-type: none"><li>Interfaced LiDAR sensors and built upon open-source ROS middleware to create an action server for Work at Height Painting Robot (WAHPR)</li><li>Spearheaded the first prototype of a parking algorithm using relevant mathematical concepts for a robot guidance system to align the WAHPR prior to painting(C++)</li></ul>	

### AWARDS AND ACHIEVEMENTS

<b>Dean's List, Nanyang Technological University</b>	<b>Jul 2020 - Jul 2020</b>
<ul style="list-style-type: none"><li>Achieved top 5% of cohort with minimum YGPA of 4.50 for AY2020-2021</li></ul>	