

checkCVal

Check for correct input values

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Syntax

`checkCVal(sObject,pID,CVal,varargin)`

Description

`checkCVal(sObject,pID,CVal,varargin)` checks the input values and returns validity of the input values. Note: Middle motor have smaller input value range due to its bracket.

Input Arguments

- `sObject` - serial port object
- `pID` - integer
- `CVal` - integer
- `varargin` - integer

Function Codes

```
function checkCVal(sObject, pID, CVal, varargin)

    CDiff = getCDiff(sObject,pID);

    % Default: Normal range checking if only 3 arguments

    if nargin == 3

        % Absolute value range (19~1002)

        minVal = 19-CDiff;

        maxVal = 1002-CDiff;
```

```

    %CVal+CDiff = Abs Value

    if (19>(CVal+CDiff) || (CVal+CDiff)>1002)

        error('Value of %d out of operational range!
Range:%d~%d',pID,minVal,maxVal);

    end

    % Special case: Check middle motor specifically due to smaller range (middle
    bracket)

    else

        % Absolute value range (105~834)

        minVal = 105-CDiff;

        maxVal = 834-CDiff;

        if (105>(CVal+CDiff) || (CVal+CDiff)>834)

            error('Value of %d out of operational range!
Range:%d~%d',pID,minVal,maxVal);

        end

    end

end
end
end

```