



Intermittent linearity of foot force direction vs center of pressure in quiet standing

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Introduction

Standing Balance via F control

- Maintaining upright postural control is an important component of human daily life and essential for preventing falls
- The control strategy is insufficiently understood to enable the development of appropriate rehabilitation for balance deficits
- Recently, we showed that the frequency-specific multi-joint coordination used to stand exhibits coordination yielding ground-on-foot force (F) with an intersection point (IP)¹ (Fig. 1)
- The IP height (zIP) varies with frequency; above the CM for $f < 1.75$ Hz and below the CM for $f > 1.75$ Hz (Fig. 3)

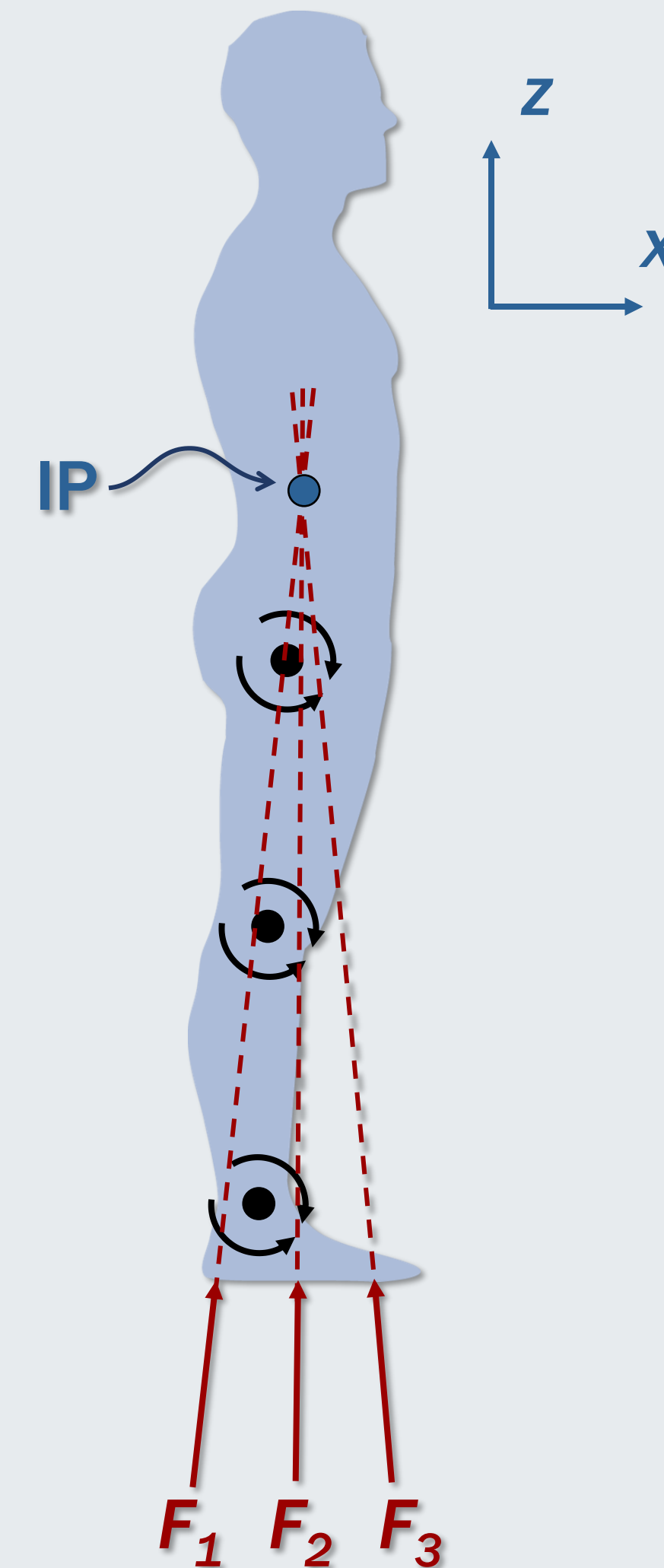


Figure 1. Humans stand with F vector changes ($F_{1,2,3}$) that exhibit an intersection point (IP), with height that varies with frequency¹ (Fig. 3).

Background

- Postural control involves sensing body posture and enacting muscular responses in a time-appropriate manner.
- In the sagittal plane the body consists of multiple linked segments that will not remain upright without muscular forces that produce torques at each joint (primarily ankle, knee, and hip).
- The multi-segmental nature of this mechanical linkage has infinite fall modes. Posture can deviate from upright in various distinct manners. Two distinct examples are pivoting only at the ankle ('falling like a board') and opposite angular motion of adjacent segments ('collapsing in a heap').
- Those fall modes have distinct kinematic motions and distinct inertial properties. Thus, each mode requires a distinct muscle coordination and temporal response.
- The force of the ground on the feet (F) is the net effect of the numerous muscles recruited.
- F change patterns quantify the complexity of standing control and may be useful for rapid and efficient diagnosis of balance disorders as well as tracking recovery.

