

# torqueOn

Enable torque for the Herkulex motor.

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## Syntax

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```
torqueOn(sObject,pID)
```

## Description

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torqueOn(sObject,pID) turn on the torque for the Herkulex motor. Torque has to be enabled first to control the motor's position.

- RAM register for torque: 0x34(52).

## Input Arguments

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- sObject - serial port object
- pID - integer

## Function Codes

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```
function torqueOn(sObject,pID)

    packet = pkGen(pID,03,'340160'); % 0x60: Torque on

    inHkx(sObject,packet);

    % Verify torque status

    torqueStat(sObject, pID);

end
```

