# reboot

Reboot the Herkulex motor

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### **Syntax**

reboot(sObject,pID)

## **Description**

reboot(sObject,pID) is used to reboot the Herkulex motor for usage like resetting motor status/ making changes to EEP

# **Input Arguments**

- sObject serial port object
- pID integer

### **Function Codes**

```
function reboot(sObject, pID)

packet = pkGen(pID,09,'');

inHkx(sObject,packet);
end
```

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