Questions

- We test two hypotheses during quiet standing in non-disabled humans:
 - Intermittent episodes³ of foot-force change exhibit IP behavior
 - zIP varies with duration of xCP change

Methods

- 87 young adults (18-59 years, 56 female, median 28 years)²
- Stood quietly: each for 3 60s trials
- 6-axis force plate (100Hz)
- Calculate anterior-posterior center-of-pressure (xCP) & force ratio (F_x/F_z) (Fig. 2)

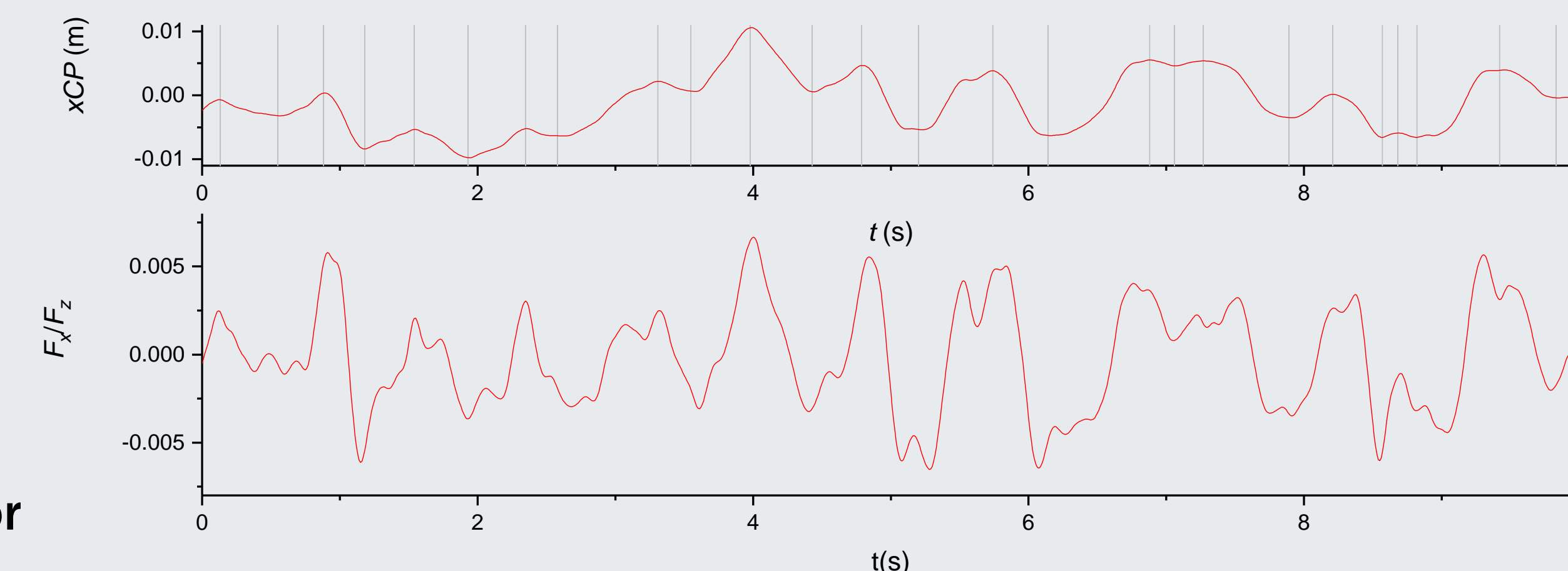


Figure 2. Time windows segmented at $d(xCP)/dt=0$.

- Band-pass Method¹:** band-pass filtered xCP and F_x/F_z in 0.2Hz non-overlapping intervals from 0–6Hz (2nd order zero-lag Butterworth), PCA of xCP vs F_x/F_z (Fig. 3) calculated zIP for each frequency band
- Intermittent Method:** xCP velocity zero-crossings segmented time windows of intermittent control (Fig. 2), PCA of xCP vs F_x/F_z (Fig. 3) calculated zIP for each window, window duration (dt) converted to 'frequency' = $1/(2dt)$
- Used zIP for windows with Variance-Accounted-For > 90%. Student's t-test (with Bonferroni correction) to infer zIP differences between two methods.

Results

- Human muscle coordination during quiet standing produces a **highly stereotypical pattern** of variation in F (Fig. 3)
- That pattern can be characterized as a linear change in F_x/F_z with respect to xCP (Fig. 3 left panels)
- 80% of windows had VAF>90%
- Linearity viewed as IP
- zIP varies with dt (Fig. 3, upper panels) and frequency (Fig. 3 lower left,)
- zIP similar for both methods but higher for Intermittent > 1.75 Hz (Fig. 3, right column)

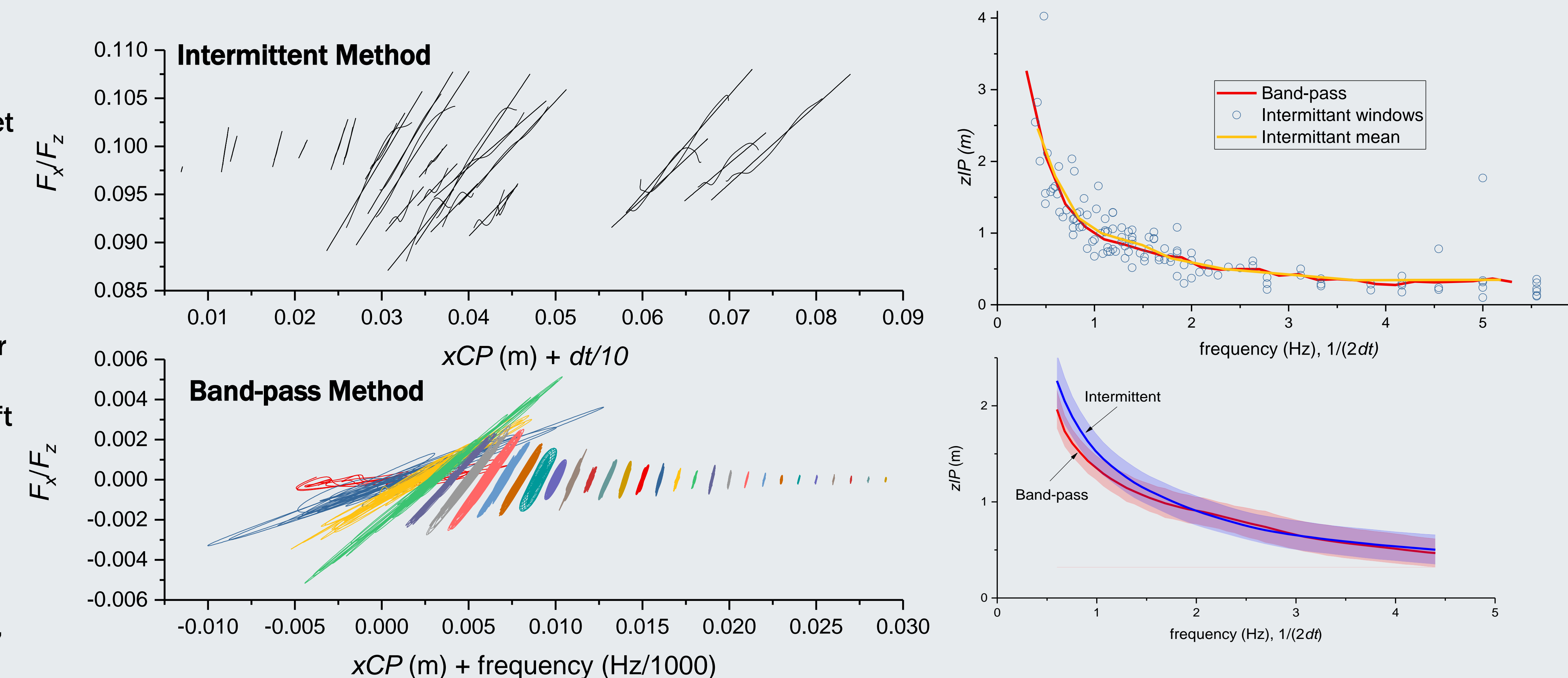


Figure 3. Linearity of F_x/F_z with respect to xCP (10s of trial in upper left panel with PCA lines, full trial lower left panel) consistent with IP (Fig. 1). Slope = $1/zIP$. Both methods give similar zIP variation with duration (Intermittent) or frequency (Band-pass) (1 full trial, upper right). zIP is similar for both methods but Intermittent is slightly higher at frequencies below 1.75 Hz (all trials mean \pm standard deviation, lower right).

Discussion

- Standing requires humans to coordinate ankle, knee, & hip muscles to arrest infinite fall modes
- Those fall modes are associated with varying amounts of whole body acceleration (Fig. 4), both translational acceleration of the center-of-mass (CM) and rotational acceleration of the whole body
- The emergence of an IP is likely the product of linear covariation of joint torques, analogous to muscle synergies or motor primitives⁴
- An IP is present and zIP varies with 'speed' for both brief time periods (Intermittent) and on average over long times (Band-pass)
- Correlation with 'speed' may be a tuning to the mechanical impedance of the fall modes
- zIP useful for diagnosis of balance disorders

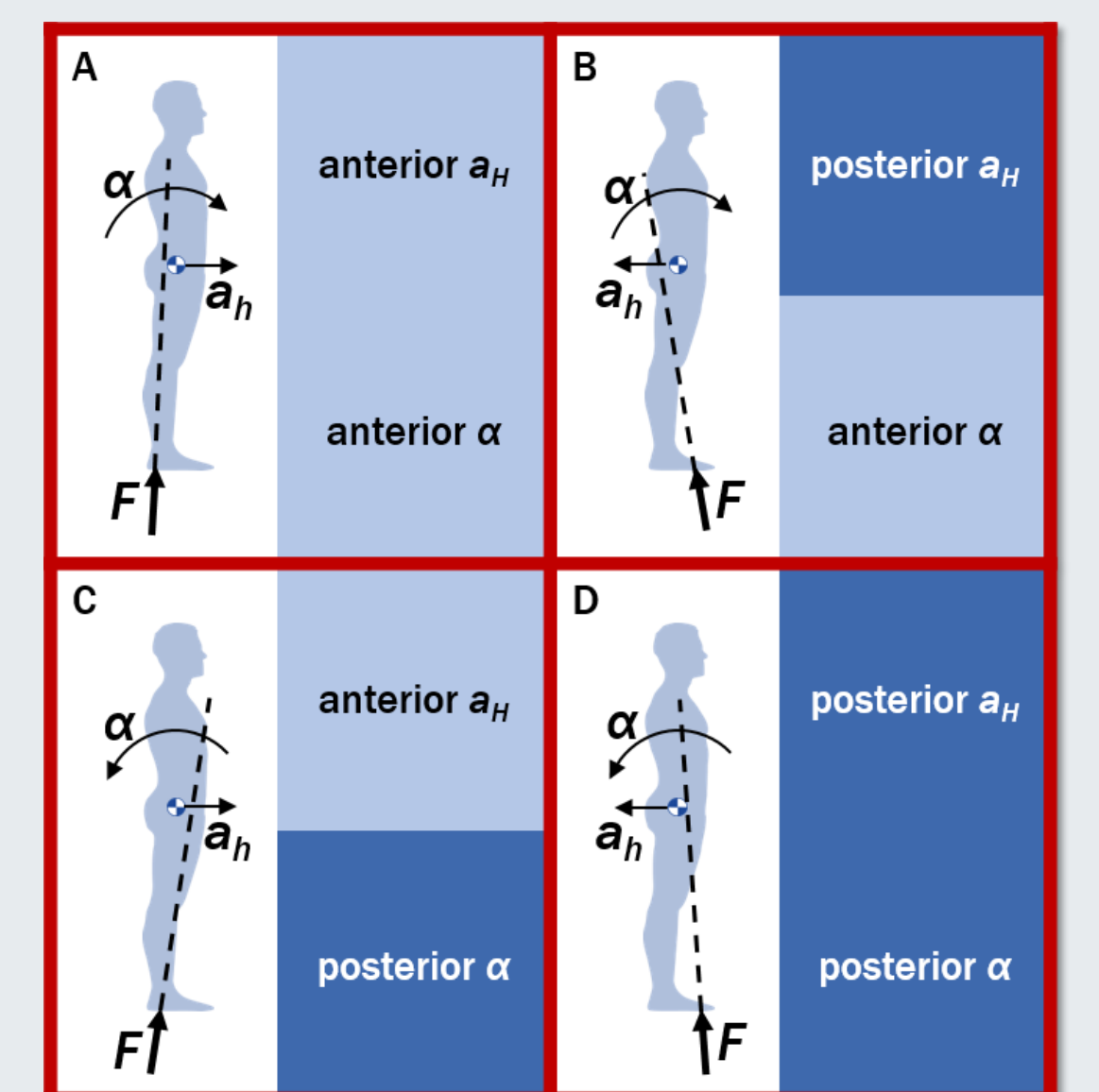


Figure 4. Coordination of joint torques determines the F that produces the various amounts of angular & translational accelerations of the whole body required to stop all fall modes.

References

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Acknowledgements

Conflict of Interest: K Gruben has an ownership interest in KIINCE LLC which develops rehabilitation technology. K Gruben & K Nichols have filed a US patent application related to this methodology.

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